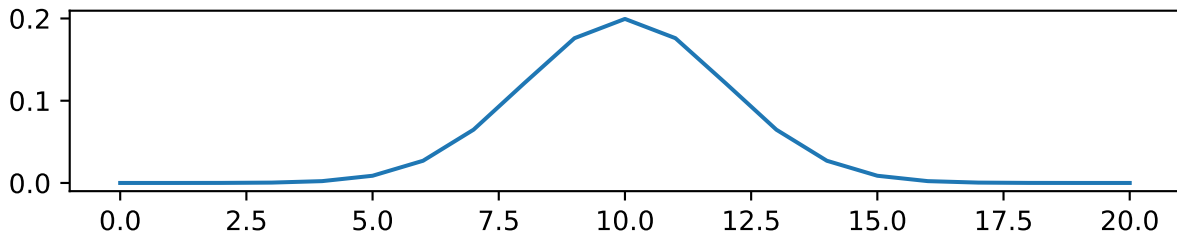
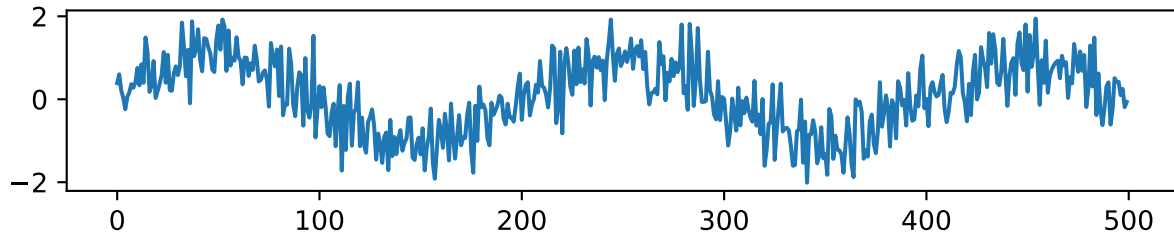


1D Gaussian filter



Sin + Noise



Convolved Sin + Noise

