Depth PID: (2.0, 0.1, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (nan, nan, nan) Roll Deadband: nan iverControlLogs/IverControlDataLogs09-13-2022/IverControlData-20220913053831.log Elevators port 20 stbd deg 0 -20 20 50 10 30 40 sec **Rudders** 0.05 upper lower 0.00 -0.0510 20 30 40 50 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 10 20 30 40 50 sec Roll 30 20 g 9 10 0 10 20 30 40 50 sec Numerical Derivative of Roll 20 deg/sec -2010 20 30 40 50 sec Elevator vs. Numerical Derivative of Roll 20 stbd deg/sec port **-**20 -20 -10 10 20 30 deg Rudder vs. Numerical Derivative of Roll 20 upper deg/sec lower 0 -200.00 -0.04-0.020.02 0.04 deg