### **OPTIMISATION**

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#### COURSE-WORK

# The final report should be submitted electronically on Blackboard by the 18th of December 2016

## Part I

To compare the performance of optimisation methods it is customary to construct *test* functions and then compare the behavior of various optimization algorithms for such functions. One, often used, test function is the so-called Rosenbrock function, *i.e.* 

$$v(x,y) = 100(y - x^2)^2 + (1 - x)^2.$$

- A1) Compute analytically all stationary points of the function v(x, y) and verify if they are minima/maxima/saddle points.
- A2) Plot (using Matlab or a similar SW) the level sets of the function v(x, y).
- A3) Implement (in Matlab or a similar SW) procedures for the minimization of the function v(x,y) using the gradient method (see Section 2.5) with Armijo line search (see Section 2.4.2).
- A4) Implement (in Matlab or a similar SW) procedures for the minimization of the function v(x, y) using Newton method (see Section 2.6) with Armijo line search.
- A5) Implement (in Matlab or a similar SW) procedures for the minimization of the function v(x, y) using the Polak-Ribiere algorithm (see Section 2.7.3) with Armijo line search.
- A6) Implement (in Matlab or a similar SW) procedures for the minimization of the function v(x, y) using the Broyden-Fletcher-Goldfarb-Shanno algorithm (see Section 2.8) with Armijo line search.
- A7) Implement (in Matlab or a similar SW) procedures for the minimization of the function v(x, y) using the simplex method (see Section 2.9).
- A8) Run the minimization procedures written in points A3) to A7) with initial point  $(x_0, y_0) = (-3/4, 1)$ .
  - A8a) Plot, on the (x, y)-plane, the sequences of points generated by each algorithm. Are these sequences converging to a stationary point of v(x, y)?
  - A8b) For a sequence  $\{x_k, y_k\}$  consider the cost

$$J_k = \log \left( (x_k - 1)^2 + (y_k - 1)^2 \right).$$

Plot, for each of the sequences generated by the above algorithms, the cost  $J_k$  as a function of k. Use such a plot to assess the speed of convergence of each of the considered algorithms.

## Part II

Consider the constrained minimization problem

$$\min_{x_1, x_2} = -x_1 x_2$$
$$x_1 + x_2 - 2 = 0.$$

- B1) Write the necessary conditions of optimality and find all points satisfying such conditions.
- B2) Check if the candidate optimal points obtained in B1) are constrained local minima.
- B3) By solving the equation of the constraint transform the considered constrained optimization problem into an unconstrained problem.
- B4) Construct the exact penalty function G(x) associated to the considered problem (see Section 3.4.3). Minimize analytically the function G(x) and show that the unconstrained minimum of G(x) is a solution of the considered constrained optimization problem.
- B5) Construct the exact augmented Lagrangian function  $S(x,\lambda)$  associated to the considered problem (see Section 3.4.4). Minimize analytically the function  $S(x,\lambda)$  and show that the unconstrained minimum of  $S(x,\lambda)$  yields a solution of the considered constrained optimization problem and the corresponding optimal multiplier.