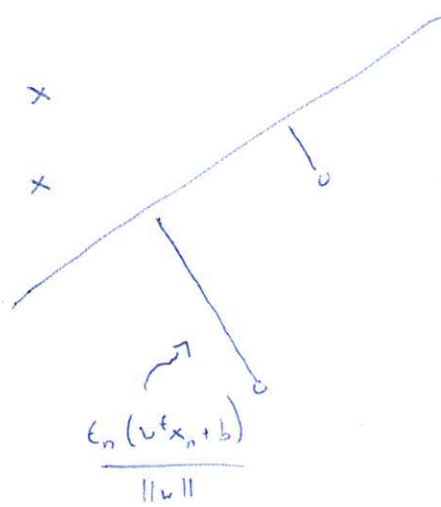


Recall



$$\{x: w^T x + b = 0\} = \text{hyperplane}$$

$$(x_1, \epsilon_1) \dots (x_N, \epsilon_N) \quad n=1 \dots N \quad \epsilon_n \in \{+1, -1\}$$

If  $x_n$  correctly classified  $(\text{sgn}(v^T x_n + b) = \epsilon_n)$

$$\frac{\epsilon_n (v^T x_n + b)}{\|v\|} \text{ is dist. from } \{x: w^T x + b = 0\}$$

$$\text{Margin} = M(w, b) = \min_n \frac{\epsilon_n (v^T x_n + b)}{\|v\|} \quad \text{I (scaling } w)$$

$$\begin{aligned} \max_{w, b} \quad & \min_n \frac{\epsilon_n (v^T x_n + b)}{\|v\|} \\ \text{s.t.} \quad & \min_n \epsilon_n (v^T x_n + b) \geq 1 \end{aligned}$$

All points classified correctly.

$$\text{Margin} = \frac{1}{\|w\|}$$

=

$$\min_{w, b} w^T w \quad \text{s.t.} \quad \epsilon_n (v^T x_n + b) \geq 1 \quad n=1 \dots N$$

①  $\min w^T w \iff \max \frac{1}{\|w\|}$

~~s.t.  $\epsilon_n (v^T x_n + b) \geq 1$~~

Interp of  $w$ :  $\frac{1}{\|w\|}$  is margin

② Have Q.P. problem.

Want to relax "all correctly classified" assumption

86.2

Replace:

$$\epsilon_n(w^t x_n + b) \geq 1 \quad n=1 \dots N$$

with

$$\epsilon_n(w^t x_n + b) \geq 1 - \underbrace{\zeta_n}_{\text{"slack" variables}} \quad \zeta_n \geq 0 \quad n=1 \dots N$$

"slack" variables.

where we try to make  $\{\zeta_n\}$  small.

Formulation

$$\min_{\substack{w, b \\ \zeta_1, \dots, \zeta_N}} w^t w + C \sum_{n=1}^N \zeta_n \quad \text{s.t.} \quad \epsilon_n(w^t x_n + b) \geq 1 - \zeta_n \quad n=1 \dots N \\ \zeta_n \geq 0 \quad n=1 \dots N$$

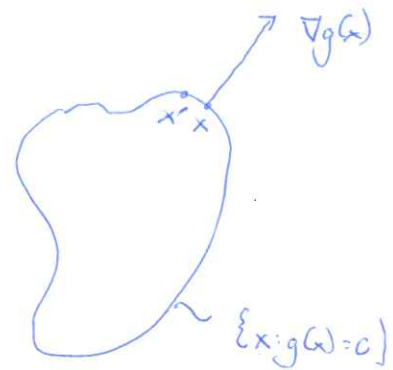
See generalized SVM.

## Lagrange Multipliers

Have level set  $\{x: g(x) = 0\}$

Fact:  $\nabla g(x)$  is "normal" (orthogonal)

to  $\{x: g(x) = 0\}$ .



To see this let  $x' \in \{x: g(x) = 0\}$  close to  $x$

$$\underbrace{g(x')}_{=0} \approx \underbrace{g(x)}_{=0} + \underbrace{\nabla g(x) \cdot (x - x')}_{=0}$$

$\Rightarrow \nabla g(x)$  orthog to  $x - x'$

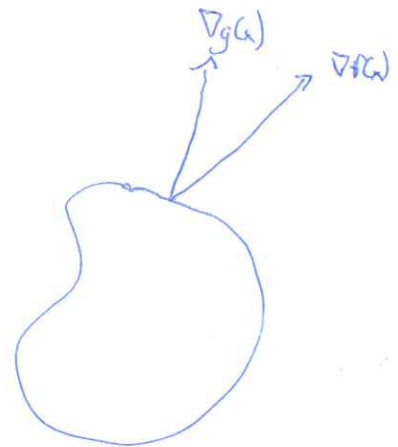
Now consider constrained opt. problem

$$\max_x f(x) \quad \text{s.t.} \quad g(x) = 0$$

Solution  $\hat{x}$  must satisfy:  $\nabla f(x) = \lambda \nabla g(x)$

( $\nabla f(x)$  and  $\nabla g(x)$  point in same direction)

Otherwise could "walk along"  $\{x: g(x) = 0\}$  making positive prog into  $\nabla f(x)$  thus increasing  $f(x)$



# The Lagrangian

Consider

$$\max_x f(x) \quad \text{s.t.} \quad g(x) = 0$$

Let

$$L(x, \lambda) = f(x) + \lambda g(x) \quad (\text{the Lagrangian})$$

Consider a stationary pt. of Lagrangian  
(ie. where  $\nabla = 0$ )

$$\nabla_{x, \lambda} L(x, \lambda) = 0$$

$\Rightarrow$

$$\left. \begin{array}{l} \nabla_x \quad 1) \quad \nabla f(x) = -\lambda \nabla g(x) \\ \nabla_\lambda \quad 2) \quad g(x) = 0 \end{array} \right\} \begin{array}{l} \text{Criteria for constrained} \\ \text{optimum} \end{array}$$

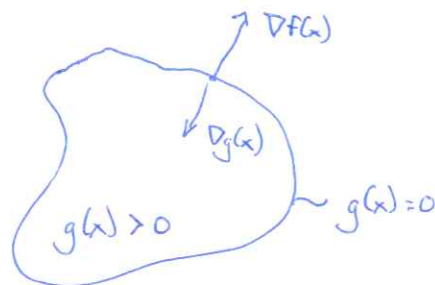
$\Rightarrow$  Stationary pts. of Lagrangian are constrained optima.

## Variation

Consider

$$\max_x f(x) \quad \text{s.t.} \quad g(x) \geq 0$$

Sol. must satisfy



$$① \quad g(x) > 0 \quad \text{and} \quad \nabla f(x) = 0$$

or

Here constraint inactive  
(corresp. stationary pt. of  $L(x, \lambda)$  has  $\lambda = 0$ )

$$② \quad \cancel{\nabla f(x) = -\lambda \nabla g(x)} \quad g(x) = 0 \quad \text{and} \quad \nabla f(x) = -\lambda \nabla g(x) \quad \cancel{\lambda = 0}$$

Here constraint active (corresp. st. pt. of  $L(x, \lambda)$  has  $\lambda > 0$ )

# Lagrangian Duality

Consider  $\max_x f(x)$  s.t.  $g_k(x) \geq 0 \quad k=1 \dots k$ .

$$L(x, \lambda, \dots, \lambda_k) = f(x) + \sum_{k=1}^k \lambda_k g_k(x)$$

$$\text{" } \lambda = \begin{pmatrix} \lambda_1 \\ \vdots \\ \lambda_k \end{pmatrix} \text{ "}$$

$$L(x, \lambda) = f(x) + \lambda^T g(x)$$

$$g(x) = \begin{pmatrix} g_1(x) \\ \vdots \\ g_k(x) \end{pmatrix}$$

Define  $\tilde{L}(\lambda) = \max_x L(x, \lambda)$

The dual problem of the original one is

$$\min_{\lambda} \tilde{L}(\lambda) \quad \text{s.t.} \quad \lambda_1, \dots, \lambda_k \geq 0$$

Dual has interesting connection to original.

For  $x, \lambda$  satisfying constraints, must have

$$\tilde{L}(\lambda) \geq L(x, \lambda) \geq f(x)$$

$$\Rightarrow \min_{\lambda \geq 0} \tilde{L}(\lambda) \geq \max_{x: g(x) \geq 0} f(x)$$

However, under some circumstances

$$\min_{\lambda: \lambda \geq 0} \tilde{L}(\lambda) = \max_{x: g(x) \geq 0} f(x)$$

In this case can solve dual to get

$$\lambda^* = \arg \min_{\lambda: \lambda \geq 0} \tilde{L}(\lambda) \quad \text{and get optimal } x, x^*, \text{ by solving}$$

$$x^* = \arg \min_x L(x, \lambda^*)$$

(unconstrained)

Dual often easier to solve due to simple constraints  $\lambda \geq 0 \dots \lambda_k \geq 0$ .

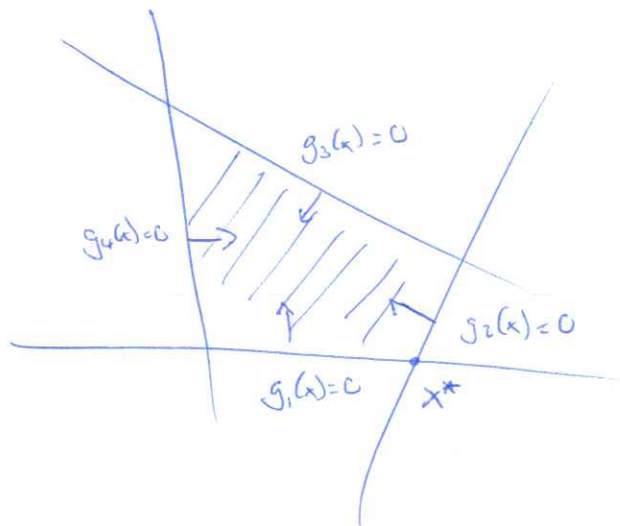
(30)

Interpretation of  $\lambda^*, x^*$

Have  $\lambda_1^* \geq 0 \dots \lambda_n^* \geq 0$

$$\lambda_k^* = 0 \iff g_k(x^*) > 0 \quad (\text{constraint inactive})$$

$$\lambda_k^* > 0 \iff g_k(x^*) = 0 \quad (\text{constraint active})$$



Constraints 1, 2 active

3, 4 inactive

## Dual Formulation of SVM

Have

$$\min_{w, b} \frac{1}{2} w^t w \quad \text{s.t.} \quad t_n (w^t x_n + b) \geq 1 \quad n=1 \dots N.$$

$\Leftrightarrow$

$$\max_{w, b} -\frac{1}{2} w^t w \quad \text{s.t.} \quad t_n (w^t x_n + b) - 1 \geq 0 \quad n=1 \dots N.$$

The Lagrangian is

$$L(w, b, \lambda) = -\frac{1}{2} w^t w + \sum_{n=1}^N \lambda_n [t_n (w^t x_n + b) - 1]$$

Dual phrased in terms of

$$\tilde{L}(\lambda) = \max_{w, b} L(w, b, \lambda)$$

$$\nabla_w L(w, b, \lambda) = 0 \Rightarrow w = \sum_{n=1}^N \lambda_n t_n x_n$$

$$\nabla_b L(w, b, \lambda) = 0 \Rightarrow \sum_{n=1}^N \lambda_n t_n = 0$$

Get  $\tilde{L}(\lambda)$  by substituting these into  $L(w, b, \lambda)$

$$\tilde{L}(\lambda) = -\frac{1}{2} \sum_{n, m=1}^N \lambda_n \lambda_m t_n t_m x_n^t x_m$$

$$+ \sum_{n=1}^N \lambda_n t_n \left[ \sum_{m=1}^N \lambda_m t_m x_n^t x_m + b \right] - \sum_{n=1}^N \lambda_n$$

$$= -\frac{1}{2} \sum_{n, m=1}^N \lambda_n \lambda_m t_n t_m x_n^t x_m - \sum_{n=1}^N \lambda_n$$



~~Lagrangian Duality~~

Have  $\max_x f(x)$  s.t.  $g_k(x) \leq 0 \quad k=1 \dots k$

~~$L(x, \lambda_1, \dots, \lambda_k) = L(x, \lambda) = f(x) + \sum_{k=1}^k \lambda_k g_k(x)$~~

## Lagrangian Dual

$$\min_{\lambda_1, \dots, \lambda_n} \quad \frac{1}{2} \sum_{n,m=1}^n \lambda_n \lambda_m t_n t_m x_n^t x_m - \sum_{n=1}^n \lambda_n \quad \text{s.t.} \quad \lambda_n \geq 0 \quad n=1 \dots n$$

$$\sum_{n=1}^n \lambda_n t_n = 0$$

This is a new QP problem.

Solve to get  $\lambda_1 \dots \lambda_n$ . Most  $\lambda$ 's are 0.

$$\lambda_n = 0 \iff \text{corresp constraint } \epsilon_n(w^t x_n + b) \geq 1 \text{ inactive } (> 1)$$

$$\lambda_n > 0 \iff \text{" " " " " active } (= 1)$$

The  $x_n$  s.t.  $\lambda_n > 0$  are "support vectors"

## Resulting Classifier

Classify by  $\text{sgn}(y(x))$  where

$$y(x) = w^t x + b$$

$$= \sum_{n=1}^n \lambda_n t_n x_n^t x + b$$

$$= \sum_{n \in S} \lambda_n t_n x_n^t x + b \quad \text{where } S = \{n: \lambda_n > 0\}$$

To compute  $b$  note for  $n \in S$

$$\epsilon_n(w^t x_n + b) = 1$$

$\implies$

$$\epsilon_n \left( \sum_{m \in S} t_m x_m^t x_n + b \right) = 1$$

Solve for  $b$ .

Note: classifier only depends on support vectors



### Important Observation

The feature vector assoc. with  $k(x, x') = e^{-\frac{1}{2\sigma^2} \|x - x'\|^2}$  is infinite!

To implement SVM with these features

$$\text{Substitute } k(x, x') = e^{-\frac{1}{2\sigma^2} \|x - x'\|^2}$$

$$\text{for } x = x'$$

in QP formulation of dual and solve for  $\lambda_1, \dots, \lambda_n$ .

The resulting classifier is

$$\text{Class}(x) = \text{sgn}(y(x))$$

$$= \text{sgn}(w^T x + b)$$

$$= \text{sgn}\left(\sum_{n=1}^n \lambda_n \epsilon_n k(x_n, x) + b(\lambda)\right)$$

$$= \text{sgn}\left(\sum_{n \in S} \lambda_n \epsilon_n e^{-\frac{1}{2\sigma^2} \|x_n - x\|^2} + b(\lambda)\right)$$