

### Multiverse Debugging

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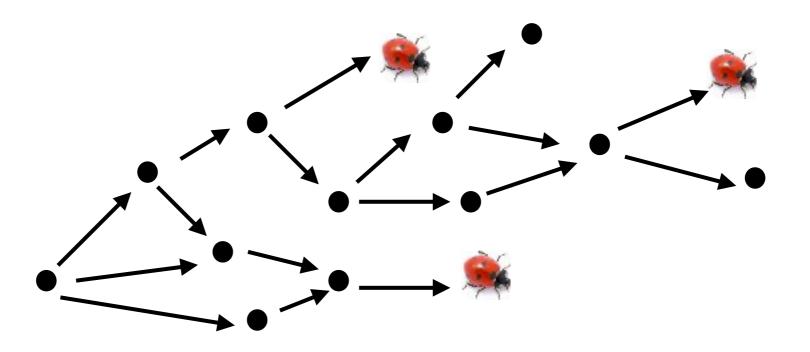




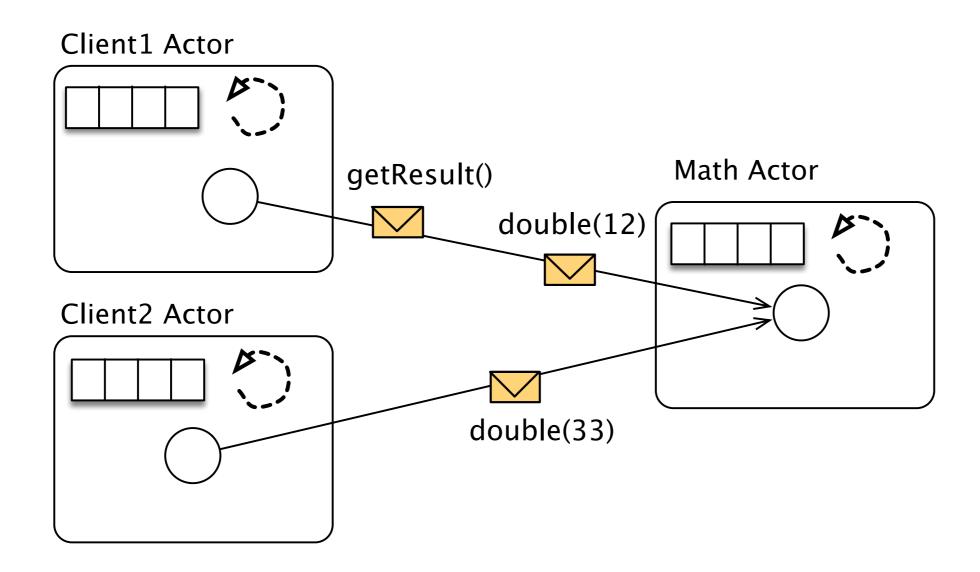


#### Goal

- To build a debugger for non-deterministic programs that
  - is probe-effect free, and
  - is able to explore the space of all possible bugs



# Running Example





### Running Example in AmbientTalk

```
def makeMath() {
    actor:{
        def result := 0;
        def double(x){result := x+x};
        def getResult(){result};
};
def makeClient1(math){
    actor:{ |math|
        def start(){
                 math<-double(12);</pre>
                 when: math<-getResult()@FutureMessage becomes: {|res|</pre>
                     system.println(res);
                 }}}
};
def makeClient2(math){
    actor: { |math|
        def start(){ math<-double(33) }}</pre>
};
def math := makeMath();
def client1 := makeClient1(math);
def client2 := makeClient2(math);
client1<-start();</pre>
client2<-start();</pre>
```

### Bad Message Interleaving

```
def makeMath() {
    actor:{
        def result := 0;
        def double(x){result := x+x};
        def getResult(){result};
    }
};
```

Faulty Interleaving	Correct Interleaving	Correct Interleaving
client 1 - double(12)	client 1 - double(12)	client 2 - double(33)
client 2 - double(33)	<pre>client 1 - getResult() -&gt; 24</pre>	client 1 - double(12)
<pre>client 1 - getResult() -&gt; 66</pre>	client 2 - double(33)	<pre>client 1 - getResult() -&gt; 24</pre>

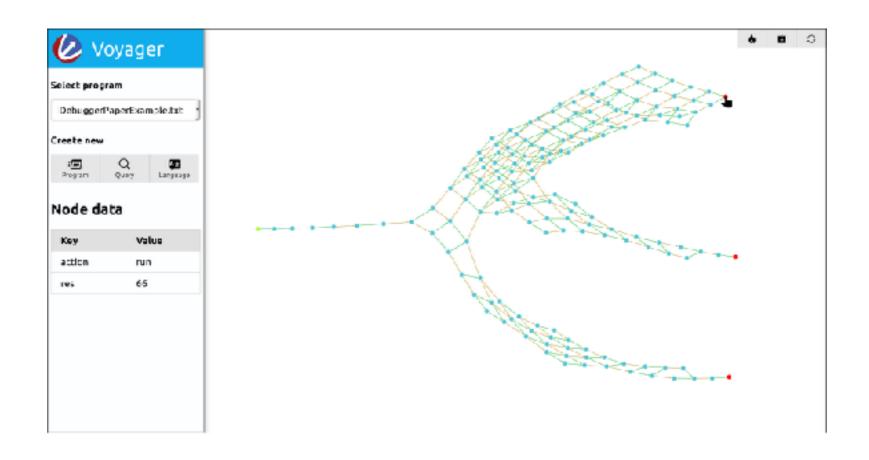
time



### Multiverse Debugging

#### **Properties:**

- 1. Observe all possible paths of the program execution
- 2. One step leads to a possible set of *universes*, i.e. paths of execution





## Multiverse Debugging Recipe

- 1. Operational semantics of the **non-deterministic base language**.
- 2. Operational semantics of the **debugger** in terms of the base-level semantics.
  - Configuration that a debugger needs to keep track of in order to debug a base level program (including the base level semantics).
  - **Debugging operations** of the debugger, in terms of the base-level semantics.



# Featherweight AmbientTalk



```
K \in \mathbf{Configuration} ::= A
                                                                                          Configurations
       a \in A \subseteq \mathbf{Actor} ::= \mathcal{A}\langle \iota_a, O, Q, e \rangle
                                                                                                       Actors
                    Object ::= \mathcal{O}\langle\iota_o, t, F, M\rangle
                                                                                                     Objects
                   t \in \text{Tag} ::= O \mid I
                                                                                                Object tags
                    Future ::= \mathcal{F}\langle \iota_f, Q, v \rangle
                                                                                                     Futures
                 Resolver ::- \mathcal{R}\langle \iota_r, \iota_f \rangle
                                                                                                  Resolvers
         \mathbf{m} \in \mathbf{Message} \quad :: - \quad \mathcal{M}\langle v, m, \overline{v} \rangle
                                                                                                  Messages
            Q \in \mathbf{Queue}
                                    := \overline{m}
                                                                                                      Queues
         M \subseteq Method
                                    := m(\overline{x})\{e\}
                                                                                                    Methods
              F \subseteq \mathbf{Field} ::= f := v
                                                                                                        Fields
               v \in Value ::= r \mid \text{null} \mid \epsilon
                                                                                                       Values
        r \in \mathbf{Reference} ::= \iota_a.\iota_o \mid \iota_a.\iota_f \mid \iota_a.\iota_r
                                                                                                References
        e \in E \subseteq \mathbf{Expr} ::= \ldots \mid r
                                                                                Runtime Expressions
                         o \in O \subseteq \mathbf{Object} \cup \mathbf{Future} \cup \mathbf{Resolver}
                               \iota_a \in \mathbf{ActorId}, \iota_o \in \mathbf{ObjectId}
     \iota_f \in \text{FutureId} \subset \text{ObjectId}, \iota_r \in \text{ResolverId} \subset \text{ObjectId}
```



Van Cutsem T., Gonzalez Boix E., Scholliers C, Lombide Carreton A., Harnie D., Pinte K., and De Meuter W., 2014. *AmbientTalk: programming responsive mobile peer-to-peer applications with actors.* Computer Languages, Systems and Structures 40, 3–4 (2014), 112–136.



# Voyager



$$\mathcal{D}\langle B_p, B_c, d_s, C, A_s, K \rangle \to_d \mathcal{D}\langle B_p', B_c', d_s', C', A_s', K' \rangle$$

```
d \in \mathbf{Debugger} ::= \mathcal{D}\langle B_p, B_c, d_s, C, A_s, K \rangle
                                                                                                   Debugger configurations
    B_p \in \mathbf{Pending\ breakpoint}
                                                                                                   Pending breakpoints
    B_c \in \mathbf{Checked\ breakpoint}
                                                                                                   Checked breakpoints
            d_s \in \mathbf{Debugger} state
                                                 ::=
                                                         run | pause
                                                                                                   Debugger states
                     C \in \mathbf{Command}
                                                                                                   Commands
          A_s \in \mathbf{Actor} state map
                                                                                                   Actor state map
           b_u \in \text{User breakpoint}
                                                       \mathcal{B}\langle t_{ub}, \iota_i \rangle
                                                                                                   User Breakpoints
                                                 ::= \mathcal{B}\langle t_{tb}, \iota_a, \iota_i \rangle
       b_t \in \text{Trigger breakpoint}
                                                                                                   Trigger Breakpoints
                                                 ::= \begin{array}{cc} \mathcal{C}\langle t_c \rangle \mid \mathcal{C}\langle t_c, n \rangle \\ ::= & \mathcal{CS}\langle \iota_a, a_s \rangle \end{array}
                                    c \in \mathbf{C}
                                                                                                   Commands
      c_s \in \text{Current actor state}
                                                                                                   Current actor state
                                                          run | pause | hold | step n
                   a_s \in \mathbf{Actor} \ \mathbf{state}
                                                                                                   Actor states
   t_{ub} \in \text{User breakpoint tag}
                                                         msb | mrb
                                                                                                   User breakpoint tags
t_{tb} \in \text{Trigger breakpoint tag}
                                                                                                   Trigger breakpoint tags
                                                          mrb-trigger
                                                         step-next-turn \iota_{\rm a}
               t_c \in \mathbf{Command\ tag}
                                                                                                   Command tags
                                                 ::=
                                                          resume
                                                          pause
```

 $\iota_i \in \mathbf{BreakpointId}$ 



### Running Example in Voyager

```
; Pending breakpoints
                                     ; Checked breakpoints
                                     ; Debugger state
run
                                     ; Commands (user interaction)
((client1 run))
                                     ; Actor map
                                     ; Base language term
((actor
  client1
  ( )
  ( )
  (let (math (actor
       (field result 0)
       (method double x (set! (this $ result) (+ x x)))
       (method result p (this $ result))))
  in
  (let (client2 (actor
          (method start math (send math double (33) c2-double-to-math)))
  in
  (let (a (send client2 start (math) c1-start-to-c2)) in
  (let (b (send math double (12) c1-double-to-math)) in
  (let (x f x r) future in
  (let (x 1 (
        let (some-var 5) in
        (object (method apply x ((x r $ resolve-mu) x))))
       ) in
  (let (var (send (let (x f1 x r1) future in
  (let (var (send math result (0 x r1) c1-result-to-math)) in x f1))
                  register-mu (x_1) c1-result-to-math)) in x f))))))
```

#### Demo

https://github.com/chscholl/GraphRedex/blob/artefact/ECOOP2019/Publications/ECOOP2019/README.md

#### Conclusion

#### "Non-deterministic programs require non-deterministic tools"

- A new exploration path in debugging with many challenges to tackle:
  - state explosion
  - multiverse breakpoint
     & stepping operations
  - novel visualisations

