

Basis of a vector space - lecture-8

Recall \Rightarrow let $S = \{u_1, u_2, \dots, u_n\} \subseteq V(\mathbb{F})$ be a finite set. Then is L.I $\Leftrightarrow \alpha_1 u_1 + \alpha_2 u_2 + \dots + \alpha_n u_n = 0$ has $\alpha_1 = \alpha_2 = \dots = \alpha_n = 0$

Basis of a vector space \Rightarrow A subset $B \subseteq V(\mathbb{F})$ is said to be a basis of $V(\mathbb{F})$ if B is a linearly independent set and $L(B) = V(\mathbb{F})$.

For every element $u \in V(\mathbb{F})$, there exists $u_1, \dots, u_m \in B$ and scalars $\alpha_1, \dots, \alpha_m \in \mathbb{F}$ such that $u = \alpha_1 u_1 + \dots + \alpha_m u_m$.

Example $\rightarrow V = \mathbb{R}^n(\mathbb{R})$.
 If we consider $\mathcal{B} = \{l_i : 1 \leq i \leq 3\}$, where $l_i \in \mathbb{R}^n$
 such that $l_i = (0, 0, \dots, 1, 0 \dots 0)$
 + i^{th} position

Suppose we have

$$\alpha_1 l_1 + \alpha_2 l_2 + \dots + \alpha_n l_n = 0 \quad \alpha_i \in \mathbb{F} \forall i$$

$$\Rightarrow \alpha_1(1, 0, \dots, 0) + \alpha_2(0, 1, 0 \dots 0) + \dots + \alpha_n(0, \dots, 1) = 0$$

$$\Rightarrow (\alpha_1, \alpha_2, \dots, \alpha_n) = 0 \text{ in } \mathbb{R}^n$$

$$\Rightarrow \alpha_i = 0 \quad \forall 1 \leq i \leq n$$

Further, if we take $u = (x_1, x_2, \dots, x_n) \in \mathbb{R}^n$

$$u = \alpha_1 l_1 + \alpha_2 l_2 + \dots + \alpha_n l_n \in L(\mathcal{B})$$

$\Rightarrow L(\mathcal{B}) = V(\mathbb{F})$. Hence \mathcal{B} is a basis of V .

Exercise \rightarrow Take $V = C^n(\mathbb{C})$. Prove that $\mathcal{B} = \{l_i\}_{i=1}^n$ is a basis set for V .

Exercise \rightarrow Take $V = C^n(\mathbb{R})$. Is $\mathcal{B} = \{l_i\}_{i=1}^n$ a basis of $C^n(\mathbb{R})$? If not, find a basis set for $C^n(\mathbb{R})$ consisting \mathcal{B} .

Hint \rightarrow take $(z_1, z_2, \dots, z_n) \in \mathbb{C}^n$

write $z_i = x_i + iy_i$ $x_i, y_i \in \mathbb{R}$.

$$\begin{aligned}(z_1, z_2, \dots, z_n) &= (x_1 + iy_1, x_2 + iy_2, \dots, x_n + iy_n) \\&= (x_1, x_2, \dots, x_n) + i(y_1, y_2, \dots, y_n) \\&= x_1\mathbf{e}_1 + x_2\mathbf{e}_2 + \dots + x_n\mathbf{e}_n + i(y_1\mathbf{e}_1 + \dots + y_n\mathbf{e}_n)\end{aligned}$$

Add

$$\bar{\mathbf{e}}_1 = (1, 0, \dots, 0), \quad (0, 1, 0, \dots, 0) \quad \dots \quad \bar{\mathbf{e}}_n = (0, 0, \dots, 1)$$

$$(z_1, \dots, z_n) = x_1\mathbf{e}_1 + \dots + x_n\mathbf{e}_n + y_1\bar{\mathbf{e}}_1 + \dots + y_n\bar{\mathbf{e}}_n$$

$\mathcal{B} = \{\mathbf{e}_1, \dots, \mathbf{e}_n, \bar{\mathbf{e}}_1, \dots, \bar{\mathbf{e}}_n\}$ is a spanning set.

Example ③ $V = P_n(\mathbb{R}) = \{ f(x) \in \mathbb{R}[x] \mid \deg(f(x)) \leq n \}$

If we take $\mathcal{B} = \{1, x, x^2, \dots, x^n\}$. Then it is easy to observe that $L(\mathcal{B}) = P_n(\mathbb{R})$

Consider $\alpha_0, \alpha_1, \alpha_2, \dots, \alpha_n \in \mathbb{R}$ st

$$\alpha_0 + \alpha_1 x + \dots + \alpha_n x^n = 0 \text{ in } P_n(\mathbb{R})$$

$$\alpha_1 \stackrel{\text{if}}{=} \neq 0$$

Remark \rightarrow We can have more than one basis set.

$\mathcal{B}_1 = \{(1,0), (0,1)\}$ & $\mathcal{B}_2 = \{(1,0), (2,3)\}$. Both are basis of \mathbb{R}^2 .

Theorem \Rightarrow B is a basis of $V(F) \Leftrightarrow B$ is a maximal linearly independent subset in V .

Proof \Rightarrow Let B be a basis of $V(F)$ and let $u \in V - B$. Since B is a basis, this implies that $\exists u_1, u_2, \dots, u_n \in B$ and scalar $\alpha_1, \alpha_2, \dots, \alpha_n \in F$ s.t $u = \alpha_1 u_1 + \alpha_2 u_2 + \dots + \alpha_n u_n$

$$1 \cdot u - \alpha_1 u_1 - \alpha_2 u_2 - \dots - \alpha_n u_n = 0$$

$\Rightarrow B \cup \{u\}$ is a L.D. set.

$\Rightarrow B$ is a maximal linearly independent set.

\Leftarrow Suppose \mathcal{B} is a maximal linearly independent set.
Then \mathcal{B} is L.I. and we need show that $L(\mathcal{B}) = V$.

let $u \in V \setminus \mathcal{B}$. Then $\mathcal{B} \cup \{u\}$ is a L.D. set.

$\Rightarrow \exists u_1, u_2, \dots, u_m \in \mathcal{B}$ and scalars $\alpha_0, \alpha_1, \dots, \alpha_m \in F$ such that
 $\alpha_0 u + \alpha_1 u_1 + \dots + \alpha_m u_m = 0$ (and $\alpha_0 \neq 0$)

$$u = -\frac{1}{\alpha_0} (\alpha_1 u_1 + \dots + \alpha_m u_m) \in L(\mathcal{B})$$

$\Rightarrow L(\mathcal{B}) = V$. Hence \mathcal{B} is a basis of $V(F)$.

Theorem \rightarrow If $B = \{u_1, u_2, \dots, u_n\}$ is a basis of $V(F)$. Then every $v \in V$ is a unique linear combination of vectors in B .

Proof \rightarrow Suppose $v = \alpha_1 u_1 + \alpha_2 u_2 + \dots + \alpha_n u_n$ $\alpha_i \in F$

$$v = \beta_1 u_1 + \beta_2 u_2 + \dots + \beta_n u_n \quad \beta_i \in F.$$

Also

$$\alpha_1 u_1 + \dots + \alpha_n u_n = \beta_1 u_1 + \dots + \beta_n u_n$$

$$(\alpha_1 - \beta_1) u_1 + \dots + (\alpha_n - \beta_n) u_n = 0$$

$$\Rightarrow \alpha_i - \beta_i = 0 \quad \forall 1 \leq i \leq n \quad (\text{as } B \text{ is a basis})$$

$$\Rightarrow \alpha_i = \beta_i \quad \forall 1 \leq i \leq n$$

Theorem \rightarrow Every vector space has a basis.

Proof \rightarrow We will consider this statement without proof.

Lemma \rightarrow Let $V(F)$ be a vector space. Then any finite L.I set in V is a part of a basis of $V(F)$.

Proof \rightarrow Let B be a basis of $V(F)$ and let S be a linearly independent subset given by

$$S = \{v_1, v_2, \dots, v_k\}.$$

We know that

$$v_i = \alpha_1 u_1 + \alpha_2 u_2 + \dots + \alpha_n u_n$$

$$\begin{array}{l} \alpha_i \in F \\ u_i \in B. \end{array}$$

(at least one α_i will be nonzero w.l.o.g $\alpha_1 \neq 0$)

$$\frac{1}{\alpha_1} v_1 = u_1 + \frac{1}{\alpha_1} (\alpha_2 u_2 + \dots + \alpha_n u_n)$$

$$\Rightarrow u_1 = \frac{1}{\alpha_1} (v_1 - \alpha_2 u_2 - \dots - \alpha_n u_n)$$

If we take $B_1 = S - \{u_1\} \cup \{v_1\}$

It is easy to observe that

Exercise

① $L(B_1) = L(S)$

② B_1 is L.I.

In second step write

$$v_2 = \alpha_1 u_1' + \dots + \alpha_n u_n' + \alpha_0 v_1$$

Observe that all α_i is non zero and not identically zero
Because if so, then $v_2 = \alpha v_1$

$$\Rightarrow v_2 - \alpha v_1 = 0 \quad (\text{But } v_1, v_2 \text{ are L.I})$$

Hence $\exists i$ b/w 1 to n such that $\alpha_i \neq 0$, taking

$$\alpha_1 \neq 0$$

$$\frac{1}{\alpha_1} v_2 = u'_1 + \frac{1}{\alpha_1} (- \dots \dots)$$

Replace u'_1 by v_2 . Keep doing it upto kth step.

Finally will be the part of a basis set.

Theorem \Rightarrow Let $V(\mathbb{F})$ be a vector space with finite basis set B , having n elements. Then any subset $S \subseteq V(\mathbb{F})$ having more than n elements is linearly dependent.

Proof \Rightarrow Let $B = \{u_1, u_2, \dots, u_n\}$ be a basis and $SSV(\mathbb{F})$

with $S = \{v_1, v_2, \dots, v_m\}$, where $m > n$.

$$v_1 = \alpha_{11} u_1 + \alpha_{21} u_2 + \dots + \alpha_{n1} u_n$$

\vdots

$$v_m = \alpha_{1m} u_1 + \alpha_{2m} u_2 + \dots + \alpha_{nm} u_n$$

We need to prove that $\exists \beta_1, \beta_2, \dots, \beta_m \in \mathbb{F}$ such that

$$\beta_1 v_1 + \beta_2 v_2 + \dots + \beta_m v_m = 0 \quad (\text{at least one } \beta_i \text{ is nonzero})$$

↑ b

$$\beta_1 \left(\sum_{j=1}^n \alpha_{ji} u_j \right) + \dots + \beta_m \left(\sum_{j=1}^n \alpha_{jm} u_j \right) = 0$$

$$\left(\sum_{i=1}^m \alpha_{1i} \beta_i \right) u_1 + \dots + \left(\sum_{i=1}^m \alpha_{ni} \beta_i \right) u_n = 0$$

↑ b

$$\sum_{i=1}^m \alpha_{1i} \beta_i = \dots = \sum_{i=1}^m \alpha_{ni} \beta_i = 0 \quad (\because B \text{ is a basis})$$

$\Rightarrow (\beta_1, \beta_2, \dots, \beta_m) \in F^n$ is a solⁿ of the homogeneous system of eqⁿ $AX=0$ where $A = (a_{ij})_{n \times m}$ (n eqⁿ and m unknowns with $m > n$)

Hence this system must have a non trivial solⁿ

$\Rightarrow \exists (\beta_1, \dots, \beta_m) \in F^n - \{0, \dots, 0\}$ s.t

$$\beta_1 v_1 + \dots + \beta_m v_m = 0$$

$\Rightarrow S \text{ is L.D.}$

Corollary \rightarrow Let $V(F)$ be a finite dim vector space and let $B_1 = \{u_1, \dots, u_n\}$ and $B_2 = \{v_1, \dots, v_m\}$ be two basis of V . Then $n = |B_1| = |B_2| = m$.

Proof \div If B_1 is a basis, then we have $m \leq n = |B_1|$ — eqⁿ(1)

If B_2 is a basis, then $n \leq m = |B_2|$ — eqⁿ(2)

$$\Rightarrow n = m.$$

Dimension of a vector space \Rightarrow let $V(F)$ be a $f.d$ vector space. Then the dim of $V(F)$, denoted by $\dim_F(V)$, is the number of elements in a basis.

If V has no finite basis, we say it is infinite dimensional.