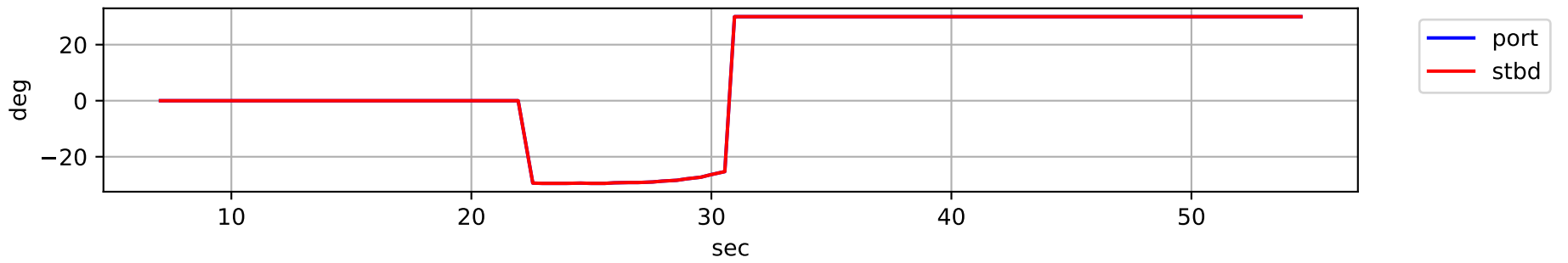
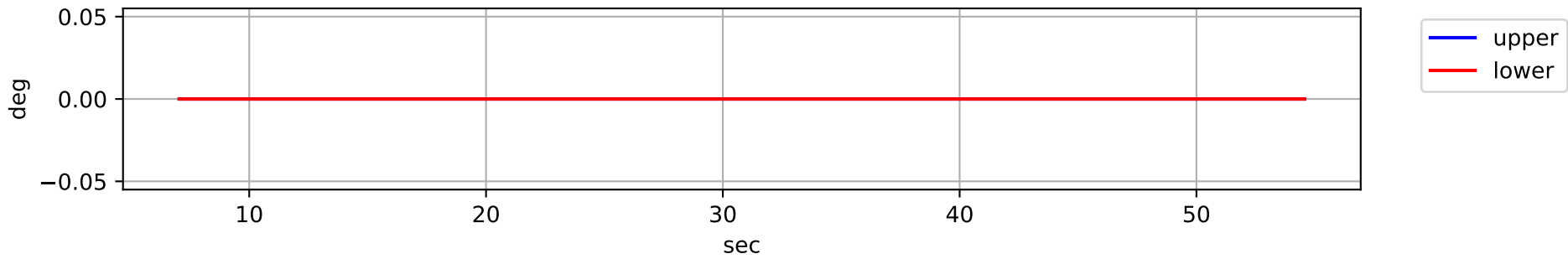


Depth PID: (10.0, 0.0, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (nan, nan, nan) Roll Deadband: nan
iverControlLogs/IverControlDataLogs09-13-2022/IverControlData-20220913050429.log

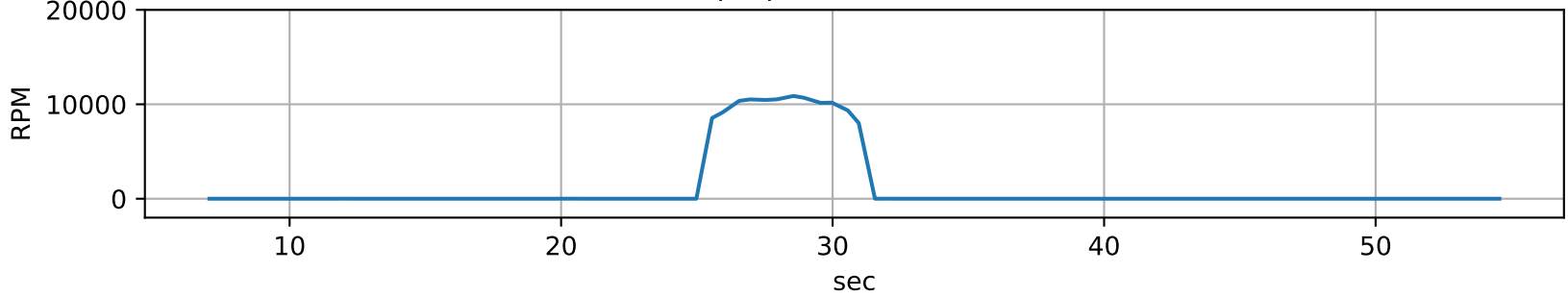
Elevators



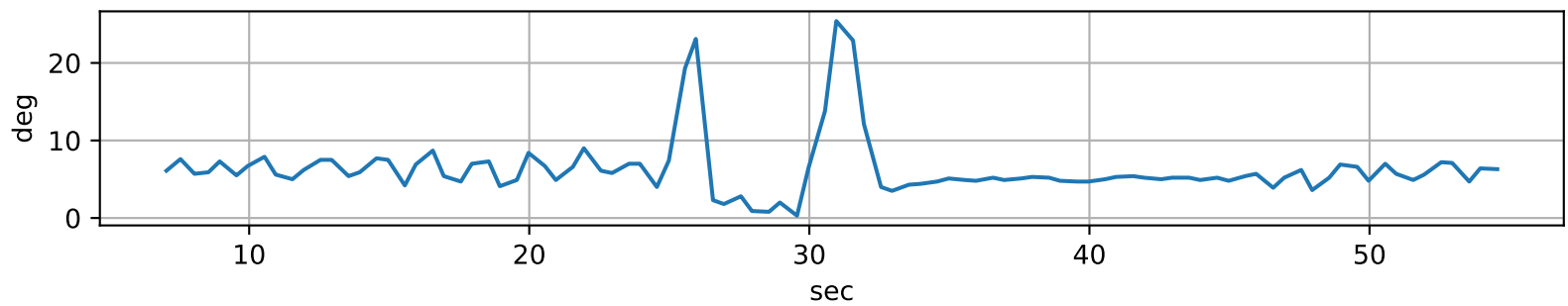
Rudders



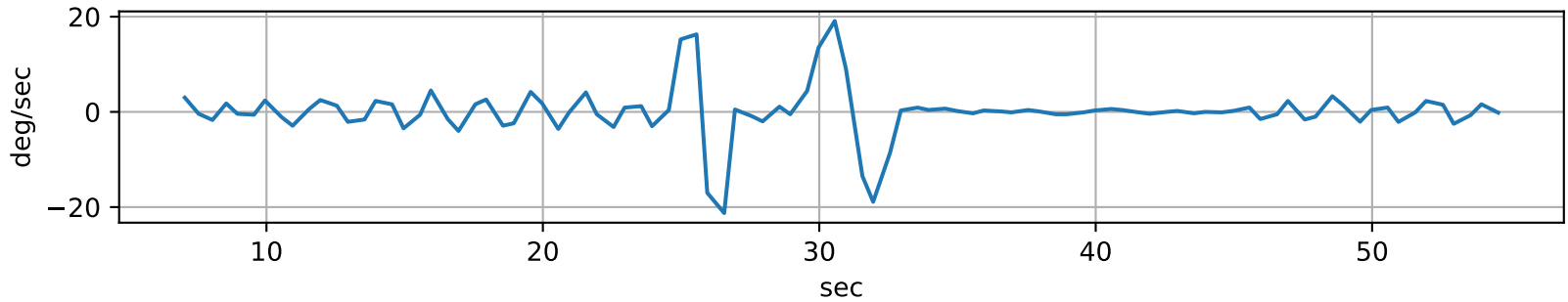
Prop Speed (Motor RPM)



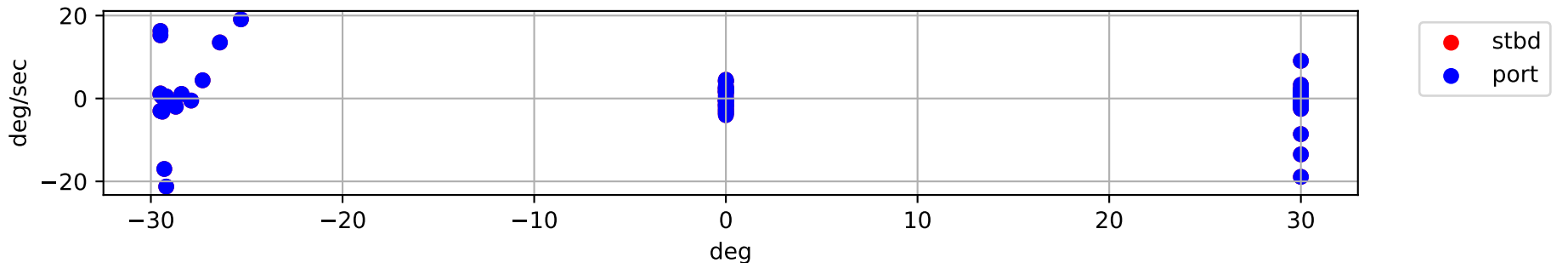
Roll



Numerical Derivative of Roll



Elevator vs. Numerical Derivative of Roll



Rudder vs. Numerical Derivative of Roll

