Depth PID: (2.5, 0.1, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (nan, nan, nan) Roll Deadband: nan iverControlLogs/IverControlDataLogs09-13-2022/IverControlData-20220913050635.log Elevators port 20 stbd deg 0 20 40 60 80 sec **Rudders** 0 upper lower -10-20 **-**30 20 40 60 80 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 20 40 60 80 sec Roll 20 10 0 -1020 40 80 60 sec Numerical Derivative of Roll deg/sec 0 **-**20 20 40 60 80 sec Elevator vs. Numerical Derivative of Roll stbd deg/sec port <del>-</del>20 -1010 20 30 deg Rudder vs. Numerical Derivative of Roll upper deg/sec lower 0 <del>-</del>20 -25 **-**20 -15-10**-**5 0 -30 deg