Depth PID: (2.0, 0.0, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (0.5, 0.0, 0.0) Roll Deadband: 3.0 iverControlLogs/IverControlDataLogs09-14-2022/IverControlData-20220915075112.log Elevators 5 port stbd 0 deg -5 20 60 80 40 100 120 sec **Rudders** upper 0 lower deg -20 20 40 60 80 100 120 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 20 40 60 80 100 120 sec Roll deg 0 -20 20 40 60 80 100 120 sec Numerical Derivative of Roll 20 deg/sec 0 -20 20 40 60 80 100 120 sec Elevator vs. Numerical Derivative of Roll 20 stbd deg/sec port -20 -8 -6 -4 **-**2 0 deg Rudder vs. Numerical Derivative of Roll 20 upper deg/sec lower 0 -20 5 -15-1010 -30 **-**25 -20 deg