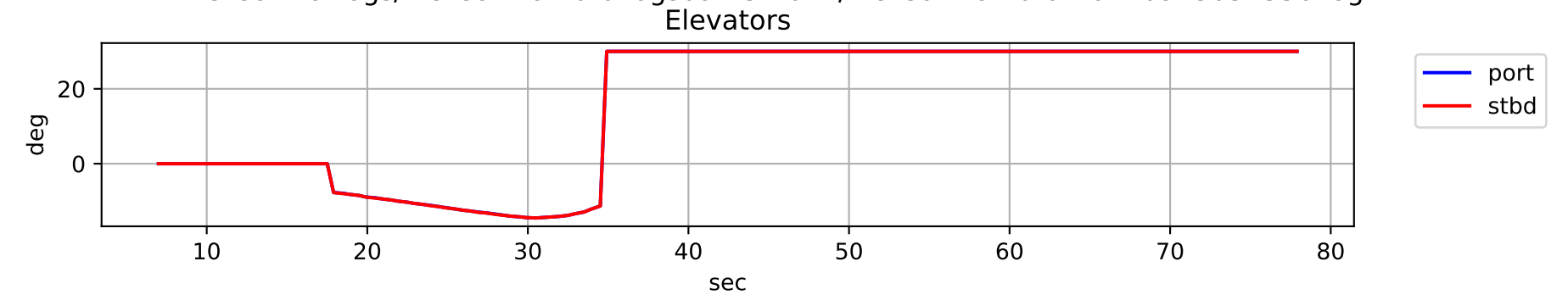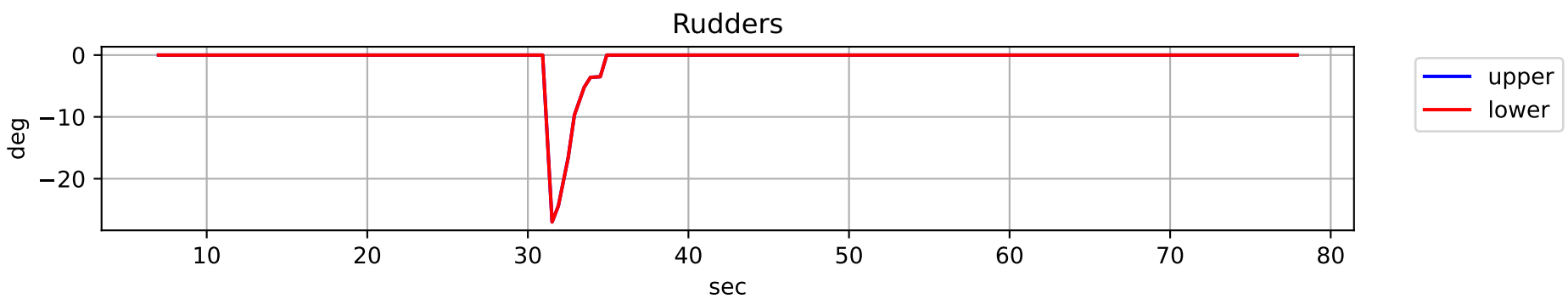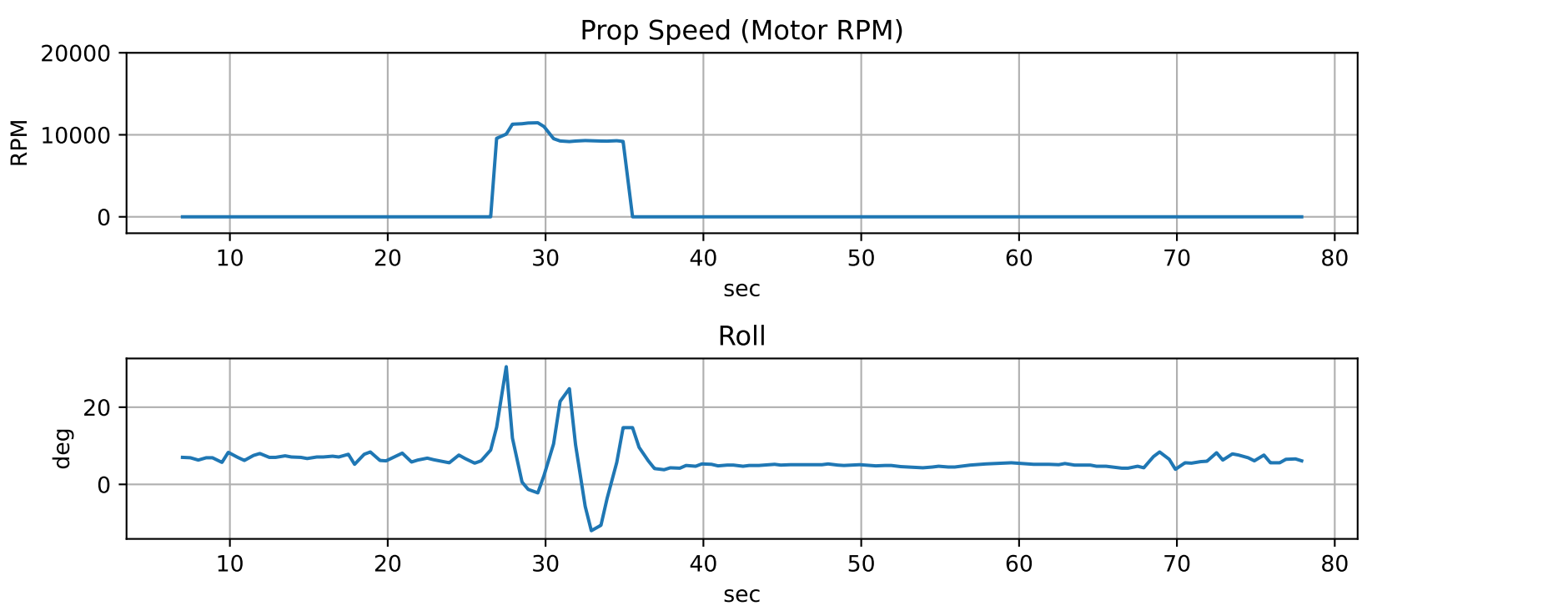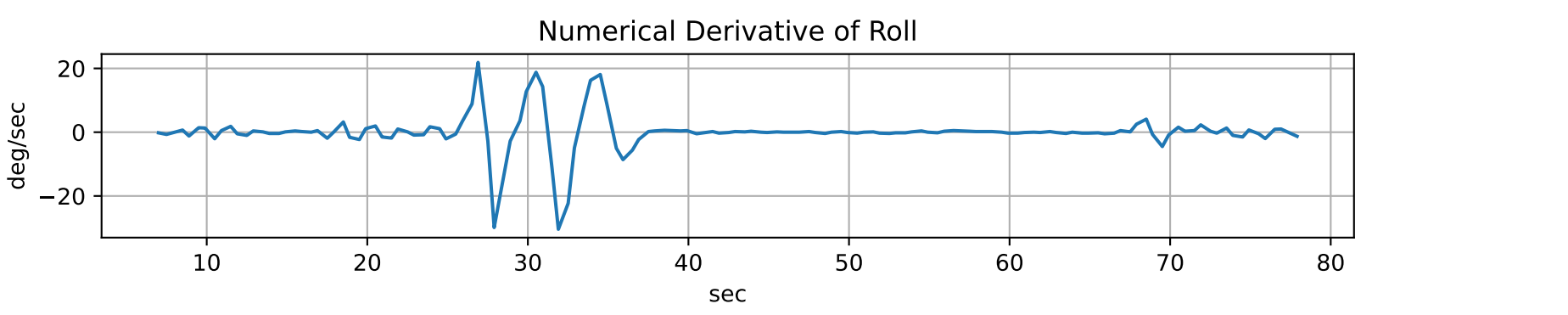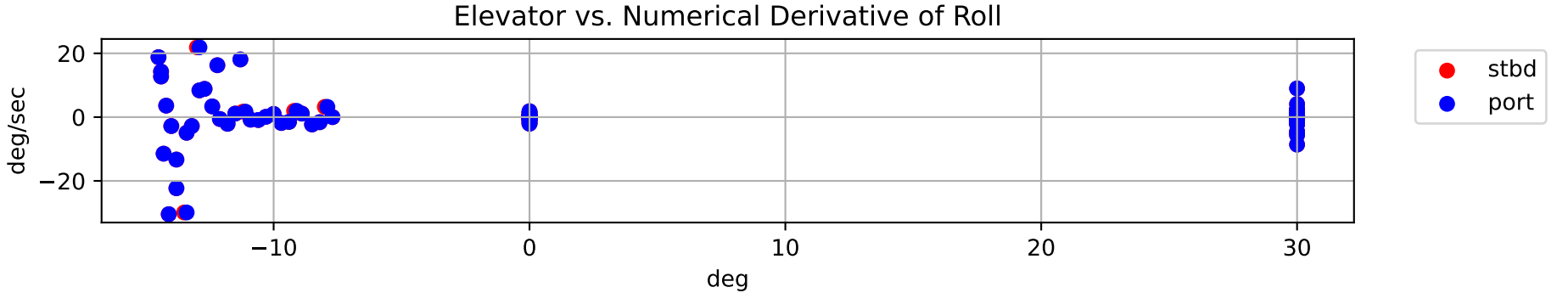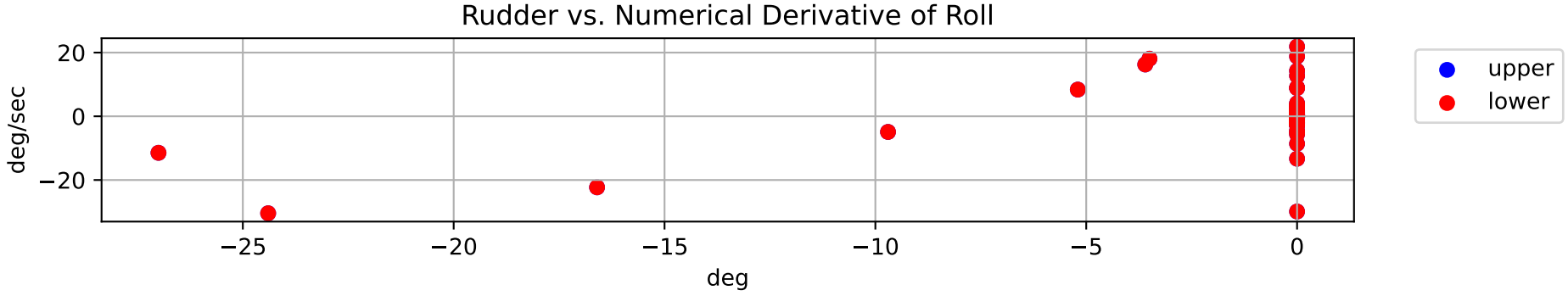Depth PID: (2.5, 0.1, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (nan, nan, nan) Roll Deadband: nan
iverControlLogs/IverControlDataLogs09-13-2022/IverControlData-20220913052556.log