Depth PID: (1.5, 0.0, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (0.5, 0.0, 0.0) Roll Deadband: 5.0 iverControlLogs/IverControlDataLogs09-14-2022/IverControlData-20220915081031.log Elevators port stbd deg 10 sec **Rudders** upper lower deg -20sec Prop Speed (Motor RPM) ₹ 10000 sec Roll deg -50 sec Numerical Derivative of Roll deg/sec -50 sec Elevator vs. Numerical Derivative of Roll stbd deg/sec port -50-5 deg Rudder vs. Numerical Derivative of Roll upper deg/sec lower -50 -10**-**5 -20 -15deg