Depth PID: (2.5, 0.05, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (nan, nan, nan) Roll Deadband: nan iverControlLogs/IverControlDataLogs09-13-2022/IverControlData-20220913055332.log **Elevators** 5 port 0 stbd deg **-**5 -1020 40 60 80 100 120 140 0 160 sec **Rudders** upper lower g −10 -20 -3020 40 60 80 100 120 140 160 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 20 40 60 80 160 100 120 140 sec Roll 20 0 20 40 120 140 160 0 60 80 100 sec Numerical Derivative of Roll 20 deg/sec 0 -20 0 20 40 60 80 100 120 140 160 sec Elevator vs. Numerical Derivative of Roll 20 stbd deg/sec port -20 2.5 -12.5-10.0-7.5-5.0-2.50.0 5.0 deg Rudder vs. Numerical Derivative of Roll 20 upper deg/sec lower -20 -25 -20 -15-10**-**5 deg