

# PANAGOTIS LIAMPAS

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## EDUCATION

SEPTEMBER 2024 – JUNE 2028

**BACHELOR'S DEGREE**, MASSACHUSETTS INSTITUTE OF TECHNOLOGY

Undeclared major, aspiring Electrical Engineering and Computer Science

JUNE 2023

**SENIOR HIGH SCHOOL DIPLOMA**, MANDOULIDES SCHOOL

G.P.A: 19.8 on a 20.0 scale

JUNE 2020

**JUNIOR HIGH SCHOOL DIPLOMA**, MANDOULIDES SCHOOL

G.P.A: 19.9 on a 20.0 scale

## OLYMPIADS

- **Mathematics**

**2023 Silver Medal** (1 place from Gold) in the **2022 International Mathematical Olympiad (IMO)** in Chiba, Japan

**2022 Silver Medal** in the **2022 International Mathematical Olympiad (IMO)** in Oslo, Norway

**2023 Silver Medal** (1 place from Gold) in the **Balkan Mathematical Olympiad (BMO)** in Turkey

**2022 Silver Medal** in the **Balkan Mathematical Olympiad (BMO)** in Cyprus

- **Astronomy – Astrophysics**

**2021 Bronze Medal** in the 14<sup>th</sup> **International Olympiad in Astronomy and Astrophysics (IOAA)** in Bogota, Colombia.

- **Informatics**

**2023 Bronze Medal** in the **Balkan Olympiad in Informatics** in Slovenia

**2021 Honorable Mention** (2 places from Bronze) in **Balkan Olympiad in Informatics** (online)

**2021, 2022, 2023** Participated in the **International Olympiad in Informatics**

## SKILLS

### Language Skills

- English: CPE (*Certificate of Proficiency in English*) (CEFR C2 level)
- French: Delf (CEFR B1 Level)

### Technology Skills

- Building and programming autonomous robots (including mechanical components like motors) with Arduino and Raspberry Pi circuit boards.
- Designing PCB circuit boards using Fritzing and EasyEDA.

- Programming Android applications using Android Studio and Windows UWP or .NET apps using Visual Studio and connecting them with online databases.
- Programming in C++, C#, Java and Python.
- Website designing and data dashboard using HTML, CSS and JavaScript along with database access using PHP.
- Building physics simulations using Unity.
- Designing robotic mechanisms' parts using Fusion 360 and 3D-printing them.
- Internet of Things connectivity, using LoRaWAN modules and sensors and the TTN network, or Wi-Fi and GSM modules along with arduino and the suitable sensors. I can connect these to an online database using PHP and SQL.
- Knowledge in Computer Vision and Machine Learning, and implementation using the Python libraries TensorFlow and OpenCV.
- Experience in training Neural Networks using TensorFlow, as well as applying Q-learning for determining the optimal policy for a Markov Decision Process.
- Knowledge in inverse kinematics and control loop mechanisms (like PID controller).
- Knowledge in Dynamical Systems and predicting their evolution, read "Nonlinear Dynamics And Chaos" by Steven H. Strogatz.
- Knowledge in Braitenberg Vehicles and their properties, as well as their connection to human psychology, read "Vehicles: Experiments in Synthetic Psychology" by Valentino Braitenberg.
- Knowledge in Robotics, Localization, Mapping and Planning, read "Probabilistic Robotics" by Sebastian Thrun.

## INTERNSHIPS

**2023** 2-month internship at Epsilon Orosimo Software, where I developed custom extension modules for the Pylon ERP software using C#, and converted existing ones from another software, that enhance the capabilities and integrate custom operations in the UI, logic and database aspects of it.

**2022** 3-month internship in Alpha Systems and implemented an IoT weather station, which is connected using LoRaWAN to the TTN Network and the Tago.io platform, and presents the data in a dashboard. I also cooperated with the Nokia technical team to integrate them with the Nokia IOC platform.

## PROJECTS

### Technology and Programming

- A 3D printed robot that uses the Robot Operating System (ROS) and Simultaneous Localization and Mapping (SLAM) algorithms to map, locate itself, and navigate around an unknown area. ([Article](#), [GitHub](#))
- A remotely controlled prototype of a rover with integrated sensors that can potentially be used to determine the habitability of a planet and show the data, the results and the rover's route in a website, an android app and a windows app. ([Website](#), [GitHub](#))
- An autonomous robot that can detect objects, track, and catch them with its robotic hand, using computer vision and machine learning. ([GitHub](#))
- A system which uses machine learning to automatically detect empty parking lots and highlight them in a website, which was given for use by the municipality and the local community to solve the problem of the difficulty finding parking spaces. ([Municipality Website](#), [System Website](#), [GitHub](#))

- A system that measures the humidity of the soil under some plants and sends the data to a website to be used to determine the amount of irrigation needed. ([Website](#), [GitHub](#))

## RESEARCH

Dr. Kevrekidis (Johns Hopkins):

- Training a Neural Network (using TensorFlow) to predict the behavior of the Reduced MSP Model, from the dynamical system described in the paper: “[On the parameter combinations that matter and on those that do not](#)”, based on data derived from time integration of the system with various parameters and start states, using the Runge-Kutta method.

Dr. Koumoutsakos (Harvard):

- Implementing a simulated environment for Braitenberg vehicles, where there are multiple sources of different types and some constrained areas where the vehicles cannot enter. We examine their behavior when multiple vehicles interact with each other, with many sources and many constrained areas. Also exploring innovative applications in various scientific areas.

Mine:

- **Wrote a research paper** called “[Risk-averse Batch Active Inverse Reward Design](#)”: an improved version of “[Active Inverse Reward Design](#)”, to improve safety and robustness of AI models and reduce uncertain, potentially dangerous behaviors after deployment. Specifically, I implemented a process that finds the intended reward function by asking queries to the human, and repeating that process on real-world data, allowing its adaptability to new environments and improving its efficiency. It also takes the actions that are the most certain, increasing the safety and control over the process.

## PROGRAMS

- **Won the Third Prize (4<sup>th</sup>-8<sup>th</sup> place), and \$1000 in funding** (and \$500 scholarship for all participants), in the [Non-Trivial Fellowship](#), for designing the RBAIRD process described in the research section.
- Innovate student in [The Knowledge Society](#) Global Virtual program.
- BlueDot Impact AI Safety Fundamentals [AI Alignment Course](#).

## MENTORING/TUTORING

**2023/24** Mathematics tutoring for students at Zografeion Lyceum of Constantinople.

**2022/23 & 2023/24** Mathematics and Informatics Olympiad tutoring for students at my school.

**2022/23** Mentoring of the robotics team of school “Mandoulides” for their participation in the National Robotics Competition FLL.

## VOLUNTEERING

- A volunteer at **Greenpeace Greece** team of Thessaloniki, for an initiative to identify all the public water taps of Thessaloniki, inform citizens to use them to fill their own bottles, and convince the municipality to fix the malfunctioning ones. I am part of the **coordinating team** for the volunteers of Thessaloniki, responsible for presenting the project to citizens and municipalities, and organizing initiatives. I am also a (volunteer) **developer of the website** where those water taps are presented, including their location, status, and additional information.
- **2 weeks volunteering at Arcturos**, taking care of Greek Shepherds on November 13th-26th, for 8 hours/day.

## ONLINE UNIVERSITY COURSES

Completed the following MITx courses from edX:

- Circuits and Electronics 1: Basic Circuit Analysis
- Circuits and Electronics 2: Amplification, Speed, and Delay ([Certificate](#))