

$$\frac{d^2 m}{dt^2} + \frac{k}{m} m = 0 \quad \text{(Equation of motion in sum)}$$

① Trigonometric solution

$$\omega = \sqrt{k/m}$$

$$m_1 = a \sin \omega t \quad \text{--- (3)}$$

$$m_2 = b \cos \omega t \quad \text{--- (4)}$$

$$m = a \sin \omega t + b \cos \omega t \quad \text{--- (5)}$$

② exponential

$$m_1(t) = e^{\alpha t} = e^{i\omega t} \quad \text{--- (6)}$$

$$m_2(t) = e^{-i\omega t} \quad \text{--- (7)}$$

$$m(t) = e_1 e^{i\omega t} + e_2 e^{-i\omega t} \quad \text{--- (8)}$$

linear superposition principle

The resultant of sym dis is simply the algebraic sum of individual displacement.

$$m_1 \quad m_2$$

$$m = m_1 + m_2$$

• Analytical, graphical, method using complex quantities.

$$\frac{d^2 m}{dt^2} = -\omega^2 m + \alpha m^2 + \beta m^3 \quad \text{--- (1)}$$

m_1, m_2 nonlinear diff equa

$$A = B$$

$$-A = -B$$

$$\frac{d^2 m_1}{dt^2} = -\omega^2 m_1 + \alpha m_1^2 + \beta m_1^3 \quad \text{--- (2)}$$

$$\frac{d^2 m_2}{dt^2} = -\omega^2 m_2 + \alpha m_2^2 + \beta m_2^3 \quad \text{--- (3)}$$

$$x = m_1 + m_2$$

$$\frac{d^2}{dt^2} (m_1 + m_2) = -\omega^2 (m_1 + m_2) + \alpha (m_1 + m_2)^2 + \beta (m_1 + m_2)^3 + \dots \quad (4)$$

$$(2) + (3) \Rightarrow \frac{d^2 m_1}{dt^2} + \frac{d^2 m_2}{dt^2} = -\omega^2 m_1 - \omega^2 m_2 + \alpha m_1^2 + \alpha m_2^2 + \beta m_1^3 + \beta m_2^3 + \dots$$

$$= -\omega^2 m_1 - \omega^2 m_2 + \alpha (m_1^2 + m_2^2) + \beta (m_1^3 + m_2^3) + \dots \quad (5)$$

$$\checkmark \quad 4 \neq 5 \quad \left\{ \begin{array}{l} \frac{d^2}{dt^2} (m_1 + m_2) = \frac{d^2 m_1}{dt^2} + \frac{d^2 m_2}{dt^2} \dots (6) \\ -\omega^2 (m_1 + m_2) = -\omega^2 m_1 - \omega^2 m_2 \quad (7) \end{array} \right.$$

$$X \quad \left\{ \begin{array}{l} \alpha (m_1 + m_2)^2 = \alpha (m_1^2 + m_2^2) \rightarrow (8) \\ \beta (m_1 + m_2)^3 = \beta (m_1^3 + m_2^3) \rightarrow (9) \end{array} \right. \quad \begin{array}{l} \text{not true} \\ \text{expect} \\ \alpha = \beta = 0 \end{array}$$