

# Type-and-Example-Directed Program Synthesis

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TFP 2016



**ExCAPE**  
Expeditions in Computer Augmented  
Program Engineering



# Joint With

Peter-Michael Osera



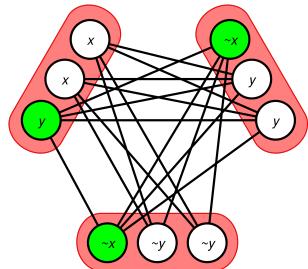
Jonathan Frankle  
Georgetown  
University

David Walker



# Program Synthesis

*Program Search + Specification*

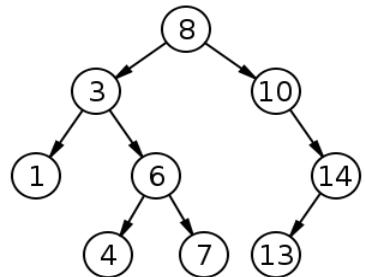
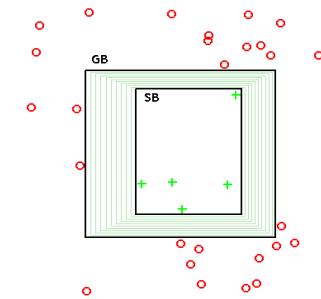


Formal methods: SMT solvers,  
model checking, CEGIS

[Solar-Lezama; Kneuss; Bodik, Torlak; Gulwani; ...]

Machine Learning: inductive  
learning, genetic prog.

[Lau; Weimer; Seshia; ...]



AI/Logic: syntactic enumerative  
(SyGus) / proof theory

[Green (1969), Summers (1976), Waldinger &  
Manna (1980) ... Kitzelmann; Albarghouthi,  
Kincaid; Kuncak, Piscak, ...]

# This talk

Type-and-Example-Directed  
Program synthesis

[PLDI 2015: Osera & Zdancewic]

Example-Directed Synthesis:  
A Type-Theoretic Interpretation

[POPL 2016: Frankle, Osera, Walker, & Zdancewic]

Verification

Optimization

Types:  
What are they good for?

Program Design

*“My program writes itself!”*  
*(a.k.a. type-directed programming)*

$t_1 \rightarrow t_2 \rightsquigarrow \text{let } f \ (x:t_1) : t_2 = \blacksquare$

$c \rightsquigarrow (g . f) \blacksquare$   
 $(f : A \rightarrow B, g : B \rightarrow C)$

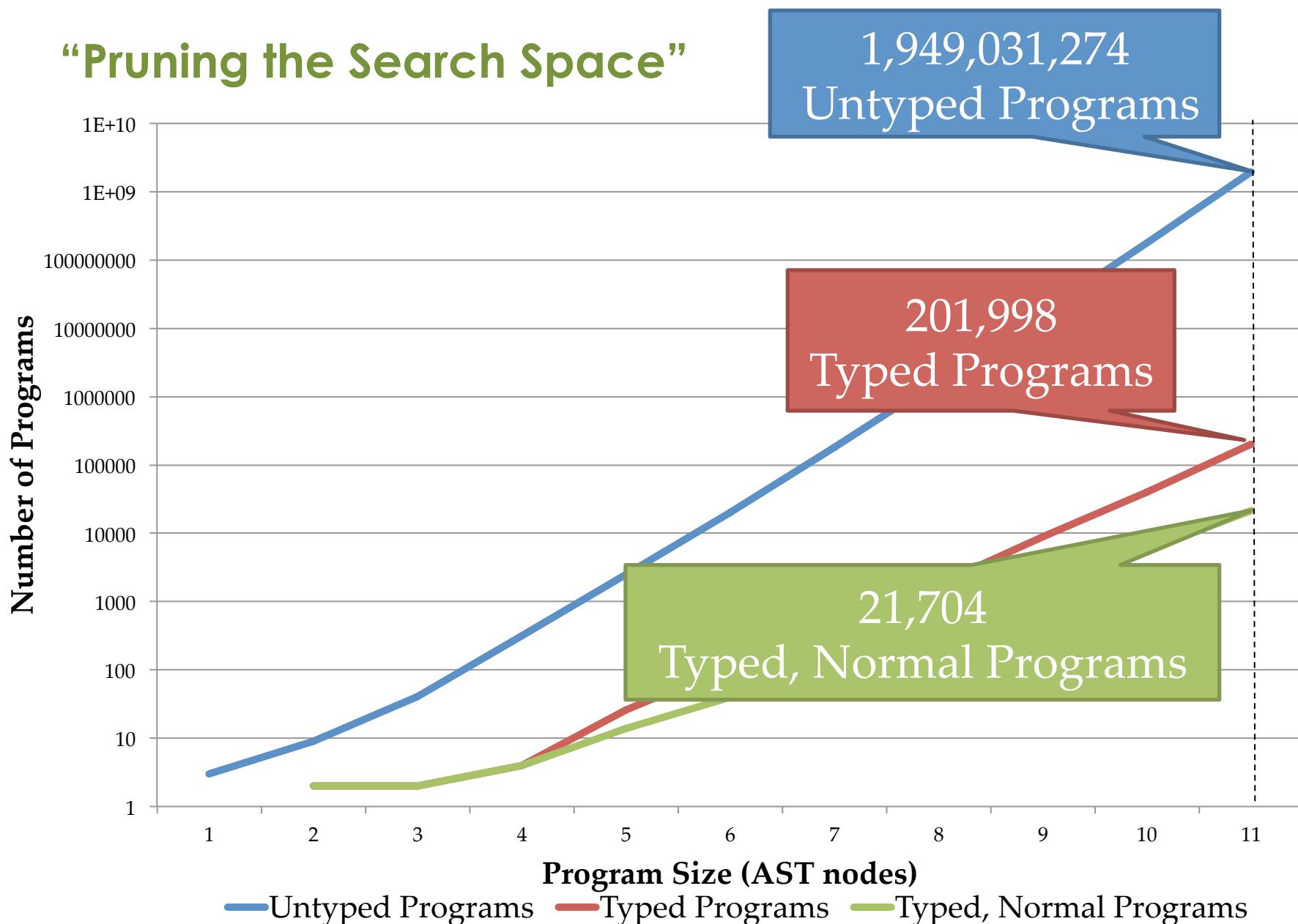
**How can we mechanize this reasoning?**

$\lambda$ 

## Type theoretic foundations

1. Synthesize programs with *higher-order functions, recursion, and algebraic datatypes.*
2. Type structure prunes the search space.
3. Take advantage of techniques from proof theory literature

## “Pruning the Search Space”



# **Myth**, a program synthesizer for typed, functional programs (OCaml).

```
1. bash
kambing-mobile:synml posera$ time ./synml.native job-talk/stutter.ml -nosugar
let stutter : mylist -> mylist =
  let rec f1 (m1:mylist) : mylist =
    match m1 with
      | Nil -> Nil
      | Cons (i1, m2) -> Cons (i1, Cons (i1, f1 m2))
  in
    f1
;;
```

(**MYTH DEMO**)

(One type per expression)

$$\Gamma \vdash e : \tau$$

Inputs                      Output\*

⇒ Typechecking specification

## Simply-typed Lambda Calculus

$$\begin{array}{lcl} \tau & ::= & \tau_1 \rightarrow \tau_2 \mid T \\ e & ::= & x \mid e_1 e_2 \mid \lambda x:\tau. e \mid c \end{array} \quad \begin{array}{c} \text{Types} \\ \text{Terms} \end{array}$$

$$\frac{}{\Gamma \vdash x : \tau} \quad \text{T-VAR}$$

$$\frac{x:\tau_1, \Gamma \vdash e : \tau_2}{\Gamma \vdash \lambda x:\tau_1. e : \tau_1 \rightarrow \tau_2} \quad \text{T-LAM}$$

$$\frac{\Gamma \vdash e_1 : \tau_1 \rightarrow \tau_2 \quad \Gamma \vdash e_2 : \tau_1}{\Gamma \vdash e_1 e_2 : \tau_2} \quad \text{T-APP}$$

$$\frac{}{\Gamma \vdash c : T} \quad \text{T-BASE}$$

## Type Checking / Inference

$$\frac{g : B \rightarrow C \in \Gamma}{\Gamma \vdash g : B \rightarrow C} \qquad \frac{\begin{array}{c} f : A \rightarrow B \in \Gamma \\ x : A \in \Gamma \end{array}}{\begin{array}{c} \Gamma \vdash f : A \rightarrow B \\ \Gamma \vdash x : A \end{array}} \qquad \frac{\Gamma \vdash f : A \rightarrow B \quad \Gamma \vdash x : A}{\Gamma \vdash f x : B}$$

---

$$\frac{\Gamma}{f : A \rightarrow B, g : B \rightarrow C, x : A \vdash g(f x) : C}$$

$$\frac{}{f : A \rightarrow B, g : B \rightarrow C \vdash \lambda x : A. g(f x) : A \rightarrow C}$$

$$\frac{}{f : A \rightarrow B \vdash \lambda g : B \rightarrow C. \lambda x : A. g(f x) : (B \rightarrow C) \rightarrow A \rightarrow C}$$

$$\vdash \lambda f : A \rightarrow B. \lambda g : B \rightarrow C. \lambda x : A. g(f x) : (A \rightarrow B) \rightarrow (B \rightarrow C) \rightarrow A \rightarrow C$$

(Many expressions per type)

Inputs

Output

$$\Gamma \vdash \tau \rightsquigarrow e$$

⇒ Well-typed term *search* procedure

Derivation → Enumerated Program

## Eliminating Redundancy: Normal Form Terms

```
(fun x : nat -> x + 1) 3 ≡ 4
```

```
match Nil with
| Nil -> 4 ≡ 4
| Cons (x,1) -> e
```

⇒ Avoid enumerating non-normal terms

$$\frac{\lambda x{:}\tau.\;e}{C(e_1,\ldots,e_k)}\quad\frac{x}{e_1\;e_2}$$

$$\mathrm{match}\; e \;\mathrm{with}\; \overline{p_i \rightarrow e_i}^{i < m}$$

$$\lambda x:\tau. I$$
$$C(I_1, \dots, I_k)$$

“Introduction”  
forms, I

$$\frac{x}{E I}$$

“Elimination”  
forms, E

match  $E$  with  $\overline{p_i \rightarrow I_i}^{i < m}$

$$\lambda x:\tau. I$$
$$C(I_1, \dots, I_k)$$

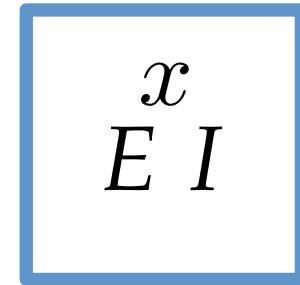
$$\begin{array}{c} x \\ E \\ I \end{array}$$

### (1) Type-directed **Refinement**

Type → Term Shape → Example Refinement.

match  $E$  with  $\overline{p_i \rightarrow I_i}^{i < m}$

$$\lambda x:\tau. I$$
$$C(I_1, \dots, I_k)$$



(1) Type-directed **Refinement**

(2) **Guess**-and-check

Normalize-and-compare strategy.

match  $E$  with  $\overline{p_i \rightarrow I_i}^{i < m}$

$$\lambda x:\tau. I$$
$$C(I_1, \dots, I_k)$$

$$\begin{matrix} x \\ E \end{matrix} \quad I$$

(1) Type-directed **Refinement**

(2) **Guess**-and-check

Decompose data to learn more information.

match  $E$  with  $\overline{p_i \rightarrow I_i}^{i < m}$

(3) **Learning** via pattern matching

$$\lambda x:\tau. I$$
$$C(I_1, \dots, I_k)$$

$$\begin{matrix} x \\ E \end{matrix} I$$

(1) Type-directed **Refinement**

(2) **Guess**-and-check

Breadth-first search for valid derivations.

$\Rightarrow$

Synthesize the *smallest* satisfying program.

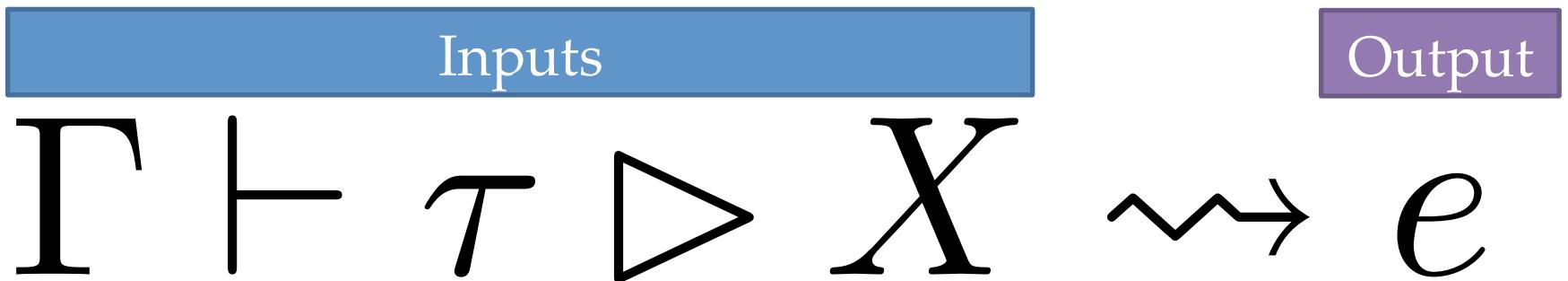
match  $E$  with  $\overline{p_i \rightarrow I_i}^{i < m}$

(3) **Learning** via pattern matching

**Example values:**

- Constructors
- Input/output pairs

$$\left[ \begin{array}{l} \chi ::= C(\chi_1, \dots, \chi_k) \\ | \overline{v_i \Rightarrow \chi_i}^{i < n} \end{array} \right]$$



⇒ Type-and-example *refinement* procedure

Derivation → Satisfying Program

**stutter : list -> list**

■ : list -> list

Context

Goal Examples:

[] => []

[0] => [0, 0]

[1, 0] => [1, 1, 0, 0]

**stutter : list -> list**

```
let rec stutter (l:list) : list =  
  ■ : list
```

<u>Context</u>	<u>Goal Examples:</u>
	↔ [ ] => [ ]
	↔ [0] => [0, 0]
	↔ [1, 0] => [1, 1, 0, 0]

stutter : list -> list

```
let rec stutter (l:list) : list =  
  ■ : list
```

Example “World”

Context

$l = []$

$l = [0]$

$l = [1, 0]$

Goal Examples:

$[]$

$[0, 0]$

$[1, 1, 0, 0]$

**stutter : list -> list**

```
let rec stutter (l:list) : list =  
  l
```

1. Generate an expression\*
2. Evaluate and check against each example world

\*We don't generate **stutter l** – syntactic restriction on recursive calls.

Context

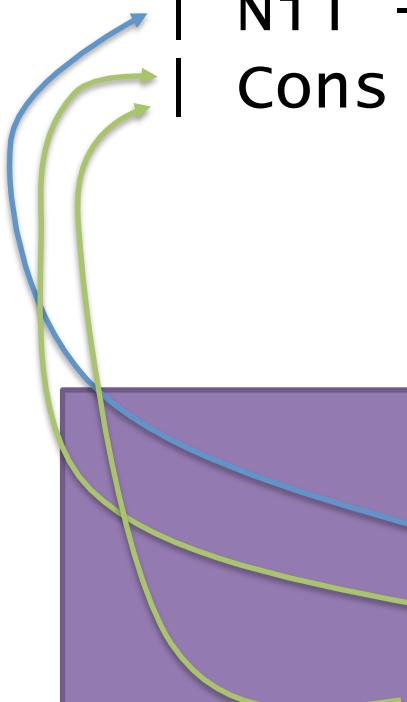
```
l=[]  
l=[0]  
l=[1, 0]
```

Goal Examples:

[]	
[0, 0]	
[1, 1, 0, 0]	

stutter : list → list

```
let rec stutter (l:list) : list =  
  match l with  
  | Nil -> [] : list  
  | Cons (x, l') -> [x, x] @ stutter l'
```



Context

$l = []$

$l = [0]$

$l = [1, 0]$

Goal Examples:

[]

[0, 0]

[1, 1, 0, 0]

**stutter : list -> list**

```
let rec stutter (l:list) : list =  
  match l with  
  | Nil -> [] : list  
  | Cons (x, l') -> [x] @ stutter l'
```

Context

$l = []$

Goal Examples:

$[]$

**stutter : list -> list**

```
let rec stutter (l:list) : list =  
  match l with  
  | Nil -> Nil  
  | Cons (x, l') -> [x] @ stutter l'
```

Context

$l = []$

Goal Examples:

$[]$



**stutter : list -> list**

```
let rec stutter (l:list) : list =  
  match l with  
  | Nil -> Nil  
  | Cons (x, l') -> ■ : list
```

Context

$l=[0], \dots$

$l=[1, 0], \dots$

Goal Examples:

[0, 0]

[1, 1, 0, 0]

**stutter : list -> list**

```
let rec stutter (l:list) : list =  
  match l with  
  | Nil -> Nil  
  | Cons (x, l') -> ■ : list
```

Context

$l=[0]$ ,  $x=0$ ,  $l'=[]$   
 $l=[1, 0]$ ,  $x=1$ ,  $l'=[0]$

Goal Examples:

[0, 0]  
[1, 1, 0, 0]

stutter : list -> list

```
let rec stutter (l:list) : list =  
  match l with  
  | Nil -> Nil  
  | Cons (x, l') ->  
    Cons (x, Cons (x, ■ : list))
```

want: stutter l'  
trv , ...

### Context

$l=[0]$ ,  $x=0$ ,  $l'=[]$   
 $l=[1, 0]$ ,  $x=1$ ,  $l'=[0]$

### Goal Examples:

[]  
[0, 0]

**stutter : list -> list**

```
let rec stutter (l:list) : list =
  match l with
  | Nil -> Nil
  | Cons (x, l') ->
    Cons (x, Cons (x, stutter l'))
```

```
stutter = ( [] => [] | [0] => [0, 0]
            | [1, 0] => [1, 1, 0, 0] )
```

Context

$l=[0]$ ,  $x=0$ ,  $l'=[]$   
 $l=[1, 0]$ ,  $x=1$ ,  $l'=[0]$

Goal Examples:

[]  
[0, 0]

stutter : list -> list

```
let rec stutter (l:list) : list =  
  match l with  
  | Nil -> Nil  
  | Cons (x, l') ->  
    Cons (x, Cons (x, stutter l'))  
  
stutter=( [] => [] | [0] => [0, 0]  
          | [1, 0] => [1, 1, 0, 0] )
```

stutter [] = []

Context  
→  $l=[0]$ ,  $x=0$ ,  $l'=[ ]$   
 $l=[1, 0]$ ,  $x=1$ ,  $l'=[0]$

Goal Examples:  
[]   
[0, 0]

**stutter : list -> list**

```
let rec stutter (l:list) : list =  
  match l with  
  | Nil -> Nil  
  | Cons (x, l') ->  
    Cons (x, Cons (x, stutter l'))
```

stutter [0] = [0, 0]

stutter= ( [] => [] | [0] => [0, 0]  
 | [1, 0] => [1, 1, 0, 0] )

### Context

$l=[0]$ ,  $x=0$ ,  $l'=[]$

→  $l=[1, 0]$ ,  $x=1$ ,  $l'=[0]$

### Goal Examples:

[]

[0, 0]



stutter : list -> list

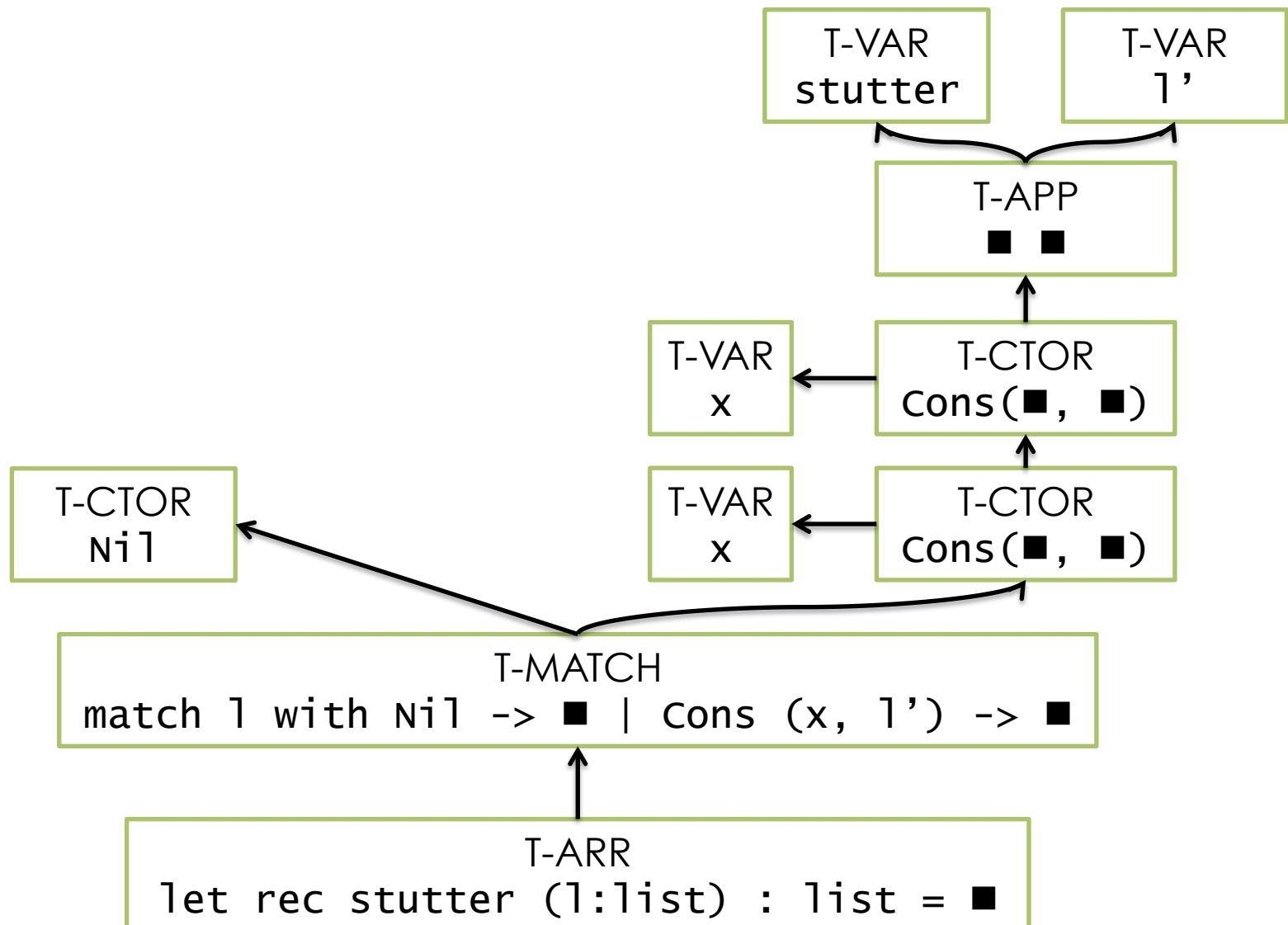
```
let rec stutter (l:list) : list =  
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```



```
stutter=( [] => [] | [0] => [0, 0]  
          | [1, 0] => [1, 1, 0, 0] )
```

“Trace Completeness”

e.g.,  $[1, 0] \rightarrow [0] \rightarrow []$



# $\lambda_{\text{syn}}$ , a logical foundation for program synthesis.

<b>IGUESS-FIX</b> $\frac{\Sigma; \Gamma, x:\tau_1 \triangleright \cdot, f:\tau_1 \rightarrow \tau_2 \triangleright \cdot \vdash \tau_2 \xrightarrow{I} I}{\Sigma; \Gamma \vdash \tau_1 \rightarrow \tau_2 \xrightarrow{I} \text{fix } f(x:\tau_1) : \tau_2 = I}$	<b>IGUESS-MATCH</b> $\frac{\Sigma; \Gamma \vdash T \xrightarrow{E} E \quad \text{split}(\Sigma, \Gamma, T) = \overline{(p_m, \Gamma_m)}^m \quad \overline{\Sigma; \Gamma_m \vdash \tau \xrightarrow{I} I_m}^m}{\Sigma; \Gamma \vdash \tau \xrightarrow{I} \text{match } E \text{ with } p_m \rightarrow I_m}$
$\boxed{\Sigma; \Gamma \vdash \tau \triangleright X \rightsquigarrow I \quad (\text{IREFINER})}$	<b>IREFINER-GUESS</b> $\frac{\Sigma; \Gamma \vdash T \xrightarrow{E} E \quad \Gamma(E) \Downarrow X}{\Sigma; \Gamma \vdash T \triangleright X \rightsquigarrow E}$
<b>IREFINER-FIX</b> $\frac{\forall i \in 1..n. X[i] = \overline{v_{im_i}} \Rightarrow ex_{im_i}^{m_i} \quad \Gamma' = f:\tau_1 \rightarrow \tau_2 \triangleright X^{[m_1, \dots, m_n]}, x:\tau_1 \triangleright v^{[m_1, \dots, m_n]}, \Gamma^{[m_1, \dots, m_n]} \quad \Sigma; \Gamma' \vdash \tau_2 \triangleright ex^{[m_1, \dots, m_n]} \rightsquigarrow I}{\Sigma; \Gamma \vdash \tau_1 \rightarrow \tau_2 \triangleright X \rightsquigarrow \text{fix } f(x:\tau_1) : \tau_2 = I}$	



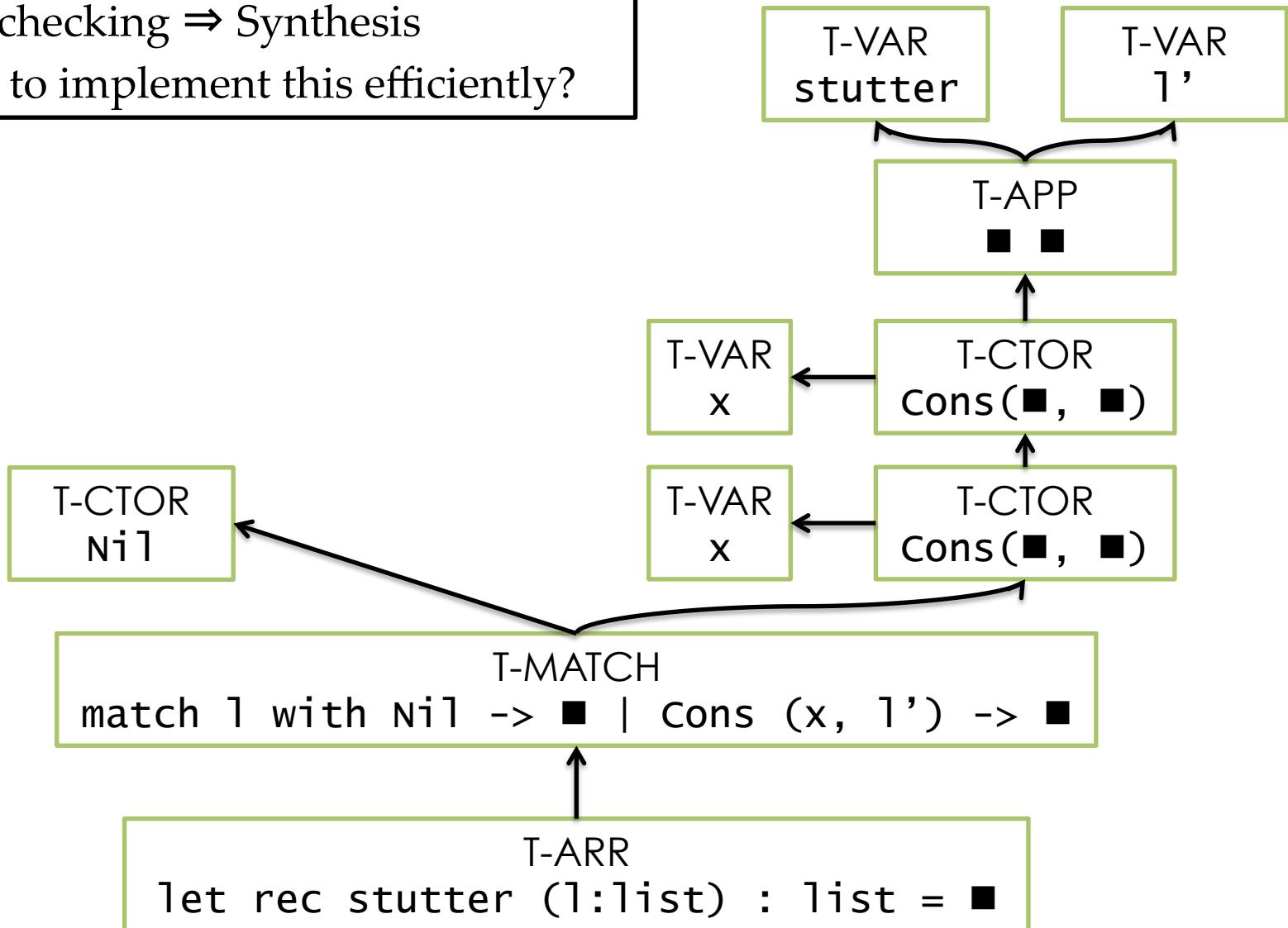
Myth, a program synthesizer for typed, functional programs (OCaml).

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  in
  f1
;;

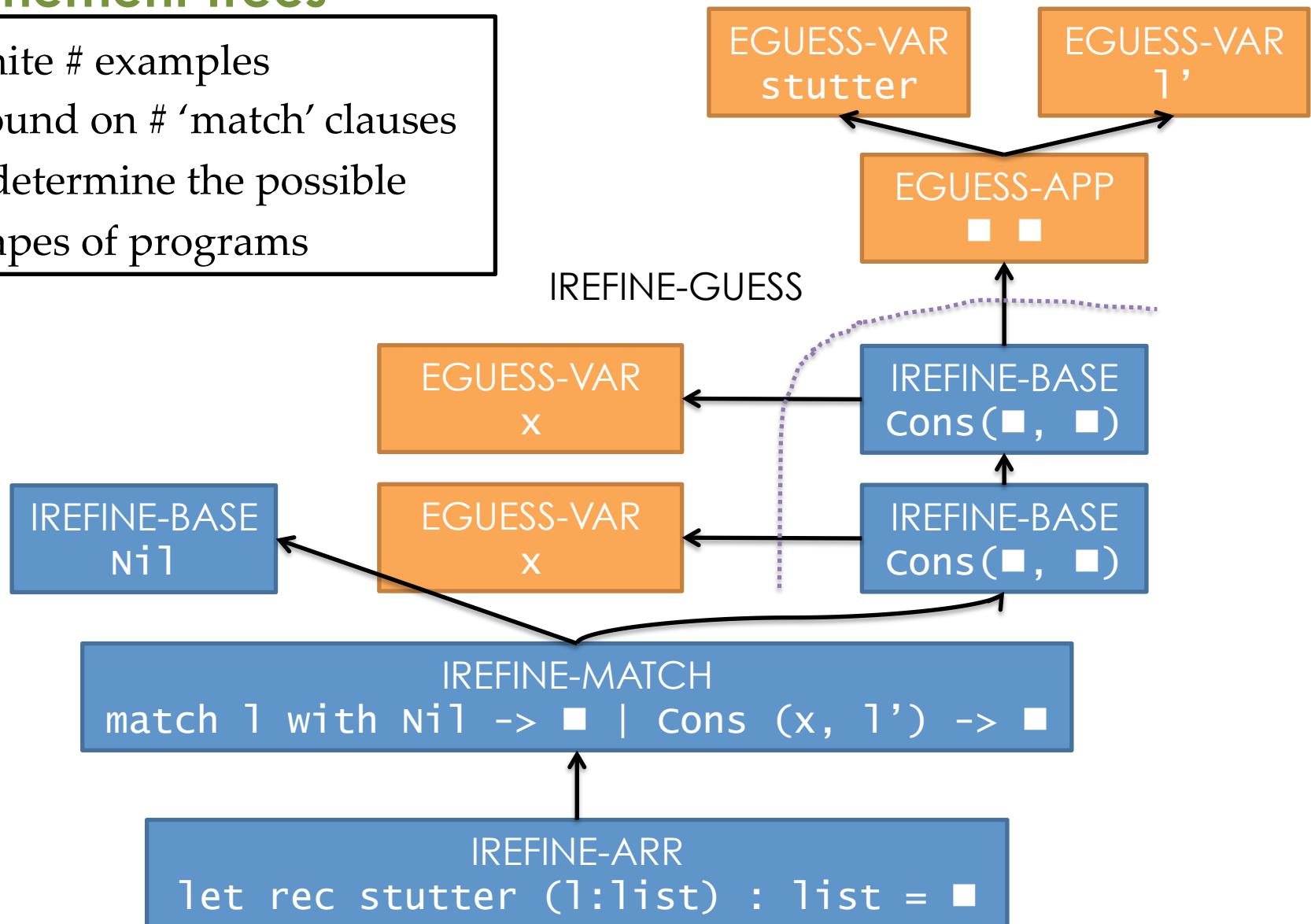
```

Typechecking  $\Rightarrow$  Synthesis  
 How to implement this efficiently?



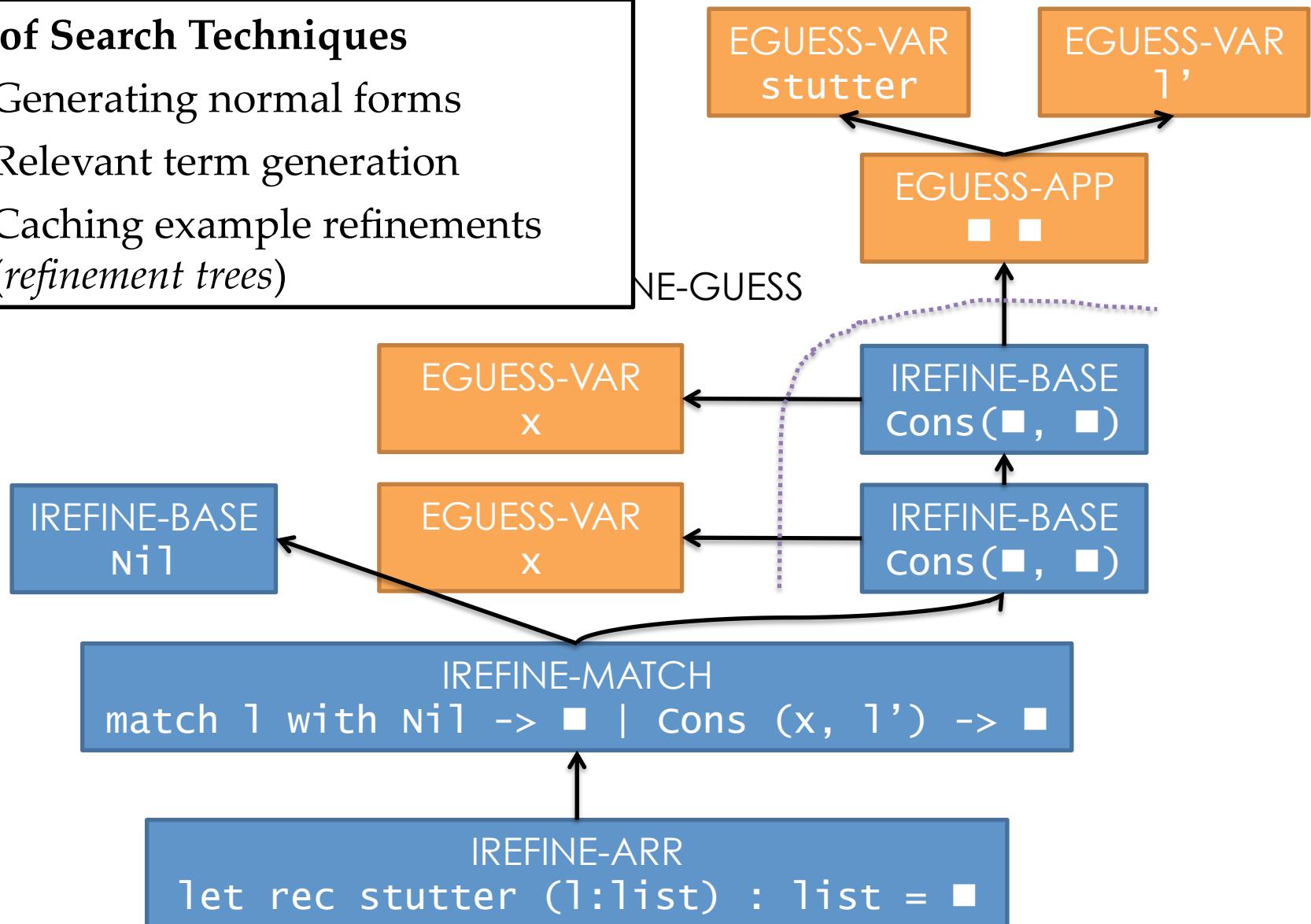
## Refinement Trees

- finite # examples
  - bound on # 'match' clauses
- ⇒ determine the possible shapes of programs



## Proof Search Techniques

- Generating normal forms
- Relevant term generation
- Caching example refinements  
(*refinement trees*)



## Algorithmic Insight: Relevance Logic $\Rightarrow$ Caching

$\mathbf{gen}_E(\Sigma; \Gamma; \tau; n)$

“Generate type  $\tau$  E-forms in context  $\Gamma$  with size  $n$ ”

$$\mathbf{gen}_E(\Sigma; \cdot; \tau; n) = \{\}$$

$$\mathbf{gen}_E(\Sigma; \cdot; \tau; 0) = \{\}$$

$$\mathbf{gen}_E(\Sigma; x:\tau_1, \Gamma; \tau; n) = \mathbf{gen}_E^{x:\tau_1}(\Sigma; \Gamma; \tau; n) \cup \mathbf{gen}_E(\Sigma; \Gamma; \tau; n)$$

x relevant  
*(must be used)*

x irrelevant  
*(not used)*

cacheable

## Implementing Relevance

---

$$\mathbf{gen}_E^{x:\tau_1}(\Sigma; \Gamma; \tau; n)$$

“Generate type  $\tau$  E-forms that *definitely mention*  $x$   
in context  $\Gamma$  with size  $n$ ”

$$\mathbf{gen}_E^{x:\tau_1}(\Sigma; \Gamma; \tau; 0) = \{\}$$

$$\mathbf{gen}_E^{x:\tau}(\Sigma; \Gamma; \tau; 1) = \{x\}$$

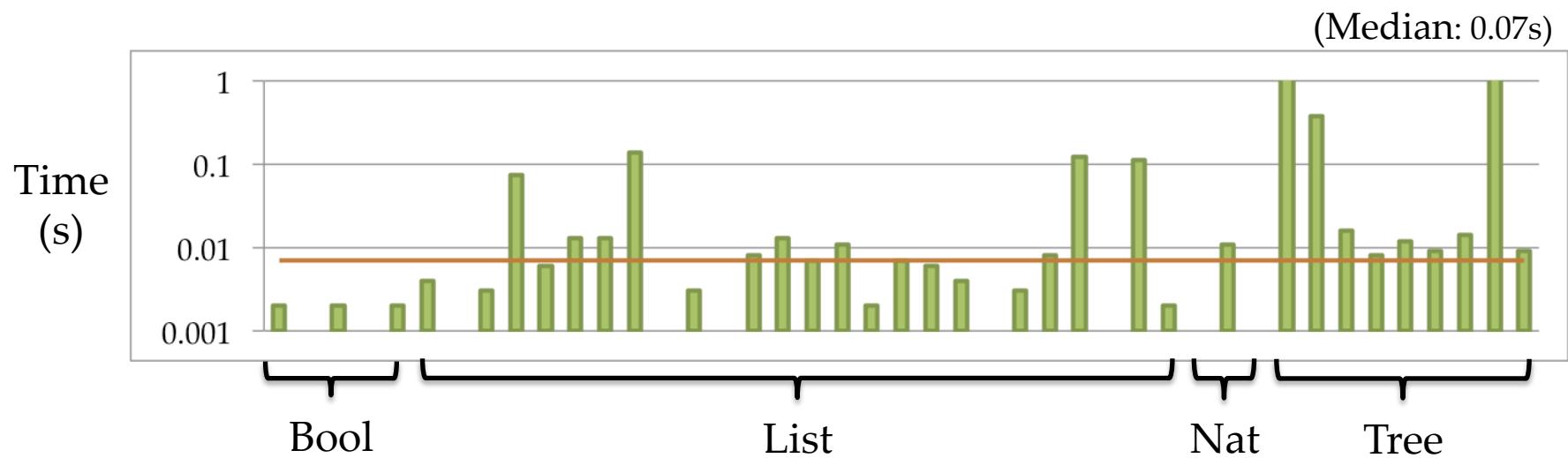
$$\mathbf{gen}_E^{x:\tau_1}(\Sigma; \Gamma; \tau; 1) = \{\} \quad (\tau \neq \tau_1)$$

$$\mathbf{gen}_E^{x:\tau_1}(\Sigma; \Gamma; \tau; n) = \bigcup_{\tau_2 \rightarrow \tau \in \Gamma} \bigcup_{k=1}^{n-1}$$

$$(\mathbf{gen}_E^{x:\tau_1}(\Sigma; \Gamma; \tau_2 \rightarrow \tau; k) \underset{app}{\otimes} \mathbf{gen}_I(\Sigma; \Gamma; \tau_2; n - k))$$

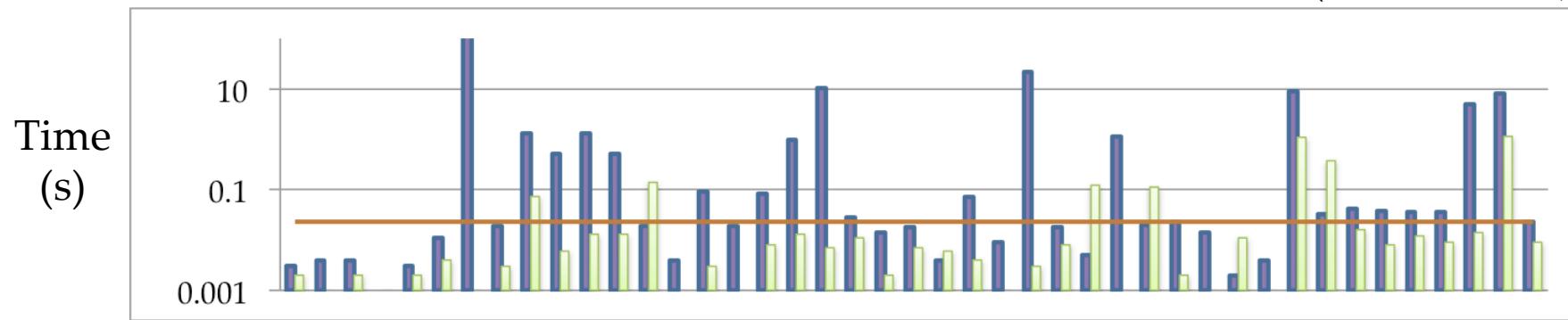
$$\cup \quad (\mathbf{gen}_E(\Sigma; \Gamma; \tau_2 \rightarrow \tau; k) \underset{app}{\otimes} \mathbf{gen}_I^{x:\tau_1}(\Sigma; \Gamma; \tau_2; n - k))$$

$$\cup \quad (\mathbf{gen}_E^{x:\tau_1}(\Sigma; \Gamma; \tau_2 \rightarrow \tau; k) \underset{app}{\otimes} \mathbf{gen}_I^{x:\tau_1}(\Sigma; \Gamma; \tau_2; n - k))$$



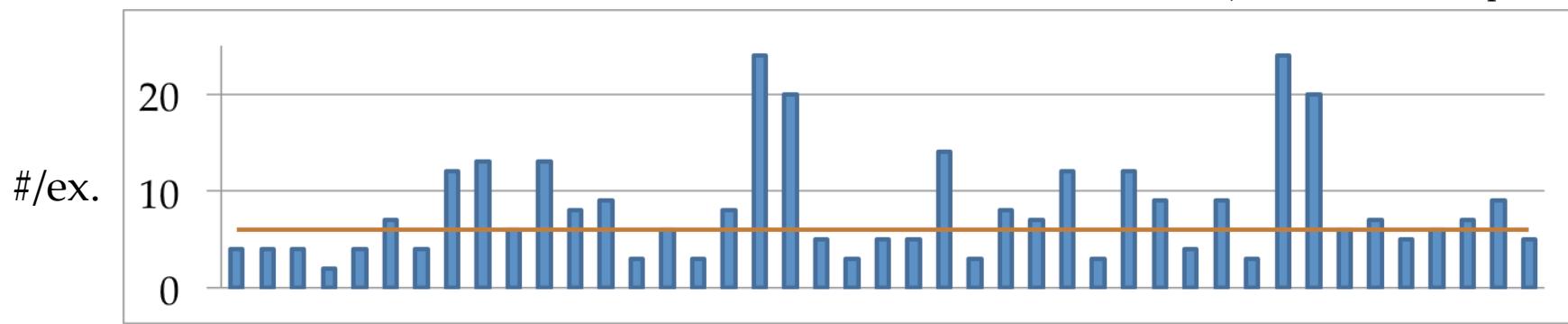
- Evaluation: 43 benchmarks tests.
  - “Intro FP programs”: bools, lists, nats, and trees.
  - *Purpose of evaluation—exploration:*
    - What is the performance?
    - How many examples are necessary to generate good results?
  - **Median runtime: 0.07s.**
  - **Average #/examples: 6.**
  - **Average program size: 13.**

(Median: 0.023s)



- Synthesis in larger contexts is challenging!
  - Outs: equivalences, richer types, *e.g.*, polymorphism.

(Median: 6 examples)



- Reigning in #/examples requires additional info.
  - Ex. taking advantage of the program being synthesized...

## Calculator interpreter.

(22 examples, size 47, 11s)

```
let arith : exp -> nat =
  let rec f1 (e1:exp) : nat =
    match e1 with
    | Const (n1) -> n1
    | Sum (e2, e3) -> sum (f1 e2) (f1 e3)
    | Prod (e2, e3) -> mult (f1 e2) (f1 e3)
    | Pred (e2) -> (match f1 e2 with
        | O -> 0
        | S (n1) -> n1)
    | Max (e2, e3) -> (match compare (f1 e2) (f1 e3) with
        | LT -> f1 e3
        | EQ -> f1 e3
        | GT -> f1 e2)
  in
  f1
;;
```

```

let fvs_large : exp -> list =
  let rec f1 (e1:exp) : list =
    match e1 with
    | Unit -> []
    | Bvar (n1) -> []
    | FVar (n1) -> [n1]
    | Lam (n1, e2) -> f1 e2
    | App (e2, e3) -> append (f1 e2) (f1 e3)
    | Pair (e2, e3) -> append (f1 e2) (f1 e3)
    | Fst (e2) -> f1 e2
    | Snd (e2) -> f1 e2
    | Inl (e2) -> f1 e2
    | Inr (e2) -> f1 e2
    | Match (e2, n1, e3, n2, e4) ->
        (match f1 e2 with
         | Nil -> append (f1 e4) (f1 e3)
         | Cons (n3, l1) ->
             Cons (n3, append (f1 e3) (f1 e4)))
    | Const (n1) -> []
    | Binop (e2, b1, e3) -> append (f1 e3) (f1 e2)
  in
  f1
;;

```

Free variable collector  
for a lambda calculus.

(31 examples, size 75, 3.9s)

# $\lambda_{\text{syn}}$ , a logical foundation for program synthesis.

<b>IGUESS-FIX</b> $\Sigma; \Gamma, x:\tau_1 \triangleright \cdot, f:\tau_1 \rightarrow \tau_2 \triangleright \cdot \vdash \tau_2 \xrightarrow{I} I$ $\Sigma; \Gamma \vdash \tau_1 \rightarrow \tau_2 \xrightarrow{I} \text{fix } f(x:\tau_1) : \tau_2 = I$	<b>IGUESS-MATCH</b> $\Sigma; \Gamma \vdash T \xrightarrow{E} E$ $\text{split}(\Sigma, \Gamma, T) = \overline{(p_m, \Gamma_m)}^m \quad \overline{\Sigma; \Gamma_m \vdash \tau \xrightarrow{I} I_m}^m$ $\Sigma; \Gamma \vdash \tau \xrightarrow{I} \text{match } E \text{ with } \overline{p_m \rightarrow I_m}^m$
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# Soundness

$$\Gamma \vdash \tau \triangleright X \rightsquigarrow e \quad \begin{array}{c} \nearrow \\ \searrow \end{array} \quad \begin{array}{l} \Gamma \vdash e : \tau \\ (\text{Type Soundness}) \end{array}$$
$$e \models X \quad \begin{array}{l} \\ \text{(Example Soundness)} \end{array}$$



# $\lambda_{\text{syn'}}$ , a logical foundation for program synthesis.

IGUESS-FIX	IGUESS-MATCH
$\frac{\Sigma; \Gamma, x:\tau_1 \triangleright \cdot, f:\tau_1 \rightarrow \tau_2 \triangleright \cdot \vdash \tau_2 \xrightarrow{I} I}{\Sigma; \Gamma \vdash \tau_1 \rightarrow \tau_2 \xrightarrow{I} \text{fix } f(x:\tau_1) : \tau_2 = I}$	$\frac{\Sigma; \Gamma \vdash T \xrightarrow{E} E \quad \text{split}(\Sigma, \Gamma, T) = \overline{(p_m, \Gamma_m)}^m \quad \overline{\Sigma; \Gamma_m \vdash \tau \xrightarrow{I} I_m}^m}{\Sigma; \Gamma \vdash \tau \xrightarrow{I} \text{match } E \text{ with } p_m \rightarrow I_m}$
$\boxed{\Sigma; \Gamma \vdash \tau \triangleright X \rightsquigarrow I \quad (\text{IREFINER})}$	
IREFINER-GUESS	IREFINER-FIX
$\frac{\Sigma; \Gamma \vdash T \xrightarrow{E} E \quad \Gamma(E) \Downarrow X}{\Sigma; \Gamma \vdash T \triangleright X \rightsquigarrow E}$	
$\frac{\forall i \in 1..n. X[i] = \overline{v_{im_i}} \Rightarrow ex_{im_i}^{m_i} \quad \Gamma' = f:\tau_1 \rightarrow \tau_2 \triangleright X^{[m_1, \dots, m_n]}, x:\tau_1 \triangleright v^{[m_1, \dots, m_n]}, \Gamma^{[m_1, \dots, m_n]} \quad \Sigma; \Gamma' \vdash \tau_2 \triangleright ex^{[m_1, \dots, m_n]} \rightsquigarrow I}{\Sigma; \Gamma \vdash \tau_1 \rightarrow \tau_2 \triangleright X \rightsquigarrow \text{fix } f(x:\tau_1) : \tau_2 = I}$	

## Completeness

$$\begin{array}{ccc} \Gamma \vdash e : \tau & & \\ e \models X & \longrightarrow & \Gamma \vdash \tau \triangleright X \rightsquigarrow e \end{array}$$



(Due to deciding equality between recursive functions.)

# Example-Directed Synthesis: A Type-Theoretic Interpretation

[POPL 2016: Frankle, Osera, Walker, & Zdancewic]

$$\Gamma \vdash \tau \triangleright X \rightsquigarrow e$$

What are "examples"?

# Examples are Refinement Types

*Singleton types* (constructors):  $[]$ ,  $0$ ,  $\text{cons}$ , ...

Function types:  $t_1 \rightarrow t_2$

*Intersection types*:  $t_1 \wedge t_2$

```
stutter : list -> list  $\wedge$ 
[] -> []  $\wedge$ 
[1] -> [1,1]  $\wedge$ 
[2,1] -> [2,2,1,1]
```

# More Expressive Types

*Union types:*

$$t_1 \vee t_2$$

*(Limited) Negations:*

$$\sim t_1$$

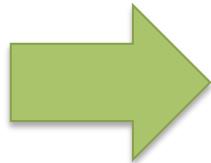
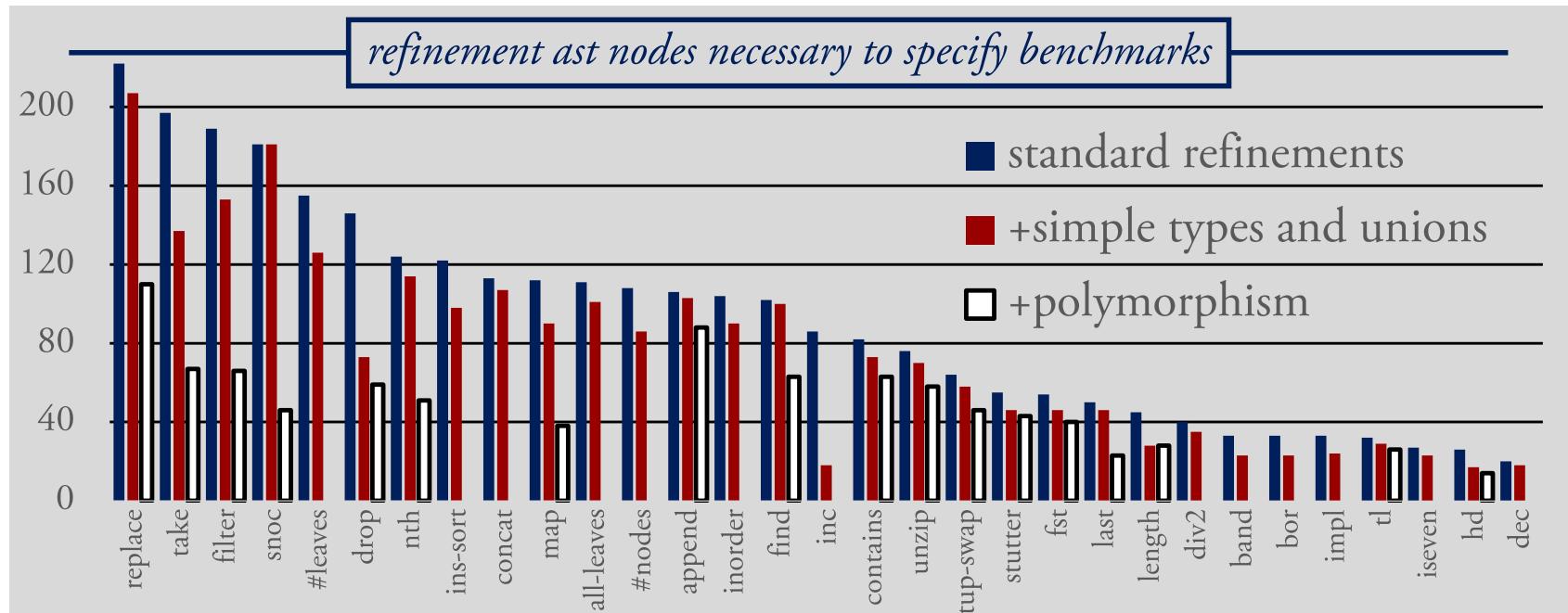
Allows for counter-example guided user interactions.

*Polymorphic Types:*

$$\forall a. \ t$$

Expresses symmetries

# Specification Size



Significantly more succinct examples (~20% shorter) & simpler specifications.

# Tradeoffs in Search

```
decrement : nat -> nat ∧  
          0 -> 0      ∧  
          1 -> 0      ∧  
          2 -> 1
```

(in the context)

decrement(■) : goal

0 -> 0	1 -> 0	2 -> 1	goal
			0
			0
			1

# Argument "Sudoku"

```
decrement : nat -> nat ∧  
          0 -> 0      ∧  
          1 -> 0      ∧  
          2 -> 1
```

(in the context)

decrement(■) : goal

0 -> 0	1 -> 0	2 -> 1	goal
			0
			0
			1

# Argument "Sudoku"

```
decrement : nat -> nat ∧  
          0 -> 0      ∧  
          1 -> 0      ∧  
          2 -> 1
```

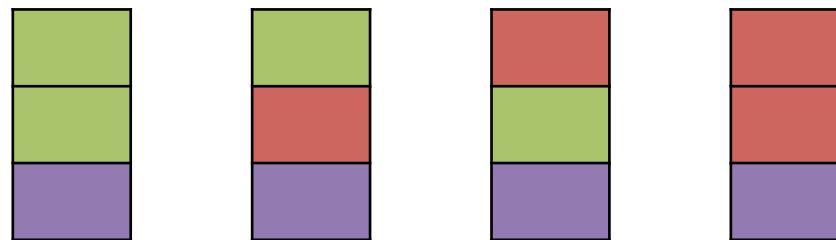
(in the context)

decrement(■) : goal

0 -> 0	1 -> 0	2 -> 1	goal
■			0
	■		0
		■	1

# Argument "Sudoku"

0 -> 0	1 -> 0	2 -> 1	goal
green	red		0
green	red		0
black		purple	1

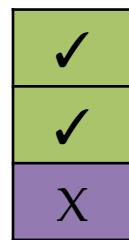


"pick boxes then find candidates"

⇒ 12 search problems (all of which fail for constant terms)

# Argument "Sudoku"

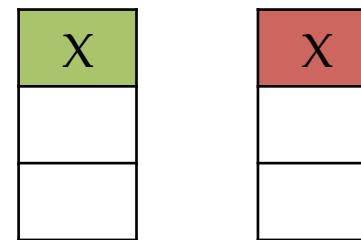
0 -> 0	1 -> 0	2 -> 1	goal
green	red		0
green	red		0
black		purple	1



Pick arg = 0



Pick arg = 1



Pick arg = 2

In practice, we found raw enumeration to be better for performance than "smarter" search approaches.

Moral: The "smoothness" of the search space can be important

# Limitations / Challenges

- Enumerative search
  - fundamentally combinatorial
- Trace completeness
  - use the definition of the partially defined function?
- I/O examples only
- Not full verification
  - other validation needed for correctness
- Normal forms
  - cannot synthesize “helper” functions
  - minimal program size can be exponentially bigger

# Benefits

- Type structure largely determines program structure  
    ⇒ very good for “wide” & “shallow” search
- Suggests principled ways to extend to richer language features

# A Surprising Example

```
1. bash
kambing-mobile:synml posera$ time ./synml.native job-talk/stutter.ml -nosugar
let stutter : mylist -> mylist =
  let rec f1 (m1:mylist) : mylist =
    match m1 with
    | Nil -> Nil
    | Cons (i1, m2) -> Cons (i1, Cons (i1, f1 m2))
  in
    f1
;;
```

(**MYTH DEMO**)

# Research Directions / Questions

- Richer specification languages
  - *Beyond I/O: fewer examples, more general constraints,*
- Other search optimizations
  - *(Higher-order) unification*
- Combination with other techniques
  - *CEGIS, constraint solving with SAT or SMT*
- Combine with domain-specific languages
  - *Application-specific types / combinator*

# Related Work

- Proof Search:
  - *Automated Theorem Proving (lecture notes)* [Pfenning]
- Recent Papers (very partial! list):
  - *Program Synthesis from Polymorphic Refinement Types* [PLDI 2016: Polikarpova, Kuraj, Solar-Lezama]
  - *Example-Directed Synthesis: A Type-Theoretic Interpretation* [POPL 2016: Frankle, Osera, Walker, & Zdancewic]
  - *Type-and-Example-Driven Program Synthesis* [PLDI 2015: Osera, Zdancewic]
  - *Synthesizing Data Structure Transformations from Input-Output Examples* [PLDI 2015: Feser, Chaudhuri, Dillig]
  - *Test-driven Synthesis* [Perelmen, et al. 2014]
  - *Recursive Program Synthesis* [Albarghouthi, Gulwani, Kincaid 2013]
  - *Complete Completion Using Types and Weights* [Gvero, et al. 2013]

# Type and Example Directed Program Synthesis

1. Synthesize programs with *higher-order functions, recursion, and algebraic datatypes.*
2. Type structure prunes the search space.
3. Take advantage of techniques from proof theory literature



**ExCAPE**  
Expeditions in Computer Augmented  
Program Engineering

```

let list_pairwise_swap : list -> list =
  let rec f1 (l1:list) : list =
    match l1 with
    | Nil -> []
    | Cons (n1, l2) ->
      (match f1 l2 with
       | Nil ->
         (match l2 with
          | Nil -> []
          | Cons (n2, l3) ->
            Cons (n2, Cons (n1, f1 l3)))
       | Cons (n2, l3) -> [])
in
f1
;;

```

??

$f_1 l2 \equiv$   
“Does  $l2$  have  
even length?”

Ex.  $[0, 1, 0, 1] \Rightarrow [1, 0, 1, 0]$   
 $[0, 1, 0] \Rightarrow []$