

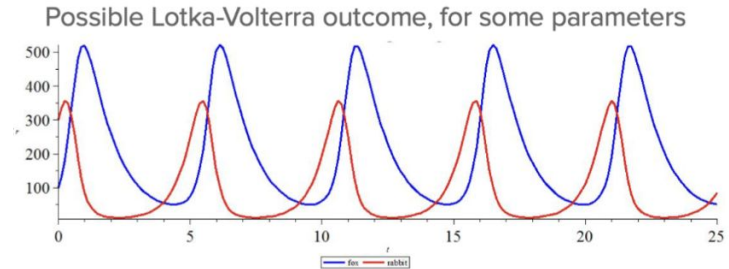
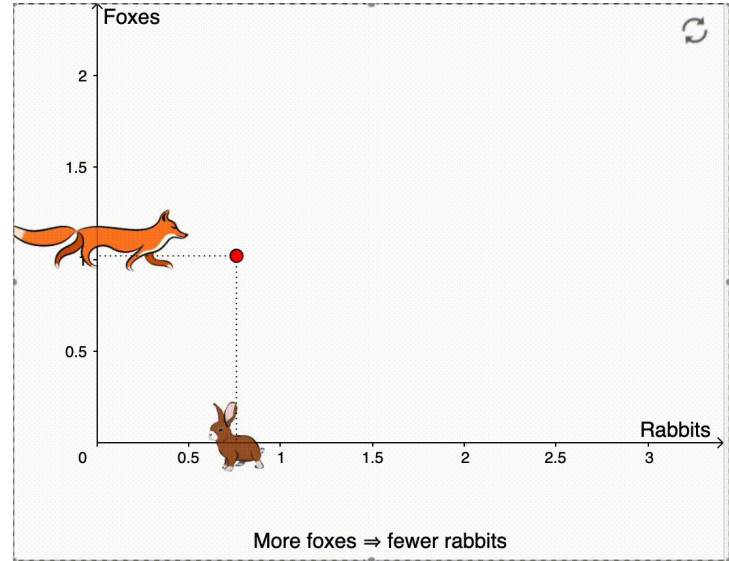


# Game-based Understanding of Replication and Trophic cycles

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# Introduction - Problem description

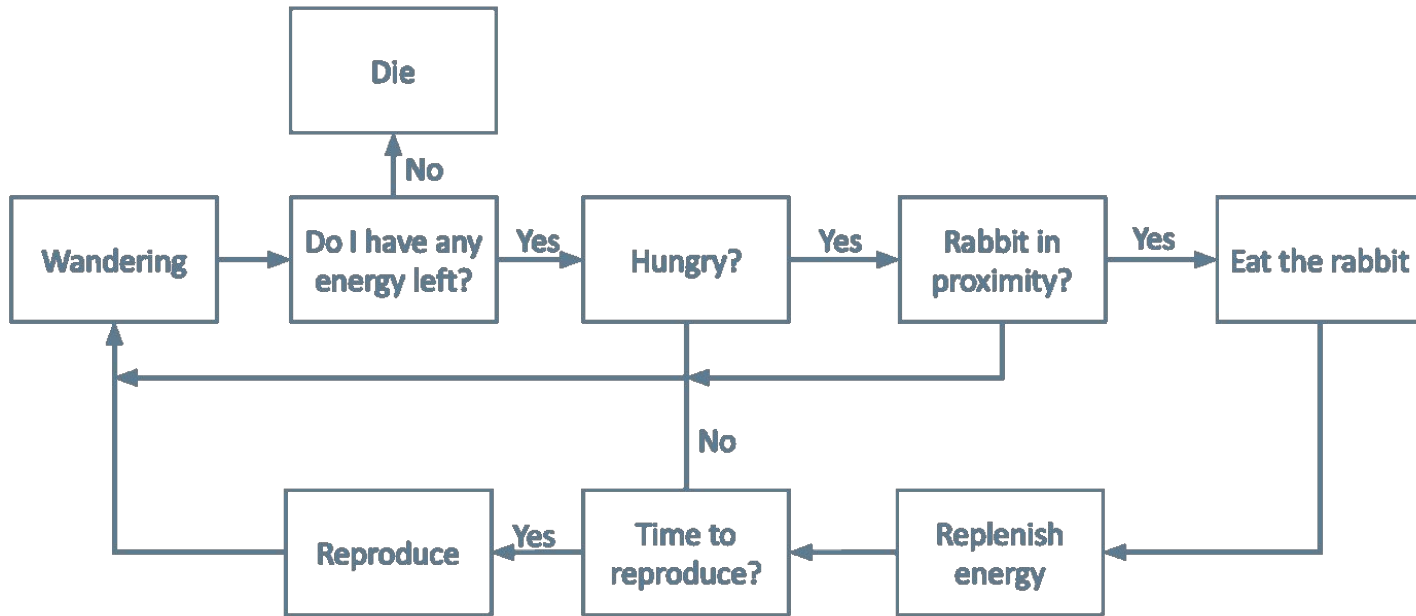
- Predator-prey competition is commonly modeled using the Lotka-Volterra model.
- This model describes how predator and prey populations change over time through hunting and reproduction.
- We use an agent-based approach to simulate predator-prey dynamics with foxes and rabbits, based on local interactions without global control.
- Survival is the primary objective for all agents: foxes hunt rabbits, rabbits reproduce and avoid predation.
- The agent-based model starts from a Lotka-Volterra-inspired baseline and is extended with an energy mechanism to enable direct comparison.
- In the energy-enabled model, key parameters are systematically varied to analyze their impact on population dynamics.
- The challenge: how does introducing energy-based survival change population dynamics?



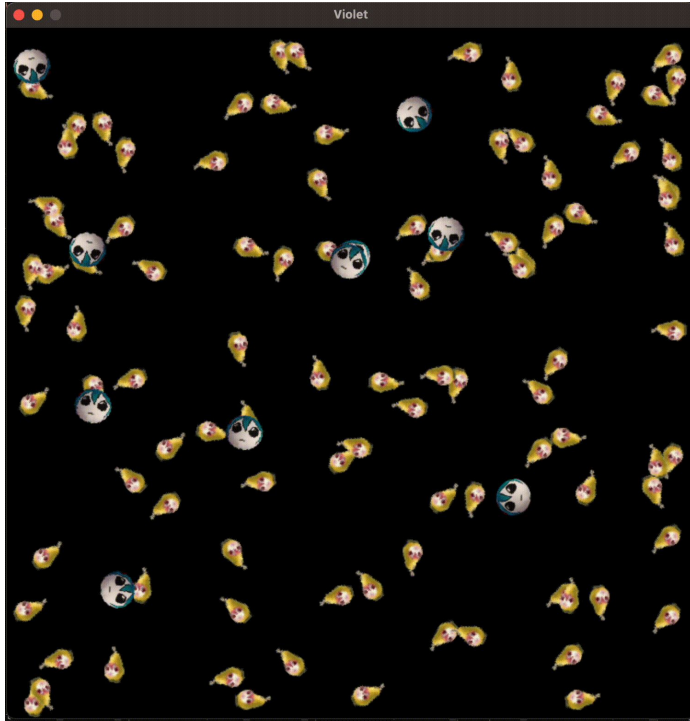
# Introduction - Purpose of the simulation

- Explore how energy mechanisms affect predator-prey population dynamics.
- Analyze oscillations in ecosystems with and without energy-based survival.
- Investigate how different parameters influences extinction risk and population cycles.
- Understand the role of resource availability and hunting pressure on collective system behavior.

# Introduction - Energy-based survival mechanism



# Introduction - Simulation Explanation



Predator: Miku (fox)



Prey: Pearto (rabbit)

Environment: Agents move within a bounded area edges act as solid boundaries (agents bounce off).

Simulation termination conditions:

- All foxes dead
- All rabbits dead
- Maximum of 2000 ticks reached

# Introduction - Parameters

Testing method: Grid search, vary one parameter at a time, others fixed.

Goal: Isolate effects on population dynamics, and extinction risk.

## Shared between both scenarios:

- rabbit\_movement\_speed: how fast rabbits move. Values: [1.0, 2.0, 3.0]
- fox\_movement\_speed: how fast foxes move. Values: [2.0, 3.0, 4.0]
- rabbit\_perception\_radius: how far rabbits can detect foxes. Values: [40, 60]
- fox\_perception\_radius: how far foxes can detect rabbits. Values: [60, 80]

## Energy-free scenario only:

- fox\_spontaneous\_death\_chance: chance of fox dying spontaneously. Values: [0.005, 0.01]
- rabbit\_reproduce\_chance: chance for rabbits to reproduce. Values: [0.005, 0.01]

## Energy-enabled scenario only:

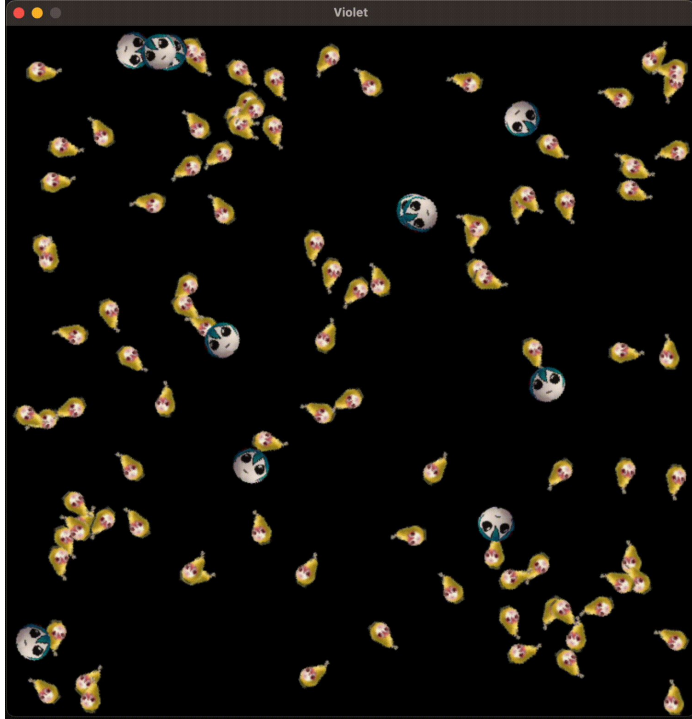
- fox\_initial\_energy: initial energy level of foxes. Values: [50.0, 100.0, 150.0]
- fox\_energy\_decay\_rate: rate at which foxes lose energy over time. Values: [0.25, 0.5, 0.75]
- rabbit\_energy\_gain: energy gained by foxes after hunting a rabbit. Values: [5.0, 10.0, 15.0]
- fox\_starvation\_threshold: energy level at which foxes die. Values: [0.0, 10.0]



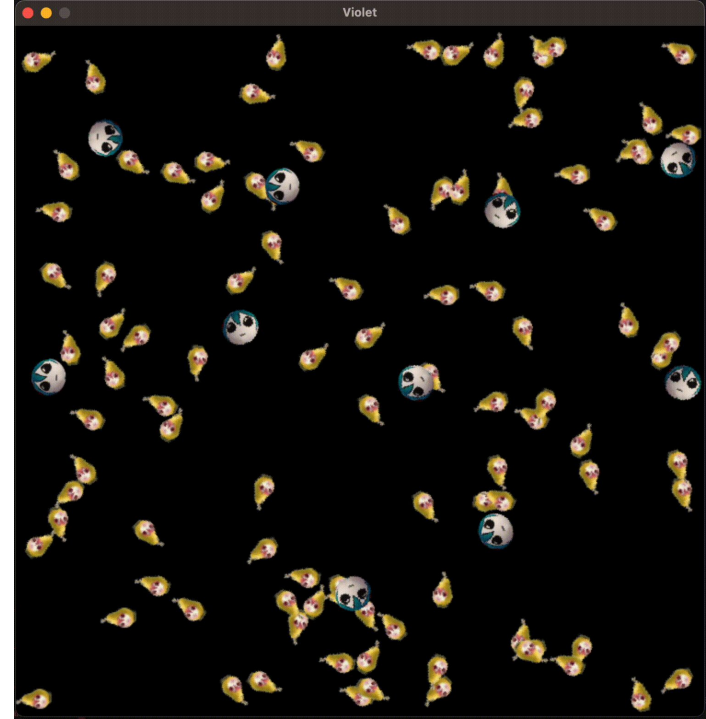
# Introduction - Type of analysis being done

- Two experimental conditions:
  - Energy-free baseline.
  - Energy-enabled model with fox energy-based survival mechanism.
- Systematically test one parameter at a time, keeping others constant.
- Observe population dynamics:
  - How do population cycles and extinction risks change?
- Metrics used:
  - Population time series.
  - Extinction times.
  - Peak populations.
  - Average fox energy (energy-enabled only).
- Plot results using various metrics and comparisons across scenarios.

# Introduction - Example of two simulation scenarios



energy\_free



energy\_enabled



# Introduction - Research Question



- How does introducing energy-based survival in predators affect population dynamics and extinction risk in an agent-based predator-prey model?

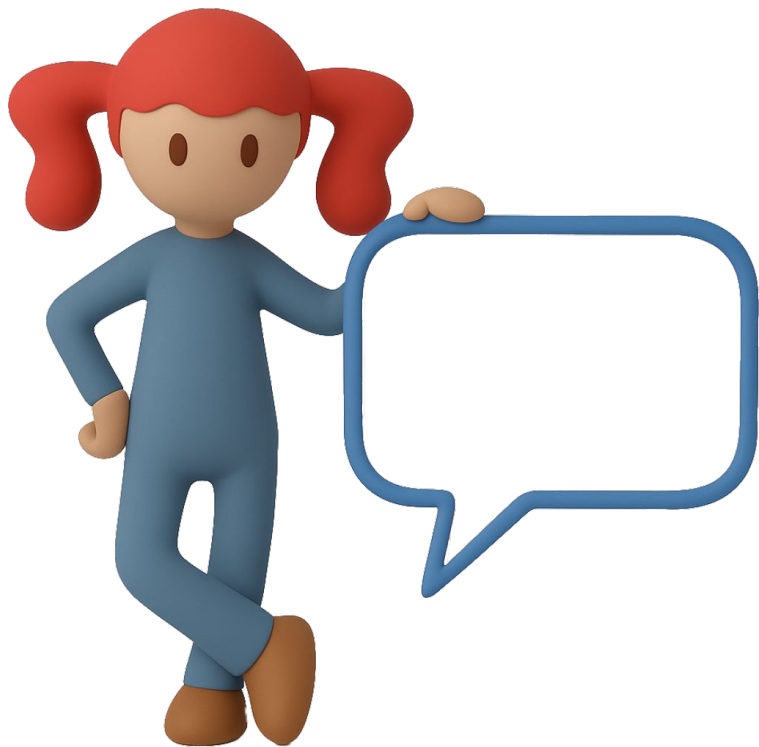
# Methodology

Agents simulate predator-prey dynamics in a 2D environment:

- Foxes (predators) hunt rabbits (prey).
- Rabbits reproduce probabilistically.
- Agents' behaviour is determined by multiple parameters.

Scenarios:

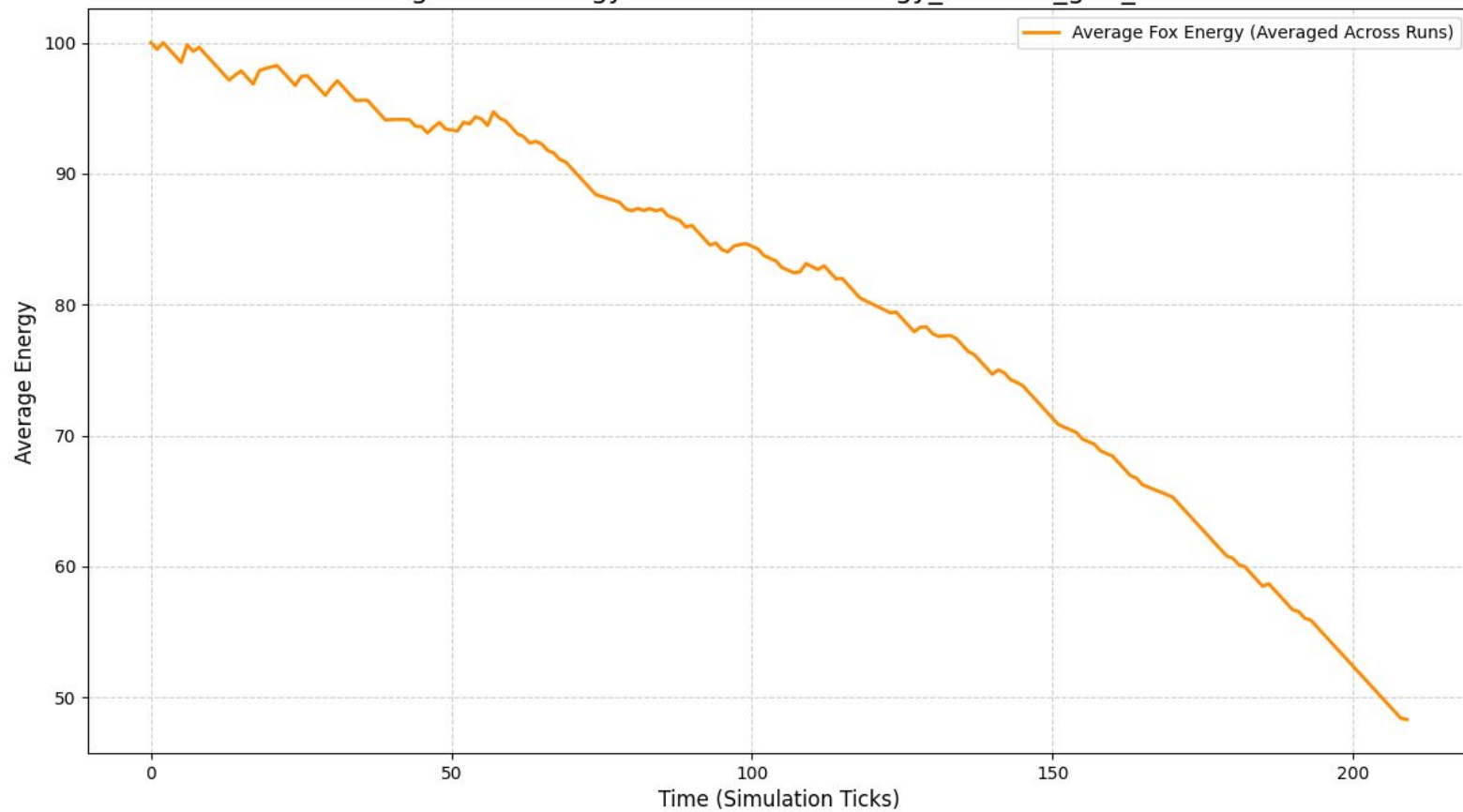
- Baseline test: energy-free.
  - Grid search on combinations of probabilistic parameters.
  - Multiple runs per combination, results averaged.
  - One parameter varied at a time, others fixed.
- Control test: energy-enabled.
  - Same approach, but with energy-based survival mechanism enabled.
  - Grid search energy related parameters.



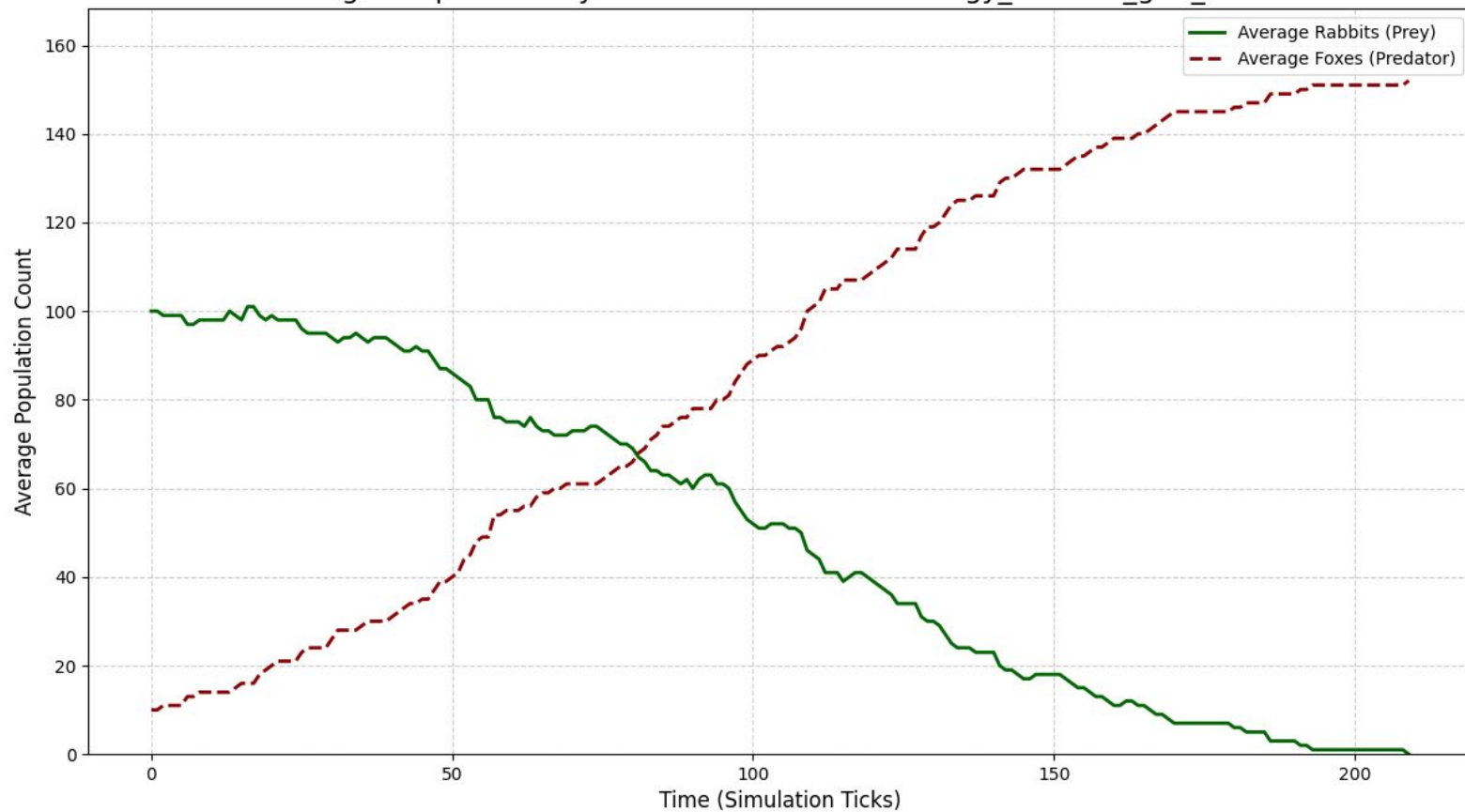
# Results

Energy enabled

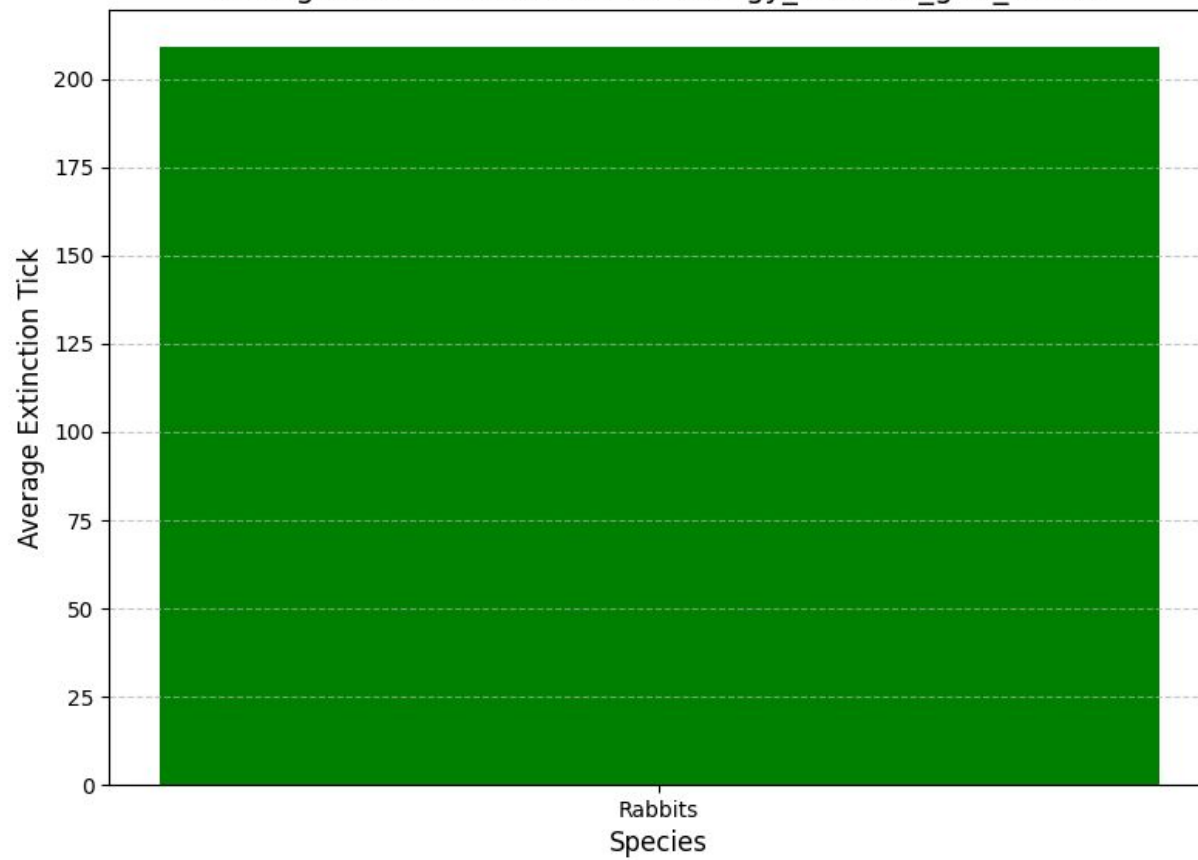
Averaged Fox Energy Over Time for energy\_enabled\_grid\_search



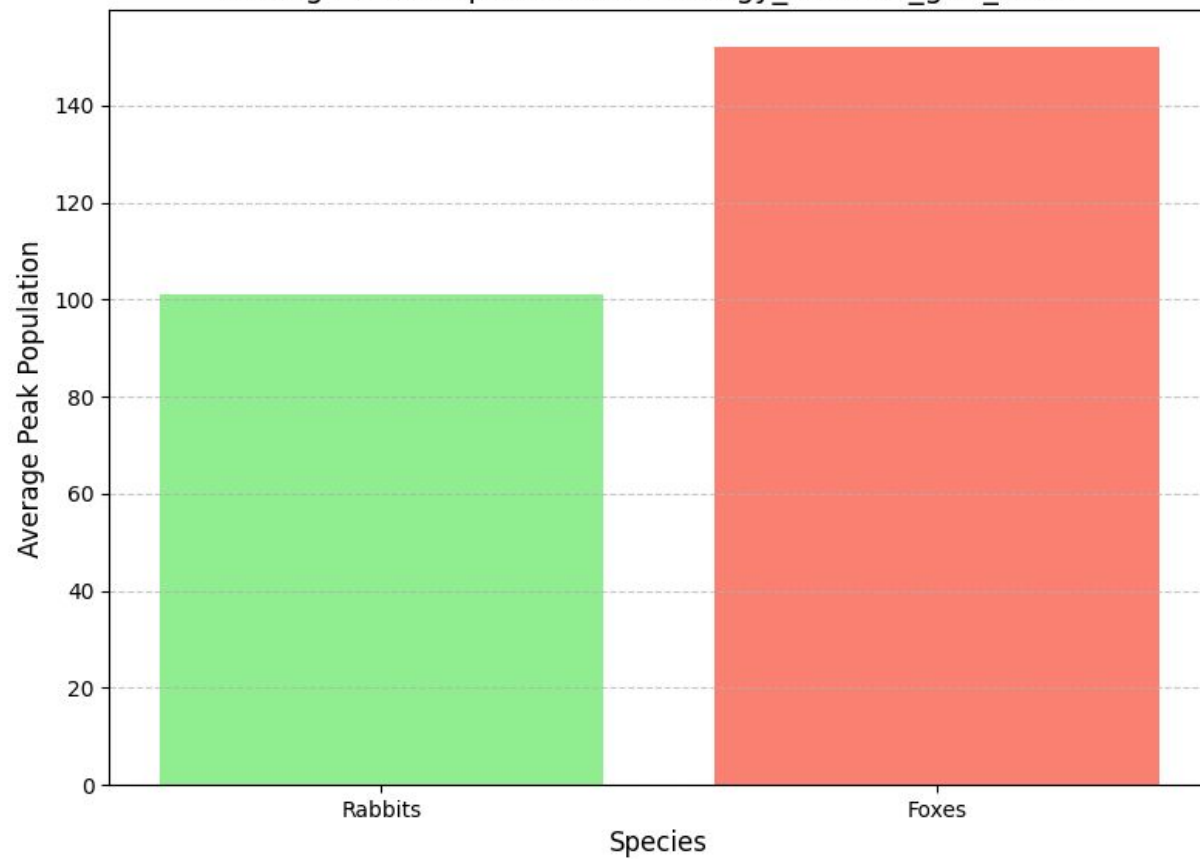
Averaged Population Dynamics Over Time for energy\_enabled\_grid\_search

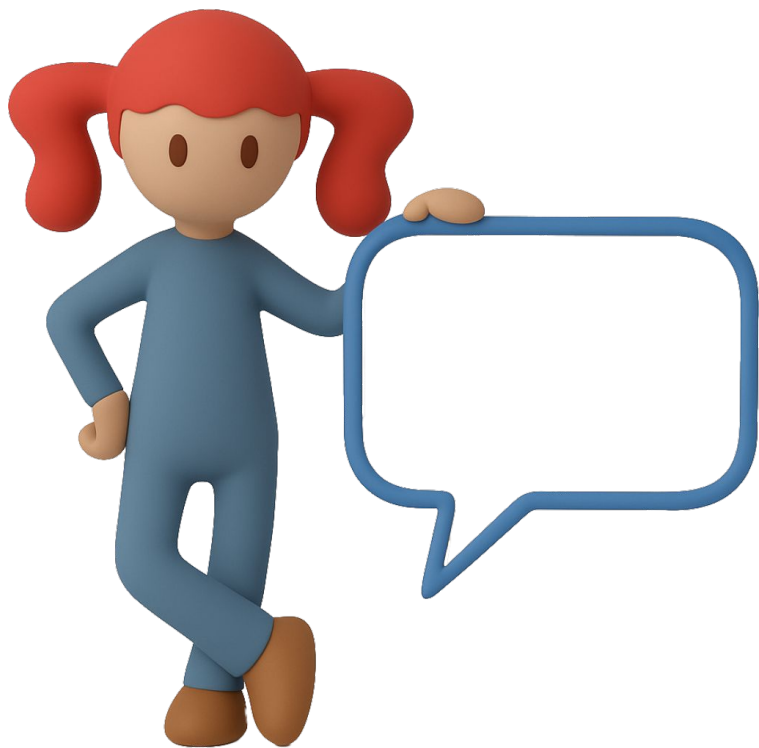


Average Time to Extinction for energy\_enabled\_grid\_search



Average Peak Populations for energy\_enabled\_grid\_search



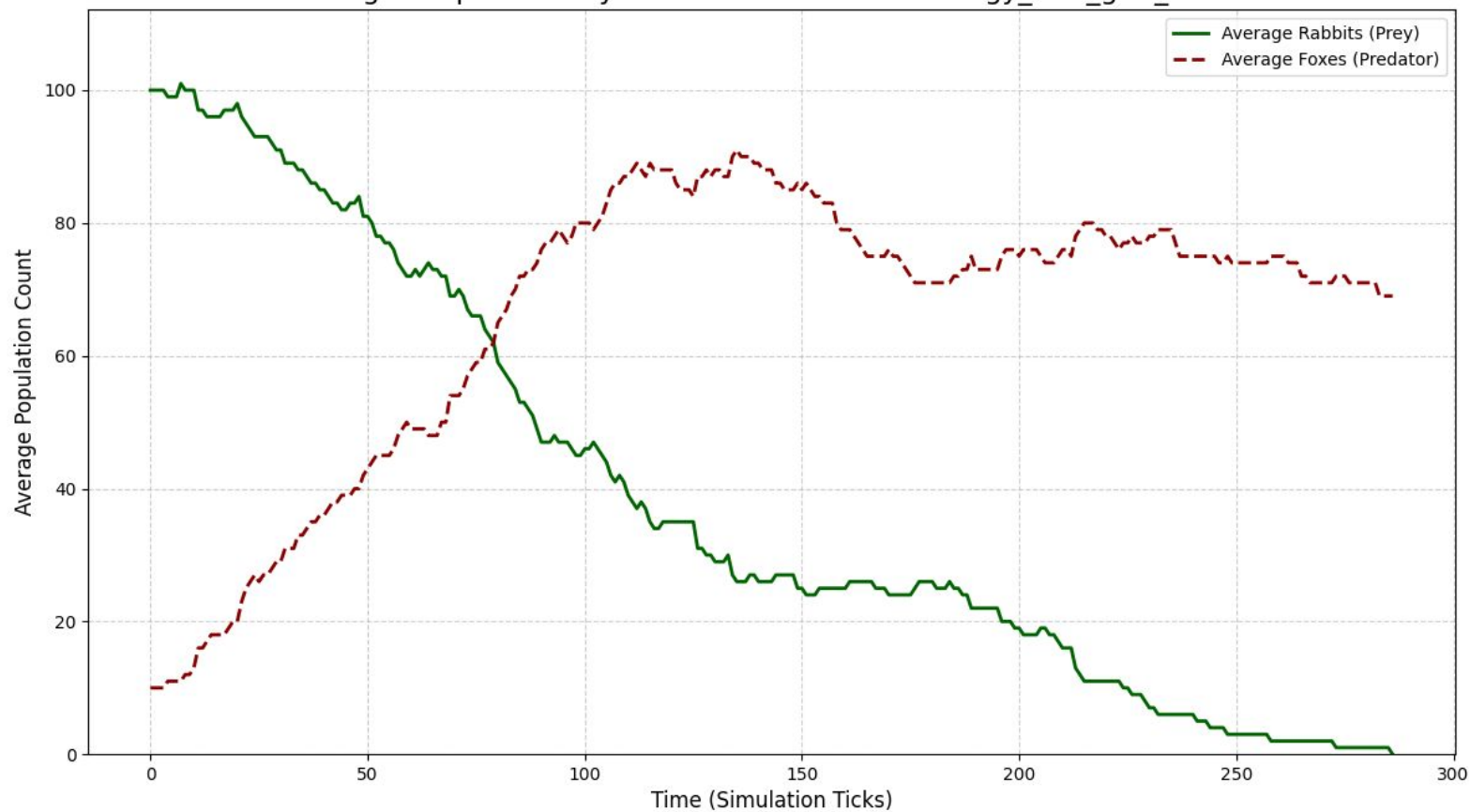


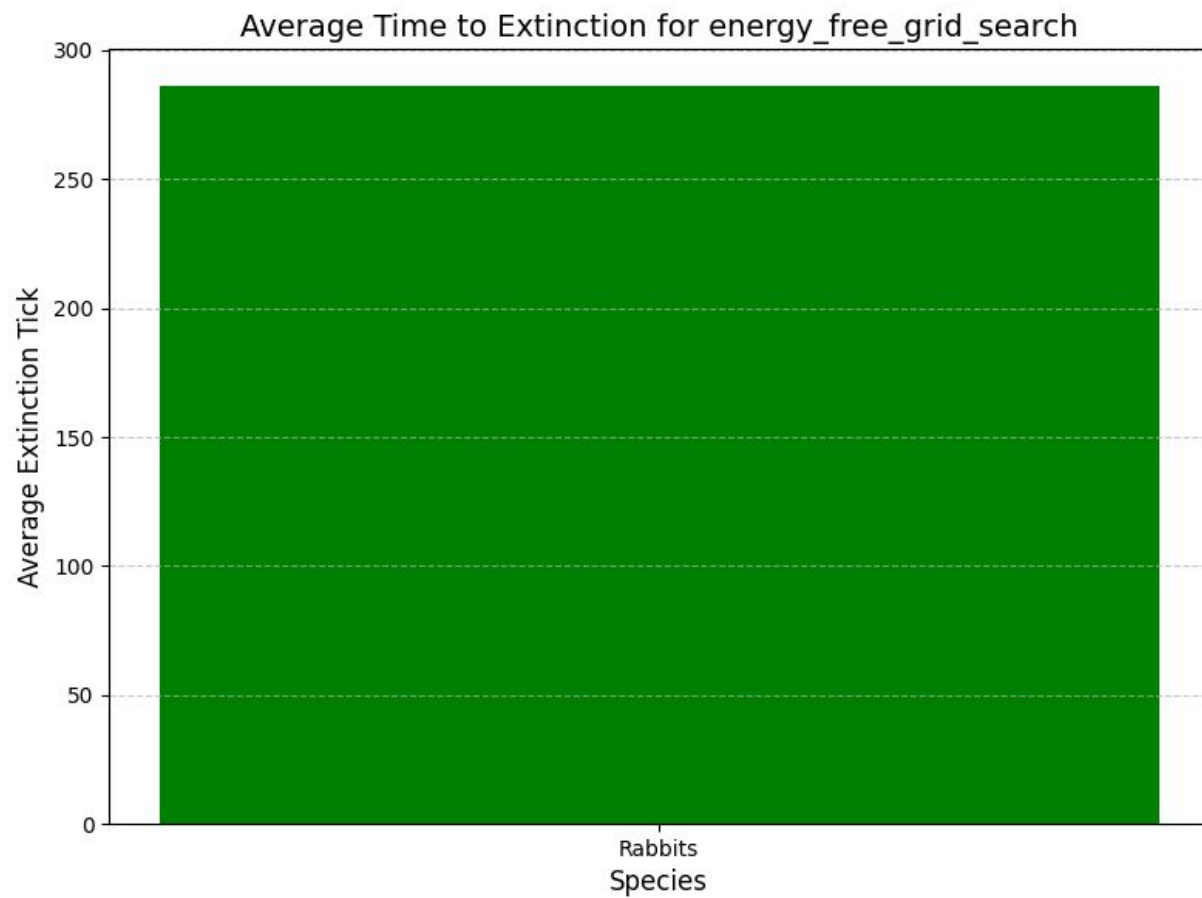
# Results

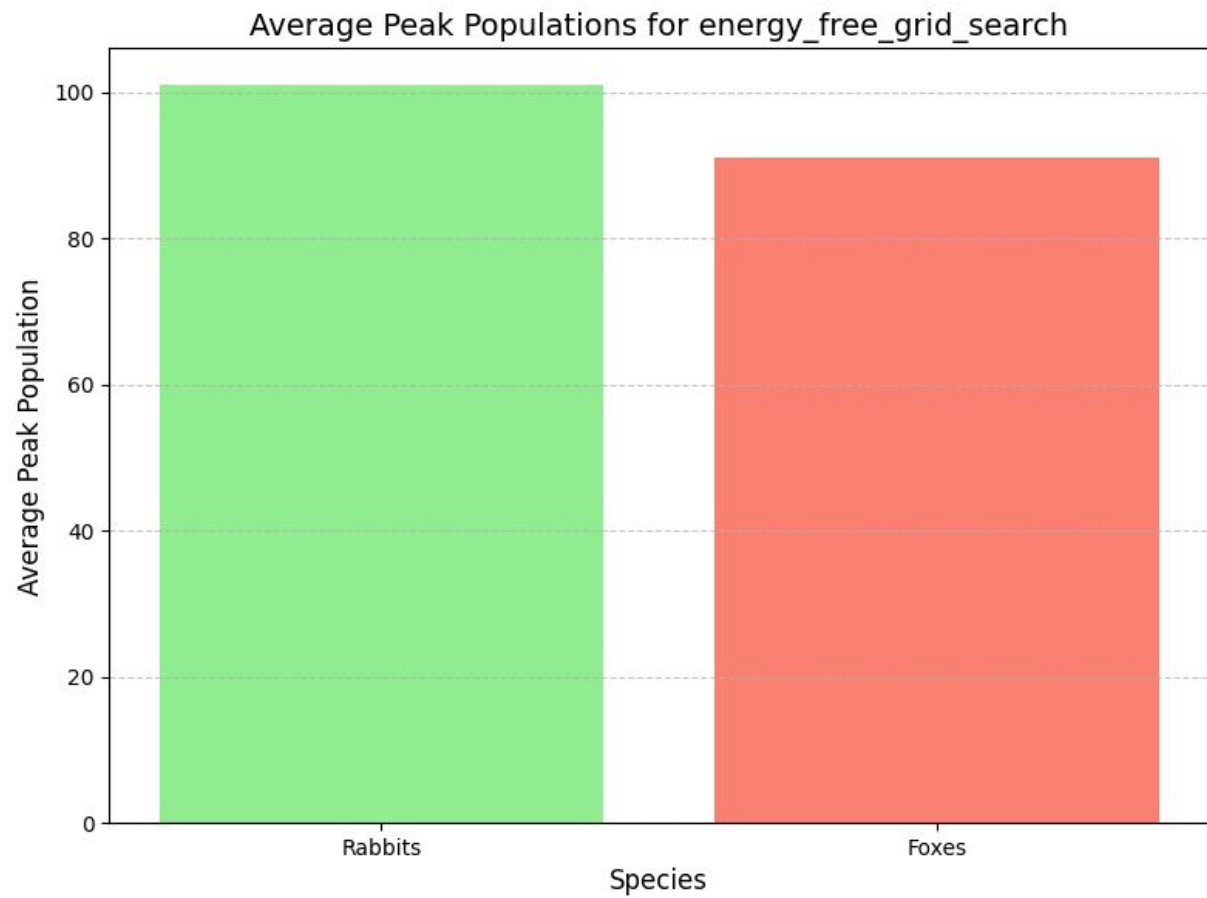
Energy free

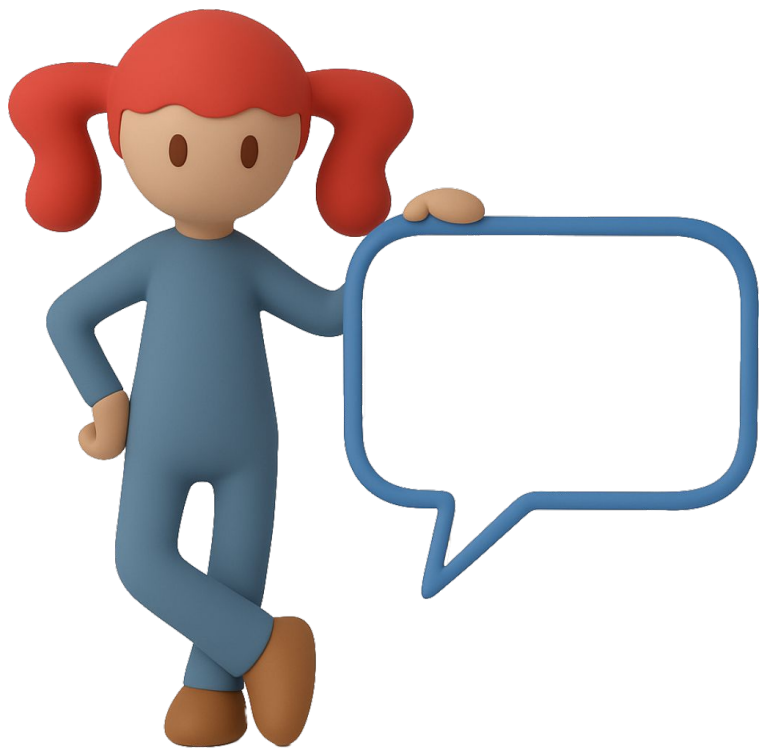


Averaged Population Dynamics Over Time for energy\_free\_grid\_search





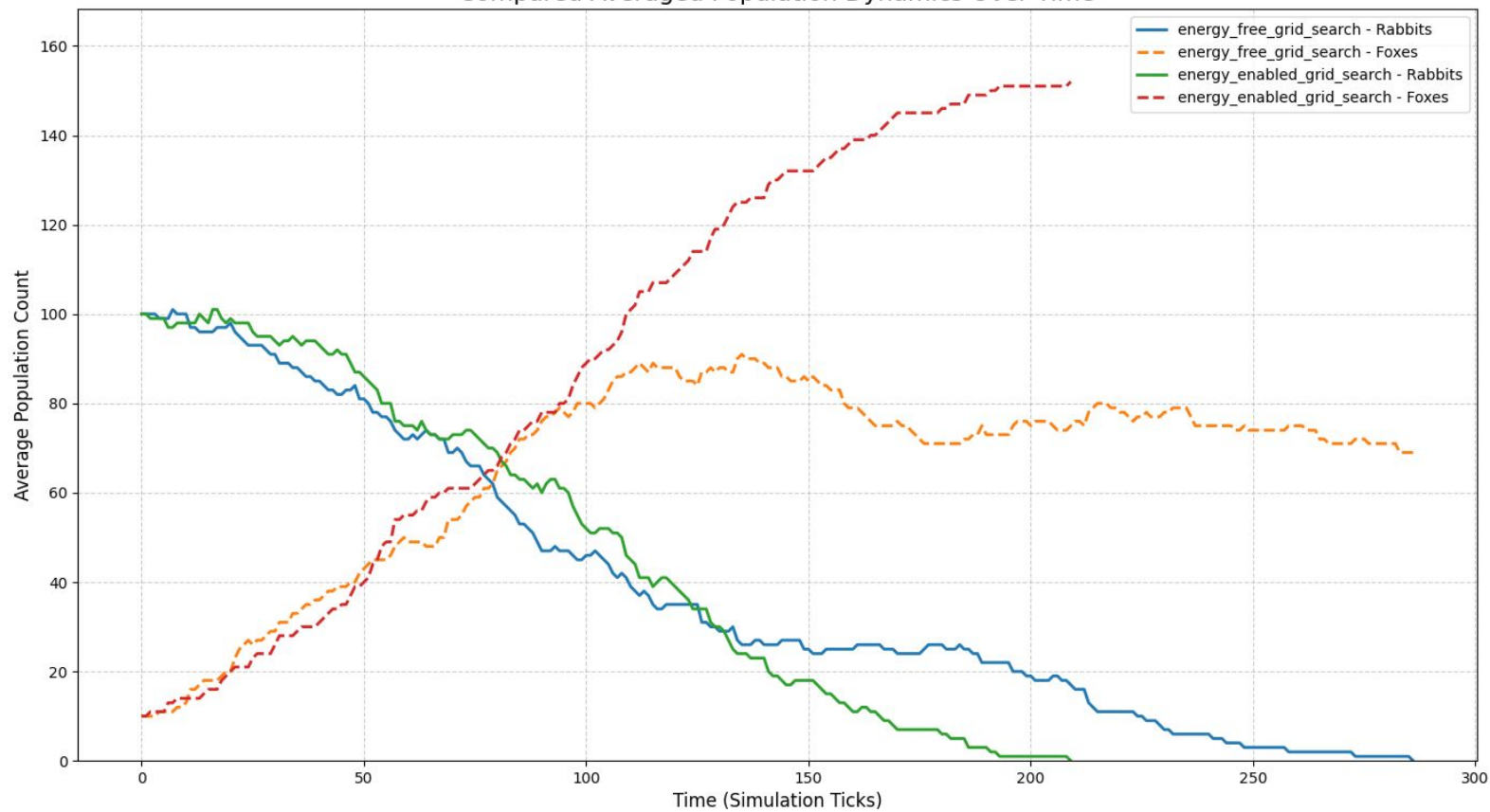




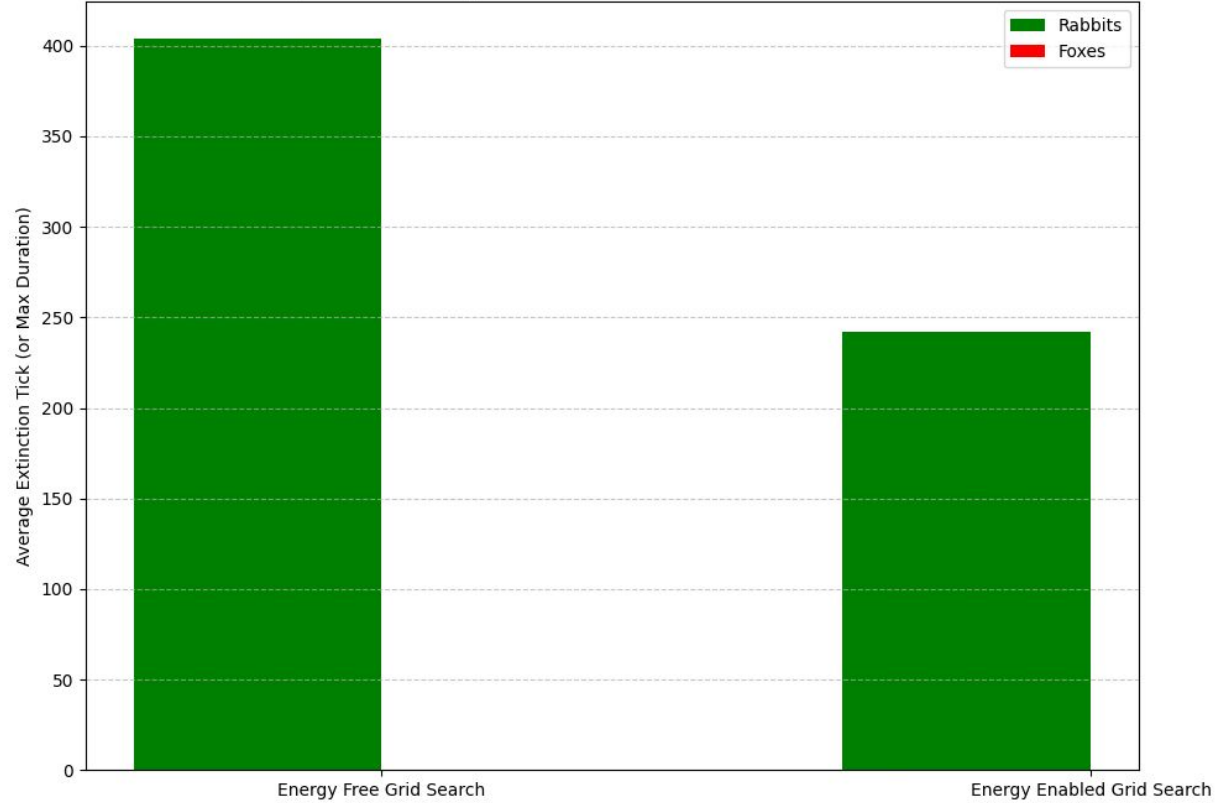
# Results

Combined

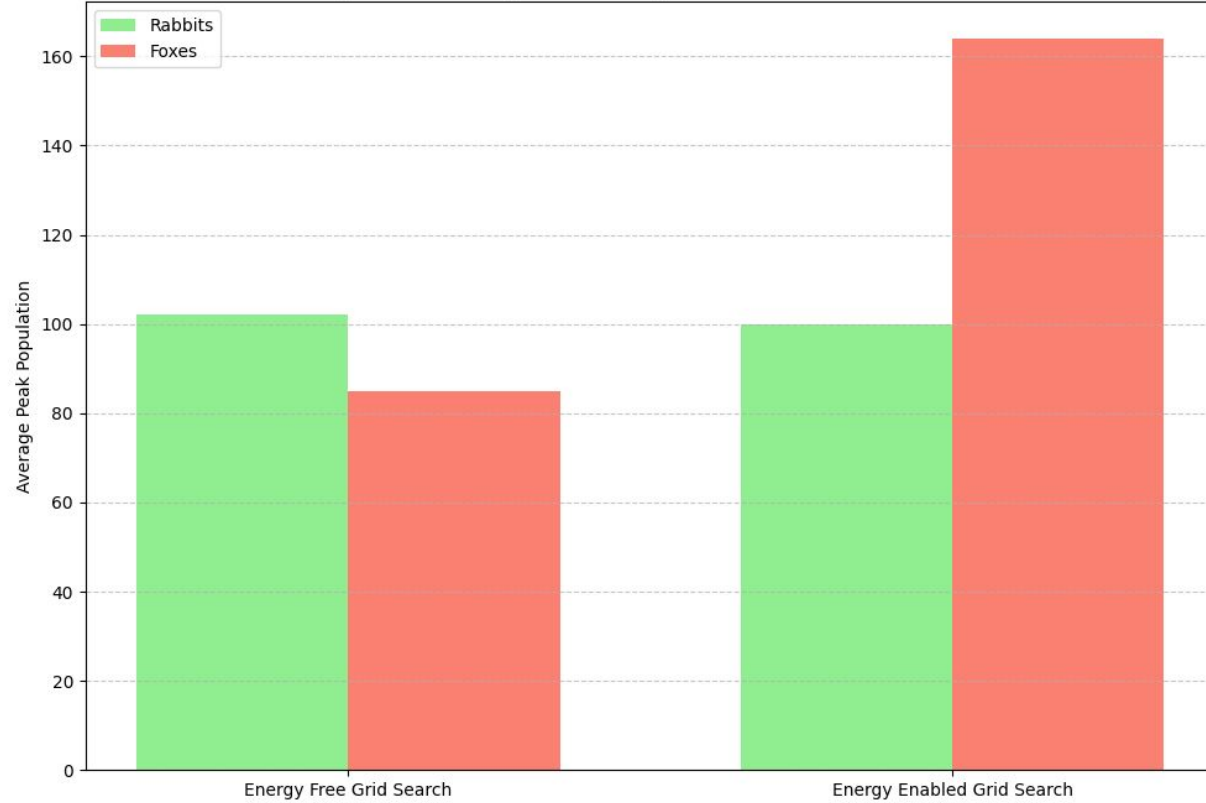
Compared Averaged Population Dynamics Over Time



Compared Average Time to Extinction Across Scenarios



Compared Average Peak Populations Across Scenarios



# Conclusions



Introducing an energy-based survival mechanism for predators significantly alters the dynamics of the model.

Compared to the baseline, it leads to:

- Increased fox peak population.
- Unchanged rabbit population.
- Reduced rabbit extinction time.
- Unchanged fox extinction time.
- More volatile population dynamics.



# Future work



Extra features that can be added in future:

- Different FOVs for predators and prey
- Movement speed change based on age
- Energy mechanic for prey
- Two agent reproduction
- Group behaviours, such as flocking
- Different space zones, such as grass fields



# Thank you

For paying attention

