

CHARACTERIZING UNCERTAINTY

LESSON 6

Linear model assumptions

The linear model rests on some important assumptions:

- Errors are additive and normally distributed
- Errors are homoskedastic (don't vary across X s)
- Observations are independent (conditional on the linear predictor)
- Linear (in covariates) mean function
- All error/randomness is in the value of the response (i.e., the X values are precisely known)
- There is no (systematic) missing data

Ecological data rarely conform to these assumptions!

SYNOPSIS

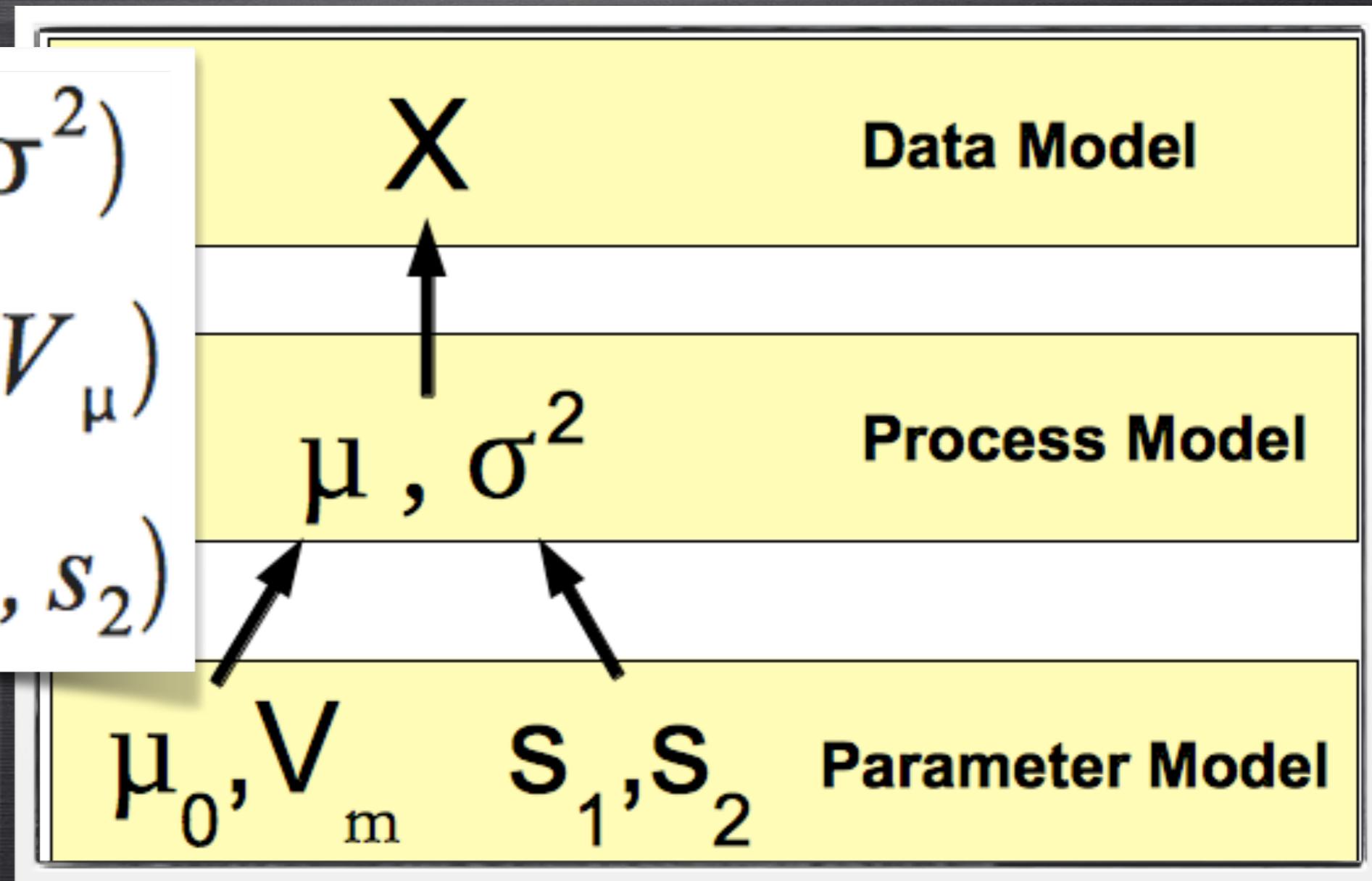
This section dives into the Bayesian methods for characterizing and partitioning sources of error that take us far beyond the classic assumption of a constant Normal variance.

- Non-Gaussian
 - Errors in X — **Latent variables**
 - Missing Data
 - Hierarchical models
 - State-Space (Wed)
 - Heteroskedasticity
-
- ```
graph TD; A[Latent variables] --> B[Errors in X]; A --> C[Missing Data]
```

$$X \sim N(\mu, \sigma^2)$$

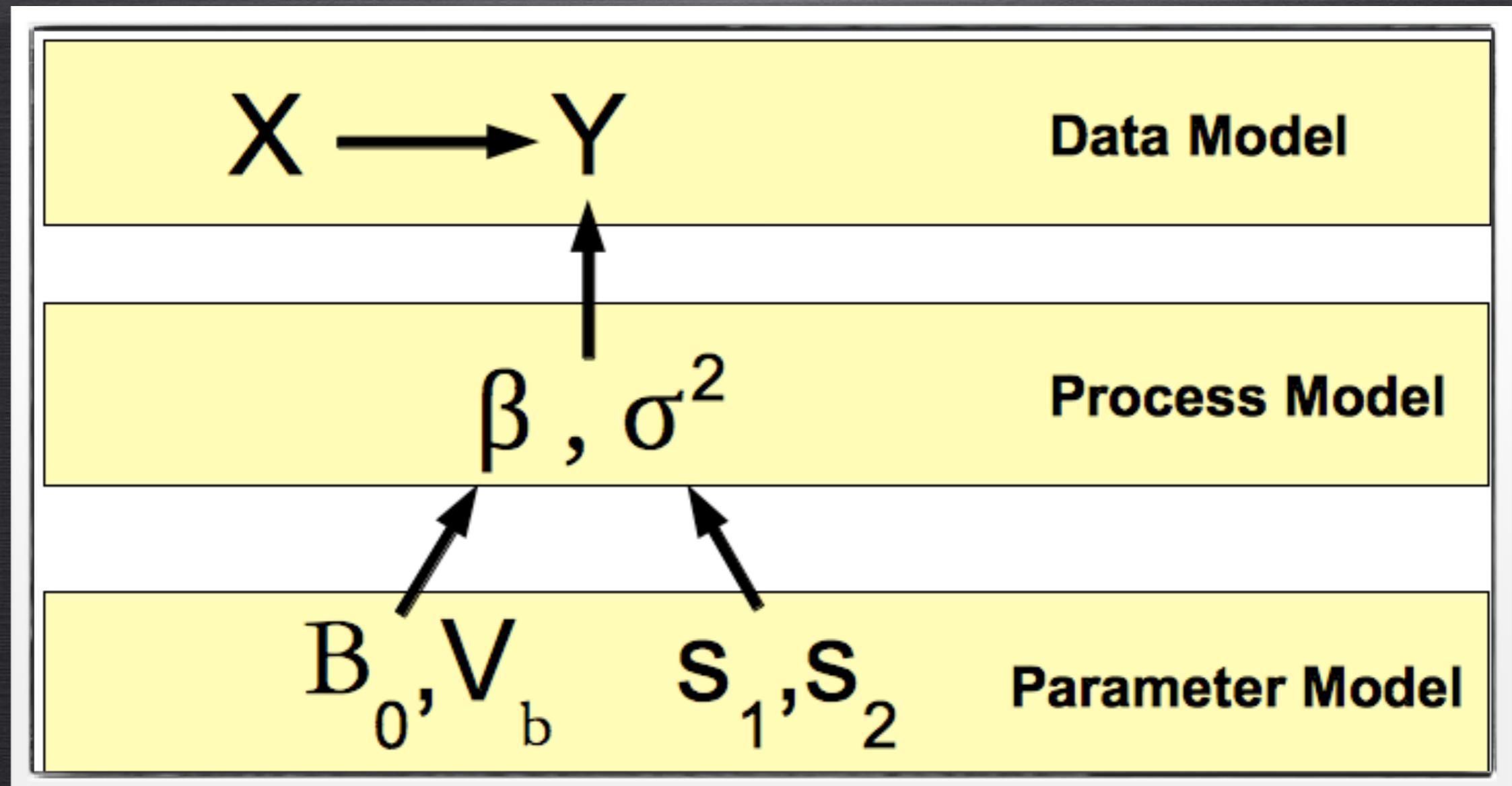
$$\mu \sim N(\mu_0, V_\mu)$$

$$\sigma^2 \sim IG(s_1, s_2)$$



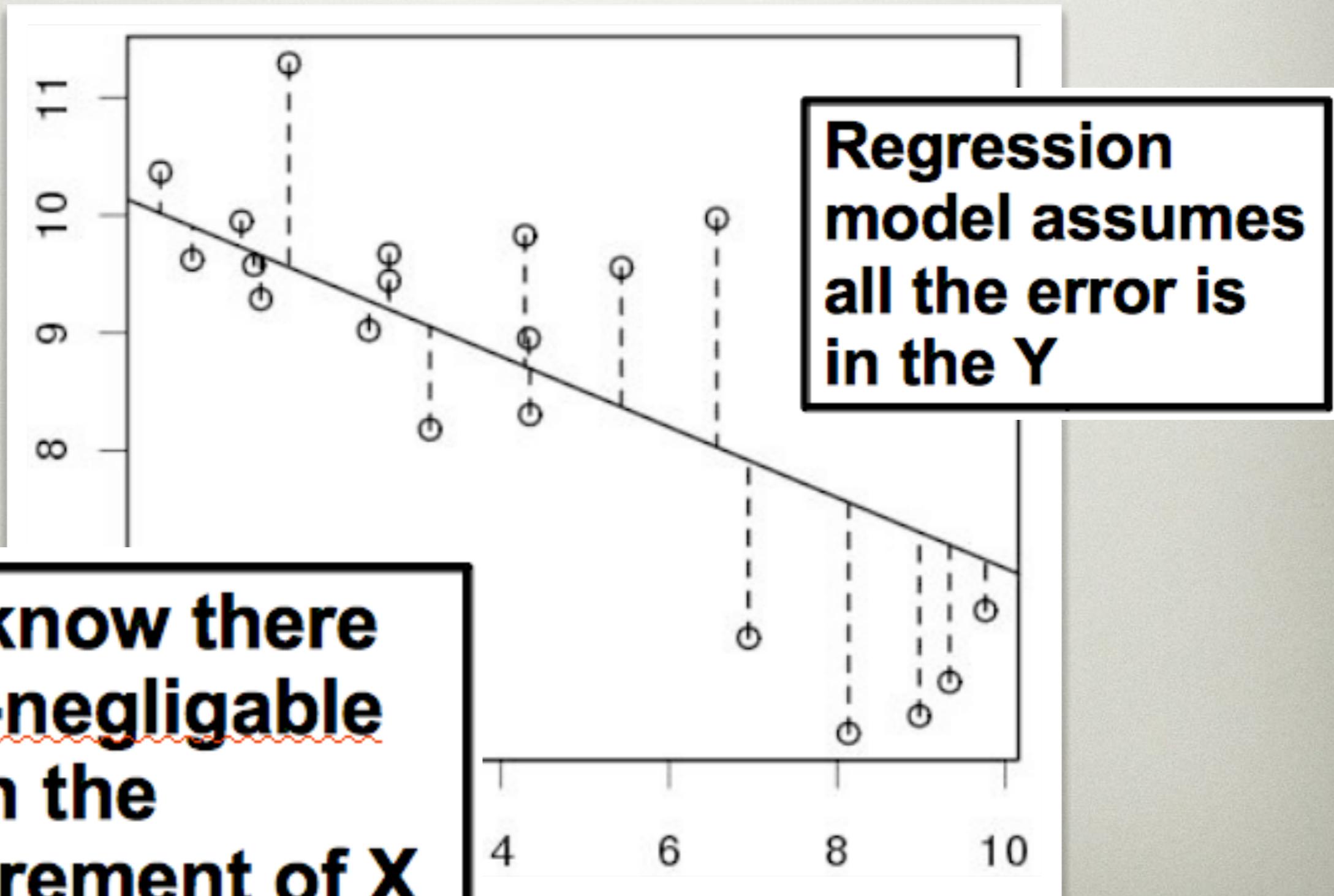
## GRAPH NOTATION

$$\vec{y} \sim N(X\vec{\beta}, \sigma^2)$$



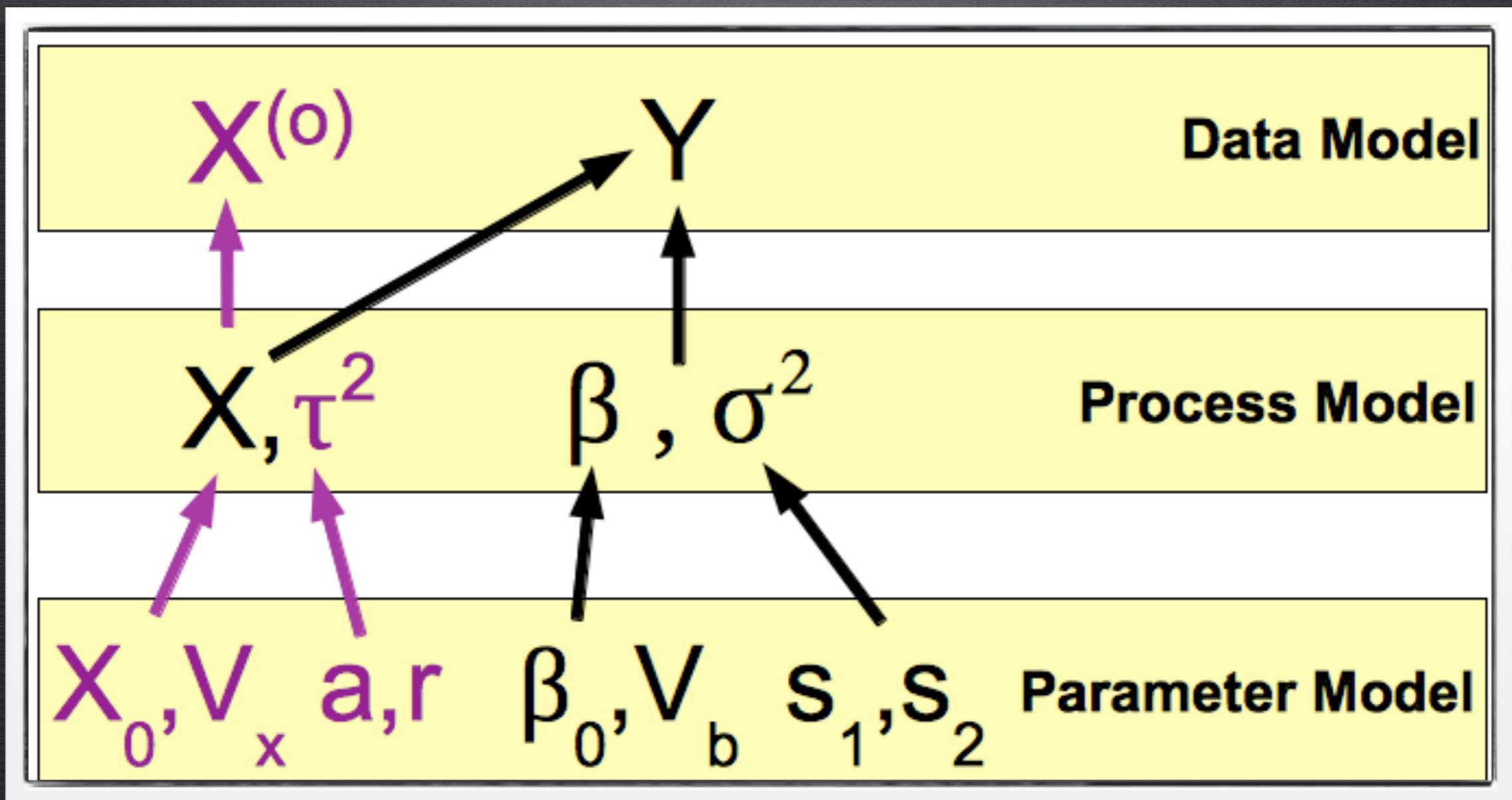
# LINEAR REGRESSION

# ERRORS IN VARIABLES



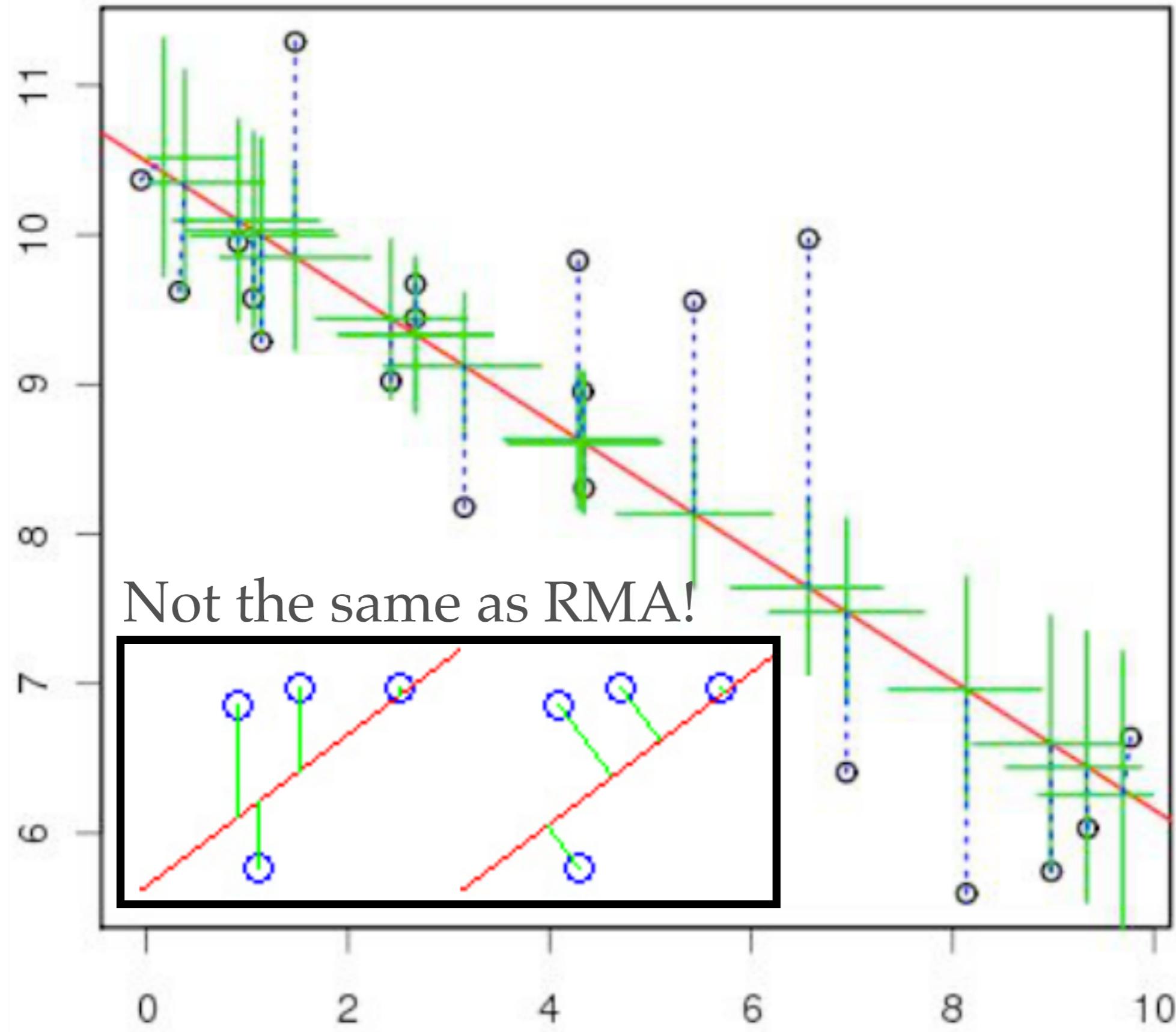
$$\vec{y} \sim N(\vec{X}\vec{\beta}, \sigma^2)$$

$$x^{(o)} \sim N(x, \tau^2)$$



```
model {
 ## priors
 for(i in 1:2) { beta[i] ~ dnorm(0,0.001)}
 sigma ~ dgamma(0.1,0.1)
 tau ~ dgamma(0.1,0.1)
 for(i in 1:n) { x[i] ~ dunif(0,10)}

 for(i in 1:n){
 xo[i] ~ dnorm(x[i],tau)
 mu[i] <- beta[1]+beta[2]*x[i]
 y[i] ~ dnorm(mu[i],sigma)
 }
}
```



# Additional Thoughts on EIV

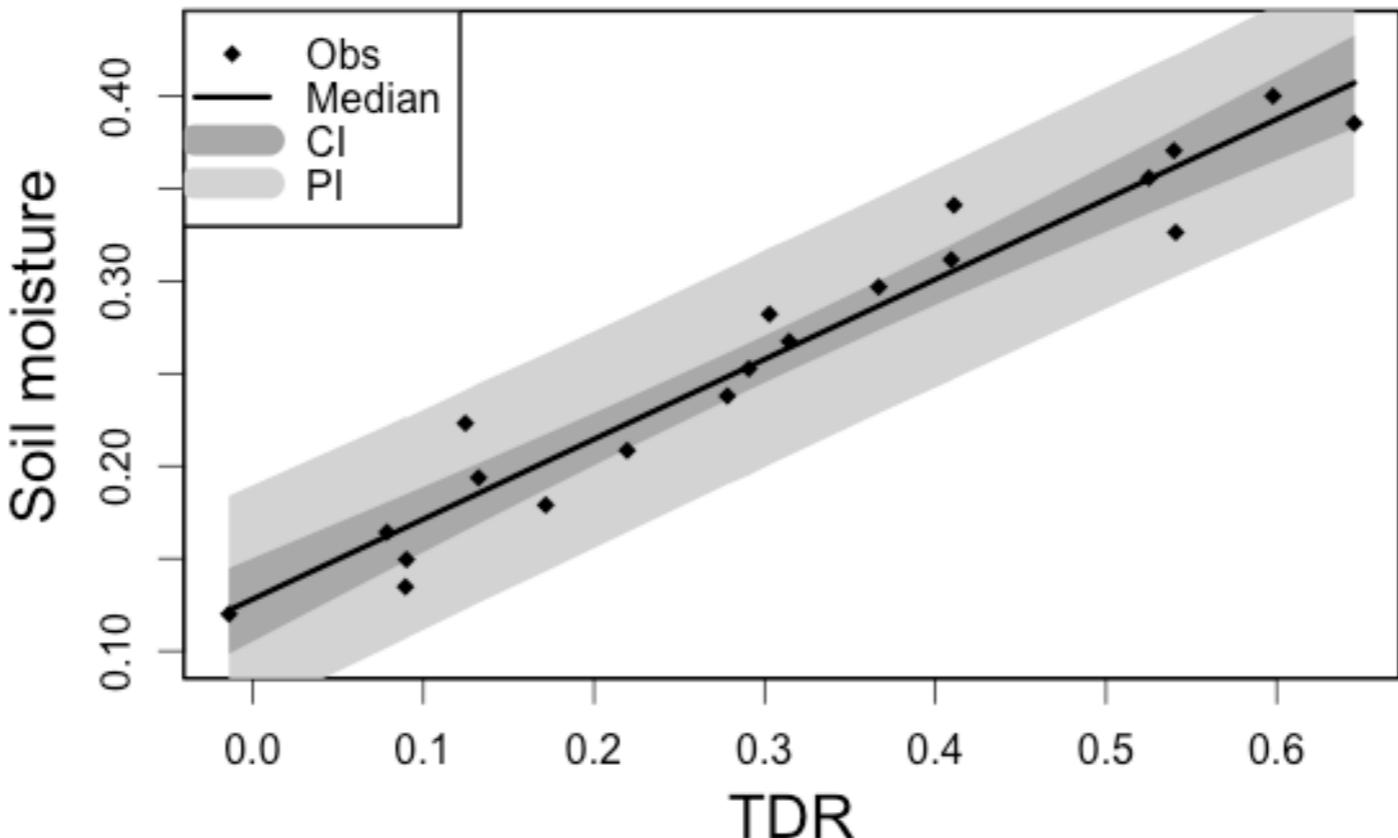
$$x^{(o)} \sim g(x|\theta)$$

- Errors in X's need not be Normal
- Errors need not be additive
- Can account for known biases

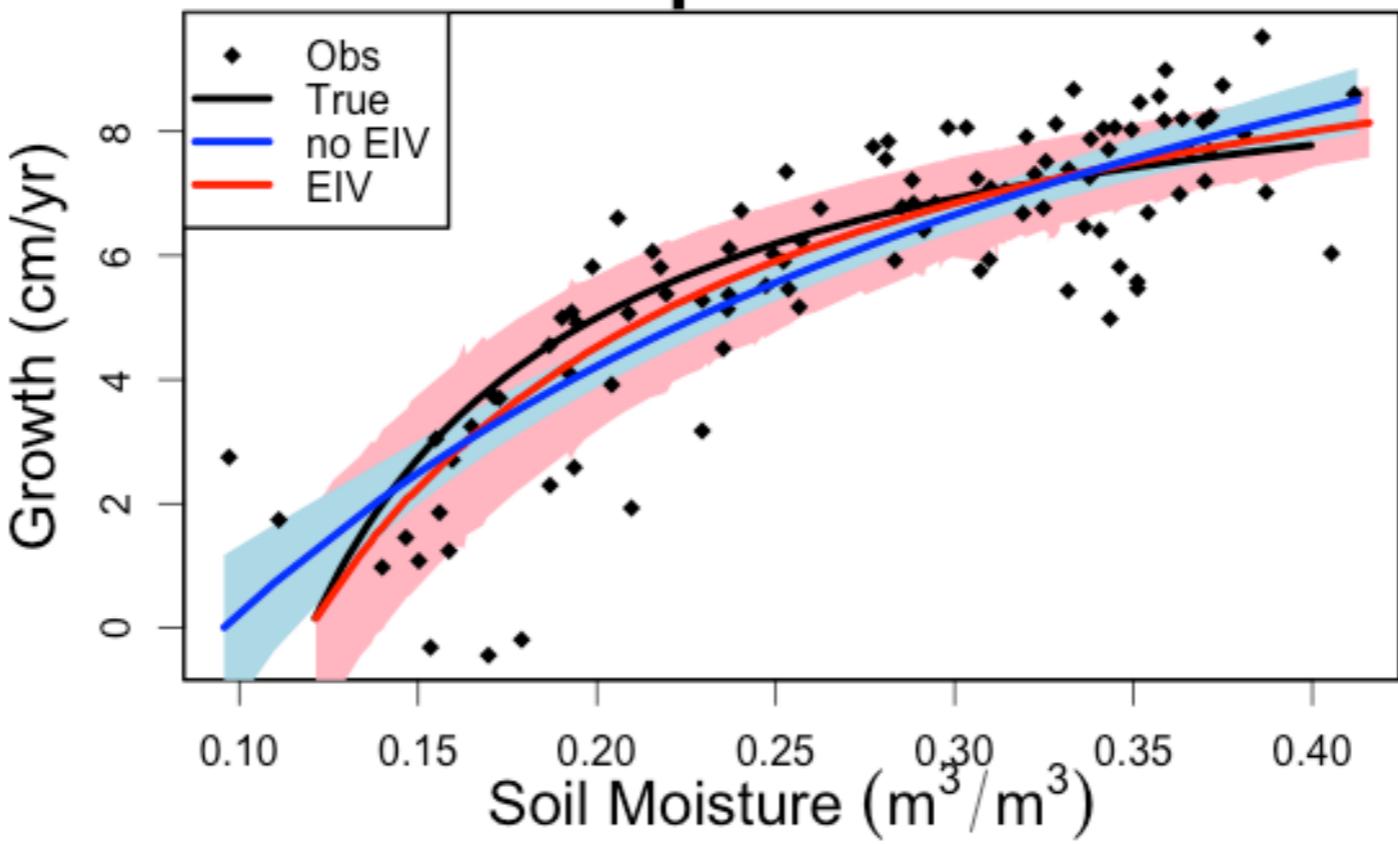
$$x^{(o)} \sim N(\alpha_0 + \alpha_1 x, \tau^2)$$

- Observed data can be a different type (proxy)
  - e.g. calibration curves
- Very useful to have informative priors

## Calibration



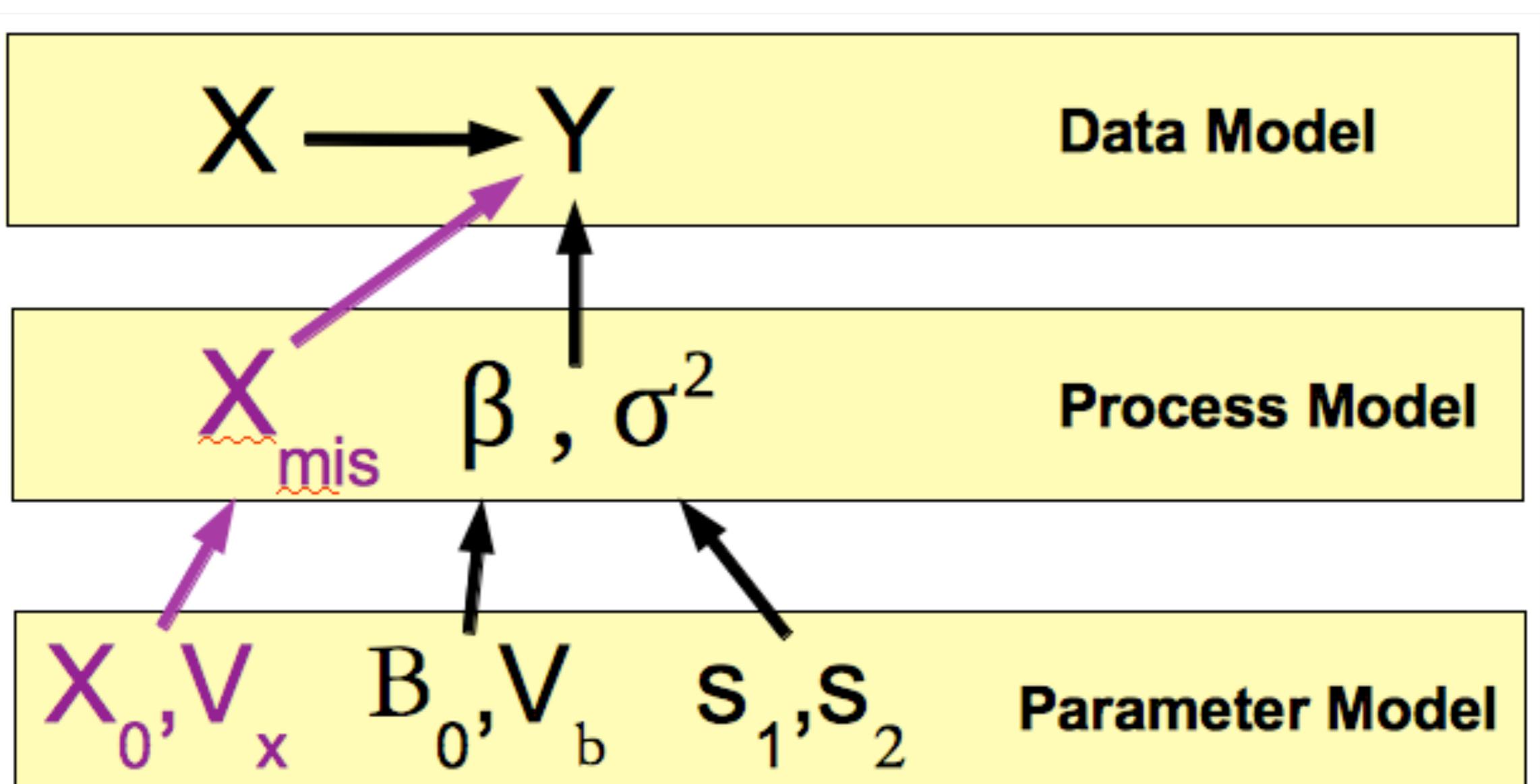
## Growth Response to Moisture



# Latent Variables

- Variables that are not directly observed
- Values are inferred from model
  - Parameter model: prior on value
  - Data and Process models provide constraint
- MCMC integrates over (by sampling) the values the unobserved variable could take on
- Contribute to uncertainty in parameters, model
- Ignoring this variability can lead to falsely overconfident conclusions

# MISSING DATA



Data needs to be Missing At Random!!

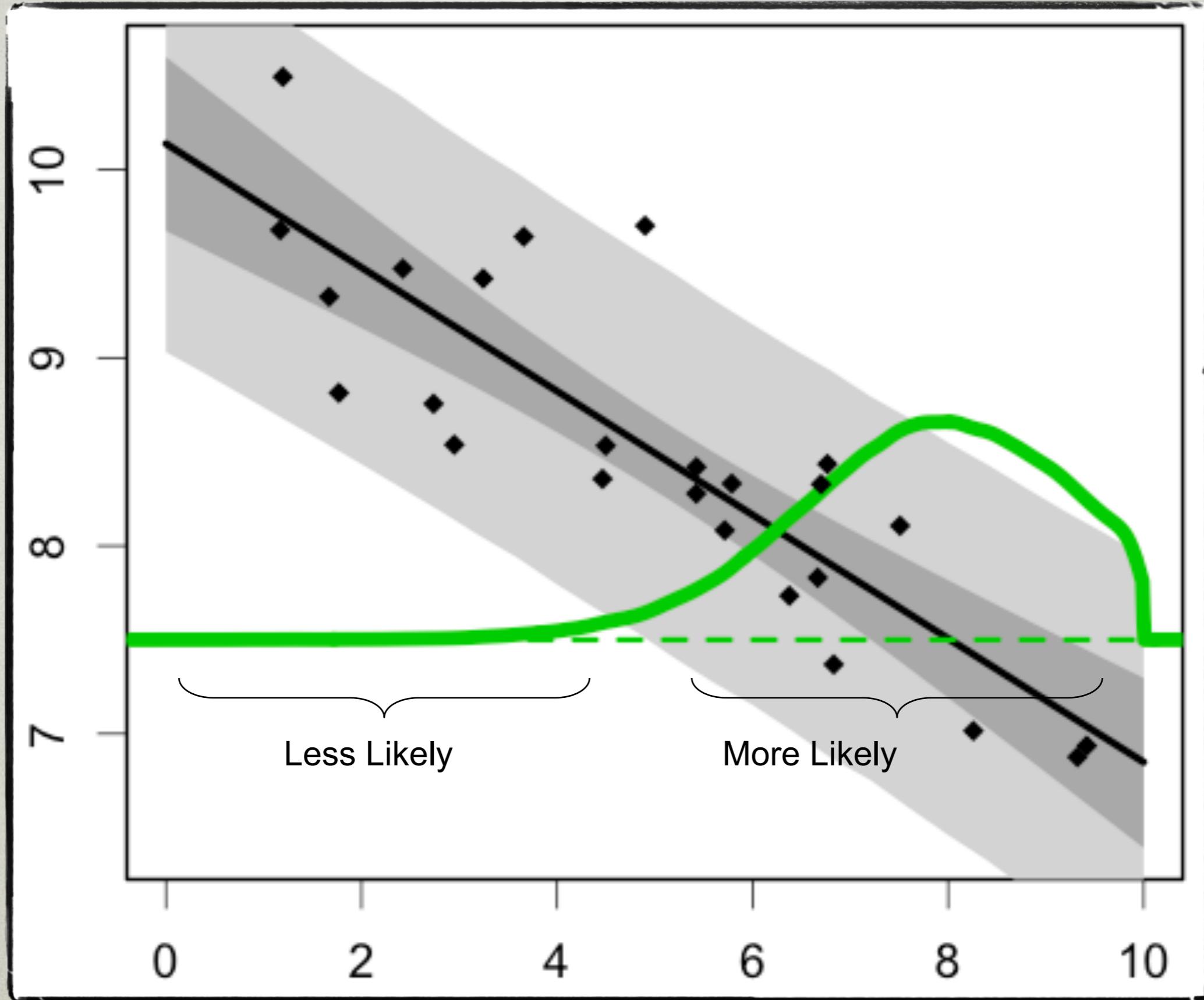
# JAGS example: Simple Regression

```
model{
 ## priors
 for(i in 1:2) { beta[i] ~ dnorm(0,0.001)}
 sigma ~ dgamma(0.1,0.1)
 for(i in mis) { x[i] ~ dunif(0,10)}
 for(i in 1:n){
 mu[i] <- beta[1]+beta[2]*x[i]
 y[i] ~ dnorm(mu[i],sigma)
 }
}
```

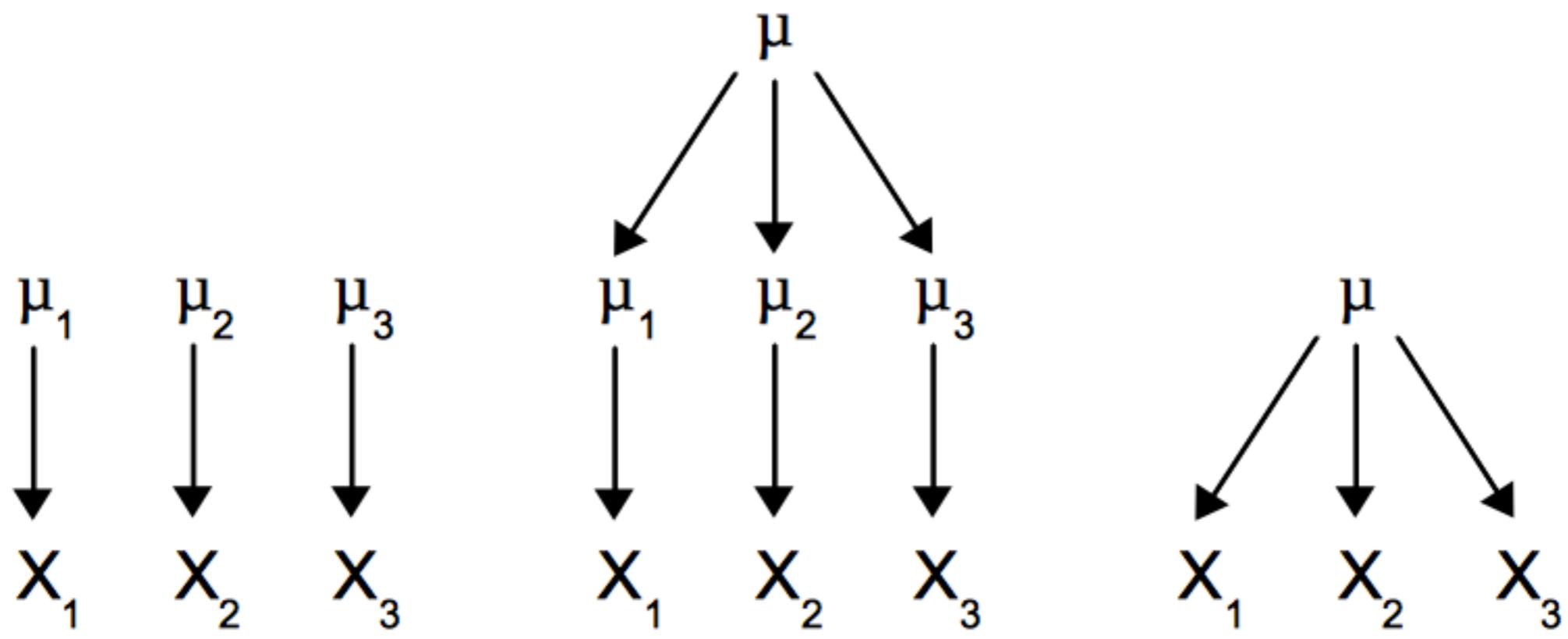
Vector giving indices of missing values

mis = 26 NA

| X    | Y     |
|------|-------|
| 4.68 | 8.46  |
| 2.95 | 8.55  |
| 9.09 | 7.01  |
| 8.15 | 9.06  |
| 1.76 | 11.38 |
| 4.23 | 9.12  |
| 7.73 | 7.3   |
| 2.43 | 8.02  |
| 6.46 | 8.45  |
| 4.06 | 8.95  |
| 2.42 | 9.62  |
| 0.6  | 9.15  |
| 8.17 | 7.51  |
| 0.22 | 10.8  |
| 4.93 | 9.78  |
| 2.99 | 10.71 |
| 8.36 | 8.89  |
| 6.4  | 8.21  |
| 8.17 | 6.22  |
| 6.46 | 5.4   |
| 1.82 | 10.05 |
| 9.52 | 7.96  |
| 2.44 | 9.63  |
| 6.84 | 7.05  |
| 7.42 | 8.73  |
|      | 7.5   |



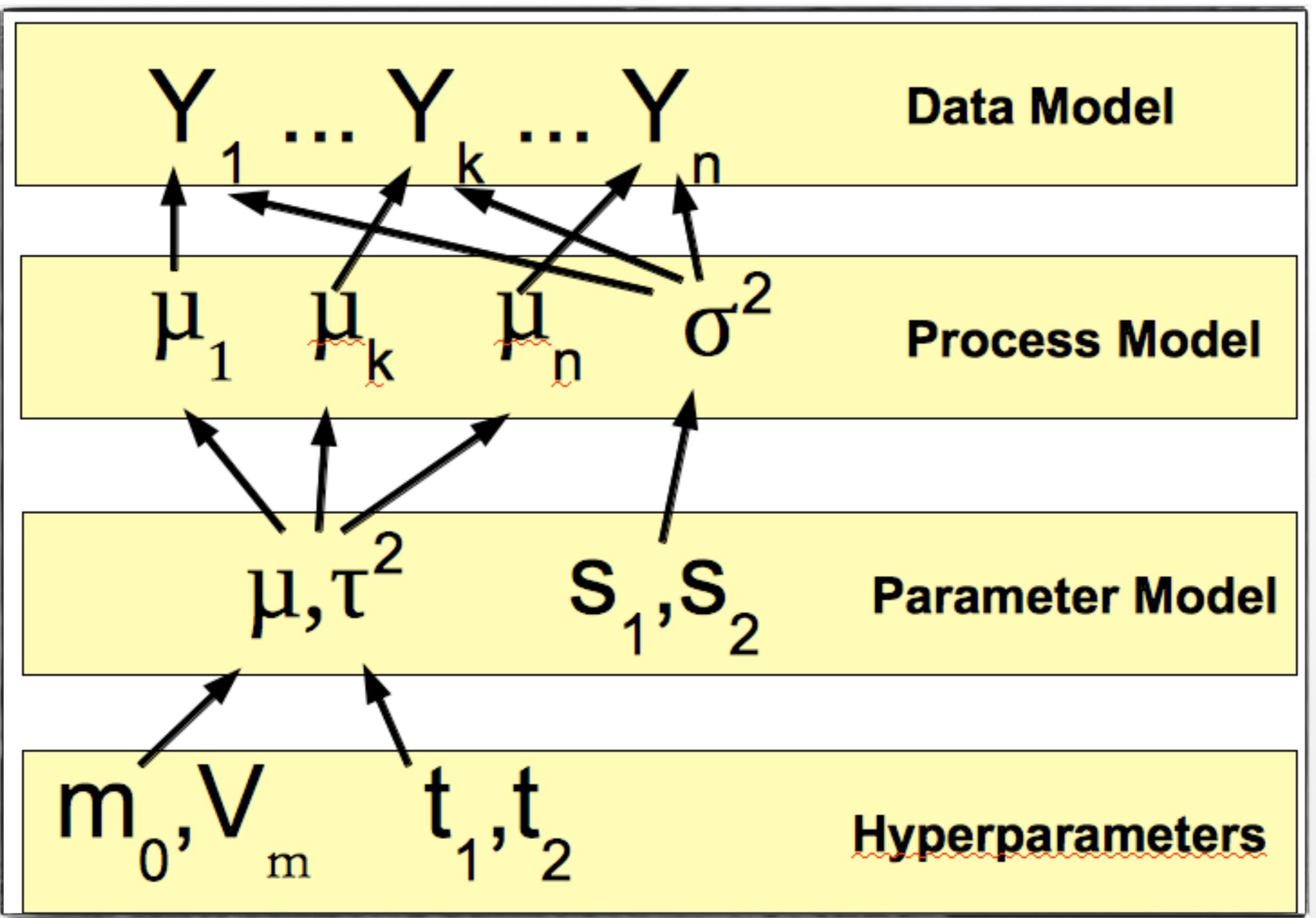
# HIERARCHICAL MODELS

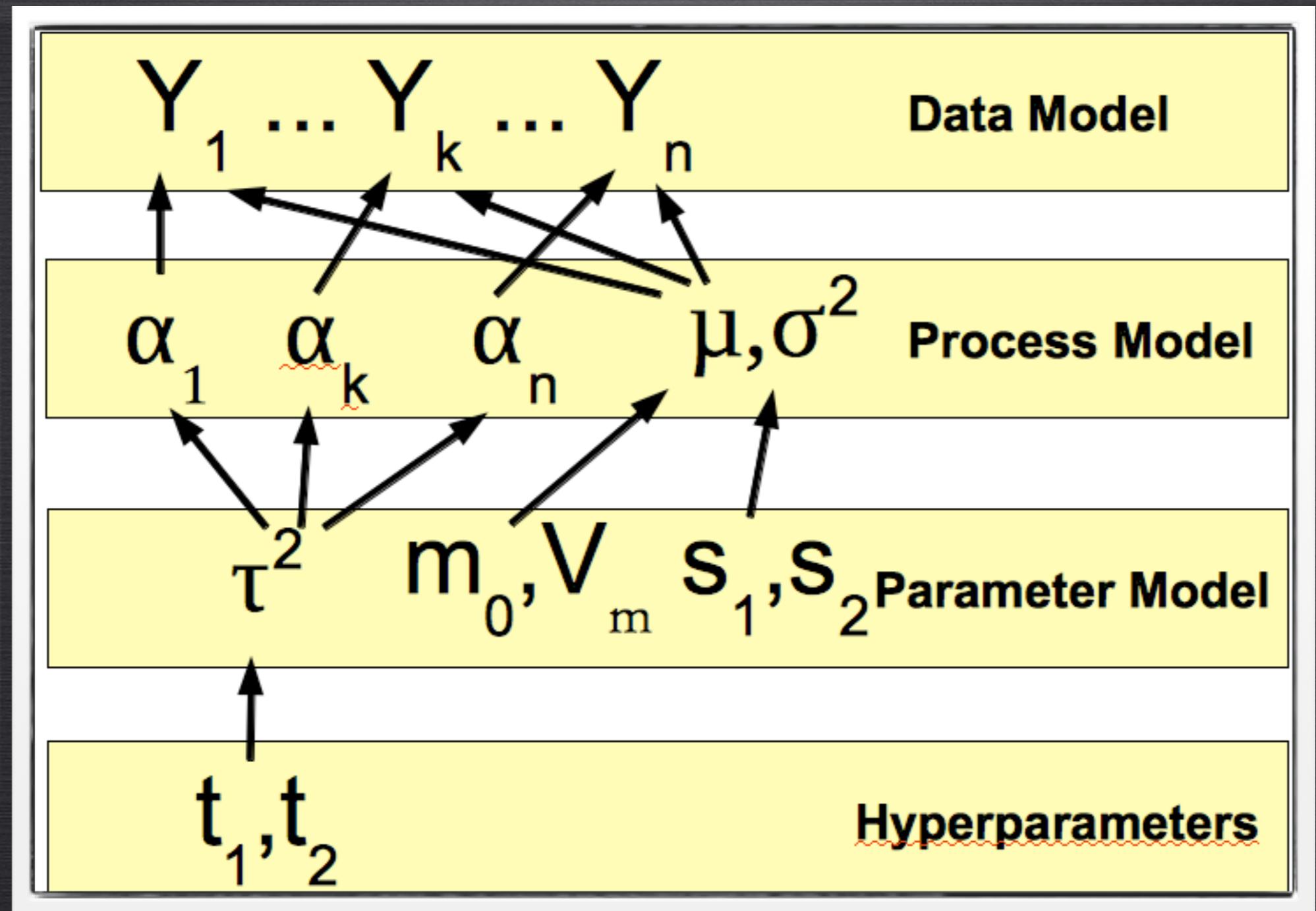


Independent

Hierarchical

Shared



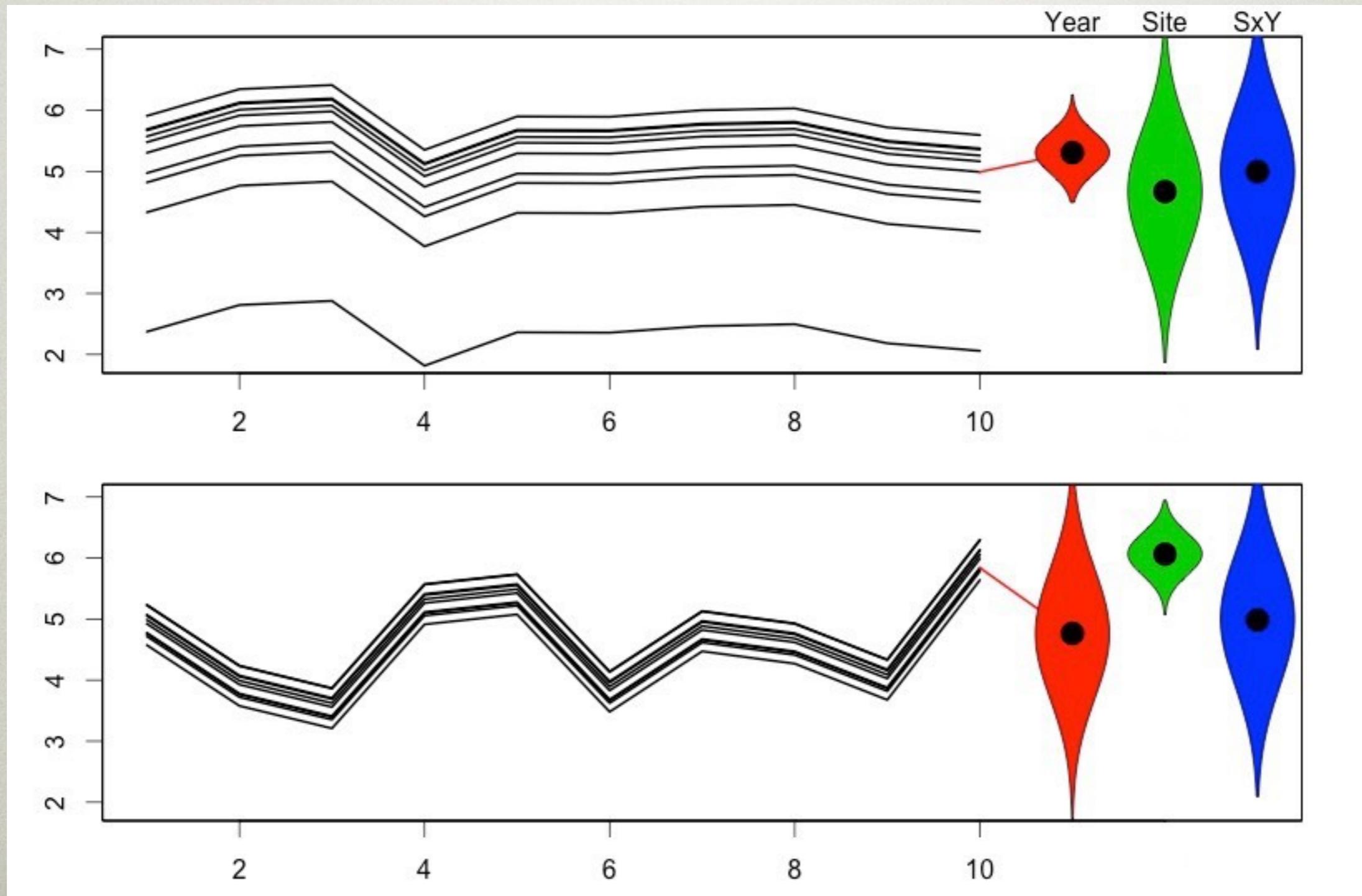


$$Y_k \sim N(\mu_g + \alpha_k, \sigma^2)$$

$$\alpha_k \sim N(0, \tau^2)$$

# IMPACTS ON INFERENCE

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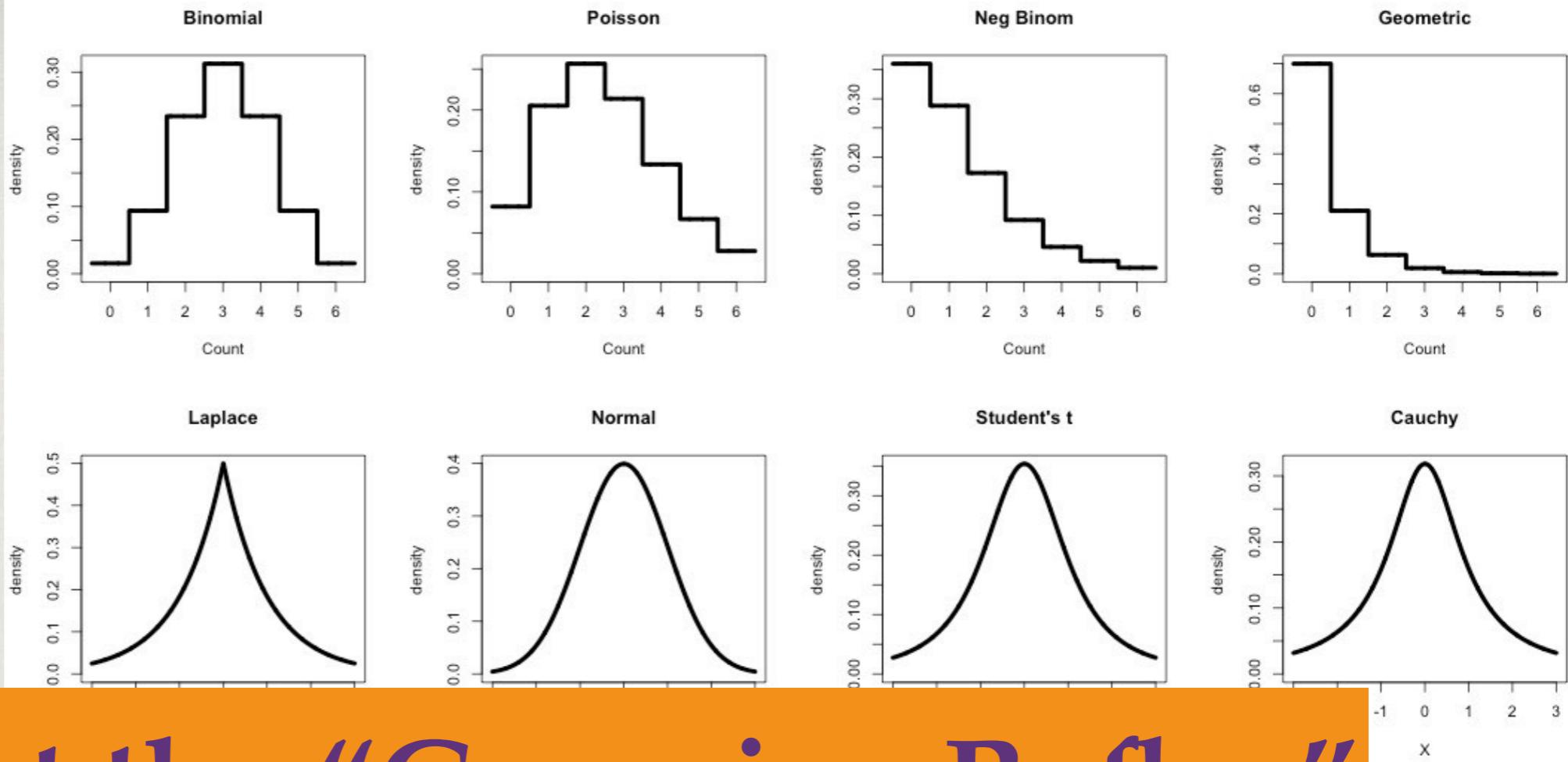


# EXPLAINING UNEXPLAINED VARIANCE

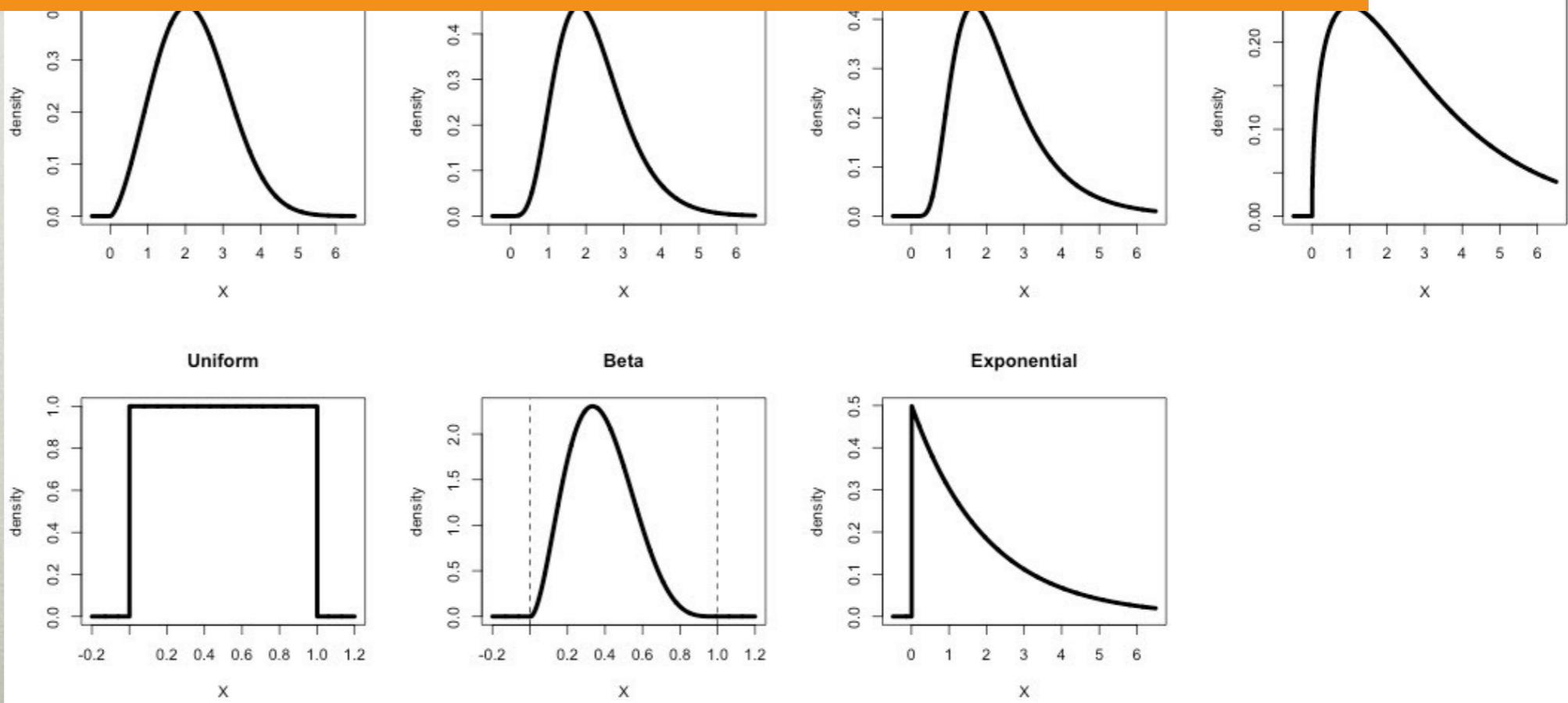
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- Random effects attempt to account for the unexplained variance associated with some group (plot, year, etc.) due to all the things that were not measured
- May point to scales that need additional explanation
- Adding covariates may explain some portion of this variance, but there's always something you didn't measure
- Sometimes additional fixed effects not justified (model selection)

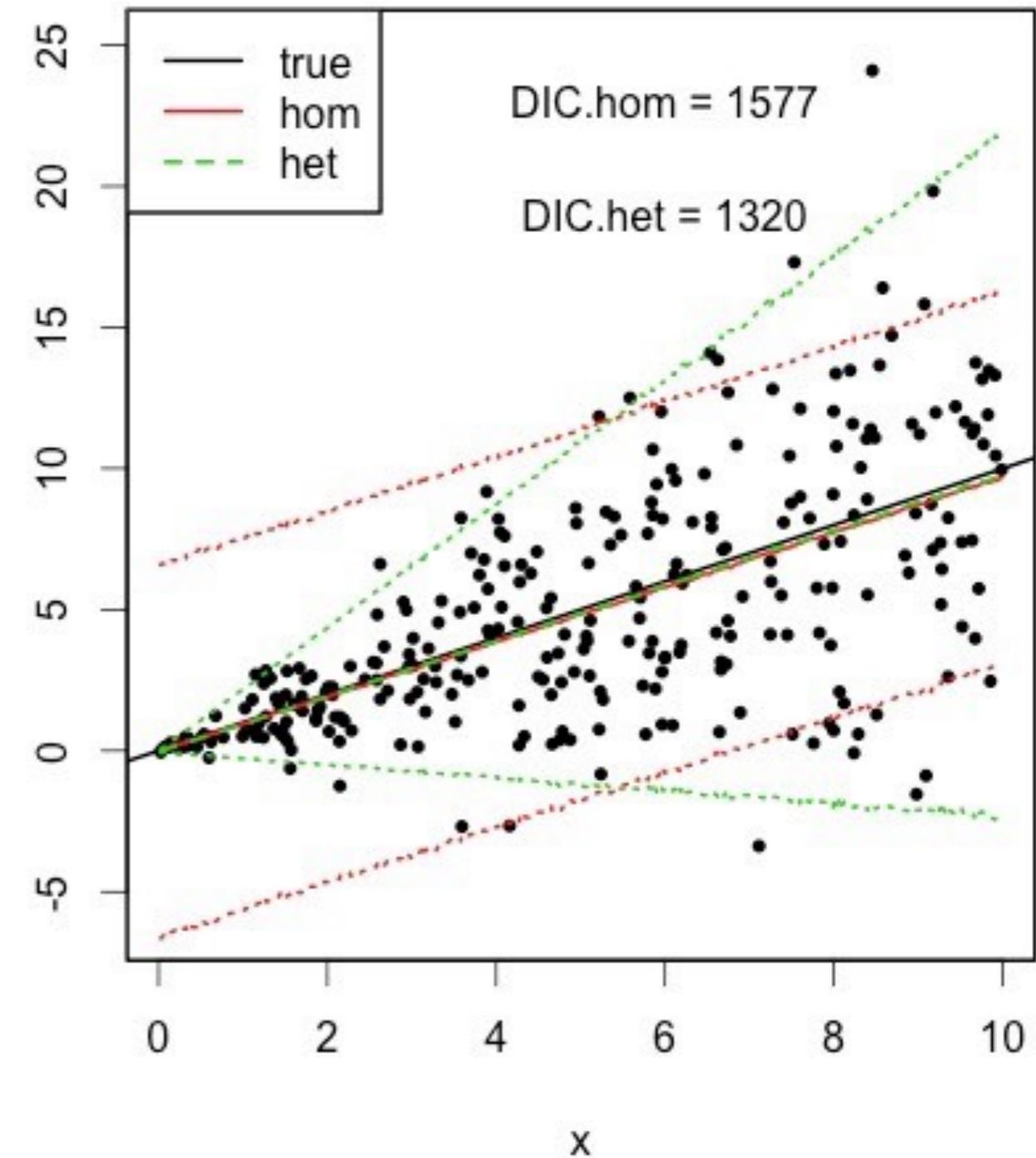
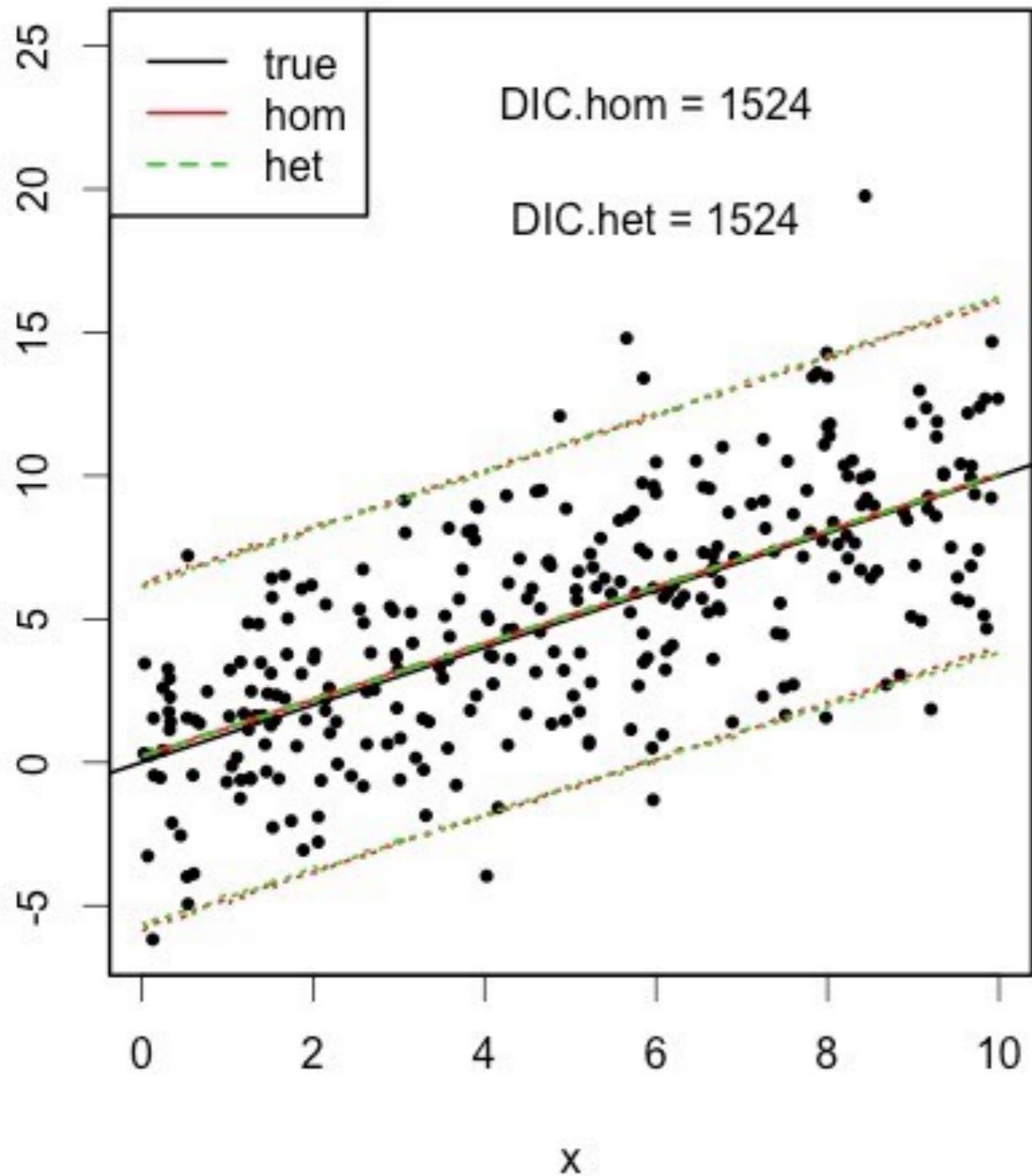
# Choosing a Distribution



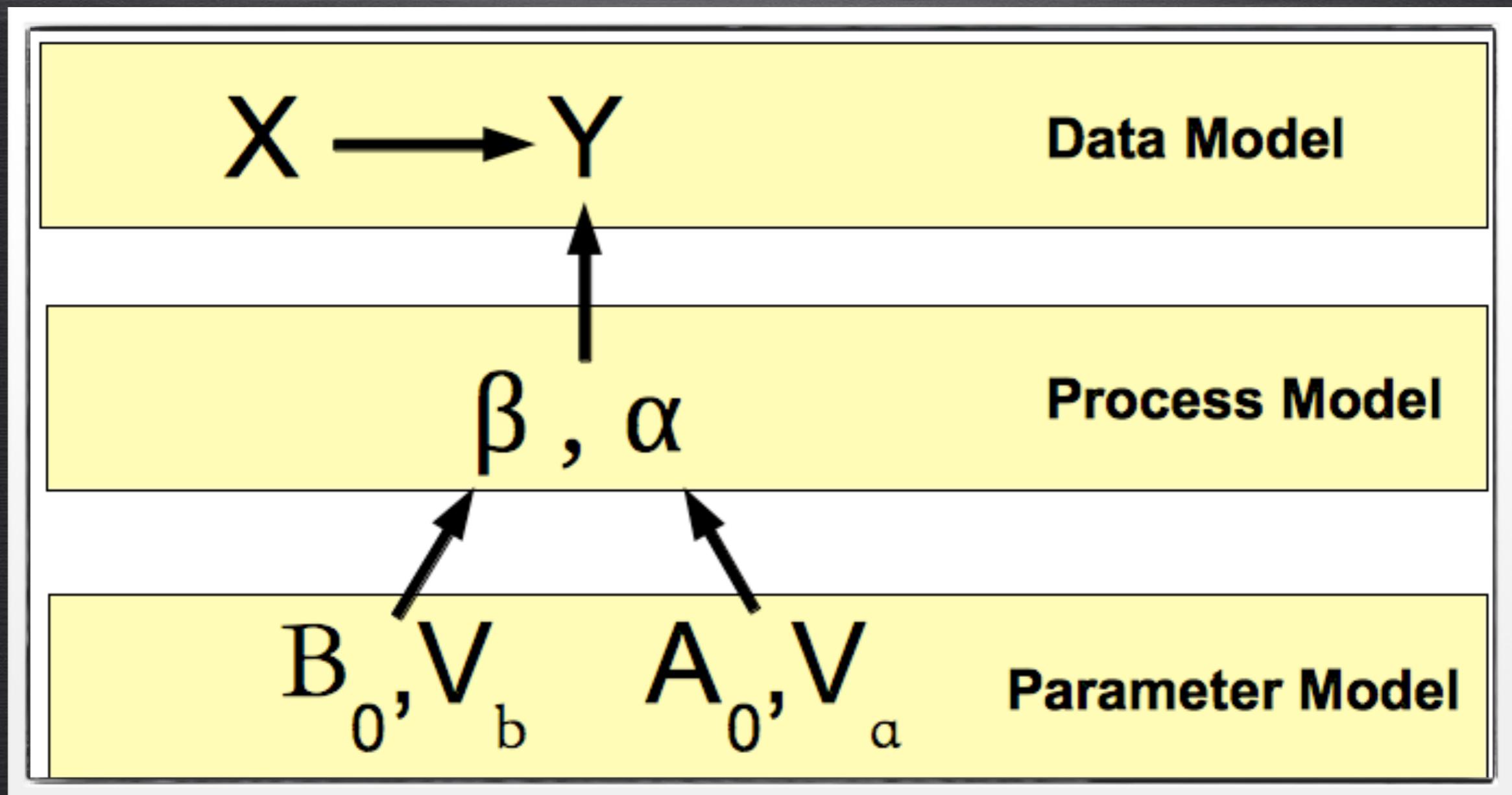
Resist the “Gaussian Reflex”



# HETEROSKEDASTICITY



$$y \sim N(\beta_1 + \beta_2 x, (\alpha_1 + \alpha_2 x)^2)$$



# Example: Linear varying SD

```
model{
 for(i in 1:2) { beta[i] ~ dnorm(0,0.001)} ## priors
 prec ~ gamma(s1,s2)
 for(i in 1:n){
 mu[i] <- beta[1]+beta[2]*x[i]
 y[i] ~ dnorm(mu[i],prec)
 }
}
```



```
model{
 for(i in 1:2) { beta[i] ~ dnorm(0,0.001)} ## priors
 for(i in 1:2) { alpha[i] ~ dlnorm(0,0.001)} ## was prec ~ gamma(a1,a2)
 for(i in 1:n){
 prec[i] <- 1/pow(alpha[1] + alpha[2]*x[i],2)
 mu[i] <- beta[1]+beta[2]*x[i]
 y[i] ~ dnorm(mu[i],prec[i])
 }
}
```