Depth PID: (2.5, 0.05, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (nan, nan, nan) Roll Deadband: nan iverControlLogs/IverControlDataLogs09-13-2022/IverControlData-20220913060259.log Elevators 0 port stbd g −10 -2020 60 80 40 100 120 sec Rudders upper 0 lower **b** −10 -20 20 40 60 80 100 120 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 20 60 80 100 120 40 sec Roll 30 20 ф 10 0 20 40 60 100 80 120 sec Numerical Derivative of Roll 20 deg/sec -2020 40 60 80 100 120 sec Elevator vs. Numerical Derivative of Roll 20 stbd deg/sec port -20 -20-15-10 **-**5 0 deg Rudder vs. Numerical Derivative of Roll 20 upper deg/sec lower 0 -20-15-25 -20-10deg