Depth PID: (1.0, 0.0, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (0.5, 0.0, 0.0) Roll Deadband: 3.0 iverControlLogs/IverControlDataLogs09-14-2022/IverControlData-20220915073940.log **Elevators** 0 port stbd **-**2 20 40 60 80 sec **Rudders** 10 upper lower deg 0 -1020 80 40 60 sec Roll 20 0 20 40 60 80 sec Numerical Derivative of Roll 20 deg/sec 0 -2020 40 60 80 sec Elevator vs. Numerical Derivative of Roll 20 stbd deg/sec port -20-0.5-2.5-2.0-1.5-1.00.0 -3.0deg Rudder vs. Numerical Derivative of Roll 20 upper deg/sec lower 0

-20

-10

-5

0

deg

5

10