Depth PID: (2.5, 0.1, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (nan, nan, nan) Roll Deadband: nan iverControlLogs/IverControlDataLogs09-13-2022/IverControlData-20220913052730.log Elevators 0 port stbd <del>g</del> −10 -2020 80 40 60 100 sec **Rudders** upper lower deg -1020 40 60 80 100 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 20 80 100 40 60 sec Roll 30 9 20 9 . 10 0 20 40 60 80 100 sec Numerical Derivative of Roll 20 deg/sec 0 **-**20 20 40 60 80 100 sec Elevator vs. Numerical Derivative of Roll 20 stbd deg/sec port 0 **-**20 -25 -20 -15-10**-**5 0 deg Rudder vs. Numerical Derivative of Roll 20 upper deg/sec lower 0 **-**20 -12.5 -10.0**-**7.5 -5.00.0 2.5 -2.55.0 deg