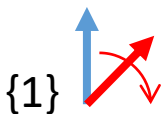
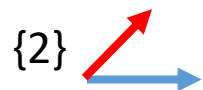
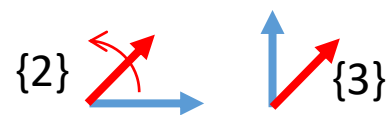


i	Θ_i	d_i	a_i	α_i	σ_i
1	q_1	L_1	0	90°	0
2	q_2	L_2	0	-90°	0
3	0	q_3	0	90°	L_3
4	q_4	0	0	-90°	0
5	0	L_4	0	0	0

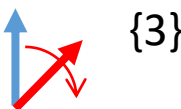
$i = 1$
 $\Theta_1 = q_1$
 $d_1 = L_1$
 $a_1 = 0$
 $\alpha_1 = 90^\circ$
 $\sigma_1 = 0$



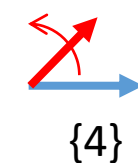
$i = 2$
 $\Theta_2 = q_2$
 $d_2 = L_2$
 $a_2 = 0$
 $\alpha_2 = -90^\circ$
 $\sigma_2 = 0$



$i = 3$
 $\Theta_3 = 0$
 $d_3 = q_3$
 $a_3 = 0$
 $\alpha_3 = 90^\circ$
 $\sigma_3 = L_3$



$i = 4$
 $\Theta_4 = q_4$
 $d_4 = 0$
 $a_4 = 0$
 $\alpha_4 = -90^\circ$
 $\sigma_4 = 0$



$i = 5$
 $\Theta_5 = 0$
 $d_5 = L_4$
 $a_5 = 0$
 $\alpha_5 = -90^\circ$
 $\sigma_5 = 0$



$i = 1$

	$\cos(q_1)$	0	$\sin(q_1)$	0
A1=	$\sin(q_1)$	0	$-\cos(q_1)$	0
	0	1	0	L_1
	0	0	0	1

$i = 2$

	$\cos(q_2)$	0	$-\sin(q_2)$	0
A2=	$\sin(q_2)$	0	$\cos(q_2)$	0
	0	-1	0	L_2
	0	0	0	1

$i = 3$

	1	0	1	0
A3=	0	0	0	0
	0	1	0	q_3
	0	0	0	1

$i = 4$

	$\cos(q_4)$	0	$-\sin(q_4)$	0
A4=	$\sin(q_4)$	0	$\cos(q_4)$	0
	0	-1	0	L_4
	0	0	0	1

