

The Count of Instantons *Fall 2023*

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Disclaimer

These notes were taken during the lectures using emacs. Any errors are mine and not the speakers'. In addition, my notes are picture-free (but will include commutative diagrams) and are a mix of my mathematical style and that of the lecturers. Also, notation may differ between lecturers. If you find any errors, please contact me at plei@math.columbia.edu.

Description

Graduate level introduction to modern mathematical physics with the emphasis on the geometry and physics of quantum gauge theory and its connections to string theory. We shall zoom in on a corner of the theory especially suitable for exploring non-perturbative aspects of gauge and string theory: the instanton contributions. Using a combination of methods from algebraic geometry, topology, representation theory and probability theory we shall derive a series of identities obeyed by generating functions of integrals over instanton moduli spaces, and discuss their symplectic, quantum, isomonodromic, and, more generally, representation-theoretic significance.

Quantum and classical integrable systems, both finite and infinite-dimensional ones, will be a recurring cast of characters, along with the other (qq-) characters.

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Classical mechanics

We will be discussing three types of physics in an attempt to create something mathematically interesting:

- Classical physics;
- Statistical physics;
- Quantum physics;

1.1 Classical physics

1.1.1 Hamiltonian dynamics We will begin with a space of classical states, which is most commonly known as a *phase space*. This is a symplectic manifold (M, ω) , where $\dim M = 2m$ and $\omega \in \Omega^2(M)$ satisfies

$$\begin{aligned} d\omega &= 0 \\ \omega \wedge \cdots \wedge \omega &\neq 0. \end{aligned}$$

This carries a function

$$H: M \rightarrow \mathbb{R},$$

called a *Hamiltonian*. Then there is a vector field V_H described by

$$dH = \iota_{V_H} \omega,$$

which generates a 1-parameter group g^t of symplectomorphisms of M . The evolution law of the physical system is given by

$$\dot{x} = V_H(x).$$

Because g^t acts by symplectomorphisms, the graph

$$\Gamma_{g^t} = \{(m, g^t(m))\} \subset M \times M$$

is a Lagrangian submanifold. Recall that a submanifold $L \subset M$ of a symplectic manifold is called *Lagrangian* if $\dim L = m$ and $\omega|_L = 0$.

Exercise 1.1.1. Locally any symplectic manifold is given by $M = \mathbb{R}^{2m}$ with the symplectic form

$$\omega = \sum_{i=1}^m dp_i \wedge dq^i.$$

This coordinate system on \mathbb{R}^{2m} is unique up to $Sp(2m)$.

Now if V is a vector field such that $\text{Lie}_V \omega = 0$, then $d\iota_V \omega = 0$. Thus there locally exists a Hamiltonian h_V . We also need the Hamiltonian vector field to be linear in the local coordinates, so the Hamiltonian itself must be quadratic.

Example 1.1.2. An important example of a symplectic manifold is T^*B for any smooth manifold B . There is a 1-form θ on T^*B given by the following formula. If v is a tangent vector at the point (p, b) , then

$$\theta(v) := p(\pi_* v).$$

Then $\omega = d\theta$ is a symplectic form.

Example 1.1.3. Another large class of examples are obtained by *symplectic reduction*. Here, we suppose that a symplectic manifold M carries the action of a compact Lie group G by exact symplectomorphisms. This defines a *moment map* $M \xrightarrow{\mu} \mathfrak{g}^*$ by the formula

$$\langle \mu(m), \xi \rangle = h_{V_\xi}(m).$$

There is some ambiguity in the choice of constants, but in the end we obtain a new space

$$M // G := \mu^{-1}(0)/G.$$

In practice, we want the moment map μ to be equivariant with respect to the coadjoint action on \mathfrak{g}^* . Then the manifold $M // G$ has a canonical symplectic form, but this requires a lot of work.

Now consider $M = \mathbb{R}^{2m}$ and $G = U(1)$, where we write $M = (\mathbb{R}^2)^m$ and $U(1)$ acts by rotations. Then the moment map is actually

$$\mu = \sum_{i=1}^m \frac{1}{2}(p_i^2 + q_i^2) - r,$$

so $\mu^{-1}(0)$ is a sphere. We then obtain

$$\mathbb{R}^{2m} // U(1) = S^{2m-1}/U(1) = \mathbb{P}^{m-1}.$$

We made no use of the complex numbers, so the fact that we obtain a complex manifold will be viewed as a bonus. The reduced symplectic form is simply r times the Fubini-Study form.

Note that \mathbb{P}^{m-1} is compact, so the interpretation that phase space records position and momentum breaks down. In this case, our phase space is called the *classical spin phase space*, where the motion is by rotations rather than by translation.

Remark 1.1.4. We will often consider time-dependent Hamiltonians, where $\dot{x} = V_{H(t)}(x)$.

1.1.2 Lagrangian mechanics There is another point of view, where dynamics on M are given by an optimization problem on the space

$$\mathcal{PM} := \text{Map}([0, 1], M)$$

of paths in M . We will consider an *action*

$$S[\gamma] := \int_{\gamma} \theta - \int_0^1 \gamma(t)^* H(t) dt,$$

where we assume that $\omega = d\theta$. If we further require that $\gamma(0) \in L_0$ and $\gamma(1) \in L_1$, our dynamics are well-defined if L_0, L_1 are Lagrangian submanifolds. Of course, we are looking for paths where $\delta S = 0$.

1.1.3 Classical field theory Classical field theory should be thought of as an infinite-dimensional version of classical mechanics, where we study loopified versions of finite-dimensional manifolds. We want to consider integrals

$$S := \int_{(\Sigma, h)} \mathcal{L}[\phi, \partial\phi] \text{vol}_h,$$

where Σ is the spacetime, h is a metric, and ϕ are the *fields*. Fields could be one of several options:

- Scalars $f: \Sigma \rightarrow X$, where X is a Riemannian manifold;
- Connections ∇ on principal bundles

$$\begin{array}{ccc} G & \longrightarrow & P \\ & & \downarrow \\ & & \Sigma, \end{array}$$

called *gauge fields*;

- The metric h itself, called *gravity*.

We can introduce more complexity into the problem by varying the action and looking for solutions of PDEs, introducing boundary to Σ , and other operations. Also note that Lagrangian mechanics can be interpreted as a 1-dimensional classical field theory.

1.2 Statistical physics

In statistical physics, a point is replaced by a cloud of points, or a probability measure. For example, the measure could contain the term $e^{-\beta H}$, where H was the classical Hamiltonian and β is a parameter of our distribution (inverse temperature). The system often flows to a stationary distribution, which is determined by the outside world. In reality, the distribution will have the form

$$\frac{1}{Z} e^{-\beta H} \quad Z = \int_M e^{-\beta H} \frac{\omega \wedge \cdots \wedge \omega}{m!}.$$

This factor Z is called the *partition function*, and most of our energy is spent on computing this partition function.

1.3 Classical physics with multiple times

Suppose we have Hamiltonians H_1, \dots, H_k such that $[V_{H_1}, \dots, V_{H_k}] = 0$. Then we obtain dynamics

$$\underline{\gamma}: [0, \varepsilon]^p \rightarrow M$$

and an action

$$S = \int \theta - \sum_{k=1}^p \underline{\gamma}^* H_k dt_k$$

defined on paths inside the cube $[0, \varepsilon]^p$. The extreme case of this is an *integrable system* where the H_i are functionally independent, and the maximum possible value of p is m .

Theorem 1.3.1 (Liouville-Arnold). *If the motion is finite (fits in a compact set), then locally M is a fibration*

$$\begin{array}{ccc} T^m & \longrightarrow & M \\ & & \downarrow \\ & & B \end{array}$$

such that the H_i factor through B and the V_{H_k} span the rotations on each S^1 factor of T^m .

A typical trajectory is a winding of the torus, where if θ_i are the angle coordinates on T^m , there is the formula

$$\theta^i(t) = \theta^i(0) + \omega^i t.$$

Generically, these paths will have dense image.

In the special case of an integrable system, there are *action-angle variables*, where the symplectic form is

$$\omega = \sum_{i=1}^m dI_i \wedge d\theta^i.$$

The θ^i are defined up to $SL(m, \mathbb{Z})$ affine transformations. If $C_i \in H_1(T^m, \mathbb{Z})$ form a basis, then the I_i are defined by

$$I_i = \frac{1}{2\pi} \oint_{C_i} d^{-1}\omega.$$

Here, C_i is transported to other fibers via the Gauss-Manin connection. We should note that the I_i are not well-defined, but the quantities $I_i(b') - I_i(b)$ are well-defined.

Because the H_k are defined on the base B , we can write $H_k(I_1, \dots, I_m)$. Fixing $\tau_1, \dots, \tau_m \in \mathbb{R}$, we can flow along

$$H = \sum_{k=1}^m \tau_k H_k,$$

we obtain

$$\omega^i = \frac{\partial H}{\partial I_i}.$$

In “reality,” which is non-integrable, consider an approximation

$$H(I, \theta) = H_0(I) + \varepsilon H_1(I, \theta).$$

Then we can understand the approximate evolution with respect to H by averaging H_1 over T^m .

1.4 Gauge symmetry

We would now like to discuss the idea of gauge symmetries and gauging in the Lagrangian formalism. Recall that the phase space (P, ω) carries an action

$$S[\gamma] = \int_{\gamma} d^{-1}\omega - \int_I \gamma^* H |dt|,$$

and we want to consider the effect of an action of a group G on P . The moment map

$$\mu: P \rightarrow G^*$$

is equivariant with respect to the coadjoint representation. Note that $P // G$ has a symplectic form $\tilde{\omega}$, and locally P looks like

$$T^*G \times P // G \xrightarrow{\pi} P // G.$$

Thus ω restricted to a tubular neighborhood of $\mu = 0$ has the form

$$\pi^* \tilde{\omega} + (\text{tautological form on } T^*G).$$

Recall that we are looking for extrema of S , and we need to find a path on the quotient space. We need to enlarge the space of variables to include $A \in \Omega_1^1(\mathfrak{g})$. Now we will define

$$\tilde{S}[\gamma, A] = S[\gamma] - \int_I \langle \gamma^* \mu, A \rangle.$$

The space of possible A has an infinite-dimensional symmetry generated by

$$\mathcal{G} = \text{Maps}(I, G) \ni g(t)$$

The action is given by

$$(g(t)) \cdot (\gamma(t), A) := (g(t)\gamma(t), \text{Ad}_{g(t)} A + g^{-1} dg).$$

Note that A transforms as a connection, not as a 1-form.

Remark 1.4.1. The translation by $g^{-1} dg$ compensates for the change of $d^{-1}\omega = \sum p_i dq^i$ under the action of G .

1.4.1 Rational Calogero-Moser model The first example is called the *Calogero-Moser-Sutherland model*. The phase spaces are

$$\tilde{P} = T^*(\mathbb{R}^N \setminus \Delta \text{ or } (S^1)^N \setminus \Delta)$$

with the standard form

$$\omega = \sum_{i=1}^N dp_i \wedge dx_i.$$

For any $v \in \mathbb{R}_+$, the Hamiltonian is given by

$$H = \sum_{i=1}^N \frac{1}{2} p_i^2 + v^2 \sum_{1 \leq i < j \leq N} \left[\frac{1}{(x_i - x_j)^2} \text{ or } \frac{1}{4 \sin^2 \left(\frac{x_i - x_j}{2} \right)} \right].$$

These are systems of n particles where they start out very far away from each other, are brought closer together, and then repel themselves apart again. These turn out to be integrable systems, and in fact they can be obtained by reduction of a system on a higher-dimensional symplectic manifold.

Define the unreduced phase space

$$P = T^*(u(N)) \times \mathbb{C}^N.$$

This is a pair of $N \times N$ Hermitian matrices (P, Q) with a vector $z \in \mathbb{C}^N$. The Liouville form will be written as

$$\text{Tr} \left(dP \wedge dQ + \frac{\text{Tr} dz \wedge dz^\dagger}{2\sqrt{-1}} \right) = \sum_{i,j=1}^N dP_{ij} \wedge dQ_{ji} + \frac{1}{2\sqrt{-1}} \sum_{i=1}^N dz_i \wedge dz_i^*.$$

Then we may define the Hamiltonians

$$H_k = \frac{1}{k} \text{Tr} P^k.$$

The flows look like

$$(P, Q; z) \mapsto (P, Q + \sum_k t_k P^{k-1}; z),$$

so they clearly commute. This system carries a $U(N) \times U(1)$ symmetry, where

$$(u, c) \cdot (P, Q, z) \mapsto (u^{-1}Pu, u^{-1}Qu, u^{-1}z).$$

Because this preserves the symplectic form, we may perform the symplectic reduction. Because $U(n)$ is not simple, there is a free parameter ν , so the moment map is given by

$$\mu(P, Q, z) = [P, Q] + \sqrt{-1}(zz^\dagger - \nu \cdot 1_N).$$

We only need to solve $\mu = 0$ up to $U(N)$, so we choose a diagonal representative of $\{u^{-1}Qu\}$. Thus, assume that $Q = \text{diag}(x_1, \dots, x_N)$ is diagonal with $x_1 \geq \dots \geq x_N$. Generically, the inequalities are strict. Then

$$\mu_{ij} = P_{ij}(x_j - x_i) + \sqrt{-1}(z_i z_j^* - \nu \delta_{ij}).$$

If $i = j$, then $|z_i|^2 = \nu$, so the remaining $U(1)^N$ -action can be used to set $z_i = z_i^* = \sqrt{\nu}$. We can now compute

$$P_{ij} = -\frac{\sqrt{-1}\nu}{x_i - x_j}$$

for the non-diagonal elements. We cannot compute the diagonal elements of P , so we obtain

$$P = \text{diag}(p_1, \dots, p_N) + \left\| \frac{\sqrt{-1}\nu}{x_i - x_j} (1 - \delta_{ij}) \right\|_{i,j=1}^N.$$

In this form, the Hamiltonians become

$$H_1 = \sum_{i=1}^N p_i$$

$$H_2 = \frac{1}{2} \sum_{i=1}^N p_i^2 + \nu^2 \sum_{i < j} \frac{1}{(x_i - x_j)^2},$$

which is what we wanted. We need to show that $\omega = \sum dp_i \wedge dx_i$, so we will compute the Poisson brackets of various functions. Recall that functions on (P, ω) form a Lie algebra with the *Poisson bracket*

$$\{f, g\} = \omega^{-1} \lrcorner df \wedge dg.$$

We note that

$$\begin{aligned} \mathcal{O}(P // G) &= \mathcal{O}(\mu^{-1}(0)/G) \\ &= \mathcal{O}(\mu^{-1}(0))^G \\ &= \mathcal{O}(P)^G / (\mu = 0). \end{aligned}$$

The functions we will consider are the resolvents

$$\begin{aligned} R(\lambda) &= \text{Tr} \frac{1}{Q - \lambda} \\ S(\lambda) &= \text{Tr} P \frac{1}{Q - \lambda}. \end{aligned}$$

Because the trace is cyclic, we obtain

$$\begin{aligned} dR(\lambda) &= -\text{Tr}(Q - \lambda)^{-1} dQ (Q - \lambda)^{-1} \\ &= -\text{Tr} \left[(Q - \lambda)^2 dQ \right] \end{aligned}$$

Therefore

$$\begin{aligned} \{R(\lambda), S(\mu)\} &= \sum_{i,j} \frac{\partial R(\lambda)}{\partial Q_{ij}} \frac{\partial S(\mu)}{\partial P_{ji}} \\ &= -\text{Tr}(Q - \lambda)^2 (Q - \lambda)^{-1} \\ &= -\frac{\partial}{\partial \lambda} \left(\frac{R(\lambda) - R(\mu)}{\lambda - \mu} \right). \end{aligned}$$

On the reduced space, the functions become

$$\begin{aligned} R(\lambda) &= \sum_{i=1}^N \frac{1}{x_i - \lambda} \\ S(\mu) &= \sum_{i=1}^N \frac{p_i}{x_i - \mu}. \end{aligned}$$

This is equivalent to $\{x_i, x_j\} = 0 = \{p_i, p_j\}$, so $\{p_i, x_j\} = \delta_{ij}$.

Note that this system has an alternative presentation where we assume that $P = \text{diag}(\tilde{p}_1, \dots, \tilde{p}_N)$ and

$$Q = \text{diag}(\tilde{x}_1, \dots, \tilde{x}_N) + \left\| \frac{\sqrt{-1} \mathbf{v}}{\tilde{p}_i - \tilde{p}_j} \right\|.$$

Then the Hamiltonians reduce to

$$H_k = \frac{1}{k} \sum_{i=1}^N \tilde{p}_i^k,$$

and the flows are given by

$$\tilde{x}_i(t) = \tilde{x}_i(0) + \sum_k t_k \tilde{p}_i^{k-1}.$$

This system is not very interesting, but we could instead consider

$$H_k^\vee = \frac{1}{k} \text{Tr } Q^k$$

and obtain a system with position and momentum exchanged.

1.4.2 Trigonometric Calogero-Moser (Sutherland) Now consider $P = T^*U(N) \times \mathbb{C}^N$. Then we have a triple $(P, g; z)$ where P is Hermitian and $g (= \exp(\sqrt{-1}Q))$ is unitary. The moment map is given by

$$\mu(P, g, z) = \sqrt{-1}(P - g^{-1}Pg + zz^\dagger - \nu \cdot 1_N).$$

We may choose to either diagonalize P as $\text{diag}(\tilde{p}_1, \dots, \tilde{p}_N)$ or diagonalize g as $\text{diag}(e^{\sqrt{-1}x_1}, \dots, e^{\sqrt{-1}x_N})$. Making the latter choice, we obtain

$$P = \text{diag}(p_1, \dots, p_N) + \left\| \frac{\nu}{e^{\sqrt{-1}(x_j - x_i)} - 1} (1 - \delta_{ij}) \right\|.$$

The Hamiltonians in this case are

$$\begin{aligned} H_1 &= \sum_k p_k \\ H_2 &= \frac{1}{2} \sum_{i=1}^N p_i^2 + \frac{\nu^2}{4} \sum_{i < j} \frac{1}{\sin^2\left(\frac{x_i - x_j}{2}\right)}. \end{aligned}$$

Making the former choice, we obtain another integrable system called the *rational relativistic Calogero-Moser system* or the *rational Ruijsenaars model*. In this model, the Hamiltonians look like

$$H_k^\vee = \sum e^{\tilde{x}_i} \times (\text{rational functions of } \tilde{p}_i).$$

Here, a relativistic particle in 1 + 1 dimensions has energy and momentum given by

$$\begin{aligned} E &= m \cosh \theta = \text{Tr}(g + g^{-1}) \\ p &= m \sinh \theta = \text{Tr}(g - g^{-1}), \end{aligned}$$

so $E^2 - p^2 = m^2$.

1.5 Infinite-dimensional symmetries

We will now replace $\mathfrak{g} = \text{Lie}$ with $\widehat{\mathfrak{g}} = \widehat{\text{Maps}(S^1, \mathfrak{g})}$, which is a central extension of the space of maps with commutator given by

$$[(f_1, c_1), (f_2, c_2)] = \left([f_1, f_2], \int_{S^1} \text{Tr } f_1 df_2 \right).$$

Then $\widehat{\mathfrak{g}}^*$ is not \mathfrak{g} but instead

$$\widehat{\mathfrak{g}}^* = \left\{ k\partial + A \mid A \in \Omega_{S^1}^1(\mathfrak{g}), k \in \mathbb{R} \right\}$$

with the pairing

$$\langle k\partial + A, (f, c) \rangle = kc + \int_{S^1} \langle A, f \rangle.$$

We will also consider the Lie algebra $\text{Maps}(\mathbb{R}, \mathfrak{g})$, but this requires us to specify some kind of boundary conditions at ∞ . We may also consider $L^2(\mathbb{R}) \otimes \mathfrak{g}$. In the case of S^1 , note that

$$c(f_1, f_2) := \int_{S^1} \text{Tr } f_1 df_2$$

is a 2-cocycle and that

$$H^2(\text{Lg}, \mathbb{R}) \cong \mathbb{R}$$

is 1-dimensional, so this is the only nontrivial cocycle.

The corresponding group is given by the following construction. Define

$$\text{LG} = \text{Maps}(S^1, G).$$

Then $\widehat{\text{LG}}$ is a nontrivial $\text{U}(1)$ -bundle

$$1 \rightarrow \text{U}(1) \rightarrow \widehat{\text{LG}} \rightarrow \text{LG} \rightarrow 1.$$

Note that $H^2(\text{LG}, \mathbb{R}) \simeq \mathbb{R}$. The cohomology $H^3(G, \mathbb{Z})$ is nontrivial with a nontrivial class given by

$$\omega := \frac{i}{8\pi^3} \text{Tr} \left(g^{-1} dg \right)^3 \rightsquigarrow \text{Tr } \xi_1 [\xi_2, \xi_3] =: c(\xi_1, \xi_2, \xi_3).$$

Then there is an evaluation map

$$e: \text{LG} \times S^1 \rightarrow G \quad (g(t), u) \mapsto g(u),$$

and then

$$\int_{S^1} e^* \omega \in H^2(\text{LG}, \mathbb{Z})$$

represents $c_1(\widehat{\text{LG}} \rightarrow \text{LG})$. Therefore, we have an identification

$$\widehat{\text{LG}} = \widehat{\text{Maps}(\mathbb{D}^2, G)} / \text{Maps}((\mathbb{D}^2, S^1), (G, 1)),$$

where $\widehat{\text{Maps}(\mathbb{D}^2, G)} = \text{Maps}(\mathbb{D}^2, G) \times \text{U}(1)$ with multiplication

$$(g_1, c_1) \times (g_2, c_2) = \left(g_1 g_2, c_1 c_2 \exp \frac{i}{4\pi} \int_{\mathbb{D}^2} \text{Tr } g_1^{-1} dg_1 \wedge dg_2 \right).$$

To embed $\text{Maps}((\mathbb{D}^2, S^1), (G, 1))$ as a normal subgroup, we make use of the fact that $\pi_2(G) = 0$, so any map g can be extended to $\widetilde{g}: B^3 \rightarrow G$. Then we define

$$\varphi(g) := (g, \exp(2\pi i) \widetilde{g}^* \omega).$$

The fact that this construction is well-defined is the *Polyakov-Wiegmann formula*.

We will now discuss the adjoint and coadjoint actions of \widehat{LG} on $\widehat{\mathfrak{g}}, \widehat{\mathfrak{g}}^*$ respectively. Infinitesimally, we have

$$(\phi, 0) \cdot (\xi, c) = \left([\phi, \xi], \int_{S^1} \text{Tr } \phi \, d\xi \right).$$

The action on the dual space is given by

$$\begin{aligned} \langle \text{ad}_\phi^*(A, k), (\xi, c) \rangle &= \left\langle (A, k), \left([\phi, \xi], \int_{S^1} \text{Tr } \phi \, d\xi \right) \right\rangle \\ &= k \int_{S^1} \text{Tr } \phi \, d\xi + \int_{S^1} \text{Tr } A[\phi, \xi] \\ &= \int_{S^1} \text{Tr } \xi(-k \, d\phi + [A, \phi]). \end{aligned}$$

Therefore, we obtain

$$\text{Ad}_g^*(A, k) = (-k \, dg \, g^{-1} - gAg^{-1}, 0).$$

Note that $\frac{A}{k}$ is a g -connection 1-form on S^1 .

There is now a natural candidate for a symplectic form, which is

$$\Omega_{T^*\widehat{\mathfrak{g}}} = \delta k \wedge \delta c + \int_{S^1} \text{Tr } \delta A \wedge \delta \xi.$$

Here, δ is the differential in the space of fields. The moment map $\mu: T^*\widehat{\mathfrak{g}} \rightarrow \widehat{\mathfrak{g}}^*$ is given by

$$\mu(k, c, A, \xi) = (G(k, c, A, \xi), 0),$$

where $G(k, c, A, \xi) = -k \, d\xi + [A, \xi]$. We will now compute

$$\mathcal{P}^{\text{red}} = \mu^{-1}(0)/LG = \{(\xi, A, k, c) \mid -k \, d\xi + [A, \xi] = 0\} / (\xi, A) \mapsto (\text{Ad}_g \xi, k \, dg \, g^{-1} + gAg^{-1}).$$

We will now solve the moment map equation with the assumption that $k \neq 0$. We will scale $k = 1$, so the equation becomes

$$d\xi + [A, \xi] = 0.$$

This is a first order matrix differential equation with periodic coefficients which can be studied using Floquet-Lyapunov theory. This says that there exists g such that

$$g^{-1} \, dg + g^{-1} A g \in \mathfrak{t} \subset \mathfrak{g}$$

is constant and lies in a maximal Cartan of \mathfrak{g} . What this means is that we can write

$$\xi(t) = G(t) \xi_0 G(t)^{-1} \quad G(t) = P \exp \int_0^t A.$$

These satisfy the equations $\dot{G}G^{-1} = A$ and $G(0) = 1$. The monodromy is

$$G_A := G(2\pi) = P \exp \int_0^{2\pi} A.$$

This must commute with ξ_0 , so we can bring

$$A \mapsto g^{-1} \, dg + g^{-1} A g \quad G_A \mapsto g(0)^{-1} G_A g(0).$$

Recall that G_A can be brought to $T \subset G$ and A can be brought to $\alpha \in \mathfrak{t}$ and $g_A = \exp(2\pi\alpha)$. There is still some remaining symmetry by

$$g(u) = \exp(u\lambda),$$

where $\lambda \in \Lambda^\vee$ is in the lattice of coroots and $u \in S^1 = \mathbb{R}/2\pi\mathbb{Z}$ is the coordinate. This shifts $\alpha \mapsto \alpha + \lambda$ while preserving monodromy. The second kind of remaining symmetry is the Weyl group $W := N(T)/T$. Taking their semidirect product, we obtain the *affine Weyl group*.

If we consider the weight space decomposition of the moment map equation and β is a root of \mathfrak{g} , then the equation for this component is

$$d\xi_\beta + \langle \beta, \alpha \rangle \xi_\beta = 0.$$

Because $\xi_\beta(u) = e^{-u\langle \beta, \alpha \rangle}$, this is generically not 1, so $\xi_\beta = 0$. Therefore $\xi \in \mathfrak{t}$, and we obtain

$$T^*\widehat{\mathfrak{g}} // LG = (T^*T)/W.$$

Note that T parameterizes conjugacy classes of $P \exp \oint A$ and that $T = \mathfrak{t}/\Lambda^\vee$. Unfortunately, the reduced space is an orbifold, not a manifold.

We will now attempt to remedy this situation by modifying the quotient. Instead of setting the moment map to be 0, we want to consider an orbit. We want $\mathcal{O} = \mathbb{P}^{N-1}$, and if $G = \mathrm{SU}(N)$, LG acts on \mathbb{P}^{N-1} by evaluation at some $0 \in S^1$. We choose $z \in \mathbb{C}^N$ such that $z^\dagger z = N$ up to $z \sim ze^{i\alpha}$, and the modified equation is

$$d\xi + [A, \xi] = \delta(u) \cdot (i\nu(1_N - z \circ z^\dagger)).$$

Remark 1.5.1. While most of the orbits are infinite dimensional, we are taking some limit where A becomes a distribution on S^1 supported on finitely many points.

We first apply Floquet-Lyupanov to make $A = \mathrm{diag}(a_1, \dots, a_N)$ diagonal with $\sum a_i = 0$. Then on each coordinate we obtain

$$\begin{aligned} d\xi_{ij} + (a_i - a_j)\xi_{ij} &= \sqrt{-1}\delta(u)\nu(-z_i\bar{z}_j) \\ d\xi_{ii} &= \sqrt{-1}\nu(1 - |z_i|^2)\delta(u). \end{aligned}$$

Because $\xi_{ii}(+0) = \xi_{ii}(2\pi - 0) = \xi_{ii}(-0)$ for any $0 \in S^1$, $|z_i|^2 = 1$. Using the maximal torus, we may force $z_i = 1$. Then we obtain

$$\begin{aligned} \xi_{ij}(u) &= e^{-u(a_i - a_j)}\xi_{ij}(+0) \\ \xi_{ij}(2\pi - 0) &= e^{-2\pi(a_i - a_j)}\xi_{ij}(+0) = \xi_{ij}(+0) + \sqrt{-1}\nu. \end{aligned}$$

Finally, the initial value is

$$\xi_{ij}(+0) = \frac{\sqrt{-1}\nu}{e^{-2\pi\sqrt{-1}(a_i - a_j)} - 1}.$$

Note that this appeared in our study of the Sutherland system.

Quantum mechanics

2.1 Quantization

The motivation for complexification of our systems is quantization. Recall that if S is the action of a Lagrangian system, many systems are not described by solving the variational equation

$$\delta S = 0$$

but by meditating on formal path integrals (due to Feynman)

$$\int_{\mathcal{P}\mathcal{P}} e^{\frac{iS[\gamma]}{\hbar}} [\mathcal{D}\gamma].$$

The classical system is obtained via stationary phase approximation. Mathematically, this is ill-defined, but if X is a finite-dimensional manifold, we can consider oscillating integrals

$$I = \int_X e^{\frac{iS}{\hbar}} \mu.$$

Here, X is one of many possible cycles in the complexification $X^{\mathbb{C}}$ and μ is viewed as a holomorphic top-degree form, so this is just a period. If $\dim X = n$, then we may consider other Γ such that

$$\int_{\Gamma} e^{\frac{iS}{\hbar}} \mu$$

converges. These will satisfy

$$\Gamma \in H_n(X^{\mathbb{C}}, X_{\ll}^{\mathbb{C}}),$$

where

$$X_{\ll}^{\mathbb{C}} = \left\{ z \mid \operatorname{Re} \left(\frac{iS(z)}{\hbar} \right) \ll 0 \right\}$$

is set to force the integral to converge. These Γ are chosen to flow from critical points of S (equivalently, of $W = iS$) in $X^{\mathbb{C}}$ into $X_{\ll}^{\mathbb{C}}$. We can construct cycles using *Lefschetz thimbles*. We can choose a critical point p which satisfies $dW(p) = 0$ and then consider the steepest descent flow for $\operatorname{Re} \left(\frac{W}{\hbar} \right)$, or in other words

$$\dot{x} = -\nabla \operatorname{Re} \left(\frac{W}{\hbar} \right),$$

where the gradient is taken with respect to some metric on $X^{\mathbb{C}}$, and finally take the union Γ_p of descending trajectories. If we choose a Hermitian metric, then $\text{Im}\left(\frac{W}{\hbar}\right)$ is actually constant. For a generic choice of \hbar , the critical points have different imaginary parts, but in the special settings we may have Stokes phenomena and wall-crossing behavior of solutions.

Exercise 2.1.1. What happens for $W = \sum_{i=1}^n z_i^2$?

2.2 Holomorphic symplectic dynamics

Now let $M^{\mathbb{C}}$ be a holomorphic symplectic manifold and consider $\mathcal{X}^{\mathbb{C}} = \text{Maps}(S^1, M^{\mathbb{C}})$ and

$$W = \int p \, dq - \beta H(p, q) \, dt.$$

We will take $S^1 = \mathbb{R}/\mathbb{Z}$ and we want to find points with $dW = 0$.

Remark 2.2.1. When we quantize everything, we will obtain

$$\text{Tr} e^{-i\beta \hat{H}} = \int e^{\frac{iS}{\hbar}} [\mathcal{D}\gamma].$$

We obtain the equations

$$\begin{aligned} \frac{dp}{dt} &= -\beta \frac{\partial H}{\partial q} \\ \frac{dq}{dt} &= \beta \frac{\partial H}{\partial p} \end{aligned}$$

If β is real, this is the usual Hamiltonian dynamics, but there may not be real solutions if β is not real. On the other hand, if $\beta = i\beta_E$ is purely imaginary (also known as *going to Euclideaen time*), then there may be solutions where q is real and p is purely imaginary.

Example 2.2.2. Let $M = \mathbb{R}^2$ and

$$U(q) = \frac{\lambda}{4}(q^2 - a^2)^2,$$

where λ, a are parameters. This is usually called the *Higgs potential*. Then the energy is

$$E = \frac{p^2}{2} + U(q).$$

We can see that there is a $q \mapsto -q$ symmetry, so near $\pm a$ there are two copies of the same physics. After complexifying, we obtain $M^{\mathbb{C}} = \mathbb{C}^2$, while the zero set C_E of E is a Riemann surface. If we compactify, we will obtain an elliptic curve with the hyperelliptic form

$$\begin{aligned} p^2 &= 2 \left(E - \frac{\lambda}{4}(q^2 - a^2)^2 \right) \\ &= -\frac{\lambda}{2}(q^2 - a_+^2)(q^2 - a_-^2). \end{aligned}$$

Note that $H_1(C_E, \mathbb{Z}) = \mathbb{Z} \oplus \mathbb{Z}$, so there are two independent cycles corresponding to classically allowed physics. Also, it is clear that

$$a_{\pm}^2 - a^2 = \pm \sqrt{\frac{4E}{\lambda}}.$$

Therefore, this family degenerates to a union of two copies of \mathbb{P}^1 when $E = 0$ (and one of our distinguished cycles is the vanishing cycle) and has another critical point when $E = \frac{\lambda a^4}{4}$. Now $\omega = \frac{dq}{p}$ is a holomorphic differential on C_E , and the Hamilton equation tells us that any

$$\gamma: S^1 \rightarrow C_E \rightarrow M^C$$

must satisfies $\gamma^* \omega = \beta dt$. Now in the low-energy region, $[\gamma] \in H_1(C_E, \mathbb{Z})$ can be specified by two integers:

$$[\gamma] = m[A] + n[B],$$

where $[A]$ is the vanishing cycle and $[B]$ satisfies $A \cap B = 1$. Note B is described up to multiples of A , so n is well-defined, but m is defined only up to multiples of $2n$. We can then find β by the period integral

$$\begin{aligned} \beta &= \int_{S^1} \gamma^* \omega \\ &= \int_{\gamma(S^1)} \omega \\ &= m \oint_A \omega + n \oint_B \omega, \end{aligned}$$

which are functions of E . Therefore, the $E = E_{m,n}(\beta)$ for $n \in \mathbb{Z}, m \in \mathbb{Z}/2n\mathbb{Z}$ satisfy a transcendental equation

$$\beta = m\omega_A(E) + n\omega_B(E).$$

We can solve this equation approximately in the $\beta \rightarrow \infty$ limit, where

$$E_{m,n} \approx \frac{\lambda a^4}{4} e^{-\frac{\beta \Omega}{n}} e^{\pi i \frac{m}{n}},$$

where $\Omega^2 = 2\lambda a^2$ is the classical period of very small oscillations around the $q = a$ critical point. This is all obtained by Picard-Lefschetz theory using the fact that

$$\begin{aligned} \omega_B(E) &\sim \frac{2\pi}{\Omega} \frac{1}{\pi i} \log E + \dots \\ \omega_A(E) &\sim \frac{2\pi}{\Omega} + \dots, \end{aligned}$$

where the $+\dots$ can be computed using knowledge of elliptic integrals. The solution where $n = 0$ corresponds to classical physics, while the solution where $m = 0$ corresponds to tunneling between the two critical points. Therefore, the general (m, n) solution is some superposition of classical motion and tunneling.

2.3 Algebraic integrable systems

We will now consider the class of systems which generalize the following feature of the previous example: our manifold $(M_{\mathbb{C}}^{2n}, \omega_{\mathbb{C}})$ has a Lagrangian fibration $M^{2n} \rightarrow B^n$ to some open subset of \mathbb{C}^n by polarized abelian varieties. These are called *algebraic integrable systems*. This structure gives the structure of special Kähler geometry on B^n .

For us, a polarization is simply an integral class $t \in H^2(F, \mathbb{Z})$, where $F = \pi^{-1}(b)$. We will now define action variables $(a^i, a_{D,i})$ on B . If we have $\gamma \in H_1(F_b, \mathbb{Z})$, this path can be transported

canonically over paths connecting b to b' that avoid the discriminant locus Ξ . We now obtain a 2-chain in M^C covering the path, and we can obtain a number

$$a_\gamma(b') - a_\gamma(b_*) = \int_{2\text{-chain}} \omega^C$$

for a distinguished choice of b_* . Therefore, we obtain a map

$$a: \widetilde{B^n \setminus \Xi} \rightarrow H^1(F_{b_*}, \mathbb{C}),$$

where $\widetilde{B^n \setminus \Xi}$ is the space of choices (b, γ) , where $b \in B^n \setminus \Xi$ and γ is a path connecting b_* to b in $B^n \setminus \Xi$ up to homotopy. The image of a is a Lagrangian with respect to t , where if A_i, B^j is a basis of 1-cycles in $H_1(F_{b_*}, \mathbb{Z})$, then $t(A_i \cap B^j) = \delta_i^j$. Now because

$$\sum_{i=1}^n da^i \wedge da_{D,i} = 0,$$

locally there exists $\mathcal{F}(a)$ such that

$$a_{D,i} = \frac{\partial \mathcal{F}}{\partial a_i}.$$

Definition 2.3.1. This \mathcal{F} is called a *prepotential*.

Example 2.3.2. One example is the *elliptic Calogero-Moser system*. Here, let E be an elliptic curve parameterized by $\tau \in \mathcal{H}$ and consider

$$M^C = (T^*E^n \setminus \Delta)/S(n).$$

Then let p_i be the coordinates in the fiber directions and z_i be the coordinates on the copies of E and define

$$H_1 = \sum_i p_i$$

$$H_2 = \sum_i \frac{1}{2} p_i^2 + v^2 \sum_{i < j} \wp(z_i - z_j).$$

This was proven to be an algebraic integrable system by Krichever (before algebraic integrable systems were defined). Set

$$L(z) := \text{diag}(p_1, \dots, p_n) + v(1 - \delta_{ij}) \frac{\theta(z_i - z_j + z)\theta'(0)}{\theta(z_i - z_j)\theta(z)},$$

where the theta function is defined by

$$\theta(z) = q^{\frac{1}{8}} (e^{\pi iz} - e^{-\pi iz}) \prod_{n=1}^{\infty} (1 - q^n)(1 - q^n e^{2\pi iz})(1 - q^n e^{-2\pi iz}).$$

Here, we make the usual substitution $q = e^{2\pi i \tau}$. This operator satisfies the equations

$$L(z+1) = L(z)$$

$$L(z+\tau) = gL(z)g^{-1}$$

and has an expansion of the form

$$L(z) \sim \frac{\gamma}{z}(1 - \delta_{ij}).$$

Therefore, the spectrum of $L(z)$ forms an n -sheeted cover over E , and in T^*E , if $g(C) = n$, then

$$C \sim n[E] + [F].$$

Then we will obtain a Lagrangian fibration where the fiber is the Jacobian $\text{Jac}(C)$.

2.4 How to compute some path integrals exactly

Recall our setting of a symplectic manifold with Hamiltonian (M, ω, H) . We will assume that there is an action of $T \cong U(1)^r$ with moment map $\mu: M \rightarrow \mathfrak{t}^*$. We will also assume that H is linear in the moment map, so

$$H = \langle \mu, \xi \rangle.$$

Example 2.4.1. Consider $M = \mathbb{R}^{2n}$ with Darboux coordinates p_i, q_i , the standard action of $U(1)^n$, and moment map given by

$$\mu_j = \frac{1}{2}(p_j^2 + q_j^2).$$

Then the Hamiltonian

$$H = \sum_{i=1}^n \xi_i \mu_i$$

generates an action $\mathbb{R} \hookrightarrow T$ which is dense for generic ξ .

If we now assume that M is compact and the fixed points of the T -action are isolated, then to obtain the statistical-mechanical partition function for some inverse temperature β , we have the *Duistermaat-Heckman* formula

$$\begin{aligned} Z(\beta) &= \int_M \frac{\omega^n}{n!} e^{-\beta H} \\ &= \sum_{dH_p=0} \frac{e^{-\beta H(p)}}{\beta^n \prod_{i=1}^n \langle m_i(p), \xi \rangle}, \end{aligned}$$

where $m_i(p)$ are the weights of the T -action on $T_p M$. With these weights, H near p behaves like

$$H = H(p) + \frac{1}{2} \sum_{i=1}^r \xi_i \sum_{j=1}^n m_{ij} (p_j^2 + q_j^2).$$

Example 2.4.2. If $M = S^2$ and $H = \cos \theta$ is the cosine of the azimuthal angle, we embed $M \subset M_{\mathbb{C}} \cong T^*S^2$, and the contour corresponding to the south pole goes into the cotangent directions.

The Duistermaat-Heckman formula can be stated in the setting of T -equivariant cohomology. If G is a Lie group acting on M , we will consider the Cartan model of equivariant cohomology.

$$\Omega_G^*(M) := \text{Fun}(\mathfrak{g}, \Omega^*(M))^G,$$

where we require that

$$f(\text{Ad}_{g^{-1}} \xi) = g^* f(\xi).$$

The grading on differential forms is deformed to be

$$2\xi \frac{\partial}{\partial \xi} + \deg_{\Omega_{\text{DR}}^*}.$$

Then the equivariant differential is defined by

$$D = d_{\text{DR}} + \iota_{V(-)},$$

where $V: \mathfrak{g} \rightarrow \text{Vect}(M)$ is a linear map. We can now compute

$$D^2 = \text{Lie}_{V(-)} = 0,$$

so we set $H_G^*(M)$ to be the cohomology of this complex. We can now compute equivariant integrals of $f \in \Omega_G^*(M)$. Note that $\int_M f \in \text{Fun}(\mathfrak{g})^G$ and

$$Z(\xi) = \int_M f_{\text{top}}(\xi) = Z(\text{Ad}_g \xi)$$

for all $g \in G$. Also note that

$$\int_M (D\psi) = \int_M d\psi = 0.$$

We will now prove the Duistermaat-Heckman formula. If $\mu: M \rightarrow \mathfrak{g}^*$ is the moment map, we claim that

$$D(\omega + \mu(-)) = 0.$$

This follows from the definition of the moment map. We then see that

$$D(\exp(\omega + \mu(-))) = 0,$$

and this is actually a Duistermaat-Heckman integral. If the G -action is free (and G is compact), then every closed form is exact. Because G is compact, there exists a G -invariant metric. Assuming that $G = T$ for now, choose some generic $\bar{\xi} \in \text{Lie } T$. Then define

$$\alpha = g(V(\bar{\xi}), -) \in \Omega^1(M).$$

We then obtain

$$D\alpha = g(V(\bar{\xi}), V(\xi)) + 2\text{-form}$$

where the function part is nonzero, and finally if

$$\psi = \frac{\alpha}{D\alpha} f,$$

we obtain $f = D\psi$ whenever $Df = 0$. Now we can replace the integral in the Duistermaat-Heckmann formula with

$$\int M_\epsilon + \sum_p \int_{B_\epsilon(p)},$$

where $M_\epsilon = M \setminus \bigcup_p B_\epsilon(p)$, and finally use Stokes' theorem to obtain the desired result.

2.5 Infinite-dimensional generalizations and supersymmetry

Now suppose that $M = LN$, where (N, g) is a Riemannian manifold. Then define for $\xi, \eta \in T_\rho M = \Gamma(S^1, \rho^*TN)$, we can define a 2-form by

$$\omega(\xi, \eta) = \int_{S^1} g(\xi, \nabla_t \eta) dt,$$

where ∇_t is the Levi-Cevita connection. The Hamiltonian that generates the standard S^1 -action is

$$H = \int g(\dot{\rho}, \dot{\rho}) dt.$$

Then the partition function of supersymmetric quantum mechanics on N (index of the Dirac operator on N) is given by

$$\int_{LN} e^{\omega - \beta H} = \int_N \hat{A}(TN),$$

where \hat{A} is the \hat{A} -genus. The term on the right should be viewed as the contribution of non-isolated components of the fixed locus and can be thought of as Fourier modes of infinitesimal loops. Of course, there is the question of the role of β in this formula.

2.5.1 The Dirac operator First, associated to the metric $g|_{T_x N}$ we have the Clifford algebra, which is generated by symbols \not{v} for $v \in T_x N = V$ with the relation

$$\not{v} \cdot \not{u} + \not{u} \cdot \not{v} = g(u, v)1.$$

This is the analogue of the Heisenberg-Weyl algebra over a symplectic vector space (W, ω) , which is generated by elements \hat{w} for $w \in W$ with the relation

$$\hat{w}_1 \cdot \hat{w}_2 - \hat{w}_2 \cdot \hat{w}_1 = \omega(w_1, w_2) \cdot 1.$$

The Clifford algebra Cl has irreducible representations, which are called *spinors*. If we choose an orthonormal basis $\{e_i\}$ of V , we can write any element as

$$\alpha + \sum_i \beta_i \not{e}_i + \sum_{i < j} \gamma_{ij} \not{e}_i \not{e}_j + \cdots$$

In addition, we see that the Clifford algebra relation is a deformation of the exterior algebra, so $Cl \cong \Lambda^* V$ as \mathbb{R} -vector spaces. The space of quadratic elements of the Clifford algebra is in fact $\text{Lie } O(V)$. Because $O(V)$ is not simply connected, representations of its Lie algebra integrate to $\text{Spin}(V)$, which is the universal cover of $SO(V)$ (at least if $\dim V > 2$). The group-like elements take the form

$$g = \exp \frac{1}{2} \sum_{i < j} \gamma_{ij} \not{e}_i \not{e}_j.$$

Now we impose a complex structure compatible with the metric and define

$$\begin{aligned} c_a &= \not{e}_{2a-1} + \sqrt{-1} \not{e}_{2a} \\ c_a^* &= \not{e}_{2a-1} - \sqrt{-1} \not{e}_{2a} \end{aligned}$$

for $a = 1, \dots, \lfloor \frac{\dim V}{2} \rfloor$. These satisfy the relation

$$c_a c_b + c_b c_a = 0.$$

Finally, we define the vector space

$$S := \mathbb{C} |\text{vac}\rangle \oplus \bigoplus_a \mathbb{C} c_a |\text{vac}\rangle \oplus \bigoplus_{a < b} \mathbb{C} c_a c_b |\text{vac}\rangle \oplus \cdots \oplus \mathbb{C} c_1 \cdots c_{\lfloor \frac{\dim V}{2} \rfloor} |\text{vac}\rangle.$$

We impose that $c^* |\text{vac}\rangle = 0$, and in general that c^* moves to the left. We then define $\Gamma = e_{\dim V}$ if $\dim V$ is odd. It satisfies

$$\Gamma^2 = 1, \quad \Gamma c_1 + c_a \Gamma = 0, \quad \Gamma c_a^* + c_a^* \Gamma = 0.$$

From now on, we will assume that $\dim V = 2k$.

Note that S is an irreducible representation of $\mathcal{C}\uparrow$, but recall that $\mathfrak{o}(V)$ is much smaller. It is spanned by elements of the form $c_a c_b, c_a c_b^*, c_a^* c_b^*$. There is a $\mathbb{Z}/2$ -valued conserved charge called $(-)^F$ which is preserved by $\mathfrak{o}(V)$. For S , it is defined by

$$\begin{aligned} F |\text{vac}\rangle &= -\frac{k}{2} |\text{vac}\rangle \\ F(c_{a_1} \cdots c_{a_p} |\text{vac}\rangle) &= p - \frac{k}{2}. \end{aligned}$$

Therefore, we can split

$$S = S_+ \oplus S_-$$

by the parity of the F -charge. Then for any $u \in V$, we have

$$\mathcal{X}: S_{\pm} \rightarrow S_{\mp}.$$

These are called *Dirac matrices*.

Unfortunately, there is not always a global spinor bundle on N . The obstruction is the Stiefel-Whitney class

$$w_2(TN) \in H^2(N, \mathbb{Z}/2).$$

If this is nonzero, then we cannot glue spinors into a vector bundle and thus the manifold N does not have a spin structure. Therefore, we will now assume that $w_2(TN) = 0$. We will now define the *Dirac operator*

$$\not{D}: \Gamma(S_+) \rightarrow \Gamma(S_-)$$

by the local formula

$$\not{D} := \sum_{i=1}^{\dim M} \gamma^i \nabla_i.$$

Here, ∇_i is a spin cover of the Levi-Civita connection and γ^i is the physicist notation for \not{e}_i . We also define \not{D}^* to be the same operator applied to S_- . The symbol of $\not{D}^* \not{D}$ or of $\not{D} \not{D}^*$ is given by the well-known formula

$$\begin{aligned} \sum_{i,j} (\gamma^i \partial_i \gamma^j) (\gamma^j \partial_j) &= \frac{1}{2} \sum_{i,j} (\gamma^i \gamma^j + \gamma^j \gamma^i) \partial_i \partial_j \\ &= \frac{1}{2} \sum_{i,j} g^{ij} \partial_i \partial_j + \cdots \\ &= \Delta + \cdots \end{aligned}$$

Because of the analogy with the Laplacian, the spaces $H_{S_+} = \ker \not{D}$ and $H_{S_-} = \ker \not{D}^*$ are known as *harmonic spinors*. There is a lucky coincidence that if $\hat{H} = \not{D}\not{D}^* + \not{D}^*\not{D}$, then

$$\begin{aligned} \text{Index } \not{D} &= \dim \ker \not{D} - \dim \ker \not{D}^* \\ &= \text{Tr}_{\mathcal{H}_{L^2(S)}} (-1)^F e^{-\beta \hat{H}} \\ &= -\text{Tr}_{L^2(S_-)} e^{-\beta \not{D}\not{D}^*} + \text{Tr}_{L^2(S_+)} e^{-\beta \not{D}^*\not{D}} \end{aligned}$$

for any $\beta > 0$. Note here that working on \mathbb{R}^n ,

$$\text{Tr}_{L^2(S)} e^{-\beta \not{D}\not{D}^*} \approx \text{Tr} e^{\beta \Delta} \approx \int d^n p e^{-\beta p^2} \sim \frac{1}{\beta^{\frac{n}{2}}}.$$

Now suppose that $\psi_{(k)} \in \Gamma(S_+)$ satisfies

$$\not{D}^*\not{D}\psi_{(k)} = \varepsilon_k \psi_{(k)}.$$

Then $\not{D}\psi_{(k)} = \chi_{(k)} \in \Gamma(S_-)$ satisfies

$$\not{D}\not{D}^*\chi_{(k)} = \varepsilon_k \chi_{(k)}.$$

This tells us that

$$\begin{aligned} \text{Tr} e^{-\beta \not{D}^*\not{D}} - \text{Tr} e^{-\beta \not{D}\not{D}^*} &= \ker \not{D} - \ker \not{D}^* + \sum_{k, \varepsilon_k > 0} e^{-\beta \varepsilon_k} - \sum_{k, \varepsilon_k > 0} e^{-\beta \varepsilon_k} \\ &= \text{Index } \not{D}. \end{aligned}$$

Note that this cancellation is our first example of *supersymmetry*. Finally, we take the $\beta \rightarrow 0$ limit.

2.5.2 The heat kernel If we were considering on flat space the ordinary heat kernel

$$K(x, x', \beta) = \langle x | e^{\beta \Delta} | x' \rangle,$$

then $\text{Tr} e^{\beta \Delta}$ is computed by

$$\int_{LN} [Dx(t)] \exp \left(-\frac{1}{2} \int_0^\beta g(\dot{x}, \dot{x}) dt \right).$$

Note that in flat space, the heat kernel must satisfy the PDE

$$\frac{\partial}{\partial \beta} K = \Delta_{x'} K = \Delta_x K.$$

As $\beta \rightarrow 0$,

$$K(x, x', \beta) \rightarrow \delta^{(n)}(x - x').$$

There must also be the integral formula

$$\int dx' K(x, x'; \beta_1) K(x', x''; \beta_2) = K(x, x''; \beta_1 + \beta_2),$$

so in fact, it is given by

$$K(x, x'; \beta) = \exp \left(-\frac{(x - x')^2}{2\beta} \right) \frac{1}{(2\pi\beta)^{n/2}}.$$

In our curved situation, we obtain the limit

$$\lim_{M \rightarrow \infty} \int dx_1 \cdots dx_M K\left(x_1, x_2; \frac{\beta}{M}\right) \cdots,$$

which can be well-approximated by the expression in flat space. Considering instead the loop space LT^*N , we now obtain

$$\int_{LT^*N} [Dx(s)Dp(s)] \exp\left(i \int p dx - \beta \int_0^1 g^{-1}(p, p) ds\right).$$

Note that the $[Dx(s)Dp(s)]$ carries the term $\prod_t \frac{1}{(2\pi\beta)^{\frac{\dim M}{2}}}$. Also, if we integrate out the p , we obtain the previous term

$$\frac{1}{2\beta} \int_0^1 g(\dot{x}, \dot{x}) ds.$$

2.5.3 Supersymmetric Duistermaat-Heckmann We will now rewrite the integral we wanted to compute at the beginning of this section in new notation as

$$\int_{LN} e^{\Omega + \varepsilon H}.$$

Here, we rewrite

$$\begin{aligned} H &= \frac{1}{2} \int_0^1 g(\dot{x}, \dot{x}) ds \\ \Omega &= \frac{1}{2} \int_{S^1} g_{ij} \psi^i \nabla_s \psi^j ds, \end{aligned}$$

where $(\psi^i(s)) \in \Gamma(S^1, \chi^*TN)$. The ψ^i satisfy the formula

$$\psi^i(s) \psi^j(s') = -\psi^j(s') \psi^i(s).$$

Finally, here $\varepsilon = \frac{1}{\beta}$ is the equivariant parameter for the action of $U(1)$ on the cotangent directions.

Now, the Duistermaat-Heckmann normalized integral (which is not the Atiyah-Singer normalized integral) is

$$\begin{aligned} \int_{LN} e^{\Omega + \varepsilon H} &= \int_M \frac{1}{\prod_{n \neq 0} \prod_{\alpha} \left(n\varepsilon + \frac{1}{\varepsilon} \alpha\right)} \\ &= \int_N \prod_{\alpha} \frac{\pi \sigma_{\alpha} / \varepsilon}{\sin(\pi \sigma_{\alpha} / \varepsilon)}, \end{aligned}$$

where $x^i(t)$ splits into Fourier modes as

$$x^i(t) = x_0^i + \sum_{n \neq 0} \xi_n^i e^{2\pi i n s}$$

and thus splits

$$\mathcal{N}_{N/LN} = \bigoplus_{n \neq 0} (TN)_n,$$

and α are the Chern roots of TN . This exactly reproduces the \hat{A} -genus. The Atiyah-Singer normalized integral has an extra factor of $\frac{1}{\prod_s \beta^{\frac{\dim M}{2}}}$.

2.6 Duality

There are two main examples: T-duality in 2d sigma-models and S-duality in 4d gauge theories.

2.6.1 p-form generalized gauge theory We will begin with p-form generalized gauge theory in D spacetime dimensions. For some $A \in \Omega^p(M^D)$, define

$$\mathcal{L} = \int_{M^D} dA \wedge * dA.$$

This is invariant under $A \rightarrow A + dB$. The space of fields in the \mathbb{R} -type theory is given by

$$\mathcal{A}_{\mathbb{R}} = \Omega^p(M^D) / d\Omega^{p-1}(M^D).$$

In the $U(1)$ -type setting, the space of fields is smaller and is given by

$$\mathcal{A}_{U(1)} = \Omega^p(M^D) / \Omega_{\mathbb{Z}}^p(M^D),$$

where $\Omega_{\mathbb{Z}}^p$ is the space of all p-forms α such that

$$\int_{Z^p} \alpha \in \mathbb{Z}$$

for all integral cycles Z^p .

Example 2.6.1. When $p = 0$ and $D = 2$, then the $U(1)$ -type theory describes maps $M^2 \rightarrow U(1)$. Locally, these look like $A: M^2 \rightarrow \mathbb{R}$ such that $A \sim A + n$. Of course, not every manifold is simply connected. Therefore, the true space of fields is

$$\mathcal{A}_{U(1)} = \text{Maps}(M^2, U(1)).$$

This has a decomposition by the topological type as follows. Let $t \in \mathbb{R}$ be a coordinate with

$$\int_{\mathbb{R}/\mathbb{Z}} dt = 1.$$

Then the topological type is given by

$$[f^* dt] \in H^1(M^2, \mathbb{Z}).$$

In general, we will assume that the curvature form dA is not exact, but instead integral, so

$$dA \in \Omega_{\mathbb{Z}}^{p+1}(M^D).$$

This can be achieved on an open cover U_{α} by choosing

$$A_{\alpha} \in \Omega^p(U_{\alpha})$$

such that

$$A_{\beta} - A_{\alpha} \in \Omega_{\mathbb{Z}}^p(U_{\alpha} \cap U_{\beta}).$$

Then the space of fields is the space of connections on all $U(1)$ -bundles and its connected components are parameterized by

$$L = H^{p+1}(M^D, \mathbb{Z}).$$

The partition function is now given by

$$Z = \int_{\mathcal{A}_{U(1)}} [\mathcal{D}A] e^{-\frac{1}{4g^2} \int_{M^D} dA \wedge *dA + \int \theta \wedge dA \wedge dA},$$

where

$$\theta \in \Omega^{D-2(p+1)}(M^D)$$

is a closed form.

We may also replace $f: M^2 \rightarrow U(1)$ by functions

$$f: M^2 \rightarrow T \cong U(1)^n = V/\Gamma.$$

We introduce tensors

$$B \in \Lambda^2 V^*, \quad G \in S_+^2 V^*.$$

In this form, the partition function becomes

$$Z(G, B, h) = \int_{\mathcal{A}_{U(1)}} [\mathcal{D}A] e^{-\int_{M^D} G_{ij} dA^i \wedge *dA^j + \int B_{ij} \wedge dA^i \wedge dA^j},$$

where $dB_{ij} = 0$ and $B_{ij} \in \Omega^{D-2(p+1)}(M^D)$. We also have

$$B \in \begin{cases} \Lambda^2 V^* & p+1 \text{ odd} \\ S^2 V^* & p+1 \text{ even.} \end{cases}$$

We now want to find the critical points of \mathcal{L} , where $\delta\mathcal{L} = 0$. The equations for A become

$$d * dA^i = 0$$

for all i . If we set $F^i := dA^i$, the equation becomes

$$d * F^i = 0,$$

which are the *generalized Maxwell equations*. Therefore, we obtain

$$Z(G, B, h) = \mathcal{N}(G, h) \sum_{c \in \Lambda = H^{p+1}(M^D, \Gamma)} \exp \left[-G_{ij} \langle c^i, *c^j \rangle - i \langle B_{ij} \wedge c^i \wedge c^j \rangle \right],$$

where $\mathcal{N}(G, h)$ is a regularized version of

$$\det_{\Omega^p / d\Omega^{p-1}} (*d * d)^{-\frac{1}{2}}$$

which is defined as follows. Define

$$\zeta_{\Delta^{(p)}}(s) := \text{Tr} \left(-\Delta^{(p)} \right)^{-s}.$$

This is defined for $\text{Re } s \gg 0$, and taking the analytic continuation, we define

$$\mathcal{N}(G, h) := \exp \frac{1}{2} \zeta'_{\Delta}(0).$$

We may need to assume that $D = 2(p+1)$. For example, if $D = 2$, then the $\langle c^i, *c^j \rangle$ term knows only about the conformal structure of M^2 . Finally, $H^{p+1}(M^D, \Gamma)$ is taken modulo torsion.

2.6.2 Duality The duality is given by inverting

$$\tau := iG + B$$

when $D = 4$ and inverting

$$\tau = G + iB$$

when $D = 2$. We may consider transformations of the form

$$\tau \mapsto -\frac{1}{\tau}$$

or more generally

$$\tau \mapsto (C\tau + D)^{-1}(A\tau + B),$$

where

$$\begin{pmatrix} A & B \\ C & D \end{pmatrix} \in \begin{cases} O(n, n, \mathbb{Z}) & D = 2 \\ Sp(2n, \mathbb{Z}) & D = 4. \end{cases}$$

Applying Poisson resummation, we obtain

$$\int_{c \in \Lambda \mathbb{R}} \sum_{\check{c} \in \Lambda^*} e^{2\pi i \check{c}(c)} \exp \left[-\frac{1}{2} G_{ij} \langle c_i, *c_j \rangle + \frac{i}{2} B_{ij} \langle c_i, c_j \rangle \right].$$

Here, we have the identity

$$\sum_j G_{ij} *c^j + \sqrt{-1} B_{ij} c^j + 2\pi \sqrt{-1} \check{c}_i = 0$$

in dimension 2. Note that when $D = 2$, $*^2 = -1$, while when $D = 4$, $*^2 = +1$. In the 4-dimensional setting, if we define

$$c_{\pm} = \frac{c \pm *c}{2},$$

the relation is

$$\tau c_i - \bar{\tau} c_+ + 2\pi \sqrt{-1} (\check{c}_+ + \check{c}_-) = 0.$$

Therefore,

$$c_- = \frac{2\pi \sqrt{-1}}{\tau} \check{c}_-, \quad c_+ = -\frac{2\pi \sqrt{-1}}{\tau} \check{c}_+.$$

The duality must give some reassignment of the degrees of freedom. Locally, if

$$M^D = X^{D-1} \times \mathbb{R},$$

which is noncompact, we must discuss the Hamiltonian system. The phase space is given by the stack

$$T^*[\Omega^p(X^{D-1}, V)/\Omega^p(X^{D-1}, \Gamma)].$$

The symplectic form is given by

$$\int_{X^{D-1}} (\delta E \wedge \delta A_{(p)}) + \int_{X^{D-1}} B_{ij} \wedge \delta(dA^i) \wedge \delta A_{(p)}^j,$$

Here,

$$E \in \Omega^{D-1-p}(X^{D-1}, V^*)$$

is the electric field and dA is the magnetic field. Now we can write the Hamiltonian as

$$\mathcal{H} = \frac{1}{2} \int_X G^{ij} E_i \wedge *E_j + \frac{1}{2} \int_X G_{ij} dA^i \wedge *dA^j.$$

We return to the space of spatial fields \mathcal{A} , which has a decomposition into connected components indexed by

$$c \in H^{p+1}(X^{D-1}, \Gamma)/\text{Tors.}$$

The component corresponding to some c is

$$\mathcal{A}_c = H^p(X^{D-1}, V)/H^p(X^{D-1}, \Gamma),$$

which is the space of flat p -connections.

All of this can be understood via the quantum mechanics of a particle on S^1 . If we define

$$\mathcal{H}_\theta = \left\{ f(t) \mid f(t+2\pi) = e^{i\theta} f(t), \int |f|^2 < \infty \right\},$$

then θ is the analogue of (B_{ij}) . Then if the standard symplectic form on T^*S^1 is given by

$$dE \wedge dt,$$

E^2 quantizes to $-\partial_t^2 = \hat{H}$, and the spectrum of this operator is given by

$$E_n = (n + \theta)^2, \quad n \in \mathbb{Z}.$$

For example, if $E_n = 0$, then n and $-n$ have the same eigenvalues, if $\theta = \frac{1}{2}$, then the spectrum is doubly degenerate, and for any other value of θ the spectrum is simple. Therefore, the duality exchanges the electric and magnetic fields whenever $D = 2(p+1)$.

Instantons

There are three main approaches:

- Morse theory;
- Twisted supersymmetric σ -models;
- Twisted supersymmetric gauge theory.

These have a Hamiltonian and Lagrangian approach, and the latter will motivate the study of integrals on moduli spaces of instantons.

3.1 Morse theory

Note that this is not the same as what topologists call Morse theory. Let (M, g) be a compact Riemannian manifold and $f: M \rightarrow \mathbb{R}$. Suppose all x such that $df_x = 0$ have nondegenerate Hessian, or in other words,

$$\det \left(\frac{\partial^2 f}{\partial x^i \partial x^j} \right) \neq 0.$$

We will consider $\Omega^*(M)$ with the differential

$$D := d + df \wedge: \Omega^*(M) \rightarrow \Omega^{*+1}(M).$$

Using the standard scalar form

$$(\alpha, \beta)_g = \int_M \alpha \wedge * \beta,$$

we define the adjoint

$$D^* = d^* + \iota_{\nabla f}.$$

Physicists refer to the study of this package as *supersymmetric quantum mechanics*. Here, the Hamiltonian is

$$\begin{aligned} H &= DD^* + D^*D \\ &= -\Delta_d + \text{Lie}_{\nabla f} + \text{Lie}_{\nabla f}^* + g(\nabla f, \nabla f). \end{aligned}$$

Note that $\ker H \cong H^*(M)$, and if $H\psi = 0$, then

$$\begin{aligned} 0 &= (\psi, H\psi) \\ &= (D\psi, D\psi) + (D^*\psi, D^*\psi), \end{aligned}$$

so we see that $H\psi = 0$ if and only if $D\psi = D^*\psi = 0$.

There are also excited states where $H\psi_i = E_i\psi_i$ for $E_i > 0$. Then we compute

$$\begin{aligned} HD\psi_i &= DD^*D\psi_i \\ &= D(H\psi_i - DD^*\psi_i) \\ &= D(E_i\psi_i) \\ &= E_i D\psi_i, \end{aligned}$$

so the states $D\psi_i$, $D^*\psi_i$, and $DD^*\psi_i$ are also eigenstates with eigenvalue E_i .

There is then the following trick. If $f \mapsto tf$ and g is fixed for $t \gg 0$, then

$$H = -\Delta_g + t^2 \|\nabla f\|^2 + t(\dots)$$

where $\|\nabla f\|^2$ is a very large potential outside of the critical locus of f . We also have

$$D_t = e^{-tf} de^{tf}$$

on the ground states, which are isomorphic to $H^*(M)$. More generally, we note that

$$\begin{aligned} D_t &= d + t df \wedge \\ D_t^* &= t^{-1} d^* + \iota_{\nabla f}. \end{aligned}$$

Ignoring the $t^{-1}d^*$ term, the Hamiltonian becomes

$$\text{Lie}_{\nabla f} + t \|\nabla f\|^2 = e^{-tf} (\text{Lie}_{\nabla f}) e^{tf}.$$

In the world where $f \mapsto tf$ and $g \mapsto tg$, we obtain states

$$\begin{aligned} \psi &\rightarrow e^{-tf} \psi =: \psi_{\text{out}} \\ \psi &\rightarrow e^{tf} \psi =: \psi_{\text{in}}. \end{aligned}$$

As $t \rightarrow \infty$, we obtain H_{in} and H_{out} , which are distributions.

Example 3.1.1. Now consider $M = \mathbb{R}$ and $f = \frac{\omega x^2}{2}$. Note in this case we need to use L^2 differential forms. Then we have basic operators

$$\begin{aligned} H_0 &:= -\partial_x^2 + \omega^2 x^2 + \omega \\ &= (-\partial_x + \omega x)(\partial_x + \omega x) \\ H^1 &:= -\partial_x^2 + \omega^2 x^2 + \omega \\ &= (\partial_x + \omega x)(-\partial_x + \omega x). \end{aligned}$$

Finally, we set $\alpha = \psi(x) dx$.

The spectrum is given in the following way. If $H\psi = 0$, then the equality $(\partial_x + \omega x)\psi = 0$ implies that $\psi = e^{-f}$, which is fine if $\omega > 0$ and bad if $\omega < 0$. Then suppose there is ψ_n such that $H\psi_n = n|\omega|\psi_n$. Then we obtain

$$\psi_n = \begin{cases} (-\partial_x + \omega x)^n \left(e^{-\frac{\omega x^2}{2}} \right) & \omega > 0 \\ (\partial_x + \omega x)^{n-1} \left(e^{-\frac{\omega x^2}{2}} \right) & \omega < 0. \end{cases}$$

Then if P is a polynomial,

$$P(\partial_x) e^{-t|\omega|x^2} \rightarrow P(\partial_x) \delta(x)$$

as $t \rightarrow \infty$ (here t scales ω). This tells us that $H_{\text{in}}^0 \cong H_{\text{out}}^1$ are regular functions, while eigenstates of H_∞ are monomials. Similarly, $H_{\text{in}}^1 \cong H_{\text{out}}^0$ are distributions supported at $x = 0$, while the eigenstates of H_∞ are those of the form $\partial_x^n \delta(x)$. Observe that

$$H_\infty = \text{Lie}_{x \frac{d}{dx}}.$$

Then, note that $\delta(x) dx$ is an invariant distribution-valued 1-form. The pairing between the in and out states must be the usual pairing between functions and distributions.

In higher dimensions, there will be both attracting and repelling states, so we can consider something like

$$f = \sum_{i=1}^{d-m} \frac{x_i^2}{2} - \sum_{j=d-m+1}^d \frac{x_j^2}{2}$$

and i the end ψ_{in} is a distribution supported on the attracting manifold. This concludes the study of the local picture.

However, we must consider the compact picture. For example, consider $S^1 = \mathbb{R} \cup \infty$ where the Morse function f is attracting at $x = 0$ and repelling at $x = \infty$. Then near ∞ , the states corresponding to monomials will look like $P.V. x^n$. Applying $x \frac{d}{dx}$ and expanding

$$\psi = \psi_\infty + \frac{1}{x} \psi_\infty^{(1)} + \cdots + \frac{1}{x^{n+1}} \psi_\infty^{(n+1)} + \cdots,$$

then the scaling $x \rightarrow tx, \varepsilon t \rightarrow \varepsilon$ gives us correction terms of $\log \varepsilon$ and $\log t$ to $\psi_\infty^{(n+1)}$. Here, the principal value

$$(x^n, \psi) = P.V. \int_{\mathbb{R}} x^n \psi dx$$

is the finite part in the ε -expansion of

$$\int_{-\frac{1}{\varepsilon}}^{\frac{1}{\varepsilon}} x^n \psi dx.$$

Therefore, we see that critical points can talk to each other via excited states.

3.2 σ -models

We will consider maps $\Sigma \rightarrow (X, \omega)$ from a Riemann surface to a symplectic manifold. We will also choose an almost complex structure J which is tame with respect to ω . If we consider the functional

$$S = \frac{1}{2} \int_{\Sigma} g(d\phi, *_h d\phi) + i \int_{\Sigma} \phi^* \omega,$$

its critical points are simply harmonic maps.

In the Hamiltonian formalism, consider $M = LX$. If $\xi \in T_{\ell} LX$, then

$$df(\xi) = \int_{S^1} \omega(\xi, \dot{\ell}).$$

Note that

$$g(d\phi, *d\phi) = \omega(Jd\phi, *_h d\phi)$$

and

$$d\phi = \frac{1+iJ}{2} d\phi + \frac{1-iJ}{2} d\phi.$$

Then S can be rewritten as

$$S = \int \phi^*(\pm\omega + iB) + \left\| \frac{1-iJ}{2} (\partial \text{ or } \bar{\partial}) \phi \right\|^2,$$

where B is the B-field, satisfying $dB = 0$. Therefore, the absolute minima are solutions to the PDE

$$\frac{1-iJ}{2} \bar{\partial} \phi = 0.$$

Example 3.2.1. Consider $X = \mathbb{R}^2$ with the standard symplectic form and complex structure. Let

$$f = \int_{S^1} p dq.$$

Let t be the loop variable and s be the noncompact direction. Then we obtain the equations

$$\begin{aligned} \frac{dp}{ds} &= -\frac{\delta f}{\delta p} = -\frac{dq}{dt} \\ \frac{dq}{ds} &= -\frac{\delta f}{\delta q} = -\frac{dp}{dt}, \end{aligned}$$

which are the Cauchy-Riemann equations. If $z = s + it$ and $w = \exp(z)$, the Cauchy-Riemann equations give

$$\bar{\partial}_{\bar{z}}(q + ip) = 0.$$