Depth PID: (3.0, 0.1, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (nan, nan, nan) Roll Deadband: nan iverControlLogs/IverControlDataLogs09-13-2022/IverControlData-20220913054014.log Elevators port 20 stbd deg 0 -20100 200 150 0 50 sec **Rudders** 5.0 upper 2.5 lower 0.0 -2.550 100 200 150 0 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 50 100 200 150 sec Roll 150 100 50 0 50 100 200 150 sec Numerical Derivative of Roll 100 deg/sec -1000 50 100 150 200 sec Elevator vs. Numerical Derivative of Roll 100 stbd deg/sec port -100-30-20 -100 10 20 30 deg Rudder vs. Numerical Derivative of Roll 100 upper deg/sec lower 0 -100**-**2 deg