### Neural Networks and Backpropagation

Alipio Jorge (DCC-FCUP)

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### What is a Neural Network?

- When our aim is to learn a classification or a regression model
  - we want a **function**  $\hat{f}$  that approximates the unknown function
- **How** do we define this function?
  - A linear function
  - By analogy of similar cases
  - By maximizing estimated probabilities
  - Using a decision tree (or a regression tree)
  - etc.

### What is a Neural Network?

- A Neural Network is another way of defining functions
  - can be graphically described
  - but it always corresponds to a mathematical function
- Neural Networks are flexible and powerful
  - but not for all types of data

### What is a Neural Network?

- Many types of networks and NN components
  - the Perceptron
  - the Multi-layer Perceptron
  - the Feed-Forward Network
  - Convolutional Neural Networks
  - Recurrent Neural Networks
  - LSTM, BiLSTM, GRU, GAN, ...
  - and multiple combinations of the above

- A perceptron is the simplest and most fundamental NN unit
   inspired in biological neurons
- It can define simple functions

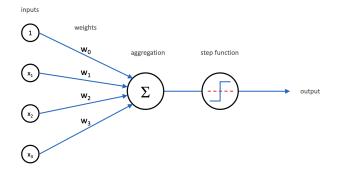


Figure 1: Binary Perceptron

Mathematically

$$\hat{y} = step(w_0 + \sum_{i=1}^k w_i.x_i)$$

• the step function gives a binary output depending on threshold

$$step(x) = \begin{cases} 0 & x < \theta \\ 1 & x \ge \theta \end{cases}$$

- A simple example:
  - New case to classify: Should we give a loan to  $x = \langle Age = 25, Salary = 1500 \rangle$ ?
  - Model parameters: Our perceptron has weights w = <0, 10, 0.2>
  - Threshold:  $\theta = 400$
- Applying the model
  - $\hat{y} = step(0 + 10 \times 25 + 0.2 \times 1500) = step(550) = 1$
  - The **predicted class** is **1**: give the loan.

- The step is an activation function
  - decides if the neuron fires or not
- The sigmoid is another activation function
  - very popular
  - good mathematical properties (to see later)

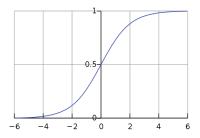


Figure 2: from wikipedia

### Activation function sigmoid

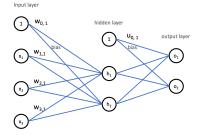
- The perceptron becomes a numerical function
  - that can be used for classification

$$\hat{y} = sigmoid(w_0 + \sum_{i=1}^k w_i.x_i)$$

sigmoid is defined as

$$sigmoid(x) = \frac{1}{1 + e^{-x}}$$

- Side by side preceptrons
  - multivalued functions (non-binary classification)
- Adding a hidden layer
  - fully connected: each node linked to all nodes in nearby layers
  - more expressive functions
  - abstraction layers
- bias weights (intercepts)



- Mathematically
  - although commonly represented as a graph, a NN is a mathematically defined function
  - A two layer example: calculate hidden layer

$$h_j = activ(w_0 + \sum_{i=1}^m w_{ij}^{\mathsf{x}}.x_i)$$

hidden layer

$$h_j = activ(w_{0j}^h + \sum_{i=1}^m w_{ij}^h.x_i) \quad j \in \{1, \dots, m_{hidden}\}$$

output layer

$$o_j = activ(w^o_{0j} + \sum_{i=1}^{m_h} w^o_{ij}.h_i) \quad j \in \{1, \dots, m_{out}\}$$

- classical ANN (Artificial Neural Networks) are MLP
  - Example with irisdata set
    - 4 predictors
    - 3 classees
  - We define previously the **topology** of the network
    - how many layers, how many nodes
  - The learning task is to find the best values for the weights
    - we say learning the weights
    - parameter fitting
    - training the network

```
from sklearn.neural_network import MLPClassifier
from sklearn.model_selection import train_test_split
X train, X test, y train, y test =
  train test split(X, y, stratify=y,random state=1)
clf = MLPClassifier(random state=1,
                    hidden layer sizes=(8,),
                    max iter=500,
                    activation='logistic'
                   ).fit(X_train, y_train)
```

- The MLP in this example
- Nodes or units
  - 4 input
    - 8 hidden
    - 3 output
- Weights (including bias weights)
  - 58 + 93
- Activation function
  - sigmoid (logistic)
- Class is given by the highest output (of the three)

#### Feedforward networks

- MLP are feedforward networks
  - they can have many hidden layers
- Prediction is done from left to right
  - **start** with the example  $x = x_1, ..., x_m$
  - assign the values to the input nodes
  - calculate the values of the hidden nodes of the next layer
  - iterate layer by layer until output
  - the prediction is in the output layer

### Defining the topology: output

### Binary classification

- 1 output node with threshold
- 2 output nodes, choose maximum output

#### k class classification

- k output nodes, choose maximum
- we can also produce a distribution using softmax

#### regression

1 output node, numerical value

### Defining the topology: input

- Number of input units
  - One per numerical attribute
  - One per binary attribute
  - K-valued attribute
    - One per value (one hot encoding)

# Defining the topology: layers

### Number of layers

- domain dependent
- as few as possible (simplicity first)
- each layer adds
  - abstractive power (good)
  - overfitting risk (bad)
  - computational effort (bad)

#### Heuristic

- keep adding layers until learning stops improving
- and while your resources allow
- use cross-validation on the validation set
  - not on the test set

### Defining the topology

- Number of units in hidden layers
  - no clear rules
- Some ideas
  - Low level input vars
    - decrease number of hidden nodes
  - High level input vars
    - increase number of hidden vars
  - Small data
    - low number of layers and units
- Trial and error
  - CV, ...
- Heuristic search, Genetic Algorithms, . . .
- Meta learning
  - Learning how to learn

### Learning

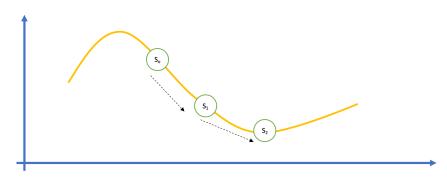
- How do we train a MLP?
  - algorithm **Backpropagation** (BP)
- BP:
  - given:
    - a set of examples
    - a network topology
  - finds
    - the "best" values for the weights (parameters)

### Learning: Backpropagation

- What is the BP algorithm?
  - the aim is to reduce prediction error
  - Init: start the MLP with random weights
    - initial state of the NN
  - Iterate: update weights optimally according to observed errors
  - until convergence or maximum iterations

### Learning: Backpropagation

- Backprogation
  - is an optimization algorithm
  - is derived mathematically from first principles



The state space (as many dimensions as parameters)

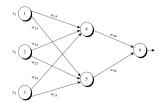
### Backpropagation: in detail

- Input: D, topology, learning rate  $\eta$
- Output: weights (trained model)
- Do
  - for each  $x \in D$ 
    - calculate the outputs ô using feedforward
    - calculate the derivative of error  $err = derror(o, \hat{o})$  wrt weights
    - backpropagate derror from output to the first hidden layer
    - update the weights
  - until stopping condition is met (each iteration is an epoch)

### Error calculation and propagation

- Output derror units calculated from output values and true values
  - assuming sigmoid activation, using the derivative of logistic

$$DErr_j = O_j(1 - O_j)(T_j - O_j)$$

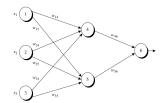


- Example 9.1 (from Han et al.)
  - $x = (1, 0, 1), o_6 = 0.474, T = 1,$
  - DErr = (0.474)(1 0.474)(1 0.474) = 0.1311

### Error calculation and propagation

Hidden layer derror units calculated from next layer k error

$$DErr_j = o_j(1 - o_j) \sum_k DErr_k w_{jk}$$

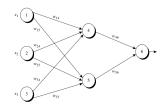


- Error of unit 4
  - $o_4 = 0.332$ ,  $DErr_6 = 0.1311$ ,  $w_{46} = -0.3$
  - $DErr_4 = 0.332(1 0.332)(0.1311)(-0.3) = -0.0087$

# Updating weights

Using error in firing unit

$$\Delta w_{ij} = \eta.DErr_j.o_i, \qquad w_{ij} = w_{ij} + \Delta w_{ij}$$



- $\eta = 0.9$ ,  $DErr_4 = -0.0087$ , (old)  $w_{14} = 0.2$ ,  $o_1 = x_1 = 1$
- $\Delta w_{14} = (0.9)(-0.0087)(1) = -0.00783$
- $w_{14} = 0.2 + (-0.00783) = 0.19217$

### Foundations of backpropagation

- Learning as optimization
  - objective is to minimize error or loss

$$\min_{w} L(y, \hat{y}) = \sum_{i=1}^{n} (y - \hat{y})^{2}$$

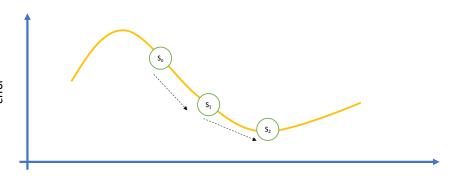
- We can define appropriate loss functions depending on the problem
- Solution is found by deriving E wrt parameters
  - no analytical solution for ANN (c.f. linear regression)

### Stopping criteria

- The increments  $\Delta_{ij}$  are too small
- Error is low enough
- Maximum number of iterations

### Foundations of backpropagation

- We use an iterative approach based on gradient descent
  - steepest descent (descida mais rápida)
- backpropagation uses gradient descent
  - start from initial weights (random)
  - move in the space of solutions as indicated by the gradient
    - learning rate  $\eta$  is the size of the step



#### Limitations

- Local minima
  - BP is an eager algorithm
  - it may miss the global optimum
- Different scales of attributes
  - make learning take longer
  - usually we **normalize** input attributes

#### Limitations

- Random start
  - initial weights are random
  - usually Gaussian with mean zero
  - a constant would give the same initial output to all cases
- Variability
  - random start may lead to different solutions (local minima)
  - good idea to repeat with different initializations (no fixed seed)

# Efficiency

- ullet Given N cases and W weights
- Each **epoch** takes O(N.W) operations
- The number of epochs depends on the data
  - easy problem converges quickly
- and on the number of weights
  - complex networks take longer to converge
  - limiting the number of iterations may be practical

### **Optimizers**

- Backpropagation is the classical ANN optimizer
  - but there are many others
  - Adam is a popular one with Deep Learning
  - the most popular use gradient descent

### Explainability

- ANN are opaque models
- We can read:
  - the coefficients of linear regression
  - the rules in a decision tree
  - the probabilities in Naive Bayes
- But the weights of a MLP are
  - not directly interpretable (no easy meaning)
  - combined to obtain an answer
- There are techniques for obtaining explanations from ANN models
  - hot topic
  - XAI: Explainable AI

### References

- Books
  - Han, Kamber & Pei, Data Mining Concepts and Techniques, Morgan Kaufman.
- Wikipedia
  - Backpropagation, https://en.wikipedia.org/wiki/Backpropagation