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```
%%Question 1:
% System 1 and 2
A = [0 1; 1 0];
B1 = [0; -2];
B2 = [0;2];
C = [1 \ 0];
% Controllability test
rank(ctrb(A,B1))
rank(ctrb(A,B2))
% Observability testU
rank(obsv(A,C))
ans =
  2
ans =
  2
ans =
  2
```

Question 3

a)

```
A = [-2 4; 1 1];
b = [1;1];
C = [1 0];
eig(A);

syms s
C*inv(s*eye(2)-A)*B;
```

b)

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