

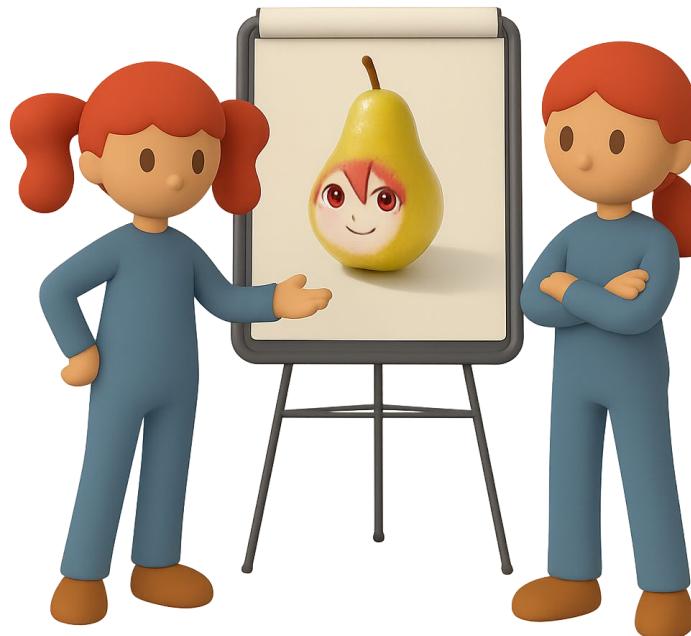


# Game-based Understanding of Replication and Trophic cycles

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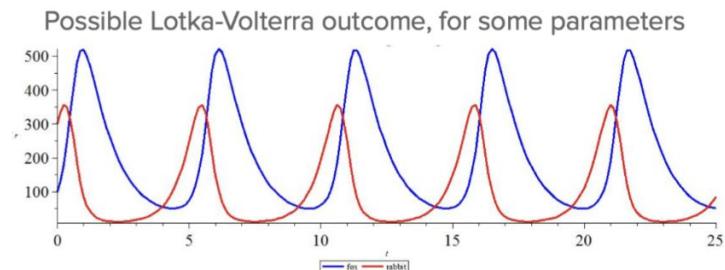
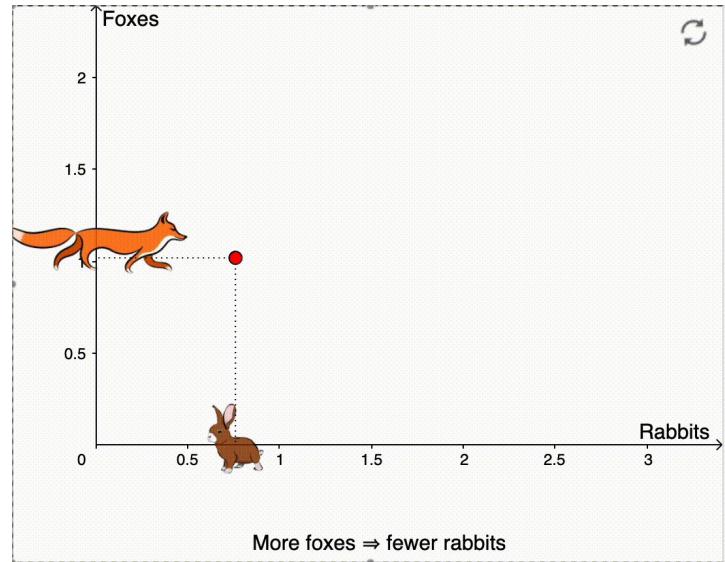




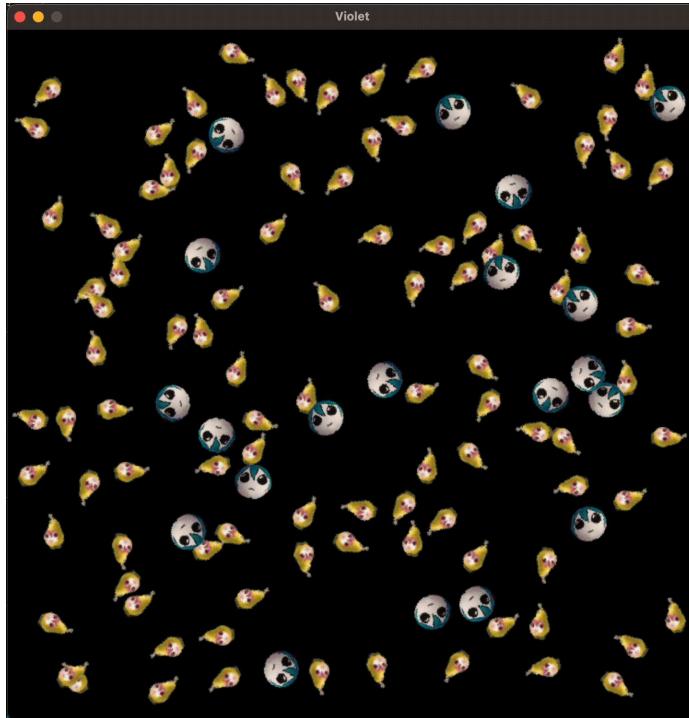
# Introduction

# Introduction - Problem description

- Predator-prey interactions are often modeled using Lotka-Volterra equations.
- We simulate these dynamics using an agent-based model with foxes and rabbits.
- Agents act locally: foxes hunt, rabbits reproduce and avoid predation.
- Our baseline is Lotka-Volterra-inspired, extended with additional mechanisms.
- We introduce features like energy use, aggregation, dynamic traits, and flocking.
- The challenge: How do these behavioral mechanisms affect population dynamics?



# Introduction - Simulation Explanation



Predator: Miku (fox)

Prey: Pearto (rabbit)

Grass: food (later)



Environment: Agents move within a bounded area edges act as solid boundaries (agents bounce off).

Simulation termination conditions:

- All foxes dead
- All rabbits dead
- Maximum of 2000 ticks reached

# Introduction - Purpose of the simulation

## Mechanisms Explored:

- Energy-based survival
- Flocking behavior
- Dynamic traits (e.g. movement speed based on age)
- Aggregation behavior

## Goals:

- Analyze population oscillations under different behavioral mechanisms.
- Investigate how different mechanisms affect extinction time, peak population, and population time series.

# Introduction - Research Questions



- RQ1: How does introducing energy-based survival affect population time series, extinction time, and peak populations in agent-based predator-prey models?
- RQ2: How does flocking behavior influence population time series, extinction time, and peak populations in agent-based predator-prey models?
- RQ3: How do dynamic traits, such as age-dependent speed and detection radius, impact population time series, extinction time, and peak populations in agent-based predator-prey models?
- RQ4: How does aggregation behavior affect population time series, extinction time, and peak populations in agent-based predator-prey models?

# Introduction - Metrics

Metrics (per species):

- Population time series: average population over time
- Extinction time: number of ticks until extinction
- Peak population: highest population reached

For each mechanism, we apply the above 6 metrics to both populations.

One hypothesis pair ( $H_0 / H_1$ ) is formulated per mechanism and metric:

- $H_0$ : The mechanism has no significant effect on the metric.
- $H_1$ : The mechanism has a significant effect on the metric.



# Methodology

# Methodology - Process per metric per research question

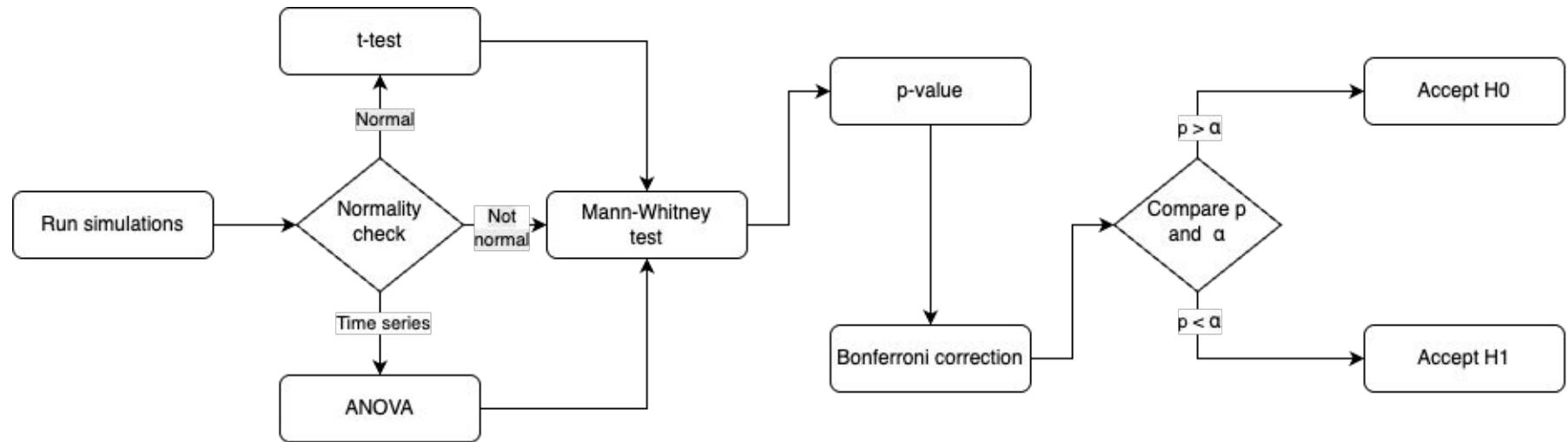
Run simulations:

- $n^3$  times with feature disabled (baseline).
- $n^3$  times with feature enabled (control).
- $n$  is the number of parameters, 3 values per parameter.
- Grid search on parameter values: other parameters held constant.
- Multiple runs per setup, results averaged for visualization.

Statistical Analysis:

1. Normality Check:
  - Per metric, we apply the Shapiro-Wilk test to check if data is normally distributed.
2. Test Selection:
  - If normal, use Welch's independent two-sample t-test.
  - If not normal, use non-parametric Mann-Whitney U test.
  - For population time series, use Repeated-Measures ANOVA test.
  - This ensures valid conclusions based on distribution properties.
3. Multiple Testing Correction:
  - We apply the Bonferroni correction to adjust the significance threshold (alpha value) and avoid false positives.
4. Hypothesis Testing:
  - For each metric, we determine whether the difference between feature-enabled and feature-disabled scenarios is statistically significant by comparing the p and alpha values.

# Methodology - Process flowchart

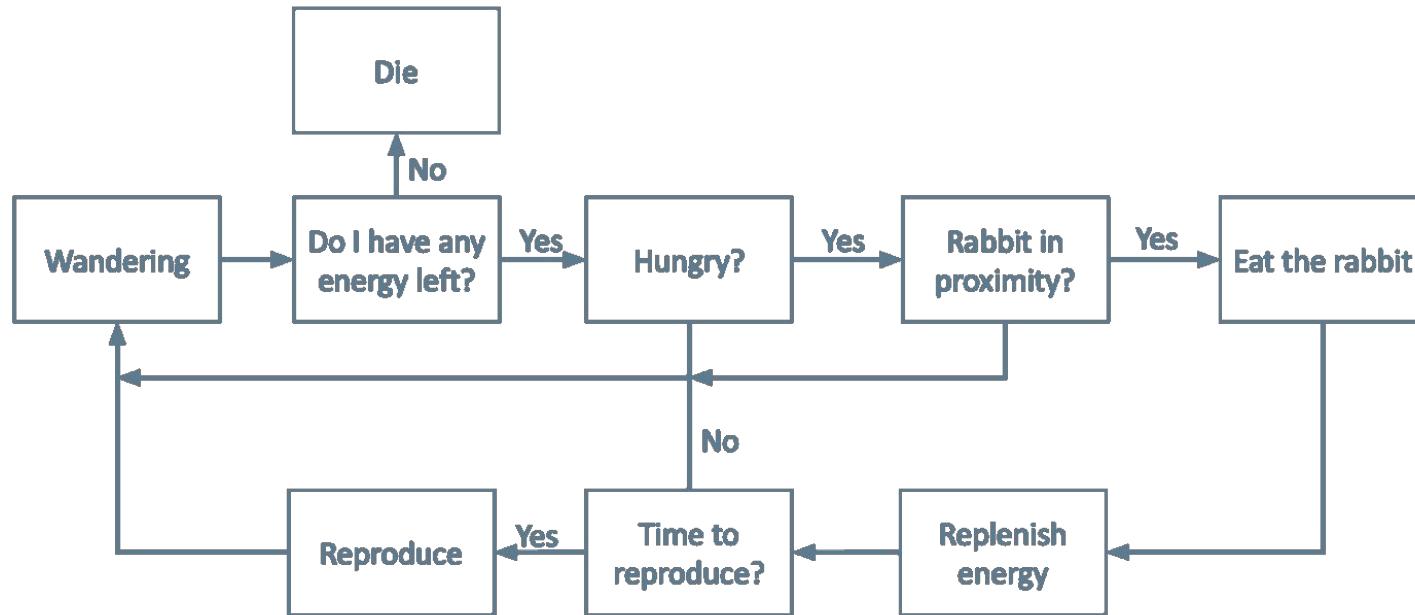




# Energy

## Mechanism

# Flowchart - Energy-based survival mechanism



# In Mathematical Terms - Energy-based survival mechanism

## Fox Energy Dynamics

The energy of a fox, denoted as  $EF$ , changes at each time step  $t$  based on energy decay and consumption of rabbits.

**1. Energy Decay:** At each simulation tick, a fox's energy decreases:  $EF(t+1)=EF(t)-DF$ .

**2. Energy Gain from Rabbit:** If a fox successfully eats a rabbit, its energy increases:  $EF(t+1)=EF(t)+GF,R$ .

**3. Energy Cap:** A fox's energy cannot exceed twice its initial energy:  $EF(t+1)=\min(EF(t+1),2 \cdot EF_{\text{initial}})$ .

**4. Starvation Condition:** A fox dies if its energy falls to or below a critical threshold: If  $EF(t) \leq SF$ , then the Fox dies.

Terms used in the formulas:

- $ER(t)$ : Energy of a Rabbit at time  $t$ .
- $EF(t)$ : Energy of a Fox at time  $t$ .
- $DR$ : Rabbit energy decay rate (energy lost per tick).
- $DF$ : Fox energy decay rate (energy lost per tick).
- $GR,G$ : Energy gained by a Rabbit when eating Grass.
- $GF,R$ : Energy gained by a Fox when eating a Rabbit.
- $SR$ : Rabbit starvation threshold (minimum energy to survive).
- $SF$ : Fox starvation threshold (minimum energy to survive).
- $ER_{\text{initial}}$ : Initial energy of a Rabbit.
- $EF_{\text{initial}}$ : Initial energy of a Fox.
- $t$ : Current simulation time in ticks.

# In Mathematical Terms - Energy-based survival mechanism

## Rabbit Energy Dynamics

The energy of a rabbit, denoted as  $ER$ , changes at each time step  $t$  based on energy decay and consumption of grass.

**1. Energy Decay:** At each simulation tick, a rabbit's energy decreases:  $ER(t+1)=ER(t)-DR$ .

**2. Energy Gain from Grass:** If a rabbit successfully eats a patch of grass, its energy increases:  $ER(t+1)=ER(t)+GR,G$ .

**3. Energy Cap:** A rabbit's energy cannot exceed twice its initial energy:  $ER(t+1)=\min(ER(t+1),2 \cdot ER_{initial})$ .

**4. Starvation Condition:** A rabbit dies if its energy falls to or below a critical threshold: If  $ER(t) \leq SR$ , then the Rabbit dies.

Terms used in the formulas:

- $ER(t)$ : Energy of a Rabbit at time  $t$ .
- $EF(t)$ : Energy of a Fox at time  $t$ .
- $DR$ : Rabbit energy decay rate (energy lost per tick).
- $DF$ : Fox energy decay rate (energy lost per tick).
- $GR,G$ : Energy gained by a Rabbit when eating Grass.
- $GF,R$ : Energy gained by a Fox when eating a Rabbit.
- $SR$ : Rabbit starvation threshold (minimum energy to survive).
- $SF$ : Fox starvation threshold (minimum energy to survive).
- $ER_{initial}$ : Initial energy of a Rabbit.
- $EF_{initial}$ : Initial energy of a Fox.
- $t$ : Current simulation time in ticks.

# Research Question - Energy-based survival



- How does introducing energy-based survival mechanic affect population time series, extinction time, and peak populations in agent-based predator-prey models?

# Parameters - Energy-based survival

## Shared Between Both Scenarios:

- rabbit\_movement\_speed: how fast rabbits move. Values: [1.0, 2.0, 3.0]
- fox\_movement\_speed: how fast foxes move. Values: [2.0, 3.0, 4.0]
- rabbit\_perception\_radius: how far rabbits can detect foxes. Values: [30, 50, 70]
- fox\_perception\_radius: how far foxes can detect rabbits. Values: [50, 70, 90]

## Energy-free Scenario Only:

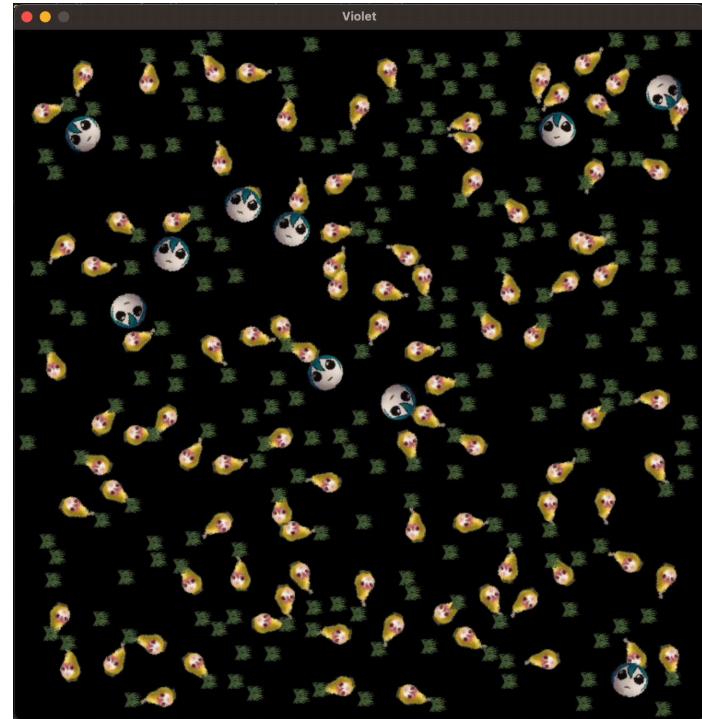
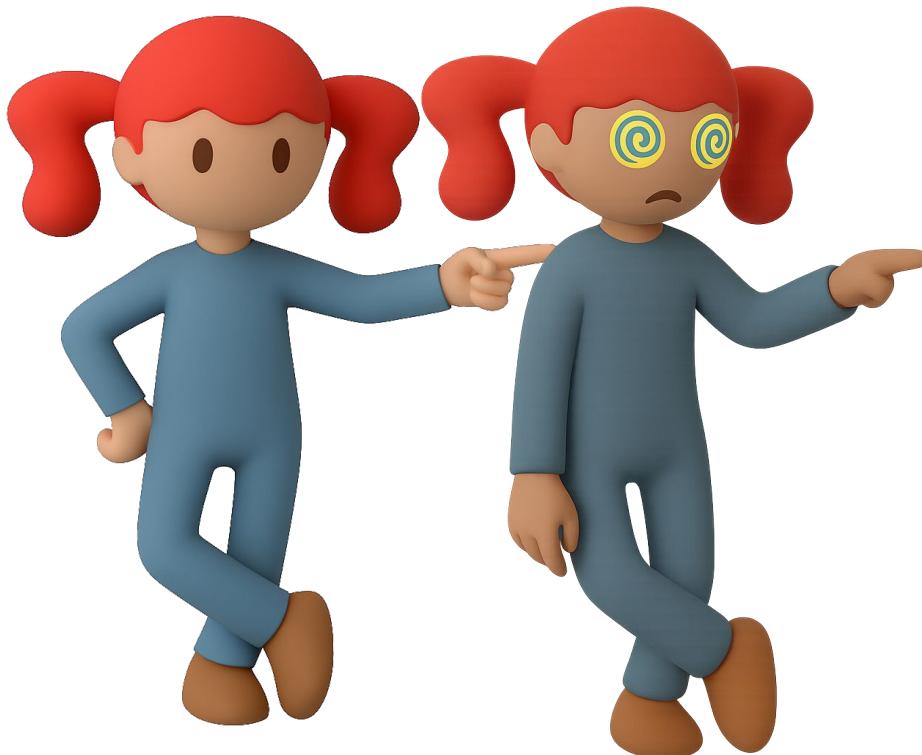
- rabbit\_reproduce\_chance: chance for rabbits to reproduce. Values: [0.003, 0.005, 0.007]
- fox\_spontaneous\_death\_chance: chance of fox dying spontaneously. Values: [0.002, 0.005, 0.008]

## Energy-enabled Scenario Only:

- fox\_initial\_energy: initial energy level of foxes. Values: [80.0, 100.0, 120.0]
- fox\_energy\_decay\_rate: rate at which foxes lose energy over time. Values: [0.3, 0.5, 0.7]
- rabbit\_energy\_gain\_for\_fox: energy gained by foxes after hunting a rabbit. Values: [5.0, 10.0, 15.0]
- fox\_starvation\_threshold: energy level at which foxes die. Values: [0.0, 10.0]
- rabbit\_initial\_energy: initial energy level of rabbits. Values: [30.0, 50.0, 70.0]
- rabbit\_energy\_decay\_rate: rate at which rabbits lose energy over time. Values: [0.1, 0.2, 0.3]
- grass\_energy\_gain\_for\_rabbit: energy rabbits gain from eating grass. Values: [3.0, 5.0, 7.0]
- rabbit\_starvation\_threshold: energy level at which rabbits die. Values: [0.0, 5.0]
- grass\_regrowth\_time: time it takes for grass to regrow. Values: [80, 100, 120]
- grass\_perception\_radius: how far rabbits can detect grass. Values: [20, 30, 40]

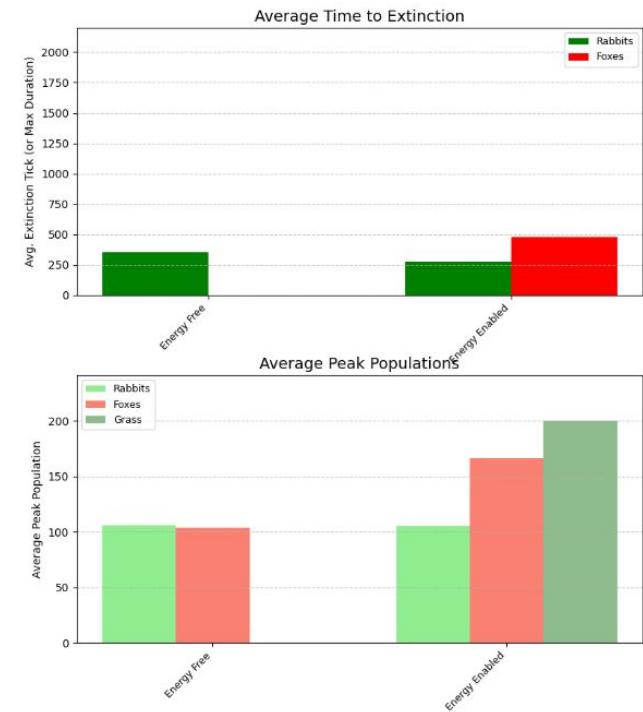
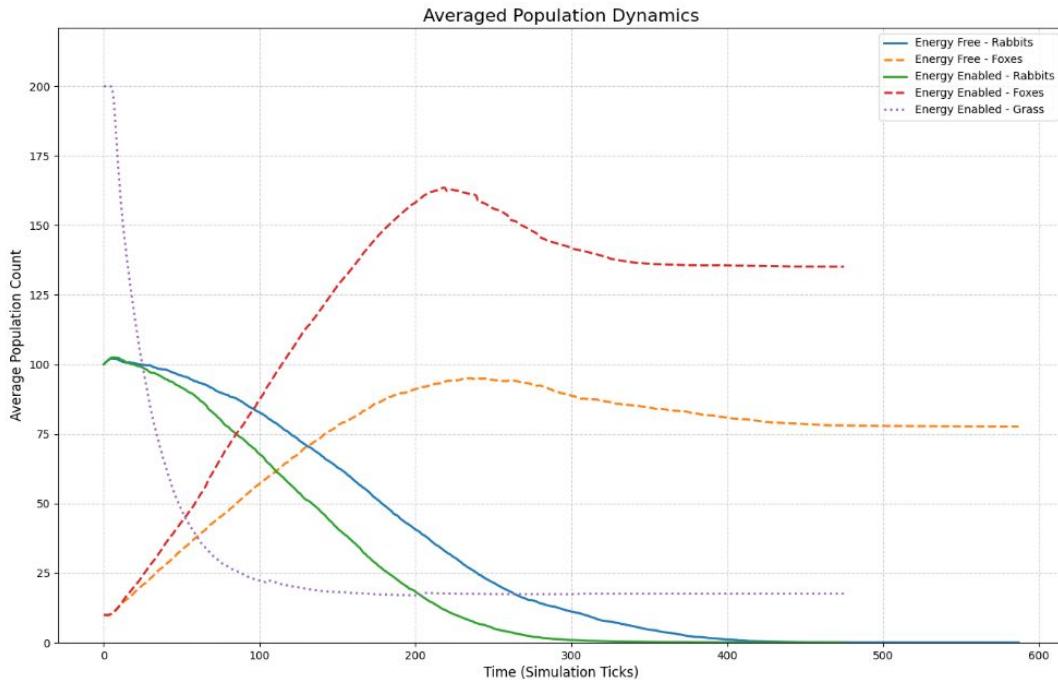


# Simulation - Energy-based survival

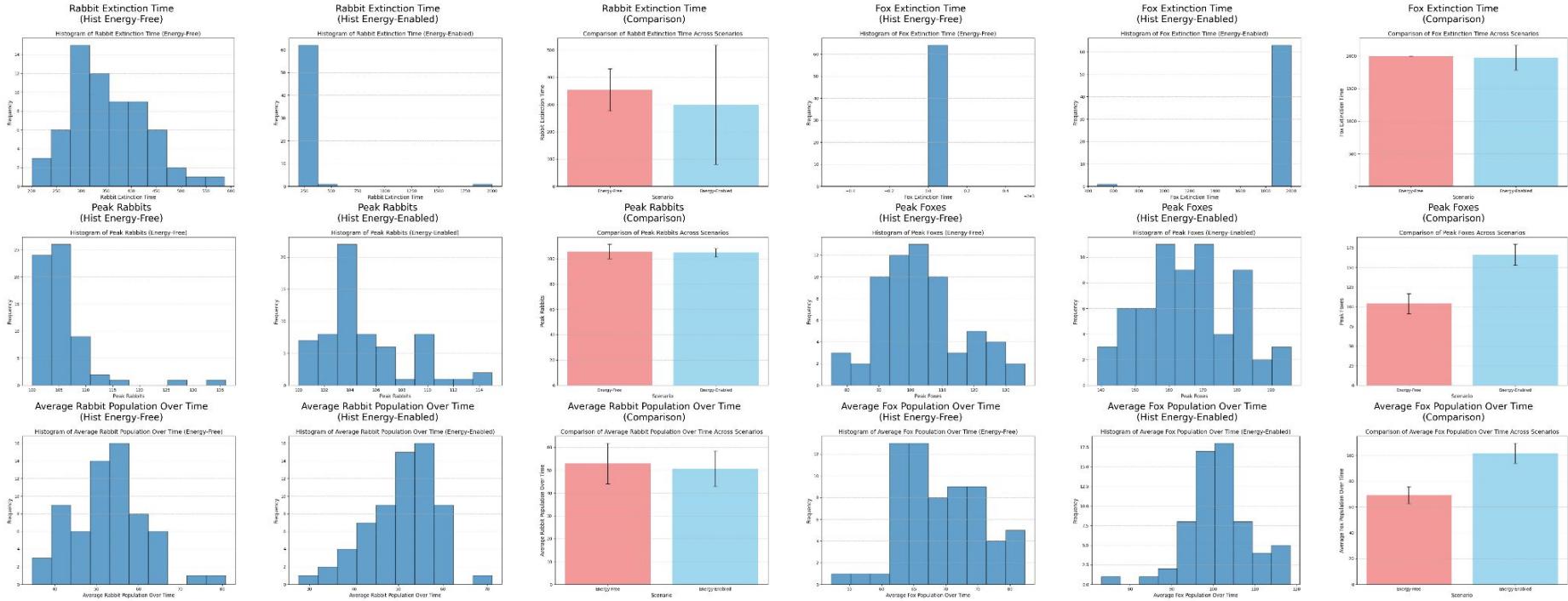


# Results - Energy-based survival

Cross-Scenario Comparison of Predator-Prey Dynamics



# Results - Energy-based survival



# Results - Energy-based survival

📊 Statistical Test Results Summary 📊			
Metric	P-value	Corrected Alpha (Energy-Free vs Energy-Enabled)	Accepted Hypothesis
Rabbit Extinction Time	0.0000	0.0083	H1 Accepted ✓
Fox Extinction Time	0.3249	0.0083	H0 Accepted ✗
Peak Rabbits	0.6031	0.0083	H0 Accepted ✗
Peak Foxes	0.0000	0.0083	H1 Accepted ✓
Average Rabbit Population Over Time	0.1271	0.0083	H0 Accepted ✗
Average Fox Population Over Time	0.0000	0.0083	H1 Accepted ✓



# Flocking

## Mechanism

# Research Question - Flocking



- How does flocking behavior influence population time series, extinction time, and peak populations in agent-based predator-prey models?

# Parameters - Flocking

## No Flocking Scenario:

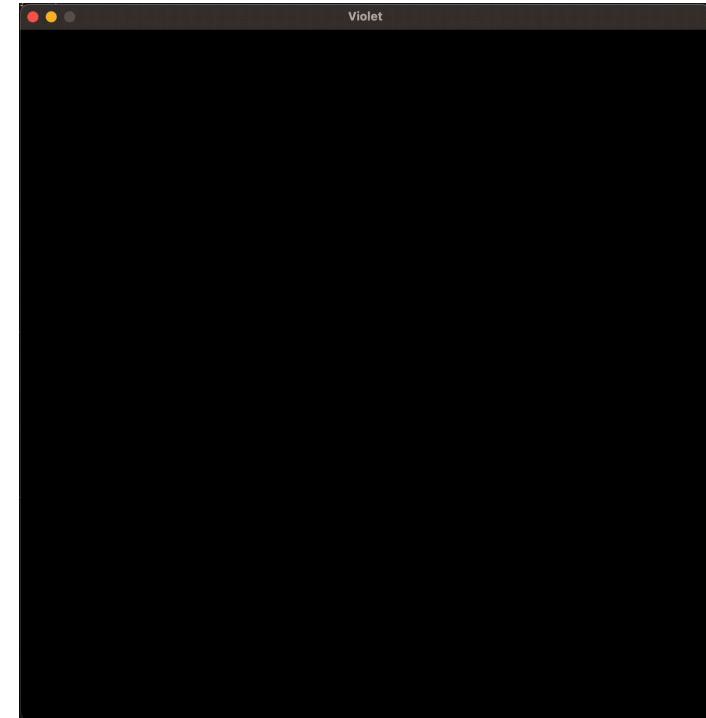
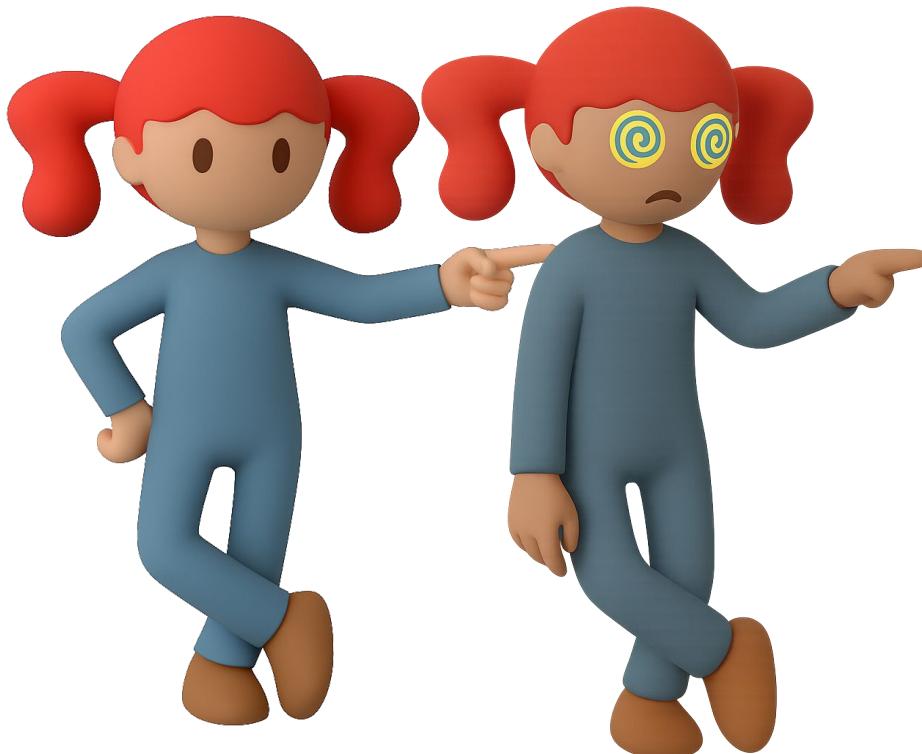
- rabbit\_movement\_speed: how fast rabbits move. Values: [1.0, 2.0, 3.0]
- fox\_movement\_speed: how fast foxes move. Values: [2.0, 3.0, 4.0]
- rabbit\_perception\_radius: how far rabbits can detect foxes. Values: [40, 50, 60]
- fox\_perception\_radius: how far foxes can detect rabbits. Values: [60, 70, 80]
- rabbit\_reproduce\_chance: chance for rabbits to reproduce. Values: [0.004, 0.005, 0.006]
- fox\_spontaneous\_death\_chance: chance of fox dying spontaneously. Values: [0.004, 0.005, 0.006]

## Flocking Scenario:

- alignment\_weight: influence of neighbors' direction. Values: [0.5, 1.0, 1.5]
- cohesion\_weight: influence of group centering. Values: [0.5, 1.0, 1.5]
- separation\_weight: influence of avoiding crowding. Values: [0.5, 1.0, 1.5]

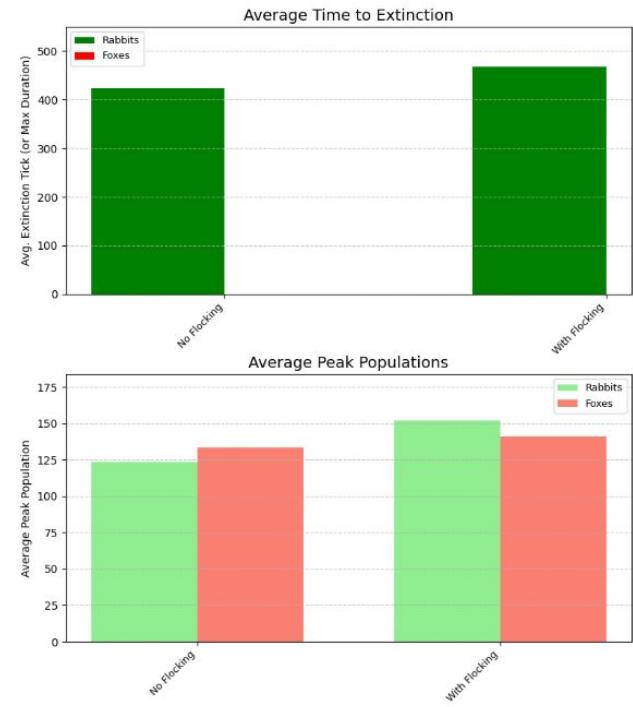
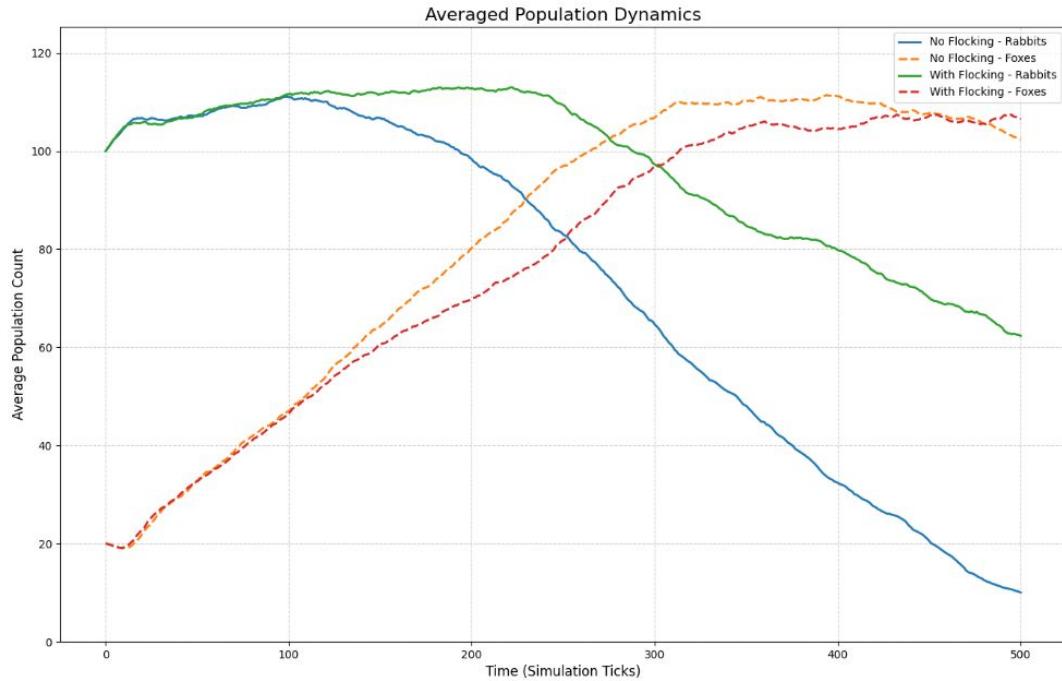


# Simulation - Flocking

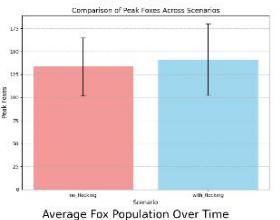
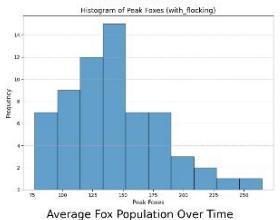
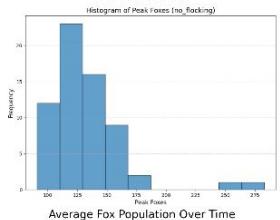
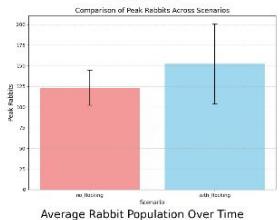
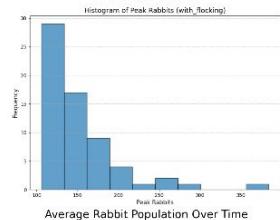
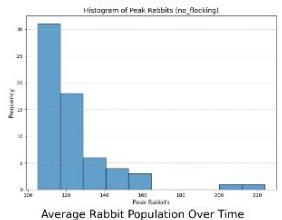
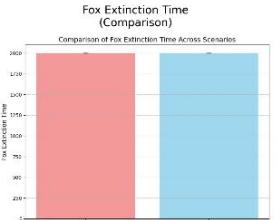
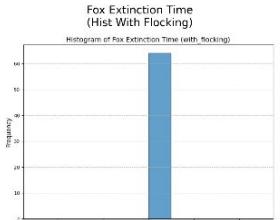
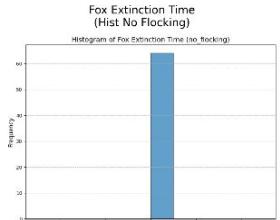
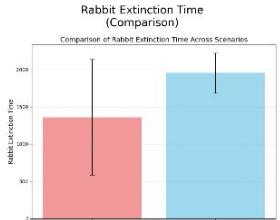
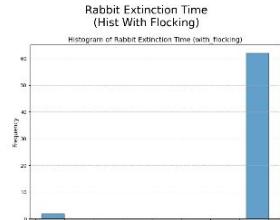
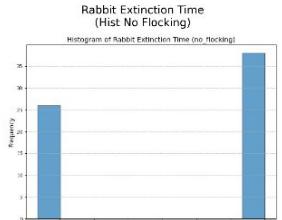


# Results - Flocking

Cross-Scenario Comparison of Predator-Prey Dynamics



# Results - Flocking



# Results - Flocking

📊 Statistical Test Results Summary 📊			
Metric	P-value	Corrected Alpha (no_flocking vs with_flocking)	Accepted Hypothesis
Rabbit Extinction Time	0.0000	0.0083	H1 Accepted ✓
Fox Extinction Time	nan	0.0083	H0 Accepted ✗
Peak Rabbits	0.0000	0.0083	H1 Accepted ✓
Peak Foxes	0.1555	0.0083	H0 Accepted ✗
Average Rabbit Population Over Time	0.0000	0.0083	H1 Accepted ✓
Average Fox Population Over Time	0.0256	0.0083	H0 Accepted ✗



# Dynamic traits

## Mechanism

# Research Question - Dynamic traits



- How do dynamic traits, such as age-dependent speed and detection radius, impact population time series, extinction time, and peak populations in agent-based predator-prey models?

# Parameters - Dynamic traits

## No Dynamic Traits Scenario:

- rabbit\_movement\_speed: how fast rabbits move. Values: [2.0, 3.0, 4.0]
- fox\_movement\_speed: how fast foxes move. Values: [3.0, 4.0, 5.0]
- rabbit\_perception\_radius: how far rabbits can detect foxes. Values: [40, 50, 60]
- fox\_perception\_radius: how far foxes can detect rabbits. Values: [60, 70, 80]
- rabbit\_reproduce\_chance: chance for rabbits to reproduce. Values: [0.004, 0.005, 0.006]
- fox\_spontaneous\_death\_chance: chance of fox dying spontaneously. Values: [0.004, 0.005, 0.006]

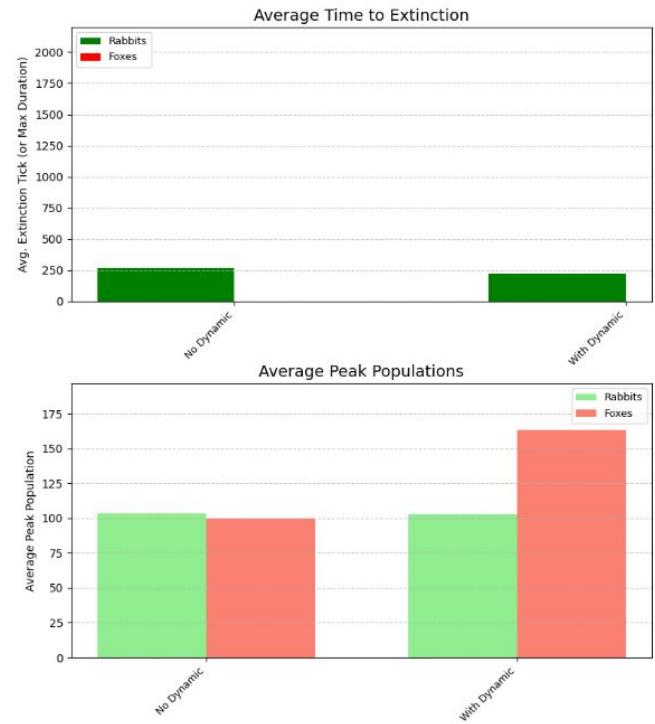
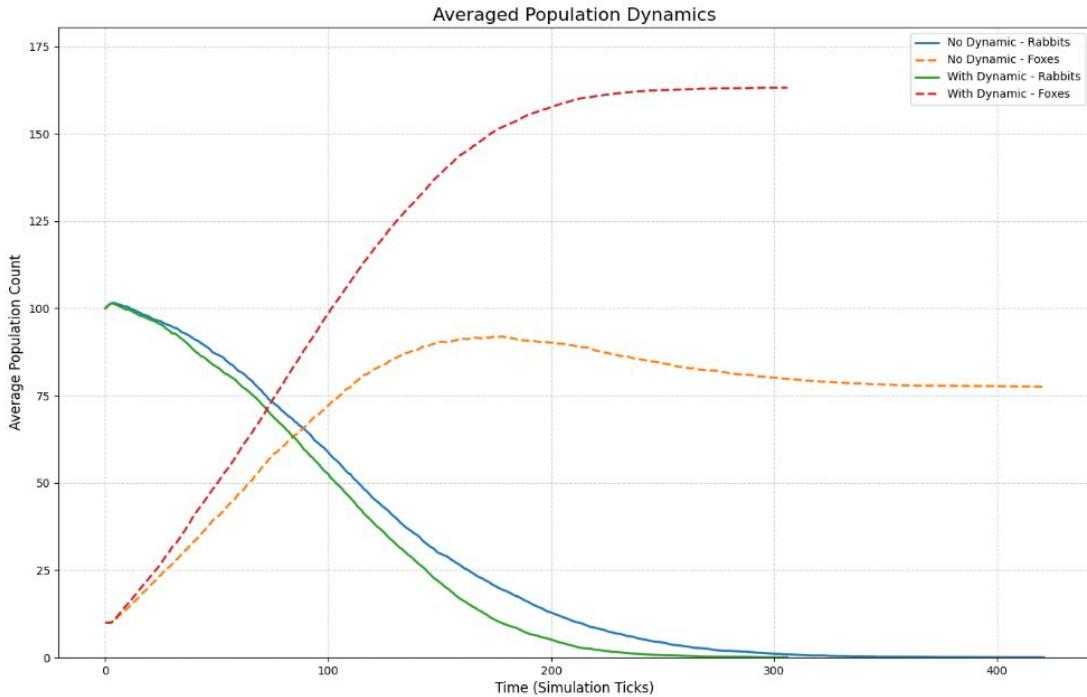
## Dynamic Traits Scenario:

- rabbit\_aging\_rate\_speed: how quickly rabbit speed declines with age. Values: [0.0005, 0.001, 0.0015]
- rabbit\_aging\_rate\_perception: how quickly rabbit vision declines with age. Values: [0.03, 0.05, 0.07]
- fox\_aging\_rate\_speed: how quickly fox speed declines with age. Values: [0.001, 0.002, 0.003]
- fox\_aging\_rate\_perception: how quickly fox vision declines with age. Values: [0.08, 0.1, 0.12]

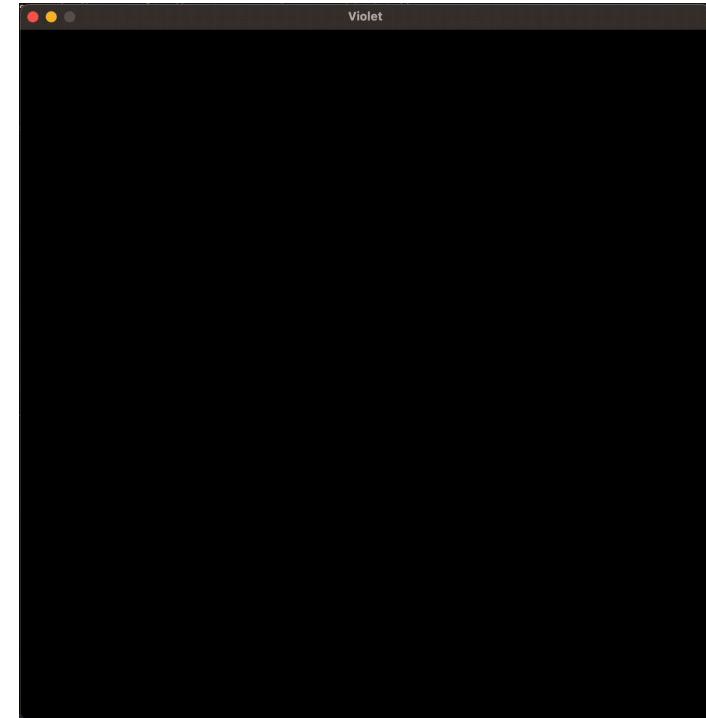
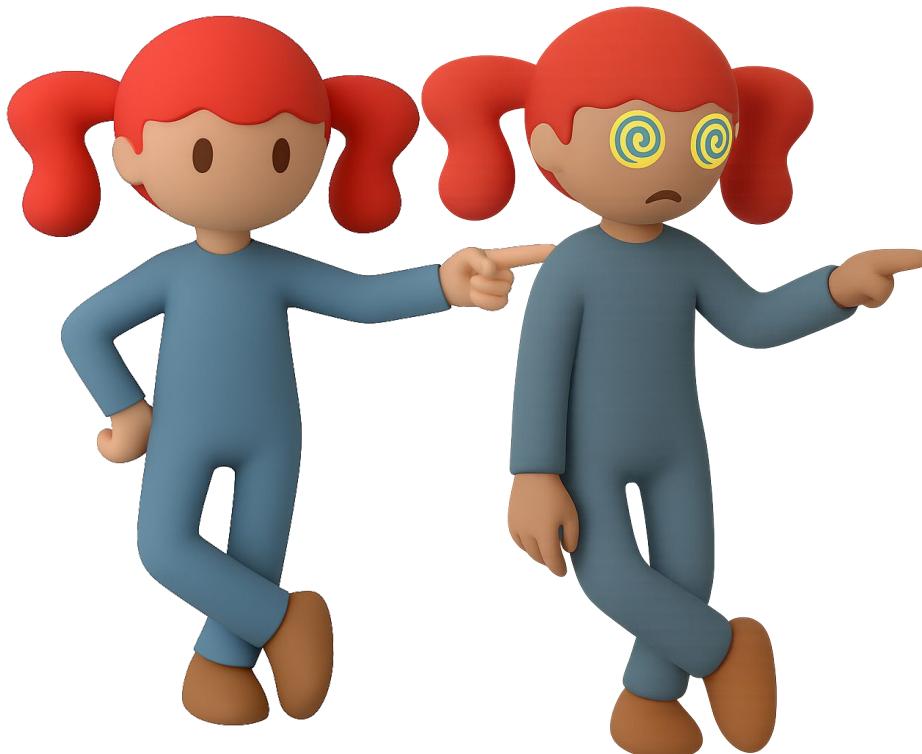


# Results - Dynamic traits

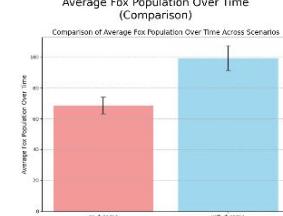
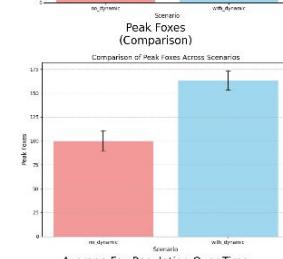
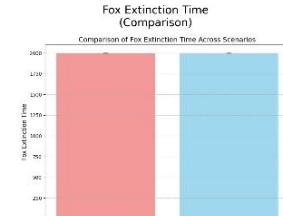
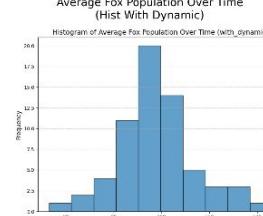
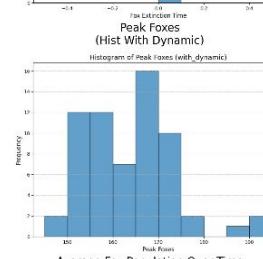
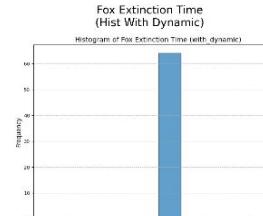
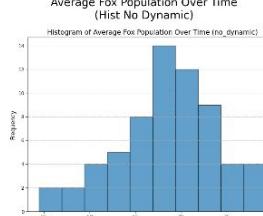
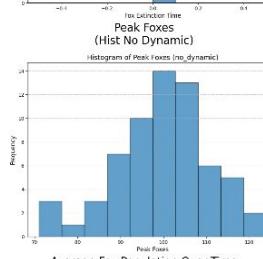
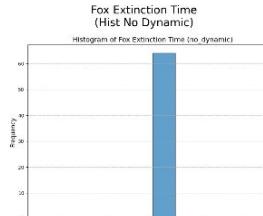
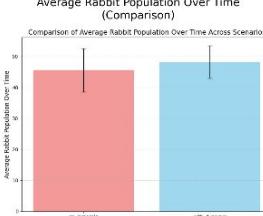
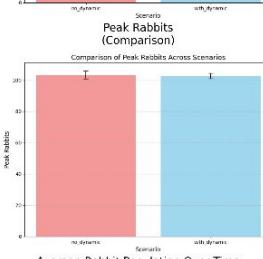
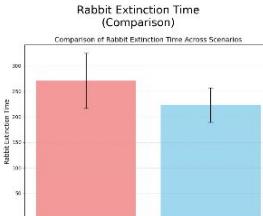
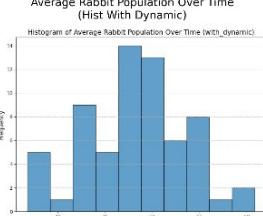
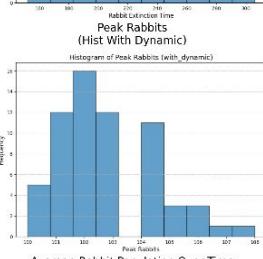
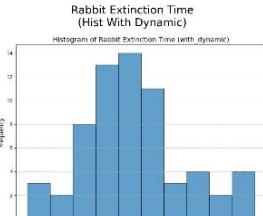
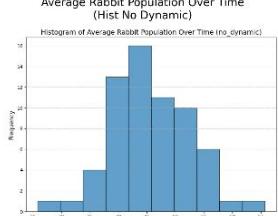
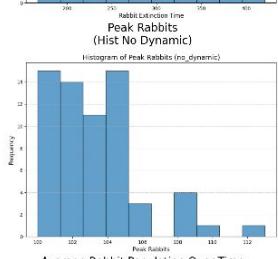
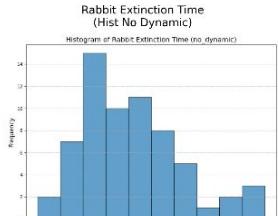
Cross-Scenario Comparison of Predator-Prey Dynamics



# Simulation - Dynamic traits



# Results - Dynamic traits



# Results - Dynamic traits

📊 Statistical Test Results Summary 📊			
Metric	P-value	Corrected Alpha (no_dynamic vs with_dynamic)	Accepted Hypothesis
Rabbit Extinction Time	0.0000	0.0083	H1 Accepted <span style="color: green;">✓</span>
Fox Extinction Time	nan	0.0083	H0 Accepted <span style="color: red;">✗</span>
Peak Rabbits	0.2789	0.0083	H0 Accepted <span style="color: red;">✗</span>
Peak Foxes	0.0000	0.0083	H1 Accepted <span style="color: green;">✓</span>
Average Rabbit Population Over Time	0.0199	0.0083	H0 Accepted <span style="color: red;">✗</span>
Average Fox Population Over Time	0.0000	0.0083	H1 Accepted <span style="color: green;">✓</span>



# Aggregation

## Mechanism

# Research Question - Aggregation



- How do dynamic traits, such as age-dependent speed, impact population time series, extinction time, and peak populations in agent-based predator-prey models?

# Parameters - Aggregation

## No Aggregation Scenario:

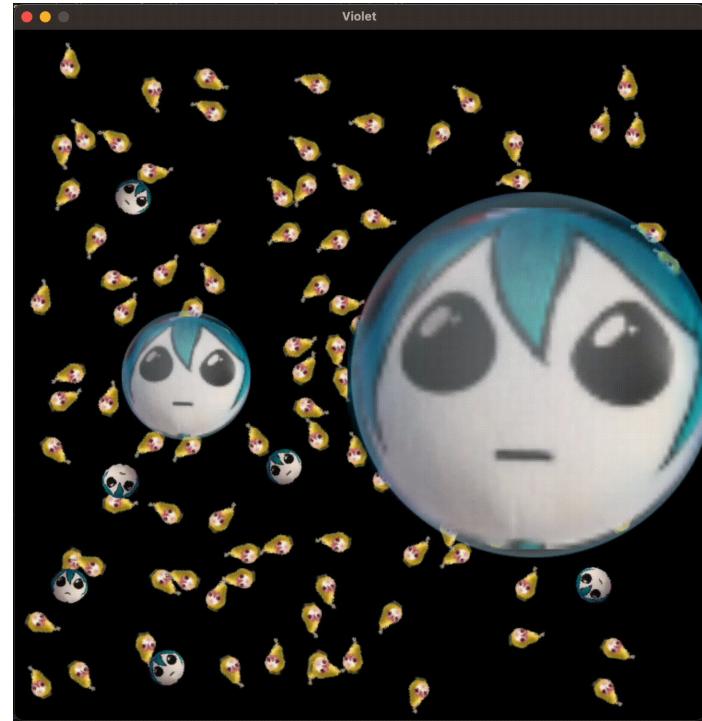
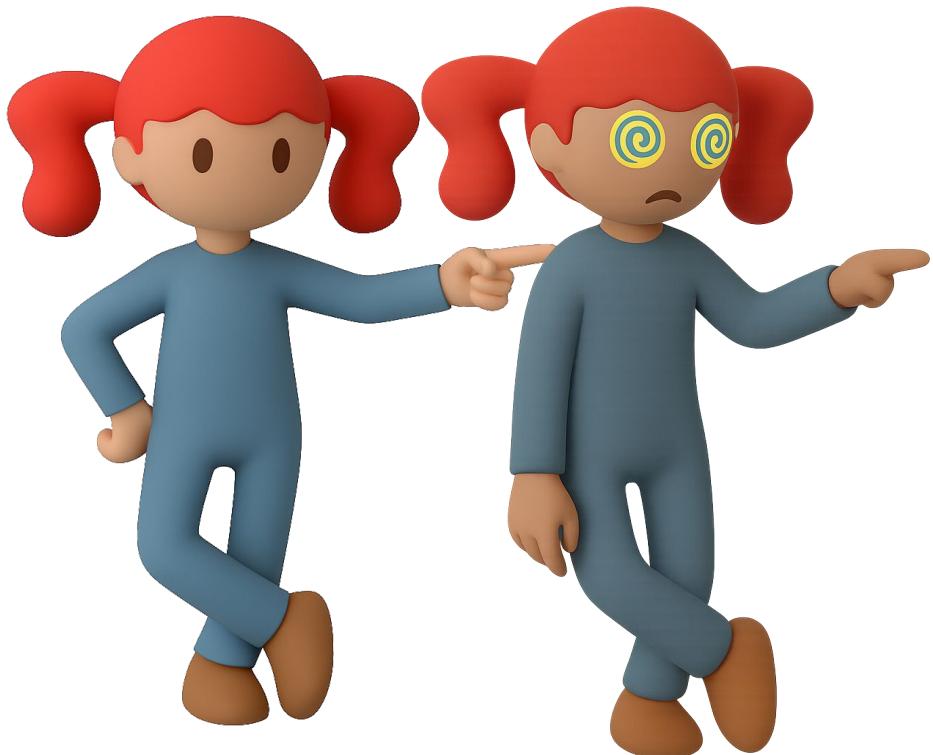
- rabbit\_movement\_speed: how fast rabbits move. Values: [1.5, 2.0, 2.5]
- fox\_movement\_speed: how fast foxes move. Values: [2.5, 3.0, 3.5]
- rabbit\_perception\_radius: how far rabbits can detect foxes. Values: [40, 50, 60]
- fox\_perception\_radius: how far foxes can detect rabbits. Values: [60, 70, 80]
- rabbit\_reproduce\_chance: chance for rabbits to reproduce. Values: [0.004, 0.005, 0.006]
- fox\_spontaneous\_death\_chance: chance of fox dying spontaneously. Values: [0.004, 0.005, 0.006]

## Aggregation Scenario:

- p\_join\_factor: likelihood of rabbits joining an aggregation site. Values: [5.0, 10.0, 15.0]
- p\_leave\_factor: likelihood of rabbits leaving an aggregation site. Values: [40.0, 50.0, 60.0]
- t\_join\_min: minimum ticks before joining a site. Values: [5, 10, 15]
- t\_join\_max: maximum ticks before joining a site. Values: [15, 20, 25]
- t\_leave\_min: minimum ticks before leaving a site. Values: [160, 180, 200]
- t\_leave\_max: maximum ticks before leaving a site. Values: [340, 360, 380]
- d\_check\_frequency: how often aggregation decisions are evaluated. Values: [20, 30, 40]
- num\_aggregation\_sites: number of available aggregation sites. Values: [1, 2, 3]

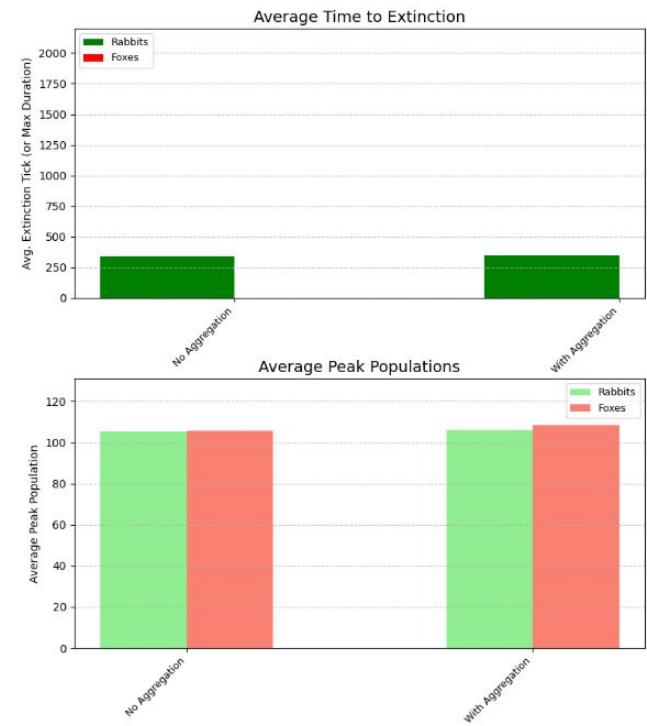
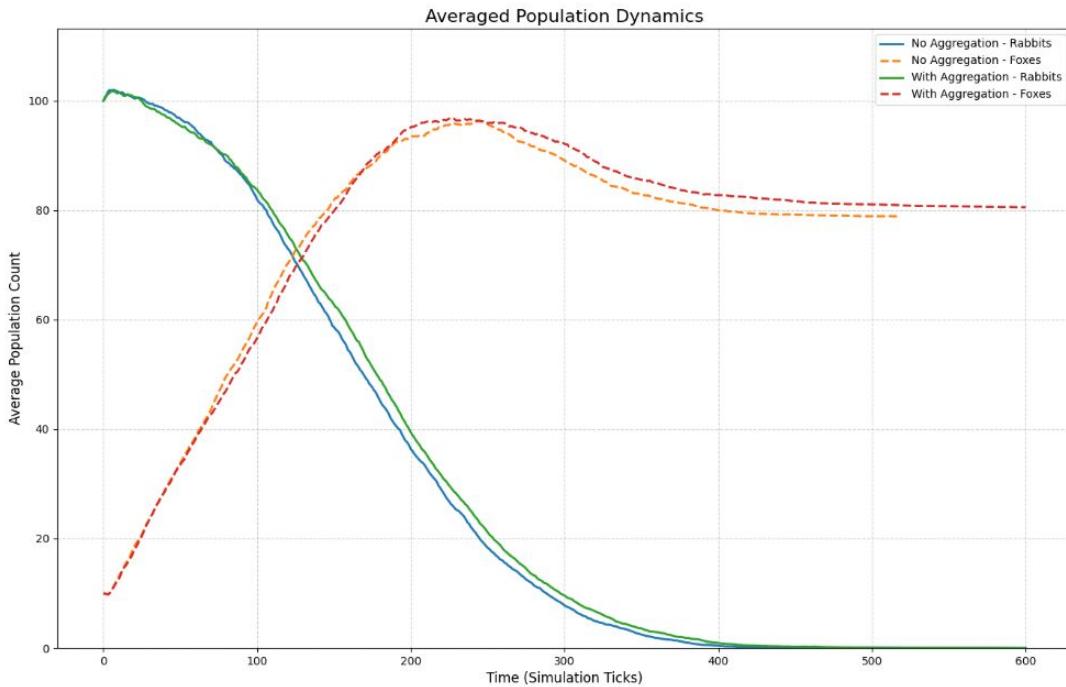


# Simulation - Aggregation

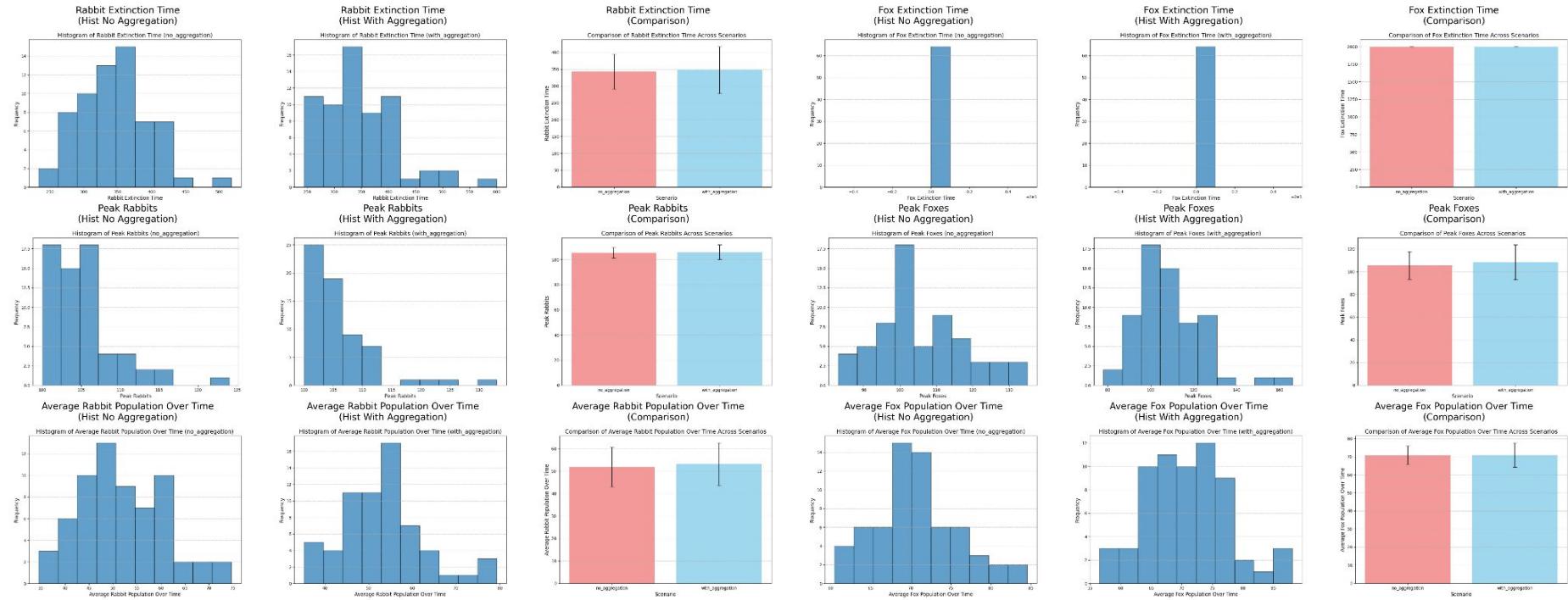


# Results - Aggregation

Cross-Scenario Comparison of Predator-Prey Dynamics



# Results - Aggregation



# Results - Aggregation

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📊 Statistical Test Results Summary 📊

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Metric	P-value	Corrected Alpha (no_aggregation vs with_aggregation)	Accepted Hypothesis
Rabbit Extinction Time	0.9487	0.0083	H <sub>0</sub> Accepted ✘
Fox Extinction Time	nan	0.0083	H <sub>0</sub> Accepted ✘
Peak Rabbits	0.9828	0.0083	H <sub>0</sub> Accepted ✘
Peak Foxes	0.3260	0.0083	H <sub>0</sub> Accepted ✘
Average Rabbit Population Over Time	0.5466	0.0083	H <sub>0</sub> Accepted ✘
Average Fox Population Over Time	0.9325	0.0083	H <sub>0</sub> Accepted ✘

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# Conclusions

# Conclusions



Statistical tests revealed the following effects of each mechanism:

Energy mechanism:

- Rabbit extinction time: significantly reduced.
- Fox peak population: significantly increased.
- Average fox population over time: significantly increased.

Flocking behavior:

- Rabbit extinction time: significantly increased.
- Rabbit peak population: significantly increased.
- Average rabbit population over time: significantly increased.

Dynamic traits:

- Rabbit extinction time: significantly reduced.
- Fox peak population: significantly increased.
- Average fox population over time: significantly increased.

Aggregation behavior:

- No significant effects observed.

# Future work



Extra features that can be added in future:

- Different FOVs for predators and prey.
- Two agent reproduction.
- Different space zones, such as grass fields.
- Additional experiments with aggregation mechanic.



Thank you  
For paying attention

