

Multi-Agent Learning in a Pricing Game

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Overview (everything is work in progress)

Aim: exploring larger games with machine learning

Example: duopoly with demand inertia.

- description of the **duopoly game**
- **new framework:**
 - learning a strategy in the **base game**
 - new strategy added to a **population game**
 - compute a new equilibrium of the population game as the next learning environment
- main advantage: **modularity**, study aspects separately.

Duopoly with demand inertia

Model:

- a multi-stage **pricing game** = our **base game**
- analysed theoretically (**subgame perfect** equilibrium)

[R. Selten (1965), Game-theoretic analysis of an oligopolic model with buyers' inertia. [German] *Zeitsch. gesamte Staatswiss.* 21, 301–304]

- experimentally with subjects and submitted programmed strategies

[C. Keser (1993), Some results of experimental duopoly markets with demand inertia. *Journal of Industrial Economics* 41, 133–151]

[1992 PhD thesis: Springer Lecture Notes Econ. Math. Systems 391]

Demand potential, prices, profits, inertia

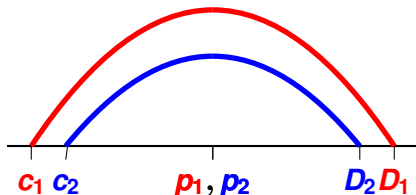
Total demand potential **400** split as $D_1 + D_2$ between two producing firms with costs $c_1 = 57$ and $c_2 = 71$.

Firm i chooses price p_i and sells $D_i - p_i$ units, gets profit $(D_i - p_i)(p_i - c_i)$

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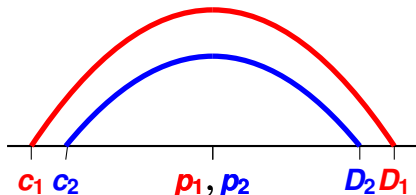
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Optimal **myopic** price $p_i = (c_i + D_i)/2$. **Example:**

$D_1 = 207$, $D_2 = 193$, $p_1 = p_2 = 132$, profits 75^2 , 61^2 .



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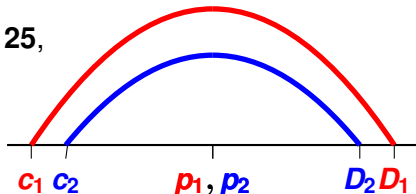
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Played over 25 stages $t = 1, \dots, 25$,

$$D_1^1 = D_1^1 = 200$$

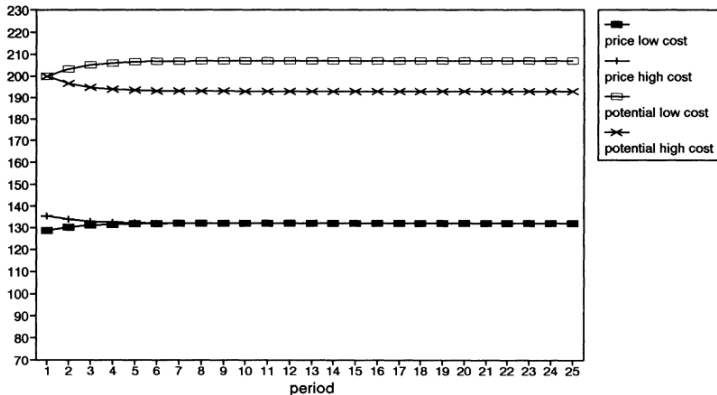
$$D_1^{t+1} = D_1^t + (p_2^t - p_1^t)/2$$

$$D_2^{t+1} = D_2^t + (p_1^t - p_2^t)/2$$



Cooperative solution

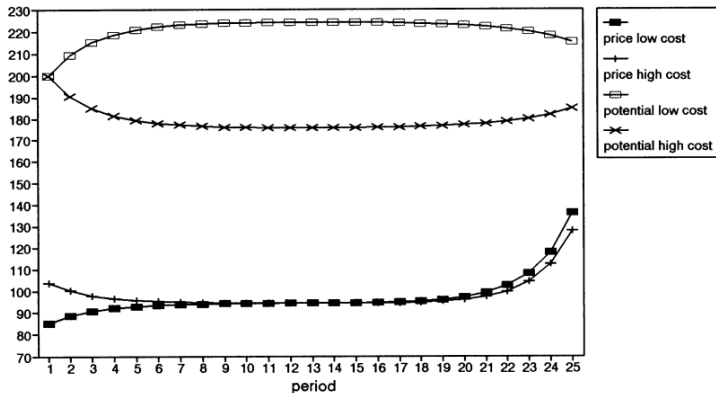
If both firms always choose myopic price:



Total profits over 25 stages about **156k**, **109k**

Subgame perfect equilibrium

Via parameterized backward induction:



Total profits about **137k**, **61k**

Strategy experiments [Keser 1993]

Submitted strategy = flowchart pair, for **low-cost** and **high-cost** firm.

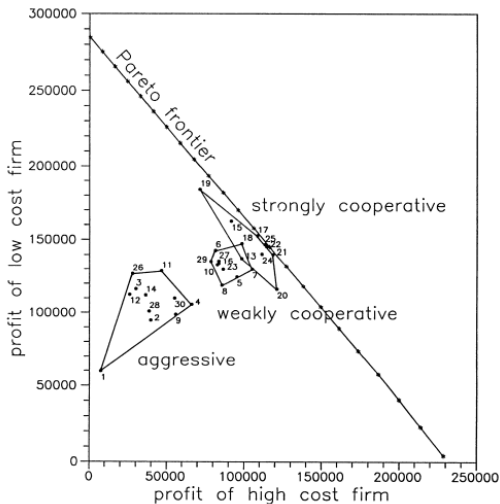
Two competition rounds:

first round: 45 entries

(after feedback:)

second round: 34 entries

second-round profits:



Lessons from a participant's perspective

Profits were totalled against all other teams (including own type)

- **Very important for doing well:** understanding the game
 - focus on demand potential, not price
 - smaller price **strongly** increases future profits
 - avoid wild swings
 - exploit “suckers”

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- **Used now to custom-design and optimize an agent**

The learning framework

- **Base game** = pricing game over 25 stages, in two roles

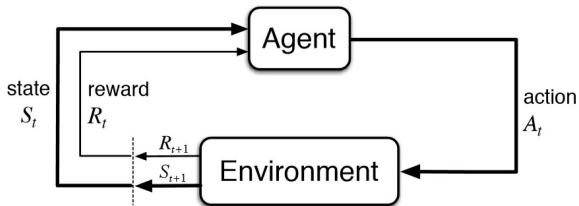
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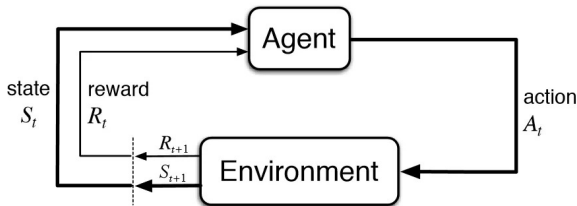
The learning framework

- **Base game** = pricing game over 25 stages, in two roles
- **strategy** represented by an **RL agent** that chooses the **next price** as a function of data for the last, say, **3** stages
- agent is **trained** by repeatedly meeting another random agent, **drawn** from a **mixed equilibrium** of existing strategies, which define the **population game** of pairwise interactions

Standard Reinforcement Learning

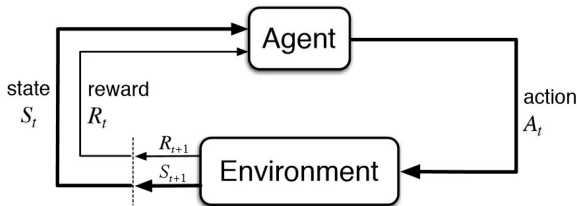


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- here: (mixed) equilibrium as learning environment, random but constant (not evolving with the learning agent)

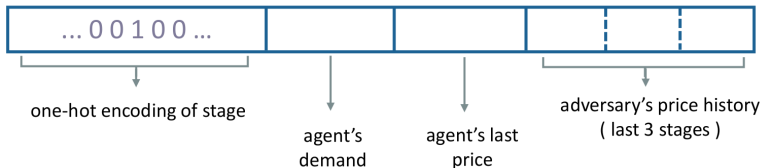
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- here: (mixed) equilibrium as learning environment, random but constant (not evolving with the learning agent)
- tested RL methods so far:
 - Q-table with rewards for (state, action) pairs
 - Policy Gradient Method: randomized policy via neural net

Learning a new strategy: not easy

- a whole strategy, for unknown situations, must be learned
- assumption: learn next price as **function** of last **3** stages with
 - information per state : **own price, own profit**, opponent price
 - explicit **state**: **demand potential, stage**
 - e.g. using Policy Gradient Method (PGM):



- learning is **slow** – Q-learning needs large Q-table

A custom learning agent for this game

Suppose the aim is a **strong strategy** for this game (“feature engineering”, as in AlphaGo).

(Not for a general base game; use as benchmark?)

- Tune a small set of **parameters** for a special own strategy:
 - aim for a “fair split” of **demand potential**
 - **predict opponent price** with multiplicative weights
 - set own price to achieve **target** demand potential
 - use **somewhat lower** price to steal customers

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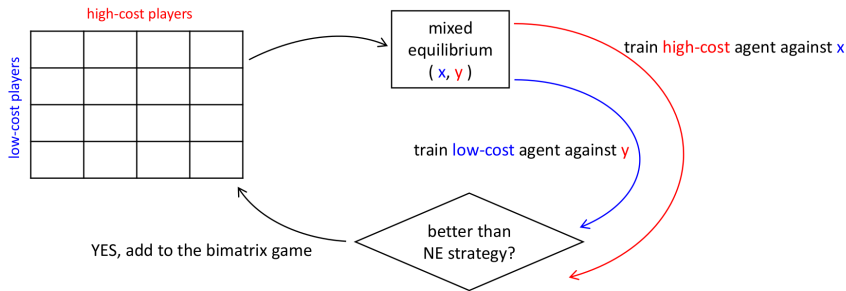
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- **optimization** of ~ 4 parameters close to human-designed agent (**not by gradient descent**, too many “cliffs”)

Add newly RL trained agents (“double oracle”)

- a successfully trained strategy is **added** to the population game
 - new entrant has payoffs against each existing strategy
 - defines **bimatrix game** with **new equilibrium** as next learning environment



The population game

A successfully trained strategy is **added** to the population game, as a **row** or **column** depending on its role (**low-** or **high-cost** firm).

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That mixed equilibrium defines the next learning environment.

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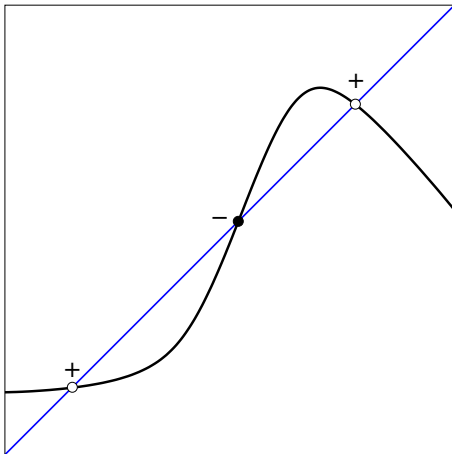
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Which equilibrium?

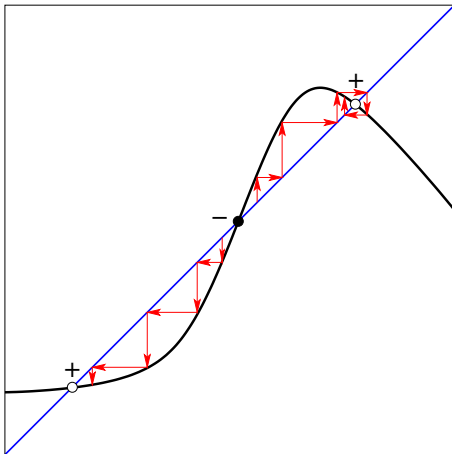
- **equilibrium selection** via computing an equilibrium from random starting pair as **prior** (Harsanyi-Selten tracing procedure)
 - as **(accurate??) proxy for evolutionary dynamics**
 - finds only positive-**index** equilibria (for dynamic stability)
 - the prior could be the previous equilibrium
- has typically **small support** (no issue with PPAD-hardness)

Index of a fixed point



Fixed point $\mathbf{x} = \mathbf{f}(\mathbf{x})$: $\text{index}(\mathbf{x}) = \text{sign det } \mathbf{D}(\mathbf{x} - \mathbf{f}(\mathbf{x}))$

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positive index necessary for **dynamic stability**

Pure NE vs. mixed NE with higher payoff

(*B*, *b*) = **PGM-learned** pure NE, stops at size **8** × **5** (SPNE?)

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(\mathbf{B}, \mathbf{b}) = **PGM-learned** pure NE, stops at size $\mathbf{8} \times \mathbf{5}$ (SPNE?)

Restricted to equilibrium supports:

		2		
		myopic	a	b
1	A	<div>80</div> <div>155</div>	<div>79</div> <div>142</div>	<div>70</div> <div>124</div>
	B	<div>46</div> <div>179</div>	<div>53</div> <div>116</div>	<div>56</div> <div>127</div>

Pure NE vs. mixed NE with higher payoff

(B, b) = **PGM-learned** pure NE, stops at size 8×5 (SPNE?)

Restricted to equilibrium supports:

		2	0.52 myopic	0.48 a	0 b	mixed NE payoffs	
1	0.875 A	80	155	79	124	70	75.75
	0.125 B	46	179	53	116	56	148.76

Advantage of this framework

It is **modular** rather than a huge simulation:

- the **base game** (pricing game)
 - is complex (**too complex?**) as an interesting learning scenario
 - allows competition and cooperation
 - potentially has “hand-made” good (benchmark?) strategies
 - can be replaced by another game
 - the **population game** . . . uses game theory
 - provides via equilibria a “stable” learning environment
 - has typically mixed, non-unique equilibria
 - allows different equilibrium concepts (mixed, evolutionary)
- ⇒ can independently investigate different aspects

Challenges ahead

- RL agents learn **slowly** (investigate further approaches)
 - often too jittery (oscillations)
- Learning for **evolutionary success** different from high-payoff
- comparison with existing approaches, e.g.
[E. Calvano, G. Calzolari, V. Denicolò, and S. Pastorello (2020),
Artificial intelligence, algorithmic pricing, and collusion.
American Economic Review 110(10), 3267–3397.]

Future extension:

- competition between more than two firms (better model)
- different **base games**

Thank you!