Depth PID: (2.5, 0.05, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (nan, nan, nan) Roll Deadband: nan iverControlLogs/IverControlDataLogs09-13-2022/IverControlData-20220913060117.log Elevators port 20 stbd deg 0 10 50 60 20 30 40 sec **Rudders** 0 upper lower 6 −10 -2010 20 40 50 60 30 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 10 20 30 50 60 40 sec Roll 20 deg 0 **-**20 20 30 40 50 60 10 sec Numerical Derivative of Roll 20 deg/sec 0 **-**20 10 20 30 40 50 60 sec Elevator vs. Numerical Derivative of Roll 20 stbd deg/sec port 0 -20 -100 10 20 30 deg Rudder vs. Numerical Derivative of Roll 20 upper deg/sec lower 0 -20 -15-25 -20 -10deg