CAV Energy and Demand Decomposition at the Aggregated National Level

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A compact and aggregated model of road vehicle travel and energy use is constructed to consider the interactions of multiple relevant identified mechanisms (Wadud et al. 2016, Stephens et al. 2016) by which automation can alter efficiency and activity. Travel demand and vehicle use derives from a standard utility-theoretic specification of driver/traveler behavior. Vehicle efficiency, travel (vehicle-kilometers traveled), average travel speed, congestion, and travel time are endogenous. Following Small and Verhoef (2007) and others, utility derives from travel, aggregate goods consumption, and liesure, subject to individual budget and time constraints.

Table of Contents

[1. Introduction, Main Points, Key Factors 2](#_Toc454909)

[2. Decomposition of Energy and GHG Impacts of CAVs 4](#_Toc454910)

[Mechanisms by Which CAVs Can Alter Energy Use and Emissions 7](#_Toc454911)

[3. Estimating Energy Impacts 7](#_Toc454912)

[3.1 Construct multiplicative factors to apply to energy intensities for each mechanism 7](#_Toc454913)

[3.2 Energy Intensity by Vehicle Type and Technology Scenario, by Composing Mechanism Effects 9](#_Toc454914)

[4. Demand Response to CAVs 11](#_Toc454915)

[4.1 Key parameters for Demand scenarios 11](#_Toc454916)

[Select a Single Scenario to Examine 12](#_Toc454917)

[4.2 Establish Base Travel Costs for Each Cost Component 13](#_Toc454918)

[Simple Base Travel Time Cost Calculation 13](#_Toc454919)

[Base (Conventional) Vehicle Travel Cost Components 14](#_Toc454920)

[Base Vehicle Travel Cost Shares by Component 14](#_Toc454921)

[4.3 Cost Changes and Fractional Increase in VKT for Demand Scenarios 16](#_Toc454922)

[Demand Scenarios Driven by Cost Reduction Parameters and Demand Response Parameters 16](#_Toc454923)

[CAV Scenario Vehicle Travel Cost Shares by Component 17](#_Toc454924)

[4.4 Calculate Adjusted Travel Cost Components for Scenario Conditions 18](#_Toc454925)

[Display Alternative Scenario Travel Costs per Mile by Component 20](#_Toc454926)

[4.5 Fractional VMT Changes in CAV Scenario 28](#_Toc454927)

[Effects on VMT Demand from Underserved Population, and Ride Hailing & Pooling 29](#_Toc454928)

[5. Policy and Scenario Calculations 30](#_Toc454929)

[5.1 Final Scenario Results Table for 2050 36](#_Toc454930)

[5.2 Bar Chart Representation of Results 38](#_Toc454931)

[5.3 Travel Time Budget 38](#_Toc454932)

[5.4 Physical Constants 39](#_Toc454933)

[5.5 Vehicle Scenario Parameters 39](#_Toc454934)

[6. Simple functions for MPG as a function of highway speed 39](#_Toc454935)

[6.1 Fuel Consumption vs. Speed - Thomas et al. Approach 39](#_Toc454936)

[6.2 Fuel Consumption vs Speed - Berry Approach 40](#_Toc454937)

[6.3 Compute the Optimum Highway Speed for a Range of Time Costs and Fuel Costs 40](#_Toc454938)

[7. Safety Costs Associated with Speed 40](#_Toc454939)

[7.1 Severity of crash injuries 42](#_Toc454940)

[7.2 Speed and Accident Risk 43](#_Toc454941)

[8. Simple Examination of VMT and PMT Given Pooling 44](#_Toc454942)

[References 46](#_Toc454943)

# 1. Introduction, Main Points, Key Factors

#### Goals for and Potential value of compact/aggregate model:

* explore affects of costs and tecnological progress on outcomes
* determine minimum cost to achieve some level of energy use and level of mobility
  + large simulation models would have to do many simulations
* approximate influence of some factors not yet in detailed ABM/Microsimulation models
* simulate effect of changing costs from technological advances through vehicle automation, electrification, and sharing.

#### Important factors driving energy and travel outcomes have an economic dimension

* Demand response to automation and shared mobility
  + consumer behavior model drives demand response
  + particularly, following Small & Verhoef, others, consumer behavior model determines choice of travel VKT, vehicle efficiency, and travel time
  + In our formulation, consumer utility derives from travel, goods, leisure.
  + Utility maximization is subject to joint constraints on budget and time.
* Endogenous interactions (identified, in development)
  + Speed - (highway free-flow) endogenous to trade-off between energy cost, time and safety costs
  + Congestion – (determines average achieved speed in traffic) endogenous to vehicle mix, VKT, automation
  + Travel demand - endogenous to costs, including energy, congestion and safety, as well as travel time utility (VTT)
  + Ride-hailing and pooling - Distinguish between VKT and PKT, given ride-hailing and ride-pooling
    - Compact representation of ride pooling choice
* CAV fuel efficiency follows one of three models
  + The technically feasible case
    - This provides an upper bound on achieved fuel savings, assuming system optimization with respect to energy.
  + CAFE-binding case
    - AVs achieve same MPG as CAFE average, counting some off-cycle benefits. AVs thus have similar intensity as MVs.
  + Cost-effective case
    - AVs may be more efficient than standard, *if* further efficiency reductions are cost-effective from a private perspective

#### Key Questions (in order of attention paid here)

* How may vehicle fuel intensity/economy change?
  + [technical and behavioral factors]
  + [dependence on infrastructure, and degree of penetration]
* How will travel demand change?
  + See EEMS2017 study of travel demand for different VOTT reports 30-50% increase in energy, mostly from demand, depending on VOTT
    - [ToDo: see what this implies for VKTDemandElas]
  + Travel patterns - details omitted
    - Impact: Trip chaining patterns
    - Impact: detailed drive cycle changes (power use over different segments of trip, from detailed traffic interactions and speed changes)
* What are the implications of shared-mobility for energy use and VKT?
  + Important to differentiate shared vehicles (aTaxi or *ride-hailing*) and shared rides (*ride-pooling*)
  + Model through occupancy, incremental VKT from re-positioning, and implications to travelers’ cost
* To what extent can CAVs enable fuel switching or electrification?
* How/when will CAVs be adopted? (not addressed endogenously)
* What are the special challenges of the transitional period, when a mix of manual, partially automated, and automated vehicles will share the roadways? (not addressed)
* HDV Automation: travel demand and energy intensity implications
  + Restricted focus on long-distance HD trucking

#### Contributions of this paper

This paper describes a new aggregated framework, building on established travel demand literature, that accounts for key features of vehicle automation, and estimates demand and energy use implications. Unlike prior known aggregate work, which relied largely on fixed-coefficient scenario analysis or accounting, it integrates technological and economic factors, including fuel, vehicle and other travel costs, and incorporates energy and travel behavior responses to economic incentives. This work abstracts from much detail offered by micro and meso-simulation models, which estimate travel and energy implications of specific AV technologies using agent/micro/mesosimulation of travel and traffic in real-world spatial and road network models (MATSIM, BEAM, POLARIS, others). The aggregate approach here complements that evolving work and seeks to incorporate some of the insights from that detailed spatial travel modeling. Our framework also is novel in the integration of a utility-based behavioral framework with technological detail and private and public costs, emphasizing the role of financial incentives in the form of costs, fees or taxation/subsidy of transport energy or road use. It extends the private utility maximization framework for travel behavior of Small and Parry 2005, Small and Verhauf 2007, and Leiby and Rubin 2017, combining it with the vehicle efficiency and automated vehicle technological details of Wadud et al 2016. It seeks to address the important issue of how to promote the mobility and energy benefits of CAV technologies while deterring potential adverse outcomes (congestion, emissions) that can have large unaccounted social costs.

#### Limitations

* An incomplete consideration of role of AV safety and its endogenous effect on travel costs and travel behavior.
* One necessary limitation is the abstraction and aggregation of potentially important detail, as discussed above. The approach here includes only an approximate aggregate representation of the effects of particular AV technologies and systems on vehicle energy use for specific drivetrains, roadway networks, traffic conditions, and drivecycles. These particular and specific results can be modeled in more detailed vehicle and spatial models such as Autonomie, FASTSim, BEAM/POLARIS, etc. Consumer heterogeneity is not explicitly represented. Local/spatially-explicit outcomes and interactions modeled elsewhere must be subsumed within aggregate, regional outcomes.

# 2. Decomposition of Energy and GHG Impacts of CAVs

The energy and GHG emissions of CAV transportation result from the interaction of a wide range of mechanisms, including the impact of vehicle technologies and vehicle design changes on vehicle operations and efficiency; system-level changes in infrastructure that alter traffic coordination, speeds, and patterns; and consumer behavioral responses that determine the number, length, and nature of trips demanded. An aggregate representation of the composition of the effects of many of these mechanisms can be conveniently accounted with a *Kaya Identity*, as used in transportation emissions by (McCollum & Yang, 2009, Greene and Plotkin, 2011) or equivalently the *Schipper ASIF framework* (Schipper et al. 2000, 2011). Mechanistic and scenario-base approaches of this type have been used to explore CAV impacts by Wadud, MacKenzie and Leiby (2016) and by Stephens et al. 2016. While this approch assumes a degree of separability in the impact of certain identified mechanisms on energy use, e.g. weight reduction versus aerodynamic load reduction through platooning, this is supported in some cases by more detailed models and experimental data [cite XXX].

From this *Kaya* or *ASIF* approach the total GHG emissions are the product of

1. the level of **A**ctivity (e.g., passenger miles of travel),
2. the **S**hare of activity for each mode, vehicle, and fuel type,
3. the energy **I**ntensity of the mode and vehicle type (e.g., energy use per vehicle mile), and
4. the **F**uel carbon intensity (ghg emission mass per unit energy)

Energy use for particular vehicle type is given by total activity (travel demand) level , the share of travel on mode *m* and the average share-weighted energy intensity of travel by vehicle type and mode.

Vehicle energy intensity *I* is a function of a vector of CAV mechanism/technology levels.

Transportation GHG emissions are then the sum over all transportation modes, vehicle types, and fuels of the product of {Transportation Services Activity[[1]](#footnote-1)} x {Shares of each mode-vehicle-fuel type} x {Energy Intensity} x {Fuel GHG Intensity}.

Defining indices

* m = transportation mode
* v = vehicle type
* f = fuel type
* t = time period (year)

for sets[[2]](#footnote-2)

* M = set of transportation modes *m*
* V = set of vehicle types *v*
* F = set of fuel types *f*
* T = set of time periods *t*

The variables are

* = the transportation services Activity provided by type (passenger v.s freight, or LDV/HDV) [billion passenger-km or tonne-km traveled/yr]
* = occupancy of each vehicle type v in year t [pass/veh, or PKT/VKT, for passenger travel; tonne/veh for freight]
* = share of energy services in transportation mode m by vehicle type v in year t [unitless]
* = the share of energy-service share produced by fuel type f [unitless]
* = the energy intensity of vehicle v in mode m using fuel type f in year t [MJ/veh-km] ([EJ/Bill veh-km])
* = the GHG intensity of fuel f in year t [g CO2e/MJ (MegaT CO2e/EJ)]
* = energy use in form of fuel f by vehicle type v in year t [EJ/y]
* = GHGs emitted in year t by type v [MT CO2e/y]

Focusing on passenger travel, we can write energy use as

with units

Total Emissions are

Combining, overall total emissions per year are

Alternatively, in the form of a vector expression over vehicle types *v*,

for v x 1, v x f and f x 1. And

In the work here, road travel demand is divided into LDV and HDV (passenger and freight), at the minimum, and can be further decomposed into vehicle size classes, and drivetrain classes.

## Mechanisms by Which CAVs Can Alter Energy Use and Emissions

We identified a set *K* of “Mechanisms” or “Technologies” associated with vehicle automation, each of which has an effect represented by multiplier that can increase or decrease a component term in the ASIF decomposition. In general, a mechanism can affect travel activity levels *A*, vehicle energy intensities *I*, or mode and fuel shares . Furthermore, a mechanism could also effect vehicle class shares or occupancy, but we do not yet consider such effects.

Taking a Scenario Approach, we can construct scenarios *s* that combine technology cases and demand cases . For each scenario values are indexed by year *t* (for selected years), vehicle class *v*, mechanism *k* and by the Combined Technology/Demand scenario *s*, i.e. ???.

The current set of mechanisms *k* represented include: Platooning, De\_emphasized\_performance, Improved\_crash\_avoidance, Right-sizing, Eco\_driving, Congestion\_mitigation, Increased\_feature\_load, Higher\_highway\_speeds. We consider vehicle classes *v* in LDV, HDV. The model is explored over time for years *t* from 2035 to 2050.

# 3. Estimating Energy Impacts

We define the effects of automation on vehicle energy intensity (energy per vehicle km traveled) through a set of identified technological and operational “mechanisms.”

The estimation for the midcase energy intensity impacts of each mechanism is based on literature review[[3]](#footnote-3) and the external calculations of the authors. Ranges of values, for sensitivity cases and scenarios, are constructed for each mechanism *k*, for effect sensitivity cases *s* from “zero” through “pessimistic,” “midcase,” and “optimistic.” Mechanism intensity effect values indicate the fractional change in energy intensity for a particular mechanism *k*, and are differentiated by year *t*, vehicle class *v*, and effect sensitivity *s*.

### 3.1 Construct multiplicative factors to apply to energy intensities for each mechanism

From the fractional changes in energy intensity, multipliers are constructed to apply for each mechanism/technology *k*, year *t*, vehicle class *v*, and effect sensitivity case *s*.

A multiplier value of 1.0 indicates no change and less/greater than one implies a multiplicative reduction/increase in energy intensity.

Intensity Multipliers by Vehicle-type, Year, and Case

|  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- |
| VC | Year | Mech | Opt | Mid | Pess | Zero |
| LDV | 2035 | Congestion\_mitigation | 0.966 | 0.9830 | 1.000 | 1 |
| LDV | 2035 | De\_emphasized\_performance | 0.770 | 0.8600 | 0.950 | 1 |
| LDV | 2035 | Eco\_driving | 0.800 | 0.8750 | 0.950 | 1 |
| LDV | 2035 | Higher\_highway\_speeds | 1.070 | 1.1450 | 1.220 | 1 |
| LDV | 2035 | Improved\_crash\_avoidance | 0.771 | 0.8580 | 0.945 | 1 |
| LDV | 2035 | Increased\_feature\_load | 1.000 | 1.0500 | 1.100 | 1 |
| LDV | 2035 | Platooning | 0.752 | 0.8575 | 0.963 | 1 |
| LDV | 2035 | Right\_sizing | 0.550 | 0.6700 | 0.790 | 1 |
| LDV | 2050 | Congestion\_mitigation | 0.958 | 0.9790 | 1.000 | 1 |
| LDV | 2050 | De\_emphasized\_performance | 0.770 | 0.8600 | 0.950 | 1 |
| LDV | 2050 | Eco\_driving | 0.800 | 0.8750 | 0.950 | 1 |
| LDV | 2050 | Higher\_highway\_speeds | 1.070 | 1.1450 | 1.220 | 1 |
| LDV | 2050 | Improved\_crash\_avoidance | 0.771 | 0.8580 | 0.945 | 1 |
| LDV | 2050 | Increased\_feature\_load | 1.000 | 1.0500 | 1.100 | 1 |
| LDV | 2050 | Platooning | 0.752 | 0.8560 | 0.960 | 1 |
| LDV | 2050 | Right\_sizing | 0.550 | 0.6700 | 0.790 | 1 |
| HDV | 2035 | Congestion\_mitigation | 0.966 | 0.9830 | 1.000 | 1 |
| HDV | 2035 | De\_emphasized\_performance | 1.000 | 1.0000 | 1.000 | 1 |
| HDV | 2035 | Eco\_driving | 1.000 | 1.0000 | 1.000 | 1 |
| HDV | 2035 | Higher\_highway\_speeds | 1.000 | 1.0000 | 1.000 | 1 |
| HDV | 2035 | Improved\_crash\_avoidance | 1.000 | 1.0000 | 1.000 | 1 |
| HDV | 2035 | Increased\_feature\_load | 1.000 | 1.0000 | 1.000 | 1 |
| HDV | 2035 | Platooning | 0.750 | 0.8250 | 0.900 | 1 |
| HDV | 2035 | Right\_sizing | 1.000 | 1.0000 | 1.000 | 1 |
| HDV | 2050 | Congestion\_mitigation | 0.958 | 0.9790 | 1.000 | 1 |
| HDV | 2050 | De\_emphasized\_performance | 1.000 | 1.0000 | 1.000 | 1 |
| HDV | 2050 | Eco\_driving | 1.000 | 1.0000 | 1.000 | 1 |
| HDV | 2050 | Higher\_highway\_speeds | 1.000 | 1.0000 | 1.000 | 1 |
| HDV | 2050 | Improved\_crash\_avoidance | 1.000 | 1.0000 | 1.000 | 1 |
| HDV | 2050 | Increased\_feature\_load | 1.000 | 1.0000 | 1.000 | 1 |
| HDV | 2050 | Platooning | 0.750 | 0.8250 | 0.900 | 1 |
| HDV | 2050 | Right\_sizing | 1.000 | 1.0000 | 1.000 | 1 |

* Note “Right\_sizing” and “Increased\_feature\_load” apply only to LDV passenger travel.

### 3.2 Energy Intensity by Vehicle Type and Technology Scenario, by Composing Mechanism Effects

We construct Scenario Multipliers (supressing subscripts *m, f*) for the vehicle energy intensity of each Scenario *j*, for Year *t* and Vehicle class *v*. These overeall intensity multipliers for technology scenario *j* reflect the combined the effect of all the mechanisms on vehicle energy intensity.

For each technology scenario *j*, year *t*, vehicle class *v*, the estimated “EffectCase” or effect sensitivity case *s* is specified for each mechanism *k*, i.e.

for .

This Effect Sensitivity case *s* determines the appropriate intensity multiplier for each mechanism in the technology scenario.

Effect Sensitivity Cases by Vehicle Class, Year, AV Mechanism and Tech Scenario

|  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| VC | Mech | Year | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
| LDV | Congestion\_mitigation | 2035 | Mid | Opt | Zero | Opt | Zero | Zero | Zero |
| LDV | De\_emphasized\_performance | 2035 | Zero | Opt | Zero | Opt | Zero | Zero | Zero |
| LDV | Eco\_driving | 2035 | Mid | Opt | Zero | Opt | Zero | Zero | Pess |
| LDV | Higher\_highway\_speeds | 2035 | Opt | Zero | Pess | Pess | Mid | Zero | Zero |
| LDV | Improved\_crash\_avoidance | 2035 | Mid | Pess | Zero | Pess | Zero | Zero | Zero |
| LDV | Increased\_feature\_load | 2035 | Opt | Opt | Pess | Opt | Opt | Zero | Opt |
| LDV | Platooning | 2035 | Mid | Opt | Zero | Opt | Pess | Zero | Mid |
| LDV | Right\_sizing | 2035 | Zero | Opt | Zero | Opt | Zero | Zero | Zero |
| HDV | Congestion\_mitigation | 2035 | Mid | Opt | Zero | Opt | Zero | Zero | Zero |
| HDV | De\_emphasized\_performance | 2035 | Zero | Zero | Zero | Zero | Zero | Zero | Zero |
| HDV | Eco\_driving | 2035 | Mid | Opt | Zero | Opt | Zero | Zero | Mid |
| HDV | Higher\_highway\_speeds | 2035 | Opt | Zero | Pess | Pess | Mid | Zero | Opt |
| HDV | Improved\_crash\_avoidance | 2035 | Zero | Zero | Zero | Zero | Zero | Zero | Zero |
| HDV | Increased\_feature\_load | 2035 | Zero | Zero | Zero | Zero | Zero | Zero | Zero |
| HDV | Platooning | 2035 | Mid | Opt | Zero | Opt | Pess | Zero | Mid |
| HDV | Right\_sizing | 2035 | Zero | Zero | Zero | Zero | Zero | Zero | Zero |
| LDV | Congestion\_mitigation | 2050 | Mid | Opt | Zero | Opt | Zero | Zero | Zero |
| LDV | De\_emphasized\_performance | 2050 | Zero | Opt | Zero | Opt | Zero | Zero | Zero |
| LDV | Eco\_driving | 2050 | Mid | Opt | Zero | Opt | Zero | Zero | Pess |
| LDV | Higher\_highway\_speeds | 2050 | Opt | Zero | Pess | Pess | Mid | Zero | Zero |
| LDV | Improved\_crash\_avoidance | 2050 | Mid | Pess | Zero | Pess | Zero | Zero | Zero |
| LDV | Increased\_feature\_load | 2050 | Opt | Opt | Pess | Opt | Opt | Zero | Opt |
| LDV | Platooning | 2050 | Mid | Opt | Zero | Opt | Pess | Zero | Mid |
| LDV | Right\_sizing | 2050 | Zero | Opt | Zero | Opt | Zero | Zero | Zero |
| HDV | Congestion\_mitigation | 2050 | Mid | Opt | Zero | Opt | Zero | Zero | Zero |
| HDV | De\_emphasized\_performance | 2050 | Zero | Zero | Zero | Zero | Zero | Zero | Zero |
| HDV | Eco\_driving | 2050 | Mid | Opt | Zero | Opt | Zero | Zero | Mid |
| HDV | Higher\_highway\_speeds | 2050 | Opt | Zero | Pess | Pess | Mid | Zero | Opt |
| HDV | Improved\_crash\_avoidance | 2050 | Zero | Zero | Zero | Zero | Zero | Zero | Zero |
| HDV | Increased\_feature\_load | 2050 | Zero | Zero | Zero | Zero | Zero | Zero | Zero |
| HDV | Platooning | 2050 | Mid | Opt | Zero | Opt | Pess | Zero | Mid |
| HDV | Right\_sizing | 2050 | Zero | Zero | Zero | Zero | Zero | Zero | Zero |

*Alternatively, could Specify VoTT assumptions for LDV and HDV by Tech Scenario here??? Or leave VoTT specification to the Demand Scenario*

The total energy intensity multiplier for each technology scenario *j* is the product of all mechanism multipliers[[4]](#footnote-4)

is the sensitivity case value for mechanism *k* on vehicle class *v* in technology scenario *j* and year *t*.

The Net Energy Intensity change for the technology scenario *j* is the difference between the combined effect of the intensity mechanism multipliers and 1.0.

Net Energy Intensity Change by Technology Scenario, Vehicle-type, and Year

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| TechScen | HDV\_2035 | HDV\_2050 | LDV\_2035 | LDV\_2050 |
| 1 | -0.189025 | -0.192325 | -0.3228782 | -0.3268132 |
| 2 | -0.275500 | -0.281500 | -0.7674212 | -0.7693473 |
| 3 | 0.000000 | 0.000000 | 0.3420000 | 0.3420000 |
| 4 | -0.275500 | -0.281500 | -0.7162538 | -0.7186037 |
| 5 | -0.100000 | -0.100000 | 0.1026350 | 0.0992000 |
| 6 | 0.000000 | 0.000000 | 0.0000000 | 0.0000000 |
| 7 | -0.175000 | -0.175000 | -0.1853750 | -0.1868000 |

This table is the fractional change in vehicle energy use per mile-travelled, as a result of the combined effect of the (8) identified technological mechanisms by which automation alters vehicle energy intensity.

## Note/Aside: Constructed Net Energy Intensity Changes match old workbook to within 1.287431e-09 total absolute error.

# 4. Demand Response to CAVs

In addition to the changes in energy intensity we account for a travel demand response based on the net change in generalized cost of travel. The change in generalized costs reflects both the change in energy cost per mile and potential changes in several other cost components, including travel time cost and other vehicle capital and operating cost.

## 4.1 Key parameters for Demand scenarios

The following are the default parameter values that influence scenarios for the cost-based demand response. They include exogenous fractional shifts for multiple vehicle travel cost components other than energy, e.g. insurance costs, vehicle capital costs, and time costs (“Value of Travel Time”, or VoTT). They also include alternative values for the elasticity of travel demand with respect to full generalized cost per mile, ElasVKT.

**Note**: This is actually ElasPKT, which equals ElasVKT for fixed occupancy. ElasVKT will vary with occupancy?

(Aside Note: Need to be clear which version of certain parameters dominate in subsequent application, e.g. from “DemScenCostChange” vs “DemRespParams” tables. The “Low, Med, High” cases in DemRespParams table are separate from the Demand Scenario cases in DemScenCostChange table (section 4.3 below)).

Key Parameters for LDV Demand Response (for all Demand Scenarios)

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| VC | Parameter | Zero | Low | Med | High |
| LDV | ElasVKT | 0 | -1.0000 | -1.0000 | -1.0000 |
| LDV | ExclVehCapCost | 0 | 0.0000 | 0.0000 | 0.0000 |
| LDV | C\_deltaMaint | 0 | 0.0000 | 0.0000 | 0.0000 |
| LDV | C\_deltaInsurX | 0 | -0.4000 | -0.6000 | -0.8000 |
| LDV | C\_deltaCapCost | 0 | 0.0000 | 0.0000 | 0.0000 |
| LDV | C\_deltaTolls | 0 | 0.0000 | 0.0000 | 0.0000 |
| LDV | C\_deltaPrkng | 0 | 0.0000 | 0.0000 | 0.0000 |
| LDV | C\_deltaRegis | 0 | 0.0000 | 0.0000 | 0.0000 |
| LDV | C\_deltaVoTTX | 0 | -0.0500 | -0.5000 | -0.8000 |
| LDV | ShrECostInt | 1 | 1.0000 | 1.0000 | 1.0000 |
| LDV | I\_deltaCAV | 0 | -0.7186 | -0.7186 | -0.7186 |
| HDV | ElasVKT | 0 | -0.9700 | -0.9700 | -2.0000 |
| HDV | ExclVehCapCost | 0 | 0.0000 | 0.0000 | 0.0000 |
| HDV | C\_deltaMaint | 0 | 0.0000 | 0.0000 | 0.0000 |
| HDV | C\_deltaInsurX | 0 | -0.4000 | -0.6000 | -0.8000 |
| HDV | C\_deltaCapCost | 0 | 0.0000 | 0.0000 | 0.0000 |
| HDV | C\_deltaTolls | 0 | 0.0000 | 0.0000 | 0.0000 |
| HDV | C\_deltaPrkng | 0 | 0.0000 | 0.0000 | 0.0000 |
| HDV | C\_deltaRegis | 0 | 0.0000 | 0.0000 | 0.0000 |
| HDV | C\_deltaVoTTX | 0 | -0.0500 | -0.5000 | -0.8000 |
| HDV | ShrECostInt | 1 | 1.0000 | 1.0000 | 1.0000 |
| HDV | I\_deltaCAV | 0 | -0.2815 | -0.2815 | -0.2815 |

### Select a Single Scenario to Examine

Energy Intensity change is dependent on the Technology Scenario, and year of interest. For example consider Technology Scenario 4, the “Strong responses” scenario, in year 2050.

Demand response is a function of full (generalized) travel cost, and energy intensity affects the energy component of travel cost.[[5]](#footnote-5) The full scenario requires updating Demand Response parameters with energy intensity reduction (by vehicle class and year) for this Technology Scenario and year, and updating other costs (travel time cost, accident/insurance costs, vehicle capital and maintenance costs) based on the Demand Scenario assumptions.

DemRespParams: Important Parameters for the Calculation of Demand Reponse, by Vehicle-type, and Year

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| VC | Parameter | Zero | Low | Med | High |
| HDV | C\_deltaCapCost | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| HDV | C\_deltaInsurX | 0.0000 | -0.4000 | -0.6000 | -0.8000 |
| HDV | C\_deltaMaint | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| HDV | C\_deltaPrkng | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| HDV | C\_deltaRegis | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| HDV | C\_deltaTolls | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| HDV | C\_deltaVoTTX | 0.0000 | -0.0500 | -0.5000 | -0.8000 |
| HDV | ElasVKT | 0.0000 | -0.9700 | -0.9700 | -2.0000 |
| HDV | ExclVehCapCost | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| HDV | I\_deltaCAV | -0.2815 | -0.2815 | -0.2815 | -0.2815 |
| HDV | ShrECostInt | 1.0000 | 1.0000 | 1.0000 | 1.0000 |
| LDV | C\_deltaCapCost | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| LDV | C\_deltaInsurX | 0.0000 | -0.4000 | -0.6000 | -0.8000 |
| LDV | C\_deltaMaint | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| LDV | C\_deltaPrkng | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| LDV | C\_deltaRegis | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| LDV | C\_deltaTolls | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| LDV | C\_deltaVoTTX | 0.0000 | -0.0500 | -0.5000 | -0.8000 |
| LDV | ElasVKT | 0.0000 | -1.0000 | -1.0000 | -1.0000 |
| LDV | ExclVehCapCost | 0.0000 | 0.0000 | 0.0000 | 0.0000 |
| LDV | I\_deltaCAV | -0.7186 | -0.7186 | -0.7186 | -0.7186 |
| LDV | ShrECostInt | 1.0000 | 1.0000 | 1.0000 | 1.0000 |

## 4.2 Establish Base Travel Costs for Each Cost Component

### Simple Base Travel Time Cost Calculation

Unit travel time cost per mile is differentiated by vehicle class, and depends on average speed and hourly time cost.

Base Travel Time Cost Parameters

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| var | V\_Class | local | intercity | average | Units |
| VoTT | LDV | 12.500 | 18.000 | 13.799 | $/hr |
| VMTtot | LDV | 1560941.000 | 482468.000 | 2043409.000 | mi/yr |
| average\_speed | LDV | NA | NA | 27.600 | mi/hr |
| average\_TTC\_per\_mi | LDV | NA | NA | 0.500 | $/mi |
| VoTT | HDV | 24.428 | 24.428 | 24.428 | $/hr |
| VMTtot | HDV | NA | NA | NA | mi/yr |
| average\_speed | HDV | NA | NA | 39.980 | mi/hr |
| average\_TTC\_per\_mi | HDV | 0.611 | 0.611 | 0.611 | $/mi |

## Check: VoTT for LDV average value matches VMT-weighted average to within -3.663731e-09 $/hr.

## Check: Average TTC per mile for LDV average value matches VoTT/speed to within 2.898551e-10 $/mi.

## Check: Average TTC per mile for HDV average value matches VoTT/speed to within 0 $/mi.

Travel time parameter values for LDVs are an average for Car and Light-truck vehicle types, and in per-mile terms they depend directly on average travel speed.

**ToDo** Needed data: Seek to benchmark average speed for local and intercity driving, for both LDVs and HDVs. These regional values should be consistent with overall average speed. **ToDo** Better-represent ways CAVs could alter average speed, and therefor travel time cost per mile.

### Base (Conventional) Vehicle Travel Cost Components

Specify the primary (private) cost components for base case (conventional, manual) road vehicle travel.

## Warning: attributes are not identical across measure variables;  
## they will be dropped

## Check: Input VTCostBase Time cost for LDVs and HDV matches Average TTC per mile to within c(-2.00000016548074e-10, -2.00000016548074e-10, 0) cents/mi.

Base Vehicle Travel Cost Components by Vehicle Type (cents/mi)

|  |  |  |  |
| --- | --- | --- | --- |
| CostCat | HDVClass8 | LDVAvgLtTruck | LDVAvgSedan |
| Fuel | 59.0 | 19.630 | 14.590 |
| Maintenance | 19.4 | 6.150 | 5.470 |
| AccAndIns | 6.7 | 8.491 | 8.447 |
| VehCapCost | 18.9 | 43.491 | 29.907 |
| TollsFees | 5.5 | 0.000 | 0.000 |
| Parking | 0.0 | 2.273 | 2.110 |
| Time | 61.1 | 49.995 | 49.995 |
| Registration | 0.0 | 7.218 | 5.148 |
| Total | 170.6 | 137.248 | 115.667 |

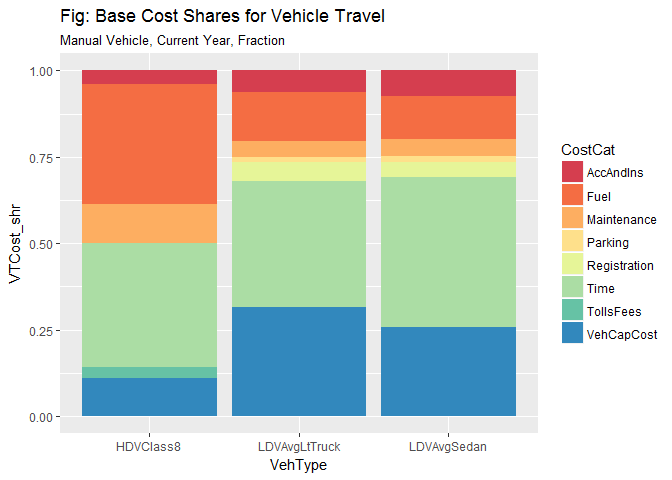
Note: these values are the average of local and intercity.

### Base Vehicle Travel Cost Shares by Component

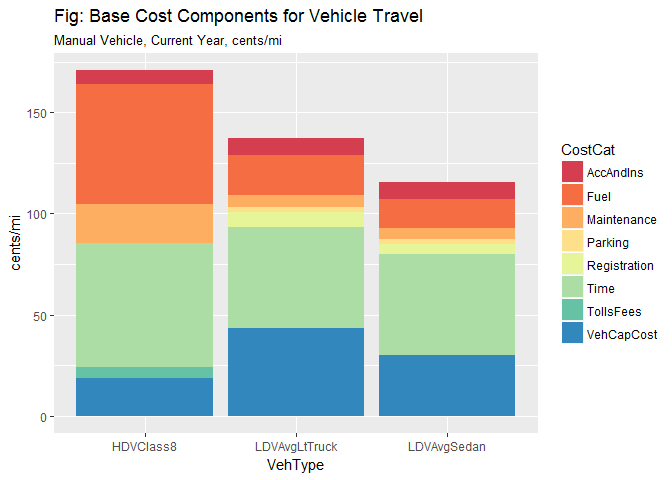
The base costs components are normalized to cost shares, establishing a reference point for the relative cost changes from vehicle automation.

Base Vehicle Travel Cost: Components Share by Vehicle Type, Year=2018

|  |  |  |  |
| --- | --- | --- | --- |
| CostCat | HDVClass8 | LDVAvgLtTruck | LDVAvgSedan |
| Fuel | 0.346 | 0.143 | 0.126 |
| Maintenance | 0.114 | 0.045 | 0.047 |
| AccAndIns | 0.039 | 0.062 | 0.073 |
| VehCapCost | 0.111 | 0.317 | 0.259 |
| TollsFees | 0.032 | 0.000 | 0.000 |
| Parking | 0.000 | 0.017 | 0.018 |
| Time | 0.358 | 0.364 | 0.432 |
| Registration | 0.000 | 0.053 | 0.045 |
| Total | 1.000 | 1.000 | 1.000 |



#### Display Base Travel Costs per Mile by Component



## 4.3 Cost Changes and Fractional Increase in VKT for Demand Scenarios

Calculate fractional change in demand, by Demand Scenario *d*, Year *t*, and VehicleClass *v*, based on changes in time cost, other vehicle fuel and operating costs, and VMT demand elasticity w.r.t generalized cost.

### Demand Scenarios Driven by Cost Reduction Parameters and Demand Response Parameters

Automation *demand* scenarios are defined by assumptions regarding CAV impacts on selected component costs (e.g. travel time costs, internal accident and insurance costs, [and vehicle incremental costs?]), and on the sensitivity of road travel demand to costs. They are not CAV penetration scenarios. CAV penetration is exogenous, and initially assumed 100%.

Vehicle Travel Cost Component Change (Reduction) by Demand Scenario

|  |  |  |  |
| --- | --- | --- | --- |
| DemScen | C\_deltaVoTT | C\_deltaInsur | Description |
| DS1 | 0.00 | -0.6 | Driver assistance, but no self-driving. Little benefits of comfort (0% reduction in VoT), lower end of insurance benefits (60%) |
| DS2 | -0.05 | -0.6 | Driver assistance, but no self-driving. Some benefits of comfort (5% reduction in VoT), lower end of insurance benefits (60%) |
| DS3 | -0.50 | -0.8 | Self driving. Large benefits of comfort + in vehicle use of time (50% reduction in VoT), large benefits of insurance (80%) |
| DS4 | -0.80 | -0.8 | Extreme Self driving case. Large benefits of comfort + in vehicle use of time (80% reduction in VoT), large benefits of insurance (80%) |
| DS5 | -0.80 | -0.8 | Same as DemScen 4 |
| DS6 | -0.80 | -0.8 | Same as DemScen 4 |
| DS7 | -0.50 | -0.8 | Same as DemScen 3 |

### CAV Scenario Vehicle Travel Cost Shares by Component

Costs are adjusted relative to Base for the cost-related assumptions of each Demand Scenario and for the Energy Intensity change associated with the current Technology Scenario. Energy intensity drives the travel energy cost, but this component is typically less than 15% of total travel costs for LDVs, and less than 35% of total costs for HDVs.

Base cost component shares are normalized and add to 1.0. Demand Scenario *relative* costs for each cost component *i* are relative to the Base (Manual Vehicle) level. The total relative cost for all components can be greater than or less than 1.0. Denoted , the scenario travel cost component shares depend on cost component *i*, Vehicle class *v*, Year *t* and Demand Scenario *d*, and TechScenario *j*.

Base fuel costs per mile are adjusted by the Scenario Multipliers for energy intensity, for TechScenario *j*, Year *t*, Vehicle class *v*. The perceived change in fuel cost effects for consumers/riders also depends on the fraction of fuel costs that are assumed visible to or perceived by them. That is, for cost component :

Other travel cost components *i* have similar scenario-based adjustments, some directly specified by assumption for demand scenario *d*, year *t* and vehicle class *v*:

Note that adjusted travel cost components are all determined relative to the reference level. Thus the adjusted component “shares” are not technically shares, and can total greater or less than 1.0, if the total adjusted costs are greater or less than total base costs. Their sum indicates the relative travel cost for the combined demand-technology scenario *dj*:

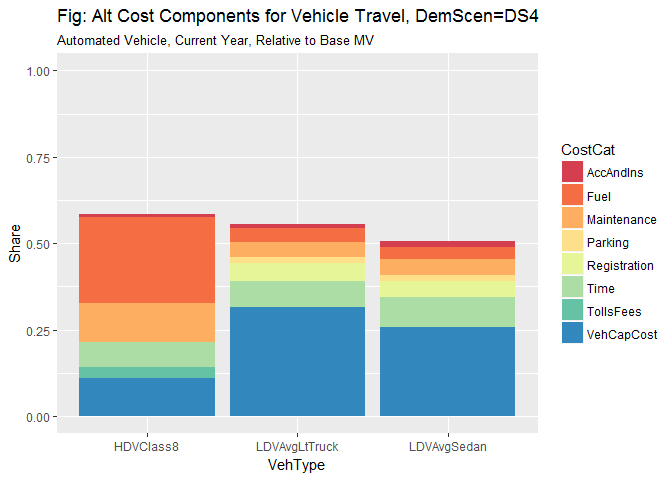
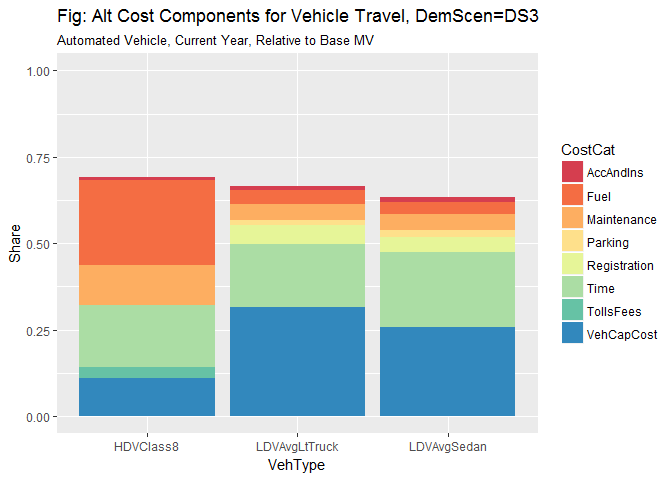
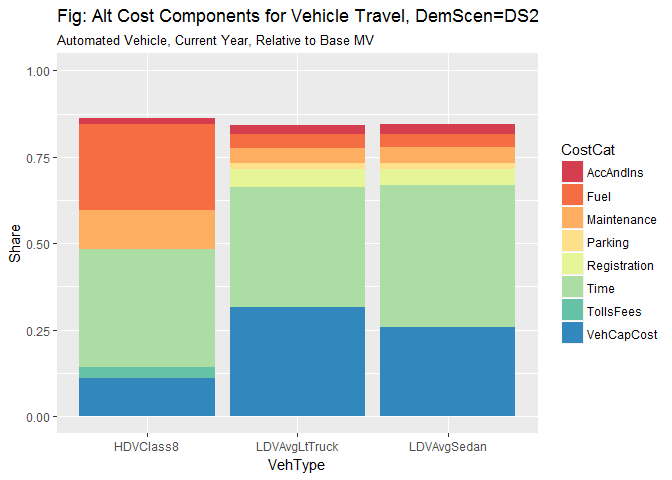
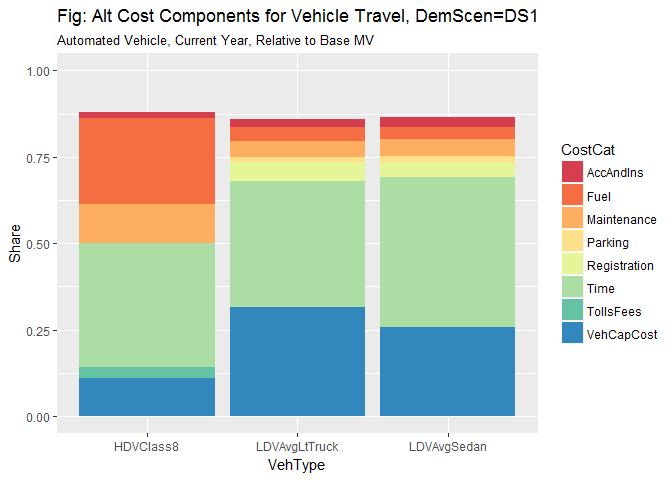
## 4.4 Calculate Adjusted Travel Cost Components for Scenario Conditions

Updated cost component table based on Scenario VoTT and other costs. Calculate cost component fractions (shares) for all demand scenarios. The Technology (energy intensity) scenario is currently held at number 4, the “Strong responses” scenario.

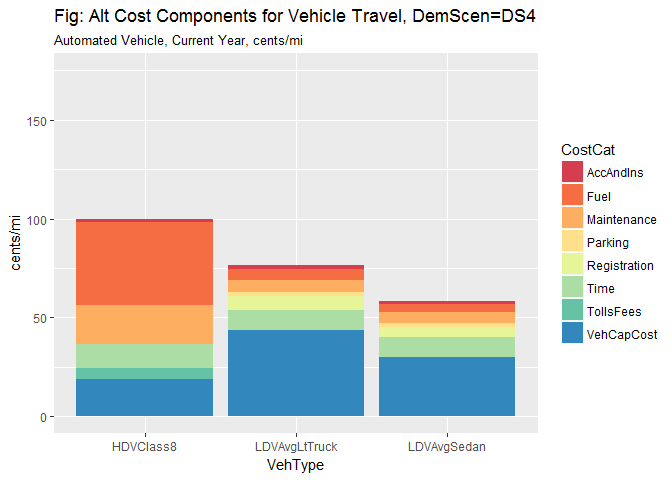
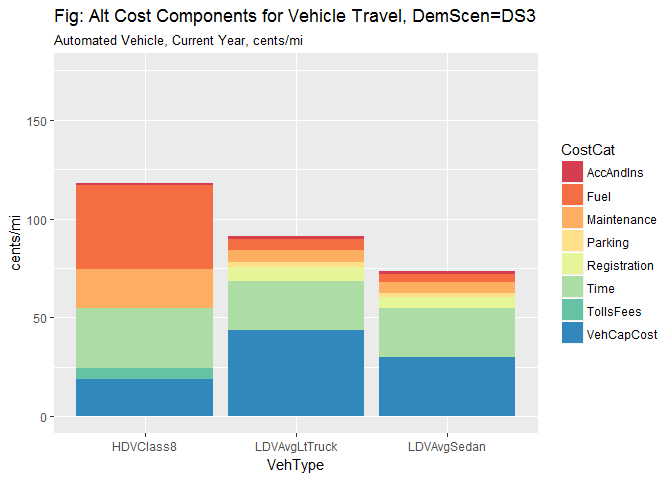
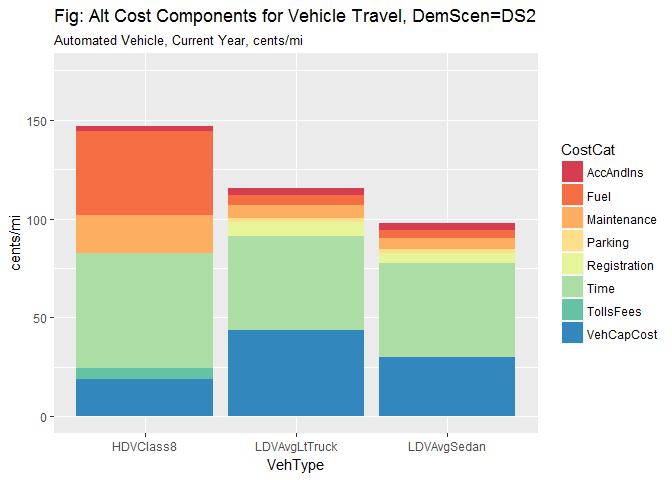
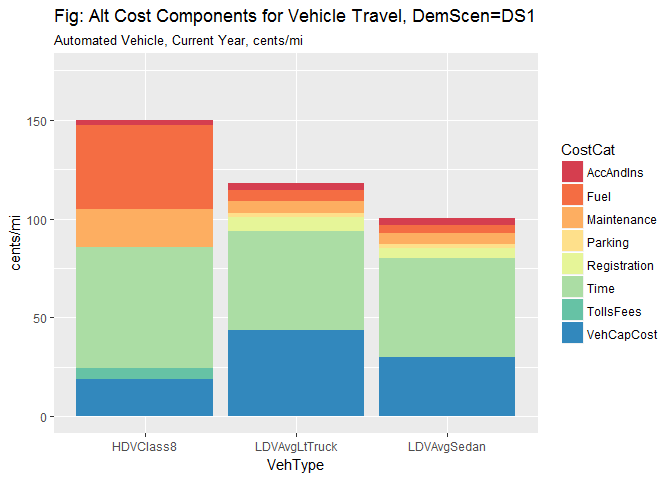
Alt Travel Cost Components Relative to Base, by Demand Scenario & Vehicle Type

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| DemScen | CostCat | HDVClass8 | LDVAvgLtTruck | LDVAvgSedan |
| DS1 | AccAndIns | 0.016 | 0.025 | 0.029 |
| DS1 | Fuel | 0.248 | 0.040 | 0.035 |
| DS1 | Maintenance | 0.114 | 0.045 | 0.047 |
| DS1 | Parking | 0.000 | 0.017 | 0.018 |
| DS1 | Registration | 0.000 | 0.053 | 0.045 |
| DS1 | Time | 0.358 | 0.364 | 0.432 |
| DS1 | TollsFees | 0.032 | 0.000 | 0.000 |
| DS1 | Total | 0.879 | 0.860 | 0.866 |
| DS1 | VehCapCost | 0.111 | 0.317 | 0.259 |
| DS2 | AccAndIns | 0.016 | 0.025 | 0.029 |
| DS2 | Fuel | 0.248 | 0.040 | 0.035 |
| DS2 | Maintenance | 0.114 | 0.045 | 0.047 |
| DS2 | Parking | 0.000 | 0.017 | 0.018 |
| DS2 | Registration | 0.000 | 0.053 | 0.045 |
| DS2 | Time | 0.340 | 0.346 | 0.411 |
| DS2 | TollsFees | 0.032 | 0.000 | 0.000 |
| DS2 | Total | 0.861 | 0.842 | 0.844 |
| DS2 | VehCapCost | 0.111 | 0.317 | 0.259 |
| DS3 | AccAndIns | 0.008 | 0.012 | 0.015 |
| DS3 | Fuel | 0.248 | 0.040 | 0.035 |
| DS3 | Maintenance | 0.114 | 0.045 | 0.047 |
| DS3 | Parking | 0.000 | 0.017 | 0.018 |
| DS3 | Registration | 0.000 | 0.053 | 0.045 |
| DS3 | Time | 0.179 | 0.182 | 0.216 |
| DS3 | TollsFees | 0.032 | 0.000 | 0.000 |
| DS3 | Total | 0.692 | 0.666 | 0.635 |
| DS3 | VehCapCost | 0.111 | 0.317 | 0.259 |
| DS4 | AccAndIns | 0.008 | 0.012 | 0.015 |
| DS4 | Fuel | 0.248 | 0.040 | 0.035 |
| DS4 | Maintenance | 0.114 | 0.045 | 0.047 |
| DS4 | Parking | 0.000 | 0.017 | 0.018 |
| DS4 | Registration | 0.000 | 0.053 | 0.045 |
| DS4 | Time | 0.072 | 0.073 | 0.086 |
| DS4 | TollsFees | 0.032 | 0.000 | 0.000 |
| DS4 | Total | 0.585 | 0.556 | 0.505 |
| DS4 | VehCapCost | 0.111 | 0.317 | 0.259 |
| DS5 | AccAndIns | 0.008 | 0.012 | 0.015 |
| DS5 | Fuel | 0.248 | 0.040 | 0.035 |
| DS5 | Maintenance | 0.114 | 0.045 | 0.047 |
| DS5 | Parking | 0.000 | 0.017 | 0.018 |
| DS5 | Registration | 0.000 | 0.053 | 0.045 |
| DS5 | Time | 0.072 | 0.073 | 0.086 |
| DS5 | TollsFees | 0.032 | 0.000 | 0.000 |
| DS5 | Total | 0.585 | 0.556 | 0.505 |
| DS5 | VehCapCost | 0.111 | 0.317 | 0.259 |
| DS6 | AccAndIns | 0.008 | 0.012 | 0.015 |
| DS6 | Fuel | 0.248 | 0.040 | 0.035 |
| DS6 | Maintenance | 0.114 | 0.045 | 0.047 |
| DS6 | Parking | 0.000 | 0.017 | 0.018 |
| DS6 | Registration | 0.000 | 0.053 | 0.045 |
| DS6 | Time | 0.072 | 0.073 | 0.086 |
| DS6 | TollsFees | 0.032 | 0.000 | 0.000 |
| DS6 | Total | 0.585 | 0.556 | 0.505 |
| DS6 | VehCapCost | 0.111 | 0.317 | 0.259 |
| DS7 | AccAndIns | 0.008 | 0.012 | 0.015 |
| DS7 | Fuel | 0.248 | 0.040 | 0.035 |
| DS7 | Maintenance | 0.114 | 0.045 | 0.047 |
| DS7 | Parking | 0.000 | 0.017 | 0.018 |
| DS7 | Registration | 0.000 | 0.053 | 0.045 |
| DS7 | Time | 0.179 | 0.182 | 0.216 |
| DS7 | TollsFees | 0.032 | 0.000 | 0.000 |
| DS7 | Total | 0.692 | 0.666 | 0.635 |
| DS7 | VehCapCost | 0.111 | 0.317 | 0.259 |

### Display Alternative Scenario Travel Costs per Mile by Component



From scenario-based cost shares, we can easily compute and visualize the total travel cost per mile for CAVs, by component. We apply the alternative scenario cost component “shares” (which can total to more or less than 1.0, as shown in the above bar chart) to the base total vehicle travel cost.



## 4.5 Fractional VMT Changes in CAV Scenario

Compute fractional increases in VKT from the changes in total generalized travel costs that result from automation.

For Vehicle Type *v*, Time *t*, Demand Scenario *d*, Technology Scenario *j*, and Elasticity Case *c* (Low and High elasticity) [??? is elasticity case to be governed by demand scenario *d*, or separate index *c*?]

Define

* = Relative Total Cost for vehicle travel [unitless, vehicle travel cost $/veh-km]
* = fractional increase in VKT [unitless, VKT is in km/vehicle-yr]

The fractional increase in VKT

The Elasticity of VKT with respect to (generalized) travel cost is a key assumption. This elasticity reflects the long-run response of road travel to travel cost changes, but is not meant to include the demand response of new/underserved uswer groups, or the VMT effects of ride hailing/pooling. Based on how they were generated, the parameter values selected may or may not include mode substitution/switching effects, and longer-run locational choices. The generalize vehicle travel costs considered here and in the cost-measure associated with this elasticity include vehicle capital and operation costs, including fuel, insurance, maintenance, fees, and travel-time costs.

Current sources for ElasVKT: (HERS-ST technical report, August 2005 + Graham and Glaister 2002)

In the CAVSIM framework, additional adjustments to the fractional change in VKT for LDV travel, beyond those from the elastic demand response to changing full generalized travel cost, follow from:

* multiplier factors on VMT to include larger travel by underserved population (elderly, youth, physically challenged)
  + Aside on original ests: =‘[CAV Energy ASIF Framework WadudMacKenzieLeiby V20161024\_Test.xlsx]calcul Dem\_LDV’!$IK$44
* multiplier factors on VMT to account for VKT increase or decline in response to ride-hailing/ride-pooling, for the same level of PKT.
  + Aside on original ests: =‘[CAV Energy ASIF Framework WadudMacKenzieLeiby V20161024\_Test.xlsx]calcul Dem\_LDV’!$IK$48

## Check: Calculated VMTIncrease from cost-elastic response matches Test values to within 4.3268442162514e-09 (fractional change).

### Effects on VMT Demand from Underserved Population, and Ride Hailing & Pooling

The fractional change in VMT demand due to the cost-elastic response is augmented by adjustments reflecting:

* estimated additional road travel by underserved/non-driving populations, specifically older and young people;
* a shift from ride hailing/pooling.

Specify Combined Scenarios. A combined scenario associates each Demand Scenario with and Underserved Multiplier Option USOption and possible further VMT adjustment for ride hailing/pooling (baseRideHailingPoolingAdj). Note that all of these demand adjustments, for cost-response , underserved-demand multiplier \_{USD}, and ride hailing/pooling demand shift , are applied multiplicatively to the base demand level:

And the proportional change in VMT for the combined scenario is

## Check: Test output to Kaya (VMTIncrease table) matches examples for CombScen in CS1 CS2 CS3 CS4 CS5 CS6 CS7 to within 3.783225e-08

# 5. Policy and Scenario Calculations

Seeking to generate bar graphs of fractional changes in energy intensity, travel demand, energy use (each by LDV/HDV), and Total Energy Use (both sectors). (As in Policy + Scenario sheet)

Create a dataframe of changes in Energy Intensity and Travel Demand, for all Combined Scenarios.

Energy intensity changes (net, accounting for the influence of all identified mechanisms)  
have been calculated by year *t*, vehicle class *v*, and technology scenario scenario *j* in EnergyIntensityChanges:

Travel demand or VMT fractional changes have been calculated by year *t*, vehicle class *v*, and technology scenario scenario *j* in VMTIncrease

# This is all vehicle energy intensity changes for all values of TechScen, Year, and Vehicle Class  
CaseEffectsEI <- EnergyIntensityChanges %>% ungroup %>%   
 select(TechScen, Year, VC, NIE)

Select Combined Scenario

# Note that the following VMT Increase calculation table in "VMTIncrease" is for a range of Demand Scenarios, but a \_single\_ tech scenario.  
# Thus they do not match the spreadsheet model results, which implicitly loops overall all TechScen values with "TBL" command.  
  
# The VMT results need to be recalulated here for each TechScen and matching DemScen assumptions  
# in the full combined scenario.  
  
CombScenResultsForOneTechScen <- function(CurrTS, CurrYr){  
   
 # Update I\_DeltaCAV in DemRespParams  
   
 # Select energy intensity changes for the Current Technology Scenario and Year, for both vehicle classes  
 nie = EnergyIntensityChanges %>% ungroup() %>%   
 filter(TechScen == CurrTS, Year == CurrYr) %>%   
 select(VC, NIE) # leaves a small df with net intensity changes for each vehicle class  
  
 # Update I\_deltaCAV, net energy intensity change, to be consistent with current TechScen  
 # Transcribe current (computed) net intensity changes (nie) to the I\_deltaCAV variable in DemRespParams  
 # This assignment is awkward, due to non-ideal organization of data tables.  
 #DemRespParams$NIE = EnergyIntensityChange$NIE # for matching VC, and Parameter=='I\_deltaCAV'  
 DemRespParams %>% gather(key = Sens, value = value, -c(VC, Parameter)) %>% # following assigns the same   
 mutate(value = ifelse((VC=="LDV" & Parameter=="I\_deltaCAV"), nie[nie$VC=="LDV",]$NIE, value),  
 value = ifelse((VC=="HDV" & Parameter=="I\_deltaCAV"), nie[nie$VC=="HDV",]$NIE, value)) %>%  
 spread(key=Sens, value=value) ->  
 DemRespParams  
   
 DemRespParams = DemRespParams[,c( "VC","Parameter", "Zero", "Low", "Med", "High")] # reorder columns after gather/spread  
   
 # Get desired Demand Response Parameters (ElasVKT, C\_deltaCapCst, ExclVehCapCost, and I\_deltaCAV), for desired cases  
 y = DemRespParams %>% select(-c(Zero, Med)) %>%   
 gather(key=Case, value=value, Low:High) %>% # for two cases (Low and High)  
 spread(key = Parameter, value=value)  
 # select(-InsurCostRed) # UGLY: \*\*Unused\*\* Insurance cost reduction determined by Demand Scenario  
   
 # VTCShrAlt  
   
 # Start with dataframe replicates the Base Vehicle Travel Cost Shares for each Demand Scenario  
 VTCShrAlt = VTCShrBase %>%   
 mutate(  
 DS1 = VTCost\_shr, # initialize to base cost shares (4 Demand Scenarios)  
 DS2 = VTCost\_shr,  
 DS3 = VTCost\_shr,  
 DS4 = VTCost\_shr,  
 DS5 = VTCost\_shr,  
 DS6 = VTCost\_shr,  
 DS7 = VTCost\_shr,  
 VC = substr(as.character(VehType), 1, 3)  
 ) %>%  
 select(-VTCost\_shr) # could also keep as Base case, DS0  
   
 # Reshape for column variables to be component cost-shares, and separate V\_Class from VehType  
 # (latter differentiates between Lt Truck and Car within LDV)  
 x = VTCShrAlt %>%   
 gather(key = DemScen, value = VCRel, DS1:DS7) %>%   
 spread(key = CostCat, value = VCRel)  
   
 # combine base cost shares in x and Demand Reponse Parameters (Fractional Adjustments) in y for their adjustment  
 x = left\_join(x, y, by=c("VC")) # note this also duplicates x (base shares) rows by Sensitivity Case in y  
 # append correct Dem Scen multipliers for other vars (VoTT and Insurance)   
 x = left\_join(x, select(DemScenCostChange, -Description), by=c("DemScen")) # currently \_not\_ Sensitivity Case-dependent  
 # x %>% select(VehType, VC, DemScen, Case, ElasVKT, C\_deltaInsur, C\_deltaInsurX, C\_deltaVoTT, C\_deltaVoTTX)  
 VTCShrAlt = x  
   
 # Apply adjustments to Cost (per mi) Components, across Demand Scenario (DemScen), Veh Type, and Case (Low - High)  
 # Note that this is perceived/internalized cost (may not include all energy gains)  
 # \*\*ToDo\*\*: generalize to include potential shifts on \_all\_ cost components  
 VTCShrAlt = VTCShrAlt %>% mutate(  
 Fuel = Fuel \* (1.0 + I\_deltaCAV\*ShrECostInt),   
 # Fuel energy intensity reduction (from energy efficiency) \* Share of energy efficiency costs internalized by traveler  
 # "Fuel energy cost reduction" = 'Policy+Scenario'!D$11  
 Maintenance = Maintenance \* (1.0 + C\_deltaMaint),  
 AccAndIns = AccAndIns \* (1.0 + C\_deltaInsur), # (1+InsChange[DemScen]) # = "DemandScenarios!$O3"  
 VehCapCost = VehCapCost \* (1.0 + C\_deltaCapCost), # (1+CapitalCostChange)  
 TollsFees = TollsFees \* (1.0 + C\_deltaTolls),  
 Parking = Parking \* (1.0 + C\_deltaPrkng),  
 Time = Time \* (1.0 + C\_deltaVoTT ), #(1-VoTTChang[DemScen]) # = "DemandScenarios!N3"   
 Registration = Registration\* (1.0 + C\_deltaRegis)  
 # Total = CostMult weighted by base CostFraction  
 )  
 VTCShrAlt$Total = 0  
 # note this summing operation relies on component cost share columns being in this alphabetic order, and Total = 0  
 VTCShrAlt %>% select(AccAndIns:VehCapCost) %>% rowSums(na.rm=TRUE) -> VTCShrAlt$Total  
   
 # RelTotCost  
 # Get main result (total relative cost) for all Demand scenarios, VehType, Cases, and elasticity of VKT  
 RelTotCost = VTCShrAlt %>% select(DemScen, VehType, VC, Case, Total, ElasVKT)  
   
 RelTotCost = RelTotCost %>% mutate(  
 fracVMTIncr = Total^ElasVKT-1.0 # fractional VMT increase base on elastic response to Total cost  
 )  
   
 # VMTIncrease  
 # New Calculated Values: % increase LD personal vehicles in VMTdemand from cost-elastic response (averaging LDV Sedans and LtTrucks)  
 VMTIncrease = RelTotCost %>%   
 #filter(Case=="Low") %>%  
 select(-VehType) %>%  
 rename(ElasCase = Case) %>% # actually, this Case could reflect sensitivity Case variations in other cost compons  
 group\_by(VC, DemScen, ElasCase) %>%  
 summarise(fracVMTIncr = mean(fracVMTIncr)) # this is an unweighted mean for Sedans and LtTrucks  
   
 # Make additional (exog) adjustments in VMT demand based on shifts from Underserved population and Ride Hail/Pooling  
 VMTIncrease = VMTIncrease %>%  
 left\_join(select(DemScenAdjustments, -Comments), by=c("VC","DemScen")) # combines cost-based VMT change with shift factors  
 VMTIncrease = VMTIncrease %>%   
 mutate(fracVMTIncr = (1+fracVMTIncr) \* USDmult \* (1+RidePoolAdj) - 1) # apply demand shifts  
   
 # Select other cost and demand response parameters for the current Technology and Demand Scenario and Year  
   
 # Case Effects on Demand (single Year, TechScen, multiple VC, DemScen, ElasCase)  
 EffectsD <- VMTIncrease %>% ungroup %>%   
 select(CombScen, DemScen, VC, ElasCase, fracVMTIncr) %>%   
 mutate(CombScen\_Num = as.integer(str\_sub(CombScen,-1,-1))) %>%  
 mutate(DemScen\_Num = as.integer(str\_sub(DemScen, -1,-1)))  
 # add labels for year and TechScen, and associated Energy Intensity NIE  
 EffectsD <- left\_join(x = EffectsD, filter(CaseEffectsEI, TechScen == CurrTS, Year == CurrYr), by = c("VC"))  
  
 return(EffectsD)  
} # end CombScenResultsForOneTechScen()  
  
# This completes the calculation of VMT fractional change for one TechScen and the set of DemScen

Loop over all Tech Scenarios (TechScen) and develop table of all combinations of Tech Scenarios and Demand Scenarios

Calculate fractional change in Energy Use by sector.

# Join Energy Effects (by Year) and Demand Effects (by ElasCase) and   
# compute fractional change in Energy Use  
# by Year, VC, CombScen, DemScen, Scenario\_Number, ElasCase   
# Note: these Demand results are actually only valid for the Currently select TechScen  
# Compute Energy Use impact  
CaseEffects <- CaseEffects %>% mutate(EnergyUse = (1+NIE)\*(1+fracVMTIncr) - 1.0)

CombScen\_Combinations <- read.delim(textConnection("  
CombScen :Year :ElasCase :VC :TechScen :DemScen\_Num :Notes  
CS1 :2050 :Low :HDV :1 :2 :Cost-base response (with ElasVKT) only  
CS2 :2050 :Low :HDV :2 :3 :Cost-base response (with ElasVKT) only  
CS3 :2050 :Low :HDV :3 :5 :Cost-base response (with ElasVKT) only  
CS4 :2050 :Low :HDV :4 :6 :Cost-base response (with ElasVKT) only  
CS5 :2050 :Low :HDV :5 :2 :HDV Same as DemScen 4  
CS6 :2050 :Low :HDV :6 :0 :HDV Same as DemScen 4  
CS7 :2050 :Low :HDV :7 :2 :HDV Same as DemScen 3  
CS1 :2050 :Low :LDV :1 :2 :Cost-base response (with ElasVKT) only  
CS2 :2050 :Low :LDV :2 :3 :Cost-base response (with ElasVKT) with Underserved multiplier effect option 1  
CS3 :2050 :Low :LDV :3 :5 :Cost-base response (with ElasVKT) with Underserved multiplier effect option 3  
CS4 :2050 :Low :LDV :4 :6 :Cost-base response (with ElasVKT) with Underserved multiplier effect option 4  
CS5 :2050 :Low :LDV :5 :2 :scenario 4 with higher LDV elasticity  
CS6 :2050 :Low :LDV :6 :0 :scenario 5 with shift to ridehailing\_ridepooling  
CS7 :2050 :Low :LDV :7 :2 :scenario 3 with shift to ridehailing\_ridepooling  
"),header=TRUE,sep=":",strip.white=TRUE) #  
CombScen\_Combinations$VC = as.character(CombScen\_Combinations$VC)

Select Predefined combinations of Tech and Demand scenarios from the full set of cross-combinations

# Note: semi\_join(df1, df2) #keep only observations in df1 that match in df2 (inner\_join without keeping df2).  
# Note: anti\_join(df1, df2) #drops all observations in df1 that match in df2.  
CaseWantedEffects = CaseEffects %>%   
 # filter(Year==CurrYear) %>%  
 semi\_join(CombScen\_Combinations, by=c("Year", "ElasCase", "VC", "TechScen", "DemScen\_Num"))

## Warning: Column `ElasCase` joining character vector and factor, coercing  
## into character vector

XXX

Calculate fractional change in Total Energy Use, with sector-change fractions weighted by sectoral VMT.

Transportation Energy Use - Estimated Reference Scenario (trillions BTU) Drawing from AEO Table 45. Transportation Sector Energy Use by Mode and Type

Transportation Energy Use Estimated Automated Vehicle Scenario = RefEnergyUse*((1+Modal Efficiency Factors)^Rebound Elasticities)*(1+Fuel Carbon Intensities)\*(1+Modal Shares/Activity Factors)

LDV Total Energy = LDV Total Energy Ref*((1+Light-Duty Vehicle)^Light-Duty Vehicle)*(1+ Jet Fuel)\*(1+Light-Duty Vehicle)

Commercial Light Trucks Motor Gasoline = Motor Gasoline*((1+Commercial Light Trucks 1/)^Commercial Light Trucks 1/)*(1+ Motor Gasoline)*(1+Commercial Light Trucks 1/) Commercial Light Trucks Motor Gasoline = Motor Gasoline*((1+Commercial Light Trucks 1/)^Commercial Light Trucks 1/)*(1+ Motor Gasoline)*(1+Commercial Light Trucks 1/) Commercial Light Trucks Distillate Fuel Oil (diesel) = Distillate Fuel Oil (diesel)*((1+Commercial Light Trucks 1/)^Commercial Light Trucks 1/)*(1+ Ethanol)\*(1+Commercial Light Trucks 1/) CLT Total Energy = Motor Gasoline+ Distillate Fuel Oil (diesel)

Freight Trucks Motor Gasoline = Motor Gasoline*((1+Freight Trucks)^Freight Trucks)*(1+ Motor Gasoline)*(1+Freight Trucks) Freight Trucks Distillate Fuel Oil (diesel) = Distillate Fuel Oil (diesel)*((1+Freight Trucks)^Freight Trucks)*(1+ Ethanol)*(1+Freight Trucks) Freight Trucks Compressed Natural Gas = Compressed Natural Gas*((1+Freight Trucks)^Freight Trucks)*(1+ Compressed Natural Gas)*(1+Freight Trucks) Freight Trucks Liquefied Petroleum Gases = Liquefied Petroleum Gases*((1+Freight Trucks)^Freight Trucks)*(1+ Liquefied Petroleum Gases)*(1+Freight Trucks) HDV Total Energy = Motor Gasoline+ Distillate Fuel Oil (diesel)+ Compressed Natural Gas+ Liquefied Petroleum Gases

Formula: SUM(LDV Total Energy, CLT Total Energy, HDV Total Energy)/SUM(LDV Total Energy Ref, CLT Total Energy Ref, HDV Total Energy Ref)-1

VMT Demand Response: pick up chosen Demand and Technology Scenario, and values for chosen scenario, for years 2035 & 2050

Years = 2007:2050  
PolicyScen\_Test\_filename = "PolicyAndScenarioData\_Test20161014.csv"  
ScenAndPolicyProj\_Test = read\_csv(paste0("./Data/",PolicyScen\_Test\_filename), comment = "#")

## Parsed with column specification:  
## cols(  
## Year = col\_integer(),  
## VMT\_LDV = col\_double(),  
## Energy = col\_double(),  
## EnergyIntensity = col\_double(),  
## adjTotalVMT = col\_double(),  
## LDV\_Penetration = col\_double(),  
## LDV\_VMTIncreaseCAV = col\_double(),  
## LDV\_VMTIncreaseRatio = col\_double(),  
## HDV\_Penetration = col\_double(),  
## HDV\_VMTIncreaseCAV = col\_double(),  
## HDV\_VMTIncreaseRatio = col\_double(),  
## LDV\_EnergyIntensityFractionalIncrFull = col\_double(),  
## LDV\_EnergyIntensityMultScaled = col\_double(),  
## HDV\_EnergyIntensityFractionalIncrFull = col\_double(),  
## HDV\_EnergyIntensityMultScaled = col\_double()  
## )

VMT Demand Response: pick up chosen Demand Scenario, and value for chosen scenario, for years 2035 & 2050  
Dem Scenario 2035 2050 Notes LDV Demand impact (depends on scenario choice in B3) 6 0.671 0.671 Dmnd change Per CAV, or at total demand impact at full penetration HDV Demand impact (depends on scenario choice in B3) 6 0.683 0.683 Dmnd change Per CAV, or at total demand impact at full penetration

LDV Demand impact (depends on scenario choice in B3) (not year t dependent) HDV Demand impact (depends on scenario choice in B3) (not year t dependent) LDV penetration: total automated/total stock in 2050 HDV penetration: total automated/total stock in 2050

LDV Penetration rate=fullyauto/totalstock LDV Increase in VMT for each automated vehicle LDV VMT increase ratio/this is linked to calculation sheets

HDV Penetration rate=fullyauto/totalstock HDV Increase in VMT for each automated vehicle HDV VMT increase ratio/this is linked to calculation sheets

LDV Energy Intensity Multiplier, scaled by penetration HDV Energy Intensity Fractional Increase at full adoption - from above LDV Energy Intensity Multiplier, scaled by penetration HDV Energy Intensity Multiplier, scaled by penetration

## 5.1 Final Scenario Results Table for 2050

TechScen :LDV.EIntens :HDV.EIntens :LDV.VMTpveh :HDV.VMTpveh :LDV.EUse :HDV.EUse :Tot.EUse :ScenarioName  
2 :-0.769347291 :-0.2815 :0.667260556 :0.428904653 :-0.615441836 : 0.026667993 :-0.447064047 :  
7 :-0.1868 :-0.175 :0.119096619 :0.109988946 :-0.089950629 :-0.08425912 :-0.088458169 :  
4 :-0.718603695 :-0.2815 :0.671164285 :0.682936788 :-0.529740545 : 0.209190082 :-0.33597384 :  
3 : 0.342 : 0.0 :0.646717246 :0.449406 : 1.209894545 : 0.449406 : 1.010474797 :  
1 :-0.326813226 :-0.192325 :0.14263231 :0.117220316 :-0.230795041 :-0.097649081 :-0.19588073 :  
5 : 0.0992 :-0.1 :0.073921709 :0.07975024 : 0.180454742 :-0.028224784 : 0.125733578 :  
TechScen :LDV.EIntens :HDV.EIntens :LDV.VMTpveh :HDV.VMTpveh :LDV.EUse :HDV.EUse :Tot.EUse :ScenarioName  
2 :-76.93% :-28.15% :66.73% :42.89% :-61.54% : 2.67% :-44.71% :Have our cake & eat it too  
7 :-18.68% :-17.50% :11.91% :11.00% : -9.00% :-8.43% : -8.85% :Stuck in the middle at Level 2  
4 :-71.86% :-28.15% :67.12% :68.29% :-52.97% :20.92% :-33.60% :Strong responses  
3 : 34.20% : 0.00% :64.67% :44.94% :120.99% :44.94% :101.05% :Dystopian nightmare  
1 :-32.68% :-19.23% :14.26% :11.72% :-23.08% :-9.76% :-19.59% :Cautiously optimistic  
5 : 9.92% :-10.00% : 7.39% : 7.98% : 18.05% :-2.82% : 12.57 :Driver assist, limited other benefits

# rotate example test results, and split out vehicle class distinction  
SR\_test = summaryScenarioResultsTableExample %>%  
 select(-ScenarioName) %>%  
 gather(key=varname, value=value, -TechScen) %>%   
 # separate(data, col, into, sep = "[^[:alnum:]]+", remove = TRUE, convert = FALSE, extra = "warn", fill = "warn", ...)  
 separate(varname, into=c("VC", "varname")) #, sep="[^[:alnum:]]+", remove = TRUE, convert = FALSE, extra = "warn", fill = "warn", ...)  
  
SR\_test = SR\_test %>%  
 spread(key = varname, value = value) %>%  
 rename(  
 fracVMTIncr = VMTpveh,  
 NIE = EIntens,  
 EnergyUse = EUse  
 )

testVars = c("fracVMTIncr", "NIE", "EnergyUse")  
SR\_test = SR\_test %>% gather(key=varname, value = testValue, testVars) %>%  
 filter(VC != "Tot") # ignore Tot case for new  
CWE\_test = CaseWantedEffects %>%   
 gather(key=varname, value = calcValue, testVars) %>%  
# gather(key=varname, value = calcValue, fracVMTIncr, NIE, EnergyUse)   
 right\_join(SR\_test, by=c("VC", "TechScen", "varname")) %>%  
 mutate(testDiff = calcValue - testValue)  
  
cat("Calculated values match Scenario test values to within total absolute error ",sum(abs(CWE\_test$testDiff)), ".\n")

## Calculated values match Scenario test values to within total absolute error 6.526996e-09 .

|  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- |
| TechScen | LDV.EIntens | HDV.EIntens | LDV.VMTpveh | HDV.VMTpveh | LDV.EUse | HDV.EUse | Tot.EUse | ScenarioName |
| 2 | -0.7693473 | -0.281500 | 0.6672606 | 0.4289047 | -0.6154418 | 0.0266680 | -0.4470640 | Have our cake & eat it too |
| 7 | -0.1868000 | -0.175000 | 0.1190966 | 0.1099889 | -0.0899506 | -0.0842591 | -0.0884582 | Stuck in the middle at Level 2 |
| 4 | -0.7186037 | -0.281500 | 0.6711643 | 0.6829368 | -0.5297405 | 0.2091901 | -0.3359738 | Strong responses |
| 3 | 0.3420000 | 0.000000 | 0.6467172 | 0.4494060 | 1.2098945 | 0.4494060 | 1.0104748 | Dystopian nightmare |
| 1 | -0.3268132 | -0.192325 | 0.1426323 | 0.1172203 | -0.2307950 | -0.0976491 | -0.1958807 | Cautiously optimistic |
| 5 | 0.0992000 | -0.100000 | 0.0739217 | 0.0797502 | 0.1804547 | -0.0282248 | 0.1257336 | Driver assist, limited other benefits |

## 5.2 Bar Chart Representation of Results

## 5.3 Travel Time Budget

BGR2014:144 (referencing Shaefer et al. 2009) apply a Travel Time Budget constraint in the following straight-forward way:

Travel time (distance *D* over speed *S*) must equal reference travel time. (Appears that they apply this to all travel based on average speed, and assume a 50% increase in average speed.)

More generally, the travel time can be expected to vary in response to travel costs and income.

## 5.4 Physical Constants

## 5.5 Vehicle Scenario Parameters

## [1] 2000.06

## [1] 5.00015e+11

# 6. Simple functions for MPG as a function of highway speed

## 6.1 Fuel Consumption vs. Speed - Thomas et al. Approach

* Source: Thomas, J., Hwang, H.-L., West, B., & Huff, S. (2013). Predicting Light-Duty Vehicle Fuel Economy as a Function of Highway Speed. SAE International Journal of Passenger Cars - Mechanical Systems, 6(2), 2013-01-1113. <doi:10.4271/2013-01-1113>
* Thomas et al. performed “analysis of dynamometer testing results for 74 vehicles at steady-state speeds from 50 to 80 mph [80 to 129 km/h]. Data has been collected for 23 light-duty vehicles at ORNL’s vehicle research laboratory and a valuable data set for 51 vehicles was loaned to ORNL by Chrysler, LLC under a non-disclosure agreement. Vehicles were tested in dynamometer laboratories at steady speeds from 40 to 80 mph [64 to 129 km/h], with the proper road-load applied. … The study includes various sizes of sedans, wagons, and SUVs, as well as pickup trucks, minivans and a few”muscle" and sports cars. Vehicles from model years 2003 to 2012 with a wide variety of powertrains were represented" [ORNL researchers quantify the effect of increasing highway speed on fuel economy](http://www.greencarcongress.com/2013/01/thomas-20130117.html) Jan 18, 2013

**Summary of MPG vs. Speed data: Percent mpg decrease for a given 10 mph increase based on 74 vehicles.**

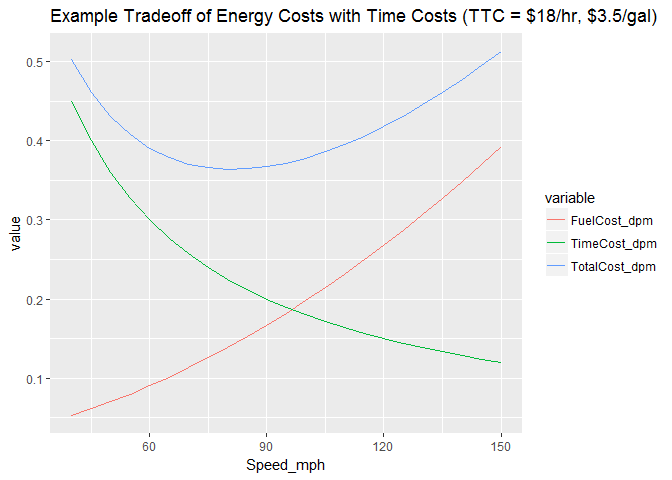
|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| Speed increase | Average | Data range | Std. deviation | Middle 2/3s of vehicle data |
| 50 to 60 mph | 12.4 | 6.9-18.3 | 2.2 | 10.0-14.3 |
| 60 to 70 mph | 14.0 | 8.8-19.5 | 2.6 | 11.2-16.1 |
| 70 to 80 mph | 15.4 | 10.8-26.0 | 3.0 | 12.5-17.5 |
| All three speed increments | 13.9 | 6.9-26.0 | 2.9 | N/A |

We can calculate the percentage decrease in MPG for a range of speed changes using the methodology Thomas, Hwang, West and Huff 2013.

Table: Percent MPG Decreases With Speed (Rows are Ref Speed)

|  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- |
|  | 40 | 50 | 60 | 70 | 80 | 90 | 100 |
| 15 | NA | 5.68 | 6.70 | 7.72 | 8.75 | 9.77 | 10.79 |
| 20 | NA | 6.67 | 7.95 | 9.23 | 10.50 | 11.78 | 13.06 |
| 25 | NA | 7.79 | 9.34 | 10.89 | 12.44 | 14.00 | 15.55 |
| 30 | NA | 8.96 | 10.80 | 12.64 | 14.47 | 16.31 | 18.15 |
| 35 | NA | 10.16 | 12.29 | 14.42 | 16.56 | 18.69 | 20.82 |
| 40 | NA | 11.38 | 13.81 | 16.24 | 18.67 | 21.10 | 23.54 |
| 45 | NA | 12.62 | 15.35 | 18.08 | 20.81 | 23.54 | 26.27 |

## 6.2 Fuel Consumption vs Speed - Berry Approach



## 6.3 Compute the Optimum Highway Speed for a Range of Time Costs and Fuel Costs

# 7. Safety Costs Associated with Speed

* [Road safety - Speed](http://www.who.int/violence_injury_prevention/publications/road_traffic/world_report/speed_en.pdf) World Health Organization, 2004
  + An increase in average speed of 1 km/h typically results in a 3% higher risk of a crash involving injury, with a 4-5% increase for crashes that result in fatalities.
  + Speed also contributes to the severity of the impact when a collision does occur. For car occupants in a crash with an impact speed of 80 km/h, the likelihood of death is 20 times what it would have been at an impact speed of 30 km/h.
* WHO 2004 World report on road traffic injury prevention \*\* Crash Risk\*\*
  + WHO 2004 [World report on road traffic injury prevention](http://apps.who.int/iris/bitstream/10665/42871/1/9241562609.pdf)
  + <http://www.who.int/violence_injury_prevention/publications/road_traffic/world_report/en/>
  + The probability of a crash involving an injury is proportional to the square of the speed. The probability of a serious crash is proportional to the cube of the speed. The probability of a fatal crash is related to the fourth power of the speed (38, 39). [Chap 3, Crash Risk, p.78]
  + Empirical evidence from speed studies in various countries has shown that an increase of 1 km/h in mean traffic speed typically results in a 3% increase in the incidence of injury crashes (or an increase of 4-5% for fatal crashes), and a decrease of 1 km/h in mean traffic speed will result in a 3% decrease in the incidence of injury crashes (or a decrease of 4-5% for fatal crashes) (40).
  + Taylor et al. (41, 42), in their study on different types of roads in the United Kingdom, concluded that for every 1 mile/h (1.6 km/h) reduction in average traffic speed, the highest reduction achievable in the volume of crashes was 6% (in the case of urban roads with low average speeds). These are typically busy main roads in towns with high levels of pedestrian activity, wide variations in speeds and high frequencies of crashes.
  + A meta-analysis of 36 studies on speed limit changes showed, at levels above 50 km/h, a decrease of 2% in the number of crashes for every 1 km/h reduction in the average speed (43).
  + For car occupants in a crash with an impact speed of 50 miles/h (80 km/h), the likelihood of death is 20 times what it would have been at an impact speed of 20 miles/h (32 km/h) (48).

TABLE 3.4: Relative risks of involvement in a casualty crash for speed and alcohol

|  |  |
| --- | --- |
| Speed (km/h) | Speed (relative risk) |
| 60 | 1.0 |
| 65 | 2.0 |
| 70 | 4.2 |
| 75 | 10.6 |
| 80 | 31.8 |

Relative to a sober driver travelling at the speed limit of 60 km/h. (Source: Kloeden et al., 1997. See alos Kloeden et al. 2001)

### 7.1 Severity of crash injuries

* Speed has an exponentially detrimental effect on safety. As speeds increase, so do the number and severity of injuries. Studies show that the higher the impact speed, the greater the likelihood of serious and fatal injury:
  + For car occupants, the severity of crash injury depends on the change of speed during the impact, usually denoted as v. As v increases from about 20 km/h to 100 km/h, the probability of fatal injuries increases from close to zero to almost 100% (46).
  + The probability of serious injury for belted front-seat occupants is three times as great at 30 miles/h (48 km/h) and four times as great at 40 miles/h (64 km/h), compared with the risk at 20 miles/h (32 km/h) (47).
  + For car occupants in a crash with an impact speed of 50 miles/h (80 km/h), the likelihood of death is 20 times what it would have been at an impact speed of 20 miles/h (32 km/h) (48).
  + Pedestrians have a 90% chance of surviving car crashes at 30 km/h or below, but less than a 50% chance of surviving impacts at 45 km/h or above (49, 50) (see Figure 3.3).
  + The probability of a pedestrian being killed rises by a factor of eight as the impact speed of the car increases from 30 km/h to 50 km/h (51).
  + Older pedestrians are even more physically vulnerable as speeds increase (52) (see Figure 3.4).
  + Excess and inappropriate speed contributes to around 30% of fatal crashes in high-income countries (53).
* Safety References
  1. Wegman F, Elsenaar P. Sustainable solutions to improve road safety in the Netherlands. Leidschendam, Institute for Road Safety Research, 1997 (SWOV Report D-097-8).
  2. Ogden KW. Safer roads: a guide to road safety engineering. Melbourne, Ashgate Publishing Ltd, 1996.
  3. Cities on the move: a World Bank urban strategy review. Washington, DC, The World Bank, 2002.
  4. Handboek: categorisering wegen op duurzaam veilige basis. Deel I (Voorlopige): functionele en operationele eisen [Handbook: categorizing roads on long-lasting safe basis. Part I (Provisional): functional and operational demands]. Ede, Stichting centrum voor regelgeving en onderwoek in de grond-, water- en wegenbouw en de verkeerstechniek, 1997 (CROW Report 116).
  5. Zone guide for pedestrian safety shows how to make systematic improvements. Washington, DC, National Highway Traffic Safety Administration, 1998 (Technology Transfer Series Number 181) ([http://](NULL) www.nhtsa.dot.gov/people/outreach/traftech/ pub/tt181.html, accessed 5 December 2003).
  6. Towards a sustainable safe traffic system in the Netherlands. Leidschendam, Institute for Road Safety Research, 1993.
  7. Safety of vulnerable road users. Paris, Organisation for Economic Co-operation and Development, 1998 (DSTI/DOT/RTR/RS7(98)1/FINAL) (http: //www.oecd.org/dataoecd/24/4/2103492.pdf, accessed 17 November 2003).
  8. Ossenbruggen PJ, Pendharkar J, Ivan J. Roadway safety in rural and small urbanized areas. Accident Analysis and Prevention, 2001, 33:485-498.
  9. Khan FM et al. Pedestrian environment and behavior in Karachi, Pakistan. Accident Analysis and Prevention, 1999, 31:335-339.
  10. Herrstedt L. Planning and safety of bicycles in urban areas. In: Proceedings of the Traffic Safety on Two Continents Conference, Lisbon, 22-24 September 1997. Linköping, Swedish National Road and Transport Research Institute, 1997:43-58.
  11. Kjemtrup K, Herrstedt L. Speed management and traffic calming in urban areas in Europe: a historical view. Accident Analysis and Prevention, 1992, 24:57-65.
  12. Brilon W, Blanke H. Extensive traffic calming: results of the accident analyses in six model towns. In: ITE 1993 Compendium of Technical Papers. Washington, DC, Institute of Transportation Engineers, 1993:119-123.

## 7.2 Speed and Accident Risk

* Notes from [Speed and Accident Risk](https://ec.europa.eu/transport/road_safety/specialist/knowledge/speed/speed_is_a_central_issue_in_road_safety/speed_and_accident_risk_en), European Road Safety Observatory
* <https://ec.europa.eu/transport/road_safety/specialist/knowledge/speed/speed_is_a_central_issue_in_road_safety/speed_and_road_safety_en>
* Assessing potential effectiveness of speed reduction measures Based on work by Nilsson in Sweden, a change in average speed of 1 km/h will result in a change in accident numbers ranging between 2% for a 120 km/h road and 4% for a 50 km/h road. This result has been confirmed by many before and after studies of different speed reduction measures. This relationship is used by other Scandinavian countries and by Australian and Dutch safety engineers.
* A similar relationship is assumed in Britain, based on empirical studies by Taylor, where changes in accident numbers associated with a 1 km/h change in speed have been shown to vary between 1% and 4% for urban roads and 2.5% and 5.5% for rural roads, with the lower value reflecting good quality roads and the higher value poorer quality roads.
* Higher speeds: more accidents : High speed reduces the possibility to respond in time when necessary. People need time to process information, to decide whether or not to react and, finally to execute a reaction. At high speed the distance covered in this period is longer. At high speeds the distance between starting to brake and a complete stand still is longer as well. The braking distance is proportional to the square of speed (v2). Therefore, the possibility to avoid a collision becomes smaller as speed increases. This is well illustrated at a broad average level by Finch [24].
* 1 km/h increase in speed implies a 3% increase in accidents
* In practice the relationship is more complex. …The higher the speed, the steeper the increase in accident risk. The relationship between speed and accident risk is a power function:
* Based on the principles of kinetic energy and validated by empirical data, Nilsson [[44](file://D:\Papers\2013AutomatedVehicles\2016CAVEnergyModel\Nilsson,%20G.%20(1982)%20The%20effects%20of%20speed%20limits%20on%20traffic%20crashes%20in%20Sweden.%20In:%20Proceedings%20of%20the%20international%20symposium%20on%20the%20effects%20of%20speed%20limits%20on%20traffic%20crashes%20and%20fuel%20consumption,%20Dublin.%20Organisation%20for%20Economy,%20Co-operation,%20and%20Development%20(OECD),%20Paris)][[45](file:///D:\Papers\2013AutomatedVehicles\2016CAVEnergyModel\Nilsson,%20G.%20(2004)%20Traffic%20safety%20dimensions%20and%20the%20power%20model%20to%20describe%20the%20effect%20of%20speed%20on%20safety.%20Bulletin%20221,%20Lund%20Institute%20of%20Technology,%20Lund)] developed the following formula:
* In words: the number of injury accidents after the change in speed (A2) equals the number of accidents before the change (A1) multiplied by the new average speed (v2) divided by the former average speed (v1), raised to the square power.

# 8. Simple Examination of VMT and PMT Given Pooling

Consider a range of vehicle occupancy levels *o*, where corresponds to the current averable level of vehicle occupancy.

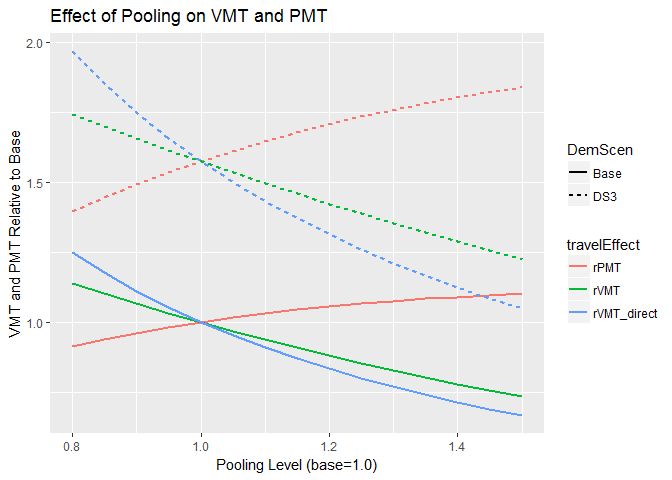
occupancyEffects = data.frame("o" = seq(0.8, 1.5, 0.05))

We establish estimates of vehicle travel cost and its primary components (those related to fuel cost, non-fuel finacial costs, and time costs).

scenData = VTCostBase  
scenData$DemScen = "Base"  
scenData = rbind(scenData, select(VTCostAlt, CostCat, VehType, VTCost\_cpm, DemScen))  
  
# Focus on the base and alt scen cost components for LDV cars  
VehTypeWanted = "LDVAvgSedan"  
DemScenWanted = c("Base", "DS3")  
  
scenData = scenData %>% filter(VehType==VehTypeWanted) %>% spread(key = CostCat, value = VTCost\_cpm)  
scenData = scenData %>%   
 rename(C\_F = Fuel,C\_T = Time) %>%   
 mutate(C\_H = Total - C\_F - C\_T, # combine all (financial) costs other than Fuel and Time. Includes accident  
 C\_V = C\_F + C\_H)  
# Keep only needed variables  
scenData = scenData %>% select(DemScen, C\_F, C\_H, C\_T, C\_V)  
  
# Keep only Base and the Alt scenario of interest  
#scenData = scenData %>% filter(DemScen == "Base" | DemScen == "DS3")  
scenData = scenData %>% filter(DemScen %in% DemScenWanted)  
  
# dplyr fn for full-join with no common vars (all combinations)  
# this gives a df with observations for all levels of occupancy o for each value of DemScen  
# Cost component values are replicated for all occupancy levels, which is correct for costs/veh-mi  
occupancyEffects = crossing(occupancyEffects, scenData)  
  
VoTT\_elas\_wrt\_o = 0.5 # an assumption regarding how occupancy (pooling) increases time cost VoTT  
  
# TravTimeCostBasePars["average\_speed.LDV","average"]  
  
occupancyEffects = occupancyEffects %>%  
 mutate(C\_Vpmt = C\_V/o, # Variable vehicle travel cost per pass-mi [c/pass-mi]  
 rho = o^VoTT\_elas\_wrt\_o, # Time-cost multiplier due to disutility of pooling [unitless]  
 C\_Tpmt = C\_T\*rho, # Time-cost per passenger mile adjusted by the disutility of occupancy [c/pass-mi]  
 Pi = 1/TravTimeCostBasePars["average\_speed.LDV","average"], # assumed pace, (constant over o) [hr/veh-mi]  
 C\_Tdph = C\_T/Pi, # Hourly Time-cost per passenger-hour (for info only) [$/pass-hr]  
 C\_Mpmt = C\_Vpmt + C\_Tpmt # Total cost per passenger mile traveled [c/pass-mi]  
 )  
  
# Now compute VMT and PMT, given travel costs per passenger mile, the elasticity of PMT w.r.t. cost, and occupancy  
ElasPMT = RelTotCost %>% filter(DemScen %in% DemScenWanted, VehType==VehTypeWanted, Case == "Low") %>%  
 .$ElasVKT

occupancyEffects = occupancyEffects %>%  
 ungroup() %>%  
 # relative PMT and VMT (unitless, ref = 1.0 for Base scen, occupancy=1)  
 mutate(  
 rPMT = (C\_Mpmt/C\_Mpmt[o==1.0 & DemScen=="Base"])^ElasPMT,   
 rVMT = rPMT/o  
 ) %>%  
 group\_by(DemScen) %>%  
 mutate( # This is a direct effect of pooling on VMT with no demand response to pooling costs  
 rVMT\_direct = rPMT[o==1.0]/o # excludes the effect of pooling on travel costs (time and financial)  
 ) %>% # but does include the effect of the Alt case on cost and PMT  
 ungroup()

TempoccupancyEffects = occupancyEffects %>%   
 select(DemScen, o, rPMT, rVMT, rVMT\_direct) %>%  
 gather(key= travelEffect, value = value, rPMT:rVMT\_direct)  
  
TempoccupancyEffects %>%  
 group\_by(DemScen, travelEffect) %>%  
 ggplot( aes(x=o, y=value , color=travelEffect, linetype=DemScen)) +   
 geom\_line(size=1.0) +  
 ggtitle("Effect of Pooling on VMT and PMT") +  
 xlab("Pooling Level (base=1.0)") + ylab("VMT and PMT Relative to Base")



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1. We differentiate between transportation services (PKT) and vehicle travel (VKT). [↑](#footnote-ref-1)
2. Additional potential disaggregations include by region, vehicle size class, drivetrain type, and time of day (e.g. operating costs vary by time of day, as described in Bösch et al. 2017). [↑](#footnote-ref-2)
3. We start from the values developed in Wadud, MacKenzie and Leiby 2016. [↑](#footnote-ref-3)
4. Here mode *m* and fuel *f* are initially fixed and suppressed, i.e. *m* = road\_vehicle and *f* = petroleum. [↑](#footnote-ref-4)
5. Note that energy cost implications of automation could also be influenced by the choice of drivetrain/fuel, i.e. the extent to which CAVs are electrifiction compared to Manual Vehicles. This vehicle technology choice could also alter other capital and operating costs. [↑](#footnote-ref-5)