Depth PID: (2.5, 0.1, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (nan, nan, nan) Roll Deadband: nan iverControlLogs/IverControlDataLogs09-13-2022/IverControlData-20220913052556.log Elevators port 20 stbd deg 0 50 70 80 10 20 30 40 60 sec **Rudders** 0 upper lower \_<del>6</del> −10 -20 10 20 30 40 50 60 70 80 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 10 20 30 40 50 60 70 80 sec Roll 20 0 10 20 30 40 50 60 70 80 sec Numerical Derivative of Roll 20 deg/sec 0 -20 10 20 30 40 50 60 70 80 sec Elevator vs. Numerical Derivative of Roll 20 stbd deg/sec port -20 10 -100 20 30 deg Rudder vs. Numerical Derivative of Roll 20 upper deg/sec lower 0 **-**20 -15-5 -25-20-10deg