KPR: Stability Testing

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1/4/2020

The purpose of this experiment is to study the relative change in KPR coefficients after making permutations to the Q, H, and Z matrices.

The file "helpers.R" loads the yatsunenko data set, and includes helper functions for comparing models.

```
## Loading KPR
##
## Attaching package: 'dplyr'
## The following objects are masked from 'package:stats':
##
## filter, lag
## The following objects are masked from 'package:base':
##
## intersect, setdiff, setequal, union
```

\mathbf{Q}

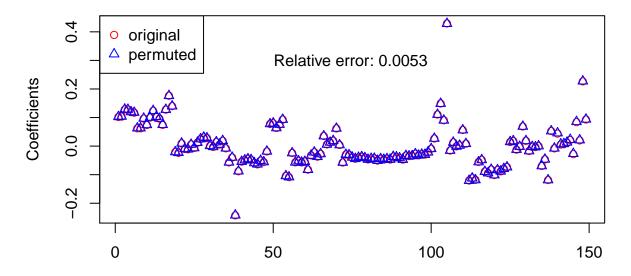
Eigenvalue Permutations

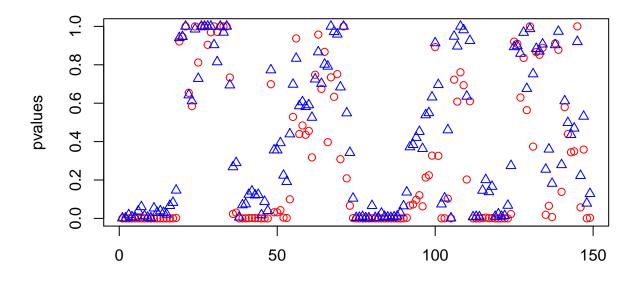
```
Q <- generateSimilarityKernel(patristic)

## Correcting small and negative eigenvalues
Q.1 <- permuteEigenvalue(Q, 1)
Q.2 <- permuteEigenvalue(Q, 75)
Q.3 <- permuteEigenvalue(Q, 149)

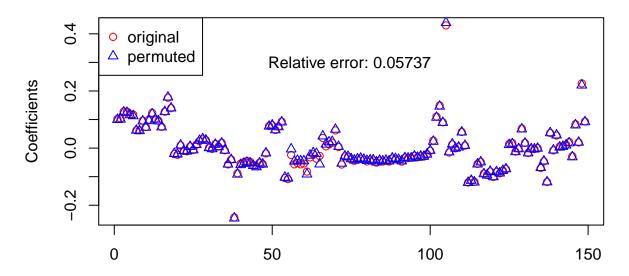
fit <- KPR(designMatrix = Z, Y = Y, Q = Q)
fit.1 <- KPR(designMatrix = Z, Y = Y, Q = Q.1)
fit.2 <- KPR(designMatrix = Z, Y = Y, Q = Q.2)
fit.3 <- KPR(designMatrix = Z, Y = Y, Q = Q.3)

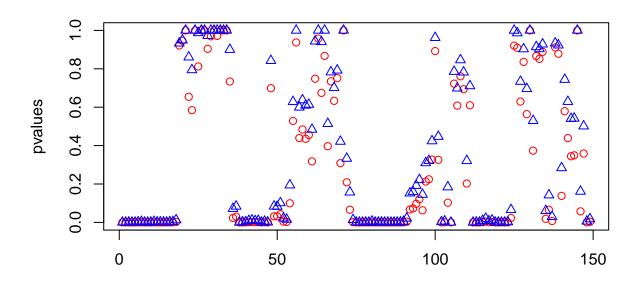
compareModels(fit, fit.1, main = "Eigenvalue 1")</pre>
```



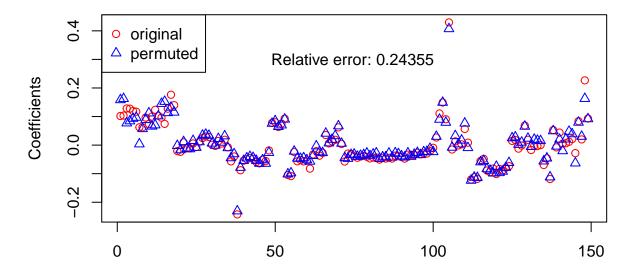


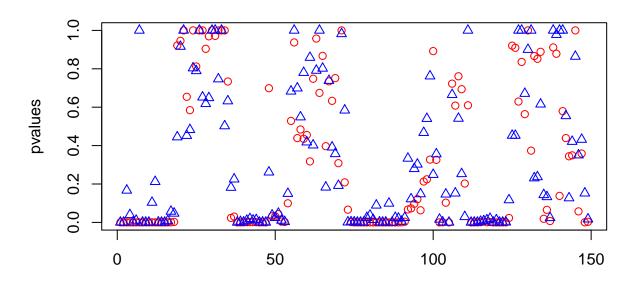
compareModels(fit, fit.2, main = "Eigenvalue 75")





compareModels(fit, fit.3, main = "Eigenvalue 149")



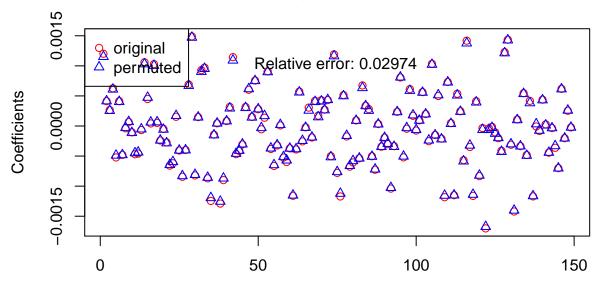


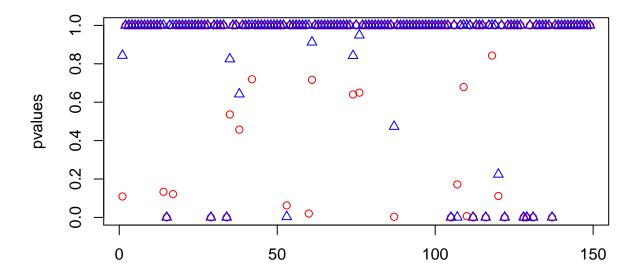
\mathbf{H}

Eigenvalue Permutations

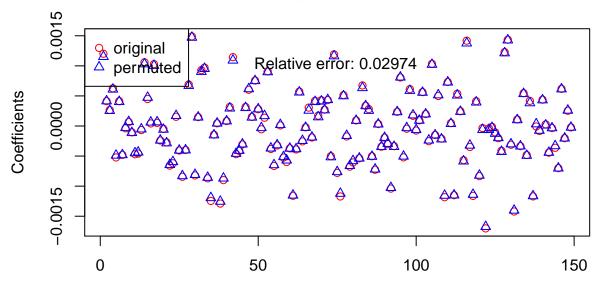
```
# H <- generateSimilarityKernel(unifrac)
H <- solve(ec %*% t(ec))
H.1 <- permuteEigenvalue(H, 1)
H.2 <- permuteEigenvalue(H, 50)
H.3 <- permuteEigenvalue(H, 100)

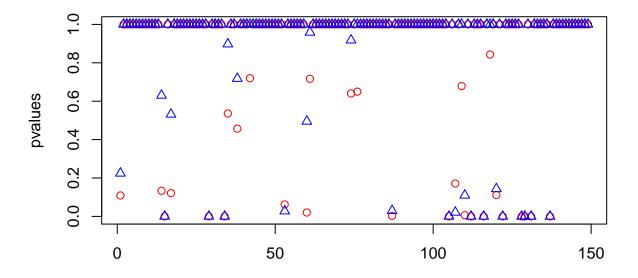
fit <- KPR(designMatrix = Z, Y = Y, H = H)
fit.1 <- KPR(designMatrix = Z, Y = Y, H = H.1)
fit.2 <- KPR(designMatrix = Z, Y = Y, H = H.2)
fit.3 <- KPR(designMatrix = Z, Y = Y, H = H.3)</pre>
compareModels(fit, fit.1, main = "Eigenvalue 1")
```



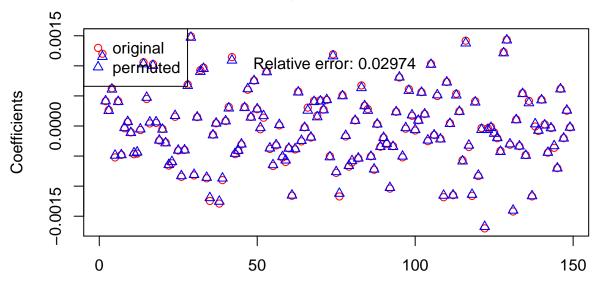


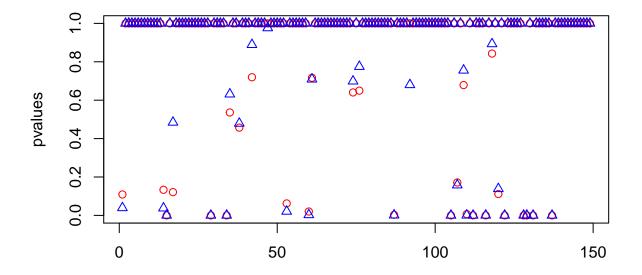
compareModels(fit, fit.2, main = "Eigenvalue 50")





compareModels(fit, fit.3, main = "Eigenvalue 100")





\mathbf{Z}

Gaussian Noise

```
Z.1 <- Z + rnorm(n = length(Z))
fit <- KPR(designMatrix = Z, Y = Y)
fit.1 <- KPR(designMatrix = Z.1, Y = Y)

compareModels(fit, fit.1, main = "Gaussian noise")</pre>
```

Gaussian noise

