

25-10-2021

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Indirect Methods.

1. Transformation Techniques.

If the constraints $g_j(\underline{x})$ have simple forms as an explicit fn. of x_i

1. If lower & upper bounds on x_i are given by

$$l_i \leq x_i \leq u_i \leftarrow$$

$$\rightarrow x_i = l_i + (u_i - l_i) \sin^2 y_i \checkmark$$

$y_i \rightarrow$ new design variable which can take any real value.

- Penalty Methods:

These penalty methods transform the constrained optimization problem into a sequential unconstrained optimization problem.

Find \underline{x} which minimizes $f(\underline{x})$
Subject to $g_j(\underline{x}) \leq 0, j = 1, 2, \dots, m$

$$\phi_k = \phi(\underline{x}, \eta_k) = f(\underline{x}) + \eta_k \sum_{j=1}^m G_j[g_j(\underline{x})]$$

G_j is some function of $g_j(\underline{x})$ & η_k is a positive constant referred to as penalty parameter.

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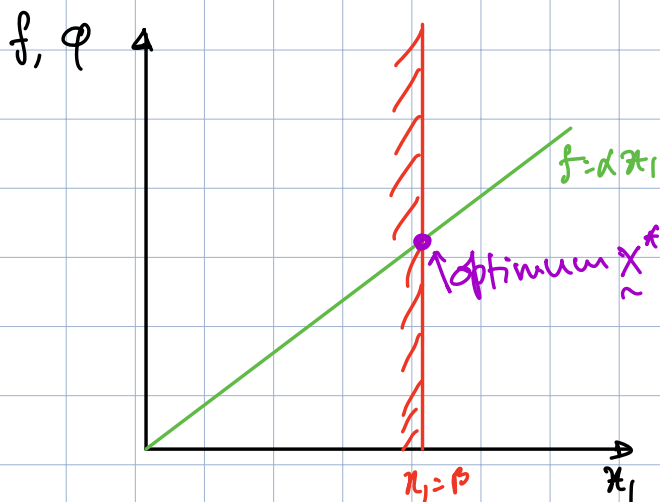
- Interior penalty Methods
- Exterior penalty Methods.

$$\left. \begin{aligned} G_j &= -\frac{1}{g_j(\underline{x})} \\ &= \log[-g_j(\underline{x})] \end{aligned} \right\} \text{Interior.}$$

$$\left. \begin{aligned} G_j &= \max[0, g_j(\underline{x})] \\ r &= \left(\max[0, g_j(\underline{x})]\right)^2 \end{aligned} \right\} \text{Exterior penalty}$$

Find $\underline{x} = x_1$ which minimizes $f(\underline{x}) = \alpha x_1$
 Subject to $g_1(\underline{x}) = \beta - x_1 \leq 0$

$$G_j^{\text{interior}} = -\frac{1}{\beta - x_1} \quad G_j^{\text{ext}} = \left\{ \max(0, \beta - x_1) \right\}^2$$



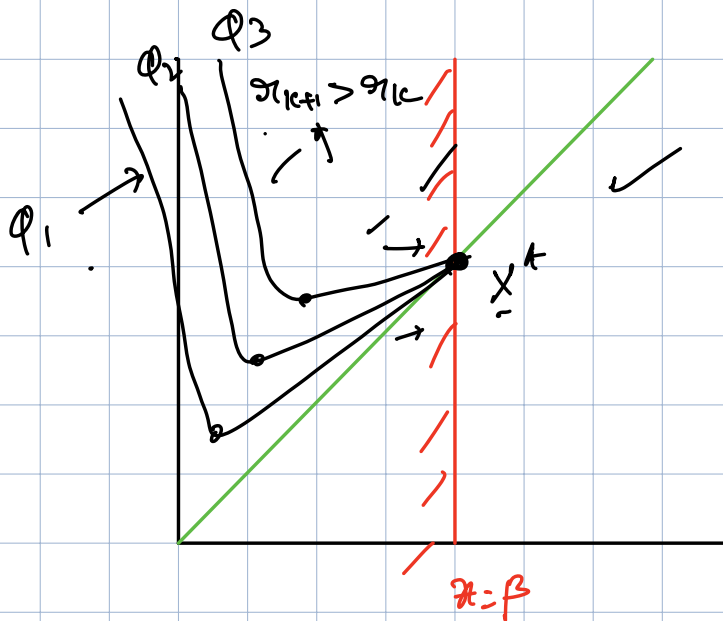
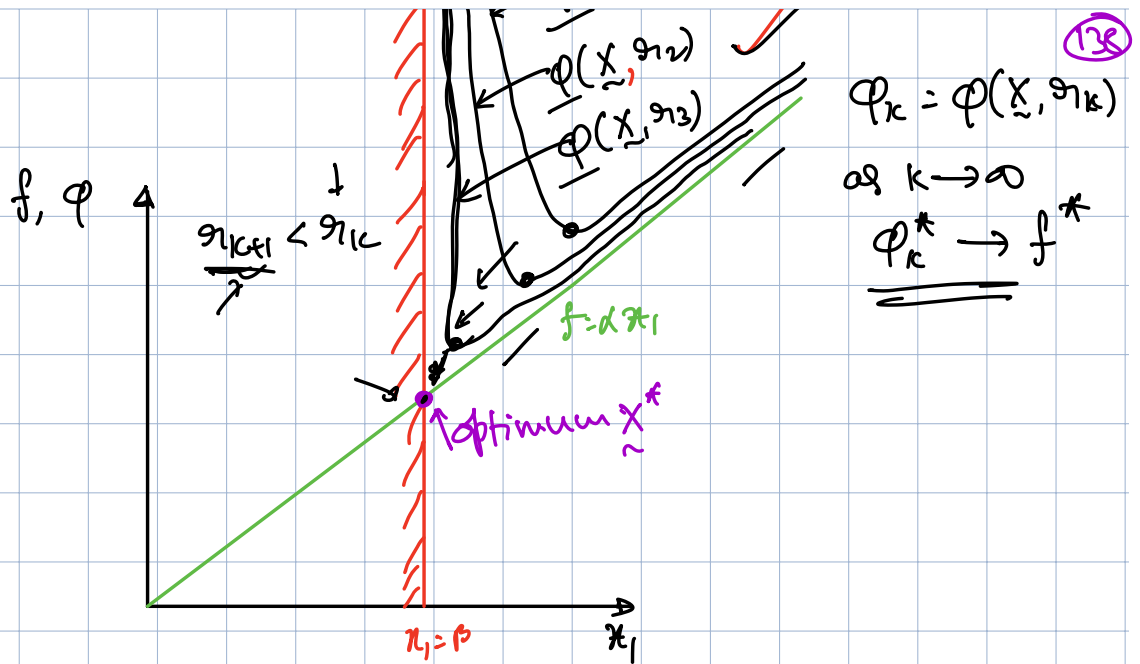
$$\phi_1 = \phi(\underline{x}, \eta_1)$$

$$\phi_2 = \phi(\underline{x}, \eta_2)$$

$$\phi_3 = \phi(\underline{x}, \eta_3)$$

$$\phi_k = \alpha x_1 - \frac{\eta_k}{\beta - x_1}$$

$$\phi(\underline{x}, \eta_1) = \dots$$



- Automobile companies to adopt to BS7 by 2025

Interior penalty function Method.

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$$\phi(\underline{x}, r_k) = f(\underline{x}) - r_k \sum_{j=1}^m \frac{1}{g_j(\underline{x})}$$

If \underline{x} is in the ^{interior of the} feasible, $g_j(\underline{x}) < 0$

$$\therefore \phi(\underline{x}, r_k) > f(\underline{x})$$

If any constraint is critically satisfied.

$$g_j(\underline{x}) = 0 \Rightarrow \phi \rightarrow \infty$$

Algorithm:

1. Start with an initial feasible point \underline{x}_1 that satisfies all the constraints.
choose $r_1 > 0$ \hookrightarrow set $k=1$
2. Minimize $\phi(\underline{x}, r_k)$ by using any UCM methods. $\rightarrow \underline{x}_k^*$
3. Test if \underline{x}_k^* is the optimum solution for the original problem, i.e. Min $f(\underline{x})$
If yes, \rightarrow terminate
If no, \rightarrow go to step 4
4. Find the value of the next penalty parameter
 r_{k+1} as $r_{k+1} = \underbrace{c}_{c < 1} r_k$
5. Set $k = k+1$, $\underline{x}_1 = \underline{x}_k^*$ \hookrightarrow go to step 2.

Issues:

1. The starting feasible point \tilde{x}_1 may not be readily available ✓
2. A suitable value for the initial penalty parameter η_1 has to be found.
3. A proper value for c has to be found.
4. Suitable convergence criterion has to be decided.
5. It's important to normalize the constraints wherever possible.

2. Choosing η_1

$$\eta_1 \approx 0.1 \text{ to } 1.0 \frac{f(\tilde{x}_1)}{-\sum_{j=1}^m \frac{1}{g_j(\tilde{x}_1)}}$$

$$3. \quad \eta_{k+1} = \underline{c} \eta_k \quad \underline{c} < 1$$

$$c = 0.1, 0.2, \text{ or } 0.5$$

4.

$$g_j(\tilde{x}) \leq 0$$

$$g_j(\tilde{x}) < 0$$

interior of
the feasible
region

4. Convergence

$$\left| \frac{f(\underline{x}_k^*) - f(\underline{x}_{k-1}^*)}{f(\underline{x}_k^*)} \right| \leq \varepsilon_1$$

$$|\underline{x}_k^* - \underline{x}_{k-1}^*| \leq \varepsilon_2$$

$$\max (\underline{x}_k^* - \underline{x}_{k-1}^*) \leq \varepsilon_3$$

5. Normalization:

$$g_1(\underline{x}) = f(\underline{x}) \leq \delta_{\max} \quad \leftarrow 10^{-4}$$

$$g_2(\underline{x}) : \underbrace{\sigma(\underline{x})}_{\text{variance}} \leq \sigma_{\max} \rightarrow 10^6$$

$$g_1(\underline{x}) : f(\underline{x}) - \delta_{\max} \leq 0 \quad \checkmark$$

$$g_2(\underline{x}) : \sigma(\underline{x}) - \sigma_{\max} \leq 0$$

$$\frac{g_1}{\delta_{\max}} : \frac{f(\underline{x})}{\delta_{\max}} - 1 \leq 0 \quad \checkmark$$

$$\frac{g_2}{\sigma_{\max}} : \frac{\sigma(\underline{x})}{\sigma_{\max}} - 1 \leq 0$$