Depth PID: (1.0, 0.0, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (0.5, 0.0, 0.0) Roll Deadband: 3.0 iverControlLogs/IverControlDataLogs09-14-2022/IverControlData-20220915073940.log Elevators 0 port stbd **-**2 **-**3 20 40 60 80 sec **Rudders** 10 upper lower deg 0 -1020 40 60 80 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 20 40 60 80 sec Roll 20 deg 10 0 -1020 40 60 80 sec Numerical Derivative of Roll 20 deg/sec 0 -2020 40 60 80 sec Elevator vs. Numerical Derivative of Roll 20 stbd deg/sec port -20-3.0-2.5-2.0-1.5-1.0-0.50.0 deg Rudder vs. Numerical Derivative of Roll 20 upper deg/sec lower -20-105 **-**5 0 10 deg