

$$-\pi_3 \dot{\theta}_3 \cos \theta_3 + \pi_4 \dot{\theta}_4 \cos \theta_4 = \pi_2 \dot{\theta}_2 \cos \theta_2 - \pi_2 \dot{\theta}_2^2 \sin \theta_2$$

Q) A 4 bar linkage with crank length = 2 unit, coupler length = 3 unit 3.5 unit, follower length = 4 unit and fixed link length is 1 unit.

I) When $\theta_1 = 0^\circ$ and $\theta_2 = 90^\circ$, find out θ_3 and θ_4

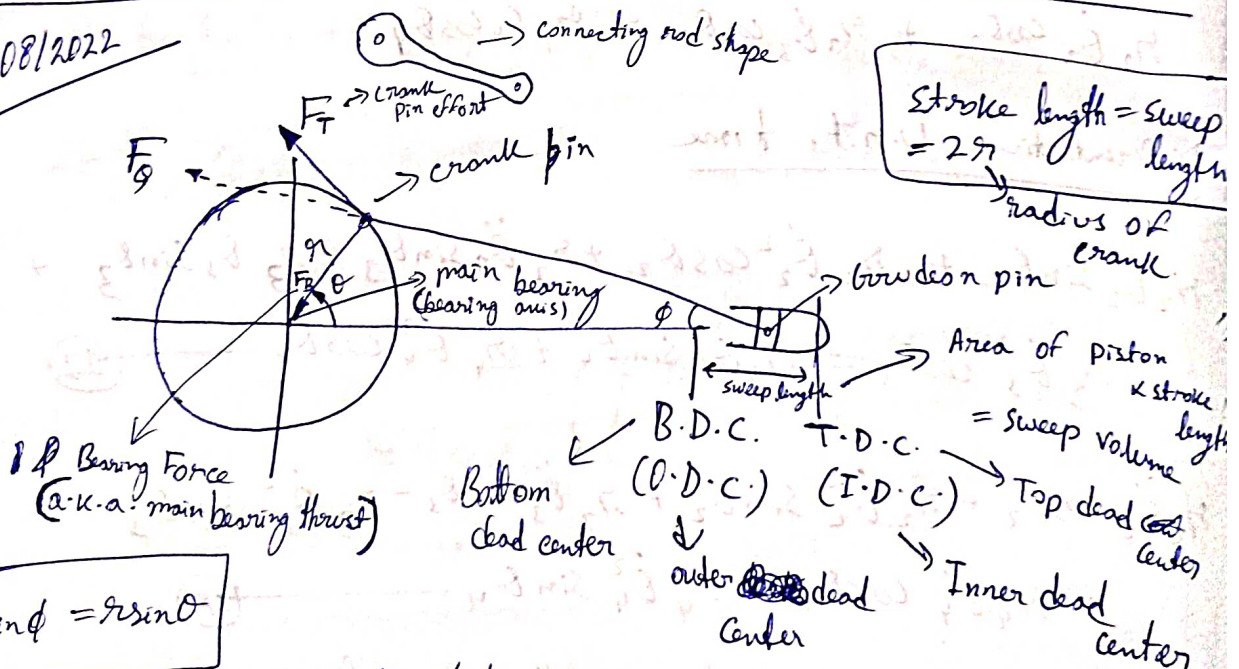
II) If $\dot{\theta}_2 = 10 \text{ rad/sec}$ and $\ddot{\theta}_2 = 0$, compute $\dot{\theta}_3$, $\dot{\theta}_4$ and $\ddot{\theta}_3$ and $\ddot{\theta}_4$

Rough

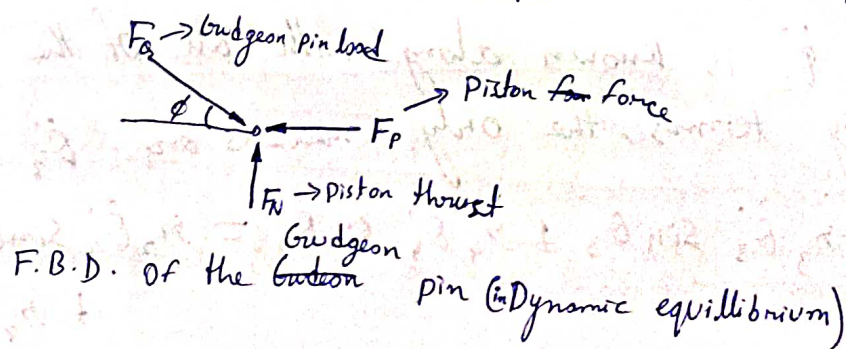
Find loop closure equation in scalar form

1st assignment assignment (A4 Page) ↑

25/08/2022

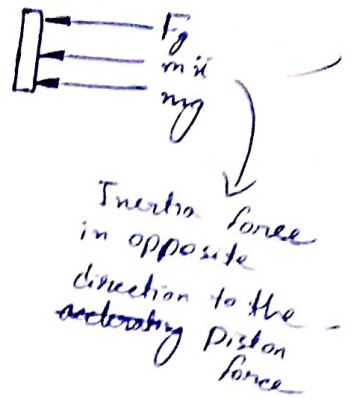


$$l \sin \phi = r \sin \theta$$



$$F_p = F_g + m\ddot{x} + mg \rightarrow \text{mass of slider (piston)} \rightarrow = 0 \text{ for horizontal engine engine}$$

\downarrow Inertia Force
 $\frac{\pi D^2}{4} \times p$
 \downarrow Pressure



From Sine rule

$$\frac{F_p}{\sin(90^\circ + \phi)} = \frac{F_g}{\sin 90^\circ} = \frac{F_n}{\sin(180^\circ - \phi)} \quad \left. \vphantom{\frac{F_p}{\sin(90^\circ + \phi)}} \right\} \text{use these to solve questions}$$

$$F_g = F_p \cdot \frac{n}{\sqrt{n^2 - \sin^2 \theta}}$$

$[n = \text{crank ratio}]$

$$F_n = F_p \cdot \frac{\sin \theta}{\sqrt{n^2 - \sin^2 \theta}}$$

Always Draw figure in Answer and write in S.I. unit and the direction of force

→ Probable question

Q) Derive the expression ~~for~~ for F_g and F_n from θ .

$$F_T = F_g \sin(\theta + \phi)$$

$$F_B = F_g \cos(\theta + \phi)$$

$$F_T = F_p \sin \theta \left[1 + \frac{\cos \theta}{\sqrt{n^2 - \sin^2 \theta}} \right]$$

$$F_B = \left[\cos \theta - \frac{\sin^2 \theta}{\sqrt{n^2 - \sin^2 \theta}} \right]$$

If one starts with 1
1.328 then round
upto 4 dec places
→ 1.328 N
for any other digit

→ round upto
3 digits
N, MN, KN,
use multiplicative
terms for higher
numbers
↓
Solution not
more accurate than
the data given
in question

Q) Derive F_T and F_B in terms of F_p

• Crank effort → Turning moment i.e. torque
 $T = F_T \cdot r$ (Q)
 \downarrow
 Torque

• Go through problems