

Wupper - a Xilinx Virtex-7 PCle Engine

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Revision History

Revision	Date	Author(s)	Description
3.0	17-05-2019	F. P. Schreuder	Updated some descriptions from the FELIX repository
2.4	06-11-2017	R. Blankers	Added Wishbone bus to the register map
2.3	14-04-2015	F.P. Schreuder	Updated register map, added description for drivers
2.1	14-04-2015	A.O. Borga	Uniformed documentatio naming convention (PCIe Engine)
2.0	21-01-2015	F.P. Schreuder	Updated register map
1.9	09-01-2015	A.O. Borga	Reviewed
1.8	07-01-2015	F.P. Schreuder	Modifications for OpenCores
1.7	29-10-2014	A.O. Borga	Major global revision
1.6	28-10-2014	A.O. Borga	Updated PCIe coregen figures, modified appearance of paths throughout the text, fixed typos, updated the simulation and testing sections, added the interrupt handling section, reversed the order of this table
1.5	23-10-2014	F.P. Schreuder	Updated register map, figures and pepo commands, some cosmetic improvements
1.4	23-09-2014	J.C. Vermeulen	Updated figures
1.3	23-09-2014	F.P. Schreuder	Updated pepo commands for memory allocation
1.2	19-09-2014	F.P. Schreuder	Added All pages of Xilinx core wizard
1.1	19-09-2014	F.P. Schreuder	Applied modifications after Andrea's review
1.0	16-09-2014	F.P. Schreuder	created

1 Supported tools

Wupper had been tested on the following platforms and tools:

- 1. Operating systems:
 - Scientific Linux CERN 6, kernel 2.6
 - Scientific Linux 7, kernel 3.10
- 2. Xilinx Vivado:
 - 2018.1: migrated 05-2019
 - 2015.4: migrated 02-2016
 - 2014.4: initial version
- 3. Xilinx FPGA:
 - Virtex-7 690T
 - Kintex Ultrascale XCKU115

2 Introduction

Wupper¹ is designed for the ATLAS / FELIX project [?], to provide a simple Direct Memory Access (DMA) interface for the Xilinx Virtex-7 PCle Gen3 hard block. The core is not meant to be flexible among different architectures, but especially designed for the 256 bit wide AXI4-Stream interface [4] of the Xilinx Virtex-7 and Ultrascale FPGA Gen3 Integrated Block for PCI Express (PCle) [3] and [5].

The purpose of Wupper is therefore to provide an interface to a standard FIFO. This FIFO has the same width as the Xilinx AXI4-Stream interface (256 bits) and runs at 250 MHz. The user application side of the FPGA design can simply read or write to the FIFO; Wupper will handle the transfer into Host PC memory, according to the addresses specified in the DMA descriptors. Several descriptors can be queued, up to a maximum of 8, and they will be processed sequentially one after the other.

Another functionality of Wupper is to manage a set of DMA descriptors, with an address, a $read/\overline{write}$ flag, the transfersize (number of 32 bit words) and an enable line. These descriptors are mapped as normal PCle memory or IO registers. Besides the descriptors and the enable line (one per descriptor), a status register for every descriptor is provided in the register map.

The high level structure of the core has been designed in HDL Works Ease [7], however this program generates readable VHDL output. Design entry tools are useful to give a graphical view of the HDL project, however it can be more convenient to use the VHDL code itself. Therefore both the Ease project, as well as the output from Ease are supplied in the Wupper repository. In order to use Wupper it is not necessary to obtain a copy of Ease.

For synthesis and implementation of the Xilinx specific IP cores, it is recommend to use the latest Xilinx Vivado release as listed in section 1. The cores (FIFO, clock wizard and PCle) are provided in the Xilinx .xci format, as well as the constraints file (.xdc) is in the Vivado Format.

For portability reasons, no Xilinx project files will be supplied with the core, but a bundle of TCL scripts has been supplied to create a project and import all necessary files, as well as to do the synthesis and implementation. These scripts will be described later in this document.

¹The person performing the act of bongelwuppen, the Gronings version of the famous Frisian sport of the Fierljeppen (canal pole vaulting) https://nds-nl.wikipedia.org/wiki/Nedersaksische_sp%C3%B6llegies#Bongelwuppen

3 Core Architecture

Xilinx has introduced the AXI4-Stream interface [4] for the PCIe EndPoint core: a simplified version of the ARM AMBA AXI bus [?]. This interface does not contain any address lines, instead the address and other information are supplied in the header of each PCIe Transaction Layer Packet (TLP). Figure 1 shows the structure of the Wupper_core design. The Wupper_core is divided in two parts:

1. DMA Control:

This is the entity in which the Descriptors are parsed and fed to the engine, and where the Status register of every descriptor can be read back through PCIe. Depending on the address range of the descriptor, the pointer of the current address is handled by DMA Control and incremented every time a TLP completes. DMA Control also handles the circular buffer DMA if this is requested by the descriptor (See 3.2).

DMA control contains a register map, with addresses to the descriptors, status registers and external registers for the user space register map.

2. DMA Read Write:

This entity contains two processes:

- ToHost / Add Header: In the first process the descriptors are read and a header according to the descriptor is created. If the descriptor is a ToHost descriptor, the payload data is read from the FIFO and added after the header.
- FromHost / Strip Header: In the second process the header of the received data is removed and the length is checked; then the payload is shifted into the FIFO.

Both processes can fire an MSI-X type interrupt by means of the interrupt controller when finished.

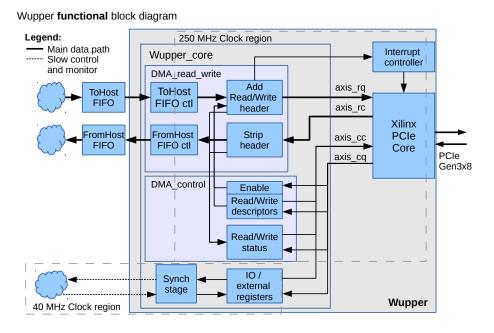


Figure 1: Structure of the Felix PCle Engine

Figure 1 shows a synchronization stage for the IO and external registers, The user space registers are stored and processed in the 40 MHz clock domain in order to relax timing closure of the design. The synchronization stage synchronizes the register map again to the clock used in the application design.

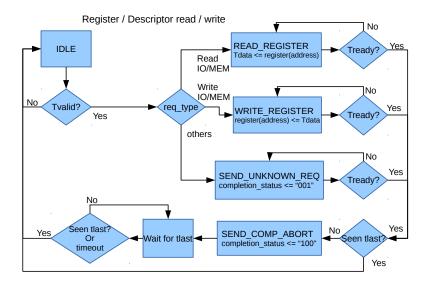


Figure 2: Flow of a Register / Descriptor Read or Write process

The DMA Control process (see Figure 2) always responds to a request with a certain req_type from the server. It responds only to IO and Memory reads and writes; for all other request types it will send an unknown request reply. If the data in the payload contains more than 128 bits, the process will send a "completion abort" reply and go back to idle state. The maximum register size has been set to 128 bits because this is a useful maximum register size; it is also the maximum payload that fits in one 250 MHz clock cycle of the AXI4-Stream interface.

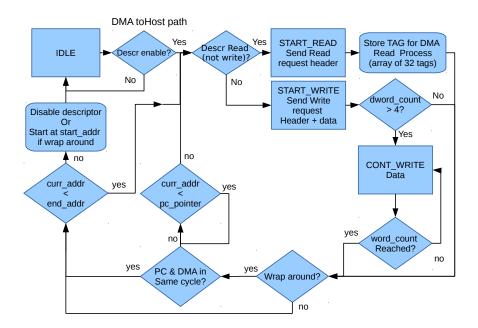


Figure 3: Flow of the DMA ToHost path, this process also handles FromHost requests

The DMA ToHost (see Figure 3) process reads the current descriptor and requests a read or write to the server memory. If the descriptor is set to ToHost, it also initiates a FIFO read and adds the data into the payload of the PCIe TLP (Transaction Layer Packet). When the descriptor is set to FromHost this process only creates a header TLP with no payload, to request a certain amount of data from the server memory that fits in one TLP.

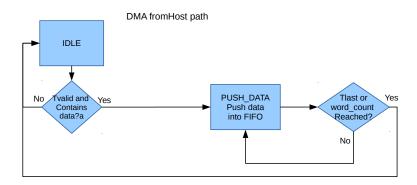


Figure 4: Flow of the DMA From Host process

The DMA FromHost (See Figure 4) process checks the size of the payload against the size in the TLP header, the data will be pushed into the FromHost FIFO.

3.1 DMA descriptors

Each transfer To and From Host is achieved by means of setting up descriptors on the server side, which are then processed by Wupper. The descriptors are set in the BAR0 section

of the register map (see Appendix??). An extract of the descriptors and their registers is shown in Table 2 below.

Address	Name/Field	Bits	Туре	Description
0×0000 D			SC_0	
	END_ADDRESS	127:64	W	End Address
	START_ADDRESS	63:0	W	Start Address
0×0010	DMA_DESC_0a			
	RD_POINTER	127:64	W	server Read Pointer
	WRAP_AROUND	12	W	Wrap around
	READ_WRITE	11	W	1: FromHost/ 0: ToHost
	NUM_WORDS	10:0	W	Number of 32 bit words
0x0200 DMA_DESC_STATUS_0				
	EVEN_PC	66	R	Even address cycle server
	EVEN_DMA	65	R	Even address cycle DMA
	DESC_DONE	64	R	Descriptor Done
	CURRENT_ADDRESS	63:0	R	Current Address
0×0400	DMA_DESC_ENABLE	7:0	W	Enable descriptors 7:0. One
				bit per descriptor. Cleared
				when Descriptor is handled.

Table 2: DMA descriptors types

Every descriptor has a set of registers, with the following specific functions:

- DMA_DESC: the register containing the start (start_address) and the end (end_address) memory addresses of a DMA transfer; both handled by the server (software API).
- DMA_DESC_a: integrates the information above by adding (i) the status of the read pointer on the server side (rd_pointer), (ii) the wrap around functionality enabling (wrap_around, see Section 3.2 below), (iii) the FromHost ("1") and ToHost ("0") transfer direction bit (read_write), and (iv) the number of 32 bits words to be transferred (num_words)
- DMA_DESC_STATUS: status of a specific descriptor including (i) wrap around information bits (even_pc and even_dma), (ii) completion bit (desc_done, (iii) DMA pointer current address (current_address)
- DMA_DESC_ENABLE: the descriptors enable register (dma_desc_enable), one bit per descriptor

3.2 Endless DMA with a circular buffer and wrap around

In $single\ shot$ transfer, the DMA ToHost process continues sending data TLPs (Transaction Layer Packets) until the end address $(end_address)$ is reached. The server can check the status of a certain DMA transaction by looking at the $desc_done$ flag and the $current_address$. Another possible operation mode is the so- called $endless\ DMA$: the DMA continues its action and starts over (wrap-around) at start address $(start_address)$ whenever the end address $(end_address)$ is reached. The second mode is enabled by asserting the wrap-around $(wrap_around)$ bit. In this mode the server has to provide another address named server pointer $(PC_read_pointer)$: indicating where it has last read out the memory. After wrapping around the DMA core will transfer To Host memory until the $PC_read_pointer$ is reached. The server read pointer should be updated more often than

the wrap-around time of the DMA, however it should not be read too often as that would take up all the bandwidth, limiting the speed of the DMA transfer in progress. A typical rule of thumb to determine what "too often" means is that software should not update the pointer every clock cycle, but rather after processing a block of a few kB of data.

In order to determine whether Wupper is processing an address behind or in front of the server, Wupper keeps track of the number of wrap around occurrences. In the DMA status registers the even_cycle bits displays the status of the wrap-around cycle. In every even cycle (starting from 0), the bits are 0, and every wrap around the status bits will toggle. The $even_pc$ bit flags a $PC_read_pointer$ wrap-around, the $even_dma$ a Wupper wrap-around. By looking at the wrap-around flags the server can also keep track of its own wrap-arounds. Note that while in the $endless\ DMA$ mode $(wrap_around\ bit\ set)$, the $PC_read_pointer$ has to be maintained by the server (software API) and kept within the start and end address range for Wupper to function correctly. Figure 5 below shows a diagram of the two pointers racing each other, and the different scenarios in which they can be found with respect to each other.

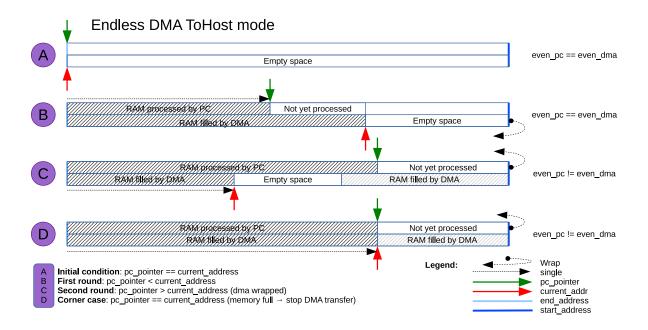


Figure 5: Endless DMA buffer and pointers representation diagram in ToHost mode

Looking at Figure 5 above, the following scenarios can be described:

- A: start condition, both the server and the DMA have not started their operation.
- B: normal condition, the PC_read_pointer stays behind the DMA's current_address
- \bullet C : normal condition, the DMA's current_address has wrapped around and has to stay behind the PC_read_pointer
- D: the server is reading too slow, the DMA is stalled because the server read pointer is not advancing fast enough, the DMA current_address has to stay behind.

If the DMA descriptor is set to FromHost, the comparison of the even bits is inverted, as the server has to fill the buffer before it is processed in the same cycle. In this mode the $pc_read_pointer$ is also maintained by the software API, however it is indicating the address up to where the server has filled the memory. In the first cycle the DMA has to stay behind the read pointer, when the server has wrapped around, the DMA can process memory up to $end_address$ until it also wraps around.

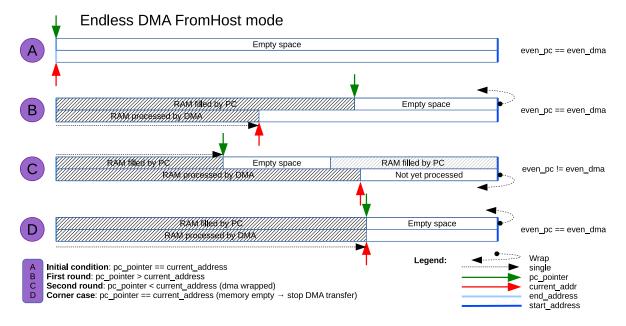


Figure 6: Endless DMA buffer and pointers representation diagram in FromHost mode

Looking at Figure 6 above, the following scenarios can be described:

- A: start condition, both the server and the DMA have not started their operation.
- B: normal condition, the DMA's current_address stays behind the PC_read_pointer
- ullet C: normal condition, the PC_read_pointer has wrapped around and has to stay behind the DMA's current_address
- D: the server is writing too slow, the DMA is stalled because the server read pointer is not advancing fast enough, the DMA current_address has to stay behind.

3.3 Interrupt controller

Wupper is equipped with an interrupt controller supporting the MSI-X (Message Signaled Interrupt eXtended) as described in "Chapter 17: Interrupt Support" page 812 and onwards of [22]. In particular the chapter and tables in "MSI-X Capability Structure".

The MSI-X Interrupt table contains eight interrupts; this number can be extended by a generic parameter in the firmware. Four of the interrupts, [0..3], are dedicated to Wupper, four interrupts, [4..7], are called from the Central Router. The interrupts are detailed in Table 3.

Table 3: PCle interrupts

Interrupt	Name	Description
0	FromHost wrap around	This interrupt is fired when the FromHost descriptor reaches the end address, or wraps around
1	ToHost wrap around	This interrupt is fired when the ToHost descriptor reaches the end address, or wraps around
2	ToHost Available	Fired when data becomes available in the ToHost FIFO (falling edge of ToHostFifoProgEmpty)
3	FromHost Full	Fired when the FromHost FIFO becomes full (rising edge of FromHostAppFifoProgFull)
4	Test interrupt #4	Fired when writing data the register INT_TEST_4
5	reserved	
6	reserved	
7	reserved	

Interrupts 0 to 3 are used by the API when controlling the DMA controller and handling the descriptors. Interrupt 0 and 1 have the same functionality, but serve in the other direction (ToHost and FromHost). These interrupts fire when the END_ADDRESS in the corresponding descriptor was reached. In single shot mode DMA this means that the DMA transfer has completed, at this point also the DESCRIPTOR_DONE bit in the descriptor status register is set to 1. In circular DMA mode, interrupt 0 and 1 are also set every time the END_ADDRESS is reached, indicating that the DMA controller wraps back to START_ADDRESS, but continues operation.

Interrupt 2 is fired when enough data has arrived in the ToHost fifo to fill at least one TLP of data.

Interrupt 3 is fired when the FromHost fifo reaches the prog full state, this is a usual thing to happen as the threshold of this fifo is set at a low level. The API does not need to take any action on this interrupt as the Wupper core will regulate itself.

Interrupt 4 is a special test interrupt that can be fired by writing the interrupt test register in the register map.

A description of how the software is initializing and handling the interrupts is described in Section ??.

3.4 Wishbone

The Wishbone protocol is a design method to connect IP cores with a common interface. The Wishbone can be used for soft, firm core or hard core IP and can be used with the VHDL language. The main purpose is to make an interconnection between IP cores and make it more compatible with each other.

The Wishbone bus is added because of a needed connection between the register map of the Wupper core and an external SLAVE. In this connection a Wishbone crossbar is added so that multiple SLAVEs can be attached. As a SLAVE example a 32 bits block memory was added. The memory has a data input to receive and a data output to send the data back to the crossbar.

The wupper_to_wb.vhd makes Wupper data Wishbone compatible. Also, two FIFOs are added to synchronize the Wupper clock with an external clock. One FIFO is to send data from Wupper to the crossbar. And one FIFO is to receive data from the crossbar to the Wupper.

The system controller makes the external clock and the external reset Wishbone compatible.

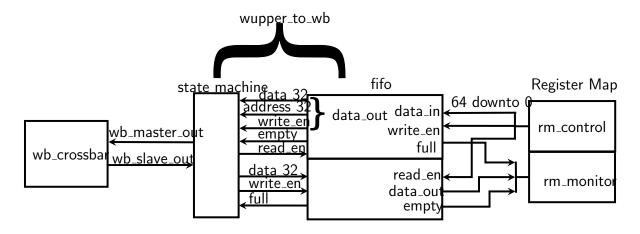


Figure 7: Block diagram of Wupper to Wishbone

4 Xilinx PCIe EndPoint Core

Wupper is based on the interface of the Virtex-7 FPGA Gen3 Integrated Block for PCI Express v3.0 [5]. This core is using a PCIe hard block in the Virtex-7 FPGA. The hard block is equipped with an AXI4-Stream interface.

4.1 Xilinx AXI4-Stream interface

The interface has the advantage that it has two separate bidirectional AXI4-Stream interfaces. The two interfaces are the requester interface, with which the FPGA issues the requests and the PC replies, and the completer interface where the PC takes initiative.

bus	Description	Direction	
axis_rq	Requester reQuest. This interface is used for DMA, the	$FPGA \to PC$	
	FPGA takes the initiative to write to this AXI4-Stream in-		
	terface and the PC has to answer.		
axis_rc	R equester C ompleter. This interface is used for DMA reads $PC \rightarrow FPGA$		
	(from PC memory to FPGA), this interface also receives a		
	reply message from the PC after a DMA write.		
<code>axis_cq</code> Completer reQuest. This interface is used to write the DMA $ PC \rightarrow F $		$PC \to FPGA$	
	descriptors as well as some other registers.		
axis_cc	Completer Completer. This interface is used as a reply inte-	$FPGA \to PC$	
	face for register reads, as well as a reply header for a register		
	write.		

Table 4: AXI4-Stream streams

4.2 Configuration of the core

The Xilinx PCIe EndPoint core is configured as a PCI express Gen3 (8.0GT/s) End Point with 8 lanes and the Physical Function (PF0) max payload size is set to 1024 bytes. AXI-ST Frame Straddle is disabled and the client tag is enabled. All other options are set to default, the reference clock frequency is 100MHz and the only option for the AXI4-Stream interface is 256 bit at 250MHz, see Figures 8 to 18.

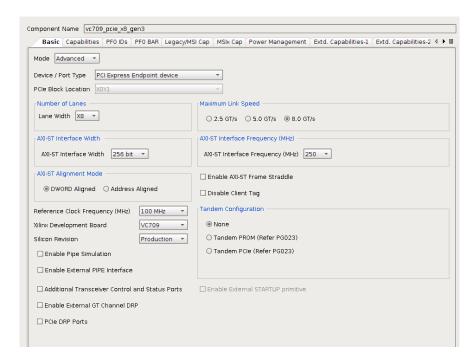


Figure 8: PCle core configuration in Vivado [Basic]

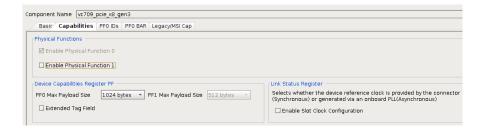


Figure 9: PCIe core configuration in Vivado [Capabilities]

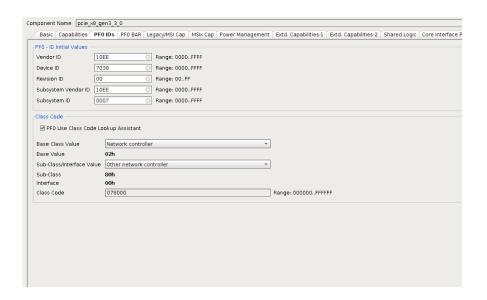


Figure 10: PCle core configuration in Vivado [PF0 IDs]

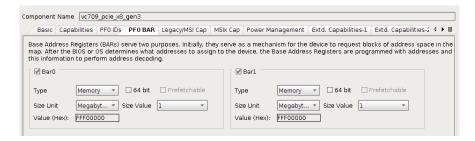


Figure 11: PCle core configuration in Vivado [PF0 BAR]

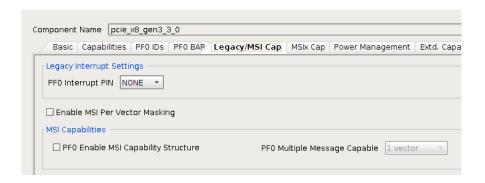


Figure 12: PCle core configuration in Vivado [Legacy/MSI Cap]

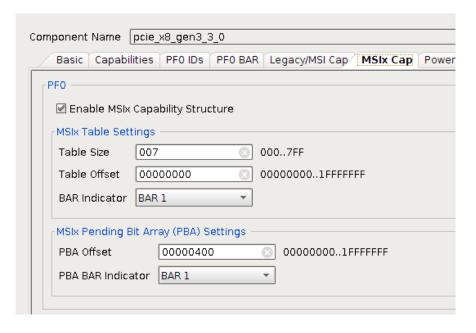


Figure 13: PCle core configuration in Vivado [MSIx]

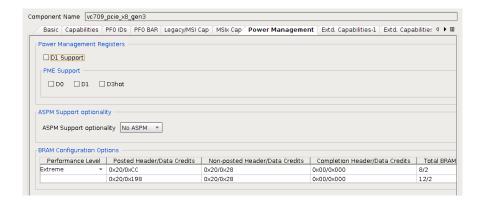


Figure 14: PCIe core configuration in Vivado [Power Management]

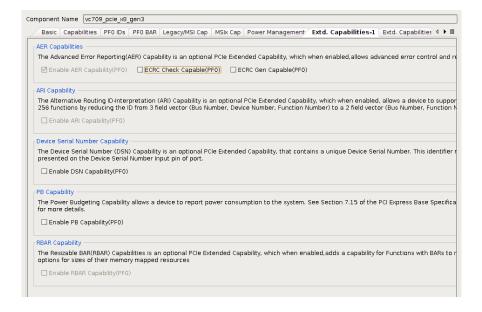


Figure 15: PCIe core configuration in Vivado [Extd. Capabilities 1]

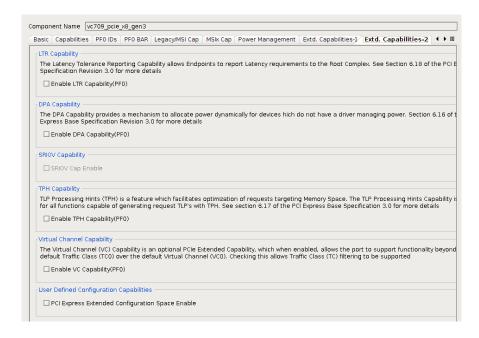


Figure 16: PCIe core configuration in Vivado [Extd. Capabilities 2]

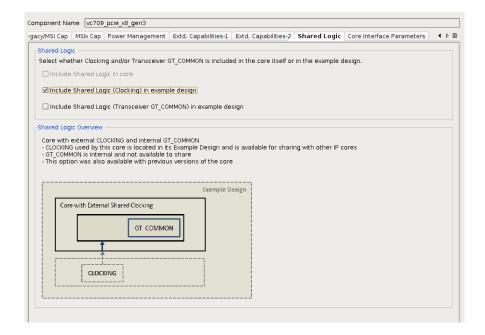


Figure 17: PCIe core configuration in Vivado [Shared LogicMSIx]

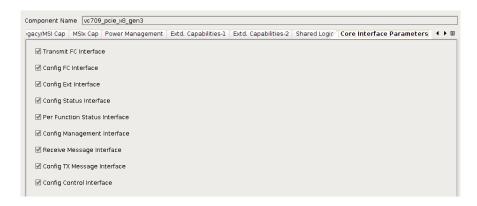


Figure 18: PCIe core configuration in Vivado [Core Interface Parameters]

5 Obtaining and building the PCle Engine

The repository is divided in several directories:

directory	contents
firmware/constraints	Contains an XDC file with Vivado constraints in-
	cluding Chipscope ILA definitions, may differ over
	different commits
firmware/output	Empty placeholder where bit files will be generated
firmware/Projects	Empty placeholder where the Vivado projects will
	be generated
firmware/scripts/pcie_dma_top	This directory contains two scripts to create the
	vivado project and to run synthesis and implemen-
	tation, see later this chapter.
firmware/simulation/pcie_dma_top	Contains a Modelsim.ini project as well as the
	scripts project.do, VSim_Functional.tcl and start.do
	to run the simulation in Modelsim (or Questasim)
firmware/sources/pcie	This directory contains the Vivado core (.xci) defi-
	nition file for the PCIe core, as well the PCIe Engine
	files.
firmware/sources/shared	Contains a Vivado .xci file for the clock generator
	and the toplevel vhdl file.
firmware/sources/application	Contains an example vhdl file for a simple applica-
	tion
firmware/sources/packages	Contains a vhdl package with some type definitions,
	but more importantly the application specific reg-
	ister definitions.

Table 5: Directories in the repository

Please note that if changes to any of the core are made, a manual copy of the relevant .xci file in *firmware/Projects/pcie_dma_top/pcie_dma_top.srcs/sources_1/ip* should be made to the relevant folder in */firmware/sources*.

5.1 Check out the svn repository

Before starting to work with this core, it is a good idea to check out the whole svn repository, if you already have it, update to the latest revision.

 $\verb|svn| co| \verb|http://opencores.org/ocsvn/virtex7_pcie_dma/virtex7_pcie_dma/trunk| \\$

besides the firmware directory with the listing in the introduction of this chapter, you will find other directories:

• **documentation** contains this document as well as a doxygen script to document the firmware structure.

hostSoftware

- **driver** contains the wupper and cmem driver, described in 7.1
- wupper_tools contains several useful tools to control DMA, the registers and application specific example tools
- wupper_gui contains an example application specific GUI application

5.2 Create the Vivado Project

The Vivado project is not supplied in the svn tree, instead a .tcl script is provided to generate the project. To create the project, open Vivado without a project, then open the TCL console and run the following commands.

Listing 2: Create Vivado Project

```
cd /path/to/svn/checkout/firmware/scripts/Wupper/
source ./vivado_import_virtex7.tcl
```

A project should now be created in *firmware/Projects/*. **beware that this script will overwrite and recreate the project if it exists already.**

After the project is created you still have to generate the core's output products. Go to the project manager, in the IP Cores tab select all cores, right click one and select "generate output products".

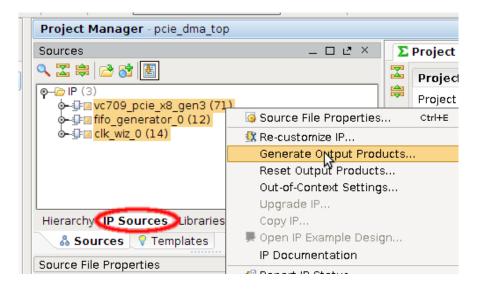


Figure 19: Generate IP Cores output products

5.3 Running synthesis and implementation

When the project has been created, you can simply press the buttons to run synthesis and implementation of the design, but a tcl script has been created to run these steps automatically. Additionally the script will create the bitfile in the <code>firmware/output</code> directory, as well as an .mcs file and an .ltx file, containing the ChipScope ILA probes. All those 3 files have a timestamp in their filename so any previous synthesis output will be maintained. The script can simply be executed if the project is open.

Listing 3: start synthesis / implementation

cd /path/to/svn/checkout/firmware/scripts/Wupper/
source ./do_implementation_VC709.tcl

6 Simulation

The directory *firmware/simulation/pcie_dma_top* contains all necessary files to run the simulation in Mentor Graphics Modelsim or Questasim [12].

6.1 Prerequisites

The directory contains a file modelsim.ini with some standard information, it is assumed that one have the Xilinx Unisim_VCOMPONENTS library compiled and the location is defined in the environment variable \$XILLIB. Also the Library "work" has to be created in the project directory.

The simulation project also relies on a simulation model of the FIFOcore, which will be generated when the cores in the Vivado project are generated. The file that should be generated is ../../Projects/pcie_dma_top/pcie_dma_top.srcs/sources_1/ip/fifo_generator_0/fifo_generator_0_funcsim.vhdl

6.2 Creating the project and running the simulation.

Like the Vivado project, also the Questasim project is generated and operated using .tcl scripts. To create and run the project execute the following commands from the Questasim console:

Listing 4: Run the simulation

```
cd firmware/simulation/Wupper/
#Create the project:
do project.do
#Start the simulation and load the waveforms:
do VSim_Functional.tcl
#Add stimuli to the AXI bus
do start.do
run 1us
```

The project does not include the actual Xilinx PCIe core simulation model, but the AXI4-Stream interface altered by stimuli in start.do, it can be edited according to your needs.

7 Software and Device drivers

The Wupper tools communicate with the Wupper core through the Wupper device driver. Buffers in the host PC memory are used for bidirectional data transfers, this is done by a part of the driver called CMEM. This will reserve a chunk of contiguous memory in the host. For the specific case of the example application, the allocated memory will be logically subdivided in two buffers (buffer 1 and buffer 2 in Figure ??). One buffer is used to store data coming from the FPGA (write buffer, buffer 1), the other to store the ones going to the FPGA (read buffer, buffer 2). The idea behind the logical split of the memory in buffers is that those buffers can be used to copy data from the write to read, and perform checks. The driver is developed for Scientific Linux CERN 6 but has been tested and used also under Ubuntu kernel version 3.13.0-44a. Building and loading/unloading the driver is explained in 7.1.

In this chapter we assume that the card is loaded with the latest firmware, it has been placed in a Gen3 PCle slot and the PC is running Linux. Optionally a Vivado hardware server can be connected to view the Debug probes of the ILA cores, as specified in the constraints file. [13]

7.1 Building / Loading the drivers

The Drivers for Wupper consist of two parts. The first part is the cmem driver, this driver allocates a contiguous block of RAM in the PC memory which can be used for the DMA transfers.

The second part is the Wupper driver which allows access to the DMA descriptors and the registermap.

Listing 5: Building and Loading the driver

```
#build the driver
cd trunk/hostSoftware/driver
./makedrivers
# load the driver
sudo scripts/drivers_wupper start
# see status of the driver
sudo scripts/drivers_wupper status
# unload the driver
sudo scripts/drivers_wupper stop
```

7.2 Driver functionality

Before any DMA actions can be performed, one or more memory buffers have to be allocated. The driver in conjunction with the wupper tools take this into account.

The application has to do two important tasks for a DMA action to occur.

- Allocate a buffer using the CMEM driver
- Create and enable the DMA descriptor.

If the buffer is for instance allocated at address 0x00000004d5c00000, initialize bits 64:0 of the descriptor with 0x00000004d5c00000, and end address (bit 127:64) 0x00000004d5c00000 plus the write size. If a <u>DMA Write</u> is to be performed, initialize bits 10:0 of descriptor 0a

with 0x40 (for 256 bytes per TLP, depending on the PC chipset) and bit 11 with '0' for write, then enable the corresponding descriptor enable bit at address 0x400. The TLP size of 0x40 (32 bit words) is limited by the maximum TLP that the PC can handle, in most cases this is 256 bytes, the Engine can handle bigger TLP's up to 4096 bytes.

Listing 6: Create a Write descriptor

If a <u>DMA Read</u> of 1024 bytes (0x100 DWords) from PC memory is to be performed at address 0x00000004d5d00000, initialize bits 64:0 of the descriptor with 0x00000004d5d00000, and bits [127:64] with 0x00000004d5d00400. Initialize bits 10:0 of descriptor 0 with 0x100 and bit 11 with '1' for read, then enable the corresponding descriptor enable bit at address 0x400. The TLP size of 0x100 is limited by the maximum TLP size of the Xilinx core, set to 1024 bytes, 0x100 words.

Listing 7: Create a Read descriptor

7.3 Reading and Writing Registers and setting up DMA

The PCIe Engine has a register map with 128 bit address space per register, however registers can be read and written in words of 32, 64, 96 or 128 bits at a time. The addresses of the register have an offset with respect to a Base Address Register (BAR) that can be readout running: The PCIe Engine has 3 different BAR spaces all with their own memory map.

BAR0 is the memory area which contains registers that are related to DMA operations. The most important registers are the descriptors.

BAR1 is the memory area which contains registers that are related to Interrupt vectors. BAR2 is the user memory area, it contains some example registers which can be implemented per the requirements for the user / application.

7.4 Wupper tools

The Wupper tools are a collection of tools which can be used to debug and control the Wupper core. These tools are command line programs and can only run if the device driver is loaded. A detailed list and explanation of each tool is given in the next paragraphs. Some

tools are specific to the example VHDL application, some other tools are more generic and can directly be used to control the Wupper DMA core, the Wupper-dma-transfer and Wupper-chaintest had been added as features for the OpenCores' benchmark example application. As mentioned before, the purpose of those applications is to check the health of the Wupper core.

The Wupper tools can be found in the directory hostSoftware/wupper_tools.

The Wupper tools collection comes with a readme [11], this explains how to compile and run the tools. Most of the tools have an -h option to provide helpful information.

Listing 8: Building Wupper Tools

```
cd trunk/hostSoftware/wupper_tools
mkdir build
cd build
cmake ..
make
```

The build directory should now contain the following tools. All the tools come with a "-h" option to show a help message.

Tool	Description
Wupper-info	Prints information of the device. For instance device ID,
	PLL lock status of the internal clock and FW version.
Wupper-reset	Resets parts of the example application core. These func-
	tions are also implemented in the Wupper-dma-transfer
	tool.
Wupper-config	Shows the PCIe configuration registers and allows to set,
	store and load configuration. An example is configuring
	the LED's on the VC-709 board by writing a hexadecimal
	value to the register.
Wupper-irq-test	Tool to test interrupt routines
Wupper-dma-test	This tool transfers every second 1024 Byte of data and
	dumps it to the screen.
Wupper-throughput	The tool measures the throughput of the Wupper core.
	The method of computing the throughput is wrong, this is
	discussed in the section 3.4.2.
Wupper-dump-blocks	This tools dumps a block of 1 KB. The iteration is set
	standard on 100. This can be changed by adding a number
	after the "-n".

7.4.1 Operating Wupper-dma-transfer

Wupper-dma-transfer sends data to the target PC via Wupper also known as half loop test. This tool operates the benchmark application and has multiple options. A list of such options is summarized in Listing 9.

Listing 9: Output of Wupper-dma-transfer -h

```
daqmustud@gimone:$ ./wupper-dma-transfer -h
Usage: wupper-dma-transfer [OPTIONS]
This application has a sequence:
1 -Start with dma reset(-d)
2 -Flush the FIFO's (-f)
3_-Then_reset_the_application_(-r)
Options:
-l___Load_pre-programmed_seed.
-q_____Load_and_generate_an_unique_seed.
-g_____Generate_data_from_PCIe_to,PC.
-b____Generate_data_from_PC_to_PCIe.
-s____Show_application_register.
-r_____Reset_the_application.
-f____Flush_the_FIFO's.
-d
             Disable and reset the DMA controller.
-h
             Display help.
```

Before using the write function, make sure that the application is ready by resetting all the values, as shown in Listing 10.

Listing 10: Reset Wupper before a DMA Write action

```
daqmustud@gimone:$ ./wupper-dma-transfer -d
Resetting the DMA controller...DONE!
daqmustud@gimone:$ ./wupper-dma-transfer -f
Flushing the FIFO's...DONE!
daqmustud@gimone:$_./wupper-dma-transfer_-r
resetting_application...DONE!
```

Before writing data into the PC, the data generator needs a seed to initialize the generator. There are two options available: load a unique seed or load a pre-programmed seed. The pre-programmed seed is always 256 bits, the unique seed value can be variable. The -s option displays the status of the register including the seed value. For a unique seed, replace the -I with -q, as shown in Listing 11.

Listing 11: Loading a pre-programmed seed in to the data generator.

The -g option performs a DMA write to the PC memory. The data generator starts to fill the down FIFO and from the PC side, a DMA read action is performed. The size of the transfer is set to 1 MB by default, but the size is configurable. When the PC receives 1 MB of data, the transfer stops. It is possible that there is still some data left in the down FIFO, resetting the FIFO's can be done by the -f option, as shown in Listing 12.

Listing 12: Start generating data to the target.

```
daqmustud@gimone:$ ./wupper-dma-transfer -g
Starting DMA write
done DMA write
Buffer 1 addresses:
0: EED9733362A50D71
...
...
```

In a similar way a DMA read action from the FPGA can be performed by using the -b option. The output of the up FIFO is fed to a multiplier. The output of the multiplier is fed to the down FIFO with a destination to the PC memory as shown in Listing 13.

Listing 13: Performing a DMA read and DMA write

```
daqmustud@gimone:$ ./wupper-dma-transfer -b
Reading data from buffer 1...
DONE!
Buffer 2 addresses:
0: 24BBEC63B53F3BCC
...
...
...
```

7.4.2 Operating Wupper-chaintest

The Wupper-chaintest tool does in one shot a complete DMA Read and Write transfer. It checks if the multiplied data is done correctly. This is done by multiplying the data in buffer 2 and compare the output of the multiplier in buffer 1 (shown earlier in Figure ??). The tool returns the number of errors out of 65536 loops as shown in Listing 14.

Listing 14: Output of Wupper-chaintest

```
daqmustud@gimone:$ ./wupper-chaintest
Reading data from buffer 1...
DONE!
Buffer 2 addresses:
0: 49A5A89745420D34
...
...
9: 5D37679AE79FA7C2
0 errors out of 65536
```

7.5 Wupper GUI

The Wupper Gui is a dedicated application for the example vhdl application, as described in 8. The concept of the Wupper GUI is based on the Wupper tools and has the same construction (see Figure 20). The GUI is developed with Qt version 5.5 (C++ based) [15] and gives the user a visual feedback of the Wupper's status/health. The GUI can only run if the device driver is loaded.

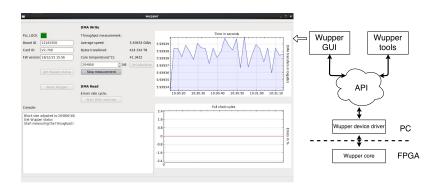


Figure 20: High and low level software overview block diagram.

7.5.1 Functional blocks and threaded programming

Multi-threading is used so functional blocks can run at the same time as the GUI. If multi-threading is not used, the GUI interface gets stuck. A thread starts a new process next to the main process. If another processor core is available, the thread will run on a separated core. By communicating via slots to the main process, the data is secured. There are two threads but only one of the threads can be used at the same time. The reason is that both threads use the same DMA ID, this will cause an error. The threads communicate with the Application Program Interface (API) to control and fetch the output of the logic. The output data communicate safely via a signal to the slots. Figure 21 shows an overview of the threaded programs in the Wupper GUI.

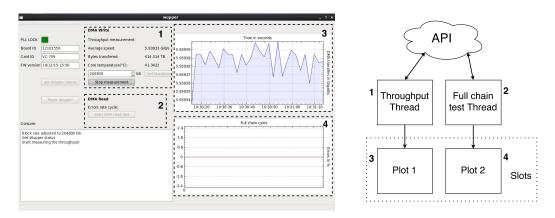


Figure 21: Threaded programs in the Wupper GUI

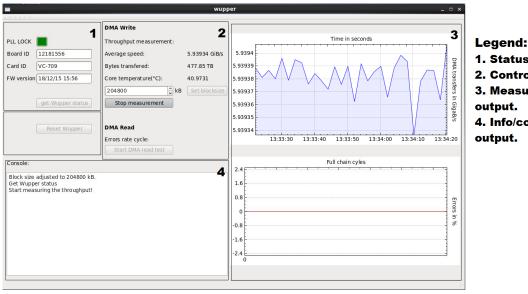
7.5.2 **GUI** operation

The GUI is separated in four regions (see Figure 22): status, control, measurement and an info region. The status region fetches the information about various parts of the FPGA on the VC-709 via the Wupper core, and about the core itself. When the user clicks on the "get Wupper status" button, it shows the internal PLL lock status, Board ID, Card ID and the firmware version.

The control region controls the logic inside Wupper through the API. The "Reset Wupper" button resets the application logic by resetting the DMA, flushing the FIFO's and reset the application values.

In the DMA Write section, the user can perform a DMA Write measurement. The user can configure the blocksize. The blocksize has effect on the speed, this is discussed in Appendix B. The measurement output is shown in the measurement region. The method of computing the throughput is different than the method of the Wupper-throughput tool. The fault is the wrong order of operations by misplacing brackets. The wrong method is A/B*C=D instead of A/(B*C)=D.

In a similar way, the user can perform a DMA Read test and the output is shown in the plot in the measurement region. The info/console output region gives the user feedback of the application and the GUI.



- 1. Status region.
- 2. Control region.
- 3. Measurement
- 4. Info/console

Figure 22: Screenshot of the example application GUI

8 Example application HDL modules

The example application, the user application inside the FPGA, replaces the counter with a pseudo-random data generator. Moreover the new feature in the application has the possibility to process data from the PC memory. A more detailed report about the example application can be found in [23]

The example application can be operated in two modes:

- 1. The random data generator directly sends data to the host via Wupper, this is referred to as "write only" or "half loop" test.
- 2. The content of the random data generator is wrote back to the FPGA, multiplied and sent to host again, this is referred as "read and write" or "full loop" test.

The example application is developed in VHDL, and the code is synthesized and implemented in Xilinx Vivado 2015.4 [16]. The example application is now part of the Wupper package on OpenCores.

8.1 Functional blocks

Figure 23 shows a detailed block diagram of the example application for Wupper. The Wupper core contains a list of addresses, this list is the register map. The values of the register map are implemented in the firmware as signals. The PC sees the signals as addresses. Wupper tools write values to these addresses which control the FPGA logic (see dashed lines in Figure 23).

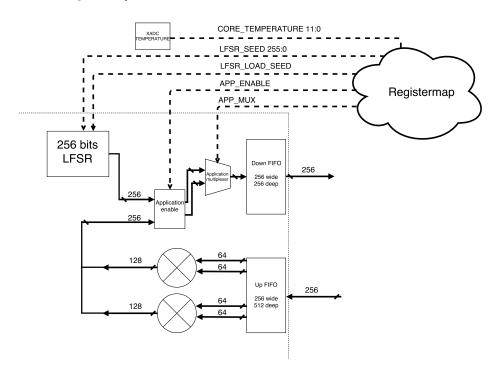


Figure 23: Overview of the example application

As introduced in the previous paragraph, one type of test possible with the example application is the "half loop": in such mode of operation, Wupper is fed by a random data generator based on a 256 bits Linear Feedback Shift Register (LFSR). An LFSR, as shown in Figure 24, consists of a number of shift registers which are fed back to the input. The feedback is manipulated by an XOR operation which creates a pseudo-random pattern. The ideal goal is to produce a sequence with a infinite length to prevent repetition. Repetition occurs by two factors, the feedback points/taps and the start value. The maximal length sequence can be approached by 2^n-1 [18]. Where the n is the number of shift registers. The 256 bits LFSR is a four stage Galois LFSR with taps at the registers 256, 254,251 and 246. The approach is explained in paper [19] by R. W. Ward and T.C.A. Molteno of the electronics group at the University of Otago. The software tools developed for the example application initialize the seed value by writing it to the register map thereafter the 1-bit $LFSR_LOAD_SEED$ signal is set to 1. This resets the LFSR process with a seed value.

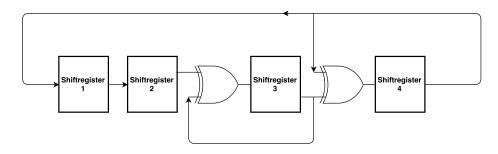


Figure 24: A 4 bit Linear Feedback Shift Register (LFSR)

For multiplication, the Xilinx multiplier IP block is used. The operations are based on the DSP48E1 [20] for the Virtex-7 series. There are two parallel multipliers used with two unsigned 64-bit inputs. To make the multiplier perform optimally at high clock rates, an 18 stage pipelining is used.

For monitoring the core temperature, a XADC IP block [21] is used. This is generated by Vivado's XADC wizard. The output signal of the block is connected to one register of the register map.

The 1-bit signal APP_MUX is attached to the select port of the application multiplexer. This enables the data flow to the down FIFO.

The signal APP_ENABLE enables the output of the LFSR and the multiplier. The 2-bits signal has three states:

- "00": No data flow, application is on standby.
- "01": Makes the example application enable 'high' causing data to flow only from the LFSR.
- "10": Makes the example application enable 'high' causing data to flow only from the multiplier.

The FIFO's are generated by Vivado's FIFO generator and using integrated common clock block RAMs. The clock is set to 250 MHz to reach the maximum theoretical throughput. The up FIFO is deeper to function as a buffer. This is an extra precaution. The reason is if the data is looped back in the application, both FIFO's can be full at the same time. If this occurs, the application stalls because of the loop back.

9 Customizing the application

9.1 connection of the DMA FIFOs

Wupper comes with an example application that is described in 8. The toplevel file for the user application is application.vhd

If you want to customize the example application for your own needs, the application can be stripped down to only containing the two FIFO cores. The application can be controlled and monitored by the records "registermap_control" and "registermap_monitor". These records contain all the read/write register and the read only registers respectively, the registers are defined in the file pcie_package.vhd.

This file contains a read and a write port for a FIFO. This FIFO has a port width of 256 bit and is read or written at 250 MHz, resulting in a theoretical throughput of 60Gbit/s.

9.2 Application specific registers

Besides DMA memory reads and writes, the PCle Engine also provides means to create a custom application specific register map. By default, the BAR2 register space is reserved for this purpose.

Listing 15: custom register types

```
type register_map_control_type is record
      STATUS_LEDS
                                     : std_logic_vector(7 downto 0);
            -- Board GPIO Leds
      LFSR SEED 0
                                     : std_logic_vector(63 downto 0);
           -- Least significant 64 bits of the LFSR seed
      LFSR SEED 1
                                    : std_logic_vector(63 downto 0);
           -- Bits 127 downto 64 of the LFSR seed
      LFSR_SEED_2
                                    : std_logic_vector(63 downto 0);
           -- Bits 191 downto 128 of the LFSR seed
      LFSR_SEED_3
                                    : std_logic_vector(63 downto 0);
          -- Bits 255 downto 192 of the LFSR seed
                                     : std_logic_vector(0 downto 0);
      APP_MUX
           -- Switch between multiplier or LFSR.
           * 0 LFSR
          * 1 Loopback
     LFSR_LOAD_SEED
                                     : std_logic_vector(64 downto 64);
          -- Writing any value to this register triggers the LFSR
         module to reset to the LFSR_SEED value
                                    : std_logic_vector(0 downto 0);
      APP_ENABLE
           -- 1 Enables LFSR module or Loopback (depending on APP_MUX)
      -- 0 disable application
      I2C WR
                                     : bitfield_i2c_wr_t_type;
                                     : bitfield_i2c_rd_t_type;
      I2C RD
      INT TEST 4
                                     : std logic vector(64 downto 64);
          -- Fire a test MSIx interrupt #4
      INT_TEST_5
                                    : std_logic_vector(64 downto 64);
          -- Fire a test MSIx interrupt #5
end record;
```

The VHDL files containing the registermap are not supposed to be modified by hand. Instead WupperCodeGen can be used.

Inside the source tree you will find the directory WupperCodeGenScripts containing the YAML file with application specific registers, and a set of scripts to generate VHDL sources, C++ headers and Latex and HTML documentation.

- registers-1.0.yaml: This is the database of registers
- build-doc.sh Run this script to generate the table of registers in A
- **build-firmware.sh** Regenerate the firmware (pcie_control.vhd and pcie_package.vhd) from the yaml file
- build-software.sh Regenerate the sources in software/regmap from the yaml file.

For more information see the documentation in software/wuppercodegen/doc

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```
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```

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Appendix A WUPPER register map, version 2.0

Starting from the offset address of BAR0, BAR1 and BAR2, the register map for BAR0 expands from 0x0000 to 0x0430 for the PCle control registers. BAR0 only contains registers associated with DMA. The offset for BAR0 is usually 0xFBB00000.

Address	PCle	Name/Field	Bits	Туре	Description
		Bar()		1
		DMA_D	ESC		
0×0000	0,1	DMA_DESC_0			
		END_ADDRESS	127:64	W	End Address
		START_ADDRESS	63:0	W	Start Address
0×0010	0,1	DMA_DESC_0a			
		SW_POINTER	127:64	W	Pointer controlled by the software, indicating read or write status for circular DMA
		WRAP_AROUND	12	W	Wrap around
		FROMHOST	11	W	1: fromHost/ 0: toHost
		NUM_WORDS	10:0	W	Number of 32 bit words
0×00E0	0,1	DMA_DESC_7			
		END_ADDRESS	127:64	W	End Address
		START_ADDRESS	63:0	W	Start Address
0×00F0	0,1	DMA_DESC_7a		1	1
		SW_POINTER	127:64	W	Pointer controlled by the software, indicating read or write status for circular DMA
		WRAP_AROUND	12	W	Wrap around
		FROMHOST	11	W	1: fromHost/ 0: toHost
		NUM_WORDS	10:0	W	Number of 32 bit words
		DMA_DESC.	STATUS		
0×0200	0,1	DMA_DESC_STATUS_0		1	
		EVEN_PC	66	R	Even address cycle PC
		EVEN_DMA	65	R	Even address cycle DMA
		DESC_DONE	64	R	Descriptor Done
		FW_POINTER	63:0	R	Pointer controlled by the firmwarre, indicating where the DMA is busy reading or writing
0×0270	0,1	DMA_DESC_STATUS_7			
UXUZ1U	0,1	EVEN_PC	66	R	Even address cycle PC
		EVEN_DMA	65	R	Even address cycle PC Even address cycle DMA
		DESC_DONE	64	R	Descriptor Done
		FW_POINTER	63:0	R	Pointer controlled by the firmwarre, indicating where the DMA is busy reading or writing
0×0300	0,1	BAR0_VALUE	31:0	R	Copy of BAR0 offset reg.
0×0310	0,1	BAR1_VALUE	31:0	R	Copy of BAR1 offset reg.

Address	PCle	Name/Field	Bits	Туре	Description
0×0320	0,1	BAR2_VALUE	31:0	R	Copy of BAR2 offset reg.
0×0400	0,1	DMA_DESC_ENABLE	7:0	W	Enable descriptors 7:0. One bit per descriptor. Cleared when Descriptor is handled.
0×0410	0,1	DMA_FIFO_FLUSH	any	Т	Flush (reset). Any write clears the DMA Main output FIFO
0×0420	0,1	DMA_RESET	any	Т	Reset Wupper Core (DMA Controller FSMs)
0×0430	0,1	SOFT_RESET	any	Т	Global Software Reset. Any write resets applications, e.g. the Central Router.
0×0440	0,1	REGISTER_RESET	any	Т	Resets the register map to default values. Any write triggers this reset.
0×0450	0,1	FROMHOST_FULL_THRESH		1	
		THRESHOLD_ASSERT	22:16	W	Assert value of the FromHost programmable full flag
		THRESHOLD_NEGATE	6:0	W	Negate value of the FromHost programmalbe full flag
0×0460	0,1	TOHOST_FULL_THRESH			
		THRESHOLD_ASSERT	27:16	W	Assert value of the ToHost programmable full flag
		THRESHOLD_NEGATE	11:0	W	Negate value of the ToHost programmalbe full flag
0×0470	0,1	BUSY_THRESHOLD_ASSERT	63:0	W	Tohost or Fromhost busy will be asserted in circular DMA mode when the server PC buffer gets full (space below ASSERT threshold)
0×0480	0,1	BUSY_THRESHOLD_NEGATE	63:0	W	Tohost or Fromhost busy will be negated in circular DMA mode when the server PC buffer gets less full (space above NEGATE threshold).
0×0490	0,1	BUSY_STATUS			
		FROMHOST_BUSY	1	R	A fromhost descriptor passed BUSY_THRESHOLD_ASSER busy flag set
		TOHOST_BUSY	0	R	A tohost descriptor passed BUSY_THRESHOLD_ASSER' busy flag set

Address	PCle	Name/Field	Bits	Туре	Description
0×04A0	0,1	PC_PTR_GAP	63:0	W	This is the minimum value that the pc_pointer in a descriptor has to decrease in order to flip the evencycle_pc bit

Table 6: FELIX register map BAR0

BAR1 stores registers associated with the Interrupt vector. The offset for BAR1 is usually $0 \times FBA00000$.

Address	PCle	Name/Field	Bits	Туре	Description
		Bar1			
		INT_VEC			
0×0000	0,1	INT_VEC_0			
		INT_CTRL	127:96	W	Interrupt Control
		INT_DATA	95:64	W	Interrupt Data
		INT_ADDRESS	63:0	W	Interrupt Address
0×00F0	0,1	INT_VEC_15			
		INT_CTRL	127:96	W	Interrupt Control
		INT_DATA	95:64	W	Interrupt Data
		INT_ADDRESS	63:0	W	Interrupt Address
0x0100	0,1	INT_TAB_ENABLE	7:0	W	Interrupt Table enable Selectively enable Interrupts

Table 7: FELIX register map BAR1

BAR2 stores registers for the control and monitor of HDL modules inside the FPGA other than Wupper. A portion of this register map's section is dedicated for control and monitor of devices outside the FPGA; as for example simple SPI and I2C devices. The offset for BAR2 is usually 0xFB900000.

Address	PCle	Name/Field	Bits	Туре	Description			
	Bar2							
		Generic Board Info	ormation					
0×0000	0	REG_MAP_VERSION	15:0	R	Register Map Version, 2.0 formatted as 0x0200			
0×0010	0	BOARD_ID_TIMESTAMP	39:0	R	Board ID Date / Time in BCD format YYMMDDhhmm			
0×0020	0	GIT_COMMIT_TIME	39:0	R	Board ID GIT Commit time of current revision, Date / Time in BCD format YYMMDDhhmm			
0×0030	0	GIT₋TAG	63:0	R	String containing the current GIT TAG			
0×0040	0	GIT_COMMIT_NUMBER	31:0	R	Number of GIT commits after current GIT_TAG			
0×0050	0	GIT_HASH	31:0	R	Short GIT hash (32 bit)			
0×0060	0	STATUS_LEDS	7:0	W	Board GPIO Leds			
0×0070	0	GENERIC_CONSTANTS						
		INTERRUPTS	15:8	R	Number of Interrupts			
		DESCRIPTORS	7:0	R	Number of Descriptors			

Address	PCle	Name/Field	Bits	Туре	Description
0x0080	0	CARD_TYPE	63:0	R	Card Type: - 105 (0x069): KCU-105 - 128 (0x080): VCU128 - 180 (0x0B4): VMK180 - 709 (0x2c5): VC-709 - 710 (0x2c6): HTG-710 - 711 (0x2c7): BNL-711 - 712 (0x2c8): BNL-712
0×0090	0	PCIE_ENDPOINT	0	R	Indicator of the PCIe endpoint on BNL71x cards with two endpoints. 0 or 1
0×00A0	0	NUMBER_OF_PCIE_ENDPOINTS	1:0	R	Number of PCIe endpoints on the card. The VCU128 cards have 2 endpoints
		House Keeping Controls	And Moi	nitors	
0×1300	0	MMCM_MAIN_PLL_LOCK	0	R	Main MMCM PLL Lock Status
0×1310	0	I2C_WR		T =	A
		I2C_WREN	any	Т	Any write to this register triggers an I2C read or write sequence
		I2C_FULL	25	R	I2C FIFO full
		WRITE_2BYTES	24	W	Write two bytes
		DATA_BYTE2	23:16	W	Data byte 2
		DATA_BYTE1	15:8	W	Data byte 1
		SLAVE_ADDRESS	7:1	W	Slave address
		READ_NOT_WRITE	0	W	READ/jo¿WRITEj/o¿
0×1320	0	I2C_RD		T -	
		I2C_RDEN	any	Т	Any write to this register pops the last I2C data from the FIFO
		I2C_EMPTY	8	R	I2C FIFO Empty
		I2C_DOUT	7:0	R	I2C READ Data
0×1330	0	FPGA_CORE_TEMP	11:0	R	XADC temperature monitor for the FPGA CORE for Virtex7 temp (C)= ((FPGA_CORE_TEMP* 503.975)/4096)-273.15 for Kintex Ultrascale temp (C)= ((FPGA_CORE_TEMP* 502.9098)/4096)-273.8195
0×1340	0	FPGA_CORE_VCCINT	11:0	R	XADC voltage measurement VCCINT = (FPGA_CORE_VCCINT *3.0)/4096

Address	PCle	Name/Field	Bits	Туре	Description
0×1350	0	FPGA_CORE_VCCAUX	11:0	R	XADC voltage measurement VCCAUX = (FPGA_CORE_VCCAUX *3.0)/4096
0×1360	0	FPGA_CORE_VCCBRAM	11:0	R	XADC voltage measurement VCCBRAM = (FPGA_CORE_VCCBRAM *3.0)/4096
0×1370	0,1	FPGA_DNA	63:0	R	Unique identifier of the FPGA
0×1800	0	INT_TEST		•	
		TRIGGER	any	Т	Fire a test MSIx interrupt set in IRQ
		IRQ	3:0	W	Set this field to a value equal to the MSIX interrupt to be fired. The
					write triggers the interrupt immediately.
0×1810	0	DMA_BUSY_STATUS	<u> </u>	1	meerupe ininiculately.
0/1010		CLEAR_LATCH	any	Т	Any write to this register
		ENABLE	4	W	clears TO- HOST_BUSY_LATCHED Enable the DMA buffer
					on the server as a source of busy
		TOHOST_BUSY_LATCHED	3	R	A tohost descriptor has passed BUSY_THRESHOLD_ASSE in the past, busy flag was
		FROMHOST_BUSY_LATCH	HE2D	R	set A fromhost descriptor has passed BUSY_THRESHOLD_ASSE in the past, busy flag was
		FROMHOST_BUSY	1	R	Set A fromhost descriptor passed BUSY_THRESHOLD_ASSE busy flag set
		TOHOST_BUSY	0	R	A tohost descriptor passed BUSY_THRESHOLD_ASSE busy flag set
		Wishbone	!		
0×2000	0	WISHBONE_CONTROL			
		WRITE_NOT_READ	32	W	wishbone write command wishbone read command
		ADDRESS	31:0	W	Slave address for Wishbone bus
0×2010	0	WISHBONE_WRITE	1	1	A A ISHIDOHE DUS
J. 1010	Ĭ	WRITE_ENABLE	any	Т	Any write to this register triggers a write to the
					Wupper to Wishbone fifo

Address	PCle	Name/Field	Bits	Туре	Description
		DATA	31:0	W	Wishbone
0×2020	0	WISHBONE_READ			
		READ_ENABLE	any	Т	Any write to this register triggers a read from the Wishbone to Wupper fifo
		EMPTY	32	R	Indicates that the Wishbone to Wupper fifo is empty
		DATA	31:0	R	Wishbone read data
0×2030	0	WISHBONE_STATUS			
		INT	4	R	interrupt
		RETRY	3	R	Interface is not ready to accept data cycle should be retried
		STALL	2	R	When pipelined mode slave can't accept additional transactions in its queue
		ACKNOWLEDGE	1	R	Indicates the termination of a normal bus cycle
		ERROR	0	R	Address not mapped by the crossbar

Table 8: FELIX register map BAR2

Appendix B Benchmark: block size versus write speed

The Wupper GUI makes it possible for the users to configure the block size value. This appendix shows how much effect the block size have on the write speed.

During a DMA write action (FPGA \rightarrow PC), a transfer request is transferred from the host to the FPGA, therefore a write descriptor is setup. This descriptor contains information such as memory addresses, direction and the size of the payload, i.e. the amount of data to be transfered. The descriptor is then handled by Wupper, and the data transfer to host initiated. The size of the payload is in this case also the block size. For example when users choose to have a block size of 1 KB, the request gets completed after 1 KB of data had been transferred to host. Subsequently a new header will be created and repeated until the throughput measurement is stopped by the user. A plot of the block size versus write speed is shown below in Figure 25. One can clearly observe from this plot that the block size have effect on the write speed. This is somehow expected as there is an overhead due to the request of those blocks, hence the more data get transfer per request, the better the PCle bandwidth is exploited. The bigger the block size is, the faster the write speed gets. The throughput obviously saturates at a level close to the theoretical maximum speed defined by an 8 lane PCle Gen3 link (64 Gbps).

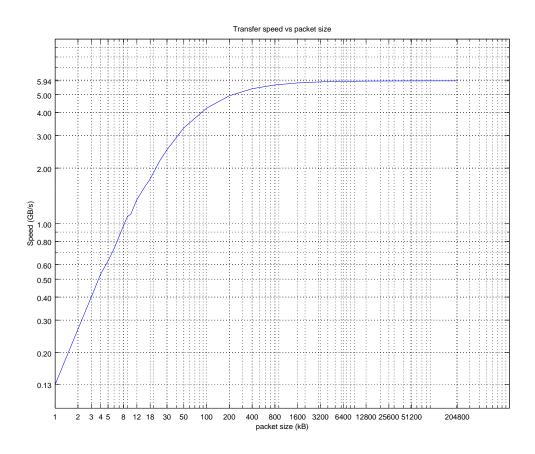


Figure 25: Transfer speed vs packet size