

Q 1

$$\psi_2 : M_3(\mathbb{R}) \rightarrow M_3(\mathbb{R})$$

$$\psi_2(A) = A + \lambda A^t$$

$$\begin{aligned}
 (a) \quad \psi_2(aA + bB) &= (aA + bB) + \lambda(aA + bB)^t \quad \text{for } a, b \in \mathbb{R} \\
 &= aA + bB + \lambda aA + \lambda bB^t \\
 &= a(A + \lambda A^t) + b(B + \lambda B^t) \\
 &= a\psi_2(A) + b\psi_2(B)
 \end{aligned}$$

Hence  $\psi_2$  is a linear transformation.

$$(b) \quad \ker \psi_2 = \{ A \in M_3(\mathbb{R}) : A + \lambda A^t = 0 \}$$

if  $\lambda = 1$ ,  $A \in \ker \psi_2 \Leftrightarrow A = -A^t$  a skew symmetric matrix

if  $\lambda = -1$ ,  $A \in \ker \psi_2 \Leftrightarrow A = A^t$  a symmetric matrix.

Thus when  $\lambda = \pm 1$ ,  $\ker \psi_2 \neq 0$ .

Hence  $\ker \psi_2 = 0$  (i.e.  $\psi_2$  is one to one)  $\Rightarrow \lambda \neq \pm 1$ .

Suppose  $\lambda \neq \pm 1$ , set  $A = \begin{pmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{pmatrix}$  then  $A^t = \begin{pmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{pmatrix}$

$\forall A \in \ker \psi_2$ , then  $\begin{pmatrix} a_1 + \lambda a_1 & b_1 + \lambda a_2 & c_1 + \lambda a_3 \\ a_2 + \lambda b_1 & b_2 + \lambda b_2 & c_2 + \lambda b_3 \\ a_3 + \lambda c_1 & b_3 + \lambda c_2 & c_3 + \lambda c_2 \end{pmatrix} = 0$

Hence  $a_1 = b_2 = c_3 = 0$  as  $1 + \lambda \neq 0$  &  $b_1 = -\lambda a_2$ ,  $c_1 = -\lambda a_3$

$a_2 = -\lambda b_1$ ,  $b_2 = -\lambda b_3$ ,  $a_3 = -\lambda c_1$ ,  $b_3 = -\lambda c_2$ .

So  $a_1 = b_2 = c_3 = 0$ ,  $b_1 = \lambda^2 b_1$ ,  $c_1 = \lambda^2 c_1$ ,  $c_2 = \lambda^2 b_3$  etc.

Hence  $a_1 = b_2 = c_3 = 0$ ,  $b_1 = c_1 = c_2 = \dots = 0$  all zero.

OR  $A + \lambda A^t = 0 \Rightarrow A^t + \lambda A = 0$  so  $A^t = -\lambda A$ . so  $A + \lambda(-\lambda)A = 0 \Rightarrow (\lambda^2 - 1)A = 0 \Rightarrow \lambda^2 A = 0$

(c)  $\text{Null}(\psi_{-1}) = \{A : A - A^t = 0\}$  consists of symmetric matrices

$\text{Range } \psi_1 = \{A + A^t : A \in M_3(\mathbb{R})\}$  ~~subset~~ it is a subset of symmetric matrices in  $M_3(\mathbb{R})$

But if  $B$  is a symmetric matrix  $B = \frac{B+B^t}{2} + \cancel{\frac{B-B^t}{2}} = \frac{B+B^t}{2}$   
 $= \frac{1}{2}B + \left(\frac{1}{2}B\right)^+$

Thus Range  $\psi_1$  consists of symmetric matrices.

Hence Range  $\psi_1 = \text{Null}(\psi_{-1})$

Q. 2

Characteristic polynomial of  $\begin{pmatrix} 0 & 1 & 2 \\ 1 & 1 & 0 \\ 1 & s & t \end{pmatrix}$  is

$$\det \begin{pmatrix} x & -1 & -2 \\ -1 & x-1 & 0 \\ -1 & -3 & x-t \end{pmatrix} = x(x-1)(x-t) + \{-(x-t)\} - 2 \{3 + (x-1)\}$$

$$= x(x^2 - (1+t)x + t) - x + t - 2s + 2 - 2x$$

$$= x^3 - (1+t)x^2 + (t-3)x + t - 2s + 1.$$

which is given to be  $x^3 - 4x - 1$ .

Comparing coefficients  $1+t=0 \Rightarrow t=-1$

$$t-3=-4 \Rightarrow t=-1 \text{ (same)}$$

$$t-2s+2=-1 \Rightarrow -1-2s=-3$$

$$\Rightarrow 2s=+2$$

$$\Rightarrow s=+1$$

$$(t, s) = (-1, 1)$$



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$$3.(a) \quad \mathcal{L}(f*g) = \mathcal{L}(f) \cdot \mathcal{L}(g)$$

$$f*g(t) = \int_0^t f(\tau) g(t-\tau) d\tau$$

$$\mathcal{L}(f*g)(s) = \int_{t=0}^{\infty} \int_{\tau=0}^t f(\tau) g(t-\tau) d\tau e^{-st} dt$$

$$= \int_{\tau=0}^{\infty} \int_{t=\tau}^{\infty} f(\tau) g(t-\tau) e^{-st} dt d\tau$$

$$= \int_0^{\infty} f(\tau) e^{-s\tau} G(s) d\tau$$

$$= F(s) G(s) \mathcal{L}(f)(s) \mathcal{L}(g)(s).$$

$$(b) \quad y(t) = 1 - \cosh t - \int_0^t e^{\tau} y(t-\tau) d\tau$$

$$\text{let } g(t) = e^t. \text{ Then } y(t) = 1 - \cosh t - y * g(t)$$

$$\text{Taking Laplace transform, } Y(s) = \frac{1}{s} - \frac{s}{s^2-1} - \frac{Y(s)}{s-1}$$

$$\left[1 + \frac{1}{s-1}\right] Y(s) = \frac{1}{s} - \frac{s}{s^2-1}$$

$$Y(s) = \frac{s-1}{s^2} - \frac{1}{s+1}$$

$$Y(s) = \frac{1}{s} - \frac{1}{s^2} - \left[\frac{1}{s+1}\right]. \quad Y(t) = 1 - t - \frac{t}{s+1}$$

4. (a)  $F(s) = \int_0^\infty e^{-st} f(t) dt$

$$\therefore F'(s) = \int_0^\infty (-t e^{-st}) f(t) dt$$

$$= \int_0^\infty e^{-st} \{-t f(t)\} dt$$

$$= \mathcal{L}\{-tf(t)\}$$

$$\Rightarrow \mathcal{L}\{tf(t)\} = -F'(s)$$

(b)  $F(s) = \tan^{-1}\left(\frac{3}{s}\right)$

$$\Rightarrow F'(s) = \frac{1}{1+\left(\frac{3}{s}\right)^2} \cdot \left(-\frac{3}{s^2}\right) = \frac{-3}{s^2+3^2}$$

$$\Rightarrow \mathcal{L}\{-F'(s)\} = \mathcal{L}\left\{\frac{3}{s^2+3^2}\right\} = \sin(3t)$$

$$\Rightarrow tf(t) = \sin(3t)$$

$$\Rightarrow \boxed{f(t) = \frac{\sin(3t)}{t}}$$



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5.

$$y'' + 2y' + 2y = 4e^{-x} \sec^3 x$$

Char. eqn. for homog. part :  $\lambda^2 + 2\lambda + 2 = 0 \Rightarrow \lambda = -1 \pm i$

$$y_h = c_1 e^{-x} \cos x + c_2 e^{-x} \sin x$$

[1 mark]

$$y_1 = e^{-x} \cos x, y_2 = e^{-x} \sin x$$

$$W(y_1, y_2) = y_1 y_2' - y_2 y_1'$$

$$= e^{-2x} (\cos x \cdot \sin x - \sin x \cdot (-\sin x - \cos x))$$

$$= e^{-2x}$$

[1 mark]

$$y_p = u_1 y_1 + u_2 y_2$$

$$\text{where } u_1 = - \int \frac{y_2 r(x)}{W(y_1, y_2)} dx$$

$$= - \int \frac{e^{-x} \sin x \cdot 4e^{-x} \sec^3 x}{e^{-2x}} dx$$

[1]

$$= - \int 4 \tan x \sec^2 x dx = - 2 \tan^2 x$$

$$\text{and } u_2 = \int \frac{y_1 r(x)}{W(y_1, y_2)} dx = \int \frac{e^{-x} \cos x \cdot 4e^{-x} \sec^3 x}{e^{-2x}} dx$$

$$= 4 \int \sec^2 x dx = 4 \tan x \quad [1]$$

$$\therefore y_p = (-2 \tan^2 x) e^{-x} \cos x + (4 \tan x) e^{-x} \sin x$$

General soln. 
$$y = c_1 e^{-x} \cos x + c_2 e^{-x} \sin x + y_p$$

$$6. (1-x^2)y'' - 2xy' + 2y = 2-x \quad y(0)=0, y'(0)=1$$

(Remark)  $y(x) = \sum_{n=0}^{\infty} a_n x^n \iff \begin{cases} y(0) = a_0 = 0 \\ y'(0) = a_1 = 1 \end{cases}$

$$x y'(x) = \sum_{n=0}^{\infty} n a_n x^n$$

$$x^2 y'' = \sum_{n=0}^{\infty} (n+1)(n+2) a_{n+2} x^n$$

$$x^2 y'' = \sum_{n=0}^{\infty} (n+1)n a_n x^n$$

(Remark)  $\sum_{n=0}^{\infty} [(n+1)(n+2)a_{n+2} - (n+1)n a_n - 2na_n + 2a_n] x^n = 2-x$

For  $n=0: 2a_2 + 2a_0 = 2$

$$a_2 = 1$$

(Remark)  $n=1: 6a_3 = -1$

$$a_3 = -\frac{1}{6}$$

For  $n \geq 2$

$$a_{n+2} = \frac{n-1}{n+1} a_n$$

$$a_4 = \frac{1}{3} a_2 = \frac{1}{3}.$$

$$a_5 = \frac{2}{4} a_3 = \frac{-1}{2 \cdot 6}$$

$$a_6 = \frac{3}{5} \cdot \frac{1}{3} = \frac{1}{5}.$$

$$a_7 = -\frac{4}{6} \cdot \frac{1}{2 \cdot 6} = -\frac{1}{3 \cdot 6}.$$

Assume  $a_{2n} = \frac{1}{2n-1}$

Assume  $a_{2n+1} = \frac{-1}{6 \cdot n}$

then

$$a_{2(n+1)} = \frac{a_{2n+2}}{2n+1} = \frac{2n-1}{2n+1} \cdot a_{2n} = \frac{1}{2(n+1)-1}$$

Then  $a_{2n+3} = -\frac{a_{2n+2}}{2n+2} = -\frac{2n}{2n+2} \cdot \frac{1}{6 \cdot n}$

thus induction

$$a_{2n} = \frac{1}{2n-1} \quad n \geq 2$$

$$= -\frac{1}{6(n+1)}$$

i. 
$$y = x + \sum_{n=1}^{\infty} \frac{1}{2n-1} x^{2n} - \sum_{n=1}^{\infty} \frac{1}{6n} x^{2n+1}$$

$$7. \quad y'' + 5y' + 6y = \delta(t - \frac{\pi}{2}) + u(t - \pi) ; \quad y(0) = 0, \quad y'(0) = 1$$

$$\mathcal{L}(y') = sY - y(0) = sY$$

$$\mathcal{L}(y'') = s^2 Y - s y(0) - y'(0) = s^2 Y - 1$$

$$\mathcal{L}\left\{\delta(t - \frac{\pi}{2})\right\} = e^{-\frac{\pi}{2}s}$$

$$\mathcal{L}\{u(t - \pi)\} = \frac{e^{-\pi s}}{s}$$

i. Taking Laplace transform, we get

$$s^2 Y - 1 + 5sY + 6Y = \frac{e^{-\frac{\pi}{2}s}}{s} + \frac{e^{-\pi s}}{s}$$

$$\Rightarrow (s^2 + 5s + 6)Y = 1 + \frac{e^{-\frac{\pi}{2}s}}{s} + \frac{e^{-\pi s}}{s}$$

$$\Rightarrow Y = \frac{1}{(s+2)(s+3)} \left[ 1 + \frac{e^{-\frac{\pi}{2}s}}{s} + \frac{e^{-\pi s}}{s} \right]$$

$$= \left( \frac{1}{s+2} - \frac{1}{s+3} \right) + e^{-\frac{\pi}{2}s} \left( \frac{1}{s+2} - \frac{1}{s+3} \right) + e^{-\pi s} \cdot \frac{1}{s(s+2)(s+3)}$$

$$\frac{1}{s(s+2)(s+3)} = \frac{1}{s} + \frac{-1}{s+2} + \frac{1}{s+3}$$

$$\mathcal{L}^{-1}\left(\frac{1}{s+2} - \frac{1}{s+3}\right) = \frac{-e^{-2t}}{e} - \frac{-e^{-3t}}{e}$$

$$\mathcal{L}^{-1}\left\{e^{-\frac{\pi}{2}s} \left( \frac{1}{s+2} - \frac{1}{s+3} \right)\right\} = e^{-2(t - \frac{\pi}{2})} u(t - \frac{\pi}{2}) - e^{-3(t - \frac{\pi}{2})} u(t - \frac{\pi}{2})$$

$$\mathcal{L}^{-1}\left\{\frac{e^{-\pi s}}{s(s+2)(s+3)}\right\} = \left[ \frac{1}{6} - \frac{1}{2} e^{-2(t - \pi)} + \frac{1}{3} e^{-3(t - \pi)} \right] u(t - \pi)$$

So,

$$\boxed{y(t) = \left( \frac{-e^{-2t}}{e} - \frac{-e^{-3t}}{e} \right) + \left[ \frac{-e^{-2(t - \frac{\pi}{2})}}{e} - \frac{-e^{-3(t - \frac{\pi}{2})}}{e} \right] u(t - \frac{\pi}{2}) + \left[ \frac{1}{6} - \frac{1}{2} e^{-2(t - \pi)} + \frac{1}{3} e^{-3(t - \pi)} \right] u(t - \pi)}$$

8.  $y' = Ay + \vec{g}(t)$ , where  $A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$ ,  $\vec{g}(t) = \begin{pmatrix} 0 \\ \sec t \end{pmatrix}$

Eigen values of  $A$  are  $\pm i$  with eigen vector

$$\begin{pmatrix} 1 \\ \pm i \end{pmatrix}.$$

$$e^{it} \begin{pmatrix} 1 \\ i \end{pmatrix} = \begin{pmatrix} \cos t + i \sin t \\ -\sin t + i \cos t \end{pmatrix} = \begin{pmatrix} \cos t \\ -\sin t \end{pmatrix} + i \begin{pmatrix} \sin t \\ \cos t \end{pmatrix}$$

i. Soln. of homog.  $\vec{y}_h = c_1 \begin{pmatrix} \cos t \\ -\sin t \end{pmatrix} + c_2 \begin{pmatrix} \sin t \\ \cos t \end{pmatrix}$

Fund. matrix  $\tilde{Y} = \begin{pmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{pmatrix}$

$$\tilde{Y}^{-1} = \begin{pmatrix} \cos t & -\sin t \\ \sin t & \cos t \end{pmatrix}$$

$$\vec{y}_p = \tilde{Y} \vec{u}, \text{ where } \vec{u}' = \tilde{Y}^{-1} \vec{g}(t)$$

$$\begin{aligned} \vec{u}' &= \begin{pmatrix} \cos t & -\sin t \\ \sin t & \cos t \end{pmatrix} \begin{pmatrix} 0 \\ \sec t \end{pmatrix} \\ &= \begin{pmatrix} -\tan t \\ 1 \end{pmatrix} \end{aligned}$$

$$\Rightarrow u_1 = - \int \tan t dt = \ln |\sec t|$$

$$u_2 = t$$

$$\therefore y_p = u_1 \vec{y}_1 + u_2 \vec{y}_2 = \ln |\sec t| \begin{pmatrix} \cos t \\ -\sin t \end{pmatrix} + t \begin{pmatrix} \sin t \\ \cos t \end{pmatrix}$$

$$\therefore \underbrace{\begin{pmatrix} y_1 \\ y_2 \end{pmatrix}}_{=} = (c_1 + \ln |\sec t|) \begin{pmatrix} \cos t \\ -\sin t \end{pmatrix} + (c_2 + t) \begin{pmatrix} \sin t \\ \cos t \end{pmatrix}$$

$$9. \quad y' = \frac{xy}{1-x^2-y^2} \quad y(0) = \alpha \quad \rightarrow \textcircled{1}$$

$$\text{Let } f(x,y) = \frac{xy}{1-x^2-y^2}$$

The  $f$  is cts on  $\mathbb{R}^2$  except the pts  $(x,y)$  such that  $x^2+y^2=1$

In particular,  $f$  is not cts at the pts  $(0, y(0)) = (0, \alpha)$  with  $\alpha^2 = 1$ .

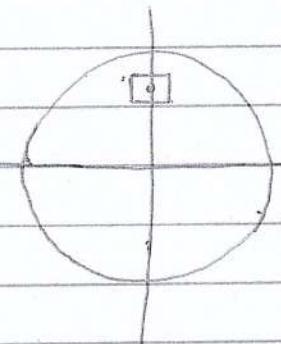
Hence we can't use existence and uniqueness theorem if  $\alpha^2 = 1$ .

Assume  $\alpha^2 \neq 1$ . Then

If  $|x| < 1$ , we can choose

a small rectangle

$$R = f(x,y) : \left. \begin{array}{l} |x| < \frac{|1-\alpha^2|}{4} \\ |y-\alpha| < \frac{|1-\alpha^2|}{4} \end{array} \right\}$$



such that  $f$  is cts on  $R$ .

It means that either  $R$  is contained in  $\{(x,y) : x^2+y^2 > 1\}$  if  $|\alpha| < 1$  or  $R \subset \{(x,y) : x^2+y^2 < 1\}$  if  $|\alpha| > 1$ .

In both cases,  $f_y = \frac{x(1-x^2-y^2)+2xy^2}{(1-x^2-y^2)^2}$  is

cts on  $R$ .

Summary: If  $\alpha^2 \neq 1$ ,  $\exists R$ -rectangle s.t.  $(0, \alpha) \in R$

(1)  $f$  is cts on  $R$ .

(2)  $f_y$  is cts on  $R$ .

then by existence & uniqueness,

$\textcircled{1}$  has a unique solution.