Depth PID: (1.0, 0.0, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (0.5, 0.0, 0.0) Roll Deadband: 3.0 iverControlLogs/IverControlDataLogs09-14-2022/IverControlData-20220915073811.log Elevators 0 port stbd **-**2 **-**3 10 30 60 20 40 50 sec Rudders 10 upper lower deg 0 -1010 20 30 50 60 40 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 30 10 20 60 40 50 sec Roll 20 စို့ 10 0 10 20 50 30 40 60 sec Numerical Derivative of Roll deg/sec -2010 20 30 40 50 60 sec Elevator vs. Numerical Derivative of Roll stbd deg/sec port **-**20 -3.0 -2.5-2.0-1.5-1.0-0.50.0 deg Rudder vs. Numerical Derivative of Roll upper deg/sec lower 0 -20-10.0-7.5-5.0 -2.50.0 2.5 5.0 7.5 10.0 deg