

Questions from yesterday:

- Discussions around value judgement and dynamics

→ this is indeed making our language lazy, which we will explore further in Week 7

- why rules have one conclusion

→ standard

→ 2 conclusions is valid, but can lead to messy proofs so the standard is 1 conclusion

→ speak to Tom if you are interested

(found no examples of 2 conclusions in the literature, probs cos non-standard / not my speciality)

~min sheet~

Sums

types $T ::= \dots$
 $T_1 + T_2$
 \bigcirc

pre-terms $e ::=$
 $\text{abort}(e)$
 $\text{inl}(e)$
 $\text{inr}(e)$
 $\text{case}(e; \underline{x}.e_1; \underline{y}.e_2)$

Statics:

ABORT $\frac{\Gamma \vdash e : \bigcirc}{\Gamma \vdash \text{abort}(e) : \tau}$

INL $\frac{\Gamma \vdash e : T_1}{\Gamma \vdash \text{inl}(e) : T_1 + T_2}$

INR $\frac{\Gamma \vdash e : T_2}{\Gamma \vdash \text{inr}(e) : T_1 + T_2}$

CASE $\frac{\Gamma \vdash e : T_1 + T_2 \quad \Gamma, x : T_1 \vdash e_1 : \sigma \quad \Gamma, y : T_2 \vdash e_2 : \sigma}{\Gamma \vdash \text{case}(e; x.e_1; y.e_2) : \sigma}$

Dynamics:

VAL-INL $\frac{}{\text{inl}(e) \text{ val}}$

VAL-INR $\frac{}{\text{inr}(e) \text{ val}}$

D-ABORT-1 $\frac{e \mapsto e'}{\text{abort}(e) \mapsto \text{abort}(e')}$

D-CASE-INL $\frac{}{\text{case}(\text{inl}(e); x.e_1; y.e_2) \mapsto e_1[e/x]}$

D-CASE-INR $\frac{}{\text{case}(\text{inr}(e); x.e_1; y.e_2) \mapsto e_2[e/y]}$

D-CASE-1 $\frac{e \mapsto e'}{\text{case}(e; x.e_1; y.e_2) \mapsto \text{case}(e'; x.e_1; y.e_2)}$

Substitution

$$\langle e_1, e_2 \rangle [e/x] \stackrel{\text{def}}{=} \langle e_1 [e/x], e_2 [e/x] \rangle$$

$$\pi_i(u) [e/x] \stackrel{\text{def}}{=} \pi_i(u [e/x]) \quad i \in [1, 2]$$

$$\text{inl}(u) [e/x] \stackrel{\text{def}}{=} \text{inl}(u [e/x])$$

$$\text{inr}(u) [e/x] \stackrel{\text{def}}{=} \text{inr}(u [e/x])$$

$$\text{case}(u; z. e_1; y. e_2) [e/x]$$

$$\stackrel{\text{def}}{=} \text{case}(u [e/x]; \text{z}. e_1 [e/x]; y. e_2 [e/x])$$

Functions

$$(\lambda x. x) : a \rightarrow a$$

Syntax:

$$\text{types } \tau ::= \dots \tau_1 \rightarrow \tau_2$$

preterms

$$e ::= \dots \lambda x:\tau. e \quad e_1(e_2)$$

Statics:

$$\text{LAM} \quad \frac{\Gamma, x:\sigma \vdash e : \tau}{\Gamma \vdash \lambda x:\sigma. e : \sigma \rightarrow \tau}$$

$$\text{APP} \quad \frac{\Gamma \vdash e_1 : \sigma \rightarrow \tau \quad \Gamma \vdash e_2 : \sigma}{\Gamma \vdash e_1(e_2) : \tau}$$

Example:

$$\lambda x:\text{Num}. \text{succ } x \quad \text{plus}(x, x)$$

Dynamics:

$$\text{VAL-LAM} \quad \frac{}{\lambda x:\tau. e \text{ val}}$$

$$\text{D-APP-1} \quad \frac{e_1 \mapsto e_1'}{e_1(e_2) \mapsto e_1'(e_2)}$$

$$\text{D-BETA} \quad \frac{}{\rightarrow_{\beta} \quad (\lambda x:\tau. e)(e_2) \mapsto e[e_2/x]}$$

Subst:

$$(e_1(e_2))[e/x] \stackrel{\text{def}}{=} (e_1[e/x](e_2[e/x]))$$

$$(\lambda y:\tau. u)[e/x] \stackrel{\text{def}}{=} (\lambda y:\tau. u[e/x])$$

$$\text{add} : \text{Num} \rightarrow \text{Num} \rightarrow \text{Num}$$

$$\lambda x:\text{Num}. \lambda y:\text{Num}. \text{succ } y$$

$$\tau = \text{Num} \rightarrow \text{Num} \quad \rho = \emptyset$$

$$\sigma = \text{Num} \quad \sigma' = \text{Num}$$

$$\begin{array}{c} \text{VAR} \quad \frac{}{\Gamma, x:\sigma, y:\sigma' \vdash x:\text{Num}} \quad \text{VAR} \quad \frac{}{\Gamma, x:\sigma, y:\sigma' \vdash y:\text{Num}} \\ \text{PLUS} \quad \frac{}{\Gamma, x:\sigma, y:\sigma' \vdash \text{plus}(x, y) : \text{Num}} \\ \text{LAM} \quad \frac{}{\Gamma, x:\sigma \vdash \lambda y:\text{Num}. \text{plus}(x, y) : \tau} \\ \text{LAM} \quad \frac{}{\Gamma \vdash \lambda x:\text{Num}. \lambda y:\text{Num}. \text{plus}(x, y) : \sigma \rightarrow \tau} \end{array}$$

This specification of functions supports higher-order (HO) functions

HO functions = function that take other functions as arguments

e.g.

$$\text{twice} :: (a \rightarrow a) \rightarrow a \rightarrow a$$

$$\text{twice } f \ x = f(f \ x)$$

$$\text{twice}_a := \lambda f : a \rightarrow a. \lambda x : a. f(f \ x)$$

not simply-typed

Benus - Inhabitants + Cat Theory

Inhabitants of a type

= the set of values that have that type

> data Unit = Unit

> data Bool = True | False

> data Tri = One | Two | Three

> data Var1

¹Unit + ²Bool = 3

In1 ()

Inr True

Inr False

(¹Unit, ²Bool) 2

(1, False)

(1, True)