

Analysis of Algorithms

CS 477/677

Instructor: Monica Nicolescu

Lecture 23

Searching in a Graph

- **Graph searching** = systematically follow the edges of the graph so as to visit the vertices of the graph
- Two basic graph searching algorithms:
 - Breadth-first search
 - Depth-first search
- The difference between them is in the order in which they explore the unvisited edges of the graph
- Graph algorithms are typically elaborations of the basic graph-searching algorithms

Breadth-First Search (BFS)

- **Input:**

- A graph $G = (V, E)$ (directed or undirected)
- A **source** vertex s from V

- **Goal:**

- Explore the edges of G to “discover” every vertex reachable from s , **taking the ones closest to s first**

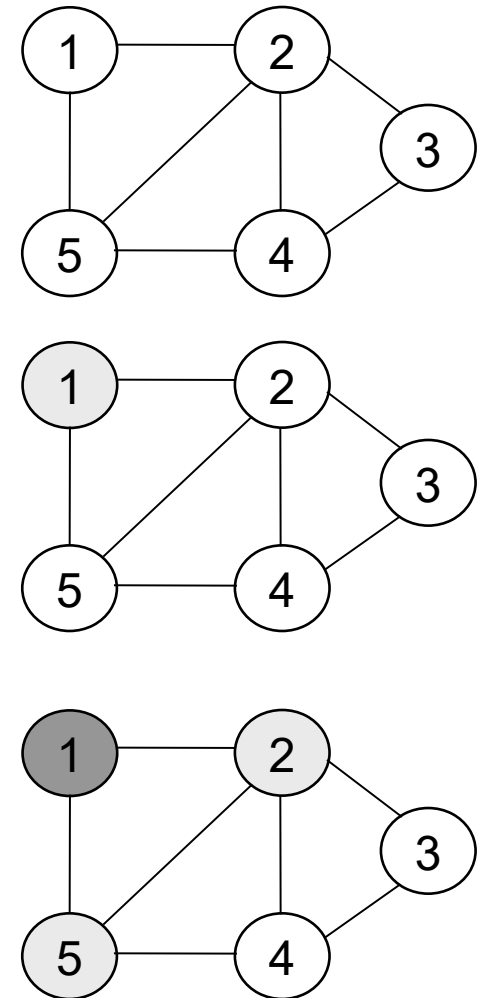
- **Output:**

- $d[v]$ = distance (smallest # of edges) from s to v , for all v from V
- A “breadth-first tree” rooted at s that contains all reachable vertices

Breadth-First Search (cont.)

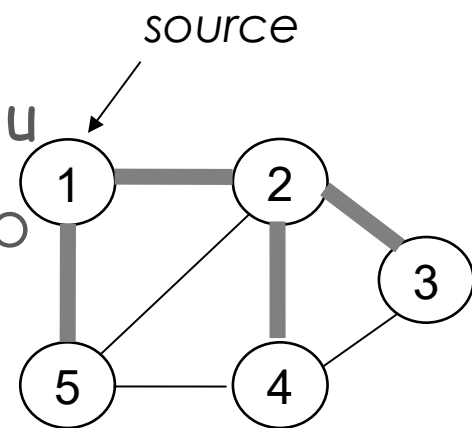
- Keeping track of progress:
 - Color each vertex in either **white**, **gray** or **black**
 - Initially, all vertices are **white**
 - When being discovered a vertex becomes **gray**
 - After discovering all its adjacent vertices the node becomes **black**
 - Use FIFO queue Q to maintain the set of gray vertices

source



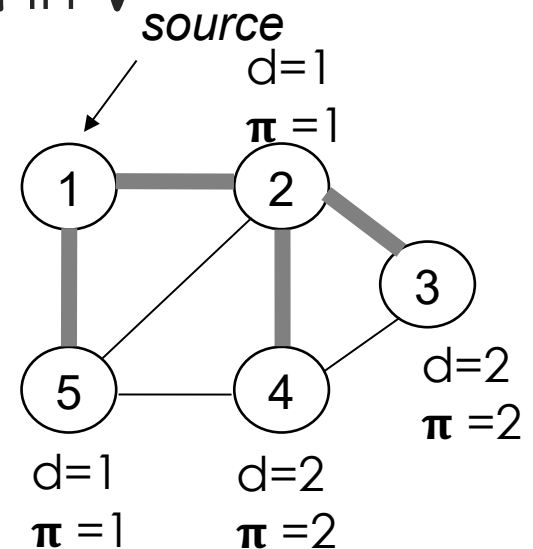
Breadth-First Tree

- BFS constructs a breadth-first tree
 - Initially contains the root (source vertex s)
 - When vertex v is discovered while scanning the adjacency list of a vertex u \Rightarrow vertex v and edge (u, v) are added to the tree
 - u is the **predecessor (parent)** of v in the breadth-first tree
 - A vertex is discovered only once \Rightarrow it has only one parent



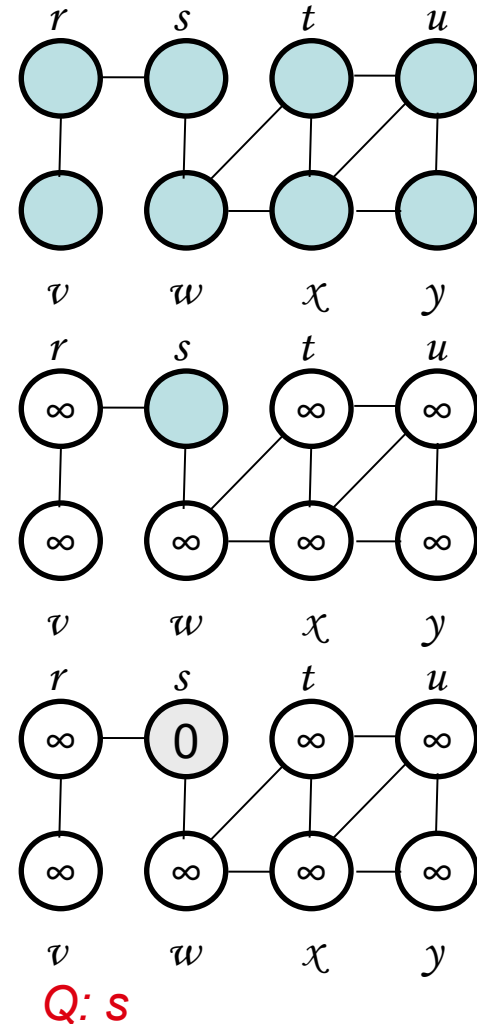
BFS Additional Data Structures

- $G = (V, E)$ represented using adjacency lists
- $\text{color}[u]$ – the color of the vertex for all u in V
- $\pi[u]$ – predecessor of u
 - If $u = s$ (root) or node u has not yet been discovered then $\pi[u] = \text{NIL}$
- $d[u]$ – the distance from the source s to vertex u
- Use a FIFO queue Q to maintain the set of gray vertices



BFS(V, E, s)

1. **for** each u in $V - \{s\}$
2. **do** $\text{color}[u] =$
 WHITE
3. $d[u] \leftarrow \infty$
4. $\pi[u] = \text{NIL}$
5. $\text{color}[s] = \text{GRAY}$
6. $d[s] \leftarrow 0$
7. $\pi[s] = \text{NIL}$
8. $Q = \text{empty}$
9. $Q \leftarrow \text{ENQUEUE}(Q, s)$

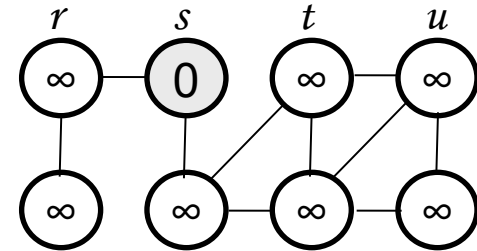


BFS(V, E, s)

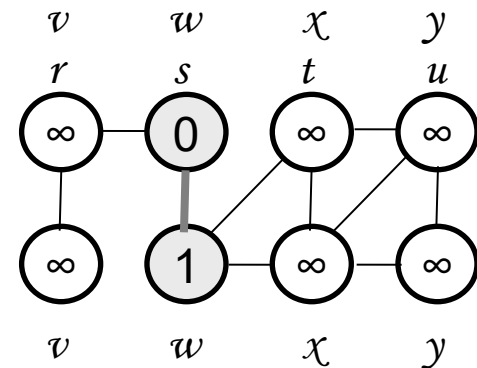
```

10. while Q not empty
11.   do  $u \leftarrow \text{DEQUEUE}(Q)$ 
12.   for each  $v$  in  $\text{Adj}[u]$ 
13.     do if  $\text{color}[v] = \text{WHITE}$ 
14.       then  $\text{color}[v] = \text{GRAY}$ 
15.          $d[v] \leftarrow d[u] + 1$ 
16.          $\pi[v] = u$ 
17.          $\text{ENQUEUE}(Q, v)$ 
18.    $\text{color}[u] = \text{BLACK}$ 

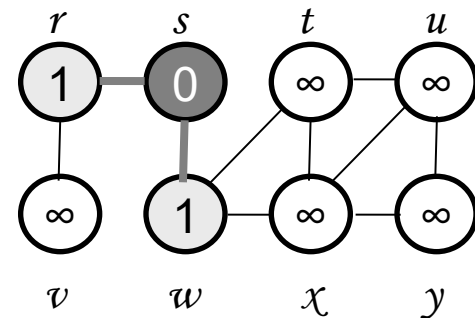
```



Q: s

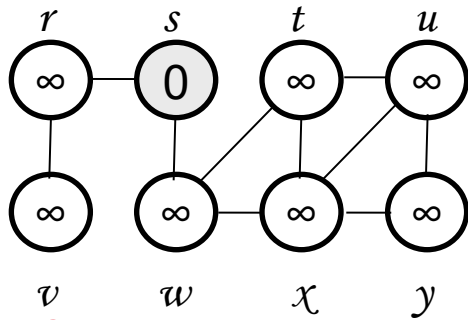


Q: w

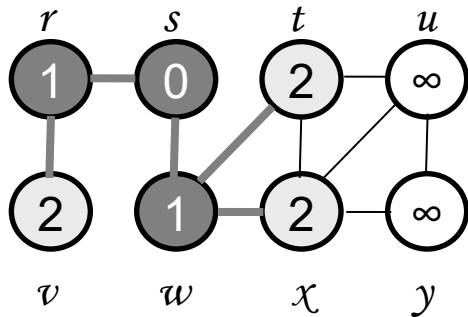


Q: w, r

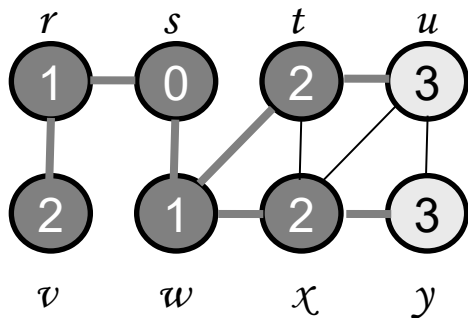
Example



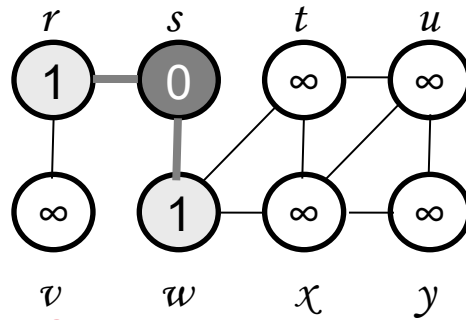
$Q: s$



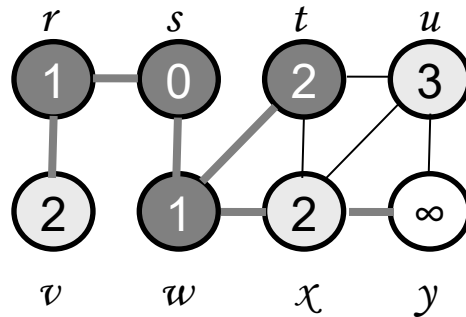
$Q: t, x, v$



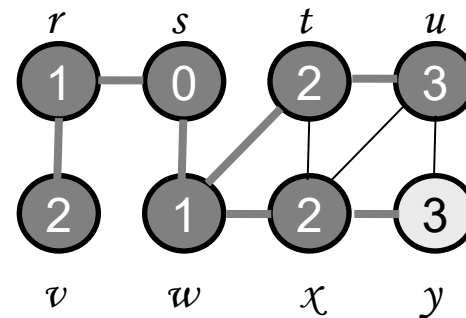
$Q: u, y$



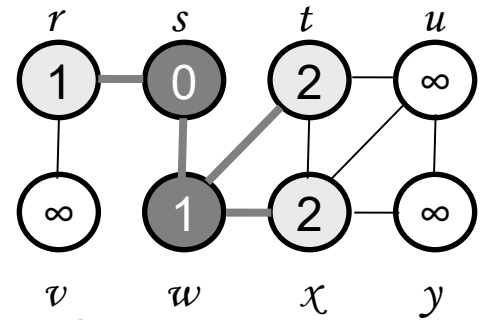
$Q: w, r$



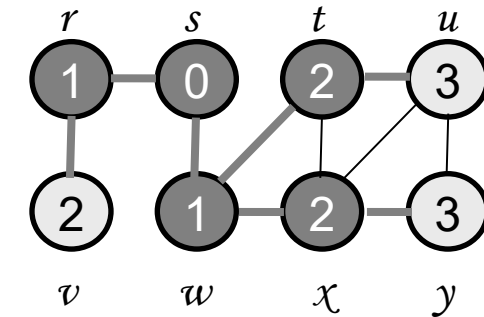
$Q: x, v, u$



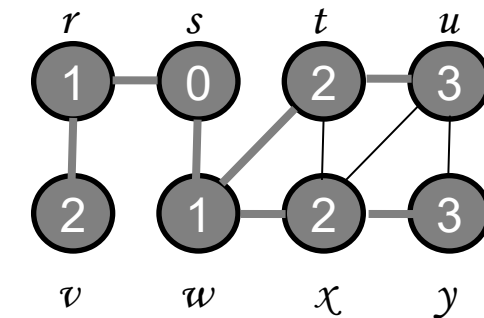
$Q: y$



$Q: r, t, x$



$Q: v, u, y$



$Q: \emptyset$

Analysis of BFS

- | | | |
|--|---|-------------|
| 1. for each $u \in V - \{s\}$ | } | $O(V)$ |
| 2. do $\text{color}[u] \leftarrow$
WHITE | | |
| 3. $d[u] \leftarrow \infty$ | | |
| 4. $\pi[u] = \text{NIL}$ | | |
| 5. $\text{color}[s] \leftarrow \text{GRAY}$ | } | $\Theta(1)$ |
| 6. $d[s] \leftarrow 0$ | | |
| 7. $\pi[s] = \text{NIL}$ | | |
| 8. $Q \leftarrow \emptyset$ | | |
| 9. $Q \leftarrow \text{ENQUEUE}(Q, s)$ | | |

Analysis of BFS

```
10. while Q not empty
11.   do u ← DEQUEUE(Q)
12.   for each v in Adj[u]
13.     do if color[v] = WHITE
14.       then color[v] = GRAY
15.         d[v] ← d[u] + 1
16.         π[v] = u
17.         ENQUEUE(Q, v)
18.   color[u] = BLACK
```

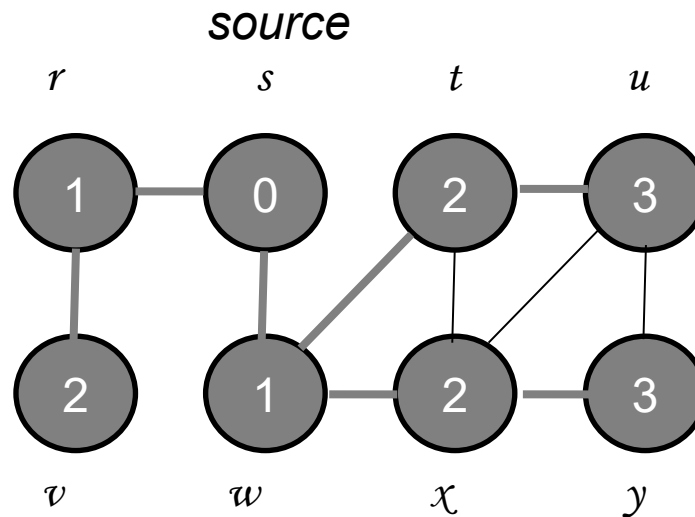
Annotations:

- Line 11: $\Theta(1)$
- Line 12: Scan Adj[u] for all vertices u in the graph
 - Each vertex u is processed only once, when the vertex is dequeued
 - Sum of lengths of all adjacency lists = $\Theta(|E|)$
 - Scanning operations: $O(|E|)$
- Line 17: $\Theta(1)$

- Total running time for BFS = $O(|V| + |E|)$

Shortest Paths Property

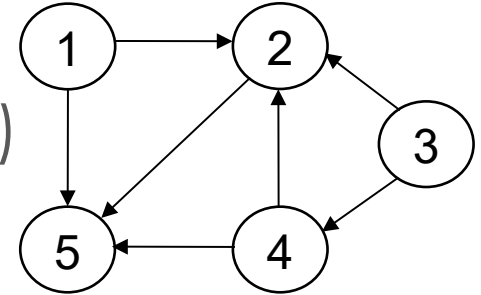
- BFS finds the shortest-path distance from the source vertex $s \in V$ to each node in the graph
- Shortest-path distance = $\delta(s, u)$
 - Minimum number of edges in any path from s to u



Depth-First Search

- **Input:**

- $G = (V, E)$ (No source vertex given!)



- **Goal:**

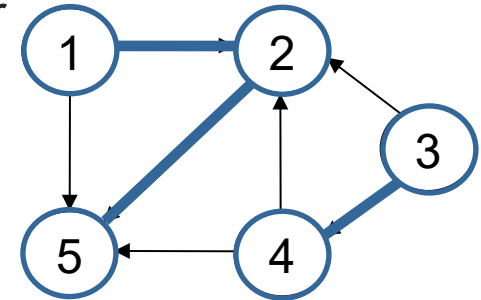
- Explore the edges of G to “discover” every vertex in V starting at the most current visited node
- Search may be repeated from multiple sources

- **Output:**

- 2 **timestamps** on each vertex:
 - $d[v]$ = discovery time
 - $f[v]$ = finishing time (done with examining v 's adjacency list)
- Depth-first forest

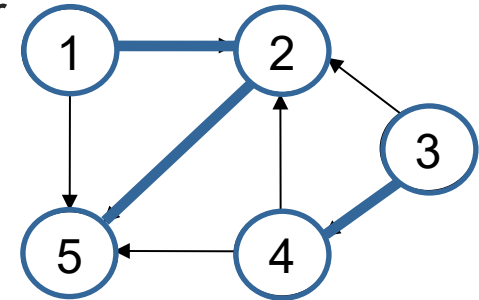
Depth-First Search

- Search “deeper” in the graph whenever possible
- Edges are explored out of the most recently discovered vertex v that still has unexplored edges
- After all edges of v have been explored, the search “backtracks” from the parent of v
- The process continues until all vertices reachable from the original source have been discovered
- If undiscovered vertices remain, choose one of them as a new source and repeat the search from that vertex
- DFS creates a “depth-first forest”



Depth-First Search

- Search “deeper” in the graph whenever possible
- Edges are explored out of the most recently discovered vertex v that still has unexplored edges
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DFS Additional Data Structures

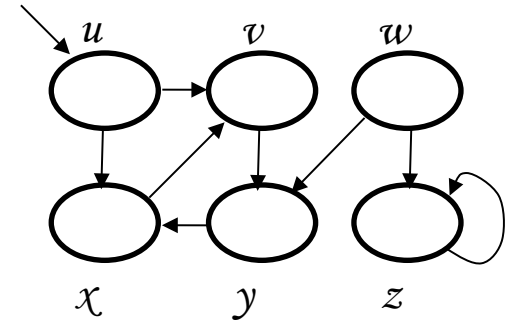
- Global variable: time-step
 - Incremented when nodes are discovered/finished
- **color[u]** – similar to BFS
 - White before discovery, gray while processing and black when finished processing
- $\pi[u]$ – predecessor of u
- $d[u], f[u]$ – discovery and finish times

$$1 \leq d[u] < f[u] \leq 2 |V|$$



DFS(V, E)

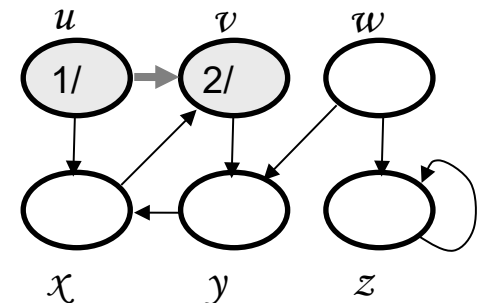
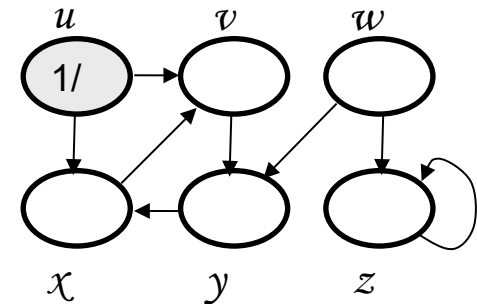
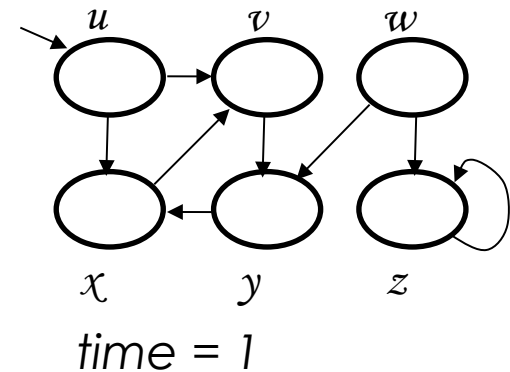
1. **for** each $u \in V$
2. **do** $\text{color}[u] \leftarrow \text{WHITE}$
3. $\pi[u] \leftarrow \text{NIL}$
4. $\text{time} \leftarrow 0$
5. **for** each $u \in V$
6. **do if** $\text{color}[u] = \text{WHITE}$
7. **then** $\text{DFS-VISIT}(u)$



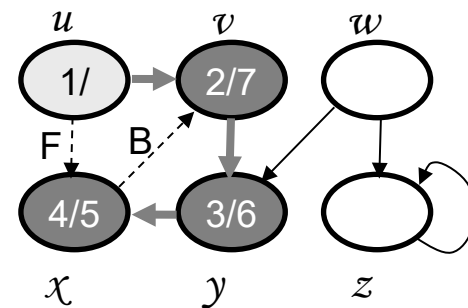
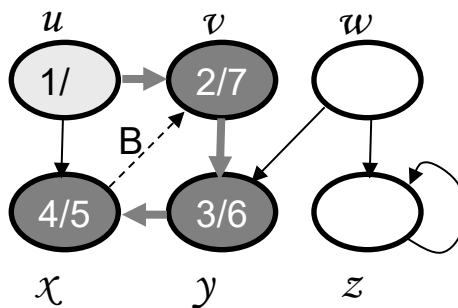
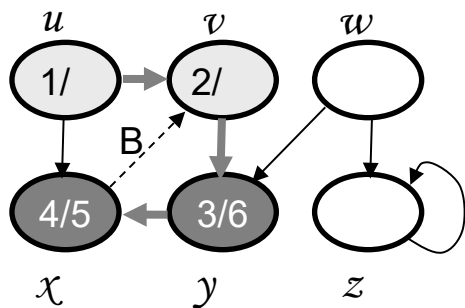
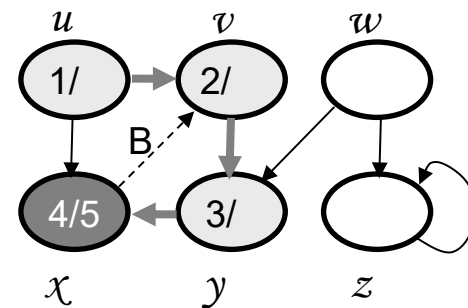
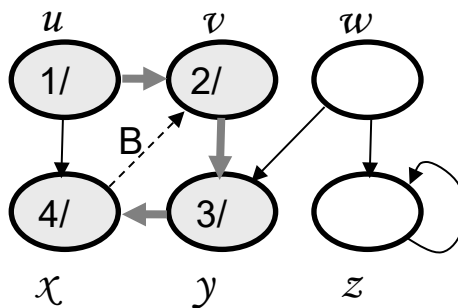
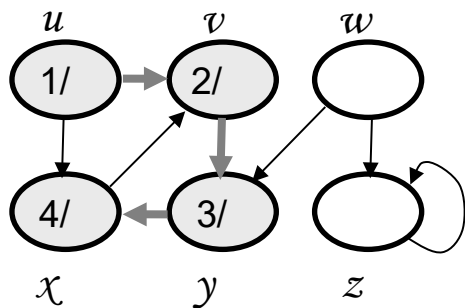
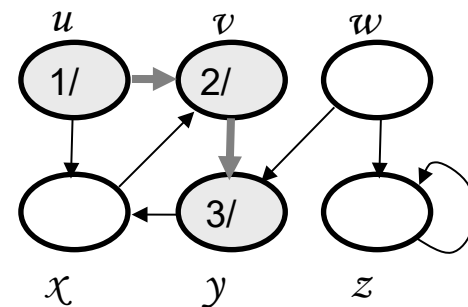
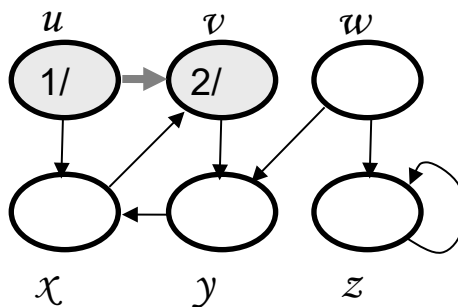
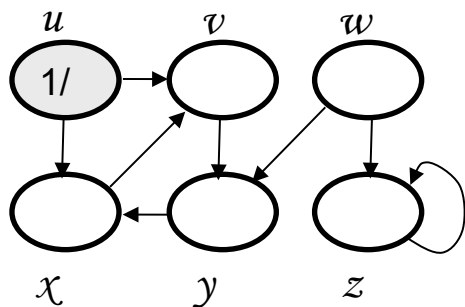
- Every time $\text{DFS-VISIT}(u)$ is called, u becomes the root of a new tree in the depth-first forest

DFS-VISIT(u)

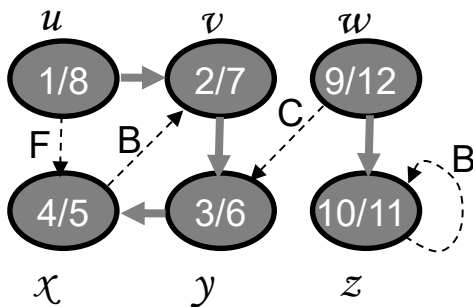
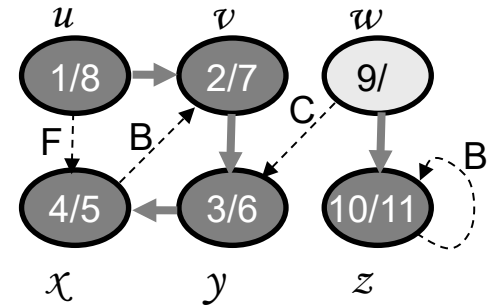
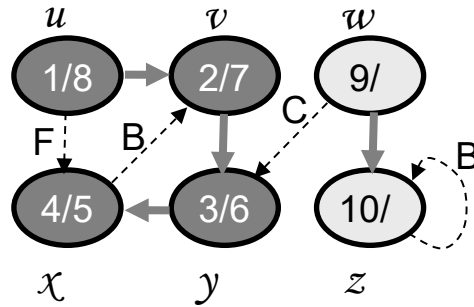
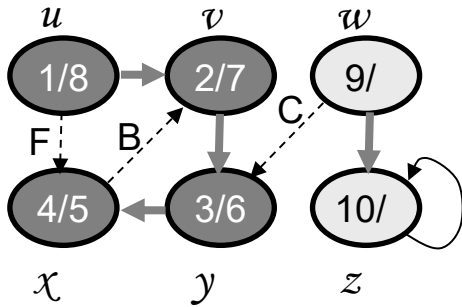
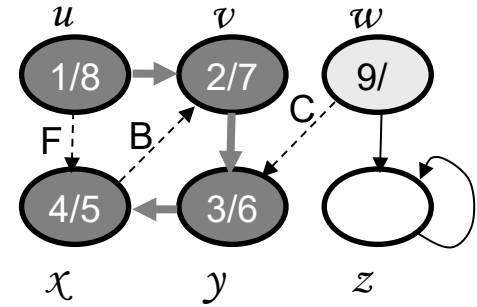
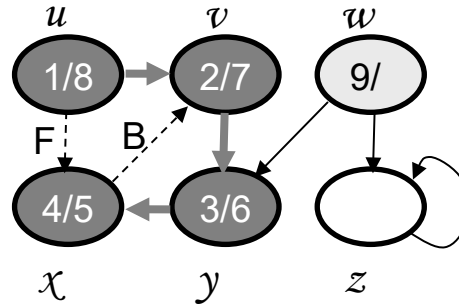
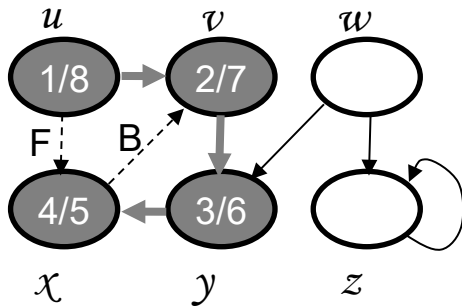
1. $\text{color}[u] \leftarrow \text{GRAY}$
2. $\text{time} \leftarrow \text{time} + 1$
3. $d[u] \leftarrow \text{time}$
4. **for** each $v \in \text{Adj}[u]$
5. **do if** $\text{color}[v] = \text{WHITE}$
6. **then** $\pi[v] \leftarrow u$
7. DFS-VISIT(v)
8. $\text{color}[u] \leftarrow \text{BLACK}$
9. $\text{time} \leftarrow \text{time} + 1$
10. $f[u] \leftarrow \text{time}$



Example



Example (cont.)

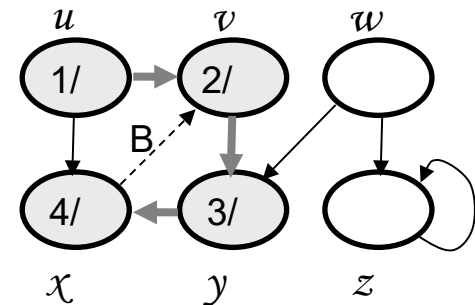
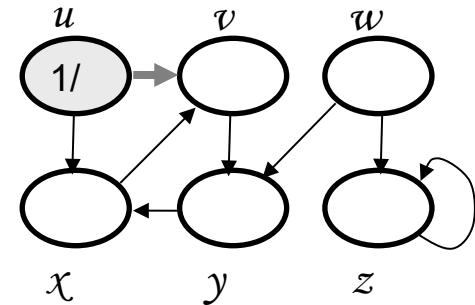


The results of DFS may depend on:

- The order in which nodes are explored in procedure DFS
- The order in which the neighbors of a vertex are visited in DFS-VISIT

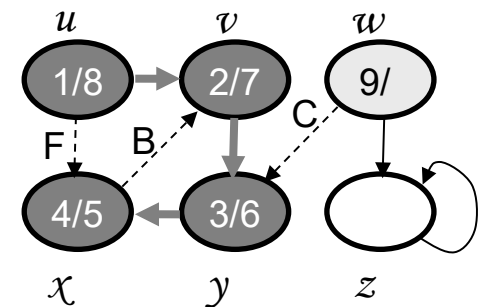
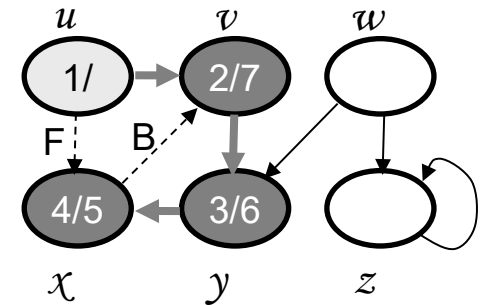
Edge Classification

- **Tree edge** (reaches a WHITE vertex):
 - (u, v) is a tree edge if v was first discovered by exploring edge (u, v)
- **Back edge** (reaches a GRAY vertex):
 - (u, v) , connecting a vertex u to an ancestor v in a depth first tree
 - Self loops (in directed graphs) are also back edges



Edge Classification

- **Forward edge** (reaches a BLACK vertex & $d[u] < d[v]$):
 - Non-tree edge (u, v) that connects a vertex u to a descendant v in a depth first tree
- **Cross edge** (reaches a BLACK vertex & $d[u] > d[v]$):
 - Can go between vertices in same depth-first tree (as long as there is no ancestor / descendant relation) or between different depth-first trees



Analysis of DFS(V, E)

1. **for** each $u \in V$
 2. **do** $\text{color}[u] \leftarrow \text{WHITE}$
 3. $\pi[u] \leftarrow \text{NIL}$
 4. $\text{time} \leftarrow 0$
 5. **for** each $u \in V$
 6. **do if** $\text{color}[u] = \text{WHITE}$
 7. **then** $\text{DFS-VISIT}(u)$
- $\left. \begin{array}{l} \text{1. for each } u \in V \\ \text{2. do } \text{color}[u] \leftarrow \text{WHITE} \\ \text{3. } \pi[u] \leftarrow \text{NIL} \end{array} \right\} \Theta(|V|)$
- $\left. \begin{array}{l} \text{5. for each } u \in V \\ \text{6. do if } \text{color}[u] = \text{WHITE} \\ \text{7. then } \text{DFS-VISIT}(u) \end{array} \right\} \Theta(|V|) - \text{without counting the time for DFS-VISIT}$

Analysis of DFS-VISIT(u)

1. $\text{color}[u] \leftarrow \text{GRAY}$

2. $\text{time} \leftarrow \text{time} + 1$

3. $d[u] \leftarrow \text{time}$

4. **for** each $v \in \text{Adj}[u]$

5. **do if** $\text{color}[v] = \text{WHITE}$

6. **then** $\pi[v] \leftarrow u$

7. DFS-VISIT(v)

8. $\text{color}[u] \leftarrow \text{BLACK}$

9. $\text{time} \leftarrow \text{time} + 1$

10. $f[u] \leftarrow \text{time}$

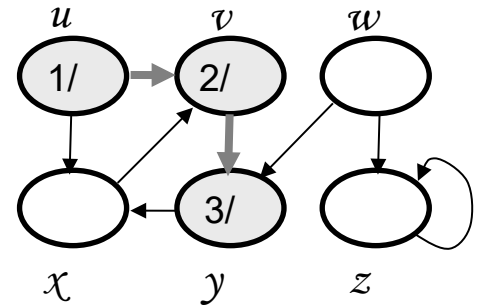
DFS-VISIT is called exactly once for each vertex

Each loop takes $|\text{Adj}[u]|$

$$\text{Total: } \underbrace{\sum_{u \in V} |\text{Adj}[u]|}_{\Theta(|E|)} + \Theta(|V|) = \Theta(|V| + |E|)$$

Properties of DFS

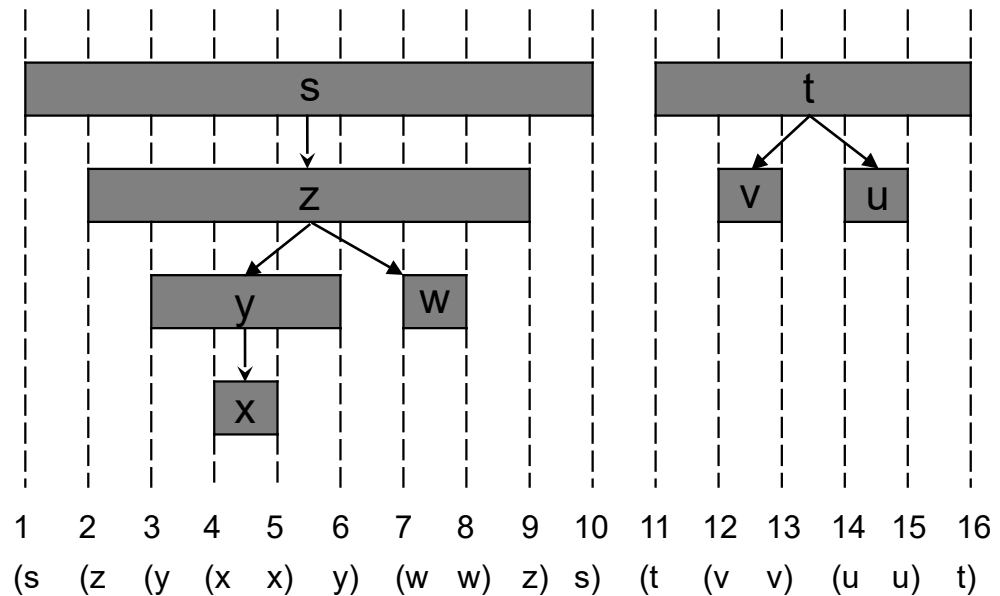
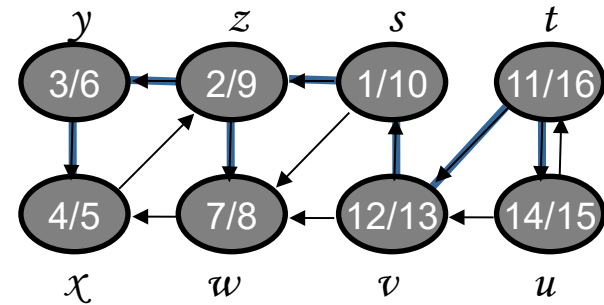
- $u = \pi[v] \iff \text{DFS-VISIT}(v)$ was called during a search of u 's adjacency list
- Vertex v is a descendant of vertex u in the depth first forest
 $\iff v$ is discovered during the time in which u is gray



Parenthesis Theorem

In any DFS of a graph G ,
for all u, v , exactly one
of the following holds:

1. $[d[u], f[u]]$ and $[d[v], f[v]]$ are disjoint, and neither of u and v is a descendant of the other
2. $[d[v], f[v]]$ is entirely within $[d[u], f[u]]$ and v is a descendant of u
3. $[d[u], f[u]]$ is entirely within $[d[v], f[v]]$ and u is a descendant of v



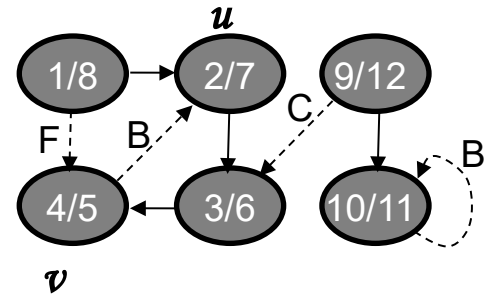
Well-formed expression: parenthesis are properly nested

Other Properties of DFS

Corollary

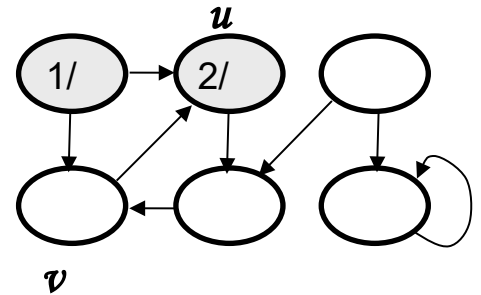
Vertex v is a proper descendant of u

$$\iff d[u] < d[v] < f[v] < f[u]$$



Theorem (White-path Theorem)

In a depth-first forest of a graph G , vertex v is a descendant of u if and only if at time $d[u]$, there is a path $u \Rightarrow v$ consisting of only white vertices.



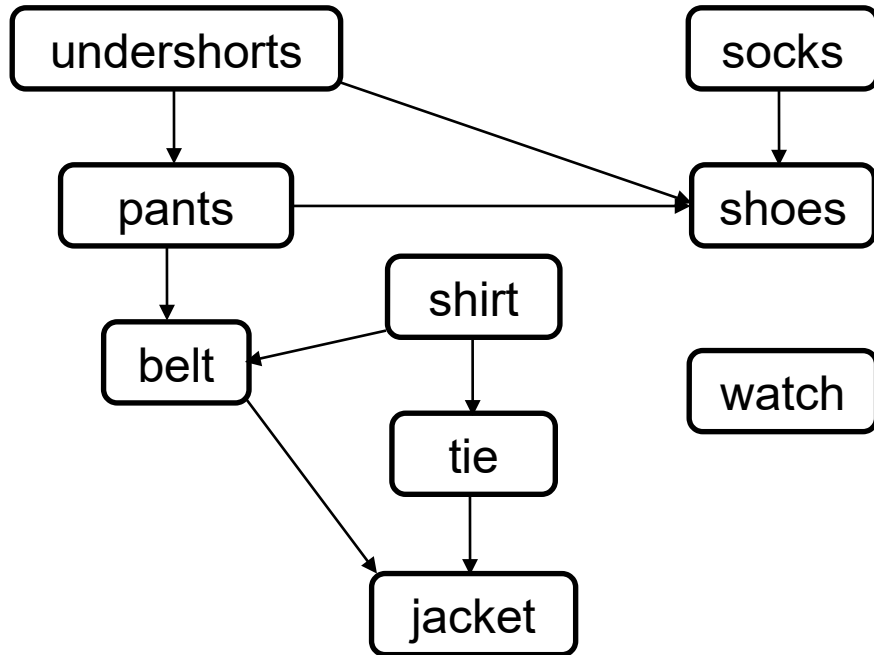
Topological Sort

Topological sort of a directed acyclic graph $G = (V, E)$: a linear order of vertices such that if there exists an edge (u, v) , then u appears before v in the ordering.

- Directed acyclic graphs (DAGs)
 - Used to represent precedence of events or processes that have a **partial order**
- $\left. \begin{array}{l} \mathbf{a} \text{ before } \mathbf{b} \\ \mathbf{b} \text{ before } \mathbf{c} \end{array} \right\} \mathbf{a} \text{ before } \mathbf{c} \quad \left. \begin{array}{l} \mathbf{b} \text{ before } \mathbf{c} \\ \mathbf{a} \text{ before } \mathbf{c} \end{array} \right\} \text{What about } \mathbf{a} \text{ and } \mathbf{b}?$

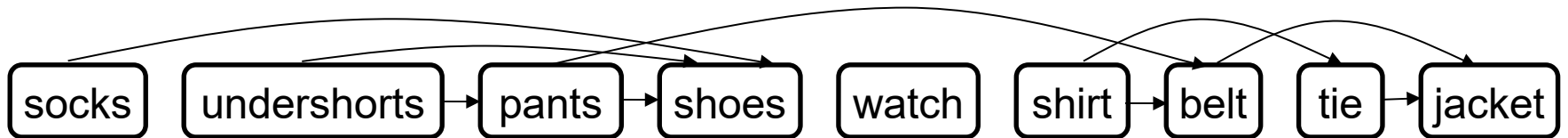
Topological sort helps us establish a **total order**

Topological Sort

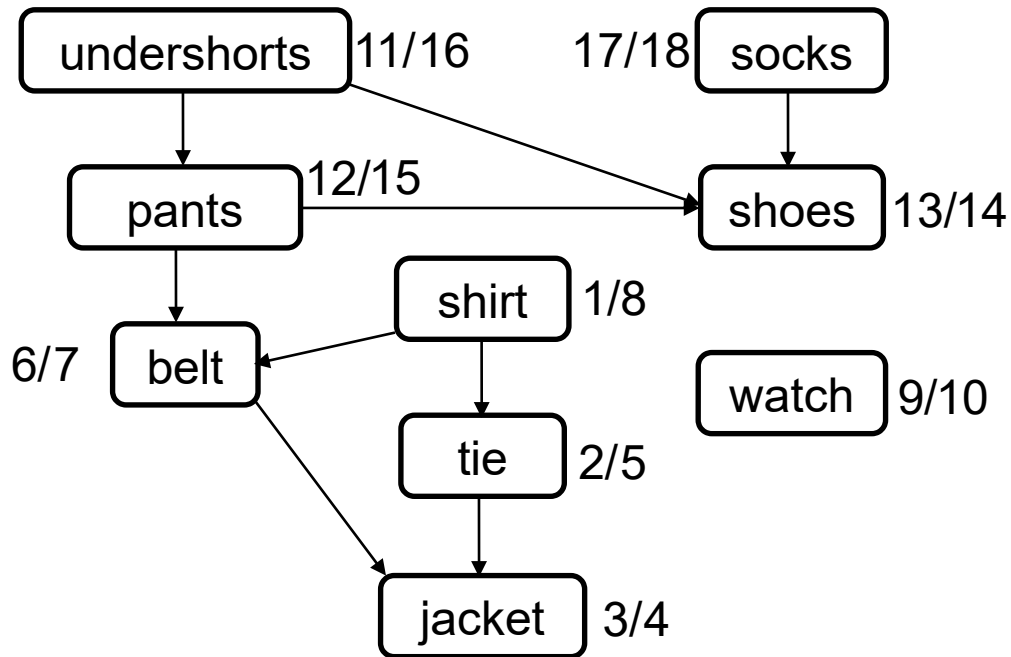


Topological sort:

an ordering of vertices along a horizontal line so that all directed edges go from left to right.



Topological Sort



TOPOLOGICAL-SORT(V, E)

1. Call DFS(V, E) to compute finishing times $f[v]$ for each vertex v
2. When each vertex is finished, insert it onto the front of a linked list
3. Return the linked list of vertices



Running time: $\Theta(|V| + |E|)$

Lemma

A directed graph is **acyclic** \iff a DFS on G yields no back edges.

Proof:

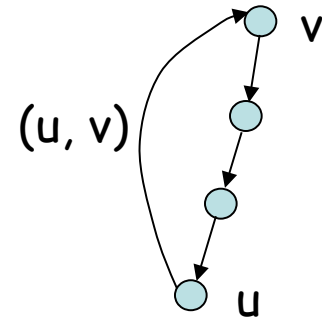
“ \Rightarrow ”: acyclic \Rightarrow no back edge

- Assume **back edge** \Rightarrow prove **cycle**
- Assume there is a back edge (u, v)

$\Rightarrow v$ is an ancestor of u

\Rightarrow there is a path from v to u in G ($v \Rightarrow u$)

$\Rightarrow v \Rightarrow u$ + the back edge (u, v) yield a cycle



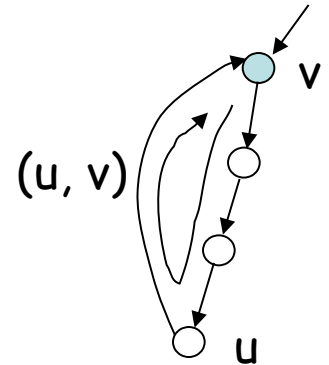
Lemma

A directed graph is **acyclic** \iff a DFS on G yields no back edges.

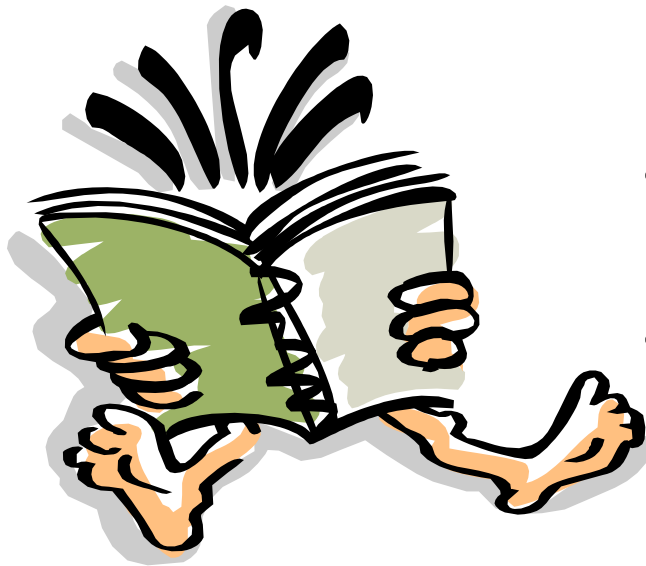
Proof:

“ \Leftarrow ”: no back edge \Rightarrow acyclic

- Assume **cycle** \Rightarrow prove **back edge**
 - Suppose G contains cycle c
 - Let v be the first vertex discovered in c , and (u, v) be the preceding edge in c
 - At time $d[v]$, vertices of c form a white path $v \Rightarrow u$
 - u is descendant of v in depth-first forest (by white-path theorem)
- $\Rightarrow (u, v)$ is a back edge



Readings



- For this lecture
 - Chapter 15
- Coming next
 - Chapter 20