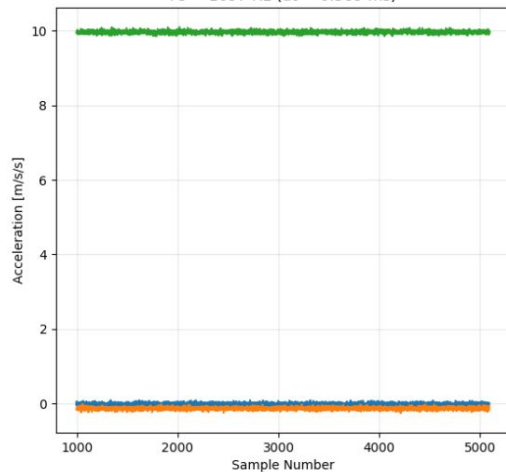
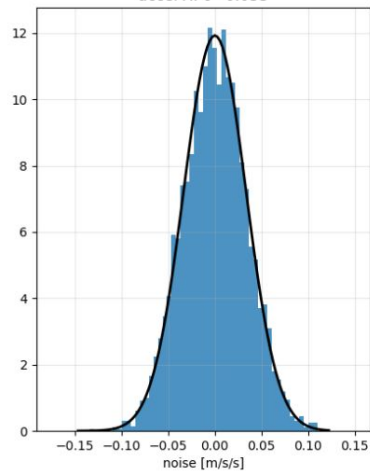


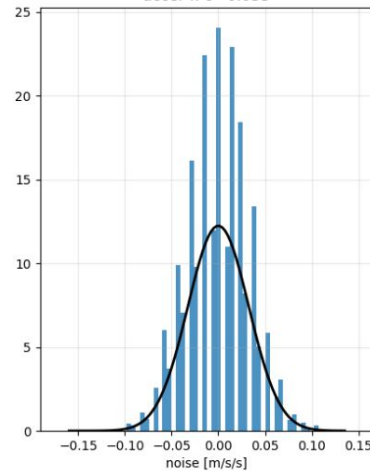
Fs = 1697 Hz (dt = 0.589 ms)



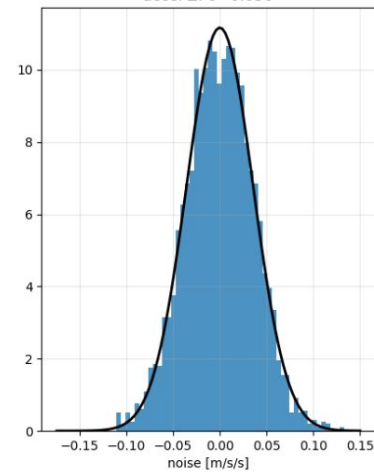
accel X: $\sigma=0.033$



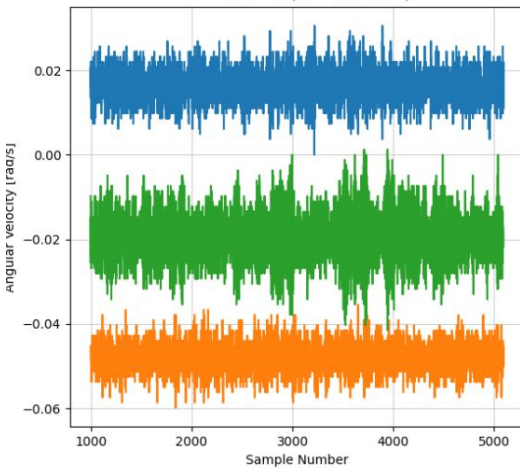
accel Y: $\sigma=0.033$



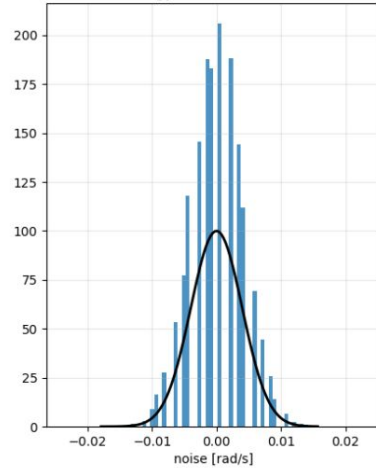
accel Z: $\sigma=0.036$



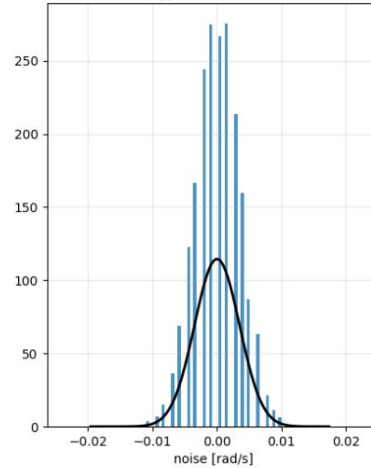
Fs = 1697 Hz (dt = 0.589 ms)



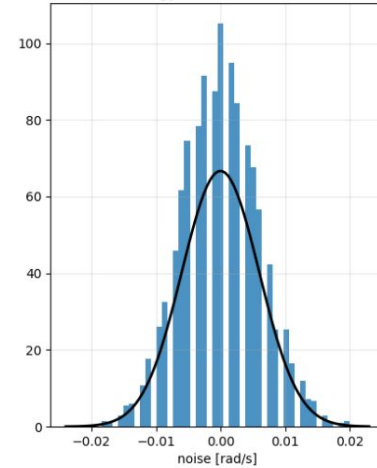
gyr X: $\sigma=0.004$



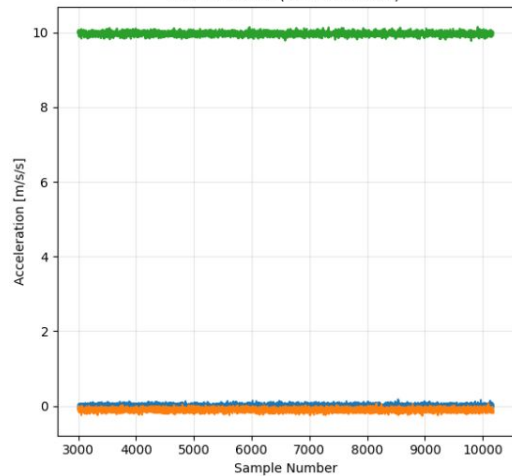
gyr Y: $\sigma=0.003$



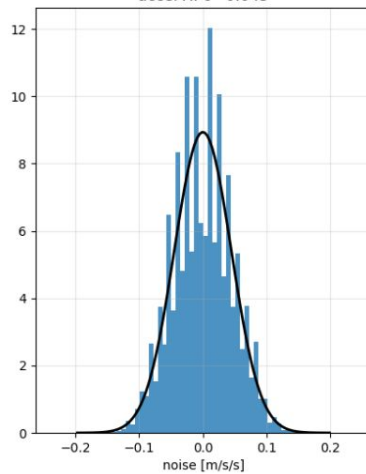
gyr Z: $\sigma=0.006$



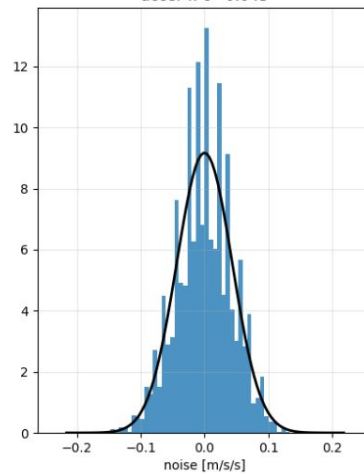
Fs = 3395 Hz (dt = 0.295 ms)



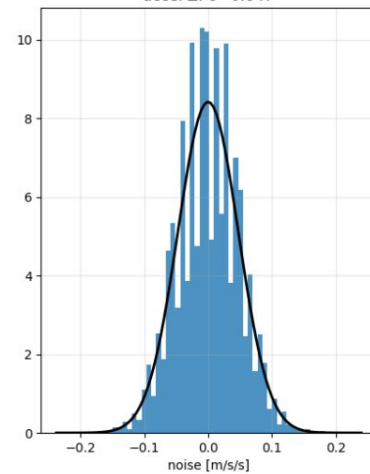
accel X: $\sigma=0.045$



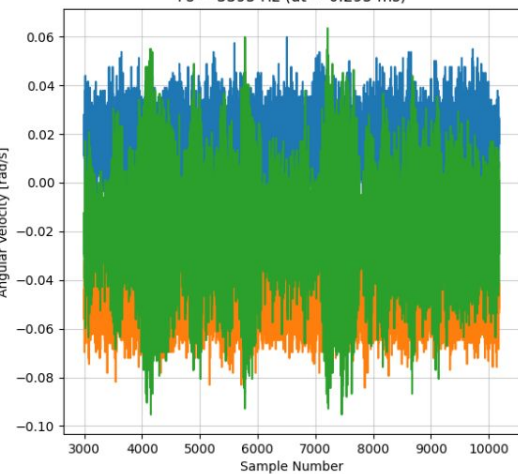
accel Y: $\sigma=0.043$



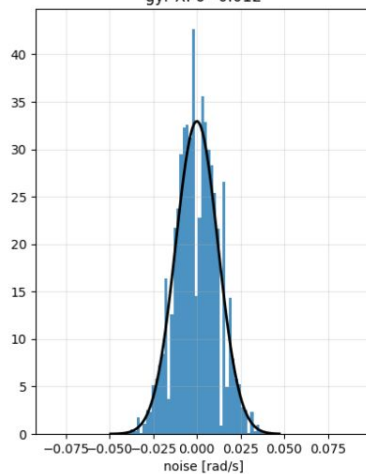
accel Z: $\sigma=0.047$



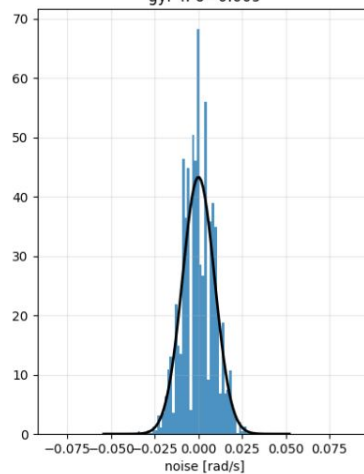
Fs = 3395 Hz (dt = 0.295 ms)



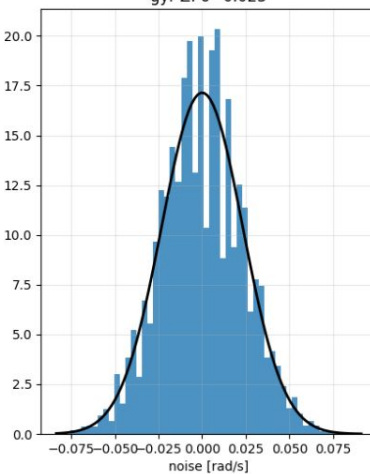
gyr X: $\sigma=0.012$



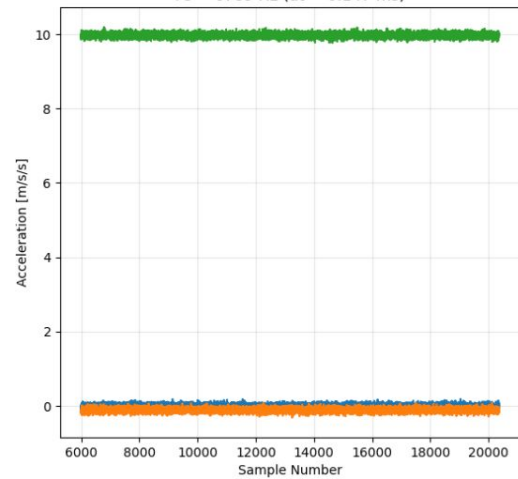
gyr Y: $\sigma=0.009$



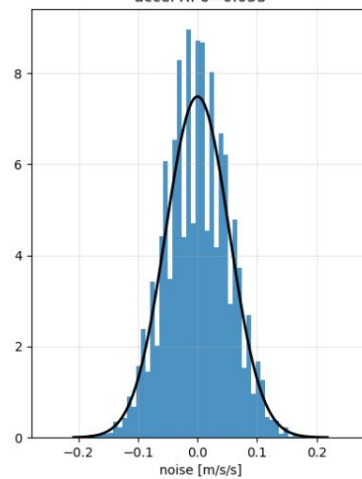
gyr Z: $\sigma=0.023$



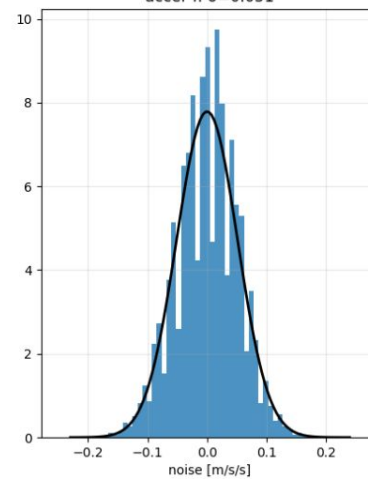
Fs = 6789 Hz (dt = 0.147 ms)



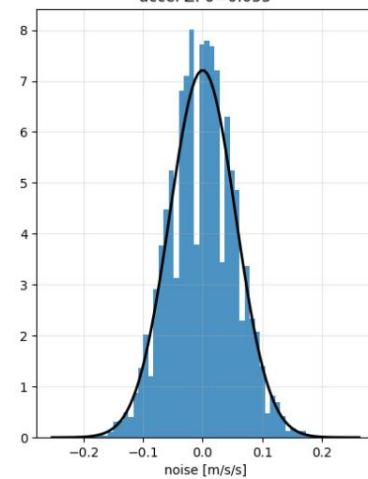
accel X: $\sigma=0.053$



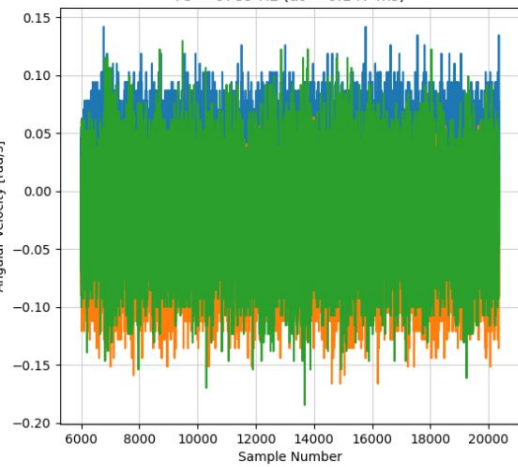
accel Y: $\sigma=0.051$



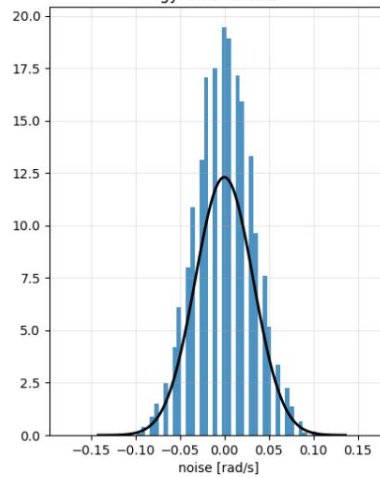
accel Z: $\sigma=0.055$



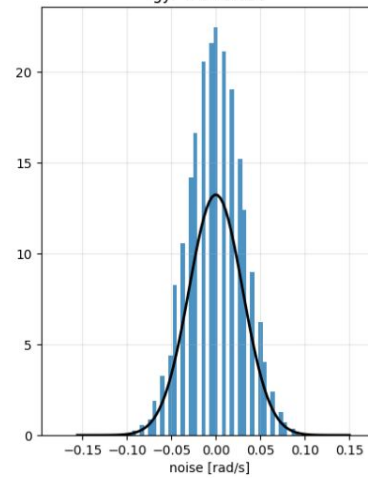
Fs = 6789 Hz (dt = 0.147 ms)



gyr X: $\sigma=0.032$



gyr Y: $\sigma=0.030$



gyr Z: $\sigma=0.040$

