

28 - Oct - 2021

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How to identify a starting feasible point  $\underline{x}_1$  for the IPM?

1. Choose an arbitrary point  $\underline{x}_1$  ✓

Evaluate  $g_j(\underline{x}_1)$

We have a total of 'm' constraints:  $g_j(\underline{x}) \leq 0$   
 $j = 1, 2, \dots, m.$

Let's say 'r' out of 'm' constraints are violated.

$$\begin{aligned} g_j(\underline{x}_1) &\leq 0 & j = 1, 2, \dots, m-r \\ g_j(\underline{x}_1) &> 0 & j = m-r+1, m-r+2, \dots, m \end{aligned}$$

2. Identify the most violated constraint at  $\underline{x}_1$ .

$$g_k(\underline{x}_1) = \max [g_j(\underline{x}_1)] \quad j = m-r+1, \dots, m$$

r constraints

3. Find  $\underline{x}$  which minimizes  $\underline{g}_k(\underline{x})$  ✓  
Subject to

$$\begin{cases} g_j(\underline{x}) \leq 0, & j = 1, 2, \dots, m-r \\ g_j(\underline{x}) - \underline{g}_k(\underline{x}_1) \leq 0, & j = m-r+1, \dots, k-1, k+1, \dots, m \end{cases}$$

4. To solve the above optimization problem, use IPM with  $\underline{x}_1$  as initial guess. Let's say the optimal solution for (3) is  $\underline{x}_M$

5. If all the constraints are not satisfied at  $\underline{x}_M$ , then set a new guess vector  $\underline{x}_1 = \underline{x}_M$

and go to step 2

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Example: Minimize  $f(x_1, x_2) = \frac{1}{3}(x_1+1)^3 + x_2$  -  
s.t.

$$g_1(x_1, x_2) = -x_1 + 1 \leq 0$$

$$g_2(x_1, x_2) = -x_2 \leq 0 \quad /$$

$$\phi(x, \eta) = f(x) + \eta \sum_{j=1}^m G_j[g_j(x)]$$

$$G_j(g_j(x)) = -\frac{1}{g_j(x)}$$

$$\phi(x, \eta) = \frac{1}{3}(x_1+1)^3 + x_2 - \eta \left( \frac{1}{-x_1+1} - \frac{1}{x_2} \right) -$$

In principle, we can use any one of the UCM methods that were discussed.

$$\frac{\partial \phi}{\partial x_1} = 0 \Rightarrow (x_1+1)^2 - \frac{\eta}{(1-x_1)^2} = 0 \quad /$$

$$\frac{\partial \phi}{\partial x_2} = 0 \Rightarrow 1 - \frac{\eta}{x_2^2} = 0$$

$$\Rightarrow x_2^2 = \eta \quad \text{or} \quad x_2^* = \sqrt{\eta} \quad /$$

$$x_1^*(\eta) = \sqrt{1+\sqrt{\eta}} \quad /$$

$$\phi_{\min} = \phi \rightarrow f^* \quad \text{as} \quad \eta \rightarrow 0$$

$$x_1^* = \lim_{\eta \rightarrow 0} x_1^*(\eta) = \lim_{\eta \rightarrow 0} \sqrt{1+\sqrt{\eta}} = 1$$

$$x_2^* = \lim_{\eta \rightarrow 0} x_2^*(\eta) = \lim_{\eta \rightarrow 0} \sqrt{1+\sqrt{\eta}} = 1$$

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$$f_{\text{min}} = \frac{1}{3}(x_i + 1)^3 + x_i^2$$

$$= \frac{1}{5} (1+1)^3 + 0 = \frac{8}{5}$$

$C = 0.1$

$k$	$\eta$	$x_1^*(\lambda) = \sqrt{(1+\sqrt{\eta})}$	$x_2^*(\lambda) = \sqrt{\eta}$	$q_{\min}(\eta)$	$f(\eta)$
1	1000	5.71164	31.623	376.263 $\rightarrow$	132.40
2	100	3.31662	10	89.9772	36.8109
3	10				
	$\vdots$				
	$\vdots$				
	$\vdots$				
	0.000001	1.00050	0.00100	2.6727	2.6697
	0	1	0	8/3	8/3

## Exterior penalty function Method.

$$\phi(\underline{x}, \gamma_k) = f(\underline{x}) + \gamma_k \sum_{j=1}^M \langle g_j(\underline{x}) \rangle$$

$$\eta_K > 0$$

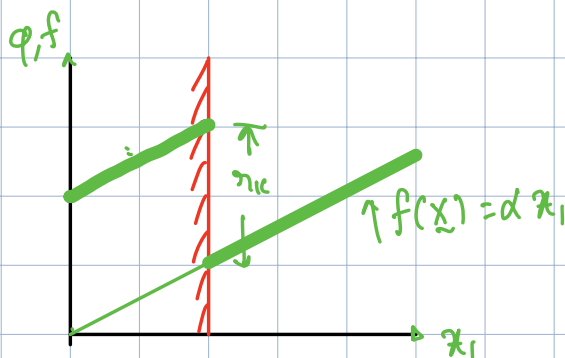
$q \leftarrow$  no-negative constant.

$$\begin{aligned} \langle g_j(\underline{x}) \rangle &= \max \langle g_j(\underline{x}), 0 \rangle \\ &= \begin{cases} g_j(\underline{x}) & \text{if } g_j(\underline{x}) > 0 \text{ (conf. violated)} \\ 0 & \text{if } g_j(\underline{x}) \leq 0 \text{ (conf. satisfied)} \end{cases} \end{aligned}$$

$\underline{x}_k^*$  converges to the optima as  $k \rightarrow \infty$  &  $\eta_k \rightarrow 0$  (145)

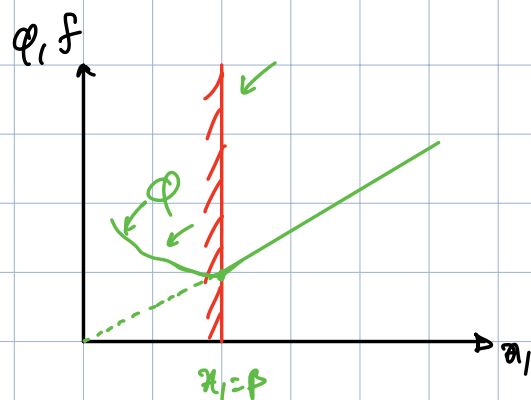
1.  $\eta = 0$  X

$$\begin{aligned}\phi(\underline{x}_k, \eta_k) &= f(\underline{x}) + \eta_k \sum_{j=1}^m \underbrace{\langle g_j(\underline{x}) \rangle^0}_{\substack{\leftarrow \text{if } g_j(\underline{x}) > 0 \\ \text{if } g_j(\underline{x}) \leq 0}} \\ &= f(\underline{x}) + m\eta_k \left\{ \begin{array}{l} \leftarrow \text{if } g_j(\underline{x}) > 0 \\ \text{if } g_j(\underline{x}) \leq 0 \end{array} \right. \\ &= f(\underline{x}) \quad \checkmark \end{aligned}$$



At the boundary the  
fn.  $\phi$  is discontinuous.

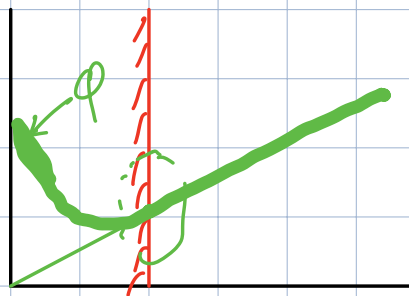
2.  $0 < \eta < 1 \rightarrow$  penalty for violating the constraint  
will be too small although  $\phi$  will be continuous.



3.  $q=1 \leftarrow$  discontinuous first derivatives across the boundary.

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4.  $q > 1 \leftarrow$  The  $\phi$  will have continuous first derivatives



$$\frac{\partial \phi}{\partial x_i} = \frac{\partial f}{\partial x_i} + \lambda_k \sum_{j=1}^m q \langle g_j(x) \rangle^{q-1} \cdot \frac{\partial g_j}{\partial x_i}$$

$$\underline{\underline{q=2}}$$

Example: Minimize  $f(x_1, x_2) = \frac{1}{3} (x_1+1)^3 + x_2$   
 s.t.  $g_1(x_1, x_2) = 1 - x_1 \leq 0$   
 $g_2(x_1, x_2) = -x_2 \leq 0$

$$\phi(x_1, x_2) = \frac{1}{3} (x_1+1)^3 + x_2 + \lambda_1 [\max(0, 1-x_1)]^2 + [\max(0, -x_2)]^2$$

$$\frac{\partial \phi}{\partial x_1} = (x_1+1)^2 - 2\lambda_1 [\max(0, 1-x_1)] = 0$$

$$\frac{\partial \phi}{\partial x_2} = 1 - 2\lambda_2 [\max(0, -x_2)] = 0$$

$$\min \left[ (x_1+1)^2, \underline{(x_1+1)^2 - 2\eta(1-x_1)} \right] = 0 \quad - (1) \quad (147)$$

$$\rightarrow \min [1, 1 + 2\eta x_2] = 0 \quad - (2)$$

if  $(x_1+1)^2 = 0 \quad \times \Rightarrow x_1 = -1$  violate g,

$$(x_1+1)^2 - 2\eta(1-x_1) = 0 \Rightarrow x_1^* = -1 - \eta + \sqrt{\eta^2 + 4\eta}$$

$$1 + 2\eta x_2 = 0 \Rightarrow x_2^* = -\frac{1}{2\eta}$$

As  $\eta \rightarrow \infty \quad x_2^* = 0$

As  $\eta \rightarrow \infty \quad x_1^* = 1$

$$\therefore f_{\min} = \lim_{\eta \rightarrow 0} \phi_{\min}(\eta) = 8/3$$

c>1    c=10  
 $\eta$

0.001

0.01

0.1

1

.

100,000

$x_1$

$x_2$

$\phi_{\min}$

$f_{\min}$

/

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