Depth PID: (3.0, 0.1, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (nan, nan, nan) Roll Deadband: nan iverControlLogs/IverControlDataLogs09-13-2022/IverControlData-20220913054014.log **Elevators** 25 port stbd -25100 200 50 150 0 sec **Rudders** 5 upper lower 50 100 200 150 sec Roll 100 6<del>9</del> p 50 100 150 200 0 sec Numerical Derivative of Roll 100 0 -10050 100 0 150 200 sec Elevator vs. Numerical Derivative of Roll 100 stbd port 0 -100-20 10 20 -30-100 30 deg Rudder vs. Numerical Derivative of Roll 100 upper lower 0

2

deg

deg

deg/sec

deg/sec

deg/sec

-100

-4

**-**2