Depth PID: (2.5, 0.0, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (nan, nan, nan) Roll Deadband: nan iverControlLogs/IverControlDataLogs09-13-2022/IverControlData-20220913045149.log Elevators port 20 stbd deg 0 50 200 100 150 0 sec **Rudders** 0 upper lower -10-20 -3050 100 150 200 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 50 100 150 200 0 sec Roll 50 б 25 0 50 100 150 200 0 sec Numerical Derivative of Roll 25 deg/sec -25-50 0 50 100 150 200 sec Elevator vs. Numerical Derivative of Roll 25 stbd deg/sec port **-**25 -50 -5 0 10 15 -105 20 25 30 deg Rudder vs. Numerical Derivative of Roll 25 upper 0 –25 –25 lower -50-25 -15**-**5 -30 -20 -10deg