Depth PID: (1.5, 0.0, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (0.5, 0.0, 0.0) Roll Deadband: 5.0 iverControlLogs/IverControlDataLogs09-14-2022/IverControlData-20220915081031.log **Elevators** port stbd sec Rudders upper lower deg -20 sec Roll deg -50sec Numerical Derivative of Roll deg/sec -50 sec Elevator vs. Numerical Derivative of Roll stbd port -50 -5 deg Rudder vs. Numerical Derivative of Roll upper

