Depth PID: (2.5, 0.05, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (nan, nan, nan) Roll Deadband: nan iverControlLogs/IverControlDataLogs09-13-2022/IverControlData-20220913054538.log Elevators port 20 stbd deg 0 -20100 200 250 50 150 0 sec **Rudders** upper 0 lower g −10 -20 50 200 250 100 150 0 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 50 100 150 200 250 sec Roll 20 0 50 200 250 0 100 150 sec Numerical Derivative of Roll 20 deg/sec 0 -200 50 100 150 200 250 sec Elevator vs. Numerical Derivative of Roll 20 stbd deg/sec port 0 -20 -30-20 -100 10 20 30 deg Rudder vs. Numerical Derivative of Roll 20 upper deg/sec lower 0 -20 5 **-**20 -15 **-**5 -25-10deg