

BRIAN K. PLANCHER

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ACADEMIC POSITIONS

BARNARD COLLEGE, COLUMBIA UNIVERSITY: New York, NY

JULY 2022 – PRESENT

- Assistant Professor of Computer Science

EDUCATION

HARVARD UNIVERSITY: Cambridge, MA

AUG 2016 – MAY 2022

- PhD Engineering Sciences: Electrical Engineering with a focus in Robotics; GPA: 3.9/4.0
MAY 2022
 - Dissertation: “GPU Acceleration for Real-time, Whole-Body, Nonlinear Model Predictive Control”
 - Advisors: Vijay Janapa Reddi and Scott Kuindersma.
- MEng in Engineering Sciences: Electrical Engineering with a focus in Robotics; GPA: 3.9/4.0
MAY 2018
 - Thesis: “Parallel and Constrained Differential Dynamic Programming for Model Predictive Control”
 - Advisor: Scott Kuindersma

MASSACHUSETTS INSTITUTE OF TECHNOLOGY (MIT): Cambridge, MA

AUG 2015 – JUNE 2016

- Advanced Study Non-Degree Student; GPA: 5.0/5.0

HARVARD UNIVERSITY: Cambridge, MA

AUG 2009 – MAY 2013

- B.A. Magna Cum Laude in Computer Science with a Minor in Economics; GPA: 3.9/4.0
 - Thesis: “Hacking the White House: Election Fraud in the Digital Age”
 - Advisor: Greg Morrisett

AWARDS AND RECOGNITION

- IEEE Micro Top Picks Honorable Mention
JAN 2022
- Harvard Faculty of Arts and Sciences Certificate in Undergraduate Mentoring
APRIL 2021
 - Certificate given for completing three undergraduate mentorship trainings covering: Developing Research Projects with Undergraduates, Undergraduate Research Fellowships, Supporting Student Science Writing, Writing Recommendation Letters, Handling Challenges and Celebrating Successes, and Supporting Student Diversity and Inclusion
- The Derek Bok Center Distinction in Teaching Award
FALL 2017,18,19,20
 - Award given for achieving above a 4.5/5.0 in course evaluations
- The Derek Bok Center Teaching Certificate
DEC 2019
 - Certificate given for recognition of commitment to improving one’s teaching through enrollment in Bok Center teaching courses (Foundations of Teaching in STEM, Problems and P-Sets: Creating and Teaching Questions in STEM, Teaching and the Job Market), filmed teaching pedagogy reviews, and development of teaching materials
- National Science Foundation Graduate Research Fellowship (NSF GRFP)
APRIL 2018

TEACHING EXPERIENCE

BARNARD COLLEGE, COLUMBIA UNIVERSITY: New York, NY – *Instructor of Record*

FALL 2022 – PRESENT

- COMS BC 3159: Parallel Optimization for Robotics (Spring 2023)
 - Designed a new 35 student course at the intersection of robotics and both numerical optimization and computer architecture / systems exploring the use of parallel programming on CPUs and GPUs to accelerate numerical optimization algorithms through the lens of robot motion planning and control
 - Designed and gave lectures on computer system design, parallel programming on the CPU and GPU using (CUDA) C++, (nonlinear) (trajectory) optimization, and numerical optimal control
 - Developed written assignments and coding assignments in both python and (CUDA) C++ covering the core course topics as well as a hands-on, team-based, final project to enable students to integrate and apply their learnings from the semester
- COMS BC 3997 – SP23: New Directions in Computing: Projects in Computer Science (Spring 2023)
 - Designed a new 30 student course providing a unifying structure to support hands-on, computational student projects ranging from academic research to industry collaborations to independent passion projects
 - Designed and gave lectures covering a variety of topics including: performance engineering, web development, and technical writing and presentation
 - Recruited guest speakers from academia and industry to present on topics including: responsible AI, startup engineering, and the business of technology
 - Mentored student projects providing high level direction and technical debugging

- COMS BC 3997 – F22: New Directions in Computing: Introduction to Robotics Engineering from Bits to Electrons (Fall 2022)
 - Designed a new 20 student course providing a hands-on introduction to computational robotics for computer scientists
 - Designed and gave lectures covering algorithms for perception, mapping and localization, planning, control, and learning
 - Developed written assignments and coding assignments in python as well as a hands-on final project using physical robot hardware to connect the algorithms learned in class into the physical world and reinforce their tradeoffs

edX Inc: Cambridge, MA – *Teaching Staff Lead*

SUMMER 2020 – SUMMER 2022

- HarvardX Professional Certificate in Tiny Machine Learning (TinyML) MOOC [[Course 1-3 Link](#) [Course 4 Link](#)]
 - Co-designed a free, hands-on, project-based professional certificate taught through three 6-week courses (and an optional fourth course) on the EdX platform covering the emerging field of Tiny Machine Learning (deploying machine learning onto microcontrollers for machine learning at the edge) with the aim of democratizing access to this developing field
 - Over 66,000 students from over 175 countries enrolled as of April 2022 since the four courses launched in September 2020, December 2020, February 2021, and March 2022 respectively
 - Served as the laboratory instructor both co-designing hands-on exercises as well as recording video walkthroughs
 - Managed the 10-person course staff to ensure that content was created, reviewed, and produced in a timely manner
 - Led and managed external relations for the course team coordinating with edX, Google, and Arduino
 - Co-designed course materials including video lectures, readings, code walkthroughs, assessments, and discussion forums
 - Released all course materials open-source to enable global adaptation for further access to TinyML education [[link](#)]

HARVARD UNIVERSITY: Cambridge, MA – *Head Teaching Fellow (Head TA)*

FALL 2017-20

- CS 249r - Special Topics in Edge Computing - Autonomous Machines (Fall 2019) and Tiny Machine Learning (Fall 2020)
 - Co-designed 40-50 student courses at the intersection of artificial intelligence (robotics and machine learning) and computer architecture / embedded systems
 - Designed and gave lectures for the introduction to robotics and introduction to machine learning sections of the courses
 - Co-developed hands-on project-based assignments (e.g., training TinyML models with Google Colab and deploying on Arduinos) and course infrastructure/tools (e.g., online paper discussion forum)
 - Mentored student teams pursuing research-based final projects
- CS 182: Introduction to Artificial Intelligence (Fall 2017-2018)
 - Managed a team of 11 teaching fellows supporting the 150 student course to ensure sections and office hours were held, exams and homework assignments were graded, and student questions on the online forum were answered.
 - Designed and gave lectures: “Introduction to Robotics and Path Planning I/II” and the related assignment/exam questions
 - Co-Designed and gave a new set of weekly recitations that mapped the weekly course content to cross-cutting themes
 - Co-developed course coding and written (theoretical) assignments, and course infrastructure/tools (e.g., autograders)
 - Mentored student teams pursuing research-based final projects

MIT / HARVARD UNIVERSITY: Cambridge, MA – *Teaching Assistant*

FALL 2017,18,19,21

- Harvard’s 15 student section of MIT’s MAS.863: How to Make Almost Anything
 - Gave recitations: “Introduction to Embedded Programming”, “Introduction to Electronics Fabrication and Design”
 - Held office hours, led introductory sessions for course tools, aided students in lab work, machine usage, and project design

MIT LINCOLN LABORATORIES BEAVER WORKS: Cambridge, MA – *Associate Instructor*

SUMMER 2016,17,18,19

- RACECAR Mini Grand Prix Challenge: a hands-on, intensive, residential, project-based, free to attend, 4-week program for high school students interested in studying STEM
 - Worked with 9-12 teams of 4-6 students to teach programming concepts and robotic algorithm design through the completion of fast autonomous navigation tasks using 1/10 scale racecars using Python/ROS
 - Co-designed weekly challenges to ensure all teams developed the technical skills needed for the final race
 - Co-designed and co-built the final race track spanning an entire ice hockey rink

PREPRINTS

- Shvetank Prakash, Matthew Stewart, Colby Banbury, Mark Mazumder, Pete Warden, **Brian Plancher**, Vijay Janapa Reddi, “Is TinyML Sustainable? Assessing the Environmental Impacts of Machine Learning on Microcontrollers,” arXiv, January 2023.

JOURNAL PAPERS

- B. Boroujerdian, H. Genc, S. Krishnan, P. Bardienus, B. Duisterhof, **B. Plancher**, K. Mansoorshahi, M. Almeida, A. Faust, V. Janapa Reddi. “The Role of Compute in Autonomous Aerial Vehicles.” in IEEE Transactions on Computers, 2022.
- V. Janapa Reddi, **B. Plancher**, S. Kennedy, L. Moroney, P. Warden, A. Agarwal, C. Banbury, M. Banzi, M. Bennett, B. Brown, S. Chitlangia, R. Ghosal, S. Grafman, R. Jaeger, S. Krishnan, M. Lam, D. Leiker, C. Mann, M. Mazumder, D. Pajak, D. Ramaprasad, J. E. Smith, M. Stewart, D. Tingley, “Widening Access to Applied Machine Learning with TinyML,” in Harvard Data Science Review, 2022.
- **B. Plancher**, S. M. Neuman, T. Bourgeat, S. Kuindersma, S. Devadas, V. Janapa Reddi, “Accelerating Robot Dynamics Gradients on a CPU, GPU, and FPGA,” in IEEE Robotics and Automation Letters (RA-L), January 2021.
 - Additionally dual-accepted under the RAL+ICRA option for presentation at the IEEE International Conference on Robotics and Automation (ICRA), Xi’an China and Virtual, June 2021.

CONFERENCE PAPERS

- S. M. Neuman, R. Ghosal, T. Bourgeat, **B. Plancher**, V. Janapa Reddi, “RoboShape: Using Topology Patterns to Scalably and Flexibly Deploy Accelerators Across Robots,” in the International Symposium on Computer Architecture (ISCA), Orlando, FL, USA, June 2023.
- Lev Grossman and **Brian Plancher**, “Just Round: Quantized Observation Spaces Enable Memory Efficient Learning of Dynamic Locomotion,” IEEE International Conference on Robotics and Automation (ICRA), London, UK, May 2023.
- Jeremiah Blanchard, John R. Hott, Vincent Berry, Rebecca Carroll, Bob Edmison, Richard Glassey, Oscar Karnalim, **Brian Plancher**, Seán Russell, “Stop Reinventing the Wheel! Promoting Community Software in Computing Education,” in Proceedings of the 2022 Working Group Reports on Innovation and Technology in Computer Science Education (ITiCSE-WGR), Dublin, Ireland, December 2022.
- V. Mayoral-Vilches, S. M. Neuman, **B. Plancher**, V. Janapa Reddi, “RobotCore: An Open Architecture for Hardware Acceleration in ROS 2,” in the IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Kyoto, Japan, October 2022.
- S. M. Neuman, **B. Plancher**, B. P. Duisterhof, S. Krishnan, C. Banbury, M. Mazumder, S. Prakash, J. Jabbour, A. Faust, C.H.E. de Croon, and V. Janapa Reddi, “Tiny Robot Learning: Challenges and Directions for Machine Learning in Resource-Constrained Robots,” in the IEEE International Conference on Artificial Intelligence Circuits and Systems (AICAS), Incheon, Korea, June 2022.
- **B. Plancher**, S. M. Neuman, R. Ghosal, S. Kuindersma, V. Janapa Reddi, “GRiD: GPU-Accelerated Rigid Body Dynamics with Analytical Gradients,” IEEE International Conference on Robotics and Automation (ICRA), Philadelphia PA, May 2022.
- B. Boroujerdian, R. Ghosal, J. Cruz, **B. Plancher**, and V. Janapa Reddi, “RoboRun: A Robot Runtime to Exploit Spatial Heterogeneity,” in the Design Automation Conference (DAC), Virtual, December 2021.
- S. M. Neuman, **B. Plancher**, T. Bourgeat, T. Tambe, S. Devadas, V. Janapa Reddi, “Robomorphic Computing: A Design Methodology for Domain-Specific Accelerators Parameterized by Robot Morphology,” in the ACM International Conference on Architecture Support for Programming Languages and Operating Systems (ASPLOS), Virtual, April 2021.
 - IEEE Micro Top Picks 2022 Honorable Mention
- **B. Plancher**, C. Brumaar, I. Brumar, L. Pentecost, S. Rama, D. Brooks, “Application of Approximate Matrix Multiplication to Neural Networks and Distributed SLAM,” in the IEEE High Performance Extreme Computing Conference (HPEC), Waltham, MA, September 2019.
- **B. Plancher** and S. Kuindersma, “A Performance Analysis of Parallel Differential Dynamic Programming on a GPU,” in the Workshop on the Algorithmic Foundations in Robotics (WAFR), Merida, Mexico, December 2018.
- **B. Plancher**, Z. Manchester, and S. Kuindersma, “Constrained Unscented Dynamic Programming,” in the IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Vancouver, Canada, September 2017.
- S. Karaman, A. Anders, M. Boulet, J. Connor, K. Gregson, W. Guerra, O. Guldner, M. Mohamoud, **Brian Plancher**, R. Shin, and J. Vivilecchia, “Project-based, collaborative, algorithmic robotics for high school students: Programming self-driving race cars at MIT,” in the IEEE Integrated STEM Education Conference (ISEC), Princeton, NJ, March, 2017.

MAGAZINE ARTICLES

- Pete Warden, Matthew Stewart, **Brian Plancher**, Sachin Katti, and Vijay Janapa Reddi, “Machine Learning Sensors: A Design Paradigm for the Future of Intelligent Sensors,” Communications of the ACM (CACM), 2023.

TECHNICAL REPORTS

- Pete Warden, Matthew Stewart, **Brian Plancher**, Colby Banbury, Shvetank Prakash, Emma Chen, Zain Asgar, Sachin Katti, and Vijay Janapa Reddi, “Machine Learning Sensors,” arXiv preprint, June 2022.

POSTERS, WORKSHOPS, ABSTRACTS, AND OTHER

- Marco Zennaro, **Brian Plancher**, Vijay Janapa Reddi, “Bridging the Digital Divide: the Promising Impact of TinyML for Developing Countries,” at the UN 8th Multi-stakeholder Forum on Science, Technology and Innovation for the Sustainable Development Goals. Remote. May 2023.
- Chloe Ho and **Brian Plancher**, “Gender Diversity in Robotics Research,” Northeast Robotics Colloquium (NERC), Lowell, Massachusetts, October 2022.
- Susan Kennedy and **Brian Plancher**, “Voice Interfaces, Gender, and Race: An Intersectional Analysis,” in the Gendering Robots (GenR) Workshop at the IEEE International Conference on Robot and Human Interactive Communication (RO-MAN), Naples, Italy, August 2022.
- Jeremiah Blanchard, John R. Hott, Vincent Berry, Rebecca Carroll, Bob Edmison, Richard Glassey, Oscar Karnalim, **Brian Plancher**, Seán Russell, “Leveraging Community Software in CS Education to Avoid Reinventing the Wheel,” in the ACM Conference on Innovation and Technology in Computer Science Education (ITiCSE), Dublin, Ireland, July 2022.
- Jason Jabbour, Sabrina M. Neuman, Mark Mazumder, Colby Banbury, Shvetank Prakash, **Brian Plancher**, and Vijay Janapa Reddi, “Closing the Sim-to-Real Gap for Ultra-Low-Cost, Resource-Constrained, Quadruped Robot Platforms,” in the Closing the Sim2Real Gap workshop at the Robotics Science and Systems (RSS) Conference, New York, New York, June 2022.

- Marco Zennaro, **Brian Plancher**, and Vijay Janapa Reddi, "TinyML: Applied AI for Development," at the UN 7th Multi-stakeholder Forum on Science, Technology and Innovation for the Sustainable Development Goals. Remote. May 2022.
- **B. Plancher** and V. Janapa Reddi, "The Tiny Machine Learning Open Education Initiative (TinyMLedu)," ACM Technical Symposium on Computer Science Education (SIGCSE), Providence, Rhode Island, March 2022.
- **B. Plancher** and S. Kuindersma, "Realtime Model Predictive Control using Parallel DDP on a GPU," in the workshop Toward Online Optimal Control of Dynamic Robots at the International Conference on Robotics and Automation (ICRA), Montreal, Canada, May 2019.

DISSERTATIONS AND THESES

- **B. Plancher**, "GPU Acceleration for Real-time, Whole-Body, Nonlinear Model Predictive Control," Harvard University, PhD Dissertation, April 2022.
- **B. Plancher**, "Parallel and Constrained Differential Dynamic Programming for Model Predictive Control," Harvard University, MEng Thesis, May 2018.
- **B. Plancher**, "Hacking the White House: Election Fraud in the Digital Age," Harvard University, Undergraduate Thesis, March 2013.

INVITED TALKS AND SEMINARS

- "GPU Acceleration for Real-Time, Whole-Body, Nonlinear Model Predictive Control," Columbia University Computer Science Faculty Seminar, New York, NY, April 2023.
- "GPU Acceleration for Real-Time, Whole-Body, Nonlinear Model Predictive Control," University of Waterloo MME Departmental Seminar Series, Remote, November 2022.
- "Machine Learning for HPC," Energy Efficient High Performance Computing Working Group, Remote, October 2022.
- "Keyword Spotting with Convolutional Neural Networks," EASI-22: The 2022 Edge AI Summer Institute, Remote, July 2022.
- "Introduction to Artificial Intelligence and (Tiny)ML," EASI-22: The 2022 Edge AI Summer Institute, Remote, July 2022.
- "Convolutions and Transfer Learning for Computer Vision," SciTinyML-22 Latam: Latin America Regional Workshop on Scientific Use of Machine Learning on Low-Power Devices Workshop, Remote, July 2022.
- "The Future of Machine Learning is Tiny and Bright," SciTinyML-22 Latam: Latin America Regional Workshop on Scientific Use of Machine Learning on Low-Power Devices Workshop, Remote, July 2022.
- "Data Pre-Processing for Hands-on Keyword Spotting," SciTinyML-22 Africa: African Regional Workshop on Scientific Use of Machine Learning on Low-Power Devices Workshop, Remote, April 2022.
- "Convolutions for Hands-on Computer Vision," SciTinyML-22 Africa: African Regional Workshop on Scientific Use of Machine Learning on Low-Power Devices Workshop, Remote, April 2022.
- "TinyMLedu: Widening Access to TinyML Education and Resources," TinyML Toronto Meetup, Remote, January 2022.
- "Hardware Acceleration for Realtime Robotics," Barnard College, New York, NY, December 2021.
- "Introduction to Robot Motion Planning," Simmons College, Boston, MA, December 2021.
- "TinyMLedu Outreach: Embedded Machine Learning for the Navajo Nation," TinyML for Good, Remote, November 2021.
- "Hands-on Embedded ML from Theory to Practice: Vision and Audio," SciTinyML-21: Scientific Use of Machine Learning on Low-Power Devices Workshop, Remote, October 2021.
- "Robust Realtime Model Predictive Control through Co-Design," CMU Robotic Exploration Lab, Remote, December 2020.
- "Custom Accelerator Chips (ASICs) for Robotics / Autonomous Systems," Pillar VC, Boston, MA, April 2020.
- "Accelerating Real Time Model Predictive Control," Optimus Ride, Boston, MA, October 2019.
- "GPU Acceleration for Robotics," DUT/MIT Formula Student Driverless, Cambridge, MA, November 2018.

GRANTS AWARDED

National Science Foundation (NSF):

- CRII: OAC: RUI: Real-Time, Mixed-Integer Model Predictive Control via Learned GPU-Acceleration – [\\$174,957](#) 2023-2025

IEEE Computer Society:

- Diversity and Inclusion Fund: TinyML Outreach Workshop with the Navajo Nation – [\\$5,000](#) SUMMER 2022

ADVISING

UNDERGRADUATE THESES

- Dhilan Ramaprasad: Highest Honors MAY 2022
Teaching Embedded Systems Programming
- Lev Jacob Grossman: Highest Honors MAY 2020
Reinforcement Learning to Enable Robust Robotic Model Predictive Control
- John Alex Keszler: Honors MAY 2019
FPGA Acceleration of Motion Planning Algorithms For Robotics Applications

MENTOR

- Barnard College Summer Research Institute (SRI) SUMMER 2022
 - Susannah Abrams: *GPU Acceleration of Robot Dynamics Algorithms*
 - Tara Bogavelli: *Sim-to-Real Reinforcement Learning for Low-Cost Walking Robots*
 - Chloe Ho: *Gender Diversity in Robotics Research*
- Harvard College Women in STEM Mentorship Program FALL 2021 – SPRING 2022
- Try AI: “A program designed to introduce early undergraduate students, particularly those identifying as women, Black, Latinx, and/or Indigenous, to research in Artificial Intelligence” FALL 2020

UNIVERSITY COMMITTEES

Barnard College, Columbia University:

- Barnard College Tenured Faculty Search Committee 2023
- Barnard College Summer Research Institute Department Representative for Computer Science 2022 – PRESENT
- Barnard Center for Research on Women (BCRW) Faculty Advisory Board 2022 – PRESENT

Harvard University:

- Harvard Women in STEM ENVISION Proposal-Writing Competition Judges Panel 2021-2022
- SEAS Committee on Diversity, Inclusion, and Belonging: Post-Baccalaureate Outreach Working Group 2021
- Harvard i3: The Harvard College Innovation Challenge Judges Panel 2021

OUTREACH AND PROFESSIONAL SERVICE

Co-Chair:

- The Tiny Machine Learning Open Education Initiative (TinyMLedu): A group of academics and industry professionals working to increase global access to low-cost embedded machine learning education and research – 2021 to Present. [[Link](#)]

Associate Co-Chair:

- IEEE RAS Technical Committee on Model-Based Optimization for Robotics – 2022 to Present. [[Link](#)]

Co-Organizer:

- EdgeMLUP 2023: An in-person 5-day hands-on workshop at ICTP for university level educators, focused on the global south, to develop and expand access to embedded machine learning curricula and research programs [[Link](#)].
- SciTinyML 2021-23: Scientific Use of Machine Learning on Low-Power Devices: a 5-day hands-on, virtual workshop for university students and professors exploring real-world applications of TinyML and their impact on the developing world. 2021 was run globally with 216 participants from 48 countries, 2022 was run regionally for Africa (187 from 29), Asia (100 from 8), and Latin America (200 from 17), 2023 will be run globally. [[Link-21](#), [Link-22](#), [Link-23](#)]
- 3rd On-Device Intelligence Workshop. A Conference on Machine Learning and Systems (MLSys) 2023 Workshop. [[Link](#)]
- Building Approachable, Hands-On Embedded Machine Learning Curriculum Using Edge Impulse and Arduino. An AAAI 2023 Conference on Artificial Intelligence Tutorial and Lab Forum. [[Link](#)]
- RoboARCH: Workshop on Robotics Acceleration with Computing Hardware. An IEEE/ACM International Symposium on Microarchitecture (MICRO) 2022 Workshop. [[Link](#)]
- Mind the Gap: Opportunities and Challenges in the Transition Between Research and Industry. A Robotics Science and Systems (RSS) 2022 Workshop. [[Link](#)]
- EASI 2022: the Edge AI Summer Institute. A 3-day, hands-on workshop for high school teachers and students serving the Navajo Nation exploring artificial intelligence through hands-on examples of TinyML. This program was a collaboration between Harvard University, Navajo Technical University and Barnard College, Columbia University. [[Link](#)]
- CRESTLEX 2021: CReating Effective STEM Learning Experiences. A 4-day, hands-on workshop for high school teachers and students serving the Navajo Nation exploring artificial intelligence through hands-on examples of TinyML. This program was a collaboration led by Harvard and Navajo Technical University with support from Google and Edge Impulse. [[Link](#)]

Program Committee:

- ACM Technical Symposium on Computer Science Education (SIGCSE TS) – 2023
- ACM Innovation and Technology in Computer Science Education (ITiCSE) – 2022-23

Reviewer:

- IEEE Robotics and Automation Letters (RAL)
- IEEE Transactions on Robotics (T-RO)
- IEEE Transactions on Control Systems Technology (TCST)
- Robotics Science and Systems (RSS) – 2023
- IEEE International Conference on Robotics and Automation (ICRA) – 2021-23
- IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) – 2020, 22-23
- UN IATT STI Forum – 2023
- IEEE International Conference on Advanced Motion Control (AMC) – 2022
- IEEE Integrated STEM Education Conference (ISEC) – 2018

Member:

- Institute of Electrical and Electronics Engineers (IEEE)
- IEEE Robotics and Automation Society (IEEE-RAS)
- IEEE-RAS Technical Committee (TC) on Model-Based Optimization for Robotics (TCOptRob), TC on Humanoids, TC on Performance Evaluation & Benchmarking, TC on Robot Learning, TC on Robot Ethics
- IEEE Computer Society (IEEE-CS)
- IEEE Women in Engineering (IEEE-WiE)
- Association for Computing Machinery (ACM)
- ACM Special Interest Group on Computer Science Education (ACM-SIGCSE)
- Association for the Advancement of Artificial Intelligence (AAAI)
- Women in AI & Robotics

ADDITIONAL PROFESSIONAL EXPERIENCE

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- PILLAR VC:** Boston, MA – *Venture Fellow* JAN 2020 - MAY 2020
- Assisted in sourcing and evaluating potential investments with a focus in robotics and AI
- MCKINSEY & COMPANY:** Boston, MA – *Business Analyst* AUG 2013 - JULY 2015
- Offered promotion to senior associate (designation reserved for top ~5% of business analyst class)
 - On multiple projects, played “junior engagement manager” role, project managing newer business analysts
 - Led product development strategy for a software product, interfacing between multiple engineering teams and management at the business unit and corporate levels for a prime defense contractor
 - Analyzed the value chain, market dynamics, and entry strategy for a new product for a high-tech materials manufacturer
 - Led business case and market entry strategy development for a novel aircraft for a major aerospace manufacturer
 - Designed a network deployment and capital planning strategy for a national wireless carrier
 - Facilitated a culture transformation for a Fortune 500 company including a simultaneous worldwide conference
 - Designed a comprehensive economic development and revitalization strategy for a rural area of the United States
 - Performed the strategic due diligence that led to a successful large (>\$10Bn) deal between Fortune 500 companies
- UNITED STATES DEPARTMENT OF DEFENSE:** Fort Meade, MD – *Cryptologic Access Program* MAY 2012 - AUG 2012
- Led an internal consulting project on the use of Cloud-based solutions by developing a Map-Reduce Analytic backed GUI prototype and researching and presenting findings on possible use cases to division management
 - Helped lead weekly meetings to coordinate a 15 person development team and ensure code reuse and efficient production
 - Designed and built generic and reusable widgets in EXT-JS and the Ozone Widget Framework in order to aid leadership in analyzing current operational metrics and improve operational efficiency and oversight
- US GREEN DATA:** Cambridge, MA – *Senior Software Engineer* SEPT 2011 - MAY 2012
- Managed the tech team consisting of 4 Harvard Students and 4 professional web developers to ensure collaboration and production as lead web designer and developer in a Django / jQuery environment
 - Evaluated the web development direction, product line and client requirements with the CEO and other company leaders
 - Worked with the consulting team to create data models to improve data analysis efficiency and maximize client savings
 - Provided system administrator function to maintain and improve the web architecture, security and design

REFERENCES

Vijay Janapa Reddi

Associate Professor of Electrical Engineering, John A. Paulson School of Engineering, Harvard University
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Scott Kuindersma

Senior Director of Robotics Research, Boston Dynamics
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Former Assistant Professor, John A. Paulson School of Engineering, Harvard University
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Zachary Manchester

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Patrick Wensing

Assistant Professor of Aerospace and Mechanical Engineering, University of Notre Dame
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