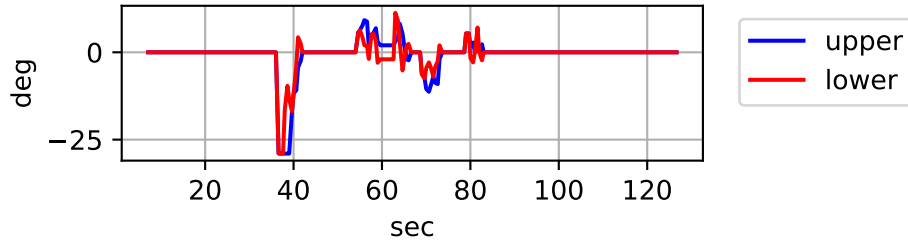
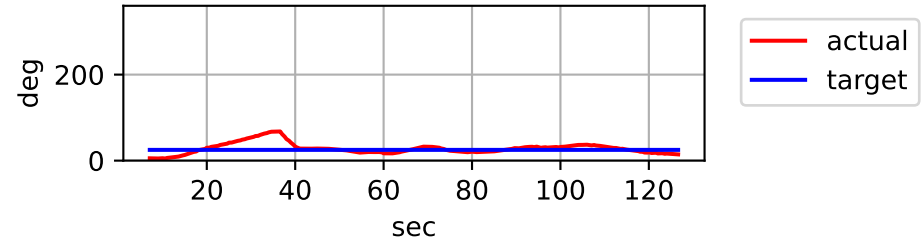


Depth PID: (2.0, 0.0, 0.0). Heading PID: (-1.0, 0.0, 0.0) Roll PID: (0.5, 0.0, 0.0) Roll Deadband: 3.0
iverControlLogs/IverControlDataLogs09-14-2022/IverControlData-20220915072714.log

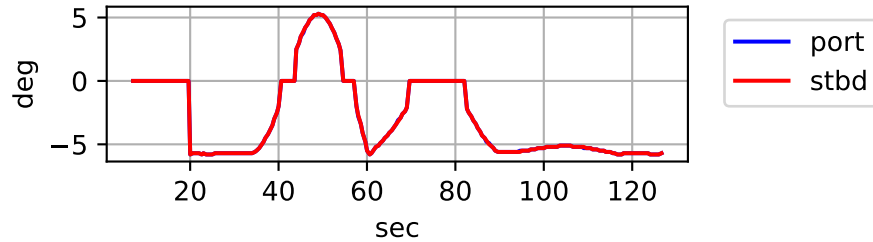
Rudders



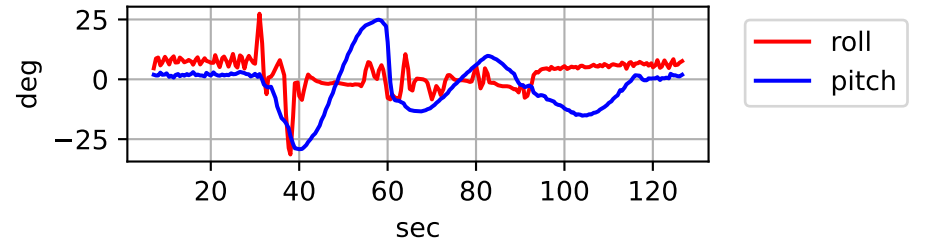
Heading



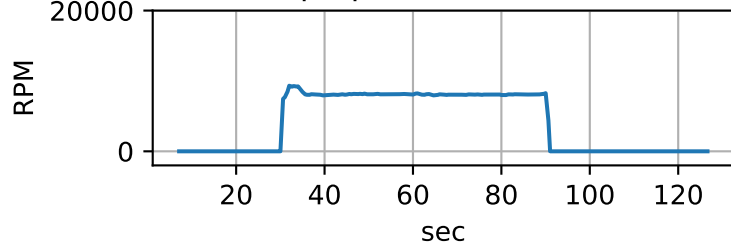
Elevators



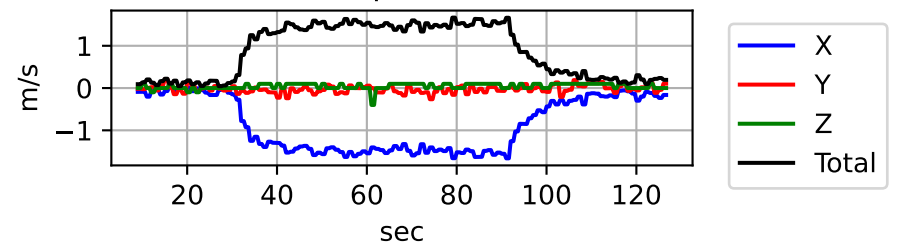
Pitch & Roll



Prop Speed (Motor RPM)



Speed



Depth

