⟨Iterator(s.roots), ∅, []⟩

initialConf

 $\frac{\langle it, K, c::F \rangle \wedge !it.hasNext}{\langle Iterator(s.neighbours(c)), K, F \rangle}$

discover(c)

 $\langle it, K, F \rangle \land it.hasNext \land (n = it.peek) \in K$ $\langle it.next, K, F \rangle$

known(n)

 $\langle it, K, F \rangle \wedge it.hasNext \wedge (n = it.peek) \notin K \langle it.next, K \cup \{n\}, F::n \rangle$

unknown(n)

 $\langle it, K, [] \rangle \wedge !it.hasNext \langle it, K, [] \rangle$

end