

Telecooperation Lab
Prof. Dr. Max Mühlhäuser

TK3: Ubiquitous Computing

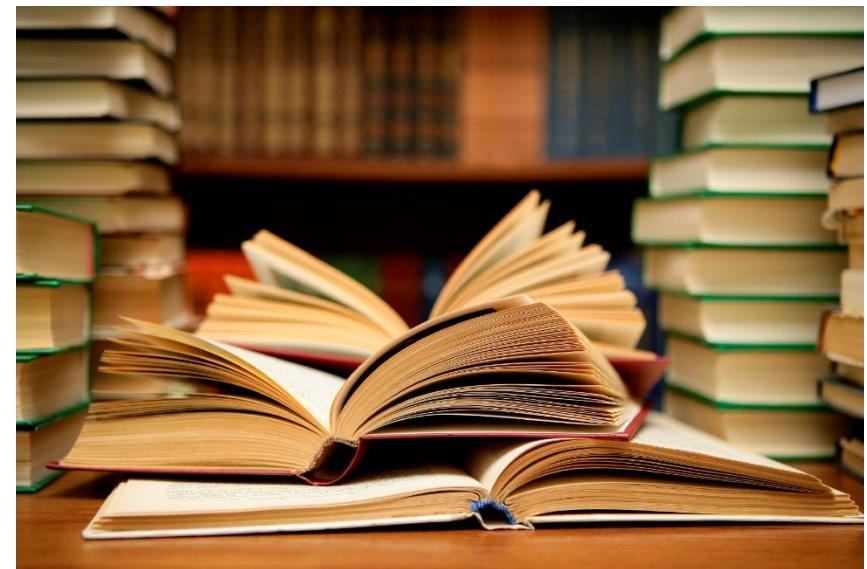
Chapter 1: Devices & Sensing
Part 2: Sensors & Actuators
Lecturer: Dr. Immanuel Schweizer

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Sources

- <http://web.cse.ohio-state.edu/~anish/788-12.html>
- <http://www.cs.berkeley.edu/~prabal/teaching/cs294-11-f05>
- *Book slides: 6LoWPAN – The Wireless Embedded Internet*
- *Book / Lecture slides: Embedded System Design & CPS, TU Dortmund*
- <http://www.ecse.rpi.edu/homepages/abouzeid/6962-05/monet12-coverage-xiang.pdf>





Recap: Tagging



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- Tagging
 - Augmenting people, objects, and the environment with digital information
- Technologies
 - RFID
 - NFC
 - iBeacons
- Automatic interaction between virtual and real world





Recap: iBeacon



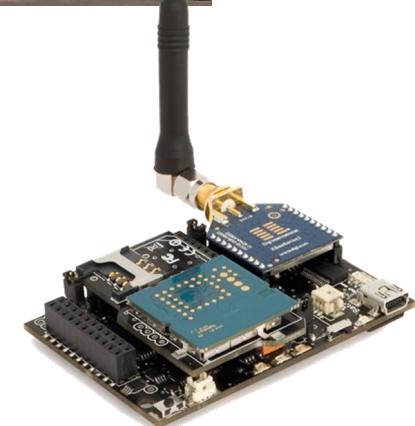
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- Tagging of the environment
 - Distribute beacons in stores / airports
- Bluetooth LE
 - Years of operation
 - Longer Range (~60-350 meters)
- RSSI measurements
 - Measure distance
 - Additional sensor data
 - Location & Direction
- Use cases:
 - Indoor location
 - Proximity services (Ads...)





- Embedded Systems
- Sensor Nodes
- Wireless Sensor Networks
- Cyber-Physical Systems





Remember



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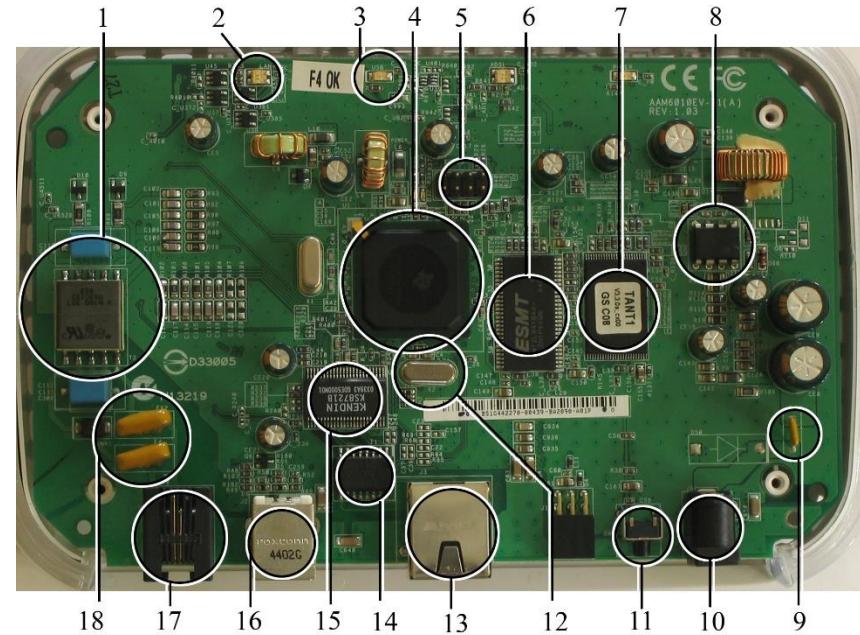
“The most profound technologies are those that disappear. They weave themselves into the fabric of everyday life until they are indistinguishable from it.”



Embedded Systems

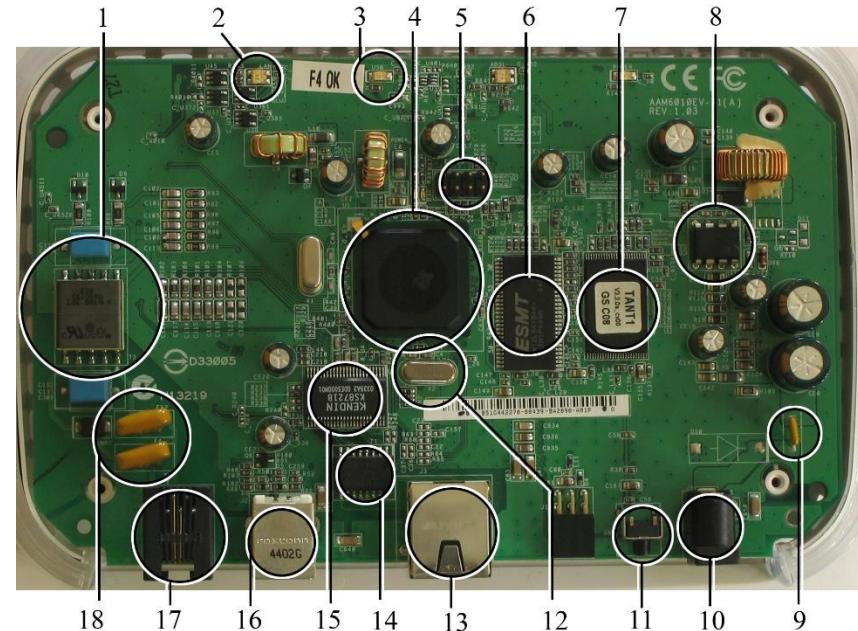


An **embedded system** is a computer **system** with a dedicated function within a larger mechanical or electrical **system**, often with real-time computing constraints. It is **embedded** as part of a complete device often including hardware and mechanical parts. **Embedded systems** control many devices in common use today.





- Embedding computer systems anywhere
- Dedicated function
- Control devices





Example: Car



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- EPS
- ABS
- Airbags
- Efficient automatic gearbox
- Blind-Angle alert systems





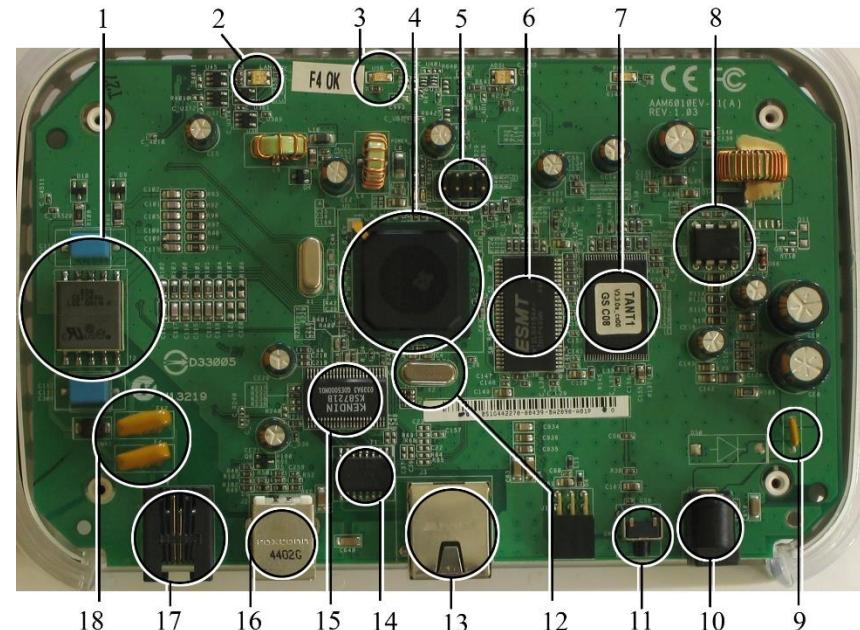
Embedded Systems



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- Embedding computer systems anywhere
- Dedicated function
- Control devices

- Stand-alone or closed systems
- Connectivity?





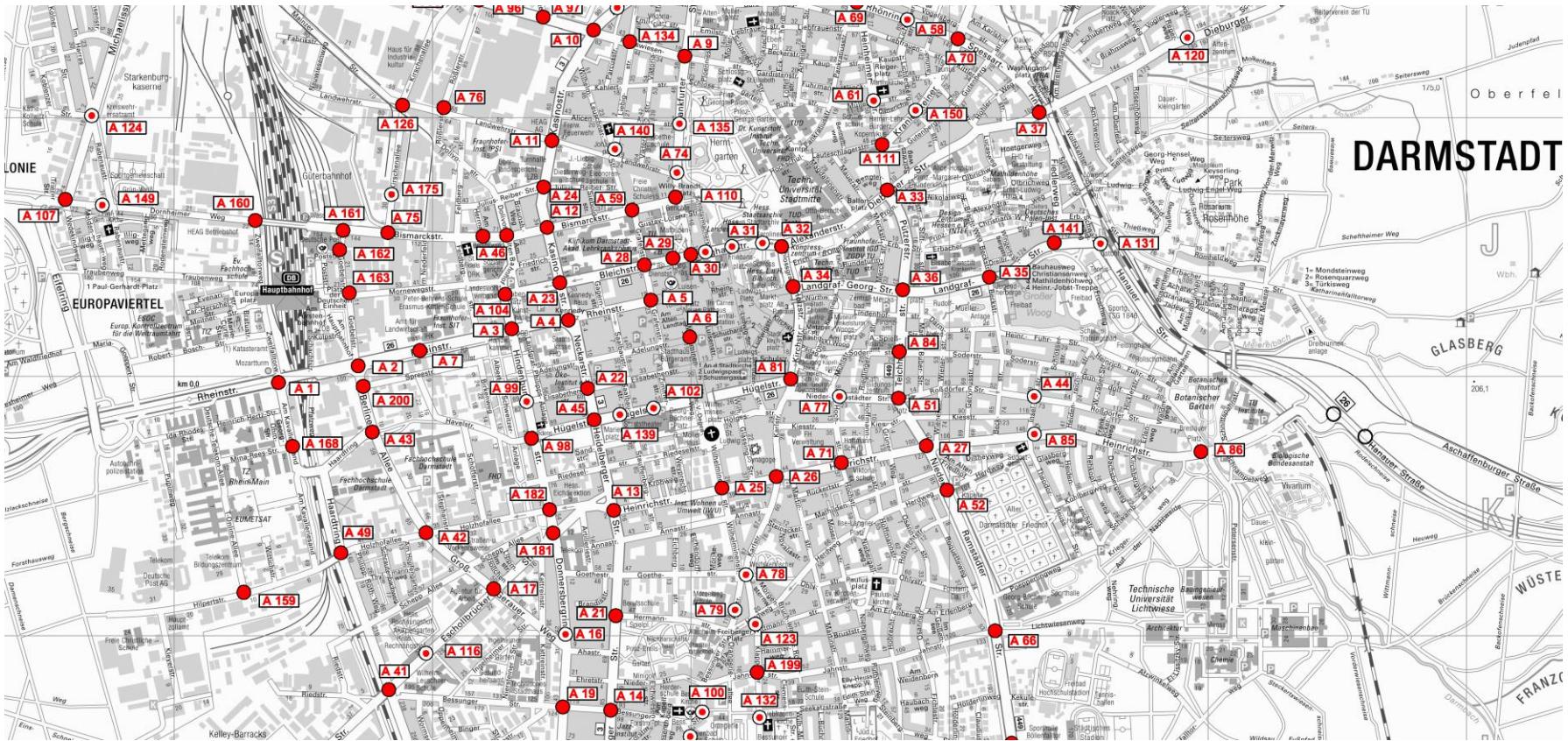
Embedded Infrastructure



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Traffic sensors

- 171 traffic lights equipped with inductive loops





- Micro fabrication and integration of low-cost sensors, actuators and computer controllers, MEMS (Micro Electro-Mechanical Systems)
- Can be sprayed & embedded throughout the digital environment
- Creating a digital skin that senses physical & chemical phenomena





Sensor Nodes



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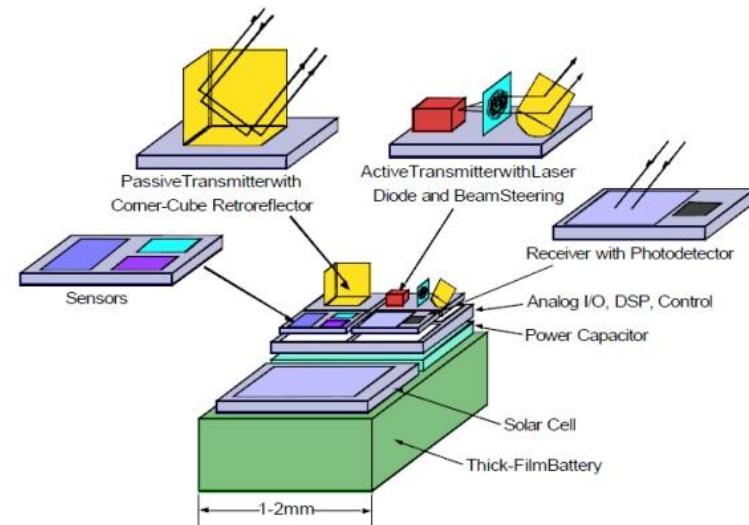
- Connect wirelessly
 - WiFi, Zigbee, 802.15.4., NFC
 - GPRS, 3G, 4G

- Small Sensors
 - Smart dust (<1mm)

- Battery
 - Months, Years
 - Infinite?

- Cheap
 - Today: 50 – 700€ per node

Smart Dust Mote



Kahn et al., Next Century Challenges: Mobile Networking for „Smart Dust“, 1999



- Small & Cheap
- Battery-powered
- Wireless

Combination of:

- Breakthroughs in MEMS technology
- Development of low power radio technologies
- Advances in low-power embedded microcontrollers





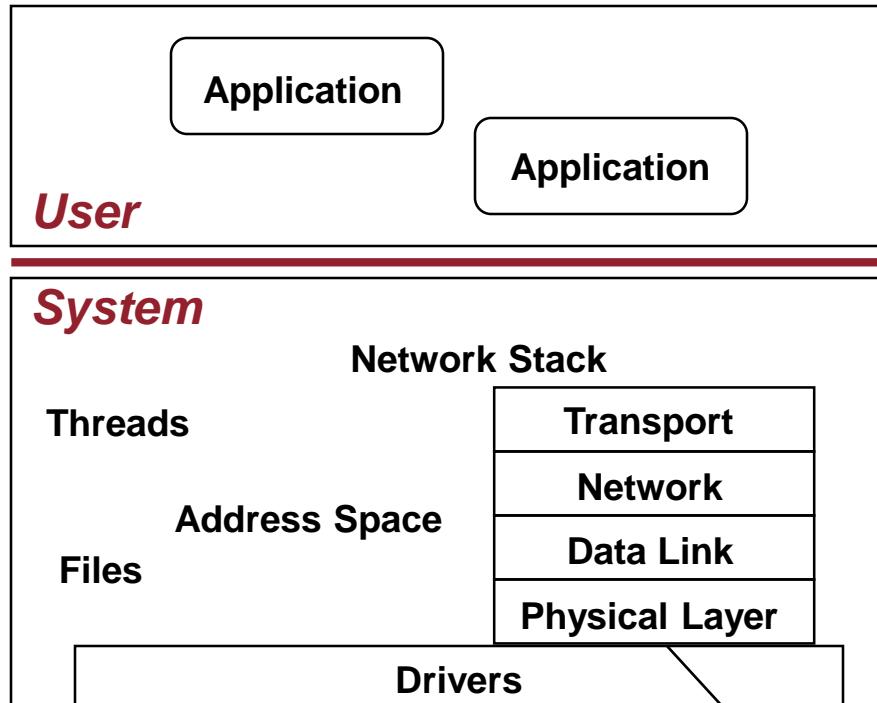
Challenges



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- Deployment
 - Self configuration
 - (Real-time) Operating System
 - Sensor installation
- Wireless Communication
 - Standards
 - Zigbee, IPv6 (6LowPan, RPL)
 - Routing, Clustering, Topology, etc.
- Energy
 - Energy-efficient algorithms
 - Energy harvesting





- Well established layers of abstractions
- Strict boundaries
- Ample resources
- Independent applications at endpoints communicate pt-pt through routers
- Well attended



Choice of Programming Primitives



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- Traditional approaches
 - Command processing loop (wait, request, act, respond)
 - Monolithic event processing
 - Full thread/socket posix regime
- Alternative
 - Provide framework for concurrency and modularity
 - Never poll, never block
 - Interleaving flows, events



Threads

- Thread stacks must be allocated at creation time
- Stack Memory Over-Provisioned
 - No Virtual Memory System
 - No Memory Protection Mechanisms
- Locking for state exclusion
- Stack memory is inaccessible to other threads

Events

- No locking
- Only one running at a time
 - Only one stack
 - Locking rare
- Hard to express some things as state machine
- Problem: Cryptography takes 2 seconds, everything else blocked.
- Solution: Preemptive Threads

- Microthreaded OS (lightweight thread support) and efficient network interfaces
- Two level scheduling structure
 - Long running tasks that can be interrupted by hardware events
- Small, tightly integrated design that allows crossover of software components into hardware





Event-Driven Sensor Access Pattern



- Clock event handler initiates data collection
- Sensor signals data ready event
- Data event handler calls output command
- Device sleeps or handles other activity while waiting
- Conservative send/ack at component boundary

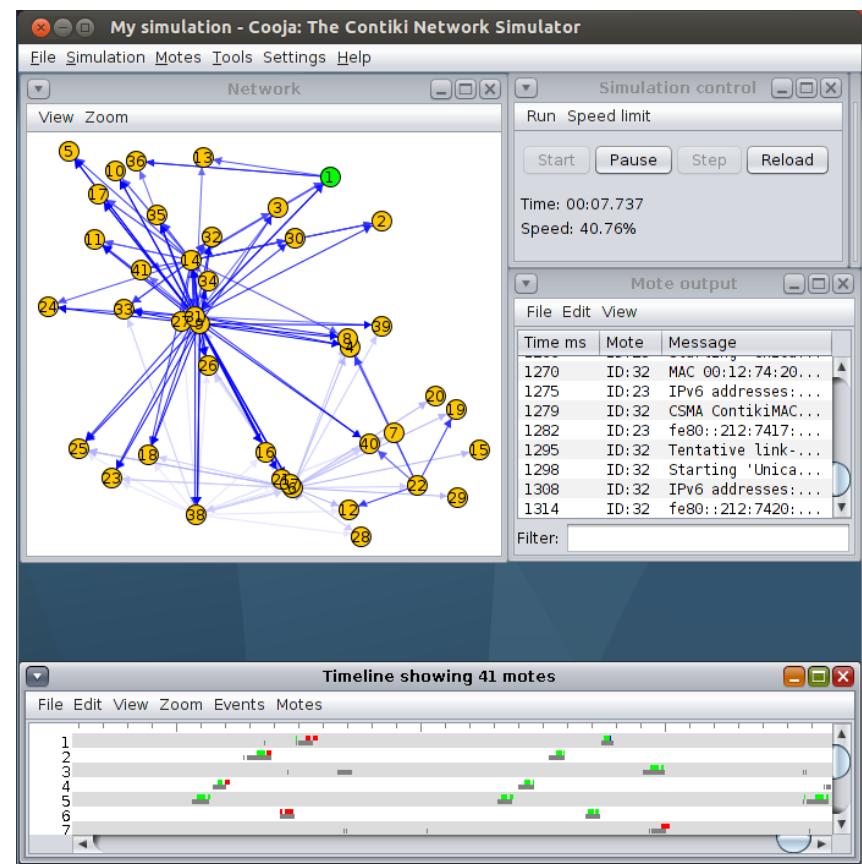
```
command result_t
StdControl.start() {
    return call
Timer.start(TIMER_REPEAT, 200);
}

event result_t Timer.fired() {
    return call
sensor.getData();
}

event result_t
sensor.dataReady(uint16_t data)
{
    display(data)
    return SUCCESS;
}
```



- Dynamic loading of programs (vs. static)
- Multi-threaded concurrency managed execution
 - In addition to event driven
- Available on MSP430, AVR, HC12, Z80, 6502, x86, ...
- Simulation environment available for BSD/Linux/Windows



"Contiki-ipv6-rpl-cooja-simulation" by Adnk - Own work. Licensed under CC BY-SA 3.0 via Wikimedia Commons



Event-based kernel with threads



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- Kernel is event-based
 - Most programs run directly on top of the kernel
- Multi-threading implemented as a library
- Threads only used if explicitly needed
 - Long running computations, ...
- Preemption possible
 - Responsive system with running computations



Multi-Thread API



```
mt_yield();
```

Yield from the running thread.

```
mt_post(id, event, dataptr);
```

Post an event from the running thread.

```
mt_wait(event, dataptr);
```

Wait for an event to be posted to the running thread.

```
mt_exit();
```

Exit the running thread.

```
mt_start(thread, functionptr, dataptr);
```

Start a thread with a specified function call.

```
mt_exec(thread);
```

Execute the specified thread until it yields or is preempted.

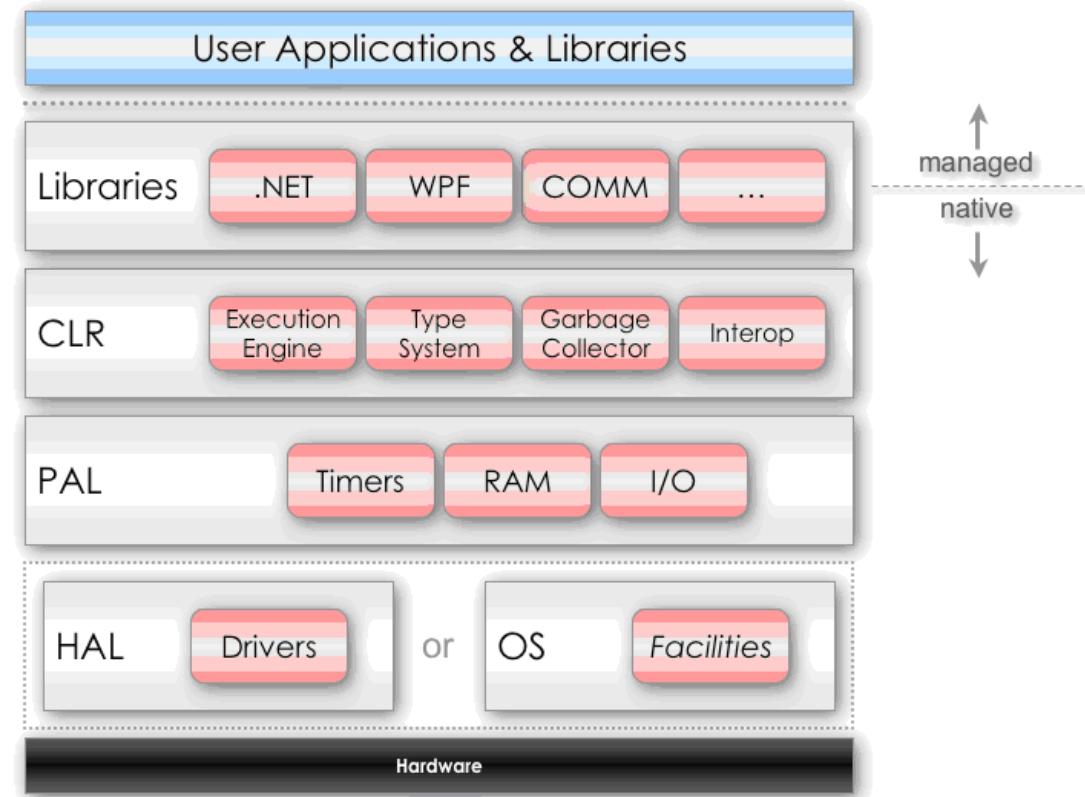
Figure 4. The multi-threading library API.



- .NET MF is a bootable runtime environment tailored for embedded development

- MF services include:

- Boot Code
- Code Execution
- Thread Management
- Memory Management
- Hardware I/O



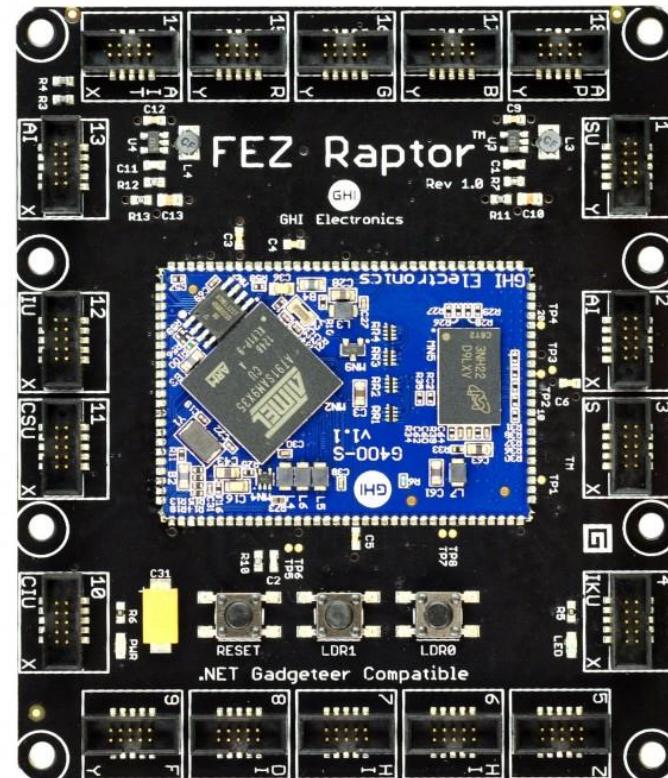


Hardware Abstraction Layer (HAL)



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- Provides an interface to access hardware and peripherals
 - Relevant only for system, not application developers
- Does not require operating system
 - Can run on top of one if available
- Interfaces include:
 - Clock Management
 - Core CPU
 - Communications
 - External Bus Interface Unit (EBIU)
 - Memory Management
 - Power
 - Watchdog Timer
 - Security

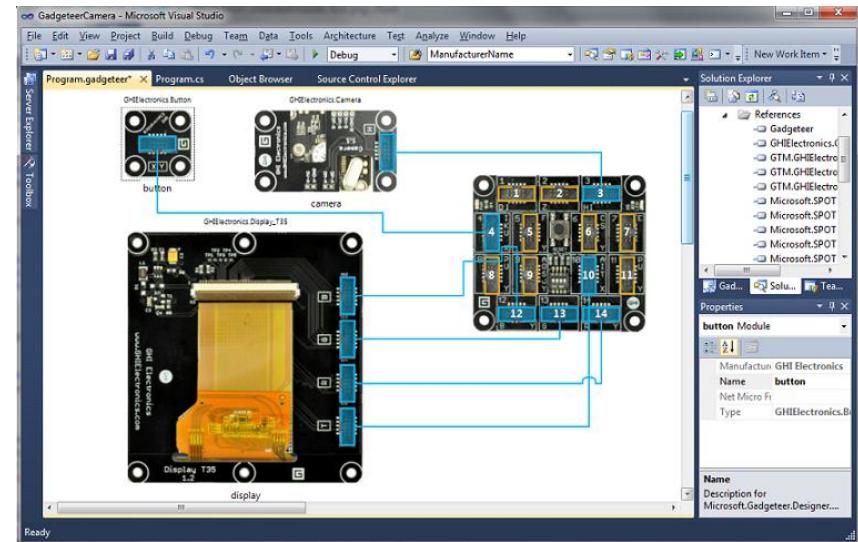




Platform Abstraction Layer (PAL)

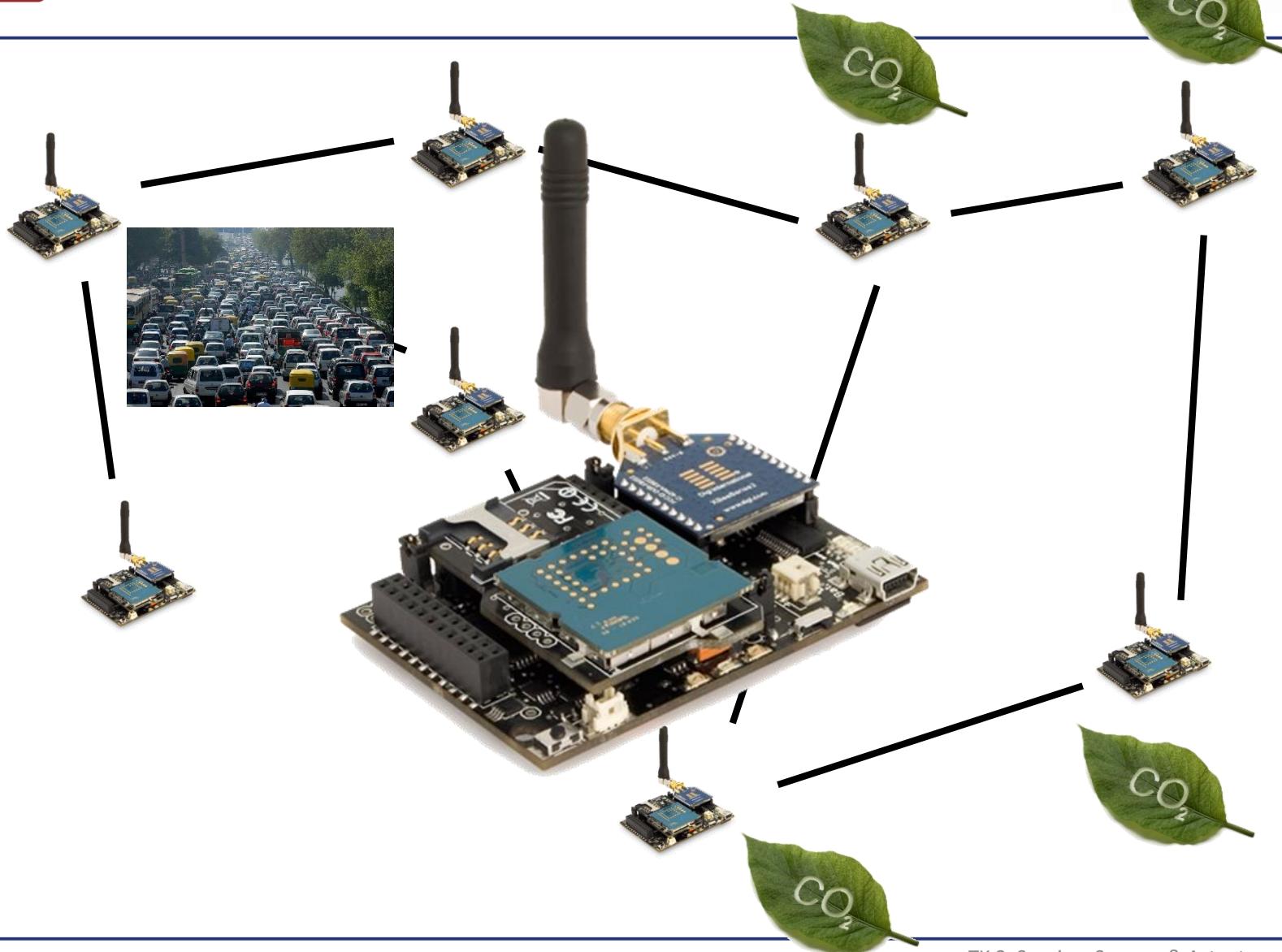


- Provides hardware independent abstractions
 - Used by application developers to access system resources
 - Application calls to PAL managed by Common Language Runtime (CLR)
 - In turn calls HAL drivers to access hardware
 - PAL interfaces include:
 - Time
 - PAL Memory Management
 - Input/Output
 - Events
 - Debugging
 - Storage
 - PAL Communications
 - Asynchronous Procedure Call
 - Bootstrap





Sensor Nodes





Definition

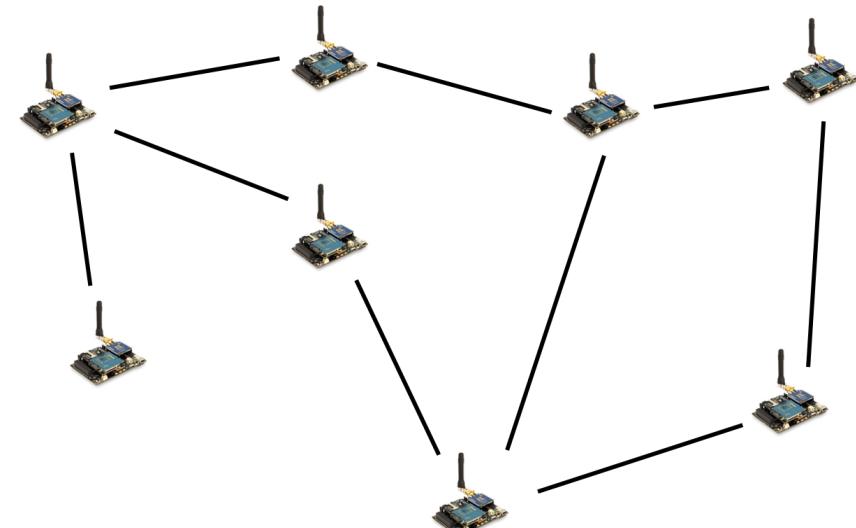


- Wireless Sensor Networks (WSNs):

- Highly distributed networks of small, lightweight wireless nodes,
- Deployed in large numbers,
- Monitors the environment or system by measuring physical parameters such as temperature, pressure, humidity.

- Node:

- sensing + processing + communication





Wireless Sensor Networks



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- Animal tracking & monitoring

- Zebranet (2004) / Great Duck Island (2002) / SWIM (2003)



- Vehicle & people tracking

- Exscale (2004)



- Data centers

- RACNet (2009)



- Wearable WSNs

- Mercury (2009)



- Environmental Sensing

- da_sense (2011)



Wireless Sensor Networks

- Machine and vehicle monitoring
 - Sensor nodes in moveable parts
 - Monitoring of temperatures, fluid levels, ...
 - Calculation of maintenance intervals
- Smart Cities
 - Intelligent buildings, building monitoring
 - Intrusion detection, mechanical stress detection
 - Smart heating, ventilating, air conditioning
- Health & medicine
 - Long-term monitoring of patients with minimal restrictions
 - Assisted Living
- Environmental monitoring, person tracking
 - Monitoring of wildlife and national parks
 - Cheap and (almost) invisible person monitoring
 - Monitoring demilitarized zones, ...
- Logistics
 - Dataloggers: Temperature, Humidity, Acceleration/Shock
 - ... and many more





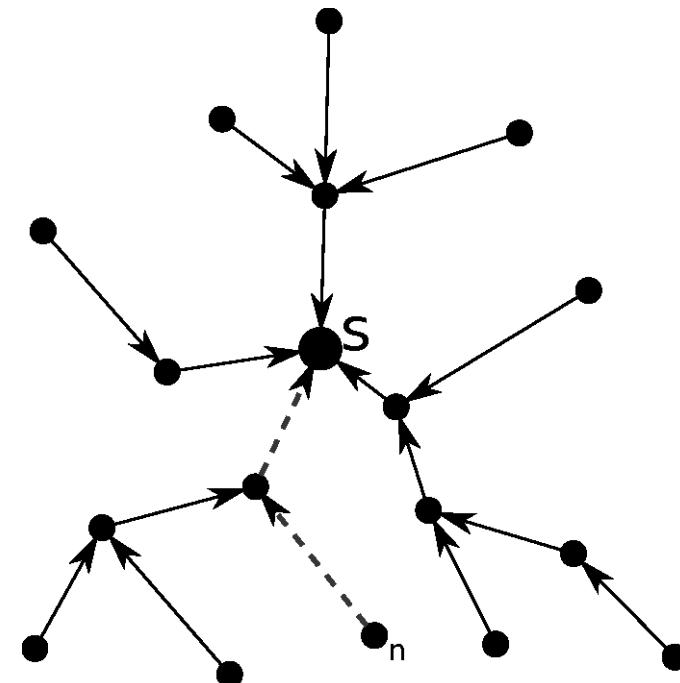
Wireless Sensor Networks

- Periodic Reporting
 - Plant Monitoring
 - Environmental Monitoring
- Event Detection
 - Fire, Chemicals, etc.
- Tracking
 - Person Tracking
 - Vehicle Tracking





- Most common application: Periodic reporting
- Two quality metrics
 - Frequent data samples
 - Sampling rate should be high /Energy consumption should be low
 - Coverage problems





Coverage problem



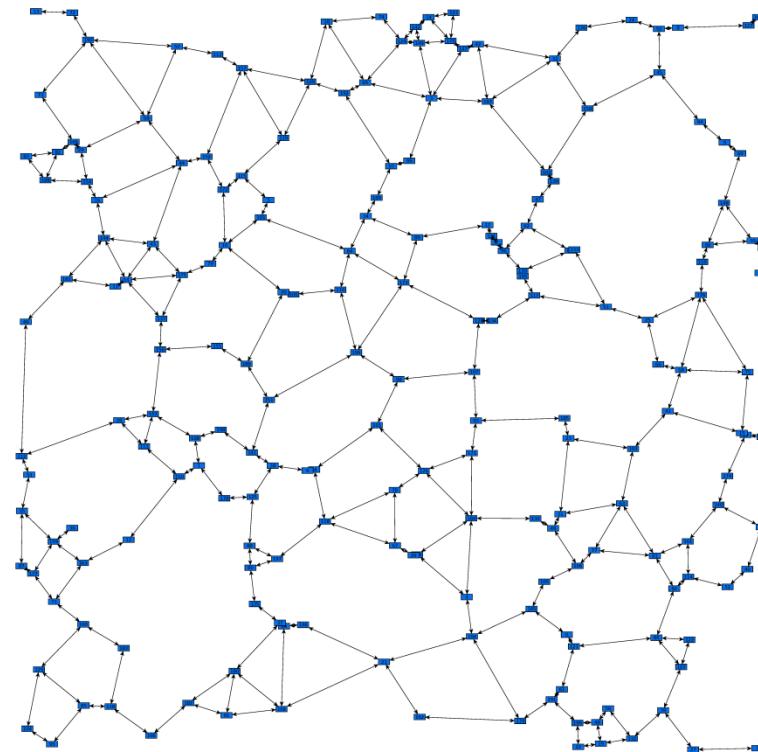
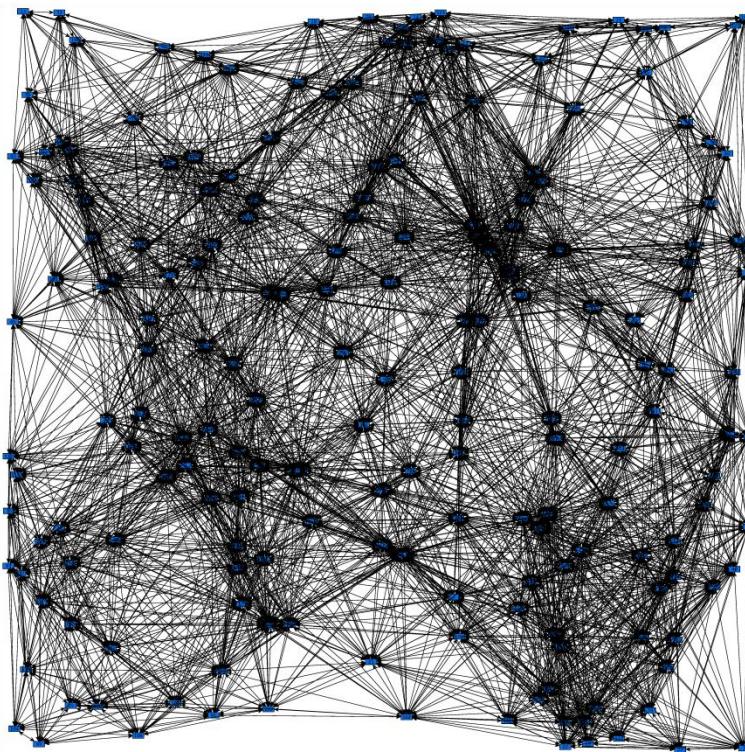
- Definition: the measurements of quality of service that can be provided by a particular sensor network
- Area coverage: Cover a given area
- Point coverage: Cover a set of (static) targets
- Detectability: Determine the maximal support / breach paths that traverse a sensor field



Topology control



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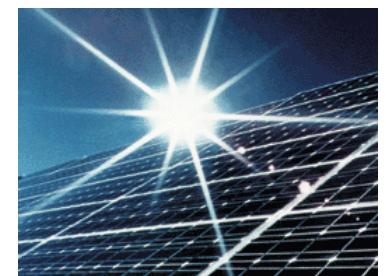




Frequent data sampling



- Most common application: Periodic reporting
 - Frequent data samples
 - Data density should be high, therefore high frequency
 - Energy consumption should be low, therefore low frequency
- Energy-efficiency
 - Given a sampling rate s how can the network survive as long as possible
- Energy-harvesting
 - Use solar cells (or other energy sources)
 - Now we might reach perpetual operation at sampling rate s
 - New question: How high can s be, without depleting one sensor node!





Solar-aware distributed flow



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- A node needs energy for:
 - Own sampling
 - Own messages
 - Messages of other nodes!
- How can we determine the other nodes routed through us?
- How can we determine the energy available to us over time?
- How can we calculate a sampling rate for us and all nodes routed through us?



Solar-aware distributed flow

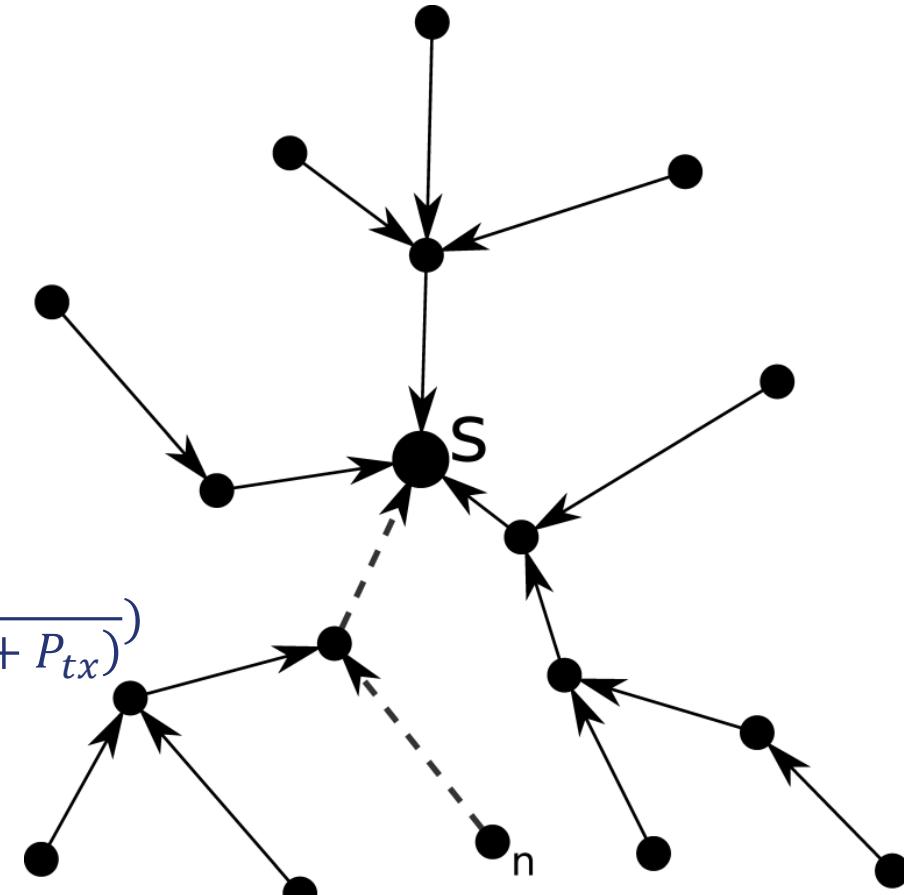


- Predict available energy c
 - Solar-energy is predictable!
- Energy consumption
 - Sensor sampling (P_{sense})
 - Sending messages (P_{tx})
 - Receiving predecessor messages (P_{rx})

- Two bounds
 - Own available energy
 - Allowed flow from successor

$$x = \min\left(\frac{f_a}{n + 1}, \frac{c}{n * (P_{rx} + P_{tx}) + (P_{sense} + P_{tx})}\right)$$

- Allocate energy
 - Set own sampling rate
 - Send control messages to direct predecessors





Solar-aware distributed flow



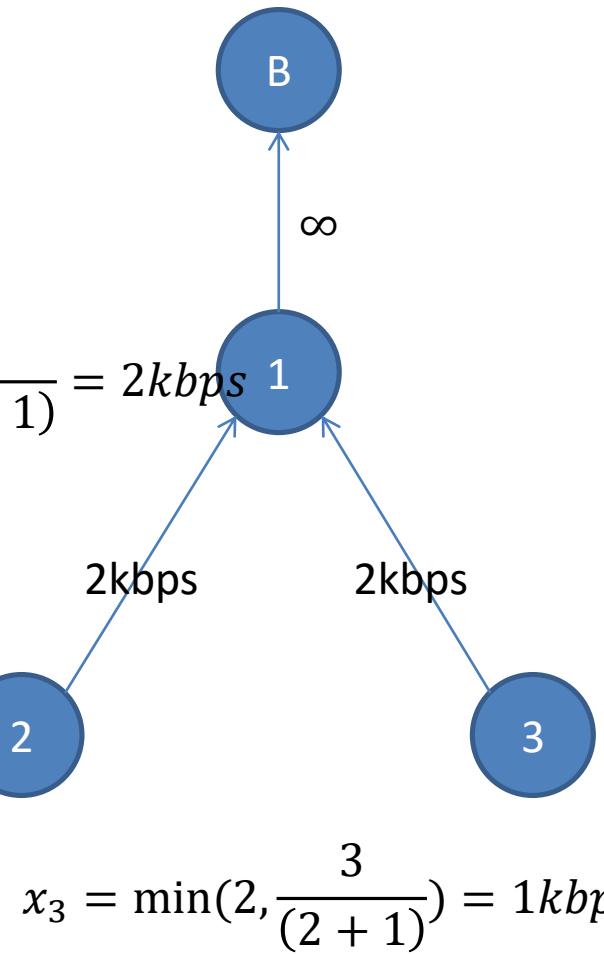
- $P_{rx} = 1,5 \text{ mW}/\text{kbps}$
- $P_{tx} = 2 \text{ mW}/\text{kbps}$
- $P_{sense} = 1 \text{ mW}/\text{kbps}$

- $c_1 = 20 \text{ mW}$
- $c_2 = 9 \text{ mW}$
- $c_3 = 3 \text{ mW}$

$$x_1 = \frac{20}{2(2 + 1,5) + (2 + 1)} = 2 \text{ kbps}$$

$$x_2 = \min\left(2, \frac{9}{(2 + 1)}\right) = 2 \text{ kbps}$$

$$x = \min\left(\frac{f_a}{n + 1}, \frac{c}{n * (P_{rx} + P_{tx}) + (P_{sense} + P_{tx})}\right)$$





Energy Harvesting



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- Solar Energy
 - Predictable, efficient
- Wind Energy
 - Bulky, less predictable
- Vibrations
 - Machines, unpredictable
- ...



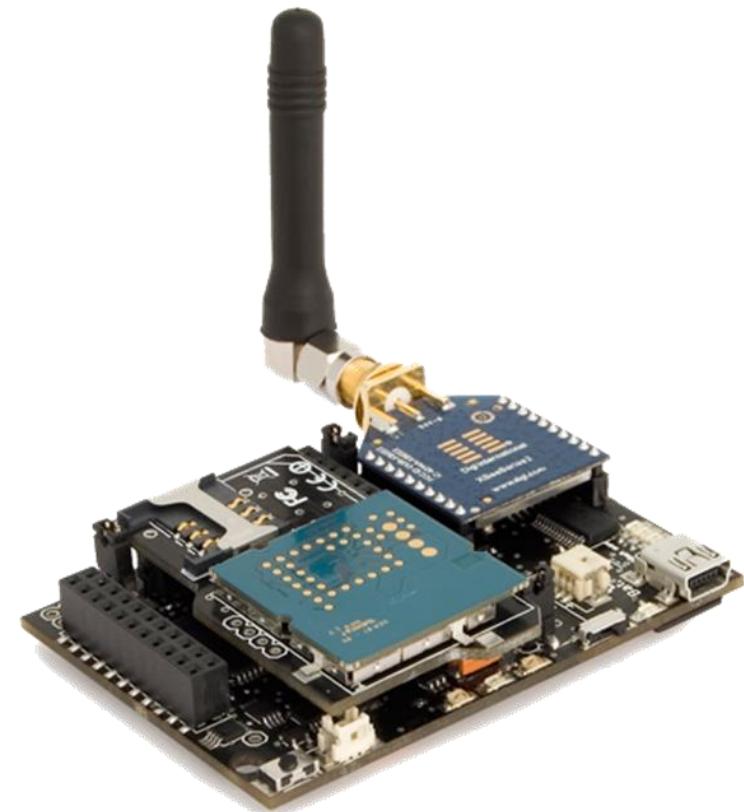


Challenges



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- Deployment
 - Self configuration
 - (Real-time) Operating System
 - Sensor installation
- Wireless Communication
 - Standards
 - Zigbee, IPv6 (6LowPan, RPL)
 - Routing, Clustering, Topology, etc.
- Energy
 - Energy-efficient algorithms
 - Energy harvesting



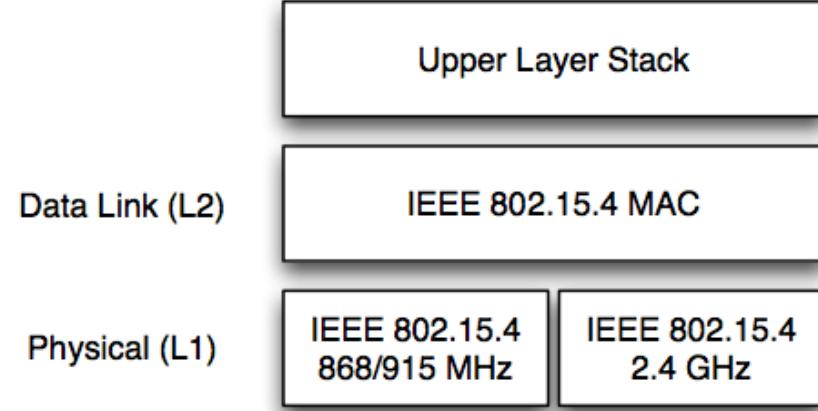


- Bluetooth - Desktop / Personal Area Net: few, „valued“ devices
- ZigBee – scales up to sensor networks („smart dust“) in terms of power, #of nodes, management ...

Market Name Standard	GPRS/UMTS (TDMA/CDMA)	Wi-Fi™ 802.11b	Bluetooth™ 802.15.1	ZigBee™ 802.15.4
Application Focus	LongDist. Voice/Data	Web, Email, Video	Cable Replacement	Monitoring & Cntrl
System Resources	16MB+	1MB+	250KB+	4KB - 32KB
Battery Life (days)	1-7	.5 - 5	1 - 7	100 - 1,000+
Network Size	(1)	(32)	7	255 / 65,000
Bandwidth (kb/s)	14 - 2000	11,000+	720	20 - 250
Transmission Range (m)	1,000+	1 - 100	1 - 10+	1 - 100+
Success Metrics	Reach, Quality	Speed, Flexibility	Cost, Convenience	Reliab., Power, Cost



- Important standard for home networking, industrial control and building automation
- Three PHY modes
 - 20 kbps at 868 MHz
 - 40 kbps at 915 MHz
 - 250 kbps at 2.4 GHz (DSSS)
- Beaconless mode
 - Simple CSMA algorithm
- Beacon mode with superframe
 - Hybrid TDMA-CSMA algorithm
- Up to 64k nodes with 16-bit addresses
- Extensions to the standard
 - IEEE 802.15.4a, 802.15.4e, 802.15.5





ZigBee Node Types, Protocol Stack



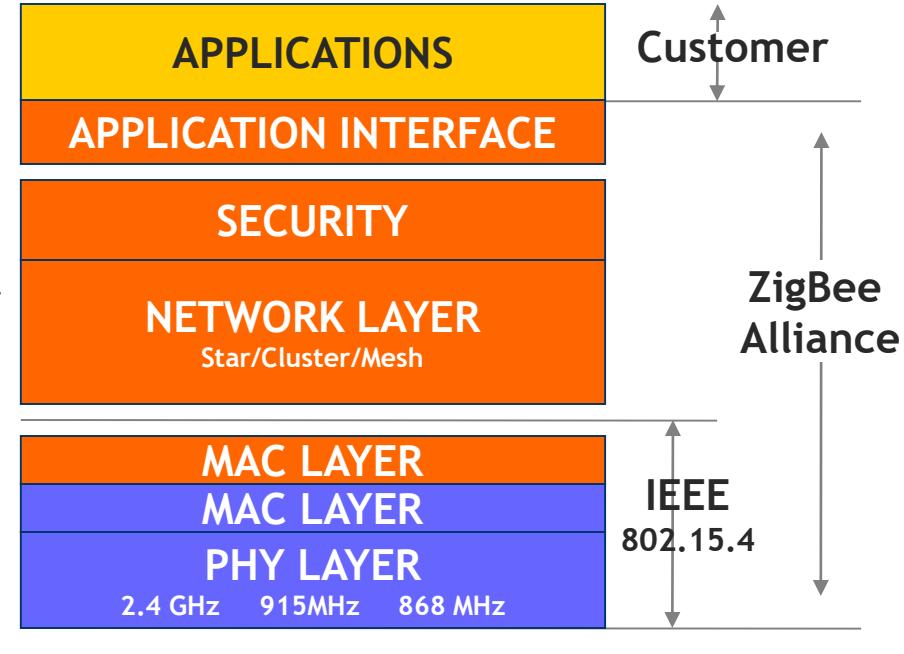
a) FFN vs. RFN: Full Function Nodes– Reduced Function Nodes

b) Coordinator vs. Router vs. EndNode

Only EndNode may (!) be RFN

- Microcontroller utilized
- FFN protocol stack <32 k
- RFN protocol stack ~4k
- Coordinators: extra RAM (DBs f. nodes/transactions/pairing)
- PHY: OQPSK (2.4GHz); CDMA
- MAC: CSMA/CA

ZigBee Net can be replaced w/ IEEE802 MAC + IP

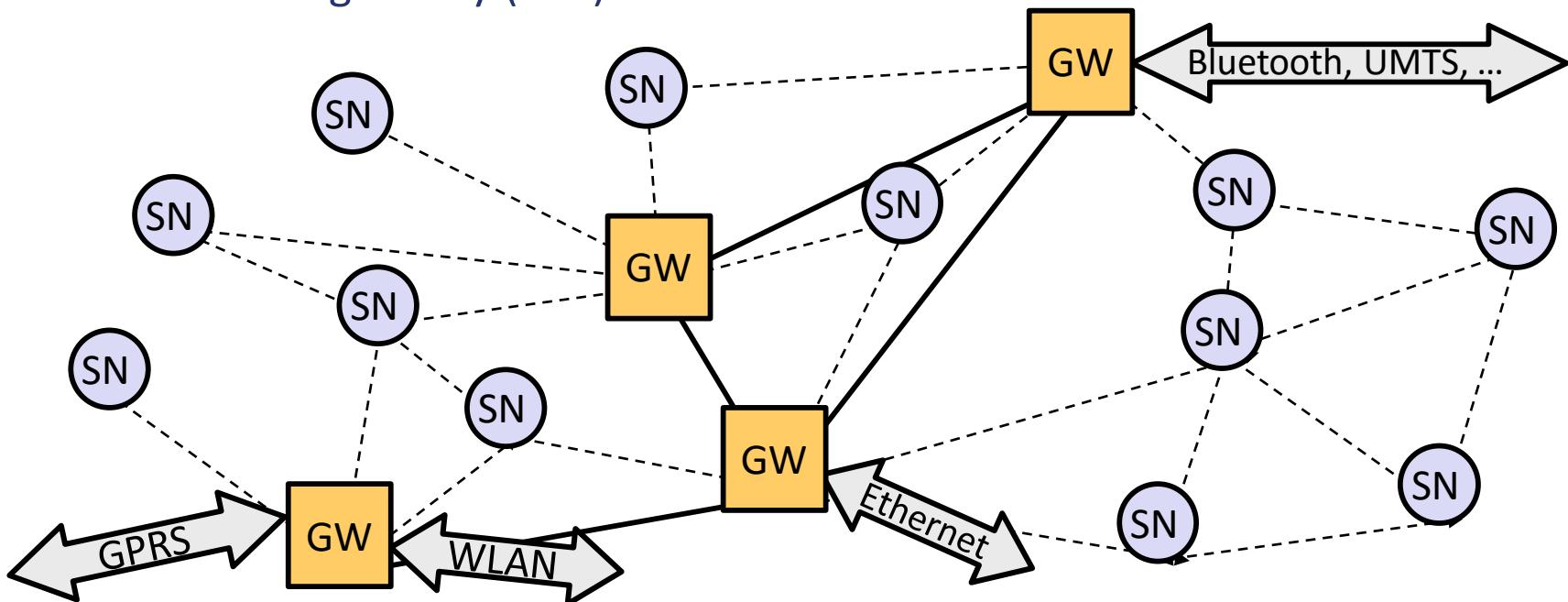


Application ZigBee Stack Silicon



■ Typical topology

- Sensor nodes (SN) monitor and control the environment
- Nodes process data and forward data via radio
- Integration into the environment, typically attached to other networks over a gateway (GW)

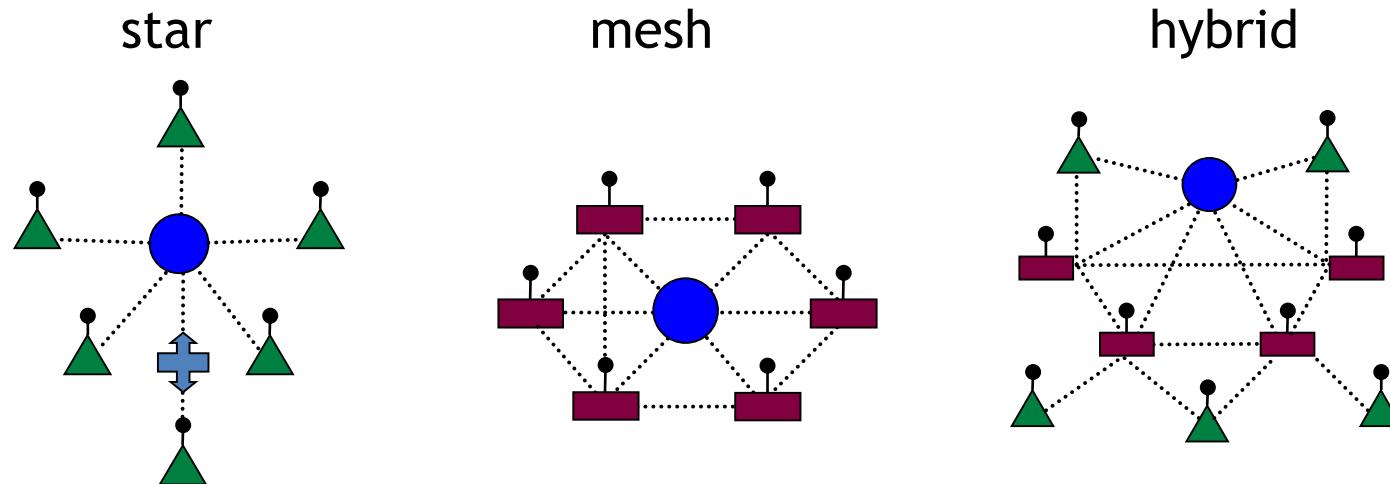




ZigBee: More Characteristics



- 3 Bands: ISM-Europe (868 MHz) / ISM US (915) / 2.4 GHz →
 - Different no. of available channels (1/10/16), speeds (20/40/250 kbps)
 - no. of chips/symbol in CDMA (15/15/32 – note: WLAN has 11)
 - Other limitations e.g. duty cycling for 868 MHz in Europe
- 3 network types, made of:



- *star*: low battery → low reliability; *mesh*: opposite (+routg complex!)
- *hybrid*: tradeoff possible



- Two channel access mechanisms
- Non-beacon network: unslotted CSMA/CA
 - Acknowledgement for successfully received packets
- Beacon-enabled network
 - ZigBee router transmits periodic beacons
 - 15ms to 252sec ($15.38\text{ms} \times 2n$ where $0 < n < 14$)
 - 16 equal-width time slots between beacons
 - Channel access in each time slot is contention free
 - Nodes can sync with beacons and may sleep between beacons



- Low power
- Many Nodes
- Based on 802.15.4
- Some security

- Proprietary stack up to the application layer
- Special nodes
- Limited choice of network protocols
- Interoperability?

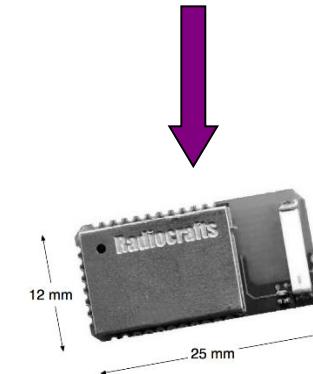
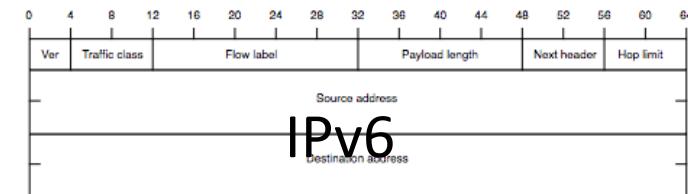




What is 6LoWPAN?



- IPv6 over Low-Power wireless Area Networks
- Defined by IETF standards
 - RFC 4919, 4944
 - draft-ietf-6lowpan-hc and -nd
 - draft-ietf-roll-rpl
- Stateless header compression
- Enables a standard socket API
- Minimal use of code and memory
- Direct end-to-end Internet integration
 - Multiple topology options

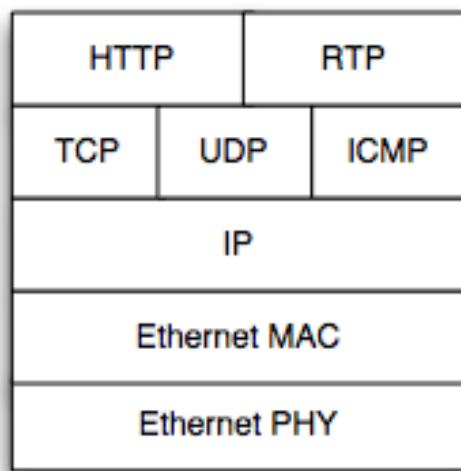




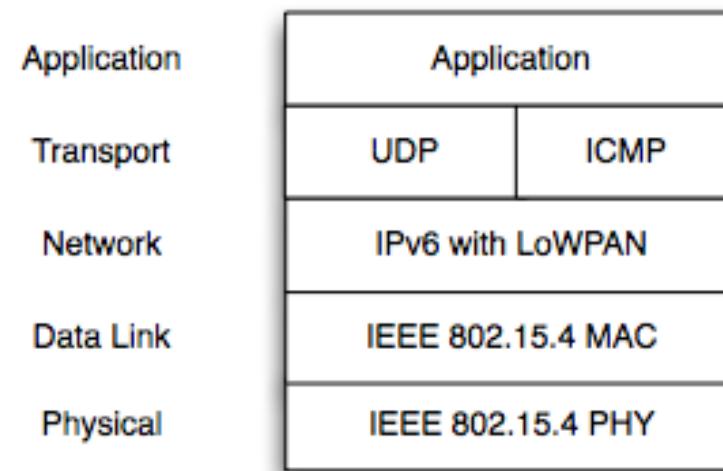
Protocol Stack



TCP/IP Protocol Stack



6LoWPAN Protocol Stack





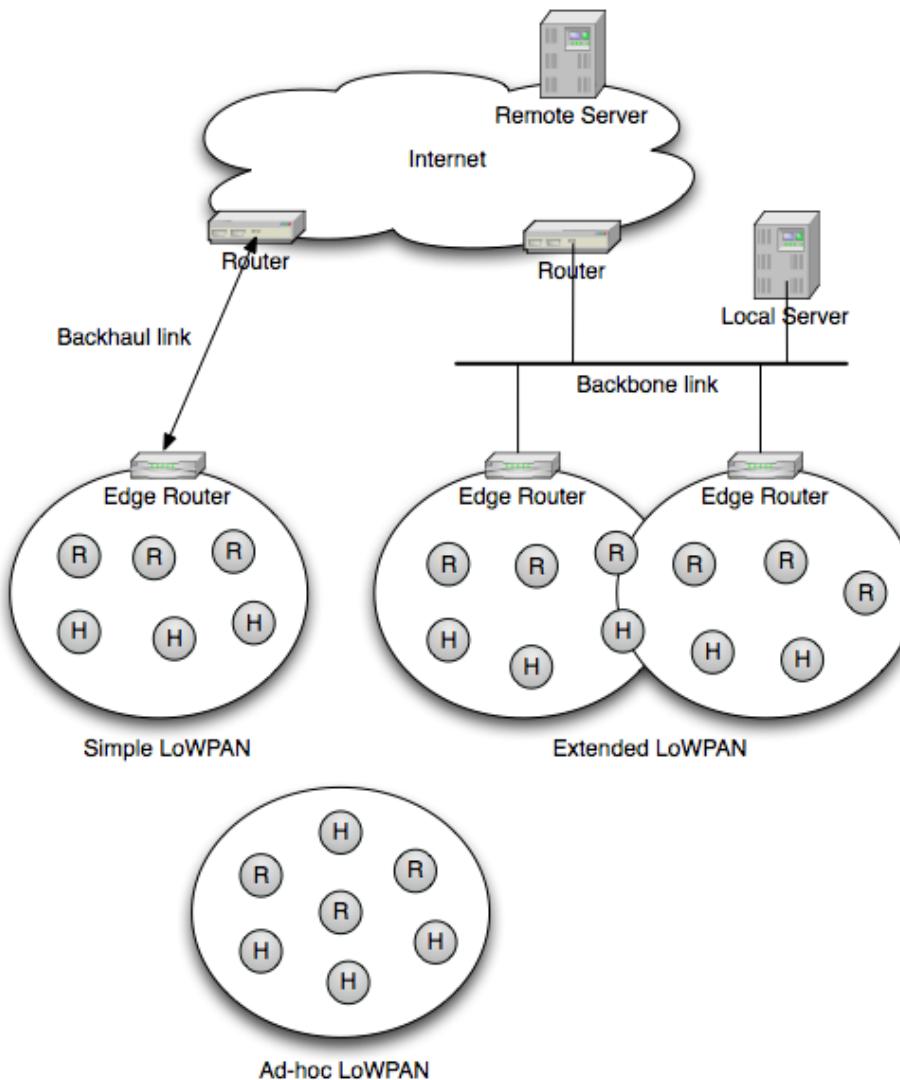
Features



- Support for e.g. 64-bit and 16-bit 802.15.4 addressing
- Useful with low-power link layers such as IEEE 802.15.4, narrowband ISM and power-line communications
- Efficient header compression
 - IPv6 base and extension headers, UDP header
- Network autoconfiguration using neighbor discovery
- Unicast, multicast and broadcast support
 - Multicast is compressed and mapped to broadcast
- Fragmentation
 - 1280 byte IPv6 MTU -> 127 byte 802.15.4 frames
- Support for IP routing (e.g. IETF RPL)
- Support for use of link-layer mesh (e.g. 802.15.5)



Architecture





- LoWPANs are stub networks
- Simple LoWPAN
 - Single Edge Router
- Extended LoWPAN
 - Multiple Edge Routers with common backbone link
- Ad-hoc LoWPAN
 - No route outside the LoWPAN
- Internet Integration issues
 - Maximum transmission unit
 - Application protocols
 - IPv4 interconnectivity
 - Firewalls and NATs
 - Security

IPv6	
Ethernet MAC	LoWPAN Adaptation
	IEEE 802.15.4 MAC
Ethernet PHY	IEEE 802.15.4 PHY

IPv6-LoWPAN Router Stack

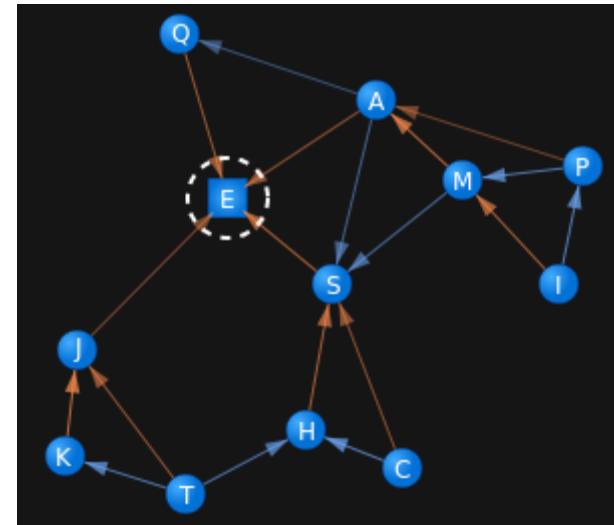


Routing Protocol for Low-Power and Lossy Networks (RPL)



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- Works on top of 6LoWPAN / IPv6
- IETF Standard RFC 6550
- RPL builds a DODAG
 - One per base station
- Parent is picked based on weight
 - Hop to destination + custom function





Challenges



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Wireless Sensor Networks

- Periodic Reporting
 - Plant Monitoring
 - Environmental Monitoring
- Event Detection
 - Fire, Chemicals, etc.
- Tracking
 - Person Tracking
 - Vehicle Tracking



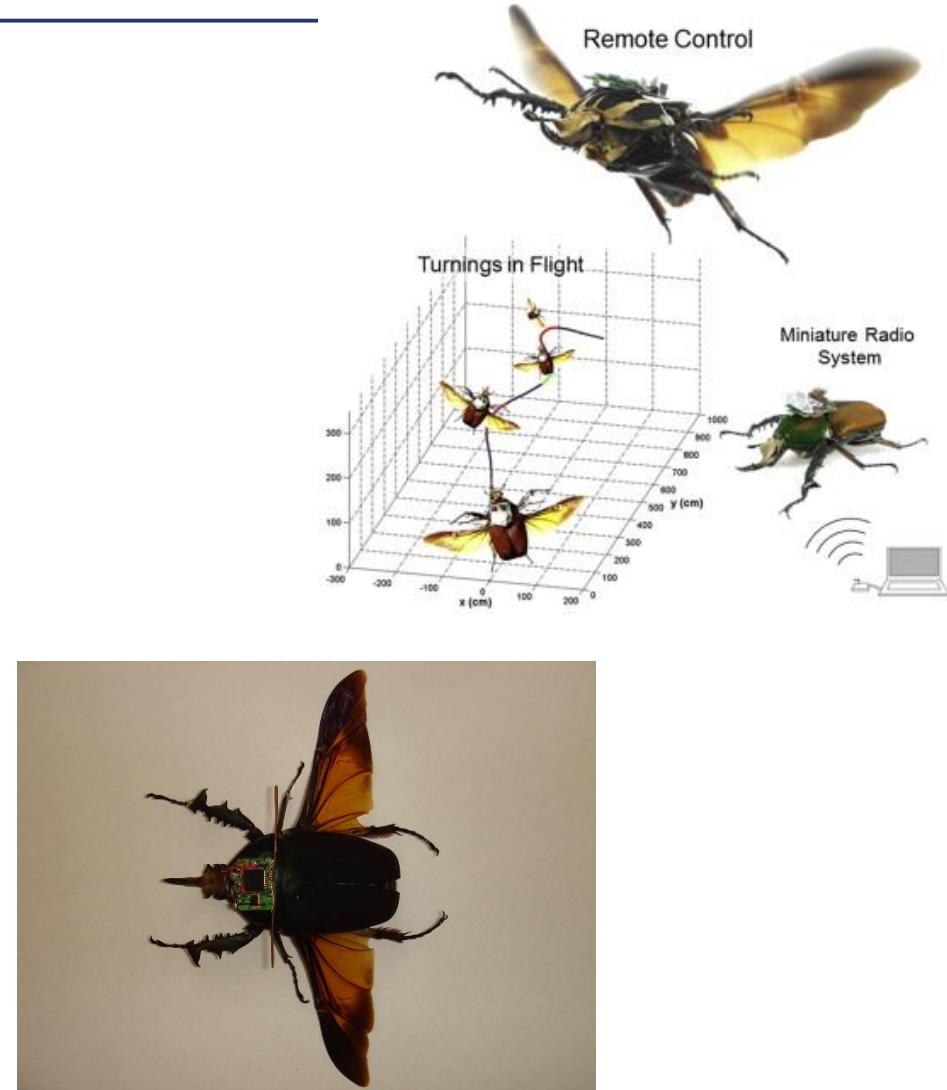


Stuff we haven't talked about



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- Personal Sensor Networks
 - Connected wearables
- Miniature Air Vehicles (MAV)
 - Drones
 - Insects
 - ...





Cyber-Physical (cy-phy)
Systems (CPS) are
integrations of
computation with physical
processes [Edward Lee,
2006].





- Production resources are self-configuring and distributed social machines
- Personalization
- 3D-Printers





Structural safety



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- Sensors + data analysis



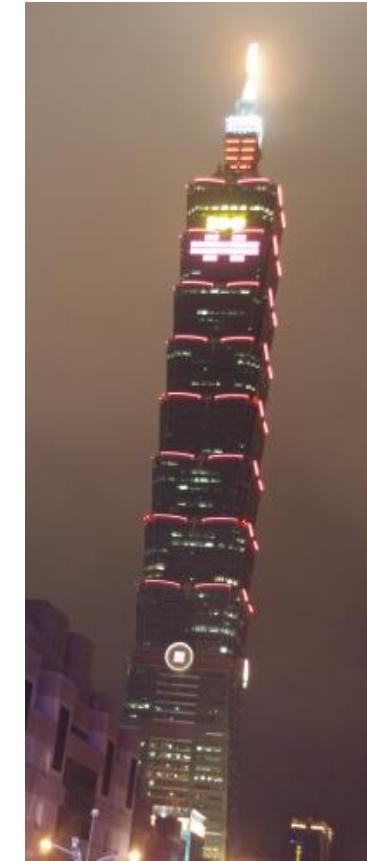
Möhne lake dam



Kilauea, Hawaii



Bridge at Vancouver



Taipei 101



- Zero energy building, generates as much energy as it consumes
- Provides safety and security
- Supports owners
- Provides maximum comfort
- ambient assisted living





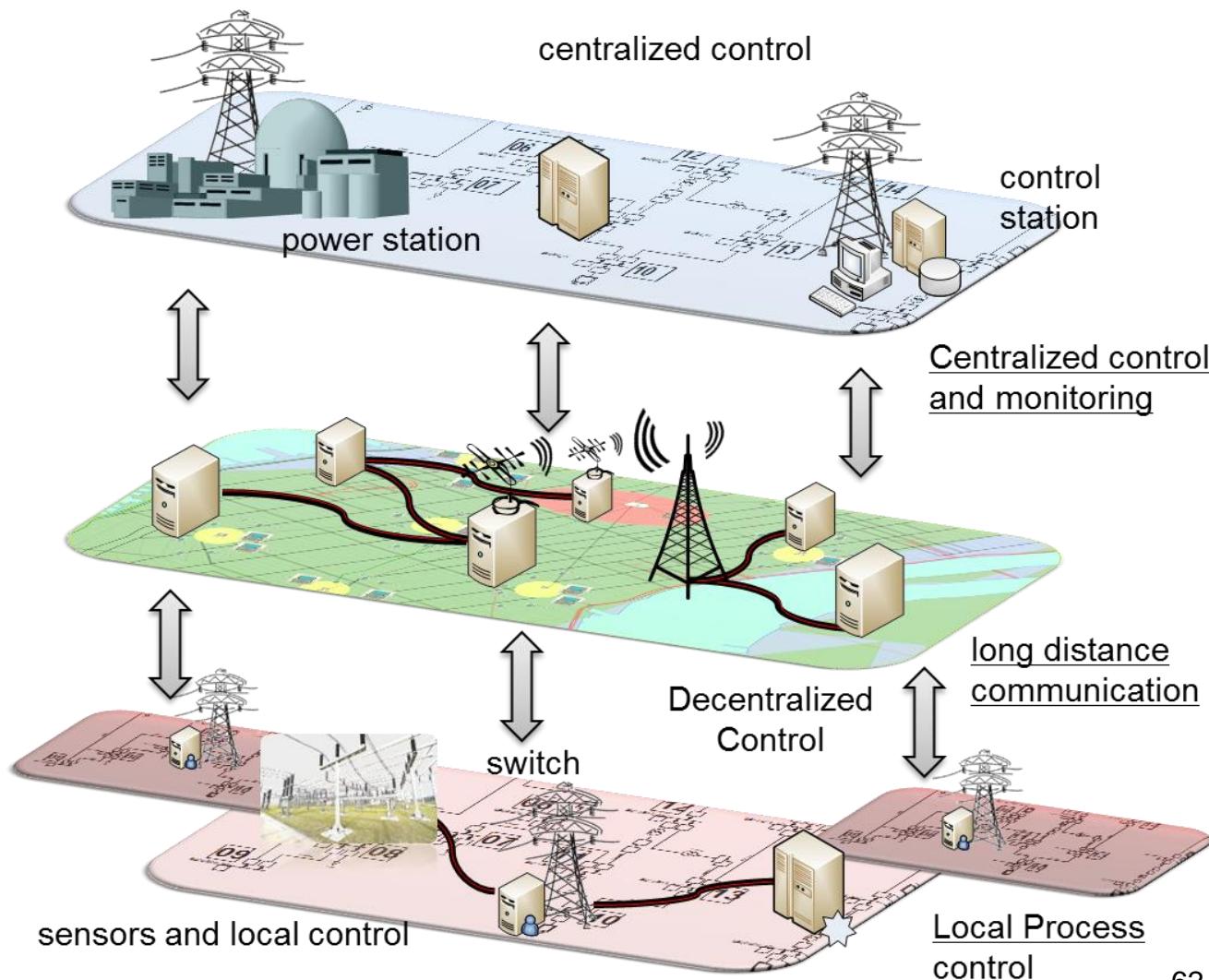
- Diagnosis
- Support of therapy
- Evaluation
- Risk analysis
- Information about patients

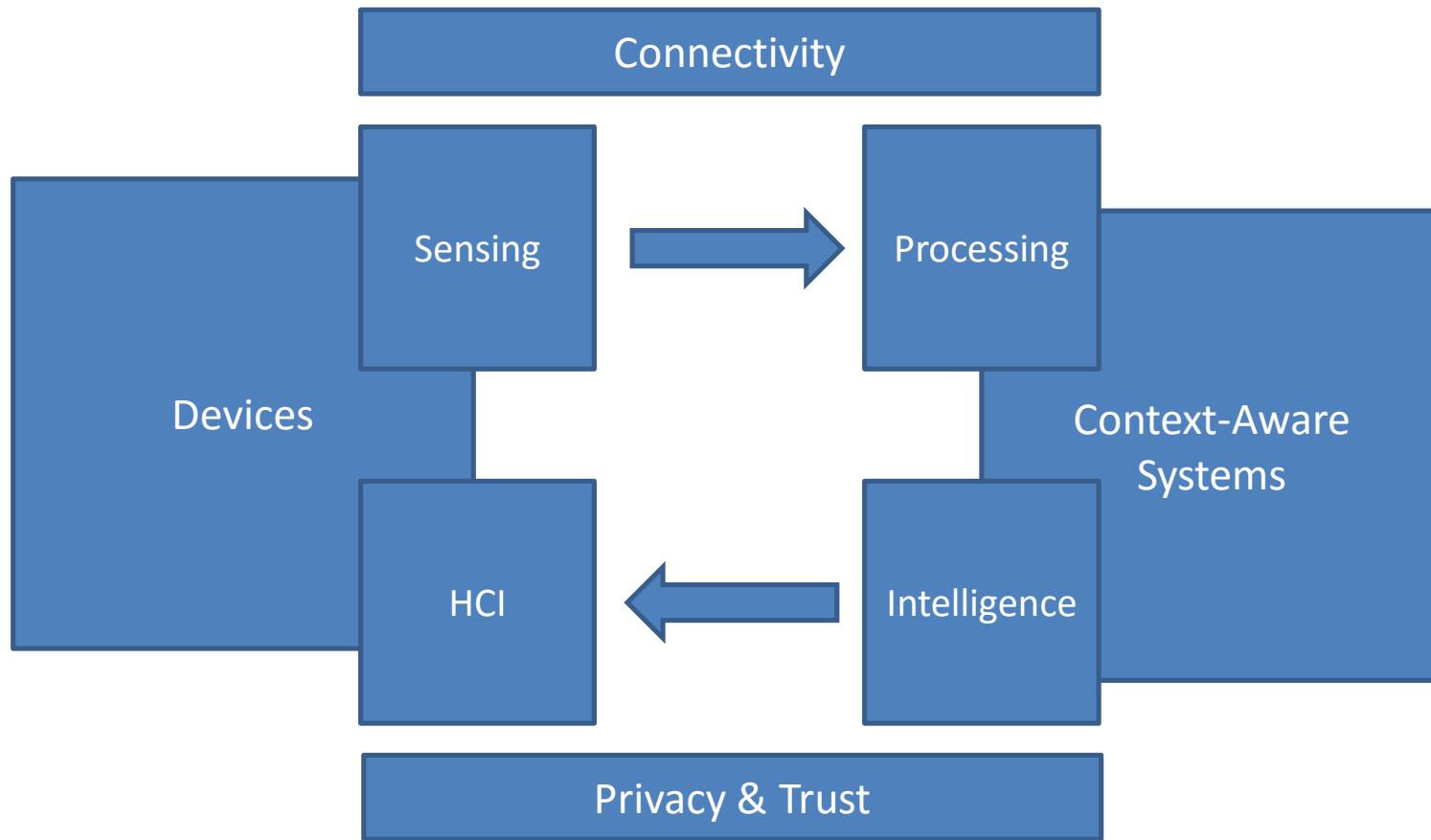
- Personalized Medicine





Smart Grid

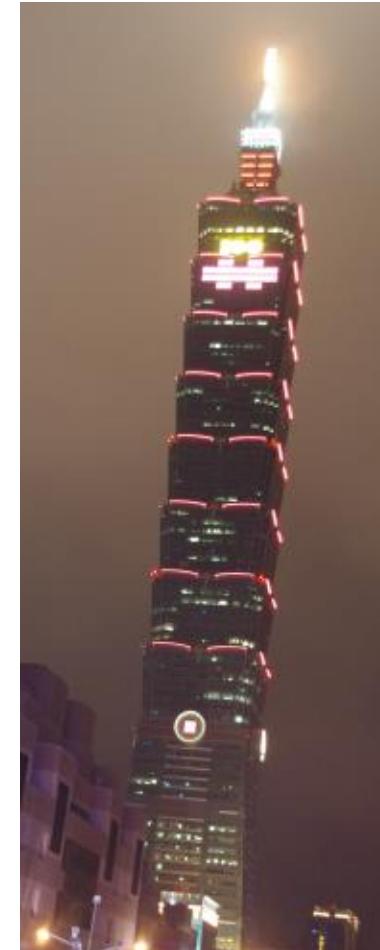






- Fast reaction times
 - Real-time constraints
- Humans out of the loop
- Safety, security

- Same building blocks
- Enabled by connectivity & smaller, more powerful devices



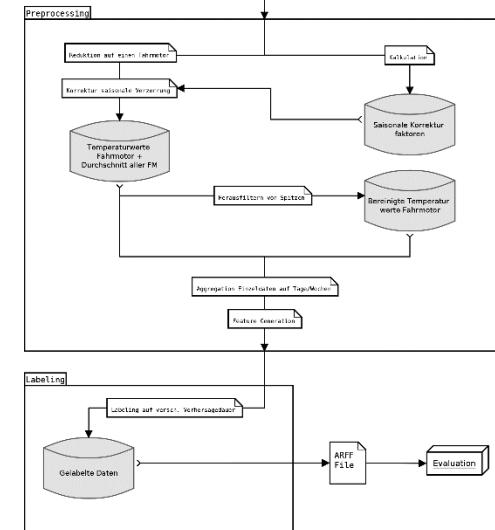
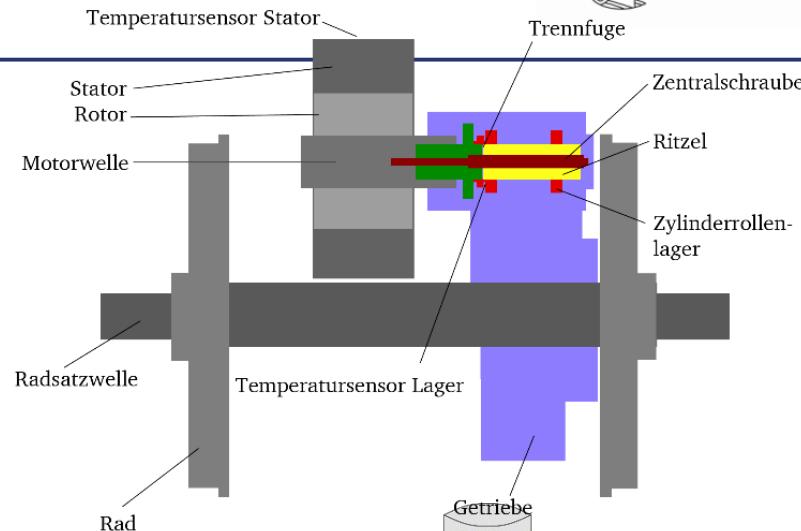


Predictive Maintenance



- Predictive Analytics: Using diagnosis, sensor, and maintenance logs to predict future failures

- Example: Failure of central screw breaks the complete engine
 - Cost ration (Repair / Maintenance) 50:1
 - Two temperature sensors





Summary



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- Embedded Systems
- Sensor Nodes
- Wireless Sensor Networks
- Cyber-Physical Systems

