Non-Parametric Instrumental Variable Models for Categorical Data

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Joint work with James Robins (Harvard)

Outline

- Randomized experiments
- Observational studies
- Combining observational studies
- Instrumental variables
- Testing instrumental variable models
- Bayesian inference

Potential outcomes with binary treatment and outcome

For binary treatment X, we define two potential outcome variables:

- Y(x = 0): the value of Y that would be observed for a given unit if assigned X = 0;
- Y(x = 1): the value of Y that would be observed for a given unit if assigned X = 1;

Notation: We will use $Y(x_i)$ as an abbreviation for Y(x=i)

Drug Response Types:

In the simplest case where Y is a binary outcome we can think of patients as belonging to one of 4 'types':

$Y(x_0)$	$Y(x_1)$	Name	
0	0	Never Recover (NR)	
0	1	Helped (HE)	
1	0	Hurt (HU)	
1	1	Always Recover (AR)	

Identification Problem

Want:
$$P(Y(x_0), Y(x_1))$$
; Given: $P(Y | X=0), P(Y | X=1)$

Under randomization: $X \perp Y(x_i)$ implies:

$$P(Y(x_\mathfrak{i})=1)=P(Y(x_\mathfrak{i})=1\mid X=\mathfrak{i})=P(Y=1\mid X=\mathfrak{i}).$$

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Thus the observed joint P(Y|X) puts two restrictions on $P(Y(x_0), Y(x_1))$:

$$P(Y=1 | X=0) = P(Y(x_0)=1, Y(x_1)=0) + P(Y(x_0)=1, Y(x_1)=1)$$

 $P(Y=1 | X=1) = P(Y(x_0)=0, Y(x_1)=1) + P(Y(x_0)=1, Y(x_1)=1).$

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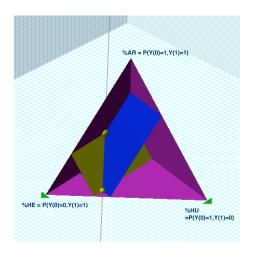
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$$P(Y=1 \mid X=1) = P(Y(x_0)=0, Y(x_1)=1) + P(Y(x_0)=1, Y(x_1)=1).$$

Each restriction implies a 2-d subset in Δ_3 . Intersection forms a 1-d subset on which ACE is constant.

3-d Plot



In this plot:

$$P(Y=1 | X=0) = P(Y(x_0) = 1) = HU + AR = 0.3$$
, (yellow)
 $P(Y=1 | X=1) = P(Y(x_1) = 1) = HE + AR = 0.6$, (blue)

Two-way Table

Under randomization, the relationship between the counterfactual distribution $P(Y(x_0),Y(x_1))$ and the observed distributions $\{P(Y\mid x_0),P(Y\mid x_1)\}$ is:

		col sums	
		P(Y=0 X=0)	$P(Y=1 \mid X=0)$
row	P(Y=0 X=1)	$P(Y(x_0)=0,Y(x_1)=0)$	$P(Y(x_0)=1,Y(x_1)=0)$
sums	P(Y=1 X=1)	$P(Y(x_0)=0, Y(x_1)=1)$	$P(Y(x_0) = 1, Y(x_1) = 1)$

Here $P(Y=i \mid X=j) = P(Y(x_j)=i)$ due to randomization.

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Here $P(Y=i \mid X=j) = P(Y(x_j)=i)$ due to randomization.

Equivalently we may write this in terms of types

	$P(Y=0 \mid X=0)$	$P(Y=1 \mid X=0)$
P(Y=0 X=1)	P(NR)	P(HU)
$P(Y=1\mid X=1)$	P(HE)	P(AR)

Observational study: one-way table!

Observed	Counterfactual	
p(X=0,Y=0)	p(X=0, NR) + p(X=0, HE)	
p(X=0,Y=1)	p(X=0, HU) + p(X=0, AR)	
p(X=1,Y=0)	p(X=1, NR) + p(X=1, HU)	
p(X=1,Y=1)	p(X=1, HE) + p(X=1, AR)	

Bounds on joints $P(Y(x_0), Y(x_1))$

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$$0\leqslant \quad \text{\%HE} \quad \leqslant P(X=0,Y=0) + P(X=1,Y=1)$$

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$$\begin{array}{lll} 0 \leqslant & \text{\%HE} & \leqslant P(X=0,Y=0) + P(X=1,Y=1) \\ 0 \leqslant & \text{\%HU} & \leqslant P(X=0,Y=1) + P(X=1,Y=0) \\ 0 \leqslant & \text{\%NR} & \leqslant P(X=0,Y=0) + P(X=1,Y=0) = P(Y=0) \\ 0 \leqslant & \text{\%AR} & \leqslant P(X=0,Y=1) + P(X=1,Y=1) = P(Y=1) \end{array}$$

Bounds on margins $P(Y(x_i))$

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p(X=1,Y=0)	p(X=1, NR) + p(X=1, HU)	
p(X=1,Y=1)	p(X=1, HE) + p(X=1, AR)	

We also have the following inequalities on the marginals:

$$\begin{array}{c} P(Y(x_0) = 1) = P(HU) + P(AR) \\ P(Y(x_1) = 1) = P(HE) + P(AR) \\ \\ P(X = 0, Y = 1) \leq P(Y(x_0) = 1) \leq 1 - P(X = 0, Y = 0) \\ P(X = 1, Y = 1) \leq P(Y(x_1) = 1) \leq 1 - P(X = 1, Y = 0) \end{array}$$

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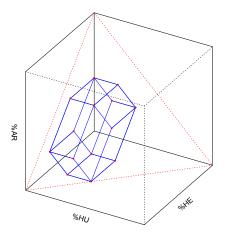
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 Thus we have 6 pairs of parallel planes.

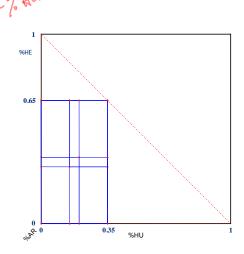
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Polytope for observational study

Set of margins $P(Y(x_0),Y(x_1))$ compatible with the Obs. Study.



ACE bounds



(But why is this helpful!?)

Inference for the ACE without randomization

(Robins-Manski bounds)

Suppose that we do not know that $X \perp Y(x_0)$ and $X \perp Y(x_1)$.

What can be inferred from the observed distribution P(X, Y)?

General case:

$$-(P(X=0,Y=1) + P(X=1,Y=0))$$

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⇒ Bounds are of length 1 and will always include zero.

Combining two Obs Studies: Cholestyramine data

Z: assignment to treatment or control arm (randomized);

X: whether patient takes (more than certain amount of) drug;

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0	0	1	14
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(Data originally considered by Efron and Feldman (1991); dichotomized by Pearl.)

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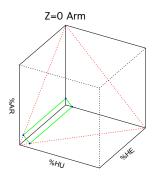
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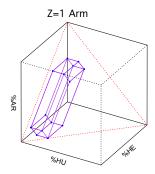
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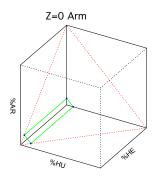
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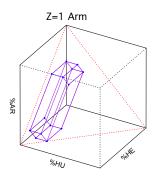
Each Z Arm





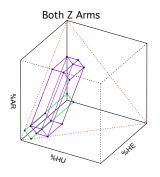
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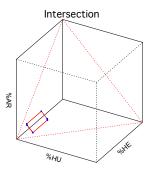




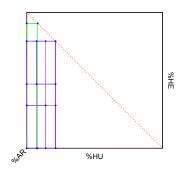
$$Z=0$$
 arm polytope is 2-d since $Z=0 \ \Rightarrow \ X=0$

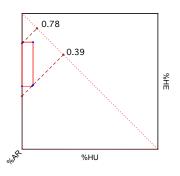
Combining the Arms





Obtaining ACE bounds

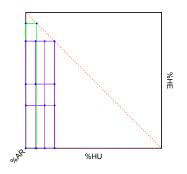


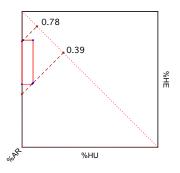


Upper bound is: 0.78; lower bound is 0.39

Note: ACE bounds for each arm contain 0, but not when combined. why?

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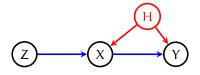


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Note: ACE bounds for each arm contain 0, but not when combined. why? These are the Balke and Pearl (1993) bounds, obtained via prinicipal strata and computational algebra;

Instrumental Variable Model

We assume that assignment Z has no direct effect on the outcome Y except through X, so $Y(x, z_0) = Y(x, z_1) \equiv Y(x)$;



Z is said to be an 'instrument' for the effect of X on Y.

Potential outcomes:

$$X(z_0), X(z_1), Y(x_0), Y(x_1)$$

Randomization becomes: for all $x, z, Z \perp \{X(z), Y(x)\}$

The assumptions: (i) No direct effect of Z on Y, and (ii) Z randomized are sufficient to justify the intersecting polytope analysis.

Bounds on ACE: Previous results

• Robins (1989) and Manski (1990) derived the 'natural' bounds:

$$\begin{split} p(y_1 \mid z_1) - p(y_1 \mid z_0) - p(y_1, x_0 \mid z_1) - p(y_0, x_1 \mid z_0) \\ \leqslant & \quad ACE(X \to Y) \quad \leqslant \\ & \quad p(y_1 \mid z_1) - p(y_1 \mid z_0) + p(y_0, x_0 \mid z_1) + p(y_1, x_1 \mid z_0) \end{split}$$

These are not sharp if there are Defiers;

they follow from (and are sharp) under Z \perp Y(x₀), Z \perp Y(x₁).

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- Balke and Pearl (1993) derived closed form expression for ACE bounds via computational algebra;
 - Resulting expressions are maxima and minima over 8 different expressions.
- Dawid (2002) re-derived these bounds without (explicitly!) using potential outcomes, again using computational algebra.

An advantage of the approach taken here is that it extends to Z with finitely many levels.

Extending to p levels of Z: Identification

Solving the identification problem requires no further work: Intersect p polytopes.

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Solving the identification problem requires no further work: Intersect \boldsymbol{p} polytopes.

The set of distributions $P(Y(x_0), Y(x_1))$ that are compatible with P(X, Y|Z) is still given by the following six pairs of parallel planes:

$$\begin{array}{lll} 0\leqslant & \text{\%NR} & \leqslant \min_{i}p(y_0\mid z_i) \\ \\ 0\leqslant & \text{\%AR} & \leqslant \min_{i}p(y_1\mid z_i) \\ \\ 0\leqslant & \text{\%HE} & \leqslant \min_{i}\{p(x_1,y_1\mid z_i)+p(x_0,y_0\mid z_i)\} \\ \\ 0\leqslant & \text{\%HU} & \leqslant \min_{i}\{p(x_0,y_1\mid z_i)+p(x_1,y_0\mid z_i)\} \\ \\ \max_{i}p(x_0,y_1\mid z_i)\leqslant & P(Y(x_0)\!=\!1) & \leqslant \min_{i}\{1-p(x_0,y_0\mid z_i)\} \\ \\ \max_{i}p(x_1,y_1\mid z_i)\leqslant & P(Y(x_1)\!=\!1) & \leqslant \min_{i}\{1-p(x_1,y_0\mid z_i)\} \\ \\ \end{array}$$

Generalizing to more levels of Z

Theorem (R+Robins 2014)

If X, Y binary and Z with p levels then under the IV model:

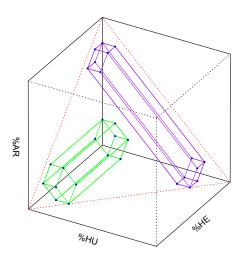
$$1 - g(1,0) - g(0,1) \leq ACE(X \rightarrow Y) \leq g(0,0) + g(1,1) - 1,$$

where

$$\begin{split} g(\mathfrak{i},\mathfrak{j}) &\equiv \min \left\{ \min_{z} \left[P(X \!=\! \mathfrak{i},Y \!=\! \mathfrak{j} \!\mid\! Z \!=\! z) + P(X \!=\! 1 - \mathfrak{i} \!\mid\! Z \!=\! z) \right], \\ &\qquad \min_{z,\tilde{z}:\, z \neq \tilde{z}} \left[P(X \!=\! \mathfrak{i},Y \!=\! \mathfrak{j} \!\mid\! Z \!=\! z) + P(X \!=\! 1 - \mathfrak{i},Y \!=\! 0 \!\mid\! Z \!=\! z) \right. \\ &\qquad \qquad + \left. P(X \!=\! \mathfrak{i},Y \!=\! \mathfrak{j} \!\mid\! Z \!=\! \tilde{z}) + P(X \!=\! 1 - \mathfrak{i},Y \!=\! 1 \!\mid\! Z \!=\! \tilde{z}) \right] \right\}. \end{split}$$

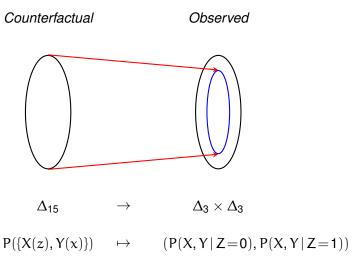
This exploits the fact that $P(Y(x_0)=1)$ and $P(Y(x_1)=1)$ are variation independent.

Polytopes may not intersect



 \Rightarrow Model places testable constraints on P(X, Y | Z).

Model for $P(X, Y \mid Z)$ (Z binary)



For Z binary requiring that the polytopes intersect leads to the following: If $p(X,Y \mid Z)$ is compatible with the binary IV model iff

$$\begin{array}{lll} p(Y=0,X=0 \mid Z=0) + p(Y=1,X=0 \mid Z=1) & \leqslant & 1, \\ p(Y=0,X=0 \mid Z=1) + p(Y=1,X=0 \mid Z=0) & \leqslant & 1, \\ p(Y=0,X=1 \mid Z=0) + p(Y=1,X=1 \mid Z=1) & \leqslant & 1, \\ p(Y=0,X=1 \mid Z=1) + p(Y=1,X=1 \mid Z=0) & \leqslant & 1, \end{array}$$

This describes a subset of $\Delta_3 \times \Delta_3$.

These are the IV inequalities of Pearl (1995) and Bonet (2001); they provide a test of the binary IV model.

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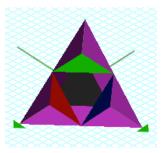
Can be interpreted as bounding away from zero $E[Y(z_1, x) - Y(z_0, x)]$, the average direct effect of Z on Y, holding X fixed at x. Leads to smooth variation independent parametrization of model (R, Evans & Robins , 2011).

Hard to visualize this subset of $\Delta_3 \times \Delta_3$. Can project onto the co-ordinates given by the LHS of the inequalities:

$$\begin{split} u_1 &\equiv \sum_{j} p(y_j, x_0 \mid z_j) & u_2 \equiv \sum_{k} p(y_k, x_0 \mid z_{1-k}) \\ u_3 &\equiv \sum_{j} p(y_j, x_1 \mid z_j) & u_4 \equiv \sum_{k} p(y_k, x_1 \mid z_{1-k}) \end{split}$$

then since $\sum_i u_i = 2$, (u_1, u_2, u_3, u_4) lies in a 3-d simplex with sum 2.

The IV inequalities are $u_i \leq 1$ for i = 1, ..., 4. This gives an octahedron:



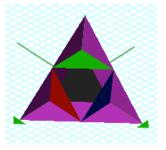
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$$u_{3} \equiv \sum_{j} p(y_{j}, x_{1} \mid z_{j}) \qquad u_{4} \equiv \sum_{k} p(y_{k}, x_{1} \mid z_{1-k})$$

then since $\sum_i u_i =$ 2, (u_1, u_2, u_3, u_4) lies in a 3-d simplex with sum 2.

The IV inequalities are $u_i \leq 1$ for i = 1, ..., 4. This gives an octahedron:



Corollary: At most one inequality is ever violated. (see also Cai, Kuroki, Pearl, Tian, 2008)

Extending to p levels of Z: Observable model

Explicitly characterizing the set of observed distributions P(X, Y|Z) does require more work. Three known types of constraint:

2p(p-1) IV inequalities, these involve 2 levels of Z;

4p(p-1)(p-2) inequalities found by Bonet (2001), these involve 3 levels of Z

p!/(p-4)! inequalities found by R, which involve 4 levels of Z.

Conjecture: These are the only constraints. Confirmed by direct computation for $p \le 7$.

(Note: Implicit solution given by seeing if the set of distributions

 $P(Y(x_0), Y(x_1))$ is non-empty.)

Bayesian Inference

What about sampling variability?

The true population distribution $p(x, y \mid z)$ is not equal to the empirical distribution observed in the sample.

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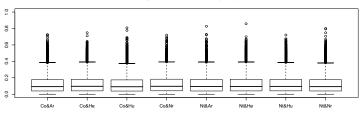
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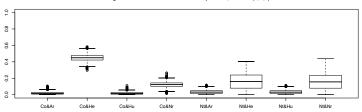
$${P(X(z_0), X(z_1), Y(x_0), Y(x_1))}.$$

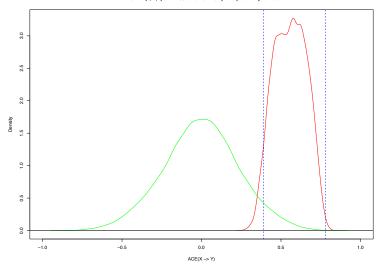
 \Rightarrow Use MCMC to sample from posterior distribution.

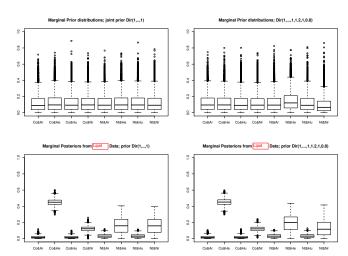
Marginal Prior distributions; Dir(1,...,1)



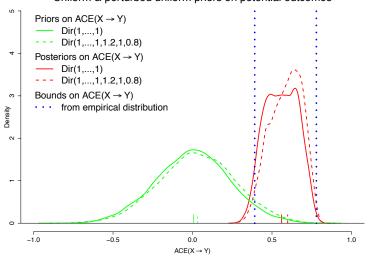
Marginal Posterior distributions from Lipid Data; Prior Dir(1,...,1)







Prior and posterior on ACE($X \rightarrow Y$) for Lipid data Uniform & perturbed uniform priors on potential outcomes



Is the problem caused by the priors?

Try a 'unit' information prior:

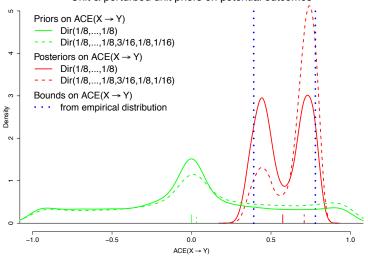
$$p({X(z), Y(x)}) \sim Dir(1/8, ..., 1/8)$$

VS.

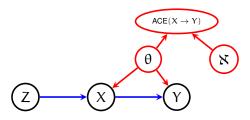
$$p({X(z), Y(x)}) \sim Dir(1/8, ..., 1/8, 3/16, 1/8, 1/16)$$

(?Though 'unit' of whose information?)

Prior and posterior on ACE($X \rightarrow Y$) for Lipid data Unit & perturbed unit priors on potential outcomes



Big picture: How to formulate priors transparently



We will re-parameterize:

$$\{P(X(z_0), X(z_1), Y(x_0), Y(x_1))\} \leftrightarrow (\theta, \aleph)$$

 θ is a 6 dim. parameter, (completely!) identifiable from P(X, Y | Z). \aleph is a 9 dim. parameter, (completely!) non-identifiable.

$$P(\theta, \aleph) = P(\theta)P(\aleph)$$

$$P(\theta, \aleph \mid Z, X, Y) = P(\theta \mid Z, X, Y)p(\aleph)$$

Note that $\mbox{\ensuremath{\mbox{$\times$}}} \mbox{\ensuremath{\mbox{\bot}}} \mbox{\ensuremath{\mbox{Z}}}, \mbox{\ensuremath{\mbox{X}}}, \mbox{\ensuremath{\mbox{Y}}}$

Simple implementation (I)

Recall that the binary IV model is defined by the inequalities:

$$\begin{array}{lll} P(Y=0,X=0 \mid Z=0) + P(Y=1,X=0 \mid Z=1) & \leqslant & 1, \\ P(Y=0,X=0 \mid Z=1) + P(Y=1,X=0 \mid Z=0) & \leqslant & 1, \\ P(Y=0,X=1 \mid Z=0) + P(Y=1,X=1 \mid Z=1) & \leqslant & 1, \\ P(Y=0,X=1 \mid Z=1) + P(Y=1,X=1 \mid Z=0) & \leqslant & 1. \end{array} \tag{1}$$

Prior: Dirichlet on P(X, Y | Z) restricted (and re-normalized) to those distributions obeying (1).

Posterior: The usual Dirichlet posterior, again restricted to those distributions obeying (1).

Inference may be performed by 'straight' Monte-Carlo.

Simple Implementation (II)

To obtain the posterior distribution on the ACE bounds, perform the following steps:

- Specify Dirichlet $(\alpha_{00z}, \alpha_{01z}, \alpha_{10z}, \alpha_{11z})$ priors on p(x, y|z) for z = 0, 1.
- ② Compute the posteriors in the usual way: Dirichlet $(\alpha_{00z} + n_{00z}, \alpha_{01z} + n_{01z}, \alpha_{10z} + n_{10z}, \alpha_{11z} + n_{11z})$ where n_{ijz} is the number of observations with X = i, Y = j, Z = z.
- **3** Simulate $p^{(1)}(x, y|z), \dots, p^{(N)}(x, y|z)$ from this posterior.
- Throw out any $p^{(i)}(x, y|z)$ violating the inequalities (1).
- **5** Compute upper and lower bounds on the ACE from each distribution $p^{(i)}(x, y|z)$ remaining after step 4.

Back to Lipid Data

Parametrize IV model as:

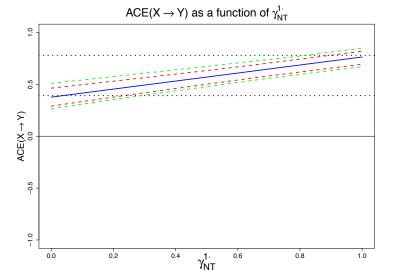
$$p(X, Y \mid Z)$$
 obeying IV inequalities

Use
$$Dir(1, 1)$$
 for $p(x = 0, y \mid z = 0)$ (since $p(x = 1, y \mid z = 0) = 0$)

and Dir(1, 1, 1, 1) for
$$p(x, y | z = 1)$$
.

(Posterior probability that IV model holds: 0.368; prior probability was 0.5.)

We then truncate and renormalize using the IV inequalities.



Here $\gamma_{NT}^{1,} \equiv P(Y(x_1) = 1 \mid NT)$, the probability of a good outcome for Never Takers, if they were to get the drug; this is completely unidentified.

Summary

- Potential outcome models provide a way to formulate causal models in terms of missing data
- Geometric analysis of randomized and observational studies
- Instrumental variable design may be seen as combining observational studies
- Non-parametric IV models impose testable constraints
- These constraints lead to a transparent method of Bayesian analysis.

Thank you!

What if I don't believe (deterministic) potential outcomes exist?

- Dawid (2003), Cai et al. (2008) show that IV inequalities may be derived without assuming existence of deterministic potential outcomes, likewise for ACE bounds
 - ⇒ multivariate link functions for GLMs are also useful even under probabilistic potential outcome models.

Similar 'coupling' arguments may also be given for the generalizations to more states for X and Z.

Extending to p levels of Z, q levels of X: identification

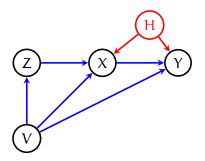
Conjecture: The set of distributions $P(Y(x_1), \ldots, Y(x_q))$ compatible with P(X, Y|Z) is given by the following constraints: For every non-empty subset $A \subseteq \{1, \ldots, q\}$, every assignment $(y^i, i \in A)$, with $y^i \in \{0, 1\}^{|A|}$ and every $z \in \{1, \ldots, p\}$:

$$0 \leqslant P(\{Y(x_i) = y^i, i \in A\}) \leqslant \sum_{j \in A} p(Y = y^j, X = j \mid z) + \sum_{k \notin A,} p(X = k \mid z)$$
(2)

Necessity is established. Sufficiency has been proved up to $\mathfrak{p} \leqslant 7$; sketch of proof in general.

Incorporating baseline covariates

May wish to model $ACE(X \to Y)$ as a function of possibly continuous baseline covariates.

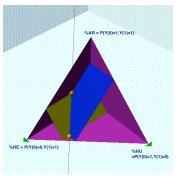


Generalized Linear Models

Need: a multivariate link function (aka diffeomorphism) from \mathbb{R}^6 into subset of $\Delta_3 \times \Delta_3$ given by the inequalities defining the IV model

⇒ incorporate covariates as in a multivariate GLM.

Fréchet inequalities



Equation for line segment in simplex:

$$\left\{ \begin{array}{ll} P(1,1) & = & \mathbf{t} \\ P(1,0) & = & c_0 - \mathbf{t} \\ P(0,1) & = & c_1 - \mathbf{t} \\ P(0,0) & = & 1 - c_0 - c_1 + \mathbf{t} \end{array} \right. \begin{array}{l} \mathbf{t} \in \left[\max\{0, (c_0 + c_1) - 1\}, \min\{c_0, c_1\} \right] \\ c_0 \equiv P(Y = 1 \mid x_0) \\ c_1 \equiv P(Y = 1 \mid x_1) \end{array} \right\}$$

Extreme points are given by 'Fréchet inequalities'.