Depth PID: (2.0, 0.0, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (0.25, 0.0, 0.0) Roll Deadband: 3.0 iverControlLogs/IverControlDataLogs09-14-2022/IverControlData-20220915071900.log Elevators port 0.0 stbd 6 9 −2.5 **-**5.0 20 40 60 80 sec **Rudders** upper lower deg 0 -1020 80 40 60 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 20 40 60 80 sec Roll 20 deg 10 0 -1020 40 80 60 sec Numerical Derivative of Roll 20 deg/sec -2020 40 60 80 sec Elevator vs. Numerical Derivative of Roll 20 stbd deg/sec port -20-6 **-**5 -4 **-**3 **-**2 -10 2 deg Rudder vs. Numerical Derivative of Roll 20 upper deg/sec lower -20-10.0**-**7.5 -5.0 -2.52.5 5.0 7.5 0.0 deg