Depth PID: (2.5, 0.1, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (nan, nan, nan) Roll Deadband: nan iverControlLogs/IverControlDataLogs09-13-2022/IverControlData-20220913051331.log Elevators 0 port stbd <u>b</u> −10 -2020 40 60 80 100 sec **Rudders** upper lower 60 −10 -20-30. 20 40 60 80 100 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 20 40 60 80 100 sec Roll 20 deg 0 20 40 80 100 60 sec Numerical Derivative of Roll 20 deg/sec 0 -20 20 40 60 80 100 sec Elevator vs. Numerical Derivative of Roll 20 stbd deg/sec port 0 -20 -15-20 -10**-**5 0 deg Rudder vs. Numerical Derivative of Roll 20 upper deg/sec lower 0 -20 -25 -20 -15-10**-**5 deg