Depth PID: (3.0, 0.0, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (1.0, 0.0, 0.0) Roll Deadband: 3.0 iverControlLogs/IverControlDataLogs09-14-2022/IverControlData-20220915075957.log Elevators port stbd deg 0 -1020 40 60 100 120 140 80 sec **Rudders** upper 20 lower deg 0 -2020 40 60 100 120 140 80 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 120 20 40 60 100 80 140 sec Roll 20 deg -20 20 40 100 120 140 60 80 sec Numerical Derivative of Roll 20 deg/sec 0 -20 20 40 60 80 100 120 140 sec Elevator vs. Numerical Derivative of Roll stbd 20 deg/sec port -20 7.5 -12.5-10.0-7.5-5.0-2.50.0 2.5 5.0 deg Rudder vs. Numerical Derivative of Roll upper 20 deg/sec lower 0 -20 -20 -10 0 10 20 30 deg