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# A Constraint Programming Model for Food Processing Industry: A Case for an Ice Cream Processing Facility

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## Abstract

This paper presents a Constraint Programming (CP) scheduling model for an ice cream processing facility. CP is a mathematical optimization tool for solving problems either for optimality (for small-size problems) or good quality solutions (for large-size problems). For practical scheduling problems, a single CP solution model can be used to optimize daily production or production horizon extending for months. The proposed model minimizes a makespan objective and consists of various processing interval and sequence variables and a number of production constraints for a case from a food processing industry. Its performance was compared to a Mixed Integer Linear Programming (MILP) model from the literature for optimality, speed, and competence using the partial capacity of the production facility of the case study. Furthermore, the model was tested using different product demand sizes for the full capacity of the facility. The results demonstrate both the effectiveness, flexibility, and speed of the CP models, especially for large-scale models. As an alternative to MILP, CP models can provide a reasonable balance between optimality and computation speed for large problems.

**Keywords:** Constraint Programming; Scheduling; Ice Cream Processing; Food Processing Scheduling

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**1 Introduction**

Companies put a significant effort to utilize production resources efficiently and effectively in their manufacturing activities. Scheduling methods improve resource utilization by providing platforms for planning, managing, and controlling resources. This paper presents a scheduling tool using Constraint Programming (CP) for a scheduling problem from the food processing industries.

Scheduling problems in the food processing industries must address a combined discrete and continuous production system. Pasteurization, dehydration, and freezing are a few examples of continuous processes whereas packaging process is a good example of discrete processes in the industry. In addition to the optimization objectives (such as production cost/profit, makespan, earliness or lateness) and constraints (assignment of tasks to machines, sequencing and/or timing of tasks, other facility related constraints) they have in common with discrete production systems, continuous systems require decisions on selection and size of processing batches (Harjunoski, et al., 2014). The perishable nature of food products would be the other factor to consider in scheduling problems in the industry. This factor constrains the manufacturing process to be completed within a limited time window frame. Hence optimization models not only need to define a constraint for this time window but also should complete the optimization run under this time limit. Time for decision making, implementation, and any corrective action would have to be included in this time window as well.

Several mathematical programming techniques have been proposed to solve optimization problems (including scheduling). Some of these techniques include Linear Programming, Mixed Integer Linear Programming (MILP), Dynamic Programming (DP), and CP (Rossi, Van Beek, & Walsh, 2006; Apt, 2003). CP was first developed as a tool for solving combinatorial problems in the artificial intelligence and computer science field of study. Problems in this method are formulated by defining the constraints on the decision variables and then solving these problems using computer programs (procedures) (Bockmayr & Hooker, 2005; I. & JF., 2013). The CP

paradigm is general and allows for many types of constraints such as linear inequalities or dis-equalities, disjunctions of constraints, and global constraints (allDifferent, cumulative) (Sitek & Wikarek, 2015).

CP utilizes an approach where a solution space is reduced using constraints/restrictors before solving the problem with different mathematical programming methods (Rossi, Van Beek, & Walsh, 2006; Apt, 2003). Problems can be formulated as Constraints Satisfaction Problem where CP aims at finding a good quality feasible solution to the problem, or as Optimization Problem where it tries to find the optimal solution based on a given objective. Scheduling problems constitute one application area for the implementation of CP. Restriction due to manufacturing environments and resource availabilities can be formulated as constraints, and the production scheduling problem can be solved as either a constraint satisfaction problem or an optimization problem.

The proposed CP model, in this paper, minimizes a makespan objective for a medium size food processing facility (ice cream processing). In our CP model, interval and sequencing variables are created to define the start and completion of processing times and order of processing in a specific machine. Constraints for these variables included no-overlap of processing time, selection and assignment of a task to machines, interlink and order of processing stages for all product types, product processing order in the packaging lines, and cease of production over the weekends. The first experimental run is used to compare the model against an MILP solution model published by Wari and Zhu (2016) for a reduced size of the case study. The model attained makespan values comparable to those from the MILP model for small size problem instances. For more complex problems, it performed better by solving instances which the MILP model was unable to solve. In the second experimental run, the model solves two demand problem sets for the full-size production facility. It is worth noting that before this paper, no other researchers have been able to

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solve this problem at its full scale. Two batch sizes were used to break total products demands and a schedule for month’s production horizon is reported.

The rest of the paper is organized as follows. The literature review on scheduling approaches for food processing industries and CP method is presented immediately after this introduction section. The proposed model is described in the third section. Section four discusses the experimental run results of the model. Finally, concluding remarks are given in the last section.

**2 Literature Review**

Scheduling problems in the food processing industries can be formulated by adopting either a general machine or production system layout or a specific industrial case study problem approach. The most common general system layout problem formulation is given by a no-wait Flow Shop (FS) and Flexible Flow Shop (FFS) manufacturing setup. Industrial application cases covered a wide range of subsectors. This section presents a brief review of these approaches.

Various heuristic and metaheuristic approaches have been utilized to optimize scheduling problems with general system layout. Wang & Liu proposed a Genetic Algorithm (GA) model where jobs were coded as genes in the solution model (Wang & Liu, 2013). In this algorithm, jobs were defined as genes and schedule as chromosomes for a two-stage production process. To utilize the best features of multiple metaheuristic approaches, a number of publications adopted hybrids of heuristics/metaheuristics methods. Jolai, Rabiee, & Asefi (2012) proposed a hybrid Simulating Annealing (SA - Population-based SA) and Imperialist Competitive Algorithm (ICA) approach in which the earlier explored the solution space whereas the later exploited the neighborhoods. Other similar mixed approaches include Moradinasab, Shafaei, Rabiee, & Ramezani (2013) who developed models using ICA, Ant Colony Optimization (ACO), and GA; Zhou and Gu (2009) who integrated GA and Gaming Theory; and Samarghandi and ElMekkawy (2012) who presented a hybrid Tabu Search (TS) – Particle Swarm Optimization (PSO) approach. Ye, Li, & Miao (2017; 2016) proposed two heuristics methods (based on average idle and departure time) for a no-wait

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3 FS. Nagano, Miyata, & Araújo presented a constructive heuristic where the scheduling problem is  
4 broken-down into smaller sized problems before being optimized (Nagano, Miyata, & Araújo,  
5 2015). Overall heuristic and metaheuristic dominate the approaches in the literature since most of  
6 no-wait FS/FFS scheduling problems were formulated as NP-Hard. However, few mathematical  
7 methods can be found which would include a branch and bound presented by Wang, Liu, & Chu  
8 (2015) for an FFS manufacturing setup.  
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17 Scheduling problems specific to the food processing facilities adopted similar  
18 metaheuristics, mathematical, or hybrid methods. The application of GA could be for whole  
19 production setup as presented by Shaw et al. (2000), and Heinonen & Pettersson (2003), or  
20 specific processing stage (the filling line of dairy plant) as proposed by Gellert, Höhn, & Möhring  
21 (2011) or production function (cost of distribution) for the case of Karray, Benrejeb & Borne  
22 (2011). In all cases, production constraints such as processing stages and precedence, clean-  
23 up/sanitization, machine capacity, and processing time were formulated into the problems.  
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Banerjee et al. (2008) presented an Artificial Bee Colony (ABC) metaheuristic model for solving  
multi-objective scheduling (optimal cost and risk levels) problem for a milk processing industry.  
Combined metaheuristics approach includes the two publications by Hecker et al. (2013; 2014)  
which adopted GA, ACO, PSO, and Random Search algorithms. Linear Programming, particularly  
MILP, dominate the mathematical approaches for specific food processing scheduling solution  
models. Bongers and Bakker (2006), Kopanos, Puigjaner and Georgiadis (2011), Kopanos,  
Puigjaner and Georgiadis (2012), and Wari and Zhu (2016) proposed MILP models for a simplified  
ice cream processing scheduling problem (the case study for this paper as well) with a makespan  
optimization objective. Bongers and Bakker (2006), Kopanos, Puigjaner and Georgiadis (2011),  
Kopanos, Puigjaner and Georgiadis (2012) integrated heuristics to supplement the limitation of the  
MILP approach such as long optimization runtime, shorter production scheduling horizon and few  
numbers of product types in the scheduling problem. Wari and Zhu (2016) presented an MILP



model for multi-week production horizon with proper weekend break-up points and clean-up sessions. These four publications considered part of the production process of the facility and a smaller number of products. The proposed CP model in this paper presents an optimization model for a larger number of products processed using the full capacity of the facility. It also presents a new mathematical approach for solving scheduling problems with the combined continuous and discrete production system. Other MILP models publications include Doganis and Sarimveis (2007; 2008a; 2008b) and Kopanos, Puigjaner, and Georgiadis (2009) who developed models to optimize production cost (yogurt processing facility), Sadi-Nezhad & Darian (2010) who presented a model to optimize production capacity (juice processing facility), and Liu, Pinto, and Papageorgiou (2010) who proposed a model to maximize profit (an edible oil manufacturing facility). New approaches, such as chance-constraint programming and a combined local search and machine learning methods, have been used to optimize industrial scheduling problems. For example, Wauters et al. presented a scheduling model where data for different food processing features were utilized by search heuristics to attain better result (Wauters, Verbeeck, Verstraete, Berghe, & De Causmaecker, 2012). Sel, Bilgen, & Bloemhof-Ruwaard demonstrated the application of chance-programming for a scheduling problem in a dairy processing facility (Sel, Bilgen, & Bloemhof-Ruwaard, 2017). The model applied chance-programming to quality decaying properties of dairy products.

Since very few publications were identified for specific applications in the food processing industries, the literature review for CP application has been expanded to include other manufacturing industries sectors. For machine scheduling application of CP, Novas and Henning (2012), Öztürk et al. (2012), and Zeballos, Quiroga, & Henning (2010) presented a makespan minimizing model for an automated wet-etch station (semiconductor manufacturing), flexible mixed-model assembly line, and machine-tool allocation and routing of products respectively. The constraints in all models include start/completion processing times, the processing order (for



products) and resource availability. Huang, Shi, & Shi (2018) proposed an MILP and CP optimization models to minimize the total weighted completion time for different product batches and unary machines. Korbaa, Yim, & Gentina (2000) and Bourdeaud'Huy, Belkahla, Yim, Korbaa, & Ghedira, (2011) presented a CP optimization approaches for a deterministic and cyclic transient state scheduling problem. For scheduling a set of tools, Gökgür, Hnich, & Özpeynirci (2018) developed a CP model to optimize a makespan objective. This model formulated constraints for variability and availability of production tools which were required by parallel machines to complete different jobs. In shift scheduling problem (for employees), the optimization objective included meeting demand requirements of labor and reducing costs such as overtime and under-utilized labor. Model constraints may be comprised of factors such as labor cost, workload balance, and allowable working hours. Publications for this instance included Han & Li (2014) – optimizing drivers and operators for a mass rapid transit train system, Weil, Heus, Francois, & Poujade, (1995) – optimizing the schedules of nurses, and Topaloglu & Ozkarahan (2011) – optimizing the schedule of medical residencies. CP can also be used for fleet scheduling optimization either in a distribution/logistics problem or an internal material handling system to minimize cost. Unsal & Oguz (2013) and El Hachemi, Gendreau, & Rousseau (2011) presented CP models to demonstrate this application. Meneghetti & Monti (2015) presented a CP model to optimize the design of a refrigerated automated storage and retrieval systems for a food processing supply chain. This model optimized rack sizes, surface area and volume of storage cells with an objective of minimizing total storage costs and maximizing energy efficiency. Meneghetti, Dal Borgo, & Monti (2015) presented a similar model focusing only on the rack sizes for the same optimization objectives. Routing, inventory, supply chain management, and combined planning and scheduling problem are a few other application areas for CP (Goel, Slusky, van Hoeve, Furman, & Shao, 2015; Zhang & Wong, 2012; Sitek & Wikarek, 2015). Table 1 summarizes the key relevant publication in the food processing industry.

**Table 1** Summary of relevant scheduling problem publication in the food processing industry

Publication	Formulation	Objective	Mathematical			Metaheuristic/Heuristic								Other
			MILP	CP	B&B	GA	SA	ICA	ACO	TS	PSO	ABC	Heuristic	
Wang & Liu, 2013	2-stage no-wait FFS	Makespan				X								
Jolai, Rabiee, & Asefi (2012)	No-wait FFS	Makespan					X	X						
Moradinasab, Shafaei, Rabiee, & Ramezani (2013)	No-wait FFS	Total completion time				X		X	X					
Zhou and Gu (2009)	No-wait FFS	Customer satisfaction				X								X
Samarghandi and ElMekkawy (2012)	No-wait FS	Makespan								X	X			
Ye, Li, & Miao (2017; 2016)	No-wait FS	Makespan											X	
Nagano, Miyata, & Araújo, 2015	No-wait FS	Total flow time											X	
Wang, Liu, & Chu (2015)	2-stage no-wait FFS	Makespan			X									
Shaw et al. (2000)	Batch/Continuous (no-wait FS)	Various production costs				X								
Heinonen & Pettersson (2003)	Batch/Continuous (no-wait FS)	Various production costs				X								
Gellert, Höhn, & Möhring (2011)	Dairy processing facility	Total production cost				X								
Karray, Benrejeb, & Borne (2011)	Agro-food industries	Various production costs				X								
Banerjee et al. (2008)	Milk processing facility	Cost and risk levels										X		
Hecker et al. (2013; 2014)	No-wait FFS (Bakery facility)	Total production cost				X			X		X		X	
Bongers and Bakker (2006)	Ice cream processing facility	Makespan	X										X	
Kopanos, Puigjaner and Georgiadis (2011; 2012)	Ice cream processing facility	Makespan	X										X	
Wari and Zhu (2016)	Ice cream processing facility	Makespan	X											
Doganis and Sarimveis (2007; 2008a; 2008b)	Yogurt processing facility	Production Cost	X											
Kopanos, Puigjaner, and Georgiadis (2009)	Yogurt processing facility	Production Cost	X											
Sadi-Nezhad & Darian (2010)	Juice processing facility	Production Capacity												
Liu, Pinto, and Papageorgiou (2010)	Edible oil manufacturing facility	Profit	X											
Wauters et. al.	Packaging line	Makespan												X
Sel, Bilgen, & Bloemhof-Ruwaard (2017)	Dairy processing facility	Makespan												X

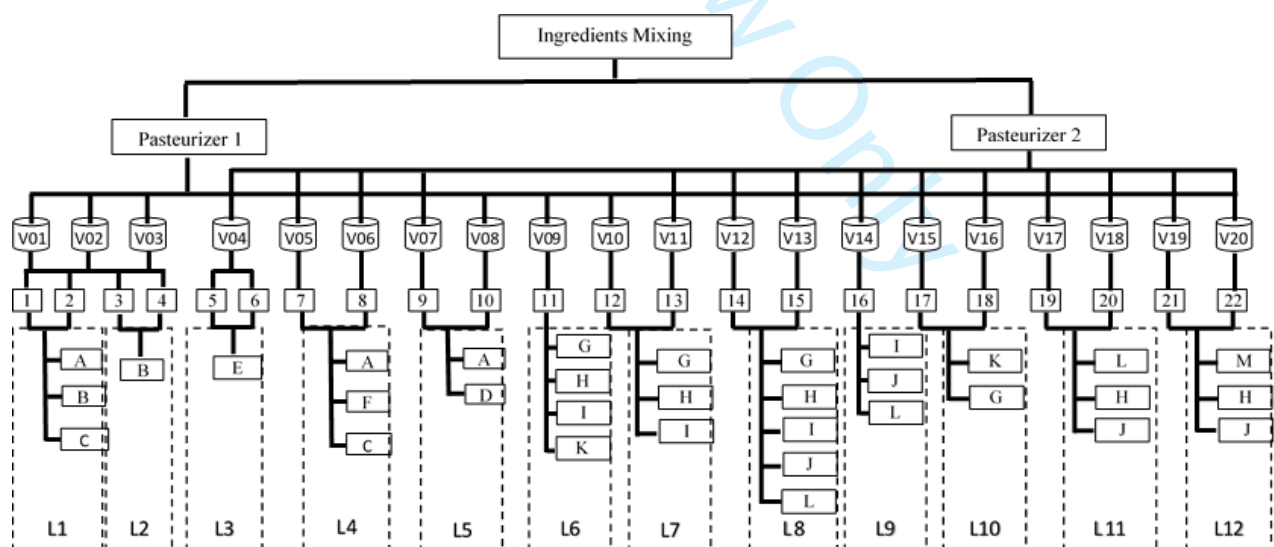
**3 Problem Description and Solution Models**

The case study for this paper was first proposed by Bongers & Bakker (2006) to improve production scheduling for an ice cream processing facility. Bonger & Bakker reduced the size of the production in the facility to three-stage processing with a fewer number of machines, and product mixes mainly due to the limitation of the optimization software. Later, relevant

publications have expanded the number of product mixes and demands sizes, while keeping the problem at the reduced size. This paper takes on the challenge of considering the facility at its full size as described in Bongers & Bakker (2006).

### 3.1 Problem Description

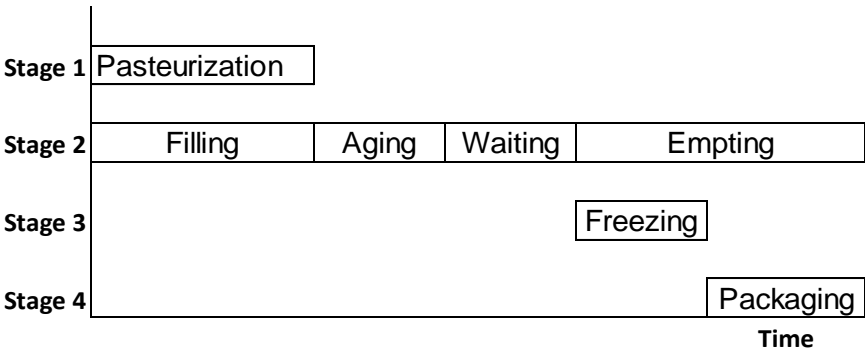
As illustrated in Figure 1, production in the ice cream processing facility starts by mixing different ingredients of the ice cream based on receipts (Bongers & Bakker, 2006). This stage is assumed to have no resource limitation and hence excluded from the scheduling problem. Ice cream mixes are pasteurized first using two continuous-pasteurization units. These units expose the mixtures to a high temperature for a short period as the mixtures flow through the equipment. The products flow to the aging vessels where the quality of the ice cream mix is improved, and the mix is cooled-down. Aging vessels are refrigerated tankers with agitators and store ice cream mixtures for a receipt-based period. Each product mixes can be aged in a specific number of vessels. The ice cream mixes are cooled further using product-specific freezers for a predefined period. The production process concludes with the packaging of product mixes into different sizes and shapes at a rate specific to each product mix.



**Figure 1.** A medium size ice cream processing facility: V01 to V20 are aging vessels; Items 1 to 22 are freezers; Items L1 to L12 are packaging lines; Items A to M are product mix types (Source: Bongers and Bakker (2006))

Product processing speeds have been defined in two methods in the problem. In the first method, machine’s processing speed determines the processing rate. For example, the two pasteurization units process all product mixes at the rate of either 4500Kg/hr or 6000Kg/hr. The second method defines the processing speed based on the product mix type. Aging and packaging rate are good examples where a product’s intrinsic nature determines the processing rate. Most machines can process only a group of product mixes except for Pasteurizer 1 which has the capacity to process all products.

The processing flow of the ice cream product mixes is composed of multiple production stages (Figure 2). In the first stage, pasteurization of the product mixes takes place at a rate based on the specific equipment under consideration. Processing inside the vessels consists of multiple steps. First, the vessels would have to be filled up before the aging commences. As a continuous process, the pasteurization and filling processes can be considered as overlapping processes (interval variables for the two would have the same value). Then product mixes are aged and either transferred to the freezer or stored depending on the availability of a freezer and packaging line. When there is no idle freezer or packaging line available, the product is temporarily stored in the vessel (creates waiting interval). When a freezer and packaging line is available to take the mix, continuous freezing and packaging processes commence. Similar to the filling step, the emptying step of a vessel is a continuous process that overlaps with the freezing and packaging stages. Freezing and packaging are independent and consecutive processes.



**Figure 2.** Processing time intervals for different stages of the ice cream production

### 3.2 CP model

Scheduling problems can be formulated using different approaches in CP. The most common approach is to define processes using integer and/or binary decision variables and a set of global constraints and propagating algorithms to solve the problem. IBM CP Optimizer tool (Laborie & Rogerie, 2008) provides a different approach where the processes and respective sequences are formulated as interval and sequence decision variables. This tool introduces some modeling concepts for scheduling problems by representing optional activities, temporal constraints, hierarchical decomposition, and different resource-related constraints (Laborie, Rogerie, Shaw, & Vilím, 2009). The proposed CP model creates processing time interval decision variables for all products in all stages. Sequencing decision variables define the processing orders of products for each equipment. The complete model is described in this section.

#### *Sets and Subsets*

Sets create collections for product mix types, and machines for pasteurization, aging, and packaging whereas subsets memorize the assignments of processing machines for product mixes.

#### *Parameters*

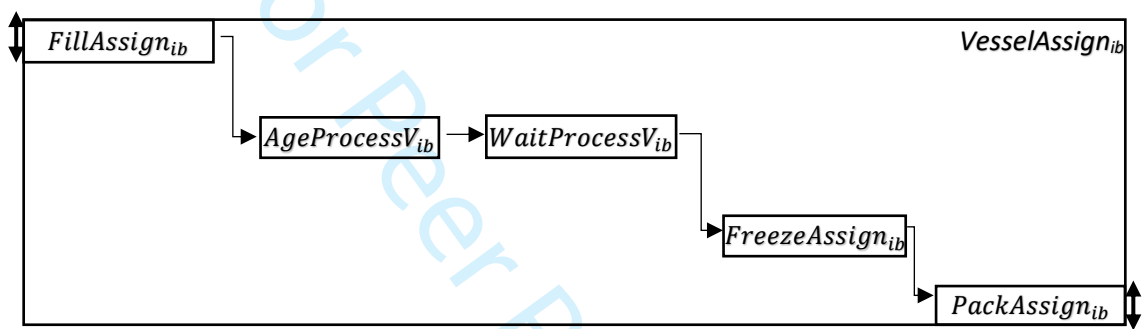
Parameters define model constants such as processing speeds (filling, aging, emptying), changeover times, working week time horizons, and scheduled weeks whereas parameter functions formulate mathematical relationship among parameters.

#### *Decision Variables*

Two types of decision variables, intervals and sequences, are created to formulate different constraint relation which emulates the processing restrictions of the ice cream production. Interval decision variables consist of two types of variables. Process Intervals construct the processing time interval for each product mix in all assigned machines (*VesselProcess*, *FillProcess*, *FreezeProcess*, *PackProcess*). Assignment intervals select a process interval among multiples of

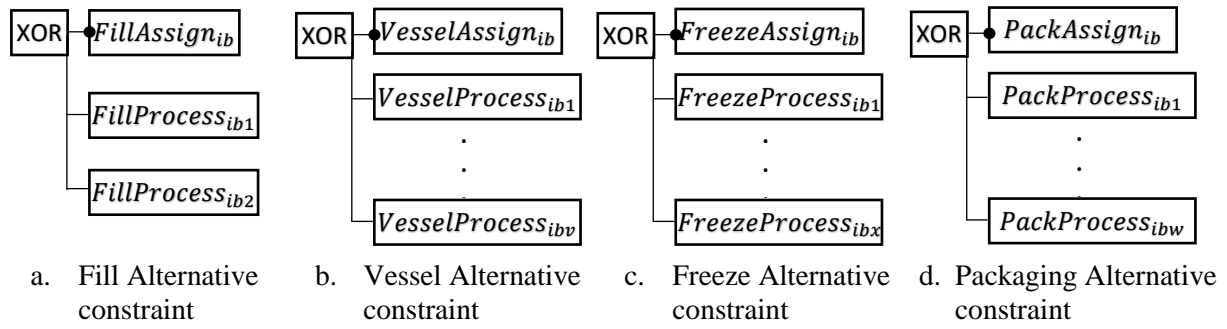
alternatives to create a schedule for each product mix (*VesselAssign*, *FillAssign*, *FreezeAssign*, *PackAssign*).

Figure 3 shows the temporal and logical constraints of the interval variables. The chain processing step is shown with the series of time intervals (linked by straight arrows). *VesselAssign* variables span over all the intervals and align with *FillAssign* at the start and *PackAssign* at the end (linked by double-headed arrows). Filling and emptying steps of the vessel are equivalent to the pasteurization process and the sum of freezing and packaging processes, respectively.



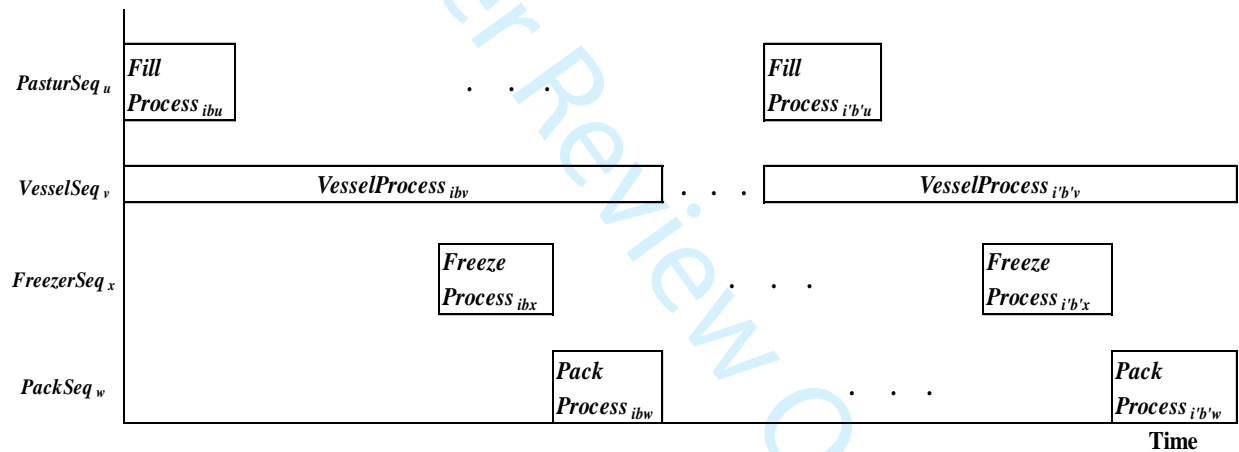
**Figure 3.** Temporal and spanning decision variables

The processes at all four stages of production can be performed by multiple equipment and the model has to pick only one equipment to create a viable schedule for each product. This feature is represented by formulating all assign intervals (*FillAssign*, *FreezeAssign*, *PackAssign*, and *VesselAssign*) as optional intervals. An interval is defined as optional interval when it is created neither as ‘must be scheduled’ (present) nor ‘must not be scheduled’ (absent) interval. The presence/absence of the interval could only be determined when a solution is obtained (IBM, 2016; Laborie, Rogerie, Shaw, & Vilím, 2018). CP ignores absent intervals in any part of the optimization model. Alternative constraints enforce the selection process for optional intervals from among the different potential interval decision variables - process interval (see Figure 4).



**Figure 4.** Alternative interval decision variables

Sequence decision variables (sequence interval variables) arrange the processing order of product mixes for each equipment (Laborie, Rogerie, Shaw, & Vilím, 2018). Figure 5 shows the process interval assigned to the sequence variable. It is important to note that *Vesselprocess* combines the filling (pasteurization), aging, waiting, and emptying (freezing + packaging) steps.



**Figure 5.** Sequence decision variables

### Objective

The model minimizes a makespan objective. It is computed as the maximum of all batches' completion time for the vessel variables (*VesselAssign*).

$$\text{Minimize } \max_{i,b} \text{endOf}(VesselAssign_{i,b}) \quad (1)$$

$$\forall i, b \text{ where } i \in \text{Product Mix}, b \in 1..\text{MinNoBatch}_i$$

### Sequence constraints

Sequence constraints in the model prohibit the overlap of intervals (defined in sequence decision variables) in all machines. The constraints for pasteurizing, aging, freezing, and



packaging stages are given in equations 2, 3, 4, and 5 respectively. These constraints also insert the respective changeover times between the processing intervals of consecutive batches. The changeover times required between product mixes are defined by two transition matrices given in Appendix 1c and 1d ( $ProcessChOTimes_{i,i'}$  for pasteurization and aging processes, and  $PackageChOTimes_{i,i'}$  for packaging process).

$$noOverlap(PasturSeq_u, ProcessChOTimes_{i,i'}) \quad (2)$$

$\forall u \text{ where } u \in \text{Pasteurizer}, i \& i' \in \text{Product Mix}$

$$noOverlap(VesselSeq_v, ProcessChOTimes_{i,i'}) \quad (3)$$

$\forall v \text{ where } v \in \text{Vessels}, i \& i' \in \text{Product Mix}$

$$noOverlap(FreezerSeq_x, PackageChOTimes_{i,i'}) \quad (4)$$

$\forall x \text{ where } x \in \text{Freezers}, i \& i' \in \text{Product Mix}$

$$noOverlap(PackSeq_w, PackageChOTimes_{i,i'}) \quad (5)$$

$\forall w \text{ where } w \in \text{Packaging Lines}, i \& i' \in \text{Product Mix}$

#### Interval constraints

Three groups of interval constraints are formulated for the optimization model. The first group constitutes constraints that interlink the start and end of intervals for successive stages of each product to create a processing chain (equations 6 and 7).

Pasteurization is immediately followed by the aging and freezing processes. Filling rates of the vessels are assumed to be equal to the pasteurization speed. Right after the completion of the aging period, the freezing/packaging intervals may not immediately commence due to the unavailability of either a freezer or packaging equipment. In these cases, the waiting decision variable cushions the processing time gap. Equation 6 defines this processing chain.

$$endAtStart(FillAssign_{i,b}, FreezeAssign_{i,b}, AgingTime_i + WaitProcessV_{i,b}) \quad (6)$$

$\forall i, b \text{ where } i \in \text{Product Mix}, b \in 1..MinNoBatch_i$

Following this, equation 7 connects the freezing stage with the packaging stage.

$$\begin{aligned} & \text{endAtStart}(\text{FreezeAssign}_{i,b}, \text{PackAssign}_{i,b}) \\ & \forall i, b \text{ where } i \in \text{Product Mix}, b \in 1..\text{MinNoBatch}_i \end{aligned} \quad (7)$$

The processing in the aging vessels contains four distinct steps. These steps are 1) filling up the tanks; 2) aging; 3) waiting; and 4) emptying the tanks. All these steps have to be completed before any succeeding batch can start its processing in the same vessel. An aggregating interval (*VesselAssign*) is created to integrate these steps by aligning it with the start and end of these processing steps. Explicitly, the starts of *VesselAssign* and *FillAssign* are aligned (equation 8) whereas the ends of *VesselAssign* and *PackAssign* are aligned (equation 9).

$$\begin{aligned} & \text{startAtStart}(\text{FillAssign}_{i,b}, \text{VesselAssign}_{i,b}) \\ & \forall i, b \text{ where } i \in \text{Product Mix}, b \in 1..\text{MinNoBatch}_i \end{aligned} \quad (8)$$

$$\begin{aligned} & \text{endAtEnd}(\text{PackAssign}_{i,b}, \text{VesselAssign}_{i,b}) \\ & \forall i, b \text{ where } i \in \text{Product Mix}, b \in 1..\text{MinNoBatch}_i \end{aligned} \quad (9)$$

As described in the previous sections, multiple machines are allocated to process each product batch. However, only one of these processing alternatives can be inserted in the final schedule. The third group of interval constraints selects and assigns processing intervals to the schedule (equations 10, 11, 12, and 13). *FillAssign*, *VesselAssign*, *FreezeAssign*, and *PackAssign* variables represent the scheduled intervals for pasteurizing, aging, freezing and packaging stages respectively.

$$\begin{aligned} & \text{alternative}(\text{FillAssign}_{i,b}, \text{FillProcess}_{i,b,u}) \\ & \forall i, b \text{ where } i \in \text{Product Mix}, b \in 1..\text{MinNoBatch}_i, u \in \text{Pasteurizer} \end{aligned} \quad (10)$$

$$\begin{aligned} & \text{alternative}(\text{VesselAssign}_{i,b}, \text{VesselProcess}_{i,b,v}) \\ & \forall i, b \text{ where } i \in \text{Product Mix}, b \in 1..\text{MinNoBatch}_i, v \in \text{Vessels} \end{aligned} \quad (11)$$

$$\begin{aligned} & \text{alternative}(\text{FreezeAssign}_{i,b}, \text{FreezeProcess}_{i,b,x}) \\ & \forall i, b \text{ where } i \in \text{Product Mix}, b \in 1..\text{MinNoBatch}_i, x \in \text{Freezers} \end{aligned} \quad (12)$$

$$\text{alternative}(PackAssign_{i,b}, PackProcess_{i,b,w})$$
$$\forall i, b \text{ where } i \in \text{Product Mix}, b \in 1..MinNoBatch_i, w \in \text{Packaging Line}$$

(13)

Weekend break constraints

In the original problem, production takes place only during the weekdays in the facility. Therefore, the solution model cannot schedule any processing over the weekends and would have to cease production making proper break-up arrangements. The first part of this arrangement is to stop the production process earlier so that shut-down procedures would be completed before the end of the production week. This is formulated in two alternative methods. The first method excludes the weekend hours from the schedule. It is expressed as a 120-hours production week (5 days with 24 hours per day) with the last two hours of the week allocated for clean-up. This reduces the actual production week from 120 to 118 hours. The second method includes the weekends in the schedule since the aging process can be extended over the weekend. This production week has 168 hours (=120 production week + 48 weekends). The two-hours clean-up times remain the same for each week. However, it may start and finish at different points of the production horizon when compared to the first method. The functions (*stepFunction WeekendBreak*) to formulate these two production horizons are given in Appendix 3. The production week, clean-up and weekend hours mapping for the first 10 weeks are shown in Figure 6.

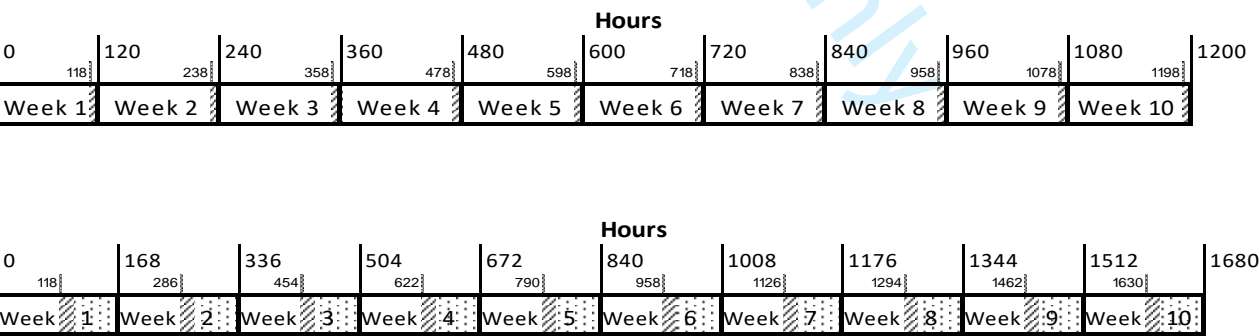


Figure 6. Production horizon for 120-hours and 168-hours week: ▨ - Clean-up time; ▤ - Weekend

Any interval for pasteurization, freezing and packaging processes cannot extend over the start of the clean-up sessions (for week 1, hours 118 to 120). A ‘*forbidExtent*’ constraint is

formulated to embody this scheduling restriction (equations 14, 15 and 16). The step-functions (*WeekendBreak*) discussed above define these forbidden periods for a given production horizon.

$$\text{forbidExtent}(\text{FillAssign}_{i,b}, \text{WeekendBreak}) \quad (14)$$

$$\forall i, b \text{ where } i \in \text{Product Mix}, b \in 1..\text{MinNoBatch}_i$$

$$\text{forbidExtent}(\text{FreezeAssign}_{i,b}, \text{WeekendBreak}) \quad (15)$$

$$\forall i, b \text{ where } i \in \text{Product Mix}, b \in 1..\text{MinNoBatch}_i$$

$$\text{forbidExtent}(\text{PackAssign}_{i,b}, \text{WeekendBreak}) \quad (16)$$

$$\forall i, b \text{ where } i \in \text{Product Mix}, b \in 1..\text{MinNoBatch}_i$$

The weekend break arrangement for the aging process follows a different approach. Aging vessels act not only as processing machines but also as storage units. Hence any process started before the beginning of the weekend break can be finished and stored in the units over the weekends. The freezing/packaging process commences at the beginning of the subsequent production week. Therefore, there are no ‘*forbid*’ constraints for either the aging process or the waiting period inside the vessels for any of the ice cream products.

#### *Packaging line constraint*

Processing in each packaging line would have to observe a precedence rule for product mix type. Higher priority product must be processed before lower priority products (in descending priority: M-L-K-J-I-H-G-F-E-D-C-B-A). A built-in function (‘*endBeforeStart*’) constraint is formulated to enforce this processing condition as given in equation 17.

$$\text{endBeforeStart}(\text{PackProcess}V_{i',b',w}, \text{PackProcess}V_{i,b,w}) \quad (17)$$

$$\forall i, i', b, b' \text{ where } i \& i' \in \text{Product Mix}, b \& b' \in 1..\text{MinNoBatch}_i,$$

$$w \in \text{Packaging Lines}, \text{ord}(\text{ProductMix}, i) > \text{ord}(\text{ProductMix}, i')$$

#### *Processing time window constraint*

As perishable products, ice creams require a quick processing chain. For the case study in this paper, the maximum processing time window for each batch is 72 hours. Equation 18

constrains the total processing time (from start to finish) for all batches to be within this production time window.

$$lengthOf(VesselAssign_{i,b}) < 72 \quad \forall i, b \text{ where } i \in Product\ Mix, b \in 1..MinNoBatch_i \tag{18}$$

*Work-in-process storage constraint*

The work-in-process storage time between the aging process and freezing/packaging is formulated as waiting time decision variable (*WaitProcessV<sub>ib</sub>*). This storage time is a non-value adding process. Therefore, the schedule model should balance the cost of storage with the benefit of cushioning for this variable. To this effect, equation 19 is formulated to regulate the total waiting time (*Totalwait*) allowed in the final schedule.

$$Totalwait < MaxWaiting \tag{19}$$

**4 Experiment Result and Discussion**

Two sets of experimental runs were used to test the proposed model. The first set compared the model’s performance with a published model from the literature. A modified data set was used to evaluate the performance of published and the proposed CP models. The second experimental run focused on solving the scheduling problem for the full-scale ice cream processing facility. This experiment aimed at finding the maximum number of product mixes that can be scheduled with the proposed model (disregarding limitations due to computing capacity and optimization software). For both sets of experiments, IBM CP Optimizer was used to formulate and execute the proposed model. All computations were performed on an Alienware Workstation with Intel® Core™ i7-5820K Processor CPU, 1TB HSD/3.6TB HDD, and 32GB RAM, on Windows 10 Enterprise operating systems.

**4.1 Experimental Run 1**

The publication by Wari and Zhu (2016) was selected as the base for comparison of the performance of the proposed CP model in this paper. This study presented an MILP model to

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2  
3 schedule the partial production processing the ice cream facility. It formulated sets and subsets,  
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5 parameters and parameter functions, decision variables, and objective and constraint functions to  
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7 represent the production environment. Sets, subsets, parameters, and parameter functions have  
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9 been created to define product-mix type, available processing equipment for each stage, processing  
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11 parameter such as processing time, and setup time, scheduling parameter (including time horizon).  
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13 Decision variables consist of the start and completion of processing times, waiting times, a binary  
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15 variable for product processing order, and a binary variable for selection of aging vessel. A  
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17 makespan objective was used. Four groups of constraints were formulated to solve the problem  
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19 (Wari & Zhu, 2016). The first group created process intervals by defining the start and completion  
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21 time for each product batch and then creating processing chains for all products and batches  
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23 (Appendix 4B equations 1 to 11). These constraints serve similar purposes to interval variables  
24  
25 and temporal constraints. The second group of constraints (specific to the MILP model) focused  
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27 on the allocation of batches to vessels (Appendix 4B equations 12 to 20). These constraints  
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29 assigned each batch to a vessel in a cyclic manner. The next group rearranged products batches  
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31 assigned to an equipment based on predefined priority level (Appendix 4B equations 21 to 28). On  
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33 the proposed CP model, these are partly formulated by temporal and 'noOverlap' constraints. The  
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35 last group consisted of miscellaneous constraints such as makespan, lower bound and domain sets  
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37 for decision variables (Appendix 4B equations 29 to 34).  
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45 Due to the limitation of each model, the test data used by Wari and Zhu was modified in  
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47 this paper to compare the two models. Since the CP model can be formulated as integer model, all  
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49 parameters and parameter function were converted to integer values for the MILP model too. The  
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51 problem model for the MILP considered only one pasteurization unit and no freezer stage. To  
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53 accommodate this reduction in model size, the CP model considered only one pasteurization  
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55 equipment. Furthermore, the freezing stage was excluded from the original model by relaxing all  
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57 constraints related to the stage (constraints 4, 7, 12, and 15), and modifying constraint 6 to link the  
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filling interval with the packaging interval. *Totalwait* was set to a maximum integer value (*'maxint'* – for an unlimited amount of waiting time) by relaxing constraint 19. The step-function *WeekendBreak1* (120 hours scheduling week) defined the scheduling horizon to create comparable production environment to that of the MILP model. To test the performance of each solution model (MILP and CP) over longer production horizon, batch sizes for problem instances were stretched from 180 or 200 to 640 batches for all three problem sets. In other words, the modified problem model mixed up part of the data from the published paper and new problem instance with larger batch sizes. The new problem instances were created by a random generation of demand size for each product mix. The complete list of these values is given in Appendix 1. Finally, the run parameter limits for CP model were set to 600 seconds maximum run time, similar to the limit set in Wari and Zhu (2016).

Table 2 compared the run results of the MILP and CP models. The table showed the makespan results for the three test demand sets (Appendix 1a) and the respective computation time for each problem instance. The last column gave the makespan difference between the two models. Overall, the difference varied in the range of 1.2% and -6.8%. Given a maximum of 10 minutes run time, while the CP model could obtain results for all instances, it could not achieve the optimal values for most problem instances. For those instances it did attain optimality (solved under 10 minutes), the model reported as good or better makespan values when compared to those obtained from the MILP model. This is because the CP model has better flexibility in assigning jobs to vessels, while the MILP is more restricted as it assigns jobs sequentially based on the job priority level. Such a restriction is needed in formulating the problem as MILP. For small size problems, the MILP model attained good makespan values faster than the CP model. As the size of these instances increased, the runtime needed for MILP to solve the problem increased sharply than the time needed for the CP model. The MILP model failed to obtain any results for large problems given the time limit while the CP model was able to obtain results in all the instances.



**Table 2** Run result summary for experiment 1 – for modified problem instances from Wari and Zhu (2016)

Set 1 (8 product mixes)							Set 2 (16 product mixes)						
Problem Instances	Total Batch Size	MILP model		CP model		Makespan Result Variation (hrs)	Problem Instances	Total Batch Size	MILP model		CP model		Makespan Result Variation (hrs)
		Make span (in hrs)	Run time (in s)	Make span (in hrs)	Run time (in s)				Make span (in hrs)	Run time (in s)	Make span (in hrs)	Run time (in s)	
1	80	130	16	130	20	0	21	80	130	22	125	600	-5
2	100	162	32	160	302	-2	22	100	163	40	155	600	-8
3	120	191	46	180	600	-11	23	120	192	62	188	600	-4
4	140	229	55	218	125	-11	24	140	225	148	222	600	-3
5	160	254	91	250	378	-4	25	160	250	158	252*	600	2
6	180	295	123	295	600	0	26	180	297	367	285	600	-12
7	200	318	134	320	600	2	27	200	316	600	315	600	-1
8	220	336	159	335	600	-1	28	220	349	540	352*	600	3
9	240	381	185	375	600	-6	29	240	379	600	380*	600	1
10	260	429	229	425	600	-4	30	260	420	600	425*	600	5
11	280	456	206	455	600	-1	31	280	-	600	452	600	-
12	320	512	310	502	600	-10	32	320	-	600	536	600	-
13	360	570	366	568	600	-2	33	360	-	600	610	600	-
14	400	664	465	665	600	1	34	400	-	600	660	600	-
15	440	-	600	698	600	-	35	440	-	600	728	600	-
16	480	-	600	762	600	-	36	480	-	600	797	600	-
17	520	-	600	852	600	-	37	520	-	600	894	600	-
18	560	-	600	938	600	-	38	560	-	600	970	600	-
19	600	-	600	992	600	-	39	600	-	600	1016	600	-
20	640	-	600	1040	600	-	40	640	-	600	1138	600	-

Set 3 (24 product mixes)						
Problem Instances	Total Batch Size	MILP model		CP model		Makespan Result Variation (hrs)
		Make span (in hrs)	Run time (in s)	Make span (in hrs)	Run time (in s)	
41	80	140	18	130	32	-10
42	100	165	34	158	600	-7
43	120	194	63	186	600	-8
44	140	223	121	218	600	-5
45	160	259	234	255	600	-4
46	180	286	227	286	600	0
47	200	335	295	318	600	-17
48	220	356	600	348	600	-8
49	240	-	600	382	600	-
50	260	-	600	408	600	-
51	280	-	600	448	600	-
52	320	-	600	510	600	-
53	360	-	600	580	600	-
54	400	-	600	652	600	-
55	440	-	600	714	600	-
56	480	-	600	796	600	-
57	520	-	600	848	600	-
58	560	-	600	932	600	-
59	600	-	600	970	600	-
60	640	-	600	1086	600	-

\*Note: Better makespan reported after 3600s run time: Problem instance 25 (248); Problem instance 28 (344); Problem instance 29 (272); Problem instance 30 (415);

Overall, the proposed model provided more flexibility for schedulers by relaxing the constraints to assign product mixes before optimizing the production. Batches of different products can be arranged freely without the need for prioritization of products. However, it made the CP

model more complex. As evident from the results, the proposed model attained good schedules for longer production horizons where the MILP model failed to attain any.

**4.2 Experimental Run 2**

The second experimental run tested the performance of the proposed CP model to optimize production schedules for the full capacity of the facility considering all the stages and equipment. The pasteurization process is synchronized with the filling step of the aging vessels. After completing aging (a discrete process), product mixes are continuously emptied from the vessel through the freezers and packaging lines as a continuous process to complete the production. The complete list of processing speed or time for each product and equipment are given in Appendix 2. It is important to note that the processing speed for the freezing and packaging processes vary and the proposed model assumes a speed buffering mechanism (such as temporary storage) exists between these two stages. Finally, in this experimental run, the step-function *WeekendBreak2* (168 hours scheduling week) was adopted to define a more explicit timeline for the results. Two values were set for the *Totalwait* decision expression: maximum integer -‘*maxint*’ for an unlimited amount of waiting time and zero for no waiting time. The earlier was attained by relaxing constraint 19 while the later was formulated by setting *MaxWaiting* to zero.

Because no large problem data can be found in the literature, we developed two sets of demand data to test the proposed model. Two batch sizes were assumed for the vessels in the facility: 4,000 and 8,000 Kg. Each product mix takes only one of these batch sizes, and multiple batches were used to generate demand volume for the mix. The first demand set predominantly consists of the 4K-batch of product mixes. The total batch size for this set started at 40 and grew to 400 batches for the last problem instance. In demand set 2, 8K dominated total demand. The two demand sets and additional parameters for the model are given in Appendix 2. The specific set of machines in which each product mix complete its processing were also given in this appendix.

Table 3 Run result summary for experiment 2

a. Set 1							b. Set 2						
Problem Instance	Total Batch	CP model			Run time (in s)	Number of constraints / variables	Problem Instance	Total Batch	CP model			Run time (in s)	Number of constraints / variables
		Make span (in hrs)	Make span (in hrs)	Difference					Make span (in hrs)	Make span (in hrs)	Difference		
		Totalwait maxint	Totalwait 0						Totalwait maxint	Totalwait 0			
1	40	40	41	1	600	994/777	11	40	69	70	1	600	844/692
2	80	72	73	1	600	3159/1602	12	80	182	187	5	600	2300/1343
3	120	177	179	2	600	5275/2290	13	120	414	414	0	600	3354/1937
4	160	220	223	3	600	10044/3236	14	160	-	453	-	600	6368/2700
5	200	-	349	-	600	12069/3731	15	200	-	453	-	600	9068/3422
6	240	-	379	-	600	19322/4676	16	240	-	608	-	600	13155/4049
7	280	-	432	-	600	22762/5122	17	280	-	892	-	600	16965/4694
8	320	-	555	-	600	25842/5559	18	320	-	931	-	600	19280/5318
9	360	-	944	-	600	30804/6225	19	360	-	701	-	600	32628/6522
10	400	-	697	-	600	47338/7409	20	400	-	853	-	600	32992/6845

The makespan results for two waiting time settings were given in Table 3. When waiting time with unlimited amount was incorporated into the model (similar setup to experiment 1), better makespan values were attained. However, the run under this setting could not obtain results for larger size problem instances in the given computation time limit. When the *MaxWaiting* was set to zero, i.e. waiting was not allowed, the proposed model attained good solutions for all problem instances. These schedules for both sets of demands extended over six production weeks in this case. For the same total batch sizes, the model attained varying makespan results for two demand sets. The cause for these variations could be associated with the variation of processing time between product mixes of the two batch sizes and the number of available processing machines (fewer number of vessels, and packaging lines for 8K). To provide some insights on the optimization size of each problem instant, the last column of each set in Table 3 gave the number of constraints and variables generated to solve the problem by the IBM CP Optimizer. As a potential future research direction, the impact of various *MaxWaiting* values (between the two extremes considered in this study, i.e., zero and *maxint*) can be explored further to improve the makespan results for large problem instances. For real-world cases, these time values can be determined based on other production decision parameters (such as finance, production lead time, and available labor).

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Figure 7 presented the schedule for problem instance 3 (makespan value of 177 hours). The schedule showed the bottleneck stage to be the pasteurizing units, unlike the cases in experiment 1 in which the packaging units were the bottleneck (Wari & Zhu, 2016). For the remaining stages, under-utilization of most of the machines was observed. The increased number of available machines gave product mixes additional alternatives to complete their processing. The figure also showed the weekend breaks for the pasteurization, freezer and packaging line processing stage where production was halted and restarted on the following week. Some aging vessels (specifically vessel 4, 5, 6 and 7) stored products over the weekends before the production commenced the freezing and packaging processes at the beginning of the second week. The total waiting time (*Totalwait*) was 343 hours where product batches from E, D, and A (two batches) were stored for the long periods (53, 52, 49, and 49 hours respectively). All waiting and aging times were shown as part of the vessel schedule in Figure 7.

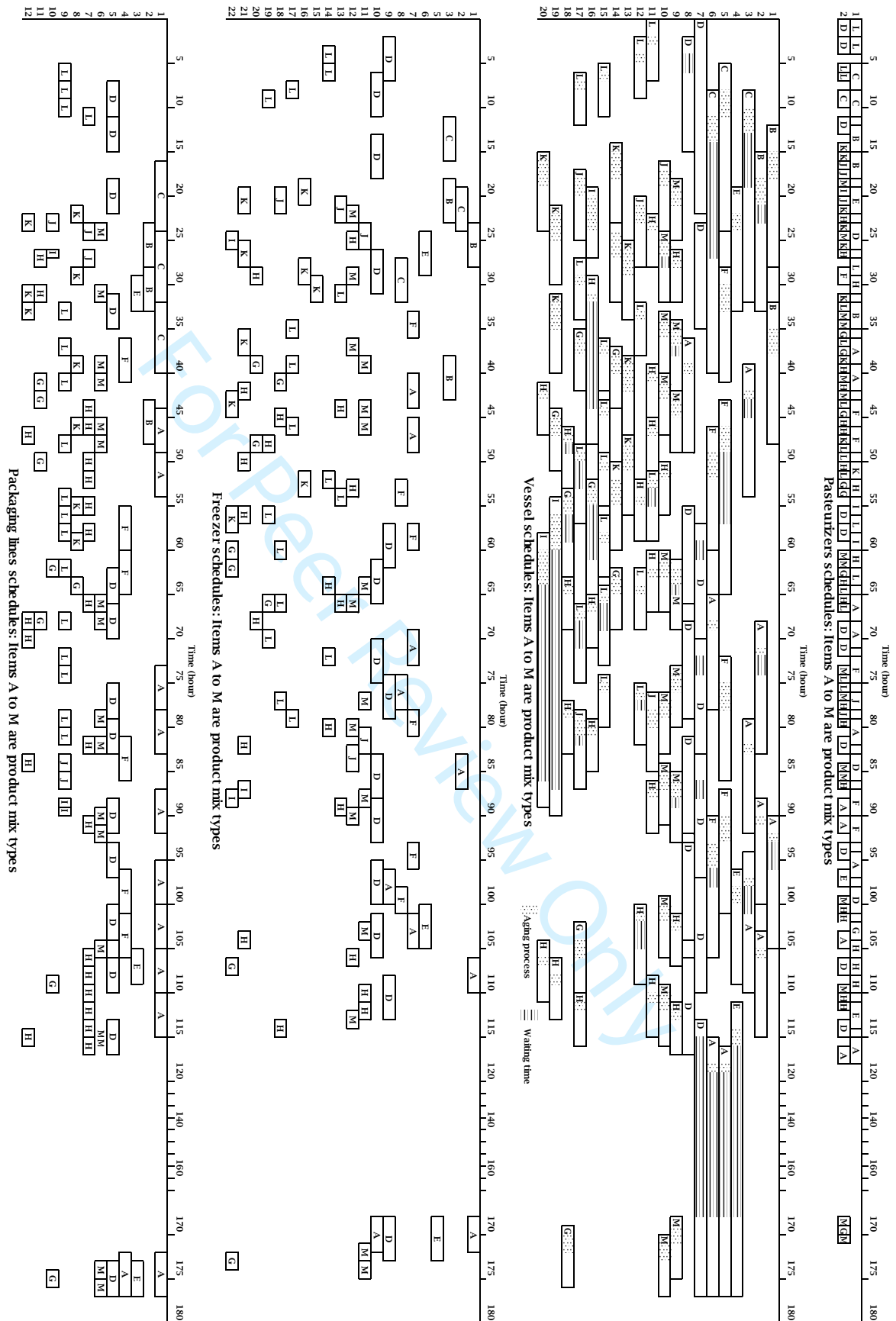


Figure 7. The production schedule for problem instance 3

5 Conclusion

The proposed CP model in this paper solved a large scheduling problem previously considered too complex and large due to optimization method limitations. Processing interval for each product mix and sequencing of these intervals in their respective machines were formulated as variables in the model. Constraints to prevent overlapping of processing interval, link processing stage, order processing stages, and restrict production only to the weekdays were integrated to emulate some limitations of the production environment. For a makespan objective, the model was compared with an MILP model using a modified larger demand data from the literature. The comparison showed that the model attained a makespan value comparable to the MILP model. However, for long scheduling horizon, it showed better performance by solving all problem instance where the MILP failed to attain results. For the primary challenge of this paper, the model was applied to a scheduling problem for multi-stage ice cream processing with multiple machines in each stage for a full-size production facility. Two demand data sets were developed to test the performance of the model under two conditions, i.e., *Totalwait* set to maximum integer and zero. For the first condition, the CP model reported better schedules. However, it could not obtain any solution for large problem instances. The model obtained good schedules for all problem instances which extended over multiple production weeks for the second condition.

The proposed CP models can optimize more complex scheduling problems and attain better results within a relatively short run time limit. It also gives practitioners the option of choosing between “better result but small-size problem capacity” and “good results but large-size problem capacity” approaches. The method could easily be integrated into an existing production system for a company. Future research directions could explore the technical and financial aspects of this integration. Other optimization objectives, such as Tardiness and Earliness, are also promising directions to extend research in this area. It would also be interesting to see the application of CP scheduling in other food processing industries (other processing industries) with even more

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3 manufacturing constraints. Scheduling problems could be combined with other production  
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5 function such as inventory, transportation and distribution, and production planning. The  
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7 performance of CP approach in these areas could also be a topic of interest.  
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10 The CP model in this paper obtained results within a short optimization runtime for large  
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12 problems. This could be used to provide timely inputs for decision making in production planning  
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14 and scheduling activities of any company. Such inputs can give companies a competitive edge in  
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16 the highly dynamic market currently observed in the industry.  
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Appendix

Appendix 1: Experiment 1 data

a. Modified problem instant data for three set types from Wari & Zhu (2016) (The numbers are in 1,000Kg)

Product Mix	Problem Instance (Set 1)																			
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
A	48	96	32	48	80	96	200	208	128	144	192	160	160	280	176	304	240	360	352	368
B	16	16	80	96	16	64	120	88	32	80	80	32	112	168	240	208	304	232	336	352
C	64	72	32	64	80	128	88	32	144	192	200	160	176	264	224	216	264	264	240	328
D	32	24	112	96	160	88	40	176	192	120	112	320	304	144	296	304	312	344	368	328
E	48	68	124	124	120	252	160	132	168	300	320	240	292	440	500	272	440	452	524	528
F	32	40	16	176	68	104	60	88	100	136	144	136	116	332	296	428	568	176	304	640
G	80	76	144	92	120	52	248	136	200	132	128	240	344	168	288	368	352	592	524	392
H	80	112	68	16	164	124	108	272	244	204	236	328	312	232	208	336	160	420	400	312
Batch Total	80	100	120	140	160	180	200	220	240	260	280	320	360	400	440	480	520	560	600	640

Product Mix	Problem Instance (Set 2)																			
	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40
A	56	64	48	16	32	64	128	80	96	136	64	80	96	176	216	176	104	200	176	176
B	16	8	48	80	88	16	16	56	96	48	104	96	136	72	120	112	152	72	152	248
C	8	16	32	56	40	48	32	64	64	88	80	104	120	96	80	64	120	88	144	176
D	24	16	8	56	16	64	32	48	16	40	104	120	104	88	72	144	112	192	160	208
I	12	68	40	100	8	152	136	88	80	84	56	252	188	260	156	92	136	260	284	372
J	20	24	88	20	36	20	48	96	176	124	72	40	116	132	104	176	188	112	204	152
K	44	20	12	136	28	60	40	60	24	68	116	196	196	92	112	156	156	180	160	388
L	32	8	12	20	84	60	16	108	24	160	100	80	128	80	132	80	172	104	116	136
E	16	16	64	16	24	16	32	48	128	32	64	32	64	96	72	216	216	168	160	128
F	8	24	24	8	112	48	48	56	48	40	104	56	64	96	168	72	144	112	192	120
G	24	32	16	56	8	128	64	80	32	104	48	184	136	176	96	136	152	256	192	224
H	40	72	32	24	16	64	144	80	64	120	48	88	104	168	200	224	216	288	240	200
M	20	4	16	20	176	28	8	60	32	36	120	48	80	48	204	176	164	172	100	148
N	8	8	16	68	12	20	16	80	32	80	124	88	148	44	36	112	136	116	192	232
O	60	104	104	20	68	140	208	64	208	108	156	160	84	348	336	380	328	460	412	224
P	28	40	56	20	60	16	80	68	112	76	68	36	88	112	168	176	192	148	224	168
Batch Total	80	100	120	140	160	180	200	220	240	260	280	320	360	400	440	480	520	560	600	640

Product Mix	Problem Instance (Set 3)																			
	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60
A	24	24	16	56	32	40	56	40	80	72	64	64	88	64	112	136	128	144	144	152
B	16	8	40	40	32	8	56	48	48	80	72	64	88	72	88	128	120	104	120	104
C	24	40	8	16	64	16	56	48	56	24	56	128	120	72	40	136	128	136	104	176
D	8	16	48	48	32	64	80	64	64	96	64	64	112	144	160	168	144	152	192	192
I	24	8	8	24	56	24	8	16	32	32	56	112	64	64	56	40	96	152	112	96
J	24	8	8	16	16	64	16	16	24	24	56	32	32	56	88	56	48	72	104	104
K	16	16	24	16	48	40	64	40	32	40	56	96	112	104	80	144	104	152	128	168
L	8	32	8	16	8	72	8	40	48	24	24	16	16	64	96	24	64	72	104	120
Q	8	8	16	16	16	8	16	24	24	32	32	32	32	56	40	40	56	72	56	48
R	16	8	56	40	8	16	40	64	48	96	88	16	48	104	112	96	112	88	120	72
S	16	40	16	16	16	16	16	56	56	32	48	32	32	56	48	48	88	80	64	88
T	8	16	24	16	40	80	64	40	32	40	40	80	104	72	120	136	96	88	160	200
E	20	16	36	40	60	88	136	52	56	76	76	120	196	132	164	292	152	180	224	300
F	4	36	28	40	8	4	8	64	76	68	36	16	16	60	72	20	112	80	80	56
G	12	12	20	40	44	8	64	32	52	60	44	88	108	64	68	140	116	136	112	128
H	20	36	32	20	4	84	8	68	56	52	72	8	12	96	136	36	92	56	140	132
M	40	12	24	40	8	4	4	36	52	64	104	16	12	104	68	48	84	128	76	28
N	12	12	12	40	148	136	80	24	52	52	36	296	228	100	188	172	212	276	336	376
O	20	20	4	20	36	8	40	24	40	24	44	72	76	68	32	100	80	120	68	104
P	8	8	4	40	12	20	28	12	48	44	20	24	40	96	64	64	64	108	76	68
U	24	36	52	20	12	68	80	88	56	72	100	24	92	100	140	184	120	124	152	196
V	4	12	4	40	8	16	8	16	52	44	12	16	16	68	60	20	64	92	68	44
W	52	36	40	40	80	16	80	76	76	80	144	160	160	104	96	212	196	184	176	212
X	8	52	88	20	36	44	24	140	72	108	104	72	60	144	152	56	196	100	188	156
Batch Total	80	100	120	140	160	180	200	220	240	260	280	320	360	400	440	480	520	560	600	640

### b. Processing parameters data

	Aging Time	Min VesselSize	Filling rate	Empty rate	Filling Time	Empty Time
A	1	8000	4500	1750	2	5
B	3	8000	4500	1500	2	5
C	3	8000	4500	1000	2	8
D	0	8000	4500	1500	2	5
I	2	8000	4500	1750	2	5
J	3	8000	4500	1500	2	5
K	2	8000	4500	2000	2	4
L	1	8000	4500	2000	2	4
Q	4	8000	4500	2500	2	3
R	2	8000	4500	1250	2	6
S	3	8000	4500	1500	2	5
T	1	8000	4500	2250	2	4
E	2	4000	4500	1750	1	2
F	2	4000	4500	2000	1	2
G	2	4000	4500	2000	1	2
H	2	4000	4500	2000	1	2
M	3	4000	4500	2250	1	2
N	2	4000	4500	2000	1	2
O	3	4000	4500	1750	1	2
P	2	4000	4500	2250	1	2
U	1	4000	4500	1500	1	3
V	2	4000	4500	2000	1	2
W	2	4000	4500	1750	1	2
X	2	4000	4500	2750	1	1

c. Processing changeover times (in hours)

	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S	T	U	V	W	X
A	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
B	1	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
C	1	1	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
D	1	1	1	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
E	1	1	1	1	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
F	1	1	1	1	1	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
G	1	1	1	1	1	1	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
H	1	1	1	1	1	1	1	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
I	1	1	1	1	1	1	1	1	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
J	1	1	1	1	1	1	1	1	1	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1
K	1	1	1	1	1	1	1	1	1	1	0	1	1	1	1	1	1	1	1	1	1	1	1	1
L	1	1	1	1	1	1	1	1	1	1	1	0	1	1	1	1	1	1	1	1	1	1	1	1
M	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0
N	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0
O	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0
P	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0
Q	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0
R	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0
S	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0
T	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0
U	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0
V	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0
W	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0
X	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0

d. Packaging line changeover times (in hours)

	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S	T	U	V	W	X
A	0	1	1	1	1	1	1	1	1	1	1	1												
B	0	0	1	1	1	1	1	1	1	1	1	1												
C	0	0	0	1	1	1	1	1	1	1	1	1												
D	0	0	0	0	1	1	1	1	1	1	1	1												
E	0	0	0	0	0	1	1	1	1	1	1	1												
F	0	0	0	0	0	0	1	1	1	1	1	1												
G	0	0	0	0	0	0	0	1	1	1	1	1												
H	0	0	0	0	0	0	0	0	1	1	1	1												
I	0	0	0	0	0	0	0	0	0	1	1	1												
J	0	0	0	0	0	0	0	0	0	0	1	1												
K	0	0	0	0	0	0	0	0	0	0	0	1												
L	0	0	0	0	0	0	0	0	0	0	0	0												
M													0	1	1	1	1	1	1	1	1	1	1	1
N													0	0	1	1	1	1	1	1	1	1	1	1
O													0	0	0	1	1	1	1	1	1	1	1	1
P													0	0	0	0	1	1	1	1	1	1	1	1
Q													0	0	0	0	0	1	1	1	1	1	1	1
R													0	0	0	0	0	0	1	1	1	1	1	1
S													0	0	0	0	0	0	0	1	1	1	1	1
T													0	0	0	0	0	0	0	0	1	1	1	1
U													0	0	0	0	0	0	0	0	0	1	1	1
V													0	0	0	0	0	0	0	0	0	0	1	1
W													0	0	0	0	0	0	0	0	0	0	0	1
X													0	0	0	0	0	0	0	0	0	0	0	0



## Appendix 2: Experiment 2 data

a. Problem instance data for two set types (The numbers are in 1,000Kg)

i	Problem Instant set 1									
	1	2	3	4	5	6	7	8	9	10
<b>A</b>	8	16	88	48	64	152	136	112	224	208
<b>B</b>	16	48	24	152	192	200	128	216	160	296
<b>C</b>	8	32	24	64	128	88	104	80	96	168
<b>D</b>	8	16	112	96	64	128	296	384	280	448
<b>E</b>	24	32	24	64	128	112	120	96	408	96
<b>F</b>	16	16	48	56	64	120	176	232	112	224
<b>G</b>	8	48	32	80	96	100	96	72	76	100
<b>H</b>	16	24	88	120	48	144	136	104	128	184
<b>I</b>	4	16	12	16	32	36	80	140	96	264
<b>J</b>	20	64	20	96	128	120	72	76	80	96
<b>K</b>	32	32	36	40	60	64	140	172	64	120
<b>L</b>	24	24	68	16	52	40	60	68	200	32
<b>M</b>	16	32	64	32	64	56	56	88	156	84
<b><math>\sum</math> Min NoBatch</b>	40	80	120	160	200	240	280	320	360	400
<b>8k</b>	10	20	40	60	80	100	120	140	160	180
<b>4k</b>	30	60	80	100	120	140	160	180	200	220

i	Problem Instant set 2									
	1	2	3	4	5	6	7	8	9	10
<b>A</b>	32	96	80	120	136	168	160	112	472	248
<b>B</b>	8	48	120	72	160	152	168	248	168	408
<b>C</b>	48	88	96	96	112	96	112	320	272	112
<b>D</b>	64	80	56	184	232	120	288	168	304	176
<b>E</b>	16	48	192	216	216	272	392	408	208	304
<b>F</b>	72	120	96	112	104	312	160	184	176	512
<b>G</b>	4	8	8	48	16	72	96	80	92	60
<b>H</b>	12	12	12	16	24	48	60	72	108	132
<b>I</b>	4	8	20	64	52	96	100	48	96	84
<b>J</b>	4	8	32	32	120	32	40	84	68	112
<b>K</b>	8	24	64	8	60	24	44	120	84	184
<b>L</b>	4	12	8	56	32	80	88	60	104	92
<b>M</b>	4	8	16	16	16	48	52	96	88	56
<b><math>\sum</math> Min NoBatch</b>	40	80	120	160	200	240	280	320	360	400
<b>8k</b>	30	60	80	100	120	140	160	180	200	220
<b>4k</b>	10	20	40	60	80	100	120	140	160	180

b. Processing parameters data (in Vessel size in kg and the rest in hours)

i	MinVessel	Fillingrate		AgingTime	Freeingrate	PackTime	Idle
	Size	1	2				
A	8000	3	2	1	4	5	2
B	8000	3	2	3	5	5	2
C	8000	3	2	3	5	8	2
D	8000	3	2	0	5	4	2
E	8000	3	2	2	5	4	2
F	8000	3	2	3	3	5	2
G	4000	2	1	2	2	2	2
H	4000	2	1	1	2	2	2
I	4000	2	1	4	2	1	2
J	4000	2	1	2	3	2	2
K	4000	2	1	3	3	2	2
L	4000	2	1	1	2	2	2
M	4000	2	1	2	2	2	2

c. Machine assignment for each product mix

	Pasturizer	Vessel	Freezer	Packaging
A	1, 2	1, 2, 3, 5, 6, 7, 8	1, 2, 7, 8, 9, 10	1, 4, 5
B	1	1, 2, 3	1, 2, 3, 4	1, 2, 5
C	1, 2	1, 2, 3, 5, 6	1, 2, 7, 8	1, 4
D	1, 2	7, 8	9, 10	5
E	1, 2	4	5, 6	3
F	1, 2	5, 6	7, 8	4
G	1, 2	20, 19, 18, 17, 16, 14, 13	22, 21, 20, 19, 18, 16, 15	8, 10, 11, 12
H	1, 2	20, 19, 18, 17, 16, 12, 11, 10, 9	22, 21, 20, 19, 18, 14, 13, 11, 12	6, 7, 10, 11, 12
I	1, 2	20, 19, 18, 17, 16, 15	22, 21, 20, 19, 18, 17	9, 10, 11, 12
J	1, 2	17, 16, 15, 12, 11, 10, 9	19, 18, 17, 14, 13, 12, 11	10, 9, 7, 6
K	1, 2	20, 19, 14, 13	22, 21, 16, 15	12, 8
L	1, 2	17, 16, 15, 12, 11	19, 18, 17, 14, 13	10, 9, 7
M	2	10, 9	12, 11	6

## d. Product specific processing rates

Product Code	Aging Period (hr)	Freezer Rate (Kg/hr)	Packaging Rate (Kg/hr)	Vessel Size (Kg)
A	1	2200	1750	8000
B	3	1600	1500	8000
C	3	1500	1000	8000
D	0	1500	1850	8000
E	2	1750	1900	8000
F	3	2400	1500	8000
G	2	2300	2000	4000
H	1	2100	2000	4000
I	4	2500	2750	4000
J	2	1250	1800	4000
K	3	1500	2300	4000
L	1	2300	2250	4000
M	2	1750	1800	4000

## e. Processing changeover times (in hours)

	A	B	C	D	E	F	G	H	I	J	K	L	M
A	0	1	1	1	1	1	1	1	1	1	1	1	1
B	1	0	1	1	1	1	1	1	1	1	1	1	1
C	1	1	0	1	1	1	1	1	1	1	1	1	1
D	1	1	1	0	1	1	1	1	1	1	1	1	1
E	1	1	1	1	0	1	1	1	1	1	1	1	1
F	1	1	1	1	1	0	1	1	1	1	1	1	1
G	1	1	1	1	1	1	0	0	0	0	0	0	0
H	1	1	1	1	1	1	0	0	0	0	0	0	0
I	1	1	1	1	1	1	0	0	0	0	0	0	0
J	1	1	1	1	1	1	0	0	0	0	0	0	0
K	1	1	1	1	1	1	0	0	0	0	0	0	0
L	1	1	1	1	1	1	0	0	0	0	0	0	0
M	1	1	1	1	1	1	0	0	0	0	0	0	0

## f. Packaging changeover times (in hours)

	A	B	C	D	E	F	G	H	I	J	K	L	M
A	0	2	2	2	2	2							
B	1	0	2	2	2	2							
C	1	1	0	2	2	2							
D	1	1	1	0	2	2							
E	1	1	1	1	0	2							
F	1	1	1	1	1	0							
G							0	2	2	2	2	2	2
H							1	0	2	2	2	2	2
I							1	1	0	2	2	2	2
J							1	1	1	0	2	2	2
K							1	1	1	1	0	2	2
L							1	1	1	1	1	0	2
M							1	1	1	1	1	1	0

Appendix 3: Nomenclature

Sets

$i \in$ Product Mix;	$x \in$ Freezer;
$b \in$ Batch of a Product Mix;	$v \in$ Vessel;
$u \in$ Pasteurizer;	$w \in$ Packaging lines;

Subsets

$PasteurizersFor_i$	Pasteurizers for processing Product Mix $i$ ;
$VesselsFor_i$	Vessels for processing Product Mix $i$ ;
$FreezersFor_i$	Freezers for processing Product Mix $i$ ;
$PackingLinesFor_i$	Packaging lines for processing Product Mix $i$ ;

Parameters

$Fillingrate_u$	Pasteurization rate for Pasteurizer $u$ ;
$AgingTime_i$	Aging time for Product Mix $i$ ;
$FreezerTime_i$	Freezer time for Product Mix $i$ ;
$Packrate_i$	Packaging rate for Product Mix $i$ ;
$MinVesselSize_i$	Minimum vessel size for Product Mix $i$ ;
$Demand_i$	Demand for Product Mix $i$ ;
$ProcessChOTimes_{ii'}$	Process change-over time between Product Mixes $i$ and $i'$ ;
$PackageChOTimes_{ii'}$	Packaging line change-over time between Product Mixes $i$ and $i'$ ;
$n$	Maximum number of weeks (= 7);
$N$	Set of processing week (1 to $n$ );
$Week$	Number of working hours per weeks (= 120 hours or 168 hours);
$idle$	Changeover time to idle state (= 2 hours);

*MaxWaiting* The maximum allowable total waiting time for a given schedule

#### Parameter functions

Minimum number of batches for Product Mix  $i$ ;  $MinNoBatch_i = Demand_i / MinVesselSize_i$

Pasteurization time for Product Mix  $i$ ;  $FillingTime_i = MinVesselSize_i / Fillingrate_i$

Packaging time for Product Mix  $i$ ;  $PackTime_i = MinVesselSize_i / Packrate_i$

Working hours: 1 when the facility is open & 0 when the facility is closed for weekend breaks;

$$stepFunction WeekendBreak1 = \begin{cases} 1 & \text{if } 0 < t \leq (l * Week) - 2 \\ 0 & \text{if } (l * Week) - 2 < t \leq l * Week \end{cases}$$

$$\forall t, t \in 1..n * Week, l \in N, Week = 120$$

$$stepFunction WeekendBreak2 = \begin{cases} 1 & \text{if } 0 < t \leq (l * Week) - 58 \\ 0 & \text{if } (l * Week) - 58 < t \leq l * Week \end{cases}$$

$$\forall t, t \in 1..n * Week, l \in N, Week = 168$$

#### Interval Decision Variables

*FillProcess<sub>ibu</sub>* Pasteurization interval for Product Mix  $i$ , batch  $b$  in unit  $u$  (optional);

*FillAssign<sub>ib</sub>* Pasteurization interval for assigning Product Mix  $i$ , and batch  $b$ ;

*FreezeProcess<sub>ibx</sub>* Freezing interval for Product Mix  $i$ , and batch  $b$  in freezer  $x$  (optional);

*FreezeAssign<sub>ib</sub>* Freezing interval for assigning Product Mix  $i$ , and batch  $b$ ;

*PackProcess<sub>ibw</sub>* Packaging interval for Product Mix  $i$ , batch  $b$  in line  $w$  (optional);

*PackAssign<sub>ib</sub>* Packaging interval for assigning Product Mix  $i$ , and batch  $b$ ;

*VesselProcess<sub>ibv</sub>* Vessel interval for aging Product Mix  $i$ , batch  $b$  in vessel  $v$  (optional);

*VesselAssign<sub>ib</sub>* Vessel interval for assigning Product Mix  $i$ , and batch  $b$ ;

#### Decision Variables

*WaitProcess<sub>Vib</sub>* Waiting decision variable for Product Mix  $i$ , batch  $b$  (positive integer);

Sequence Decision Variables

- PasturSeq<sub>u</sub>*            Pasteurization sequence for intervals *FillProcess<sub>ibu</sub>* in pasteurizer *u*;
- VesselSeq<sub>v</sub>*            Vessel sequence for intervals *VesselProcess<sub>ibv</sub>* in vessel *v*;
- PackSeq<sub>w</sub>*            Packaging sequence for intervals *EmptyProcess<sub>ibw</sub>* in line *w*;
- FreezerSeq<sub>x</sub>*           Freezing sequence for intervals *FreezeProcess<sub>ibx</sub>* in freezer *x*;

Decision Expression Variables

$$Totalwait = \sum_{i,b} WaitProcessV_{ib} \quad \forall i, b \quad i \in \text{Product Mix}, \quad b \in \text{Batch of a Product Mix}$$

IBM CP Optimizer built-in modeling variables and functions (IBM, 2016)

*Interval decision variable*:- Variable time interval whose exact position is yet to be determined.

*Sequence decision variable*:- Variable to determine the order of interval decision variables.

*stepFunction*:- a function to create a step-wise function (to create varying value 0-slope graphs)

*noOverlap*:- constraint function to prevent interval variables overlapping in a sequence.

*forbidExtent*:- constraint function to prevent interval variables overlapping a given time period.

*alternative*:- constraint function for creating an encapsulating interval over low-level intervals

*startAtStart*:- precedence constraint linking the start of a given interval with the start of another

*endAtEnd*:- precedence constraint linking the end of a given interval with the end of another

*endAtStart*:- precedence constraint linking the start of a given interval with the end of another

*endBeforeStart*:- precedence constraint to arrange the start of a given interval after the end of another

*startOf*:- variable that gives the starting time of a given interval variable

*endOf*:- variable that gives the ending time of a given interval variable

*lengthOf*:- variable that gives the length of time for a given interval variable (*endOf* – *startOf*)

## Appendix 4: MILP ice cream Model by (Wari &amp; Zhu, 2016)

## A. Nomenclature

Sets		$\beta Itransfer_i^{min}$ Minimum number of batches transferred from preceding week for product $i$
$b, b', b'' \in B$	Batches of products	
$i, i' \in I$	Product types	$\gamma_{iij}$ Sequence-dependent change-over time between product $i$ and $i'$ in units $j$
$j \in J$	Processing units	$\gamma_j^{min}$ Minimum sequence-dependent change-over time in packaging units $j$
$s \in S$	Processing stage	
$Itransfer \in I$	Product types transferred from preceding week	$IdleGamma_i$ Sequence-dependent change over time from product to idle state
Subsets		$\varepsilon_i^{life}$ Shelf life for product $i$ in processing
$I_j$	Product $i$ processed in unit $j$	$\zeta_i$ Demand for product $i$
$I_i^{Suc}$	Immediate successor of product $i$	$\theta_i$ Priority of product $i$ in the packaging unit $j$
$I_i^{Succ}$	Successors of product $i$	$\omega$ Long production horizon (Big M value)
$I_i^{Pred}$	Predecessor of product $i$	$\lambda_i$ Total number of aging vessels for product $i$
$I_i^{SP}$	Products that share the same packaging line with product $i$	$\mu_j^{max}$ Maximum capacity of aging vessel $j$
$J_i$	Units $j$ that process product $i$	$\rho_{ij}$ Processing rate of product $i$ in process line or packaging line $j$
$J2_i$	Units $j$ that process product $i$ in the second stage	$\tau_i^{ag}$ Minimum aging time for product $i$
$Mach_s$	Units $j$ that process in stage $s$	$\tau_i^{empty}$ Emptying time in aging vessel for product $i$
$J_{ij}^{last}$	Last unit $j$ that process product $i$	$\tau_i^{fill}$ Filling time in aging vessel for product $i$
Parameters		$\phi_j^{min}$ Minimum wait time to begin packaging in line $j$
$\alpha_j^{min}$	Minimum number of products assigned to packaging line $j$	$Workweeklength$ Available production horizon
$\beta_i^{min}$	Minimum number of batches for product $i$	$WeekNumber$ Processing week
Parameter Function		
$\beta_i^{min} = \zeta_i / \mu_j^{max}$ where $i \in I, j \in J2_i$		
$\beta Itransfer_i^{min} = \zeta_i / \mu_j^{max}$ where $i \in Itransfer, j \in J2_i$		



$$\tau_i^{empty} = \mu_j^{max} / \rho_{ij} \text{ where } i \in I, j \in Mach[s]: s = 3$$

$$\tau_i^{fill} = \mu_j^{max} / \rho_{ij} \text{ where } i \in I, j \in Mach[s]: s = 1$$

$$\omega = 1.2 (\phi_j^{min} + (\alpha_j^{min} - 1)\gamma_j + \min_j(\sum_{i \in I_j} \tau_i^{empty} \beta_i^{min})) \text{ where } j \in Mach[s] : s = 3$$

Decision Variables

$C_{ibs}$ Completion time for stage $s$ of batch $b$ of product $i$	$L_{0\ ibs}$ Starting time for stage $s$ of transferred batch $b$ of product $i$
$C_{0\ ibs}$ Completion time for stage $s$ of transferred batch $b$ of product $i$	$W_{ibs}$ Waiting (standing) time for stage $s$ of batch $b$ of product $i$
$C_{max}$ Makespan	$W_{0\ ibs}$ Waiting (standing) time for stage $s$ of transferred batch $b$ of product $i$
$CWeek_{ibs}$ Processing completion week for stage $s$ batch $b$ of product $i$	$\bar{X}_{ibib'}$ (Binary) 1 if batch $b$ of product $i$ processed before batch $b'$ of product $i'$
$L_{ibs}$ Starting time for stage $s$ of batch $b$ of product $i$	$Y_{ibsj}$ (Binary) 1 if batch $b$ of product $i$ in stage $s$ is processed in unit $j$

B. Model

Objective: Min  $C_{max}$

Constraints:

$$L_{ibs} + \tau_i^{fill} = C_{ibs} \quad \forall i, b \leq \beta_i^{min}, s = 1 \tag{1}$$

$$L_{ibs} + \tau_i^{fill} + \tau_i^{ag} + W_{ibs} + \tau_i^{empty} = C_{ibs} \quad \forall i, b \leq \beta_i^{min}, s = 2 \tag{2}$$

$$W_{ibs} \leq \varepsilon_i^{life} - \tau_i^{ag} \quad \forall i, b \leq \beta_i^{min}, s = 2 \tag{3}$$

$$L_{ibs} + \tau_i^{empty} = C_{ibs} \quad \forall i, b \leq \beta_i^{min}, s = 3 \tag{4}$$

$$L_{ibs} = L_{ibs-1} \quad \forall i, b \leq \beta_i^{min}, s = 2 \tag{5}$$

$$C_{ibs} = C_{ibs-1} \quad \forall i, b \leq \beta_i^{min}, s = 3 \tag{6}$$

$$C_{ibs} \leq L_{ib+1s} \quad \forall i, b \leq \beta_i^{min}, s = 3 \tag{7}$$

$$C_{0\ ibs} = W_{0\ ibs} + \tau_i^{empty} \quad \forall i, b \leq \beta_{Itransfer_i}^{min}, s = 2 : i \text{ in } Itransfer \tag{8}$$

$$C_{0\ ibs} = L_{0\ ibs} + \tau_i^{empty} \quad \forall i, b \leq \beta_{Itransfer_i}^{min}, s = 3 : i \text{ in } Itransfer \tag{9}$$

$$C_{0ibs} = C_{0ib{s-1}} \quad \forall i, b \leq \beta Itransfer_i^{min}, s = 3 : i \in Itransfer \quad (10)$$

$$C_{0ibs} = L_{0ib+1s} \quad \forall i, b \leq \beta Itransfer_i^{min} - 1, s = 3 : i \in Itransfer \quad (11)$$

$$\sum Y_{ibsj} = 1 \quad \forall i, i \in I, b \leq \beta_i^{min}, s = 2, \quad (12)$$

$$Y_{ibsj} = 1 \quad \forall i, i \in Itransfer, b = 1, s = 2, j = first(J2_i) \quad (13)$$

$$Y_{ibsj} = Y_{ib+1sj+1} \quad \forall i, i \in Itransfer, b \leq \beta Itransfer_i^{min} - 2, s = 2, j \in J2_i : \beta Itransfer_i^{min} \leq \beta_i^{min} \quad (14)$$

$$Y_{ibsj} = Y_{ib+1sj+1} \quad \forall i, i \in Itransfer, b \leq \beta_i^{min} - 2, s = 2, j \in J2_i : \beta Itransfer_i^{min} > \beta_i^{min} \quad (15)$$

$$Y_{ibsj} = Y_{i'b'sj+1} \quad \forall i, i \in Itransfer, b = \min(\beta Itransfer_i^{min} - 1, \beta_i^{min}), i' \in IPred_i, b' = \beta Itransfer_{i'}^{min}, s = 2, j \in J2_i : \text{card}(IPred_i) > 0 \quad (16)$$

$$Y_{ibsj} = Y_{i'b'sj+1} \quad \forall i, i \in Itransfer, b = \beta Itransfer_i^{min} - 1, i' \in IPred_i, b' = \beta Itransfer_{i'}^{min}, s = 2, j \in J2_i : \beta Itransfer_i^{min} \leq \beta_i^{min}, \text{card}(IPred_i) = 0 \quad (17)$$

$$Y_{ibsj} = Y_{i'b'sj+1} \quad \forall i, i \in Itransfer, b = \beta Itransfer_i^{min} - 1, i' \in ISuc_i, b' = \beta Itransfer_{i'}^{min}, s = 2, j \in J2_i : \beta Itransfer_i^{min} - 1 \leq \beta_i^{min}, \text{card}(IPred_i) = 0 \quad (18)$$

$$Y_{ibsj} = Y_{i'b'sj+1} \quad \forall i, i \in I, b = \beta_i^{min}, i' \in ISuc_i, b' = \beta Itransfer_{i'}^{min}, s = 2, j \in J2_i \quad (19)$$

$$Y_{ibsj} = Y_{ib+1sj+1} \quad \forall i, i \in I, \beta Itransfer_i^{min} \leq b \leq \beta_i^{min}, s = 2, j \in J2_i \quad (20)$$

$$L_{ib's} \geq C_{ibs} + \gamma_{ii'} - \omega(1 - \bar{X}_{ibi'b'}) \quad \forall i, b \leq \beta_i^{min}, i' \in I, b' \leq \beta_{i'}^{min}, s = 1, j \in J_i \cap J_{i'} \cap Mach[s] : i < i' \quad (21)$$

$$L_{ib's} \geq C_{ib's} + \gamma_{i'i} - \omega \bar{X}_{ibi'b'} \quad \forall i, b \leq \beta_i^{min}, i' \notin I, b' \leq \beta_{i'}^{min}, s = 1, j \in J_i \cap J_{i'} \cap Mach[s] : i < i' \quad (22)$$

$$L_{ib's} \geq C_{ibs} + \gamma_{ii'} \quad \forall i, b \leq \beta_i^{min}, i' \in I_i^{SP}, b' \leq \beta_{i'}^{min}, s \neq 2, j \in J_i \cap J_{i'} \cap Mach[s] : \theta_i < \theta_{i'} \quad (23)$$

$$L_{ib's} \geq C_{ibs} + \gamma_{ii'} - \omega(2 - Y_{ibsj} - Y_{i'b'sj}) \quad \forall i, b \leq \beta_i^{min}, i' \in I_i^{SP}, b' \leq \beta_{i'}^{min}, s = 2, j \in J_i \cap J_{i'} \cap Mach[s] : \theta_i < \theta_{i'} \quad (24)$$

$$L_{ib's} \geq C_{ibs} \quad \forall i, b \leq \beta_i^{min}, b' \leq \beta_{i'}^{min}, s = 2, j \in J_i \cap Mach[s] : b < b' \quad (25)$$

$$L_{ib's} \geq C_{ibs} - \omega(2 - Y_{ibsj} - Y_{i'b'sj}) \quad \forall i, b \leq \beta_i^{min}, b' \leq \beta_{i'}^{min}, s = 2, j \in J_i \cap Mach[s] : b < b' \quad (26)$$

$$L_{ib's} = C_{0ibs} + \gamma_{i'i} - \omega(2 - Y_{ibsj} - Y_{i'b'sj}) \quad \forall i, b \leq \beta Itransfer_i^{min} - 1, i' \in I, \beta_i^{min} \leq b' \leq \beta_{i'}^{min}, s = 2, j \in J_i \cap Mach[s] : i \in Itransfer \quad (27)$$

$$L_{ib's} = C_{0ibs} + \gamma_{i'i} \quad \forall i, b \leq \beta Itransfer_i^{min} - 1, i' \in I, \beta_i^{min} \leq b' \leq \beta_{i'}^{min}, s = 3, j \in J_i \cap Mach[s] : i \in Itransfer \quad (28)$$

$$C_{Max} \geq C_{ibs} \quad \forall i, b \leq \beta_i^{min}, s \geq 2 \tag{29}$$

$$C_{max} = \phi_j^{min} + (\alpha_j^{min} - 1)\gamma_j + \min \sum_{i \in I_j} \tau_i^{fill} \beta_i^{min} \quad \forall j \in Mach[s] : s = 3 \tag{30}$$

$$Y_{ibsj} \in \{0,1\} \quad \forall i, b \leq \beta_i^{min}, s = 2, j \in J_i \cap Mach[s] \tag{31}$$

$$\bar{X}_{ibi'b'} \in \{0,1\} \quad \forall i, b \leq \beta_i^{min}, i' \in I_i^{SP}, b \leq \beta_{i'}^{min} : i < i' \tag{32}$$

$$L_{ibs}, C_{ibs}, C_{0ibs} \geq 0 \quad \forall i, b \leq \beta_i^{min}, s \in S \tag{33}$$

$$W_{ibs}, W_{0ibs} \geq 0 \quad \forall i, b \leq \beta_i^{min}, s = 2 \tag{34}$$

$$L_{ibs} \leq (n * Workweeklength) \&\& C_{ibs} \geq ((n * Workweeklength) - IdleGamma_i) \Rightarrow L_{ibs} \geq (n) * Workweeklength \quad \forall i, j \in J_s, i \in I, \beta Itransfer_i^{min} \leq b \leq \beta_{i'}^{min}, s = 3, n \in WeekNumber \tag{35}$$

$$L_{ibs} \geq ((n * Workweeklength) - IdleGamma_i) \&\& L_{ibs} \leq (n * Workweeklength) \Rightarrow L_{ibs} \geq (n) * Workweeklength \quad \forall i, j \in J_s, i \in I, \beta Itransfer_i^{min} \leq b \leq \beta_{i'}^{min}, s = 1, n \in WeekNumber \tag{36}$$

$$CWeek_{ibs} \leq (C_{ibs} / (Workweeklength - IdleGamma_i)) + 1 \quad \forall i, i \in I, j \in J, s \in S \tag{37}$$

$$CWeek_{ibs} \geq C_{ibs} / (Workweeklength - IdleGamma_i) \quad \forall i \in I, j \in J, s \in S \tag{38}$$

Dear Editor-in-Chief, Editor and Reviewers:

The reviewer comment drove us to think more carefully about our presentation. We have re-run the experiments and tried to explain more clearly. The revision is highlighted in red color in the paper. Please find below the response to the reviewer comment.

We greatly appreciate your consideration and hope this revision can meet your expectation.

Sincerely

Authors

**Reviewer(s)' Comments to Author:**

**Reviewer: 1**

**Comments to the Author**

I think the paper is now very close to acceptance \*but\* there is still an important issue to be fixed: with the new experimental results shown on Table 2, again as it used to be in the original version of the article, for some instances where both MILP and CP finish before the time limit (600s) and thus prove optimality, the value of the optimal makespan is different for MILP and for CP. This does not make any sense. For example for instance 1, MILP finds an optimal of 129 whereas CP finds a "worse" optimal value at 130. For instance 2, it is the opposite: CP finds a "better" optimal value than MILP. This should be fixed in the final version.

**Answer:** Thank you. We have made the correction. We have double checked the models. We re-ran all MILP models and presented a revised Table 2.

There is a small difference in the implementation between the MILP model and the CP model, besides being two different modeling methods. The MILP model is restricted in its ability to assign jobs to processing vessels because of the constraints it incorporates. Specifically, it assigns jobs sequentially based on the job's priority level. The CP allows the selection of the vessels to improve the makespan value. Hence, the makespan results of the CP should always be as good as or better than the MILP model's results if both models attained optimal results. The new Table 2 reflects this.

For problems instances 25, 28, 29, and 30, the CP results are worse given the 600 seconds limit. To prove that the CP model should actually find a better makespan value for these instances too, we ran these instances for 3,600 seconds (1 hour), and results do show that they can achieve better results (shorter makespan) than those of MILP model, given enough computation time. This is provided as a note below Table 2.