## Goals of compiler optimization

#### Minimize number of instructions

- Don't do calculations more than once
- Don't do unnecessary calculations at all
- Avoid slow instructions (multiplication, division)

#### Avoid waiting for memory

- Keep everything in registers whenever possible
- Access memory in cache-friendly patterns
- Load data from memory early, and only once

#### Avoid branching

- Don't make unnecessary decisions at all
- Make it easier for the CPU to predict branch destinations
- "Unroll" loops to spread cost of branches over more instructions

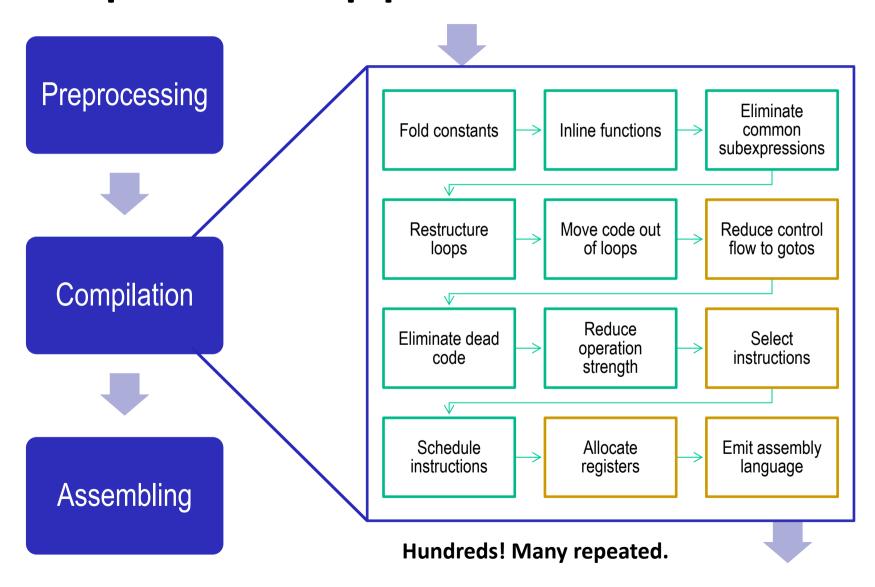
## Limits to compiler optimization

- Generally cannot improve algorithmic complexity
  - Only constant factors, but those can be worth 10x or more...
- Must not cause any change in program behavior
  - Programmer may not care about "edge case" behavior, but compiler does not know that
  - Exception: language may declare some changes acceptable
- Often only analyze one function at a time
  - Whole-program analysis ("LTO") expensive but gaining popularity
  - Exception: inlining merges many functions into one
- Tricky to anticipate run-time inputs
  - Profile-guided optimization can help with common case, but...
  - "Worst case" performance can be just as important as "normal"
  - Especially for code exposed to malicious input (e.g. network servers)

#### **Performance Realities**

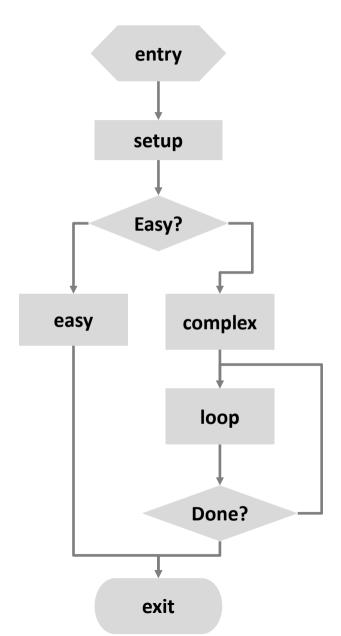
- There's more to performance than asymptotic complexity
- Constant factors matter too!
  - Easily see 10:1 performance range depending on how code is written
  - Must optimize at multiple levels:
    - algorithm, data representations, procedures, and loops
- Must understand system to optimize performance
  - How programs are compiled and executed
  - How modern processors + memory systems operate
  - How to measure program performance and identify bottlenecks
  - How to improve performance without destroying code modularity and generality

#### **Compilation is a pipeline**



### Two kinds of optimizations

- Local optimizations work inside a single basic block
  - Constant folding, strength reduction, dead code elimination, (local) CSE, ...
- Global optimizations process the entire control flow graph of a function
  - Loop transformations, code motion, (global) CSE, ...



# **Today**

- Principles and goals of compiler optimization
- Local optimization
  - Constant folding, strength reduction, dead code elimination, common subexpression elimination
- Global optimization
  - Inlining, code motion, loop transformations
- Obstacles to optimization
  - Memory aliasing, procedure calls, non-associative arithmetic
- Quiz
- Machine-dependent optimization
  - Branch predictability, loop unrolling, scheduling, vectorization

# **Constant Folding**

Do arithmetic in the compiler

```
long mask = 0xFF << 8; \rightarrow long mask = 0xFF00;
```

- Any expression with constant inputs can be folded
- Might even be able to remove library calls...

```
size_t namelen = strlen("Harry Bovik"); →
size_t namelen = 11;
```

# Strength reduction

Replace expensive operations with cheaper ones

```
long a = b * 5; \rightarrow long a = (b << 2) + b;
```

- Multiplication and division are the usual targets
- Multiplication is often hiding in memory access expressions

#### Dead code elimination

Don't emit code that will never be executed

```
if (0) { puts("Kilroy was here"); }
if (1) { puts("Only bozos on this bus"); }
```

Don't emit code whose result is overwritten

$$x = 23;$$
  
 $x = 42;$ 

- These may look silly, but...
  - Can be produced by other optimizations
  - Assignments to x might be far apart

## **Common Subexpression Elimination**

Factor out repeated calculations, only do them once

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# **Inlining**

#### Copy body of a function into its caller(s)

- Can create opportunities for many other optimizations
- Can make code much bigger and therefore slower (size; i-cache)

```
int func(int y) {
int pred(int x) {
    if (x == 0)
                                   int tmp;
        return 0;
                                   if (y == 0) tmp = 0; else tmp = y - 1;
    else
                                   if (0 == 0) tmp += 0; else tmp += 0 - 1;
        return x - 1;
}
                                   if (y+1 == 0) tmp += 0; else tmp += (y + 1) - 1;
                                   return tmp;
int func(int y) {
    return pred(y)
         + pred(0)
         + pred(y+1);
}
```

# **Inlining**

#### Copy body of a function into its caller(s)

- Can create opportunities for many other optimizations
- Can make code much bigger and therefore slower

```
int pred(int x) {
    if (x == 0)
        return 0;
    else
        return x - 1;
}
int func(int y) {
    return pred(y)
        + pred(0)
        + pred(y+1);
}
```

```
int func(int y) {
  int tmp;
  if (y == 0) tmp = 0; else tmp = y - 1;
  if (0 == 0) tmp += 0; else tmp += 0 - 1;
  if (y+1 == 0) tmp += 0; else tmp += (y + 1) - 1;
  return tmp;
}
```

**Always true** 

**Does nothing** 

**Can constant fold** 

# **Inlining**

#### Copy body of a function into its caller(s)

- Can create opportunities for many other optimizations
- Can make code much bigger and therefore slower

```
int func(int y) {
  int tmp;
  if (y == 0) tmp = 0; else tmp = y - 1;
  if (0 == 0) tmp += 0; else tmp += 0 - 1;
  if (y+1 == 0) tmp += 0; else tmp += (y + 1) - 1;
  return tmp;
}

int func(int y) {
  int tmp = 0;
  if (y != 0) tmp = y - 1;
  if (y != -1) tmp += y;
  return tmp;
}
```

#### **Code Motion**

- Move calculations out of a loop
- Only valid if every iteration would produce same result

```
long j;
for (j = 0; j < n; j++)
    a[n*i+j] = b[j];

→
long j;
int ni = n*i;
for (j = 0; j < n; j++)
    a[ni+j] = b[j];</pre>
```

Rearrange entire loop nests for maximum efficiency

Loop interchange: do iterations in cache-friendly order

Loop fusion: combine adjacent loops with the same limits

Induction variable elimination: replace loop indices with algebra

# **Today**

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# **Memory Aliasing**

```
/* Sum rows of n X n matrix a and store in vector b. */
void sum_rows1(double *a, double *b, long n) {
    long i, j;
    for (i = 0; i < n; i++) {
        b[i] = 0;
        for (j = 0; j < n; j++)
            b[i] += a[i*n + j];
    }
}</pre>
```

```
# sum_rows1 inner loop
.L4:

movsd (%rsi,%rax,8), %xmm0 # FP load
addsd (%rdi), %xmm0 # FP add
movsd %xmm0, (%rsi,%rax,8) # FP store
addq $8, %rdi
cmpq %rcx, %rdi
jne .L4
```

- Code updates b[i] on every iteration
- Why couldn't compiler optimize this away?

## **Memory Aliasing**

```
/* Sum rows of n X n matrix a and store in vector b. */
void sum_rows1(double *a, double *b, long n) {
    long i, j;
    for (i = 0; i < n; i++) {
        b[i] = 0;
        for (j = 0; j < n; j++)
            b[i] += a[i*n + j];
    }
}</pre>
```

```
double A[9] =
  { 0, 1, 2,
    4, 8, 16},
    32, 64, 128};

double B[3] = A+3;

sum_rows1(A, B, 3);
```

```
double A[9] =
  { 0,   1,   2,
   3,   22,  224},
  32,  64,  128};
```

#### Value of B:

```
init: [4, 8, 16]
i = 0: [3, 8, 16]
i = 1: [3, 22, 16]
i = 2: [3, 22, 224]
```

- Code updates b[i] on every iteration
- Must consider possibility that these updates will affect program behavior

```
/* Sum rows of n X n matrix a and store in vector b. */
void sum_rows2(double *a, double *b, long n) {
    long i, j;
    for (i = 0; i < n; i++) {
        double val = 0;
        for (j = 0; j < n; j++)
            val += a[i*n + j];
        b[i] = val;
    }
}</pre>
```

```
# sum_rows2 inner loop
.Loop:
    addsd (%rdi), %xmm0  # FP load + add
    addq $8, %rdi
    cmpq %rax, %rdi
    jne .Loop
```

Use a local variable for intermediate results

```
/* Sum rows of n X n matrix a and store in vector b. */
void sum_rows2(double *a, double *b, long n) {
    long i, j;
    for (i = 0; i < n; i++) {
        double val = 0;
        for (j = 0; j < n; j++)
            val += a[i*n + j];
        b[i] = val;
    }
}</pre>
```

```
double A[9] =
  { 0,   1,   2,
   4,   8,  16},
  32,  64,  128};

double B[3] = A+3;

sum_rows1(A, B, 3);
```

```
double A[9] =
  { 0, 1, 2,
    3, 27, 224},
    32, 64, 128};
```

#### Value of B:

```
init: [4, 8, 16]
i = 0: [3, 8, 16]
```

```
i = 1: [3, 27, 16]
```

$$i = 2$$
: [3, 27, 224]

- Still changes A in the middle of the operation
- Different results

```
/* Sum rows of n X n matrix a and store in vector b. */
void sum_rows3(double *restrict a, double *restrict b, long n) {
    long i, j;
    for (i = 0; i < n; i++) {
        b[i] = 0;
        for (j = 0; j < n; j++)
            b[i] += a[i*n + j];
    }
}</pre>
```

```
# sum_rows3 inner loop
.Loop:
    addsd (%rdi), %xmm0  # FP load + add
    addq $8, %rdi
    cmpq %rax, %rdi
    jne .Loop
```

- Use restrict qualifier to tell compiler that a and b cannot alias
- Less reliable than using local variables

```
subroutine sum_rows4(a, b, n)
   implicit none
   integer, parameter :: dp = kind(1.d0)
   real(kind=dp), dimension(:), intent(in) :: a
   real(kind=dp), dimension(:), intent(out) :: b
   integer, intent(in) :: n
   integer :: i, j
   do i = 1,n
        b(i) = 0
        do j = 1,n
        b(i) = b(i) + a(i*n + j)
        end
   end
end
```

```
# sum_rows4 inner loop
.Loop:
    addsd (%rdi), %xmm0  # FP load + add
    addq $8, %rdi
    cmpq %rax, %rdi
    jne .Loop
```

- Use Fortran
- Array parameters in Fortran are assumed not to alias

# Function calls are opaque

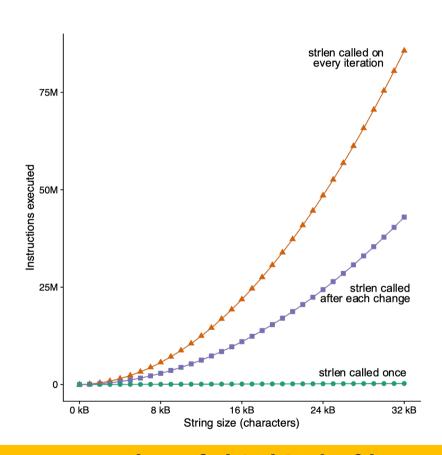
- Compiler examines one function at a time
  - Some exceptions for code in a single file
- Must assume a function call could do anything
- Cannot usually
  - move function calls
  - change number of times a function is called
  - cache data from memory in registers across function calls

```
size_t strlen(const char *s) {
    size_t len = 0;
    while (*s++ != '\0') {
        len++;
    }
    return len;
}
```

- O(n) execution time
- Return value depends on:
  - value of s
  - contents of memory at address s
    - Only cares about whether individual bytes are zero
    - Does not modify memory
- Compiler might know some of that (but probably not)

## Can't move function calls out of loops

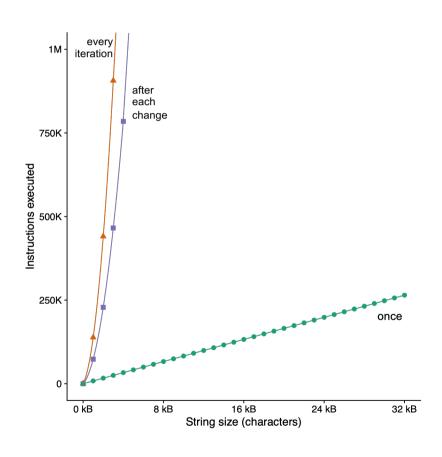
```
void lower quadratic(char *s) {
  size t i;
  for (i = 0; i < strlen(s); i++)
    if (s[i] >= 'A' \&\& s[i] <= 'Z')
      s[i] += 'a' - 'A';
void lower still quadratic(char *s) {
  size t i, n = strlen(s);
  for (i = 0; i < n; i++)
    if (s[i] >= 'A' \&\& s[i] <= 'Z') {
      s[i] += 'a' - 'A';
      n = strlen(s);
}
void lower linear(char *s) {
  size t i, n = strlen(s);
  for (i = 0; i < n; i++)
    if (s[i] >= 'A' \&\& s[i] <= 'Z')
      s[i] += 'a' - 'A';
```



Lots more examples of this kind of bug: accidentallyquadratic.tumblr.com

## Can't move function calls out of loops

```
void lower quadratic(char *s) {
  size t i;
  for (i = 0; i < strlen(s); i++)
    if (s[i] >= 'A' \&\& s[i] <= 'Z')
      s[i] += 'a' - 'A':
void lower still quadratic(char *s) {
  size t i, n = strlen(s);
  for (i = 0; i < n; i++)
    if (s[i] >= 'A' \&\& s[i] <= 'Z') {
      s[i] += 'a' - 'A';
     n = strlen(s);
void lower linear(char *s) {
  size t i, n = strlen(s);
  for (i = 0; i < n; i++)
    if (s[i] >= 'A' \&\& s[i] <= 'Z')
      s[i] += 'a' - 'A';
```



#### Non-associative arithmetic

- When is  $(a \odot b) \odot c$  not equal to  $a \odot (b \odot c)$ ?
  - Octonions
  - Vector cross product
  - Floating-point numbers
- **Example:** a = 1.0,  $b = 1.5 \times 10^{38}$ ,  $c = -1.5 \times 10^{38}$  (single precision IEEE fp)

$$a + b = 1.5 \times 10^{38}$$
  $(a + b) + c = 0$   
 $b + c = 0$   $a + (b + c) = 1$ 

Blocks any optimization that changes order of operations

#### Non-associative arithmetic

```
void mmm(double *a, double *b,
         double *c, int n) {
  memset(c, 0, n*n*sizeof(double));
  int i, j, k;
 for (i = 0; i < n; i++)
    for (j = 0; j < n; j++)
      for (k = 0; k < n; k++)
        c[i*n + j] += a[i*n + k]
                    * b[k*n + j];
```

