

Ordered Basis :- A basis of a Vector Space V with an ordering of the elements of B is called an ordered basis.

Now we consider finite dimensional Vector Space V.

Let  $B = \{v_1, \dots, v_n\}$  be a basis of a Vector Space V over a field F. We fix an ordering say  $v_1, v_2, \dots, v_n$ .  
 Let  $v = c_1v_1 + \dots + c_nv_n \in V$ . Then  $[v]_B = \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix}$

Example :- We know  $B = \{e_1, e_2, e_3\}$  is a basis of  $\mathbb{R}^3$  over R.

If we choose ordering  $e_1, e_3, e_2$  of elements of B,

then  $v = (2, 3, 5)$  can be written as  $2e_1 + 5e_3 + 3e_2$

$$\text{Thus } [v]_B = \begin{bmatrix} 2 \\ 5 \\ 3 \end{bmatrix}$$

$[v]_B$  is called the coordinate vector of  $v$  with respect to the basis  $B$ .

Change of Basis :-

\*  $\{(1,0), (0,1)\}$  is a basis of  $\mathbb{R}^2$ . Let  $B = \{(1,0), (0,1)\}$

\*  $\{(1,1), (1,-1)\}$  is a basis of  $\mathbb{R}^2$ . Let  $B' = \{(1,1), (1,-1)\}$

Then  $[(\alpha, b)]_B = \begin{bmatrix} a \\ b \end{bmatrix}$  and  $[(\alpha, b)]_{B'} = \begin{bmatrix} \frac{\alpha+b}{2} \\ \frac{\alpha-b}{2} \end{bmatrix}$

Note that,  $[(\alpha, b)]_{B'} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$

$$(1,0) = \frac{1}{2} (1,1) + \frac{1}{2} (1,-1)$$

$$(0,1) = \frac{1}{2} (1,1) - \frac{1}{2} (1,-1)$$

$B = \{v_1, \dots, v_n\}$  and  $B' = \{\omega_1, \dots, \omega_n\}$  be two ordered basis of  $V$ . Let  $v_j = \sum_{i=1}^n p_{ij} \omega_i$

Suppose for  $v \in V$ ,  $[v]_B = (a_1 \ a_2 \ \dots \ a_n)^T$

$$\text{Then } v = \sum_{j=1}^n a_j v_j$$

$$= \sum_{j=1}^n a_j \sum_{i=1}^n p_{ij} \omega_i$$

$$= \sum_{i=1}^n \left( \sum_{j=1}^n p_{ij} a_j \right) \omega_i$$

$$\begin{aligned} v_1 &= p_{11} \omega_1 + p_{12} \omega_2 + \dots + p_{1n} \omega_n \\ v_2 &= p_{21} \omega_1 + p_{22} \omega_2 + \dots + p_{2n} \omega_n \\ &\vdots \quad \vdots \\ v_n &= p_{n1} \omega_1 + p_{n2} \omega_2 + \dots + p_{nn} \omega_n \end{aligned}$$

$$\text{Thus, } [v]_{B'} = \begin{bmatrix} \sum_{j=1}^n p_{1j} a_j \\ \vdots \\ \sum_{j=1}^n p_{nj} a_j \end{bmatrix} = \begin{bmatrix} p_{11} a_1 + p_{12} a_2 + \dots + p_{1n} a_n \\ p_{21} a_1 + p_{22} a_2 + \dots + p_{2n} a_n \\ \vdots \\ p_{n1} a_1 + p_{n2} a_2 + \dots + p_{nn} a_n \end{bmatrix}$$

NOTE:-  $[v]_B = (P_{ij})^{-1} [v]_{B'} = (P_{ij})_{n \times n} [v]_B$

Problem :- Find the coordinate vector of  $\alpha = (1, 3, 1)$  relative to the ordered basis  $B = (\alpha_1, \alpha_2, \alpha_3)$  of  $\mathbb{R}^3$  where  $\alpha_1 = (1, 1, 1)$ ,  $\alpha_2 = (1, 1, 0)$ ,  $\alpha_3 = (1, 0, 0)$ .

Solution : Let us find scalars  $c_1, c_2, c_3$  such that

$$(1, 3, 1) = c_1(1, 1, 1) + c_2(1, 1, 0) + c_3(1, 0, 0)$$

$$\Rightarrow (1, 3, 1) = (c_1 + c_2 + c_3, c_1 + c_2, c_1)$$

$$\text{Then } c_1 + c_2 + c_3 = 1$$

$$c_1 + c_2 = 3$$

$$c_1 = 1$$

$$\Rightarrow c_1 = 1, c_2 = 2 \quad \& \quad c_3 = -2$$

Therefore,  $[\alpha]_B = \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix}$

Problem :- Find the vector  $\alpha$  in  $\mathbb{R}^3$  s.t.  $[\alpha]_B = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix}$   
 $B = \{(1, 1, 1), (1, 1, 0), (1, 0, 0)\}$

Solution :-  $\alpha = 3(1,1,1) + 2(1,1,0) + (1,0,0)$   
 $= (6,5,3)$

Problem :- Let  $\alpha = \{x^2+x+1, x^2+1, x-1\}$  and  $\beta = \{2x^2+3x+1, 2x^2+2x+1, -x^2-2\}$  be two basis of  $P_3 := \{f \in R[x], \deg f < 3\}$ . For a vector  $v \in P_3$  if  $[v]_{\beta} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ , then what is  $[v]_{\alpha}$ ?

Solution :-  $2x^2+3x+1 = 2(x^2+x+1) + 0 \cdot (x^2+1) + (x-1)$   
 $2x^2+2x+1 = (x^2+x+1) + (x^2+1) + (x-1)$   
 $-x^2-2 = - (x^2+x+1) + 0(x^2+1) + (x-1)$

Here  $P = \begin{bmatrix} 2 & 1 & -1 \\ 0 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix}$ . Thus,  $[v]_{\alpha} = P[v]_{\beta}$

NOTE: (i)  $[v]_{\beta} = P^{-1}[v]_{\alpha}$

$$= \begin{bmatrix} 2 & 1 & -1 \\ 0 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

(ii) We need to express old basis element in terms of new basis to get the matrix  $P$ .

Problem :- Find a basis of the solution space of  $AX = 0$  where  $A = \begin{bmatrix} 1 & 2 & 0 & 1 \\ 1 & 2 & 1 & 4 \\ 2 & 4 & 1 & 5 \end{bmatrix}$  and  $X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$ .

Solution :-

$$\xrightarrow{\frac{R_2 - R_1}{R_3 - 2R_1}}$$

$$\begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 1 & 3 \end{bmatrix}$$

$$\xrightarrow{R_3 - R_2}$$

$$\begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Thus the system of linear equations is equivalent to

$$x_1 + 2x_2 + x_4 = 0$$

$$x_3 + 3x_4 = 0$$

Let  $x_2 = a$  and  $x_4 = b$  then  $x_1 = -2a - b$  and  $x_3 = -3b$ .

Therefore,  $(x_1, x_2, x_3, x_4) = (-2a - b, a, -3b, b)$

$$= a(-2, 1, 0, 0) + b(-1, 0, -3, 1)$$

Since  $\{-2, 1, 0, 0\}, \{-1, 0, -3, 1\}\}$  is linearly independent (if it is not a scalar multiplication of other), that set is a basis.

Note that, number of unknown is 4, rank of A is 2  
Thus dim of solution space is  $4-2=2$ .

Theorem:- The dimension of the solution space of  $AX=0$  is  $n-\gamma$ , where  $n$  is the number of unknown and  $\gamma$  is the rank of the matrix A.

Proof:- The solution space of  $AX=0$  is same as the solution space of  $RX=0$  where R is the reduced echelon matrix form of A.  
Since  $\text{rank}(A)=\gamma$ , R has  $\gamma$  non-zero rows and  $R_1, R_2, \dots, R_\gamma$  has leading elements 1. The leading 1 are in the  $k_i$ -th column where  $k_1 < k_2 < \dots < k_\gamma$ .  
we can assume  $\{x_1, x_2, \dots, x_n\} \setminus \{x_{k_1}, \dots, x_{k_\gamma}\}$  as arbitrary elements  $d_1, d_2, \dots, d_{n-\gamma}$ , then each  $x_{k_i}$

Can be expressed in terms of  $d_1, d_2, \dots, d_{n-\sigma}$ .

$$\det(x_1, x_2, x_3, \dots, x_n) = d_1 S_1 + d_2 S_2 + \dots + d_{n-\sigma} S_{n-\sigma}.$$

Then the solution space is  $\text{Span}\{S_1, \dots, S_{n-\sigma}\}$ .

Further,  $\{S_1, \dots, S_{n-\sigma}\}$  is linearly independent.

as  $c_1 S_1 + \dots + c_{n-\sigma} S_{n-\sigma} = (0, \dots, 0)$  implied

$$(c_1, c_2, \dots, c_{n-\sigma}) = (0, 0, \dots, 0)$$

$$\Rightarrow c_1 = c_2 = \dots = c_{n-\sigma} = 0.$$

Thus  $\{S_1, \dots, S_{n-\sigma}\}$  is a basis of the solution space of  $AX=0$ , and hence it has dimension  $n-\sigma$ .

Row Space :- let  $A_{m \times n} \in M_{m \times n}(F)$ , let  $R_1, R_2, \dots, R_m$

be rows of  $A_{m \times n}$ . Then  $R_1, \dots, R_m \in F^n$ .

The vector space span by  $\{R_1, \dots, R_m\}$  is called the row space of  $A$ .

Note that,  $\{R_1, \dots, R_m\}$  may not be linearly independent and it is a subspace of  $F^n$ .  
Therefore the dimension of the row space of  $A$   $\leq \min\{m, n\}$ .

If  $A$  has rank  $r$  and  $R'_1, \dots, R'_r$  are the non-zero rows of the row reduced echelon form of  $A$  then  $\text{Span}\{R_1, \dots, R_m\} = \text{Span}\{R'_1, \dots, R'_r\}$  (as  $R'_i$  is linear combination of  $R_i$  and vice versa)

Also,  $\{R'_1, \dots, R'_r\}$  is linearly independent.

Therefore  $\text{rank}(A) = \text{dimension of the row space of } A$ .