Depth PID: (2.5, 0.05, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (nan, nan, nan) Roll Deadband: nan iverControlLogs/IverControlDataLogs09-13-2022/IverControlData-20220913055014.log Elevators 0.05 port stbd deg 0.00 -0.0520 10 30 40 50 sec **Rudders** 0.05 upper lower 0.00 -0.0510 20 40 50 30 sec Prop Speed (Motor RPM) 20000 ₹ 10000 0 20 10 30 40 50 sec Roll 12.5 10.0 7.5 5.0 10 40 20 30 50 sec Numerical Derivative of Roll 5 deg/sec 0 10 20 30 40 50 sec Elevator vs. Numerical Derivative of Roll stbd 5 deg/sec port 0 0.00 -0.04-0.020.02 0.04 deg Rudder vs. Numerical Derivative of Roll upper 5 deg/sec lower 0 **-**5 -0.040.00 -0.020.02 0.04 deg