Depth PID: (1.5, 0.0, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (0.5, 0.0, 0.0) Roll Deadband: 5.0 iverControlLogs/IverControlDataLogs09-14-2022/IverControlData-20220915080725.log Elevators 0.05 port stbd deg 0.00 -0.0520 30 10 40 50 60 sec **Rudders** 0.05 upper lower 0.00 -0.0510 20 30 50 60 40 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 20 30 60 10 40 50 sec Roll 7.5 9 5.0 2.5 10 20 30 40 50 60 sec Numerical Derivative of Roll deg/sec 0 10 20 30 40 50 60 sec Elevator vs. Numerical Derivative of Roll 10 stbd deg/sec port 0 -0.040.00 -0.020.02 0.04 deg Rudder vs. Numerical Derivative of Roll 10 upper deg/sec lower 0 0.00 -0.04-0.020.02 0.04 deg