

Dynamic Binary Firmware Analysis With Avatar²

THCon 2023

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> whoami

Paul OLIVIER

- Recent Ph.D. graduate (EURECOM)
- Just joined as postdoc @ LAAS-CNRS
- Dynamic analysis for embedded system security
- Part of the maintainer team of avatar²



> Content

- Motivation
- Rehosting Firmware
- Avatar²: A Multi-Target Orchestration Platform
- Framework Overview
- Conclusion

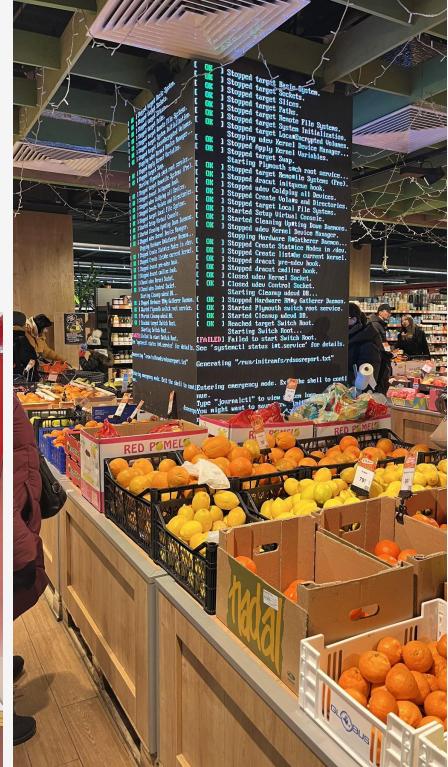
> Introduction

Prevalence of bugs in the Wild



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- **Severity and impact** of software bugs
 - Vulnerabilities: *unauthorized access, information leak, denial of service, ransomware*
 - Cost: *finding & fixing, system downtime*
 - Human life: *car driving assistance, Boeing 737 MAX, radiology, etc.*

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- Thorough **testing** of firmware is crucial to guarantee its safety and **security**
- **Static and dynamic** analysis are two main approaches.

> Motivation: Firmware Analysis

Static analysis

- Examine without executing code

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Static analysis

- Examine without executing code
- Limitations
 - Achieve **larger coverage**... but **less precise** (no execution context)
 - No need to run code... but does not require external systems

> Motivation: Firmware Analysis

- **Dynamic** analysis techniques are plenty & powerful
 - more precise... but smaller coverage
 - *tracing, profiling, fuzzing, concolic execution, sanitizers, data taint tracking, record-replay, interactive debugging, etc.*



PANDA



LTTng



angr



AFL++



Manticore



systemtap



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 - **Constrained** environment (*computing power, memory size, network bandwidth*)

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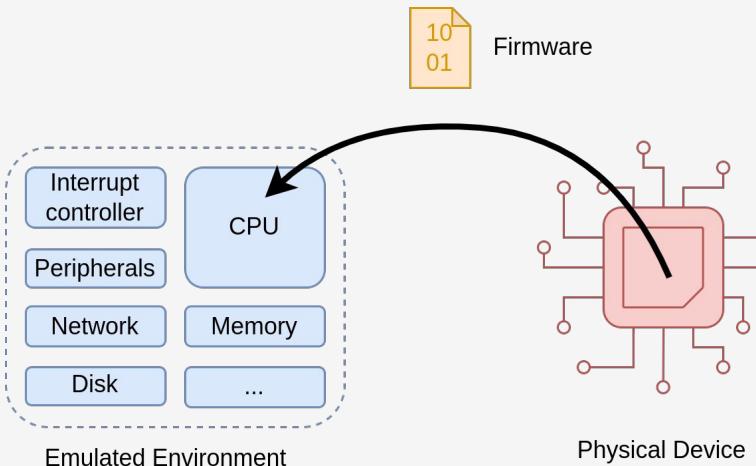
- ... but require to **setup** the environment
- Not always feasible to **run** them **on** the physical device:
 - **Constrained** environment (*computing power, memory size, network bandwidth*)
 - **Insufficient** ability to **control & observe** code execution

> Motivation: Emulation & Rehosting

- Alternative: **emulation**

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- Alternative: **emulation**
- **Rehosting:**



The process of moving the firmware from its original “host” into a virtualized environment that reproduce the original well enough for its execution and analysis

> Motivation: Rehosting Challenges

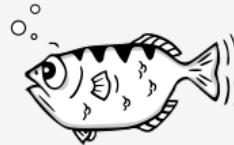
- **Challenges** to run a firmware in an emulator
 - 1. *Acquisition:*
 - Protected memory, disable debug interface, anti-tampering sensors
 - Encryption, obfuscation, proprietary format

> Motivation: Rehosting Challenges

- **Challenges** to run a firmware in an emulator
 - 1. *Acquisition:*
 - Protected memory, disable debug interface, anti-tampering sensors
 - Encryption, obfuscation, proprietary format
 - 2. *Execution:*
 - Understand the Instruction Set Architecture (ARM, MIPS, m68k, Blackfin, Xtensa, etc.)
 - Design to run on a specific hardware (peripherals)

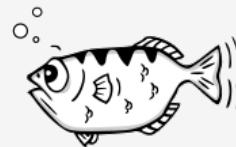
> Problem Statement

- Various techniques
 - *emulation,*
 - *record-replay,*
 - *symbolic execution,*
 - *hardware-in-the-loop,*
 - *hybrid*



> Problem Statement

- Various techniques
 - *emulation,*
 - *record-replay,*
 - *symbolic execution,*
 - *hardware-in-the-loop,*
 - *hybrid*
- How to **combine tools** to leverage their strengths and tackle complex problems?



> avatar²

- Facilitate **interoperability** between Dynamic Binary Analysis techniques and tools
- Provide **abstractions** of debuggers, emulators and other frameworks
- Open source <https://github.com/avatartwo/avatar2>

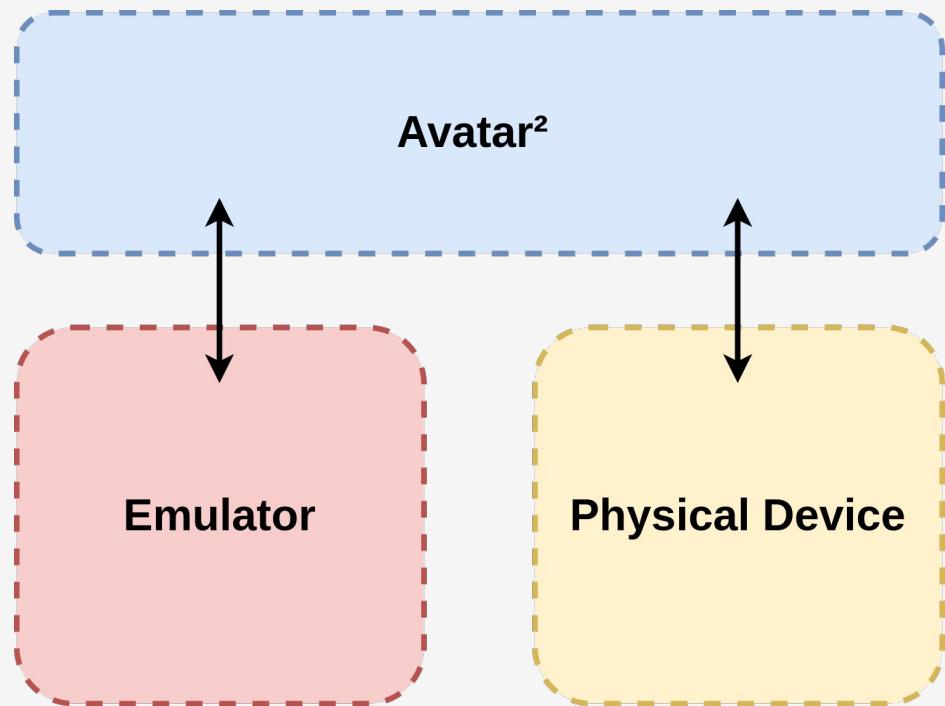


> avatar² Features

- Scriptable (Python based)
- Multiple architecture (ARM, MIPS, x86)
- Target orchestration
 - State transfer & Synchronization
 - Forward memory & I/O accesses
 - Model peripheral

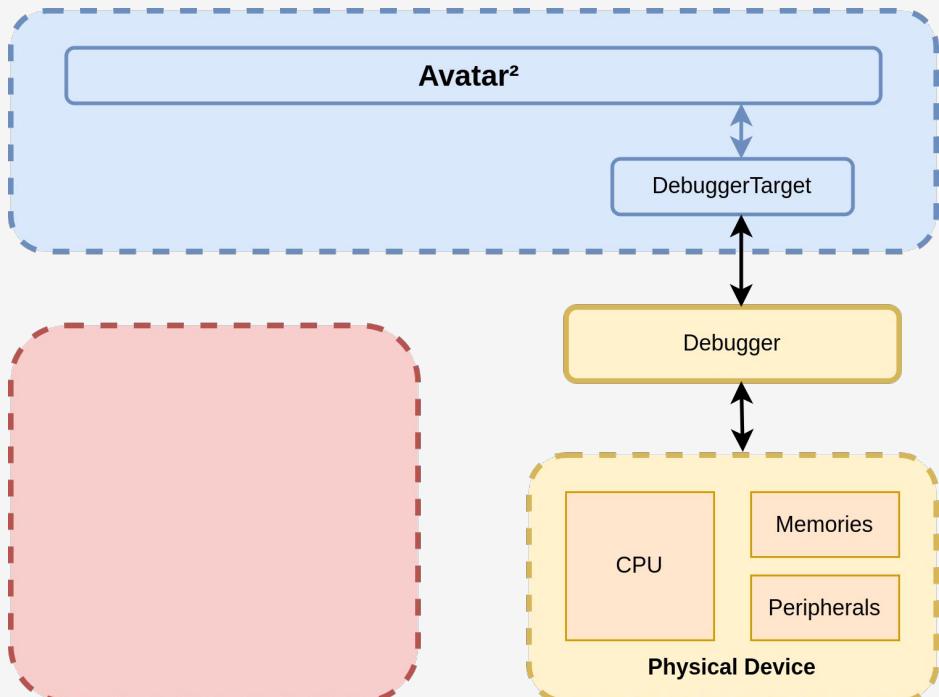
> avatar² Overview

- Orchestration



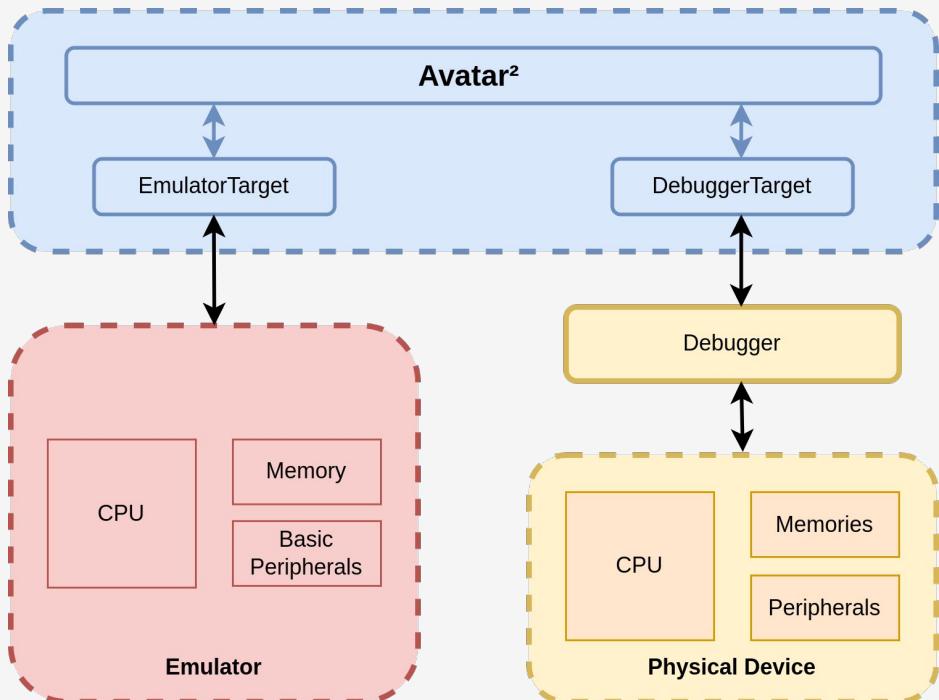
> avatar² Overview

- Physical device



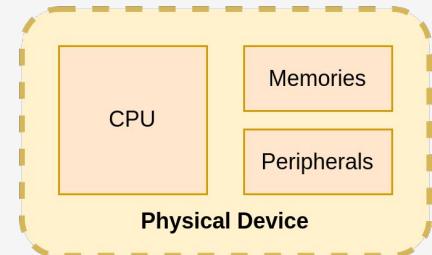
> avatar² Overview

- Emulator



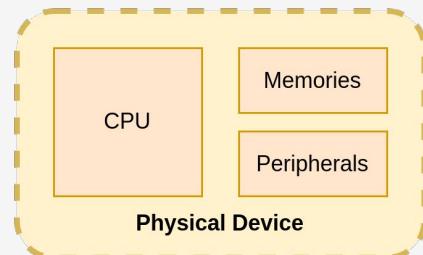
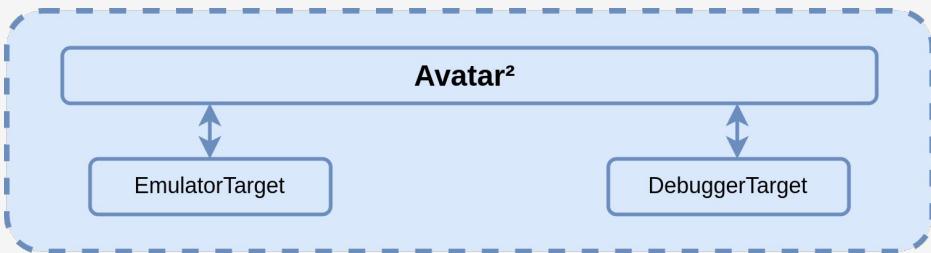
> Initialization

```
# Init  
avatar = Avatar(arch=ARM_CORTEX_M3)
```



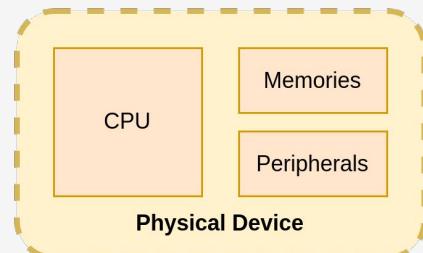
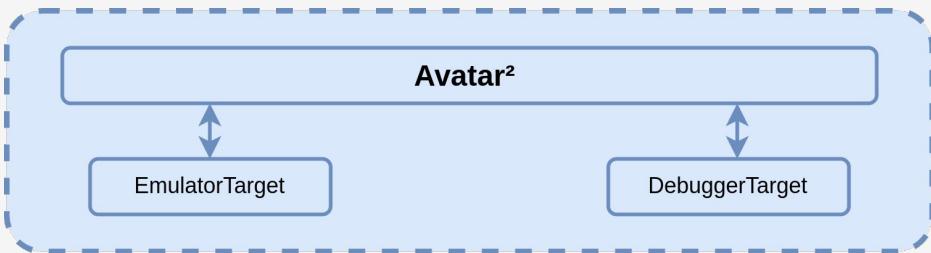
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avatar = Avatar(arch=ARM_CORTEX_M3)  
  
device = avatar.add_target(OpenOCDTarget)  
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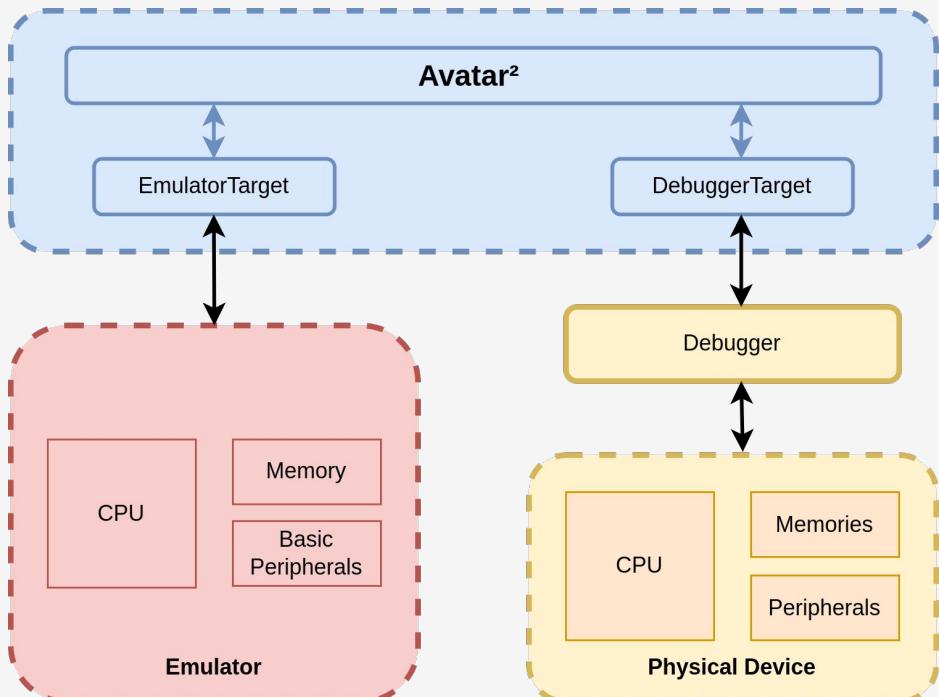
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avatar = Avatar(arch=ARM_CORTEX_M3)  
  
device = avatar.add_target(OpenOCDTarget)  
emulator = avatar.add_target(QemuTarget)  
  
rom = avatar.add_memory_range(0x08000000,  
0x1000000, file=firmware)  
ram = avatar.add_memory_range(0x20000000,  
0x14000)
```



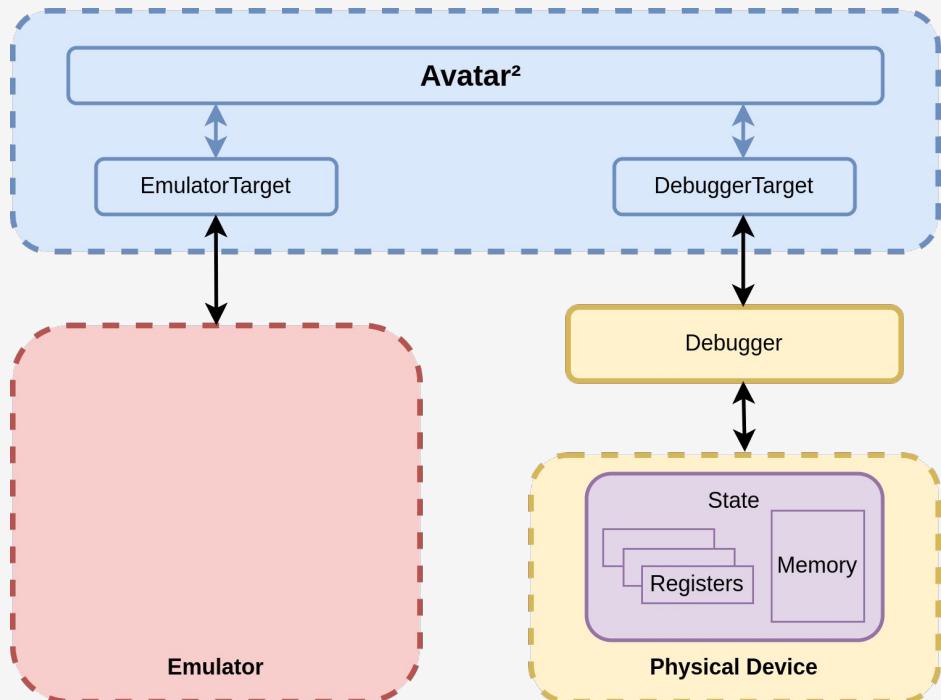
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avatar.init_targets()
```



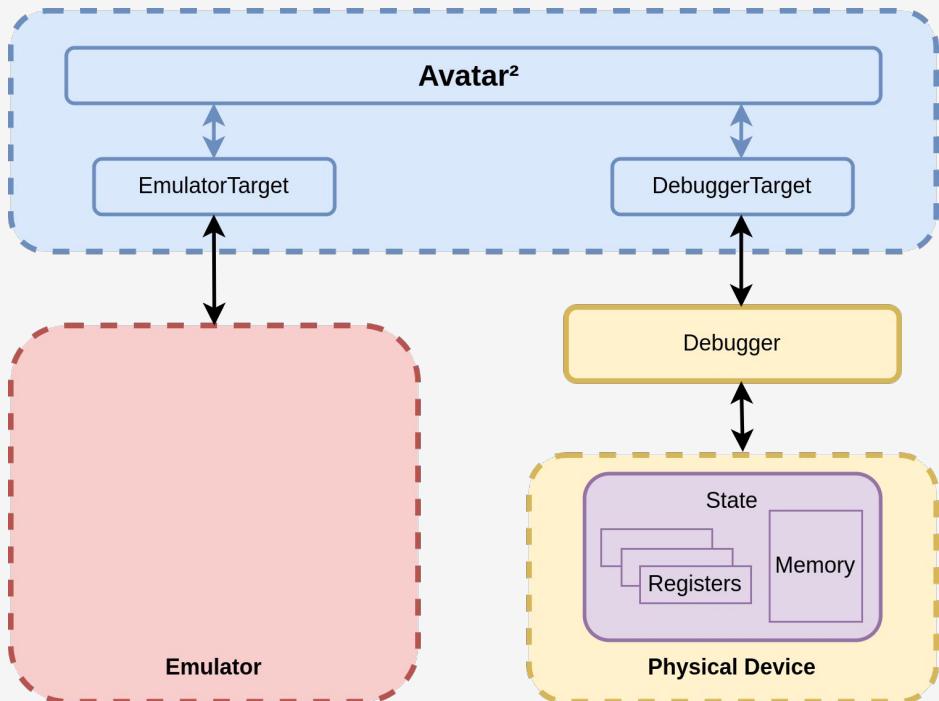
> State Transfer

- **Synchronize** CPU registers and memory content
- **Focus** the analysis
(device & firmware initialization)



> State Transfer

```
# 1) Set the breakpoint on the physical  
device  
device.set_breakpoint(0x8005104)  
device.cont()  
device.wait()
```



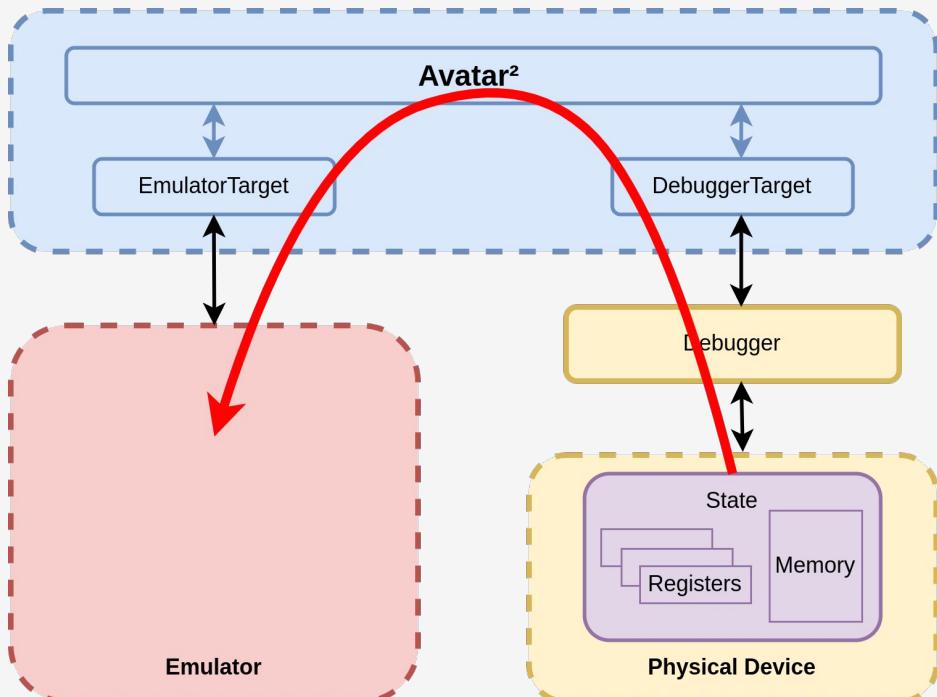
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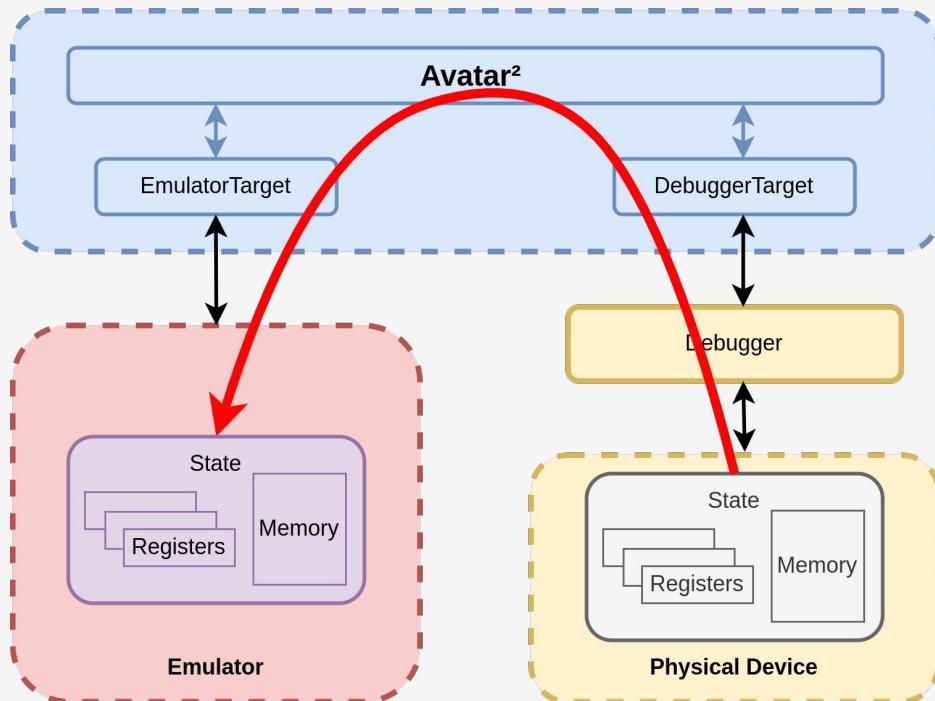
```
# 2) Transfer the state
```

```
avatar.transfer_state(device, emulator,  
                      synced_ranges=[ram])
```



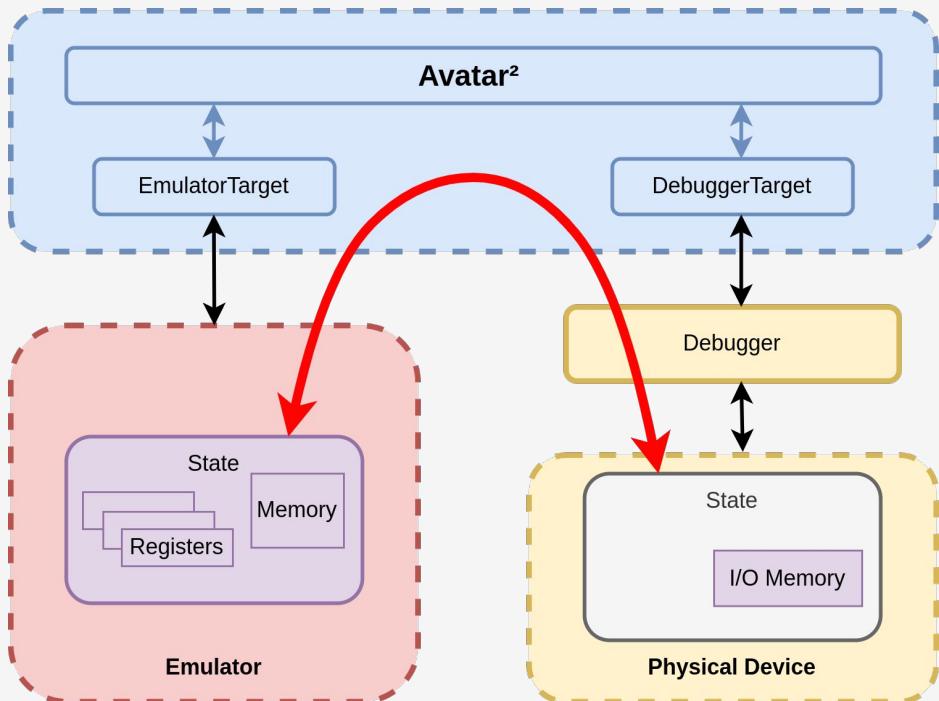
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device.cont()  
device.wait()  
  
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avatar.transfer_state(device, emulator,  
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emulator.cont()
```



> Peripheral Forwarding

- Forward I/O memory



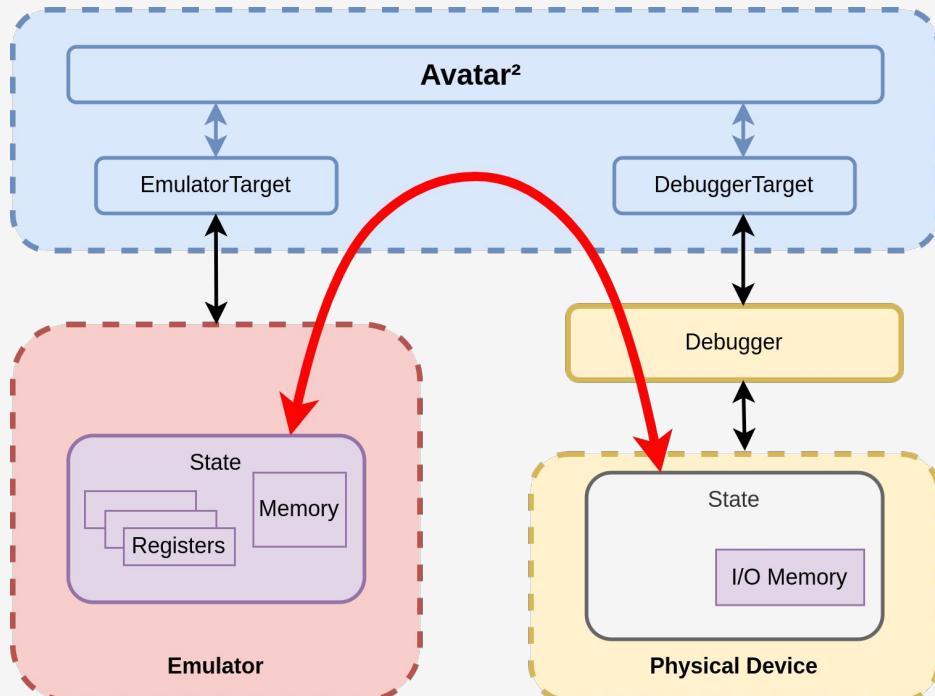
> Peripheral Forwarding

```
# Define the various memory ranges

rom = avatar.add_memory_range(0x08000000,
0x1000000, file=firmware)

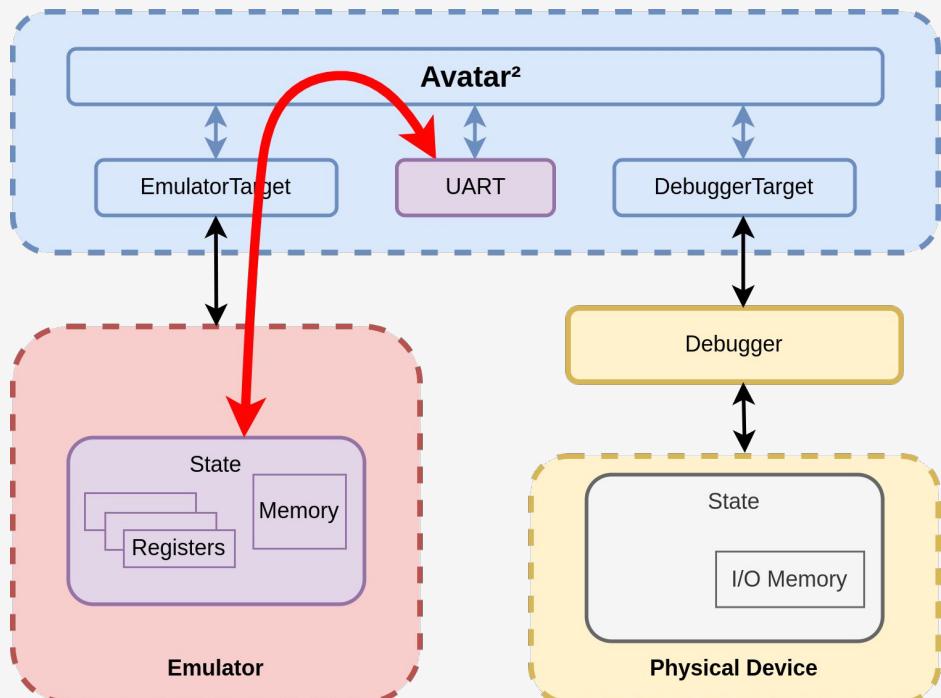
ram = avatar.add_memory_range(0x20000000,
0x14000)

mmio = avatar.add_memory_range(0x40000000,
0x1000000, forwarded=True,
forwarded_to=device)
```



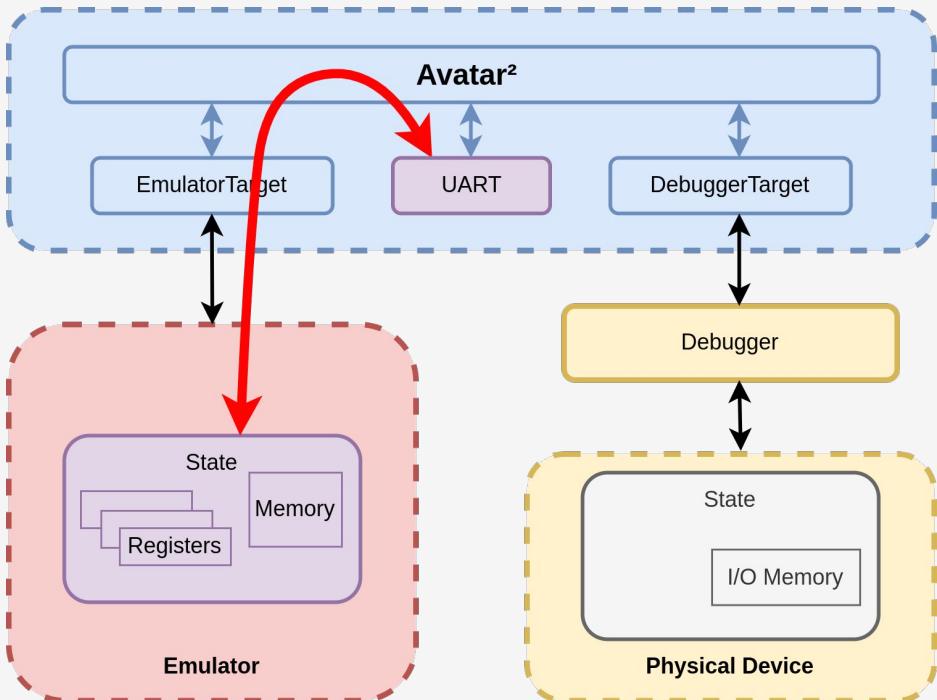
> Peripheral Modeling

- Emulate peripheral in python



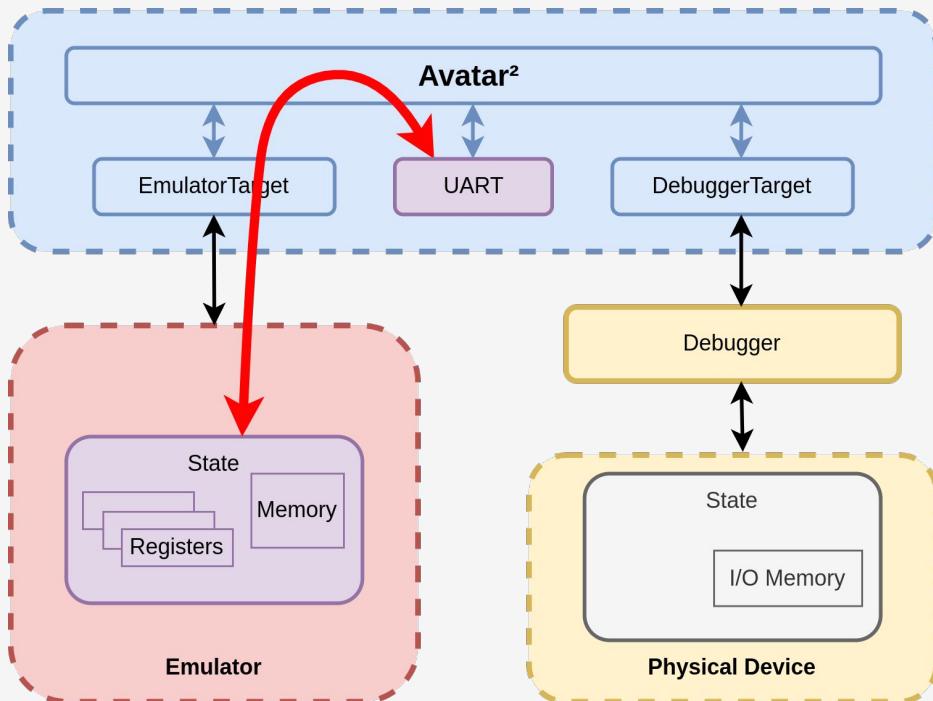
> Peripheral Modeling

```
class UART(AvatarPeripheral):  
    # ...  
  
    def dispatch_read(self, offset, size):  
        if offset == 0x11c:  
            return self.txdone  
        return 0x00  
  
    def dispatch_write(self, offset, size, value):  
        if offset == 0x11c:  
            self.txdone = value  
        elif offset == 0x51c:  
            print(f">>> {chr(value)} <<<")  
            self.txdone = 1  
  
        return True
```



> Peripheral Modeling

```
class UART(AvatarPeripheral):  
    # ...  
  
    # Define the various memory ranges  
    # ...  
    uart = avatar.add_memory_range(0x40002000,  
        0x1000, emulate=UART)
```



> Going Further

- Handbook
 - <https://github.com/avatartwo/avatar2/tree/main/handbook>

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 - <https://github.com/avatartwo/avatar2/tree/main/handbook>
- Examples
 - <https://github.com/avatartwo/avatar2-examples>
 - U-Boot - Example without hardware
 - NUCLEO L152RE - Transfer state
 - NRF51 BLE - WiSec'21 tutorial on avatar2
 - Rehosting the Raspberry Pi Pico blink example

> Going Further

- Rehosting
 - <https://github.com/halucinator/halucinator>
 - Records peripheral accesses to model them: <https://github.com/ucsb-seclab/pretender>
- Fuzzing
 - <https://github.com/FirmWire/FirmWire>
 - <https://github.com/fgsect/unicorefuzz>
- Symbolic execution
 - https://angr.io/blog/angr_symbion/
 - <https://github.com/csvl/SEMA-ToolChain>

> Conclusion

- Dynamic firmware binary analysis is still a challenging topic
- Various possible approaches
- Avatar² focuses on interoperability of tools

> Links

- Framework
<https://github.com/avatartwo/avatar2>
- Examples
<https://github.com/avatartwo/avatar2-examples>
- Slack
<https://avatartwo.slack.com/>
- Team
 - Paul OLIVIER (paul.olivier@laas.fr)
 - Marius MUENCH
 - Florian ALBRECHT
 - Aurélien FRANCILLON



Backup slides

> A wide variety of systems for firmware



arm
MBED



U-Boot



NUCLEUS
RTOS



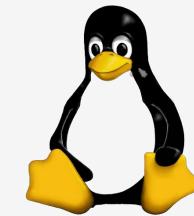
VxWorks



MicroPython



*μ*Clinux



busybox



Windows®
Embedded CE

> Firmware classification

Type I

- *General purpose*
OS-based devices
- minimalist
- lightweight user mode
applications



busybox



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busybox



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- Embedded OS-based devices
- small footprint
- high performance
- real-time scheduling



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busybox



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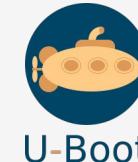


Type III

- Devices *without an OS-Abstraction*
- monolithic firmware



MicroPython



U-Boot



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