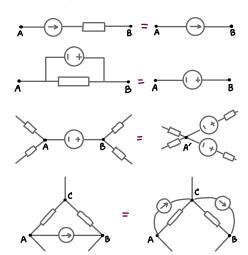
サーキット・ソーリーII CIRCUIT THEORY II

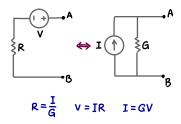
Midterm: Cheat sheet

1) Source transformation

▶ Source relocation

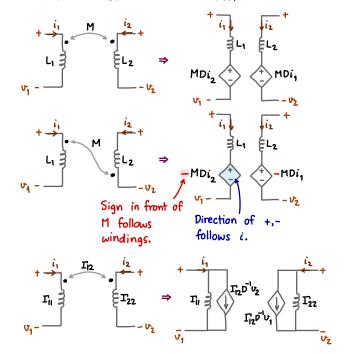


▶ Thévenin-Norton transformation

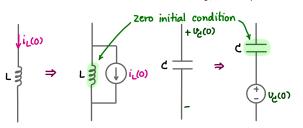


(Also works for dependent sources)

▶ Mutual inductance transformation

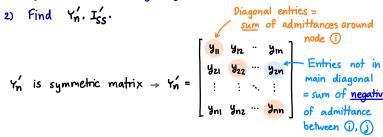


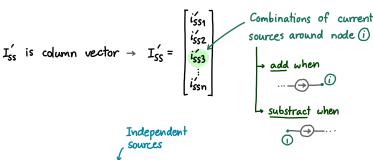
▶ Initial condition to source transformation



- 2 Nodal analysis
- · Systematic method
- 1) Perform source transformation.
- 2) Draw digraph, choose one reference node and write down reduced incidence matrix A.
- 3) Find branch equations, then write them in a matrix form.

- 4) Find $Y_n \triangleq AY_bA^T$ and $I_{SS} \triangleq AY_bv_S Ai_S$, the node equations are $Y_ne = I_{SS}$.
- 5) Find the initial condition of e e(0).
- · Inspection method
- 1) Try to transform everything to current sources.





3) Express $I'_{SS} = I'_{SS} + Y_C e$

Admittance matrix from current sources.

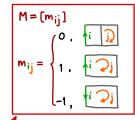
- 4) Let $Y_n = Y_n' Y_c$. the node equations are $Y_n e = I_{ss}$.
- 5) Find the initial condition of e e(0).

Note: Initial conditions of e are only dependent to $R, L, C, v_S, i_S, i_L(0)$ and $v_C(0)$.

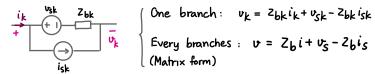
(3) Mesh analysis

· Systematic method

- 1) Perform source transformation.
- 2) Draw digraph, draw mesh currents and write down mesh matrix M.



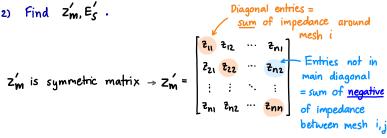
3) Find branch equations, then write them in a matrix form.

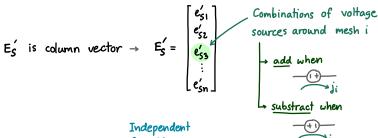


- 4) Find Zm = MZbMT and Es = MZbis MUs, the mesh equations are $Z_{mj} = E_{S}$.
- 5) Find the initial condition of j: j(0)

Inspection method

1) Try to transform everything to voltage sources.





~ Impedance matrix from voltage sources.

- Let $Z_m = Z'_m Z_v$. the node equations are $Z_m j = E_S$.
- 5) Find the initial condition of j: j(0).

Node/Mesh Response

Node Equation initial $Y_n(D)e(t) = I_{ss}(t)$ $Z_m(D) \dot{\mathbf{j}}(t) = E_{ss}(t)$ $Z_{\mathbf{m}}(s)\mathbf{J}(s) = \mathbf{E}_{ss}(s) + \mathbf{E}_{i}$ $Y_n(s)E(s) = I_{ss}(s) + I_i$ Complete Response : $E(s) = Y_n(s)^{-1}I_{ss}(s) + Y_n(s)^{-1}I_i$ $J(s) = Z_{m}(s)^{-1}E_{ss}(s) + Z_{m}(s)^{-1}E_{i}$ State Response = 0 (sources) State Equation $\dot{x} = Ax + Bu$,เรียก Resolvent Matrix \mathcal{L} ; SX(s) - x(o) = AX(s) + BU(s) $X(s) = (sI-A)^{-1}x(o) + (sI-A)^{-1}BU(s)$

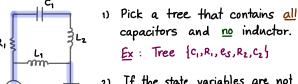
(4) State equations

$$x = \text{state vector}$$

 $u = \text{input vector}$
 $y = \text{output vector}$
State equations:
 $\dot{x} = Ax + Bu$
Output equations:
 $y = Cx + Du$

In LTI circuit, state variables often be the inductor currents and capacitor voltages.

How to: write state, output equations.



2) If the state variables are not given, use capacitor voltages and inductor currents as the state variables.

These equations must be expressed in terms of chasen variables in Step (2) and input variables.

- 3) Write a cut-set equation or KCL for each capacitor.
- 4) Write a loop equation or KVL for each inductor.
- 5) Rearrange the equations in step (3),(4) to obtain state equations $\dot{x} = Ax + Bu$.
- 6) Write down the outputs in terms of state variables and inputs and obtain output equations y = Cx + Du

ตารางผลเ

การแปลงลาปลาซ	
f(t)	F(s)
$\delta(t)$	1
1	$\frac{1}{s}$
t	$\frac{\frac{1}{s^2}}{\frac{2}{s^3}}$
t^2	$\frac{2}{s^3}$
t^n	$\frac{n!}{s^{n+1}}$
e^{-at}	$\frac{1}{s+a}$
$\sin \omega t$	$\frac{\omega}{s^2 + \omega^2}$
$\cos \omega t$	$\frac{s}{s^2 + \omega^2}$
$e^{-at}\sin\omega t$	$\frac{\omega}{(s+a)^2 + \omega^2}$
$e^{-at}\cos\omega t$	$\frac{s+a}{(s+a)^2+\omega^2}$
e-at cosh(wt)	$\frac{s+a}{(s+a)^2-\omega^2}$
e ^{at} sinh (wt)	(5-49)2 - W2