

H.P. WILLIAMS

LONDON SCHOOL OF
ECONOMICS

MODELS FOR SOLVING
THE
TRAVELLING SALESMAN PROBLEM

h.p.williams@lse.ac.uk

STANDARD FORMULATION OF THE (ASYMMETRIC) TRAVELLING SALESMAN PROBLEM

Conventional Formulation:

(cities $1, 2, \dots, n$) (Dantzig, Fulkerson, Johnson) (1954). x_{ij} is a link in tour

Minimise:

$$\sum_{i,j} c_{ij} x_{ij}$$

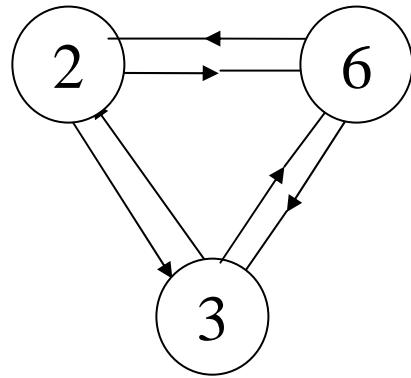
subject to:

$$\sum_i x_{ij} = 1 \quad \text{all } j$$

$$\sum_j x_{ij} = 1 \quad \text{all } i$$

$$\sum_{i,j \in S} x_{ij} \leq |S| - 1 \quad \text{all } S \subset \{2, \dots, n\}$$

e.g.



$$x_{32} + x_{26} + x_{63}$$

$$+ x_{23} + x_{62} + x_{36} \leq 2$$

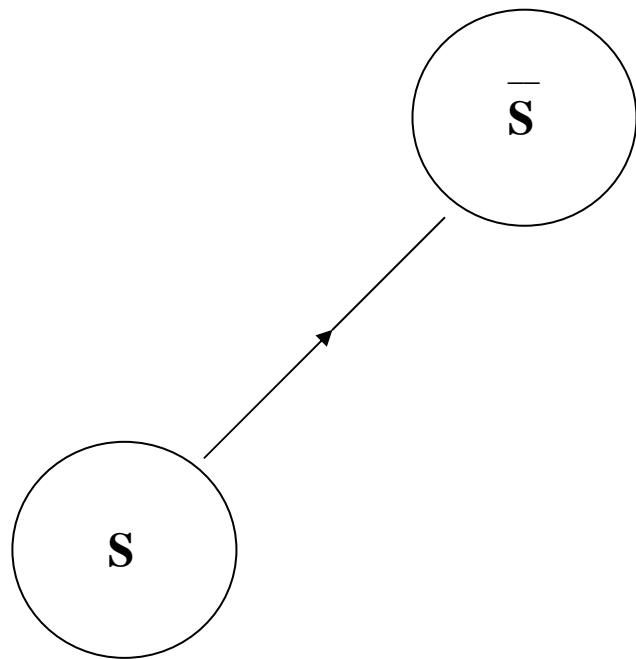
$$\Theta(2^n) \text{ Constraints} = (2^{n-1} + n - 2)$$

$$\Theta(n^2) \text{ Variables} = n(n - 1)$$

EQUIVALENT FORMULATION

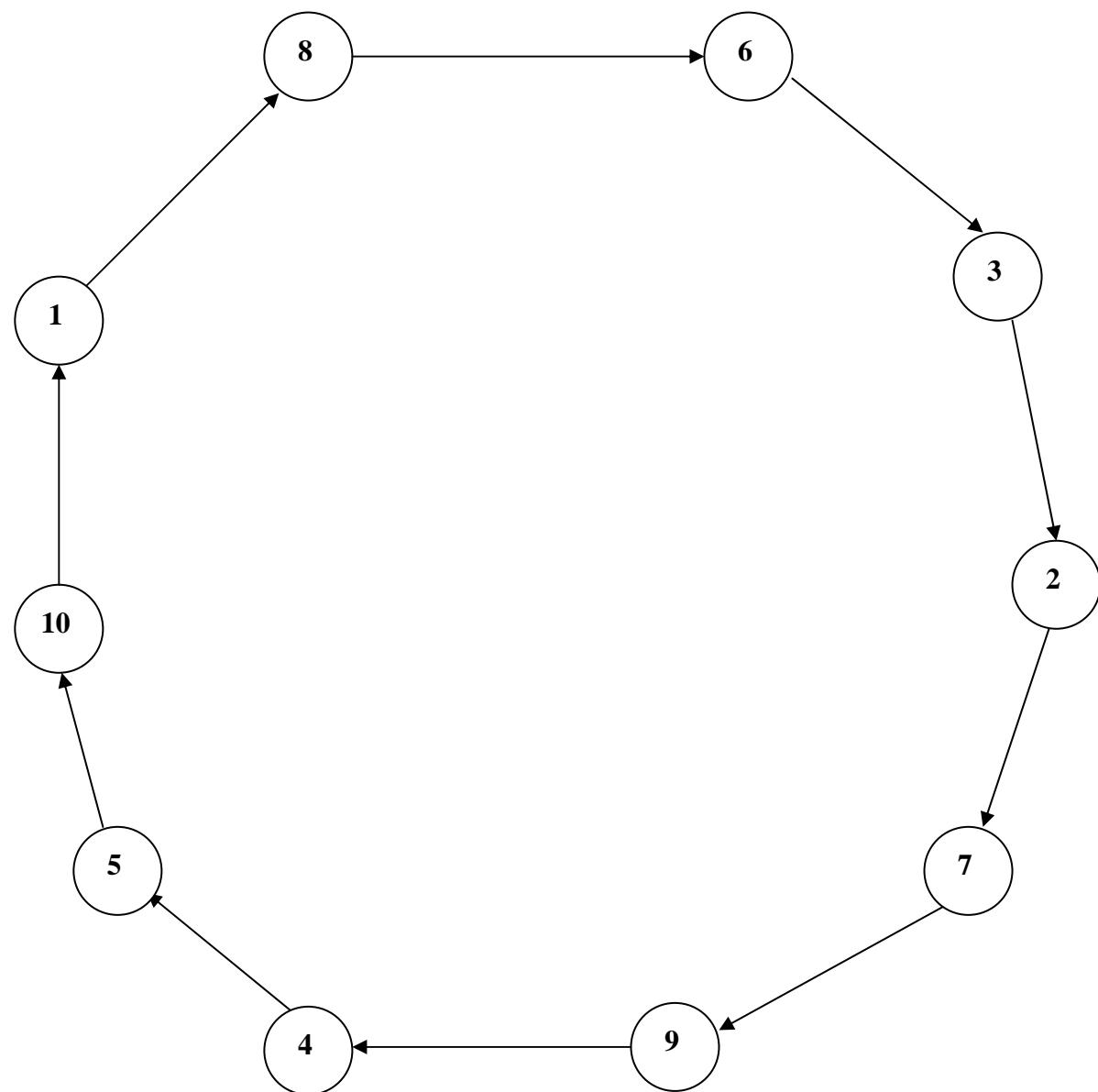
Replace subtour elimination
constraints with

$$\sum_{\substack{i \in S \\ j \in \bar{S}}} x_{ij} \geq 1 \quad \text{all } S \subset \{1, 2, \dots, n\}$$



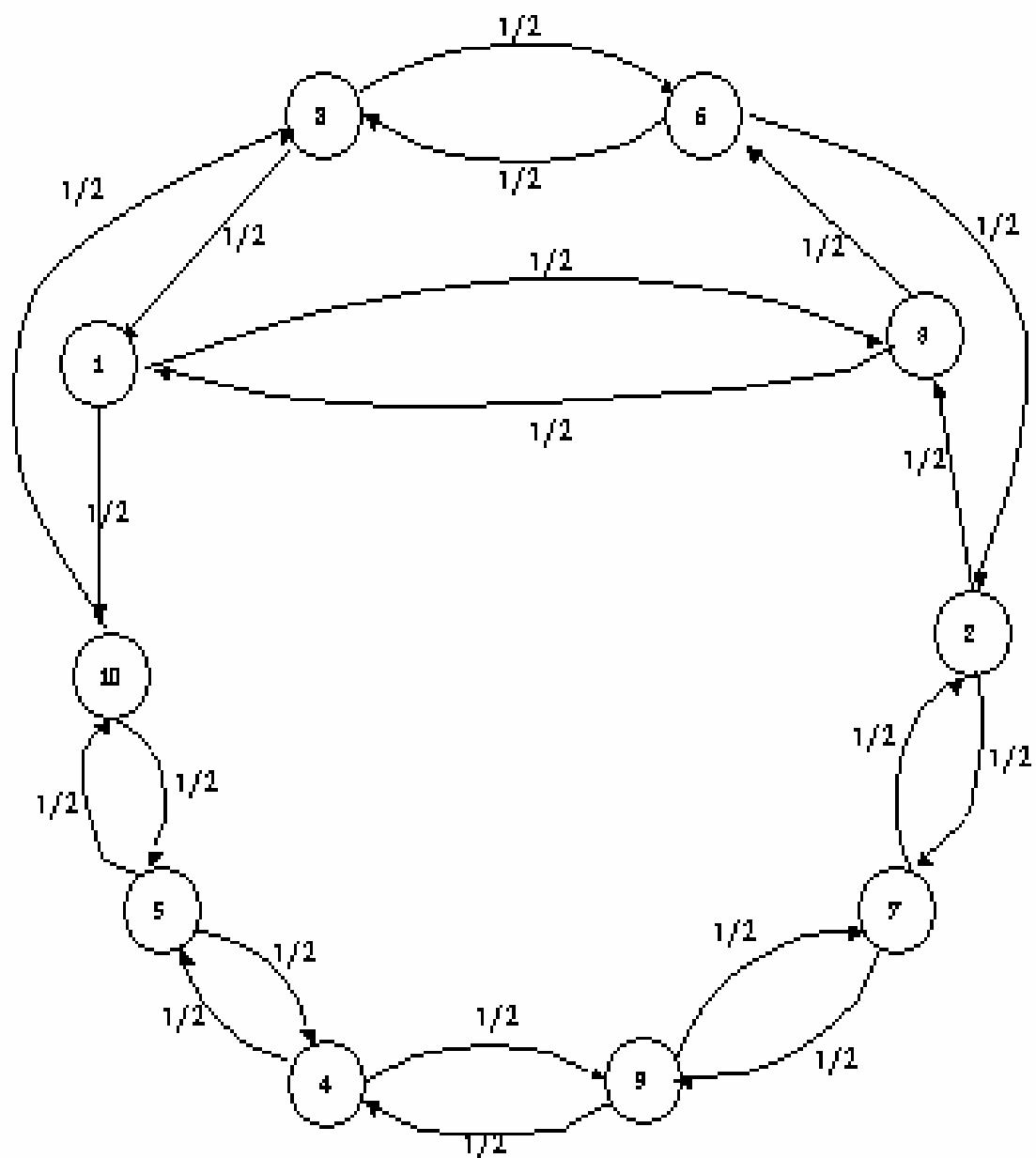
Add second set of constraints for all i in S and
subtract from subtour elimination constraints for S

OPTIMAL SOLUTION TO A 10 CITY TRAVELLING SALESMAN PROBLEM



Cost = 881

FRACTIONAL SOLUTION FROM CONVENTIONAL (EXPONENTIAL) FORMULATION



Cost = 878 (Optimal Cost = 881)

Sequential Formulation (Miller, Tucker, Zemlin (1960))

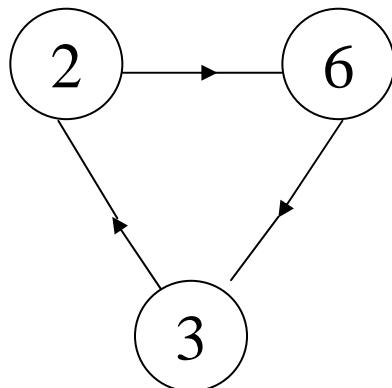
u_i = Sequence Number in which city i visited

Defined for $i = 2, 3, \dots, n$

Subtour elimination constraints replaced by

S: $u_i - u_j + nx_{ij} \leq n - 1 \quad i, j = 2, 3, \dots, n$

Avoids subtours
but allows total tours (containing city 1)



$$u_2 - u_6 + nx_{26} \leq n-1$$

$$u_6 - u_3 + nx_{63} \leq n-1$$

$$u_3 - u_2 + nx_{32} \leq n-1$$



$$3n \leq 3(n - 1)$$

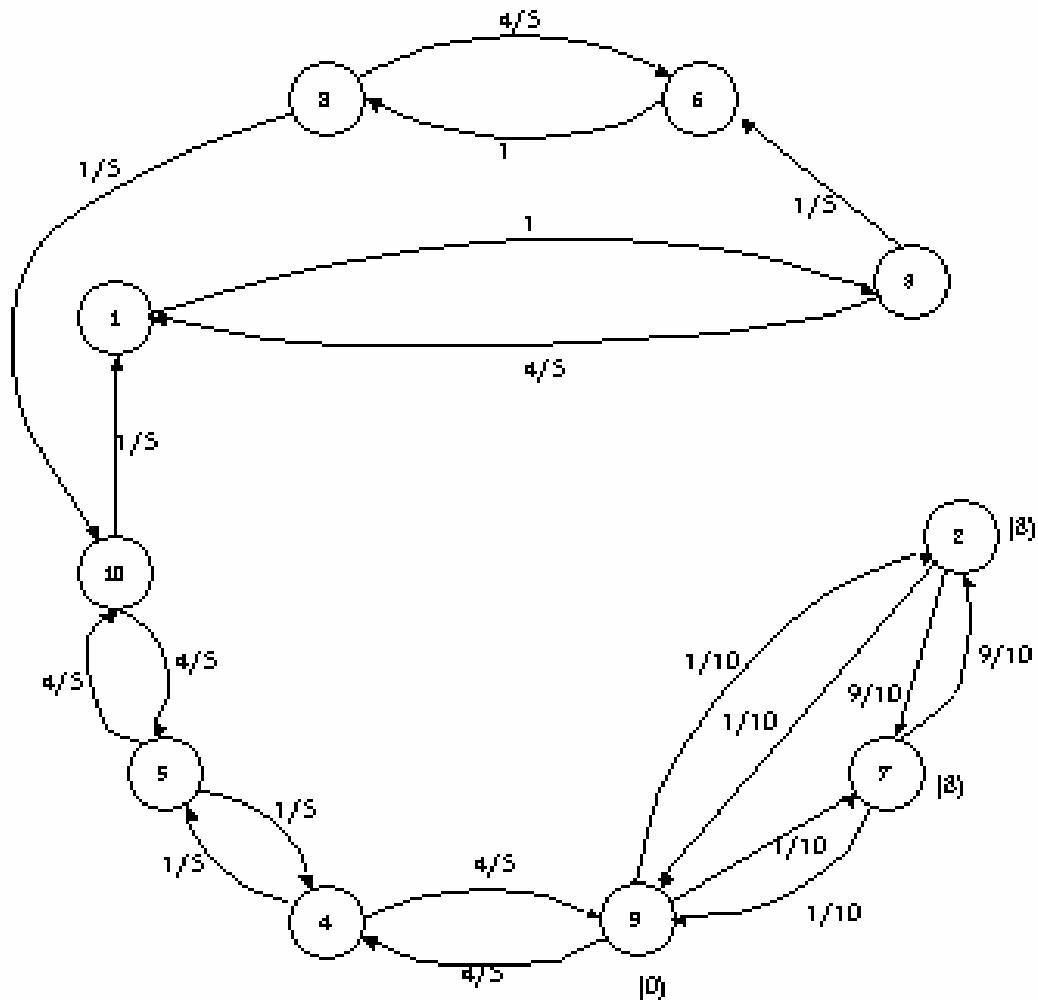
$$O(n^2) \text{ Constraints} = (n^2 - n + 2)$$

$$O(n^2) \text{ Variables} = (n - 1)(n + 1)$$

Weak but can add 'Logic Cuts'

e.g. $u_k \geq 1 + x_{ij} + x_{jk} - x_{1j}$

FRACTIONAL SOLUTION FROM SEQUENTIAL FORMULATION



Subtour Constraints Violated : e.g. $x_{27} + x_{72} \leq 1$

Logic Cuts Violated: e.g. $u_9 \geq 1 + x_{27} + x_{79} - x_{17}$

Cost = $773 \frac{3}{5}$ (Optimal Cost = 881)

Flow Formulations

Single Commodity (Gavish & Graves (1978))

Introduce extra variables ('Flow' in an arc)

Replace subtour elimination constraints by

F1:

$$y_{ij} \leq (n-1)x_{ij} \quad \text{all } i, j$$

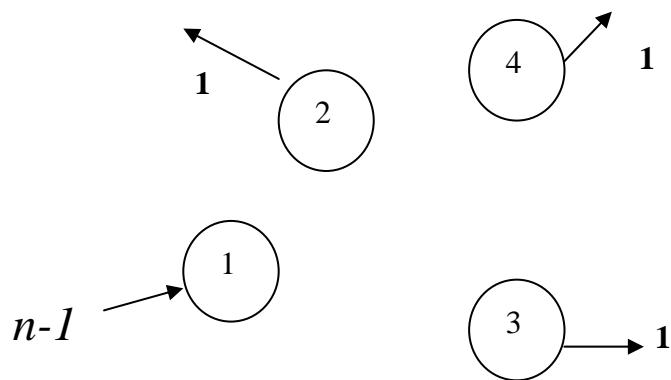
$$\sum_j y_{1j} = n-1$$

$$\sum_i y_{ij} - \sum_k y_{jk} = 1 \quad \text{all } j \neq 1$$

Can improve (F1') by amended constraints:

$$y_{ij} \leq (n-2)x_{ij} \quad \text{all } i, j \neq 1$$

Network Flow formulation in y_{ij} variables over complete graph

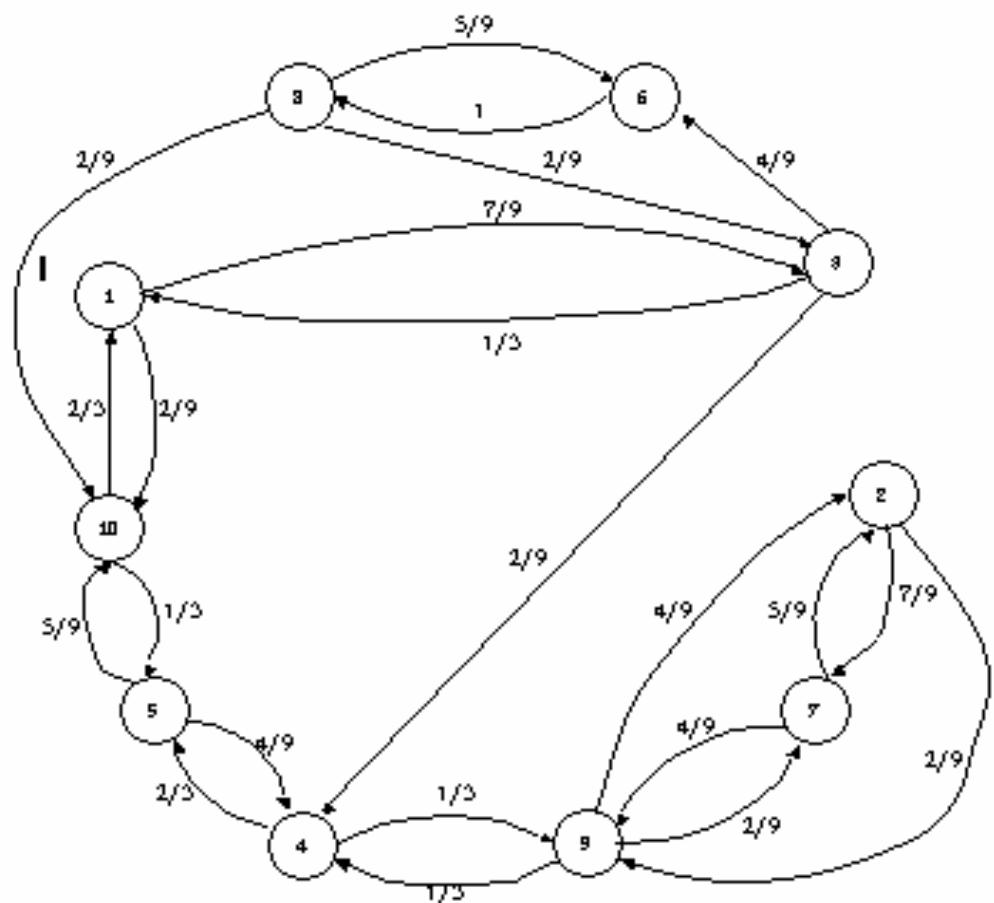


Graph must be connected. Hence no subtours possible.

$$0(n^2) \quad \text{Constraints} \quad = n(n+2)$$

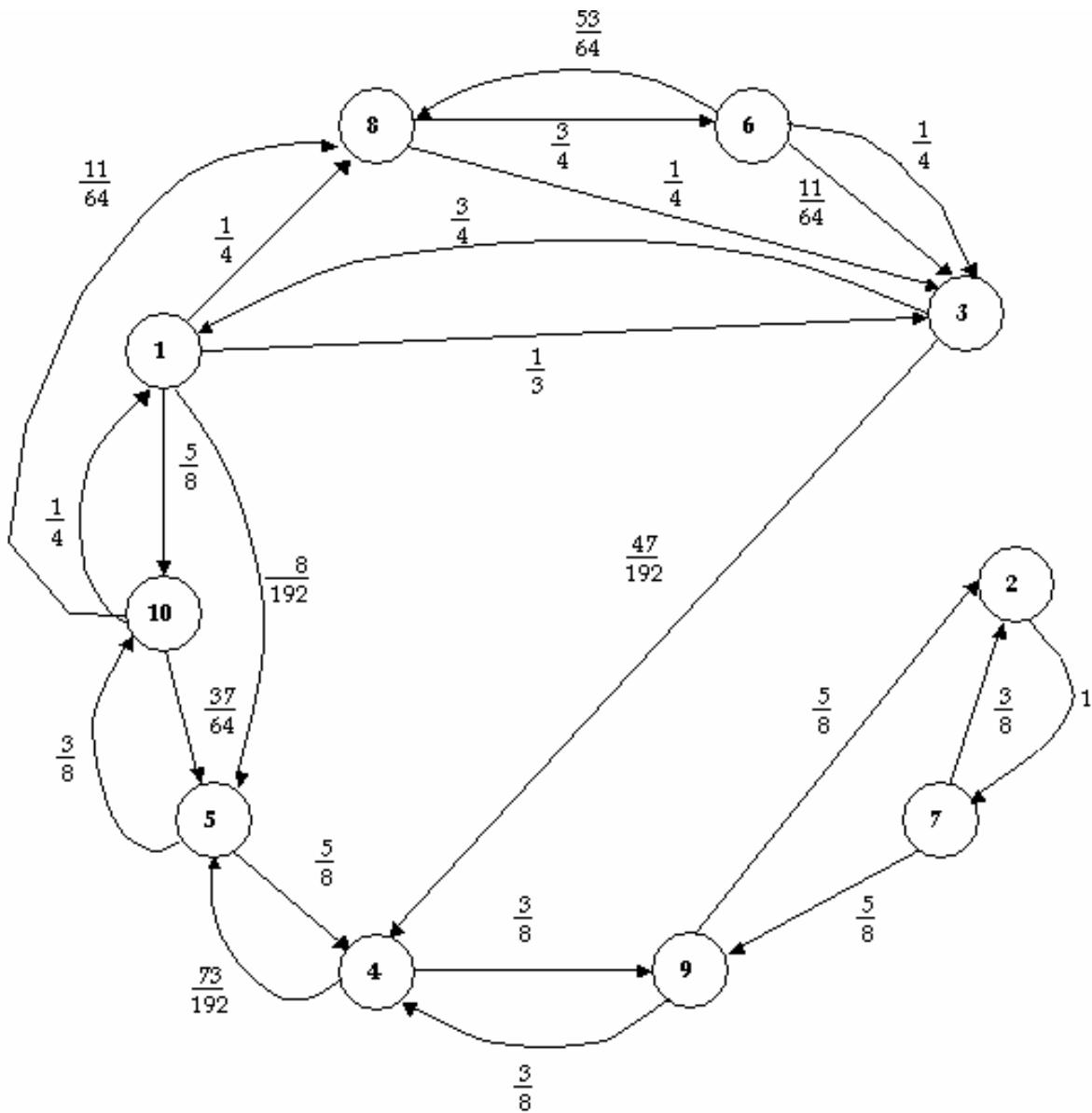
$$0(n^2) \quad \text{Variables} \quad = 2n(n-1)$$

FRACTIONAL SOLUTION FROM SINGLE COMMODITY FLOW FORMULATION



Cost = $794 \frac{2}{9}$ (Optimal solution = 881)

FRACTIONAL SOLUTION FROM MODIFIED SINGLE COMMODITY FLOW FORMULATION



$$\text{Cost} = 794 \frac{43}{48} \quad (\text{Optimal solution} = 881) \quad (192=3 \times 64)$$

Two Commodity Flow (Finke, Claus Gunn (1983))

y_{ij} is flow of commodity 1 in arc $i \rightarrow j$

z_{ij} is flow of commodity 2 in arc $i \rightarrow j$

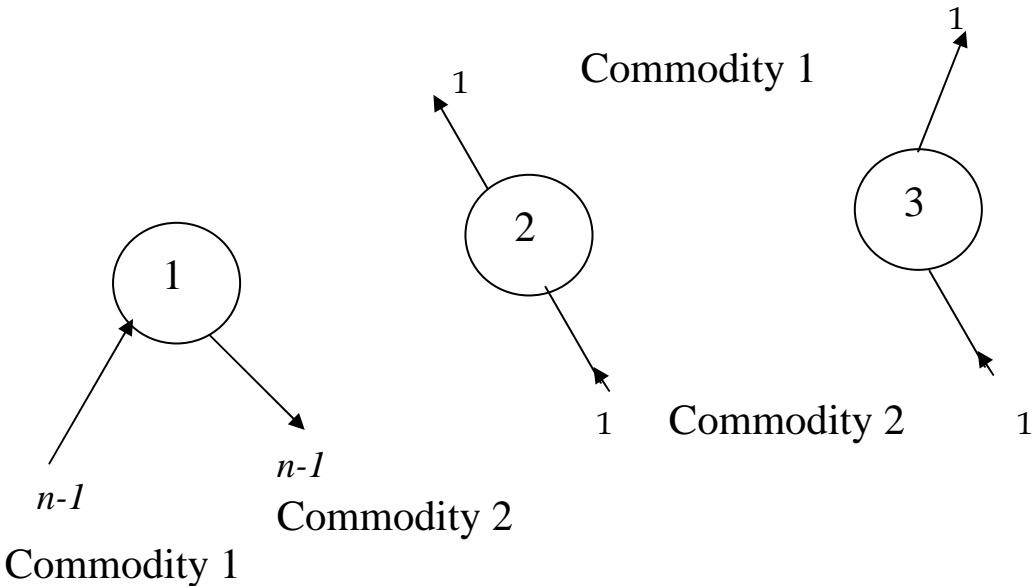
$$\begin{aligned} \sum_j y_{ij} - \sum_j y_{ji} &= -1 \quad i \neq 1 \\ &= n-1 \quad i = 1 \end{aligned}$$

F2: $\sum_j z_{ij} - \sum_j z_{ji} = 1 \quad i \neq 1$

$$= -(n-1) \quad i = 1$$

$$\sum_j z_{ij} - \sum_j z_{ji} = n-1 \quad \text{all } i$$

$$y_{ij} + z_{ij} = (n-1)x_{ij} \quad \text{all } i, j$$



$$0(n^2) \text{ Constraints} = n(n+4)$$

$$0(n^2) \text{ Variables} = 3n(n-1)$$

Multi-Commodity (Wong (1980) Claus (1984))

“Dissaggregate” variables

y_{ij}^k is flow in arc destined for k

$$y_{ij}^k \leq x_{ij} \text{ all } i, j, k$$

F3 $\sum_i y_{ik}^k = 1 \quad \sum_i y_{1i}^k = 1 \quad \sum_i y_{i1}^k = 0 \quad \sum_j y_{kj}^k = 0 \text{ all } k$

$$\sum_i y_{ij}^k = \sum_i y_{ji}^k \text{ all } j, k, j \neq 1, j \neq k.$$

$$0(n^3) \text{ Constraints} = n^3 - 2n^2 + 6n - 3$$

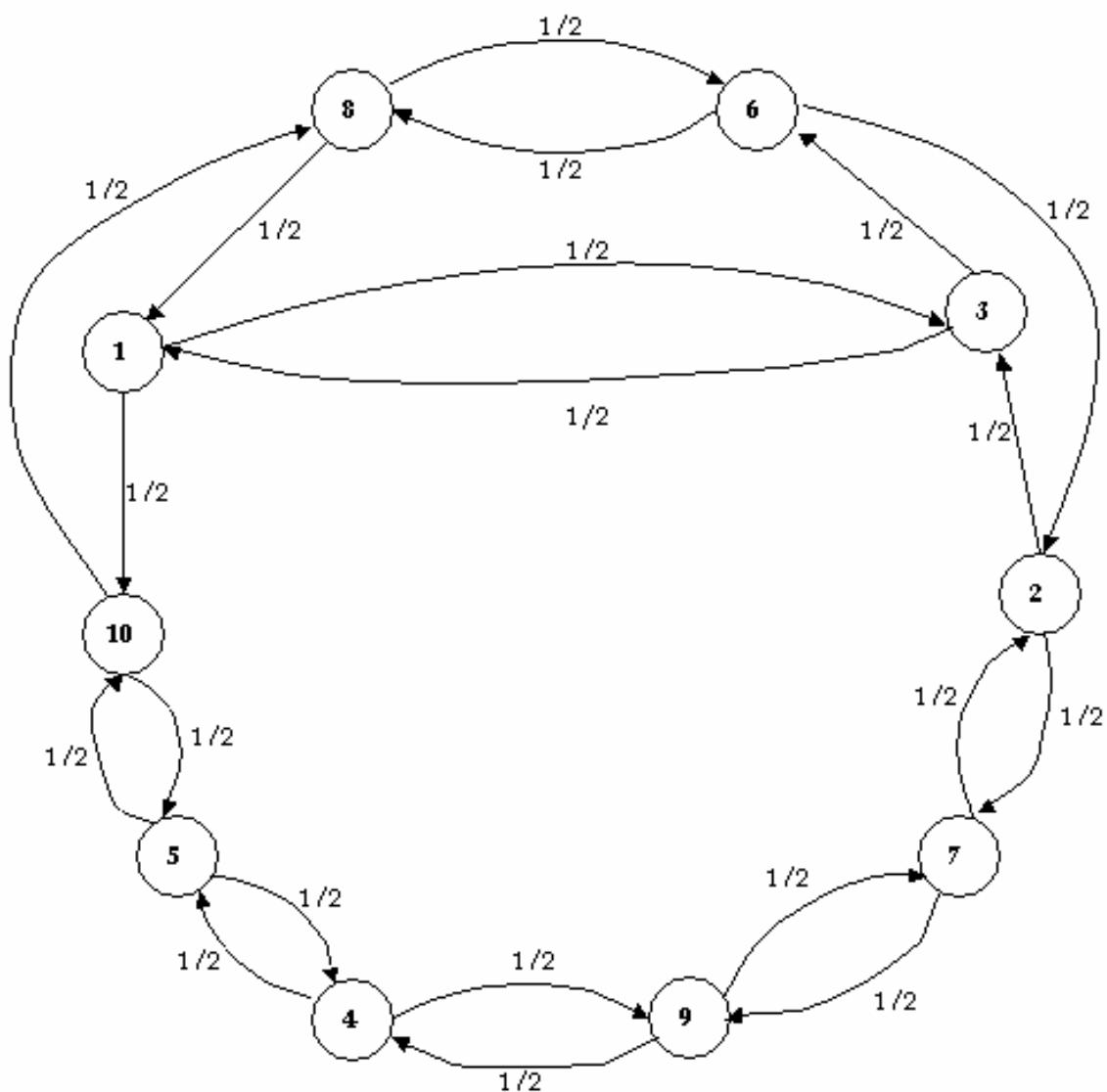
$$0(n^3) \text{ Variables} = n^2(n-1)$$

LP Relaxation of equal strength to Conventional Formulation.

But of polynomial size.

Tight Formulation of Min Cost Spanning Tree
+ (Tight) Assignment Problem

**FRACTIONAL SOLUTION FROM MULTI
COMMODITY FLOW FORMULATION (=
FRACTIONAL SOLUTION FROM CONVENTIONAL
(EXPONENTIAL) FORMULATION)**



Cost = 878 (Optimal Cost = 881)

Stage Dependent Formulations

First (Fox, Gavish, Graves (1980))

$$\begin{aligned}
 &= 1 \text{ if arc } i \rightarrow j \text{ traversed at stage } t \\
 &= 0 \text{ otherwise}
 \end{aligned}$$

T1:

$$\begin{aligned}
 \sum_{i,j,t} y_{ij}^t &= n \\
 \sum_{j=1}^n \sum_{t=2}^n t y_{ij}^t - \sum_{j=1}^n \sum_{t=1}^n t y_{ji}^t &= 1 \quad i = 2, 3, \dots, n
 \end{aligned}$$

(Stage at which i left 1 more than stage at which entered)

$$y_{i1}^t = 0, t \neq n$$

$$y_{1j}^t = 0, t \neq 1$$

$$y_{ij}^1 = 0, i \neq 1$$

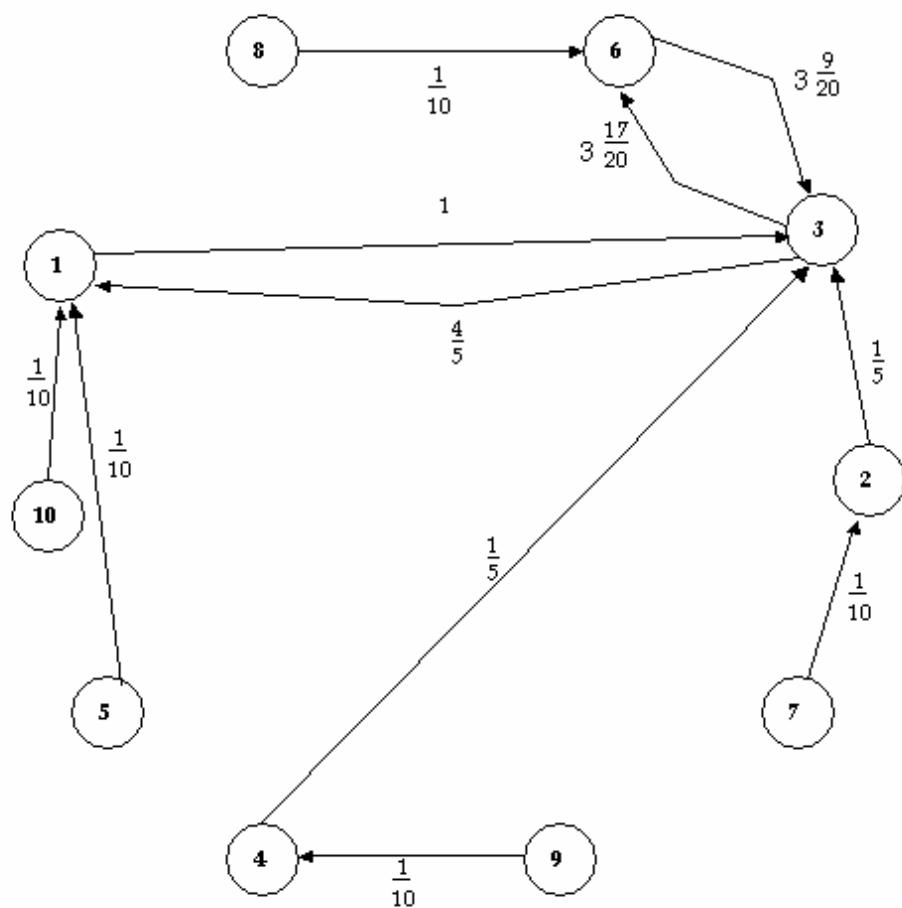
$$0(n) \text{ Constraints} = n$$

$$0(n^3) \text{ Variables} = n^2(n-1)$$

Also convenient to introduce x_{ij} variables with constraints

$$x_{ij} = \sum_t y_{ij}^t$$

FRACTIONAL SOLUTION FROM 1ST (AGGREGATED) TIME-STAGED FORMULATION



Cost = 364.5 (Optimal solution = 881)

NB 'Lengths' of Arcs can be > 1

Second (Fox, Gavish, Graves (1980))

T2: Disaggregate to give

$$\sum_{i \neq j, t} y_{ij}^t = 1 \quad \text{all } j$$

$$\sum_{j \neq i, t} y_{ij}^t = 1 \quad \text{all } i$$

$$\sum_{i, j, i \neq j} y_{ij}^t = 1 \quad \text{all } t$$

$$\sum_{j=1}^n \sum_{t=2}^n ty_{ij}^t - \sum_{j=1}^n \sum_{t=1}^n ty_{ji}^t = 1 \quad i = 2, 3, \dots, n$$

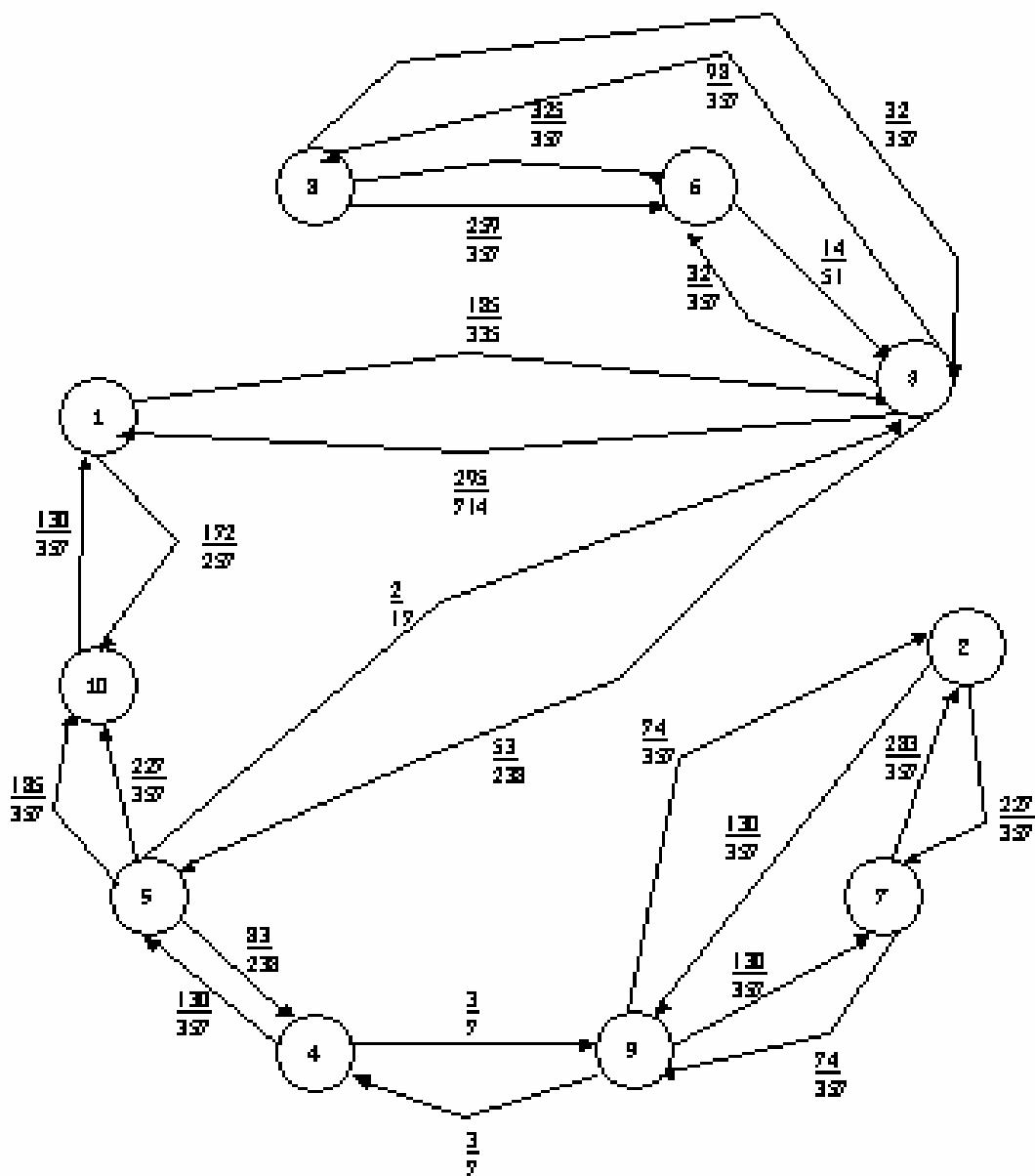
Initial conditions no longer necessary

$$O(n) \text{ Constraints} = 4n - 1$$

$$O(n^3) \text{ Variables} = n^2(n - 1)$$

FRACTIONAL SOLUTION FROM 2nd TIME-STAGED FORMULATION

|



$$\text{Cost} = 799 \frac{164}{357} \text{ (optimal solution} = 881)$$

$$(714 = 2 \times 3 \times 7 \times 17)$$

Third (Vajda/Hadley (1960))

T3: y_{ij}^t interpreted as before

$$\sum_{i \neq j} y_{ij}^t = 1 \quad \text{all } j$$

$$\sum_{j \neq i} y_{ij}^t = 1 \quad \text{all } i$$

$$\sum_t y_{ij}^t = 1 \quad \text{all } t$$

$$\sum_{i \neq j} y_{ij}^t - \sum_{k \neq j} y_{jk}^{t+1} = 0 \quad \text{all } j, t$$

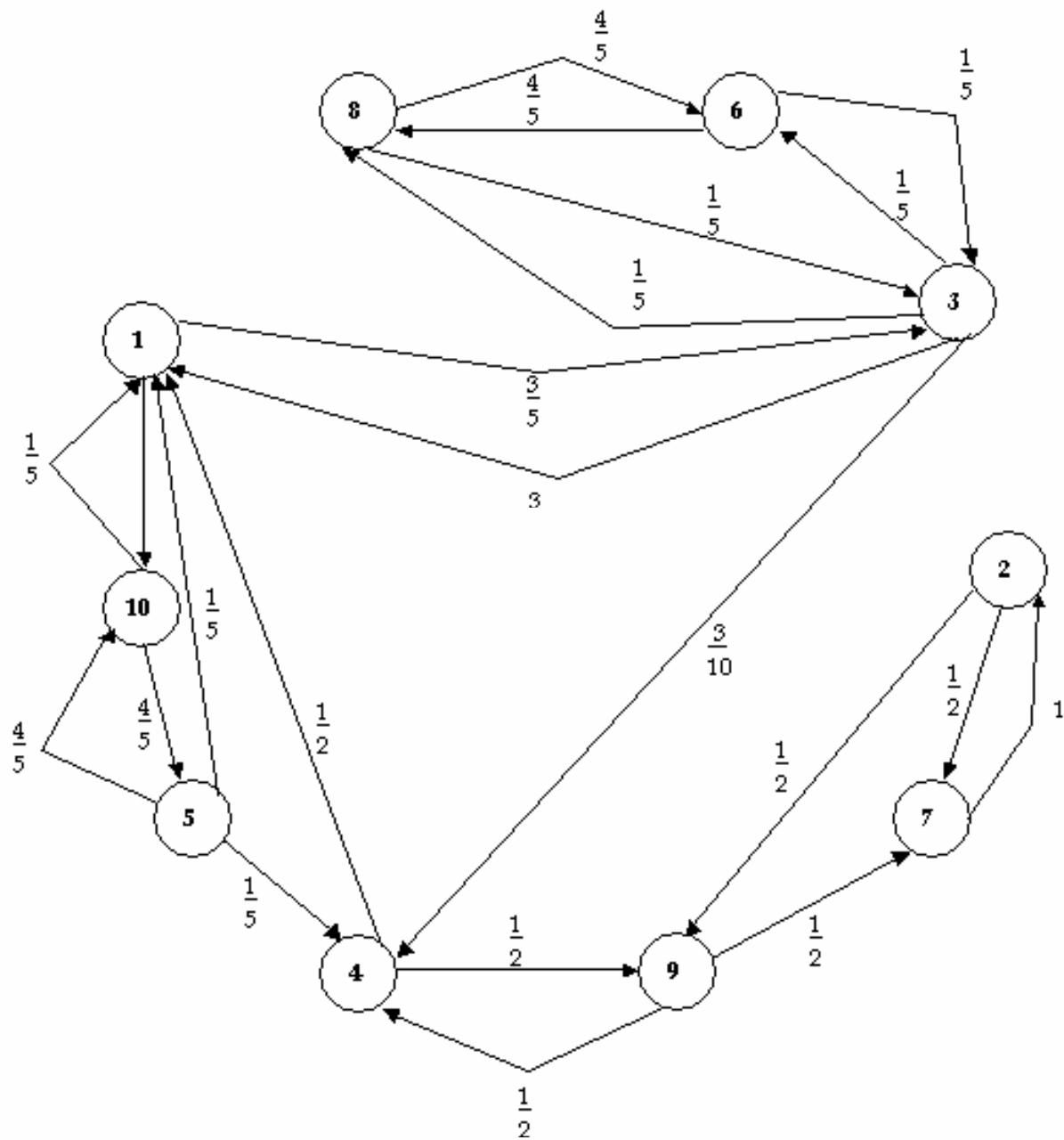
$$\sum_{j \neq 1} y_{1j}^1 = 1$$

$$\sum_{i \neq 1} y_{i1}^n = 1$$

$$0(n^2) \text{ Constraints} = (2n^2 + 3)$$

$$0(n^3) \text{ Variables} = n^2(n-1)$$

FRACTIONAL SOLUTION FROM 2nd TIME 2nd TIME-STAGED FORMULATION



Cost = $804\frac{1}{2}$ Optimal solution = 881

OBSERVATION

Multicommodity Flow Formulation

$$\sum_i \mathbf{y}_{ij}^t - \sum_k \mathbf{y}_{jk}^t = 0$$

\mathbf{y}_{ij}^t is flow $i \rightarrow j$ destined for node t

Time Staged Formulation

$$\sum_{ij} \mathbf{y}_{ij}^t - \sum_{jk} \mathbf{y}_{jk}^{t+1} = 0$$

$\mathbf{y}_{ij}^t = 1$ *iff* go $i \rightarrow j$ at stage t

Are these formulations related?

Can extra variables (\mathbf{y}_{ij}^t), introduced *syntactically*, be given different *semantic* interpretations?

COMPARING FORMULATIONS

Minimise: $c^T x$

Subject to: $Ax + By \leq b$
 $x, y \geq 0, x$ integer

$$W = \{w \mid wB \geq 0, \underline{w} \geq 0\}$$

W forms a cone which can be characterised by
its extreme rays giving matrix Q such that

$$QB \geq 0$$

Hence $QAx \leq Qb$

This is the projection of formulation
into space of original variables x_{ij}

COMPARING FORMULATIONS

Project out variables by Fourier-Motzkin elimination to reduce to space of conventional formulation.

$P(r)$ is polytope of LP relaxation of projection of formulation r .

Formulation S (Sequential)

Project out around each *directed cycle* S by summing

$$u_i - u_j + nx_{ij} \leq n - 1$$



$$n \sum_{i,j \in S} x_{ij} \leq (n-1)|S|$$

ie $\sum_{i,j \in S} x_{ij} \leq |S| - \frac{|S|}{n}$ weaker than $|S| - 1$ (for S a subset of nodes)

Hence $P(S) \supset P(C)$

Formulation F1 (1 Commodity Network Flow)

Projects to $\sum_{ij \in s} x_{ij} \leq |S| - \frac{|S|}{n-1}$ stronger than $|S| - \frac{|S|}{n}$

Hence $P(S) \supset P(F1) \supset P(C)$

Formulation F1' (Amended 1 Commodity Network Flow)

Projects to $\frac{1}{n-1} \sum_{\substack{j \in \bar{S} - \{1\} \\ j \in S}} x_{ij} + \sum_{i,j \in S} x_{ij} \leq |S| - \frac{|S|}{n-1}$

Hence $P(S) \supset P(F1) \supset F(F1') \supset P(C)$

Formulation F2 (2 Commodity Network Flow)

Projects to $\sum_{i,j} x_{ij} \leq |S| - \frac{|S|}{n-1}$

Hence $P(F2) = P(F1)$

Formulation F3 (Multi Commodity Network Flow)

Projects to $\sum_{\substack{i,j \\ \in S}} x_{ij} \leq |S| - 1$

$$\text{Hence } P(F3) = P(C)$$

Formulation T1 (First Stage Dependant)

Projects to

$$\sum_{\substack{i \in S \\ j \in \bar{S} - \{1\}}} x_{ij} \geq \frac{|S|}{n - 1}$$

$$\sum_{i,j \in N} x_{ij} = n$$

(Cannot convert 1st constraint to ' $\sum_{i,j \in S} x_{ij} \leq$ ' form since
Assignment Constraints not present)

Formulation T2 (Second Stage Dependant)

Projects to

$$\frac{1}{n - 1} \sum_{\substack{i \in S \\ j \in \bar{S} - \{1\}}} x_{ij} + \frac{1}{n - 1} \sum_{\substack{i \in \bar{S} - \{1\} \\ j \in S}} x_{ij} + \sum_{ij \in s} x_{ij} \leq |S| - \frac{|S|}{n - 1}$$

+ others

Hence $P(T2) \subset P(F1')$

Formulation T3 (Third Stage Dependant)

Projects to

$$\frac{1}{n - 1} \sum_{\substack{i \in S \\ j \in \bar{S} - \{1\}}} x_{ij} + \frac{1}{n - 1} \sum_{\substack{i \in \bar{S} - \{1\} \\ j \in S}} x_{ij} + \sum_{n, j \in S} x_{ij} \leq |S| - \frac{|S|}{n - 1}$$

+ others

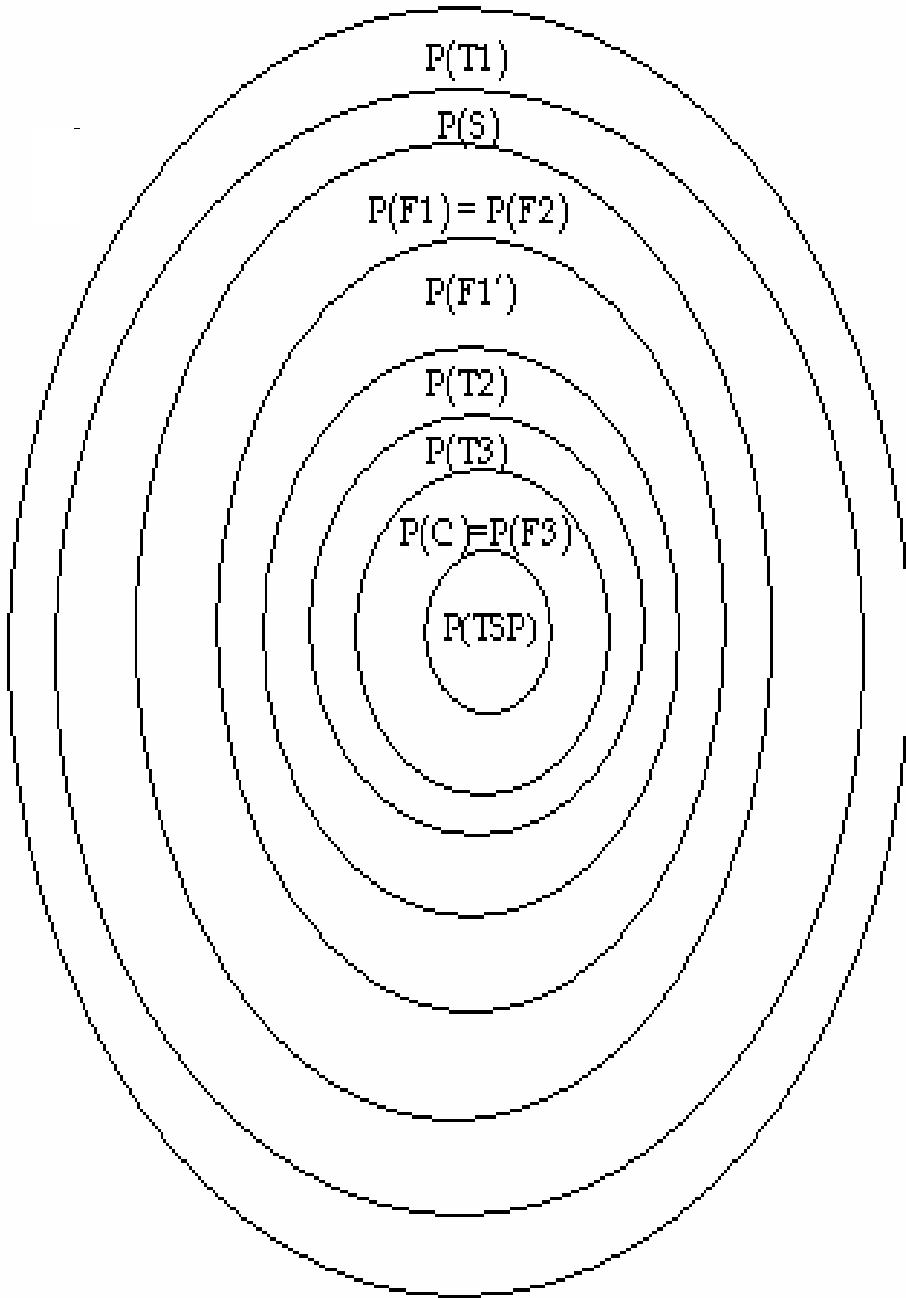
Can show stronger than T2

Hence $P(T3) \subset P(T2)$

Computational Results of a 10-City TSP in order to compare sizes and strengths of LP Relaxations

Model	Size	LP Obj	Its	Secs	IP Obj	Nodes	Secs
C (Conventional)	502x90						
	(Ass. Relax	766	37	1	766	0	1
	+Subtours (5)	804	40	1	804	0	1
	+Subtours (3)	835	43	1	835	0	1
	+Subtours (2)	878	48	1	881	9	1
S (Sequential)	92x99	773.6	77	3	881	665	16
F1 (Commodity Flow	120x180	794.22	148	1	881	449	13
	F' (F1 Modified)	794.89	142	1	881	369	11
F2 (2 Commodity Flow)	140x270	794.22	229	2	881	373	12
F3 (Multi Commodity Flow)	857x900	878	1024	7	881	9	13
T1 (1 st Stage Dependent)	90x990 (10)x(900)	364.5	63	4	881	∞	∞
T2 (2 nd Stage Dependent)	120x990 (39) x (900)	799.46	246	18	881	483	36
T3 (3 rd Stage Dependent)	193x990 (102)x(900)	804.5	307	5	881	145	27

Solutions obtained using NEW MAGIC and EMSOL



$P(TSP)$ TSP Polytope – not fully known

$P(X)$ Polytope of Projected LP relaxations