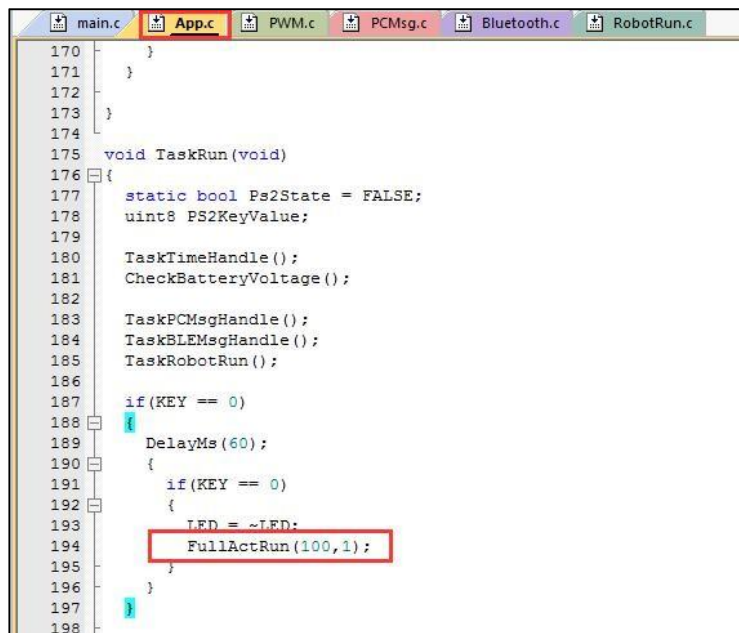


Add offline Running Action

i This section takes STM32 source code as an example. It is recommended to back up the source code program before modifying the program.

The provided program and PC software can only save up to 255 actions in each action group. If this number is exceeded, the action will not run. If you want to add action, please follow these steps:

- 1) Divide the action to be programmed into multiple action groups, e.g. when 225 actions have been programmed into an action group, then save the file and the remaining actions is programmed into the new action group.
- 2) Open the source code and find the following code in App.C.



```

170 }
171 }
172 }
173 }
174
175 void TaskRun(void)
176 {
177     static bool Ps2State = FALSE;
178     uint8 PS2KeyValue;
179
180     TaskTimeHandle();
181     CheckBatteryVoltage();
182
183     TaskPCMsgHandle();
184     TaskBLEMsgHandle();
185     TaskRobotRun();
186
187     if (KEY == 0)
188     {
189         DelayMs(60);
190         {
191             if (KEY == 0)
192             {
193                 TFD = ~TFD;
194                 FullActRun(100,1);
195             }
196         }
197     }
198 }

```

The code means that the programmed action is downloaded into No.100 action group, then press the KEY 1 button on the controller to execute this action. This parameter 100 can be modified. If it is modified, the action is required to download into the modified action group and then the corresponding action can be executed when pressing the key.

- 3) After the modification is completed in the previous step, there are another modification need to be made, as shown in the following figure:

An if statement is added here, which will continue to execute the No.101 action group after the 100th action group is executed.

Note: If we modified the value 100 in the previous step, then it also needs to be modified here.

- 4) According to this method, you can continue to add action followed by this action, as shown in the figure:

```

111     if(gSystemTickCount >= TimeActionRunTotal)
112     {
113         fFrameRunFinish = TRUE;
114         if(++FrameIndex >= FrameIndexSum)
115         {
116             FrameIndex = 0;
117             if(ActFullRunTimesSum != 0)
118             {
119                 if(++ActFullRunTimes >= ActFullRunTimesSum)
120                 {
121                     fRobotRun = FALSE;
122                     if(ActFullNum == 100)
123                     {
124                         FullActRun(101,1);
125                     }
126                     else if(ActFullNum == 101)
127                     {
128                         FullActRun(102,1);
129                     }
130                     else if(ActFullNum == 102)
131                     {
132                         FullActRun(103,1);
133                     }
134                     else if(ActFullNum == 103)
135                     {
136                         FullActRun(104,1);
137                     }
138                 }
139             }
140         }
141     }
142 }
143

```

The rule is: the previously executed action group is the judgment condition of the next action group to be executed, so it must be followed when modifying.

- 5) We have finished adding the action. Finally, compile the program.

```

144     FrameIndex = 0;
145
146     ActFullRunTimes = 0;
...
Build Output
compiling RobotRun.c...
compiling BusServoCtrl.c...
linking...
Program Size: data=18.7 xdata=1288 const=38 code=7799
creating hex file from ".\Obj\OpenArm"...
".\Obj\OpenArm" - 0 Error(s), 0 Warning(s).

```

- 6) If no error is displayed after compiling, then the program will be burnt into Arduino Nano microcontroller .