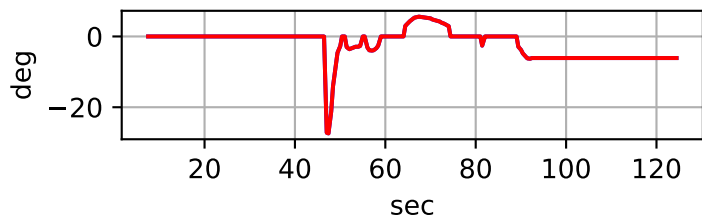


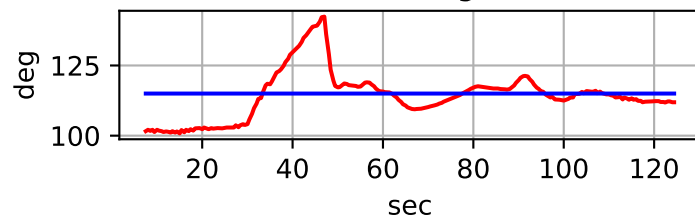
Depth PID: (2.5, 0.05, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (nan, nan, nan) Roll Deadband: nan  
iverControlLogs/IverControlDataLogs09-13-2022/IverControlData-20220913060259.log

Rudders



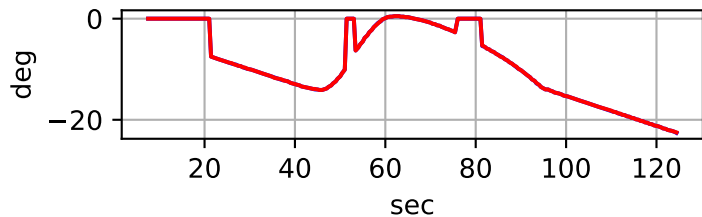
upper  
lower

Heading



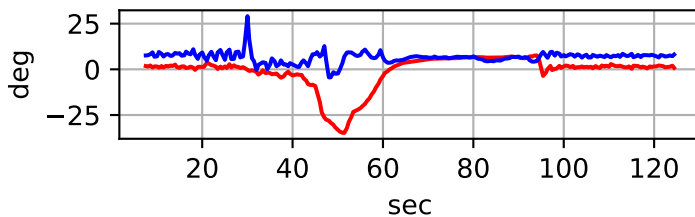
actual  
target

Elevators



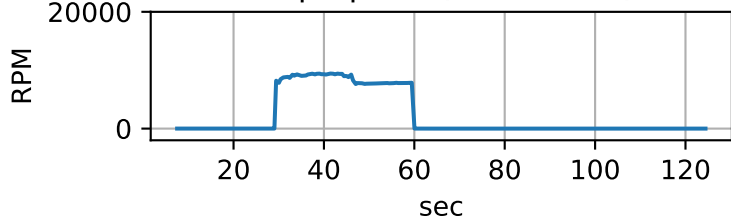
port  
stbd

Pitch & Roll

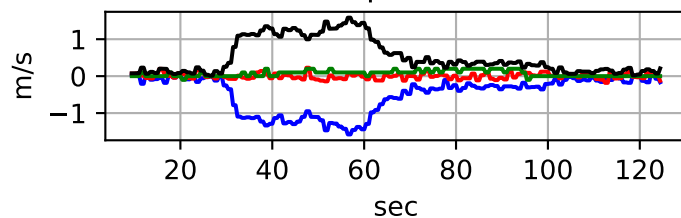


roll  
pitch

Prop Speed (Motor RPM)



Speed



X  
Y  
Z  
Total