Depth PID: (2.0, 0.0, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (0.5, 0.0, 0.0) Roll Deadband: 3.0 iverControlLogs/IverControlDataLogs09-14-2022/IverControlData-20220915072548.log Elevators 0.05 port stbd deg 0.00 -0.0515 20 10 25 30 35 40 45 sec **Rudders** 0.05 upper lower 0.00 -0.0510 15 20 25 30 35 40 45 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 10 15 20 25 30 35 40 45 sec Roll 10.0 7.5 5.0 10 15 20 25 30 35 40 45 sec Numerical Derivative of Roll 5 deg/sec 0 10 15 20 25 30 35 40 45 sec Elevator vs. Numerical Derivative of Roll stbd 5 deg/sec port 0 **-**5 0.00 -0.04-0.020.02 0.04 deg Rudder vs. Numerical Derivative of Roll upper 5 deg/sec lower 0 -5 0.00 -0.04-0.020.02 0.04 deg