

93

$$n = 2$$

$$S_i^p = x_i - x_{i-n}$$

$$1-3, 2-5 \quad - \quad - \dots$$

## conjugate directions Method (Powell's Method)

$$S_i^T A S_j = 0 \quad \text{for all } i \neq j$$

$i = 1, 2, \dots, n, \quad j = 1, \dots, n$

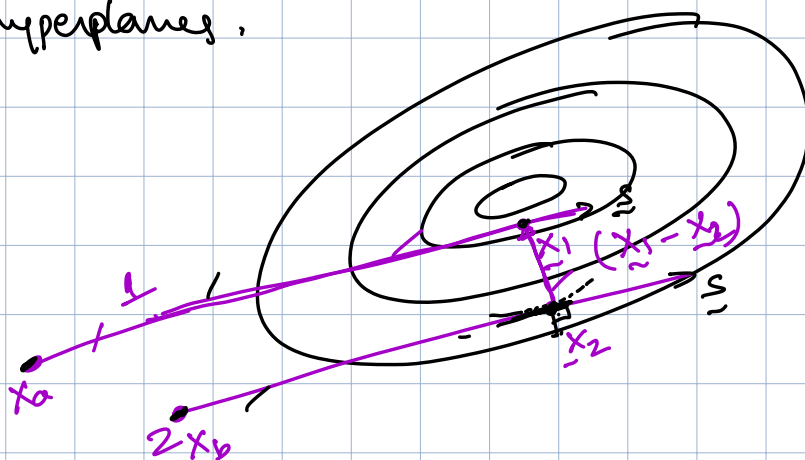
### Quadratically convergent Method:

If a minimization method using exact arithmetic, can find the minimum in  $n$  steps while minimizing a quadratic fn. in  $n$  variables, then the method is called quadratically convergent.

914

$$f(\underline{x}) = B\underline{x} + \frac{1}{2} \underline{x}^T A \underline{x} + C$$

Theorem: Given a quadratic function in  $n$  variables and two parallel hyperplanes 1 & 2 of dimension  $k < n$ . Let the constrained stationary points of the quadratic function in the hyperplanes 1 & 2 be  $\underline{x}_1$  &  $\underline{x}_2$ , respectively. Then, the line joining  $\underline{x}_1$  &  $\underline{x}_2$  is conjugate to any line parallel to the hyperplanes.



$$Q(\underline{x}) = \frac{1}{2} \underline{x}^T A \underline{x} + B\underline{x} + C$$

$$\nabla Q(\underline{x}) = A \underline{x} + B$$

$$\nabla Q(\underline{x}_1) = A \underline{x}_1 + B$$

$$\nabla Q(\underline{x}_2) = A \underline{x}_2 + B$$

$$\nabla Q(\underline{x}_1) - \nabla Q(\underline{x}_2) = A (\underline{x}_1 - \underline{x}_2)$$

$\underline{s}$  is a vector  $\parallel$  to the hyperplanes.

The  $\underline{\underline{S}}$  will be orthogonal to  $\nabla Q(\underline{\underline{x}}_1)$  &  $\nabla Q(\underline{\underline{x}}_2)$  (93)

$$\underline{\underline{S}}^T \nabla Q(\underline{\underline{x}}_1) = \underline{\underline{S}}^T A \underline{\underline{x}}_1 \neq \underline{\underline{S}}^T B = 0$$

$$\underline{\underline{S}}^T \nabla Q(\underline{\underline{x}}_2) = \underline{\underline{S}}^T A \underline{\underline{x}}_2 + \underline{\underline{S}}^T B = 0$$

$$\Rightarrow \underline{\underline{S}}^T A (\underline{\underline{x}}_1 - \underline{\underline{x}}_2) = 0$$

Hence  $\underline{\underline{S}}$  &  $(\underline{\underline{x}}_1 - \underline{\underline{x}}_2)$  are A conjugate.

Theorem 2 If  $Q(\underline{\underline{x}}) = \frac{1}{2} \underline{\underline{x}}^T A \underline{\underline{x}} + B \underline{\underline{x}} + C$  is minimized sequentially, once along each direction of a set of  $n$  mutually conjugate directions, the minimum of the function  $Q$  will be found at or before  $n$ th step irrespective of the starting point.

Proof: Let's say  $\underline{\underline{x}}^*$  is the minima of  $Q(\underline{\underline{x}})$

$$\nabla Q(\underline{\underline{x}}^*) = B + A \underline{\underline{x}}^* = 0$$

We will start with an initial point  $\underline{\underline{x}}_1$  & a set of linearly independent direction  $\underline{\underline{S}}_1, \dots, \underline{\underline{S}}_n$  & constants  $\beta_i$

$$\underline{\underline{x}}^* = \underline{\underline{x}}_1 + \sum_{i=1}^n \beta_i \underline{\underline{S}}_i$$

by using  $\underline{\underline{S}}_i$  as basis vectors.

If  $\underline{S}_i$  are A-conjugate & none of them null vectors. (96)

$$\nabla Q(\underline{x}^*) = B + A \underline{x}^* = 0$$

$$B + A \left( \underline{x}_1 + \sum_{i=1}^n \beta_i \underline{S}_i \right) = 0$$

$$\Rightarrow (B + A \underline{x}_1) + A \sum_{i=1}^n \beta_i \underline{S}_i = 0$$

$$\underline{S}_j^T (B + A \underline{x}_1) + \underline{S}_j^T A \left[ \sum_{i=1}^n \beta_i \underline{S}_i \right] = 0$$

$$\Rightarrow \underline{S}_j^T (B + A \underline{x}_1) + \beta_j \underline{S}_j^T A \underline{S}_j = 0$$

$$\Rightarrow \beta_j = - \frac{(B + A \underline{x}_1)^T \underline{S}_j}{\underline{S}_j^T A \underline{S}_j}$$

$$\beta_i = - \frac{(B + A \underline{x}_1)^T \underline{S}_i}{\underline{S}_i^T A \underline{S}_i}$$

Let's say we start  $\underline{x}_1$  & successively minimize

$$\underline{x}_{i+1} = \underline{x}_i + \lambda_i^* \underline{S}_i \quad i = 1, \text{ to } n$$

$\lambda_i^*$  is to be found by minimizing  $Q$  along  $\underline{S}_i$

$$Q(\underline{x}_i + \lambda \underline{S}_i)$$

$$\Rightarrow \underline{S}_i^T \nabla Q(\underline{x}_{i+1}) = 0$$

$$\underline{S}_i^T [B + A \underline{x}_{i+1}] = 0$$

$$\therefore \underline{\underline{S}}_i^T [B + A(\underline{\underline{x}}_i + \lambda_i^* \underline{\underline{S}}_i)] = 0$$

(97)

$$\Rightarrow \underline{\underline{S}}_i^T (B + A \underline{\underline{x}}_i) + \lambda_i^* \underline{\underline{S}}_i^T A \underline{\underline{S}}_i = 0$$

$$a^T b = b^T a$$

$$\therefore \lambda_i^* = - \frac{(\underline{\underline{B}} + A \underline{\underline{x}}_i)^T \underline{\underline{S}}_i}{\underline{\underline{S}}_i^T A \underline{\underline{S}}_i}$$

$$\underline{\underline{x}}_i = \underline{\underline{x}}_1 + \sum_{j=1}^{i-1} \lambda_j^* \underline{\underline{S}}_j$$

$$\underline{\underline{x}}_i^T A \underline{\underline{S}}_i = \underline{\underline{x}}_1^T A \underline{\underline{S}}_i + \sum_{j=1}^{i-1} \lambda_j^* \underline{\underline{S}}_j^T A \underline{\underline{S}}_i$$

$\underbrace{\hspace{10em}}_0$

$$\begin{aligned} \underline{\underline{x}}_2 &= \underline{\underline{x}}_1 + \lambda_1^* \underline{\underline{S}}_1 \\ \underline{\underline{x}}_3 &= \underline{\underline{x}}_2 + \lambda_2^* \underline{\underline{S}}_2 \\ &= \underline{\underline{x}}_1 + \lambda_1^* \underline{\underline{S}}_1 + \lambda_2^* \underline{\underline{S}}_2 \\ &= \underline{\underline{x}}_1 + \sum_{j=1}^{i-1} \lambda_j^* \underline{\underline{S}}_j \end{aligned}$$

$$\therefore \underline{\underline{x}}_i^T A \underline{\underline{S}}_i = \underline{\underline{x}}_1^T A \underline{\underline{S}}_i + \underbrace{B^T \underline{\underline{S}}_i + \underline{\underline{x}}_i^T A \underline{\underline{S}}_i}_{\lambda_i^* \underline{\underline{S}}_i^T A \underline{\underline{S}}_i}$$

$$\therefore \lambda_i^* = - \frac{B^T \underline{\underline{S}}_i + \underline{\underline{x}}_1^T A \underline{\underline{S}}_i}{\underline{\underline{S}}_i^T A \underline{\underline{S}}_i}$$

$$\therefore \lambda_i^* = - \frac{(\underline{\underline{B}} + A \underline{\underline{x}}_1)^T \underline{\underline{S}}_i}{\underline{\underline{S}}_i^T A \underline{\underline{S}}_i}$$