# MR – Random Forest Algorithm for Distributed Action Rules Discovery

Mythri S. Madhu, Prateek Mahendrakar, Vamsy Ram Kundula, Hanisha Marothu, Kaushal Kanakamedala, Navaneeth Reddy Matta Department of Computer Science University of North Carolina at Charlotte Charlotte,NC,USA

e-mail: <u>mmadhu@uncc.edu</u>, <u>pmahend1@uncc.edu</u>, <u>vkundula@uncc.edu</u>, <u>hmarothu@uncc.edu</u>, <u>kkanakam@uncc.edu</u>, <u>nmatta1@uncc.edu</u>

Abstract—Action rules are built from atomic expressions, which describe the possible transition of object from one state to another based on a decision attribute. An association action rule is like action rule, which involves change of several attributes in its decision part. Earlier algorithms to discover action rules required extraction of classification rules before constructing any action rule. Newest algorithms extract action rules directly from the given information system. Action rules assume that attributes are divided into two groups: stable and flexible. Action rules can be constructed from two rules extracted from database. These rules represent two different decision classes. Flexible attributes help in re-classifying objects from one class to another. The set of conditional attributes are partitioned into flexible, stable, semi-stable. The semi- stable attributes based on the semantics can sometimes be treated as flexible. A same new action rule can be constructed using the semi stable attributes, which are used to replace the existing action rule whose confidence is too low.

Keywords-Data-mining; Association Action rule; Map Redu ce; Hadoop;

#### I. Introduction

Many business enterprises accumulate large quantities of data from their day-to-day operations. For example, huge amounts of customer purchase data are collected daily at the checkout counters of grocery stores. Retailers are interested in analyzing the data to learn about the purchasing behavior of their customers. Such valuable information can be used to support a variety of business-related applications such as promotions, inventory management, and marketing customer relationship management. Association analysis is useful for discovering interesting relationships hidden in large data sets. The uncovered relationships can be represented in the form of association rules or sets of frequent items. Besides market basket data, association analysis is also applicable to other application domains such as bioinformatics, medical diagnosis, Web mining, and scientific data analysis. There are two key issues that need to be addressed when applying association analysis to market basket data. First, discovering patterns from a large transaction data set can be computationally expensive. Second, some of the discovered patterns are potentially spurious because they may happen simply by chance.

Association rules are created by analyzing data for frequent if/then patterns. An association rule has two parts, an antecedent (if) and a consequent (then). An antecedent is an item found in the data. A consequent is an item that is found in combination with the antecedent.

An association rule is an implication expression of the from  $X \rightarrow Y$ , where X and Y are disjoint items, i.e;  $X \cap Y = \varphi$ . The strength of association rule is measured in terms of **support** and **confidence**. Support is an important measure that defines how often a rule is applicable to a given data set. Support is used to eliminate un-interesting rules. A rule which has low support may occur by chance and it is likely to be of less importance. Confidence defines the number of times items in Y appear in transactions that contain X. Confidence provides an estimate of conditional probability of Y given X.

Consider a dataset of an information system of the form  $S=\{X \cup Y \cup Z\}$ , where Y and Z are flexible attributes and X is the stable attribute. Following is an example of action rule if user desires the decision attribute value to change from z1 to z2; where  $\{x1,x2,x3..xn\} \subseteq X$ ,  $\{y1,y2,y3,...yn\} \subseteq Y$ ,  $\{z1,z2,..zn\} \subseteq Z$ . Rule 1 means that if attribute x changes its value from 1 to 2, and attribute y value remains y2, then attribute z is expected to change from z1 to z2.

Rule1 = 
$$(X, x1 \rightarrow x2) \land (Y,y2) \rightarrow (Z, z1 \rightarrow z2)$$

As data in real-time is very large, to generate action rules on a single becomes expensive. Hence we use an algorithm which runs on a distributed system. To generate action rules in a distributed system we use MapReduce. To run MapReduce we used Apache's open source Hadoop

framework, to process large datasets on multiple nodes in multiple clusters.

To discover action rules we used MapReduce-Random Forest Algorithm. We used algorithm known as *Action Rules Discovery Based on Grabbing Strategy* and *Learning from Example Based on Rough Sets* to the distributed MapReduce environment. Using *LERS* we extracted the action rules in Mappers. The output from Mapper is sent to reducers, where reducers user Random Forest to produce a set of action rules. These action rules are called Association Action Rules(AAR).

#### II. RELATED WORK

The action rules notion was initially proposed with the idea of splitting the attributes into stable attributes, flexible attributes and a decision attribute. In the earlier research, however the action rules were produced using some of the classification rules. Ras and Wyrzykowska [1] later gave a LERS [3] type of algorithm that considers only marked certain rules to construct the action rules. A new algorithm named ARoGS was proposed by Ras and Wyrzykowska [2] which combines each action rule generated from single classification rule with the remaining stable attributes to offer more action rules. This helps discover more action rules that were missed out in the previous algorithms.

#### III. METHODOLOGY

We implemented the Random-Forest algorithm for action rules discovery using Hadoop framework and Google MapReduce. We take as an input a set of files: the data, the attribute names, user specified parameters such as: minimum support, and confidence thresholds, stable attribute names, flexible attribute names, decision attribute choice, decision attribute value to *change\_from*, and decision attribute value to *change\_to*, which is the desired value of decision attribute. We import these input files into the HDFS (Hadoop Distributed File System).

## A. MapReduce

MapReduce is a way to perform special-purpose computations that process large amounts of raw data to compute various kinds of derived data. MapReduce handle issues like how to parallelize the computation, distribute the data and handle failures. Though such computations are conceptually straightforward, the input data is generally large and the computations have to be distributed across hundreds of machines in order to finish the task in a reasonable amount of time. MapReduce is a new abstraction that allows expressing the simple computations and hides the messy details of parallelization, fault tolerance etc.

The abstraction is inspired by the *map* and *reduces* primitives present in Lisp and many other functional languages. Most of their computations involved applying a map operation to each logical record in input in order to

compute a set of intermediate key/value pairs, and then applying a reduce operation to all the values that shared the same key in order to combine the derived data appropriately. The intermediate values are supplied to the user's reduce function via an *iterator* which allows to handle lists of values that are too large to fit in memory. The programming model can also be used to parallelize computations across multiple cores of the same machine.

The special features of MapReduce are:

Fault Tolerance: Worker failures are very well handled with the help of the master by periodically checking the responses from the workers. This mechanism helped in solving the issue of 80 unreachable machines.

Locality: The MapReduce master tries to schedule a map task on a machine that contains a replica of the corresponding input data so as to consume no network bandwidth - which is relatively scarce resource in our computing environment.

Task Granularity: The map and reduce phases should be considerably more than the worker threads so that having each worker perform many different tasks improves dynamic load balancing and also speeds up recovery when a worker fails.

Backup Tasks: There might be cases where a machine might take unusually more time due to some performance issues which delays the task assigned to that machine. But the mechanism of scheduling backup executions of remaining in-progress tasks by the master will significantly improve the execution time.

After including the locality optimization, dynamic load balancing of task execution across work machines, there has a broad use of MapReduce across a wide range of domains within Google. i.e. large-scale machine learning problems, clustering problems, extracting data to produce results for popular queries, processing of satellite imagery data, large scale graph computations and so on. The most significant use of MapReduce to date is a complete rewrite of the production indexing system that produces the data structures used for the Google Web search service.

#### B. LERS

The LERS (Learning from Examples based on Rough Sets) method is used to find all certain and possible rules in a distributed scenario using MapReduce. The system induces rules from databases. Rules indication is based on four different algorithms. Two algorithms are used for indicating rules in minimal discriminant form, remaining two are used for discovering of all potential rules hidden in a database. Input data may be imperfect or data may contain errors like missing attributes, numerical attributes and inconsistencies. LERS classifies new unseen cases using principles similar to clustering. LERS is also equipped with a tool for multiple-fold cross validation. The system has

in medical area, nursing, global warming, environmental protection, natural languages and data transmission. LERS may process big datasets and frequently outperforms not only other rule induction system but also human experts. The decision table represents input data, gathered from any domain. In the decision table examples are described by values of attributes (e.g., tests) and characterized by a value of a decision, assigned by an expert. All examples with the same value of the decision belong to the same concept. The decision table is similar in format to a data base. The system LERS looks for regularities in the decision table. The output of LERS are rules, a knowledge about original data. These rules are more general than information contained in the original decision table, since in general more new examples may be correctly classified by rules than may be matched with examples from the original decision table. The system LERS belongs to the class of machine learning systems from examples. LERS, like other such systems, is finding a minimal description of a concept, described by 2 positive examples, excluding from the description of the concept the remaining, negative examples. Thus rules induced by LERS may be described as a minimal discriminant description of the concept. [6]

#### C. ARoGS

ARoGS is Action Rules Discovery Based on Grabbing Strategy, which uses LERS. ARoGS are applicable for complete information systems. To extract the action rules, ARoGS use LERS to skip verifying few of the certain relations. The complexity of the algorithm decreases as the module is pre-processed in LERS and the classification rules are defined.

Let us assume  $S = (U, A_1 \ A_2 \ \{d\})$  is a complete decision system, where

Elements of  $A_1$  are stable conditions Elements of  $A_2$  are flexible conditions

d is the decision attribute and d  $A_1$   $A_2$ 

Assume  $d_1 V_d$  and x U. We say that x is a  $d_1$ -object if  $d(x) = d_1$ 

Also assume that  $\{a_1, a_2, ..., a_p\}$   $A_1, \{a_{p+1}, a_{p+2}, ..., a_n\} = A_1 - \{a_1, a_2, ..., a_p\}, \{b_1, b_2, ..., b_q\}$   $A_2, a_{[i,j]}$  denotes a value of attribute  $a_i, b_{[i,j]}$  denotes a value of attribute  $b_i$ , for any i, j and that

$$r = [[a_{[1,1]} \quad a_{[2,1]} \quad \dots \quad a_{[p,1]} \quad b_{[1,1]} \quad b_{[2,1]} \quad \dots \\ b_{[q,1]}] \xrightarrow{} d_1]$$

is a classification rule extracted from  $d_1$ -objects in S. d1 is the preferable class and the expected result is to reclassify  $d_2$  to  $d_1$ . Using the above classification rule we can reclassify  $d_2$  as

$$r_{[d_2 ot d_1]} = [[a_{[1,1]} \quad a_{[2,1]} \quad \dots \quad a_{[p,1]} \quad (b_1, - \to b_{[1,1]})$$
  
 $(b_2, - \to b_{[2,1]}) \quad \dots \quad (b_q, - \to b_{[q,1]})] \xrightarrow{-} (d, d_2 \xrightarrow{-} d_1)]$ 

Similarly the action rule schema is defined as  $r[-\rightarrow d_1] = [[a_{[1,1]} \quad a_{[2,1]} \quad ... \quad a_{[p,1]} \quad (b_1, -\rightarrow b_{[1,1]})$   $(b_2, -\rightarrow b_{[2,1]}) \quad .... \quad (b_q, -\rightarrow b_{[q,1]})] \rightarrow (d, -\rightarrow d_1)]$ 

Now we generate the set of Action Rules from the available schema  $r[d2 \rightarrow d1]$ .

```
Algorithm AR(r, d_2)
 while i \le n + q do begin
    i:=2; m:=1
 while j < J(i) do begin
                                    U_{[r,d_2]}
if [h[r[d_2 \rightarrow d_1]]
                                                       A_2 then
                        C(i,j)
                                                Ci
     begin
     mark[c(i,j)];
output Action Rule
 [[h[r_{(d_2 \rightarrow d_1)}] \quad (c_i, c_{(i,j)} \rightarrow c_{(i,1)})] \rightarrow [d, d_2 \rightarrow d_1]]
     end
    if [h[r[d_2 \rightarrow d_1]]
                              C(i,j)
                                          U[r,d_2] C_i
                                                              A_1 then
    begin
     \max[c_{(i,j)}];
     output Action Rule
     [[h[r_{(d_2 \rightarrow d_1]}] \quad (c_i, c_{(i,j)})] \rightarrow [d, d_2 \rightarrow d_1]]
    end
    j:=j+1
  end end
    I_k := \{i_k\};
    (where ik - index randomly chosen from \{2, 3, ..., q + n\}).
     for all j_k \leq J(i_k) do [c(i_k,j_k)]_{i_k} l_k := c(i_k,j_k);
    for all i, j such that both sets [c(ik,jk)]ik lk, c(i,j)
     are not marked and
     i
          I_k
     do
     begin
     if [[h[r_{d_2} \rightarrow d_1]]
                                 C(ik,jk) ik lk
                                                        C(i,j)
     U_{[r,d_2]}
                 Ci
                      A_2 then
     begin
     mark [[c(ik,jk)]ik \ lk]
```

output Action Rule

$$[[h[r[d_2 \rightarrow d_1]] \quad [c(ik,jk)]ik \quad k \quad (ci, c(i,j) \rightarrow C(i,1))]$$

$$\rightarrow [d, d_2 \rightarrow d_1]]$$
end

if  $[[h[r[d_2 \rightarrow d_1]] \quad [c(ik,jk)]ik \quad k \quad C(i,j)]] \quad U[r,d_2]$ 

$$Ci \quad A_1$$
then
begin
mark  $[[c(ik,jk)]ik \quad k \quad C(i,j)];$ 

output Action Rule
$$[[h[r[d_2 \rightarrow d_1]] \quad [c(ik,jk)]ik \quad k \quad (ci, c(i,j))] \rightarrow$$

$$[d, d_2 \rightarrow d_1]] \quad [c(ik,jk)]ik \quad k \quad (ci, c(i,j))] \rightarrow$$

$$[d, d_2 \rightarrow d_1]]$$
end
else
begin
$$Ik := Ik \quad \{i\}; [c(ik,jk)]ik \quad k := [c(ik,jk)]ik \quad k \quad C(i,j)$$
end

In most of the classification techniques the classification rules are grouped into clusters of non-conflicting rules. Then all the possible pairs of classification rules in the clusters are used to build the action rules. In ARoGS algorithm the target decision is treated as a seed and then it grabs the remaining classification rules describing them as non-target values and builds decision rules from them. Rules grouped into a seed are only compared with that seed. Therefore, the number of pairs of rules which have to be checked gets reduced.

The confidence of generated action rules depends on the number of remaining objects supporting them.

If  $Sup(r[d_2 \rightarrow d_1]) =$ , then  $r[d_2 \rightarrow d_1]$  can not be used for reclassification of objects. Similarly,  $r[\rightarrow d_1]$  can not be used for reclassification, if  $Sup(r[d_2 \rightarrow d_1]) =$ , for each  $d_2$  where  $d_2 = d_1$ .

## IV. EXPERIMENT AND RESULTS

For execution of our codes of Forest Algorithm to find association rules we choose two data sets: Mammographic Mass Data and Car Evaluation Database. Both are obtained from UCI Machine Learning Repository[5].

We chose UNC Charlotte DSBA cluster as our target server for execution. The Java application was exported as a JAR file and copied on to DSBA cluster. The data sets mentioned above are also copied to cluster server.

Command line interface on DSBA server for all the operations required for the experiment. The predominant commands used were Put, JAR.

University of North Carolina at Charlotte is configured to have 72 nodes. The default size of Hadoop blocks is 64Mb. We did not change this setting for our program execution.

We had two files for each type of data sets chosen. One file for attributes and one file with entire data set. Attributes file is space separated file.

The format of action and association rules output is as stated below:

Meaning when flexibleAttribute1 changes its value from X to Y and flexibleAttribute2 changes value from A to B and stableAttribute1 retains value as C implies that decisionAttribute changes value from F to K with support N1 and confidence being N2%.

Let's see individual data set runs results:

## A. Mammographic data set:

Mammographic data set is donated by M. Elter. This data set can be used to predict the severity (benign or malignant) of a mammographic mass lesion from BI-RADS attributes and the patient's age. This dataset has 6 attributes namely: birads[4], age, shape, margin, density and severity. This data set has 961 instances.[5]

In one of the execution iteration, birads, age, shape were kept as stable attributes. margin, density were kept as flexible attributes. 'severity' was chosen to be our decision attributes. Minimum support was chosen to be 2 and minimum confidence to be 70%.

Our goal is to find results for action and association rules for the action severity changing from benign to malignant i.e 0 to 1. Which means we need to find the changes that required in flexible attributes if the severity is to change from 0 to 1 for minimum support 2 and confidence 70%.

After running MR Forest algorithm program on -mammographic data set we got 2 folders . One for action rules ARoGs output and one for association action rules output.

An example of result for ARoGS is as follows.

(margin,marginN  $\rightarrow$  margin4)^(age,age63  $\rightarrow$  age63)  $\Rightarrow$  (severity,severity0  $\rightarrow$  severity1) 2 [Support: 2.0, Confidence: 100.0%]

This states if margin value changes from N to 4 and age remains same at 63 that implies severity would change from 0 to 1. This action would have support of 2 and confidence 100%.

An example of result for association action rule is as follows

(shape,shape3→shape3)^(density,density3→density3)^(m argin,margin1→margin5) ⇒ (severity,severity0→ severity1) [Support: 2.0, Confidence: 90.0%]

This states if shape and density values remain as they are and margin changes from 1 to 5, severity can change from 0 to 1 with 90% confidence and support being 2.

# Results from log:

	ARoGS	AAR
Total no. of counters	49	50
FILE: Number of bytes read	3055	2331
FILE: Number of bytes written	763850	762769
FILE: Number of read operations	0	0
FILE: Number of large read operations	0	0
FILE: Number of write operations	0	0
HDFS: Number of bytes read	21665	21665
HDFS: Number of bytes written	1648	2216

HDFS: Number of large read operations		ı	
Operations		18	18
operations         2         2           Launched map tasks         5         5           Launched reduce tasks         1         1           Data-local map tasks         5         4           Rack-local map tasks         -         1           Total time spent by all maps in occupied slots (ms)         171822         112118           Total time spent by all reduces in occupied slots (ms)         19730         27956           Total time spent by all map tasks (ms)         85911         56059           Total time spent by all reduce tasks (ms)         9865         13978           Total vcore-seconds taken by all reduce tasks         85911         56059           Total vcore-seconds taken by all reduce tasks         9865         13978           Total megabyte-seconds taken by all reduce tasks         9865         13978           Total megabyte-seconds taken by all reduce tasks         20203520         28626944           Map input records         500         500           Map output pytes         22611         14022           Map output materialized bytes         3607         3053           Input split bytes         660         660           Combine output records         0         0           Combine input records<		0	0
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·	Reduce input groups	169	96
Reduce input records 180 115	Reduce shuffle bytes	3607	3053
	Reduce input records	180	115

Reduce output records	11	16
Spilled Records	360	230
Shuffled Maps	5	5
Failed Shuffles	0	0
Merged Map outputs	5	5
GC time elapsed (ms)	1870	1752
CPU time spent (ms)	31060	10500
Physical memory (bytes) snapshot	3922235392	337205248 0
Virtual memory (bytes) snapshot	23549698048	235097579 52
Total committed heap usage (bytes)	4859625472	458542284 8
File Input Format Counters Bytes Read	21005	21005
File Output Format Counters Bytes Written	1648	2216

### A. Car Evaluation Database

Car Evaluation Database is donated by Marko Bohanec and Blaz Zupan. It was derived from a simple hierarchical decision model originally developed for the demonstration of DEX (M. Bohanec, V. Rajkovic: Expert system for decision making. Sistemica 1(1), pp. 145-157, 1990.)

Because of known underlying concept structure, this database may be particularly useful for testing constructive induction and structure discovery methods. It has 4 classes for Classification. Documentation on everything 1728 instances, 6 attributes ordered nominally. The data set doesn't have any missing values. [5] The 6 attributes in the dataset are: buying, maint, doors, persons, lug\_boot, safety, label.

In one of the execution iteration we chose buying, maint, doors, persons as stable attributes; lug\_boot and label were kept as flexible attributes. 'safety' was chosen to be the decision attribute.

Our goal was to check for action rule : (safety , safetyLow  $\rightarrow$  safetyHigh) meaning what factor of change in attributes impact the car safety to change from low to high .

After running MR Random forest algorithm below are the results.

Example of a resulting action rule:

(maint,maintlow→maintlow)^(persons,persons4→persons4) ^(label,labelunacc → labelgood)^(lug\_boot,lug\_bootsmall → lug\_bootsmall) ⇒ (safety,safetylow → safetyhigh) 2 [Support: 4.0, Confidence: 100.0%]

Above statement means when maint changes from low to high and no. of persons remains at 4 as constant and label changes from unaccounted to good and lug\_boot remains small then it implies safety measure has increased from low to high with Support 4 and confidence 100%.

Example of association action rule output:

(persons,personsmore→personsmore)^(label,labelunacc → labelvgood) ⇒ (safety,safetylow → safetyhigh) [Support: 17.5, Confidence: 81.23%]

The above-mentioned rule states if no. of persons remains more and label changes from unaccounted to very good then it implies that safety measure changes from low to high with support of 17.5 and confidence 81.23%

# Results from log:

	ARoGS	AAR
Total no. of counters	50	49
FILE: Number of bytes read	3664	12871
FILE: Number of bytes written	765263	784243
FILE: Number of read operations	0	0
FILE: Number of large read operations	0	0
FILE: Number of write operations	0	0
HDFS: Number of bytes read	156140	156140
HDFS: Number of bytes written	3515	21281
HDFS: Number of read operations	18	18

HDFS: Number of large read operations	0	0
HDFS: Number of write operations	2	2
Launched map tasks	5	5
Launched reduce tasks	1	1
Data-local map tasks	4	5
Rack-local map tasks	1	
Total time spent by all maps in occupied slots (ms)	509582	213854
Total time spent by all reduces in occupied slots (ms)	22436	22424
Total time spent by all map tasks (ms)	254791	106927
Total time spent by all reduce tasks (ms)	11218	11212
Total vcore-seconds taken by all map tasks	254791	106927
Total vcore-seconds taken by all reduce tasks	11218	11212
Total megabyte-seconds taken by all map tasks	521811968	218986496
Total megabyte-seconds taken by all reduce tasks	22974464	22962176
Map input records	1728	1728
Map output records	201	201
Map output bytes	38090	38090
Map output materialized bytes	4501	4501
Input split bytes	535	535
Combine input records	0	0
Combine output records	0	0
Reduce input groups	183	183
Reduce shuffle bytes	4501	4501
Reduce input records	201	201
Reduce output records	17	17
Spilled Records	402	402

Shuffled Maps	5	5
Sharred Waps	3	
Failed Shuffles	0	0
Merged Map outputs	5	5
GC time elapsed (ms)	3983	3983
CPU time spent (ms)	191430	191430
Physical memory (bytes) snapshot	5157806080	5157806080
Virtual memory (bytes) snapshot	2355459276 8	2355459276 8
Total committed heap usage (bytes)	5950668800	5950668800
File Input Format Counters Bytes Read	155605	155605
File Output Format Counters Bytes Written	3515	3515

#### V. CONCLUSION

In this activity, we implemented Random Forest algorithm from MapReduce framework of Hadoop big data technology to calculate Action Rules based on Grabbing Strategy and Association action rules. Comparing results, we observe that ARoGS job took lesser time than AAR job overall and less complex. The action rules calculation helped us to study how can we can extract novel knowledge by action rules. For car data we could train system and learn how safety measure would increase by other features and for mammographic data we could analyze what parameters reduce the possibility of having malignant tumor.

Since the data set used was between 900-1800 and the number of nodes were 72, it is clear from empirical result that more the nodes, better the performance of action rules jobs. The practical usage of this can be to analyze data of an e-commerce system or shopping site application database to predict possible behavior of customers and gain profit by giving customers recommendations or make them buy similar things grouping the things together. For larger data sets the data block size may further have to be increased to optimize performance. Not only these, there are many other fields with huge database can be benefited from action rules such as medical, financial, stock market, insurance and astrology.

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