

# Multiagent decision making: Repeated Games



# Outline

- **Introduction to Repeated games**
- Finitely-repeated games
- Infinitely-repeated games
- Folk Theorem
- Replicator dynamics



# Repeated Games

- What happens if we play the same normal-form game over and over?



# Repeated Games

- Questions we will need to answer in repeated games:
  - Can agents **observe** other agent's actions?
  - Can agents **remember** the past?
  - What is the agent's **utility** for the whole game?

# Repeated Games

- Some of the questions will have **different answers** for:
  - **Finitely-repeated games**
  - **Infinitely-repeated games**
- The normal-form game that we play repeatedly is called the **stage game**

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- **Finitely-repeated games**
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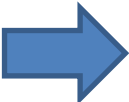
# Finately-Repeated Games

- How can we analyze a **repeated game with a finite number of repetitions?**
  - We can model this game as an **extensive-form game with imperfect information**
    - At each round, **players do not know what the other players have done, but afterward, they do**
    - **The overall payoff function is additive:** the sum of payoffs in stage games

# Finely-Repeated Games

- Let us analyze the Prisoner's Dilemma in a two-stage game

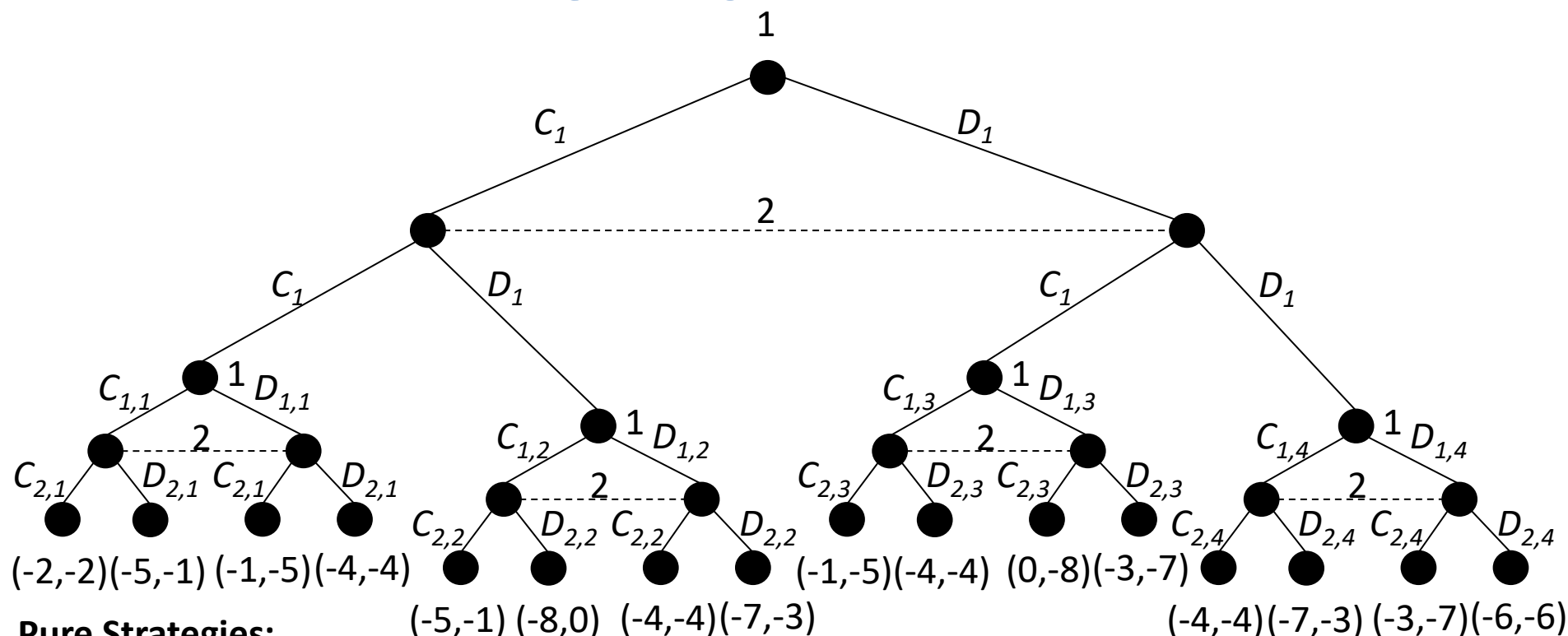
	<i>C</i>	<i>D</i>
<i>C</i>	-1, -1	-4, 0
<i>D</i>	0, -4	-3, -3



	<i>C</i>	<i>D</i>
<i>C</i>	-1, -1	-4, 0
<i>D</i>	0, -4	-3, -3



# Finately-Repeated Games



**Pure Strategies:**

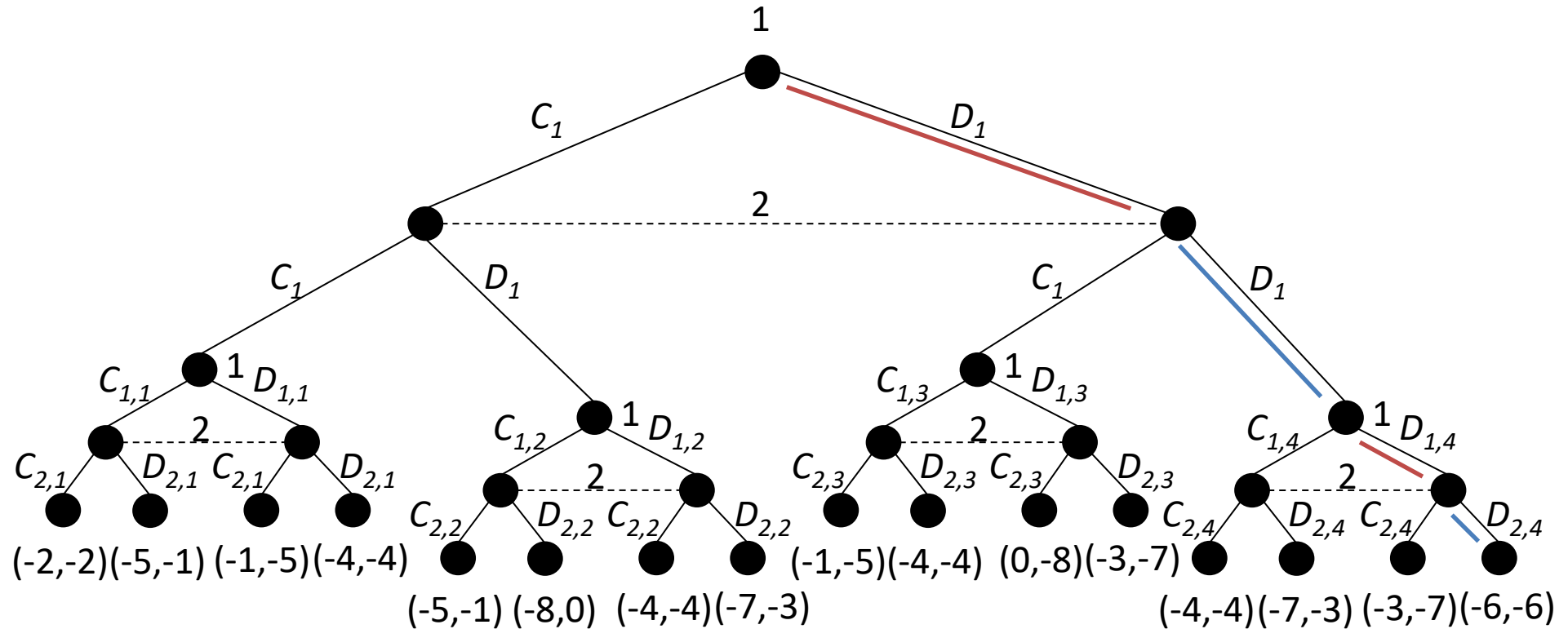
Agent 1:

$\{(C_1, C_{1,1}), (C_1, D_{1,1}), (C_1, C_{1,2}), (C_1, D_{1,2}), (C_1, C_{1,3}), (C_1, D_{1,3}), (C_1, C_{1,4}), (C_1, D_{1,4}),$   
 $(D_1, C_{1,1}), (D_1, D_{1,1}), (D_1, C_{1,2}), (D_1, D_{1,2}), (D_1, C_{1,3}), (D_1, D_{1,3}), (D_1, C_{1,4}), (D_1, D_{1,4})\}$

Agent 2:

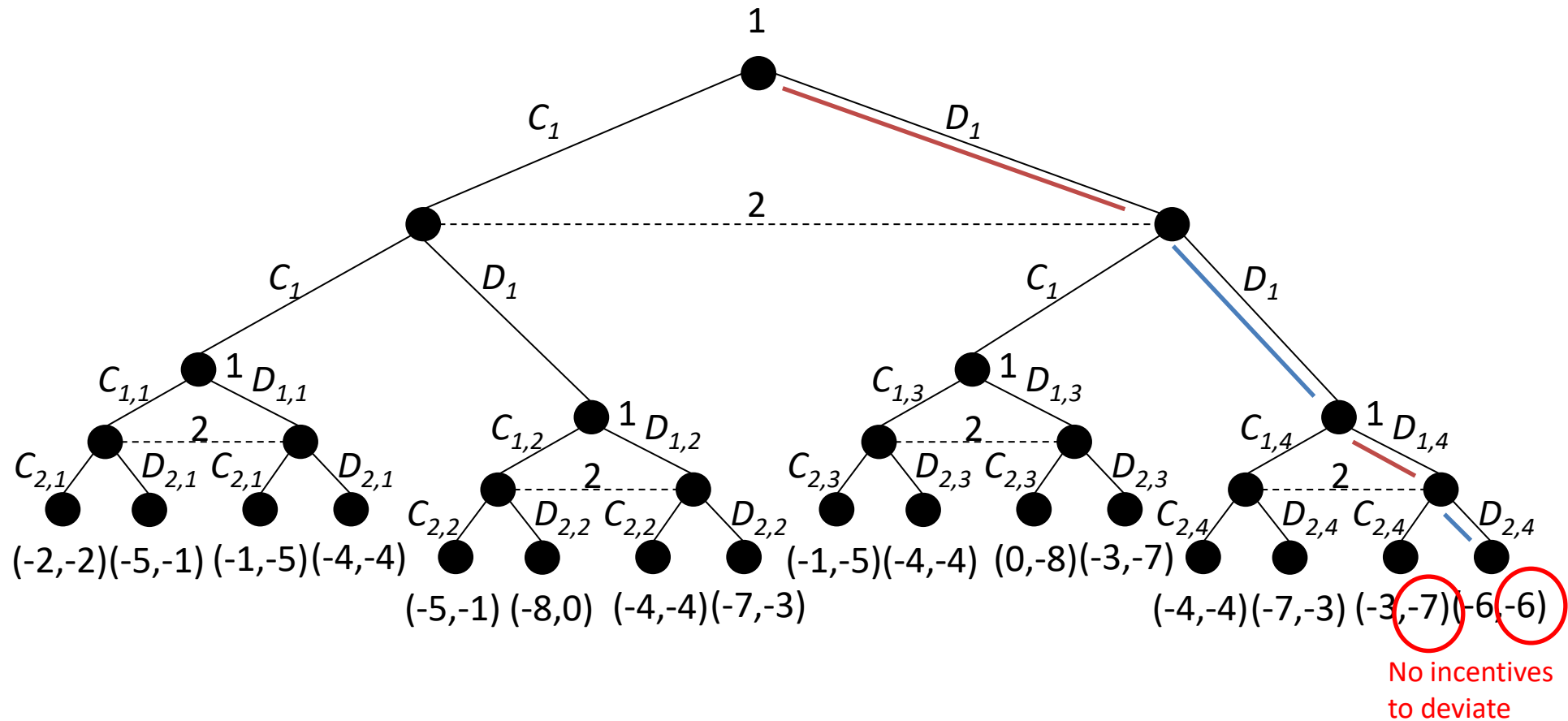
$\{(C_1, C_{2,1}), (C_1, D_{2,1}), (C_1, C_{2,2}), (C_1, D_{2,2}), (C_1, C_{2,3}), (C_1, D_{2,3}), (C_1, C_{2,4}), (C_1, D_{2,4}),$   
 $(D_1, C_{2,1}), (D_1, D_{2,1}), (D_1, C_{2,2}), (D_1, D_{2,2}), (D_1, C_{2,3}), (D_1, D_{2,3}), (D_1, C_{2,4}), (D_1, D_{2,4}),\}$

# Finely-Repeated Games



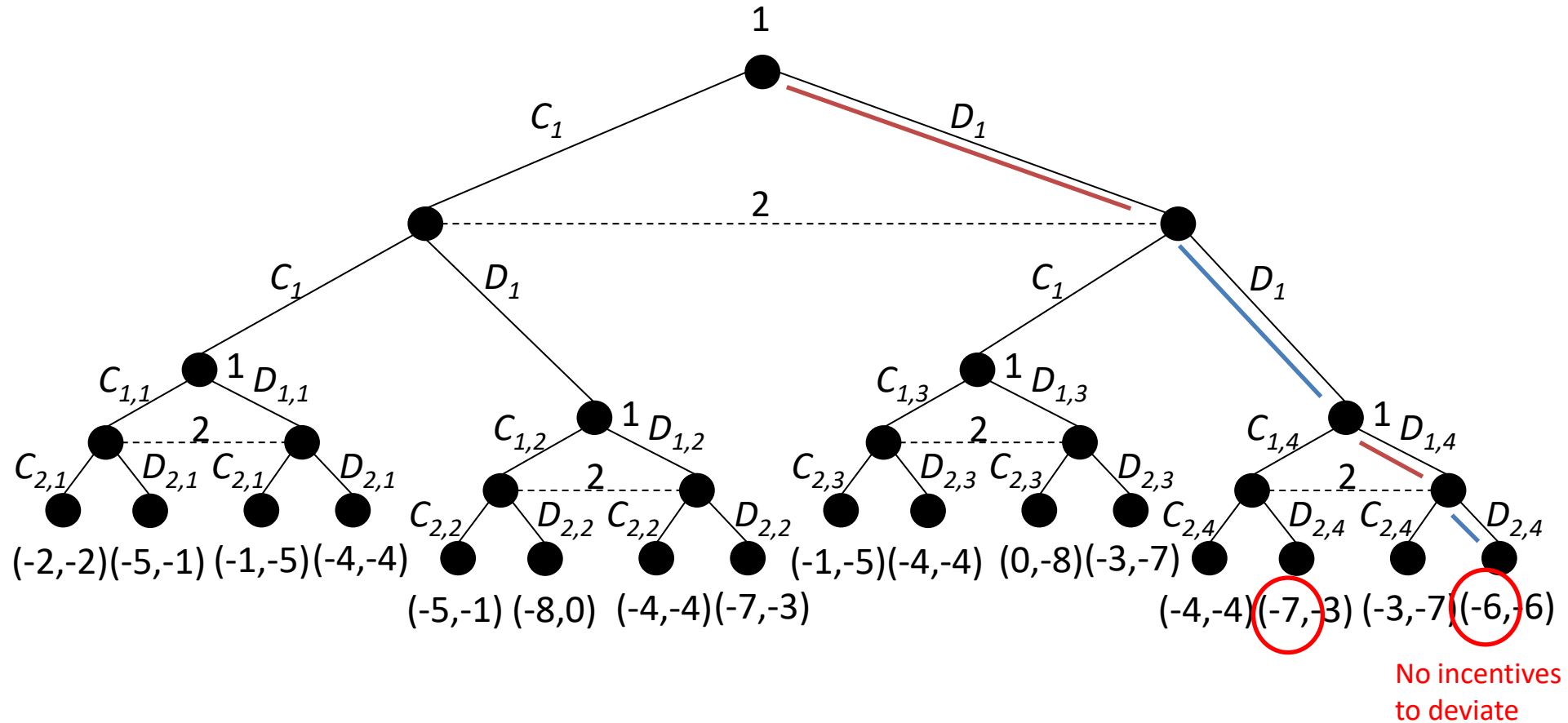
Is the strategy profile  $(D_1, D_{1,4}), (D_1, D_{2,4})$  a Nash equilibrium?

# Finely-Repeated Games



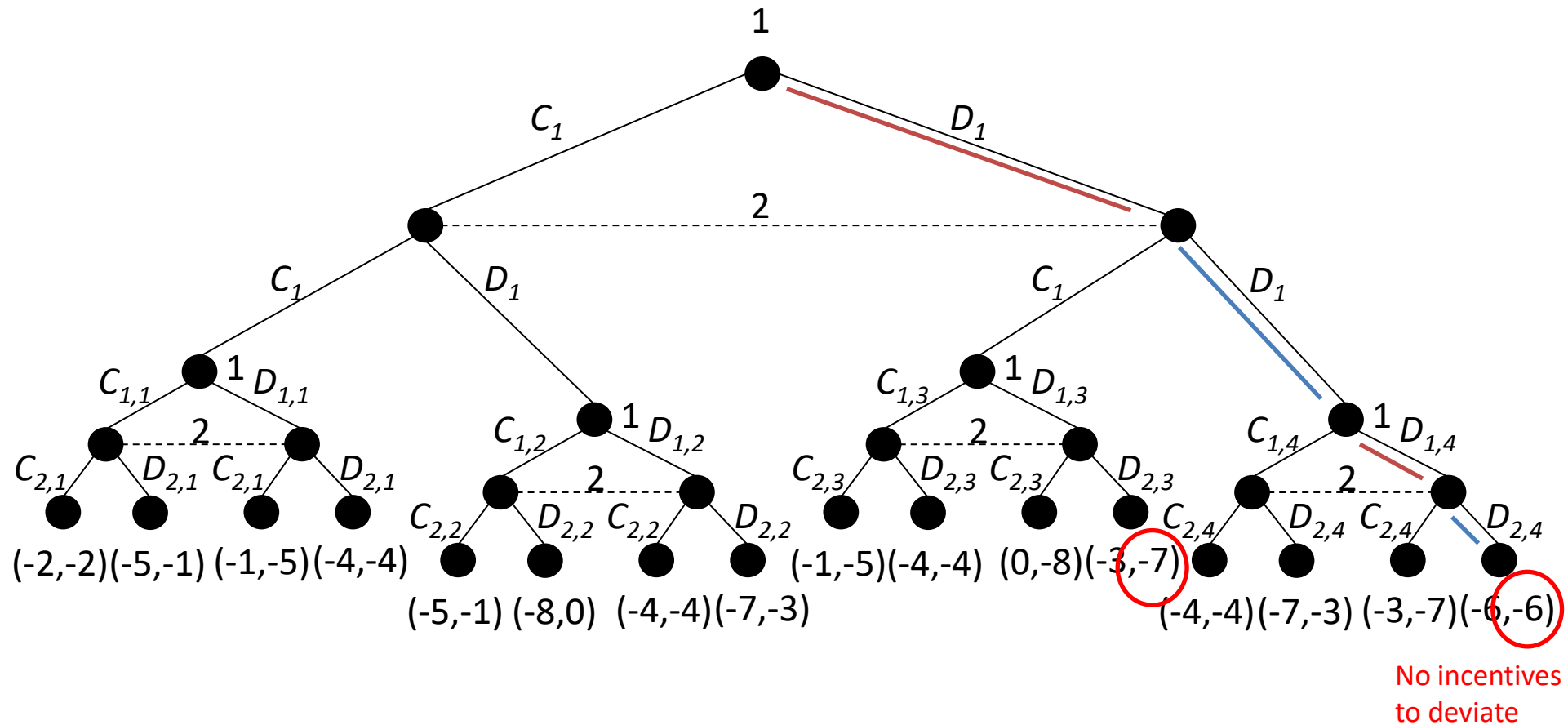
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# Finely-Repeated Games



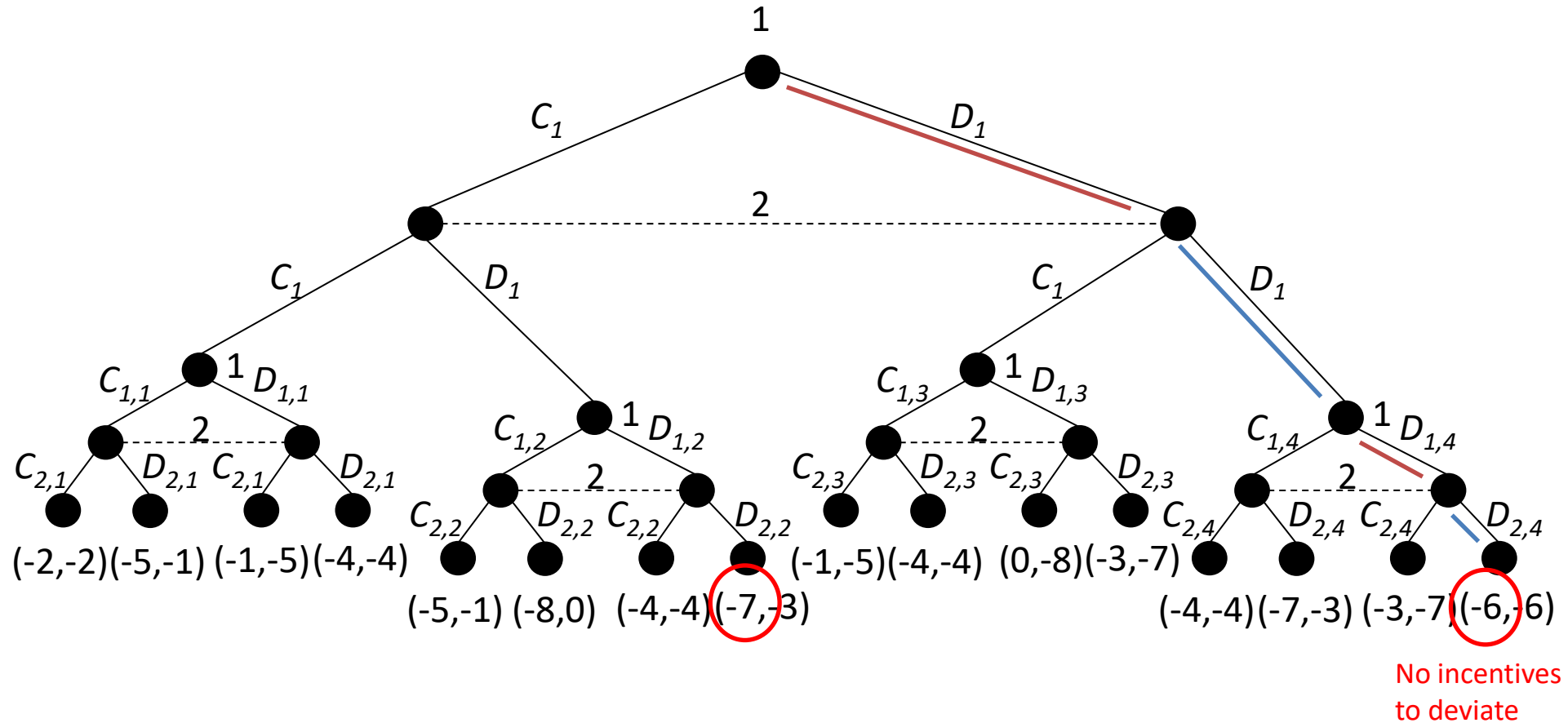
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# Finely-Repeated Games



Is the strategy profile  $(D_1, D_{1,4}), (D_1, D_{2,4})$  a Nash equilibrium?

# Finely-Repeated Games



Is the strategy profile  $(D_1, D_{1,4}), (D_1, D_{2,4})$  a Nash equilibrium?

YES

# Finately-Repeated Games

- **Proposition:** *If the stage game  $G$  has a unique Nash equilibrium then, for any finite  $T$ , the repeated game  $G(T)$  has a unique outcome: the Nash equilibrium of  $G$  is played in every subgame-perfect stage*

# Outline

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- Finitely-repeated games
- **Infinitely-repeated games**
- Folk Theorem
- Replicator dynamics





# Infinitely-Repeated Games

- Let us now consider a **game is repeated an infinite number of times**
- Can we represent this as an **extensive-form game**?
  - An **infinite tree**!
  - Sum of payoffs is **infinity**!

# Infinitely-Repeated Games

- **Definition:** Given an infinite sequence of payoffs  $r_1, r_2, \dots$  for agent  $i$ , the **average reward** of agent  $i$  is:

$$\lim_{k \rightarrow \infty} \sum_{j=1}^k \frac{r_j}{k}$$

# Infinitely-Repeated Games

- **Definition:** Given an infinite sequence of payoffs  $r_1, r_2, \dots$  for agent  $i$  and discount factor  $\beta$  with  $0 < \beta < 1$ , the **future discounted reward** of agent  $i$  is:

$$\sum_{j=1}^{\infty} \beta^j r_j$$

- **Interpretation:** the agent cares more about her well-being in the near term than in the long term

# Infinitely-Repeated Games

- What is a **pure strategy** in an infinitely-repeated game?
  - A **choice of action at every decision point**
    - In these games, this means **an action at every stage game** (for an infinite number of actions!)

# Infinitely-Repeated Games

- More formally:
  - Histories of length  $t$ :
    - $H^t = \{h^t : h^t = (a^1, \dots, a^t) \in A^t\}$
    - $a^t = (a_1^t, \dots, a_n^t)$  and  $a_i^t \in A_i$
  - All finite histories:  $H = \bigcup H^t$
  - A pure strategy:  $s_i : H \rightarrow A_i$

# Infinitely-Repeated Games

- Prisoner's Dilemma
  - $A_i = \{C, D\}$
  - A history of length  $t = 3$  :
    - $t = 1$ :  $(C, C)$
    - $t = 2$ :  $(C, D)$
    - $t = 3$ :  $(D, D)$
  - A strategy for period 4 would specify what an agent would do after seeing  $(C, C), (C, D), (D, D)$

# Infinitely-Repeated Games

- Some famous strategies (repeated Prisoner's Dilemma):
  - **Tit-for-tat:** Start out cooperating. If the opponent defected, defect in the next round. Then go back to cooperation.
    - **Agent 1:** C, C, C, D, C, C,...
    - **Agent 2:** C, C, D, C, C, C,...

# Infinitely-Repeated Games

- Some famous strategies (repeated Prisoner's Dilemma):
  - **Trigger:** Start out cooperating. If the opponent ever defects, defect forever.
    - **Agent 1:** C, C, C, D, D, D,...
    - **Agent 2:** C, C, D, C, C, C,...



# Infinitely-Repeated Games

- **Subgame-perfect equilibrium**
  - Profile of strategies that are a **Nash equilibrium in every subgame**
    - Hence, a Nash equilibrium following every possible history
- Repeatedly playing a Nash equilibrium of the stage game is always a **subgame-perfect equilibrium** of the repeated game

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- Infinitely-repeated games
- **Folk Theorem**
- Replicator dynamics



# Folk Theorem

- There are many **Folk Theorems** for infinitely-repeated games
  - **All are concerned with Nash equilibria** of an infinitely repeated game
  - This result was called the Folk Theorem because it **was widely known among game theorists** in the 1950s, even though **no one had published it**

# Folk Theorem

- Consider a **finite normal form game**  $G$  (stage game)
- Let  $a = (a_1, a_2, \dots, a_n)$  be a **Nash equilibrium** of the stage game  $G$
- If  $a' = (a'_1, a'_2, \dots, a'_n)$  is such that  $u_i(a') > u_i(a)$  for all  $i$ , then:
  - there **exists a discount factor**  $\beta$  ( $0 < \beta < 1$ ), such that  $\beta_i \geq \beta$  for all  $i$ , and
  - there **exists a subgame perfect equilibrium** of the infinite repetition of  $G$  that has  $a'$  played in every period on the equilibrium path

# Folk Theorem

- Outline of the Proof:
  - **Play  $a'$**  as long as **every agent is also playing**
  - If **any agent ever deviates**, then **play  $a$  forever after** (Trigger strategy)
  - Check that this is a **subgame-perfect equilibrium** for high enough discount factors

# Folk Theorem

- Check that this is a **subgame-perfect equilibrium** for high enough discount factors
  - **Playing  $a$  forever** (if anyone deviated) is a **Nash equilibrium** in any subgame
  - Will **someone gain by deviating from  $a$**  if nobody has in the past?

# Folk Theorem

- Check that this is a **subgame-perfect equilibrium for high enough discount factors**
- Will **someone gain by deviating from  $a'$**  if nobody has in the past?
  - **Maximum gain from deviating** (over all agents) is

$$M = \max_{i, a''} u_i(a_i'', a'_{-i}) - u_i(a')$$

- **Minimum per-period loss from future punishment** is

$$m = \min_i u_i(a') - u_i(a)$$

# Folk Theorem

- Check that this is a **subgame-perfect equilibrium** for high enough discount factors
- Will **someone gain by deviating from  $a'$**  if nobody has in the past?
  - If an agent deviates, given the other agents' strategies, the **maximum possible net gain** is

$$M - m \frac{\beta_i}{1 - \beta_i}$$



# Folk Theorem

- Check that this is a **subgame-perfect equilibrium for high enough discount factors**
- Will **someone gain by deviating from  $a'$**  if nobody has in the past?
  - **Deviation is not beneficial if**

$$M - m \frac{\beta_i}{1 - \beta_i} \leq 0$$

$$\frac{M}{m} \leq \frac{\beta_i}{1 - \beta_i}$$

$$\beta_i \geq \frac{M}{M+m}, \text{ for all } i$$

# Infinitely-Repeated Games

- Example: **Prisoner's Dilemma** – Can we sustain cooperation?

We want to  
sustain  
cooperation

	<i>C</i>	<i>D</i>
<i>C</i>	3, 3	0, 5
<i>D</i>	5, 0	1, 1

Nash equilibrium  
of the stage game

# Infinitely-Repeated Games

- Example: **Prisoner's Dilemma** – Can we sustain cooperation?
  - Agent cooperates as long as the other agent is cooperating in the past
  - Both agents defect if anyone deviates (**Trigger strategy**)

When is this an equilibrium? Is there a value of  $\beta$  that could sustain this equilibrium above?

	<i>C</i>	<i>D</i>
<i>C</i>	3, 3	0, 5
<i>D</i>	5, 0	1, 1

# Infinitely-Repeated Games

- Example: **Prisoner's Dilemma** – Can we sustain cooperation?

- **Always cooperate:**  $3 + \beta 3 + \beta^2 3 + \beta^3 3 + \dots = \frac{3}{1-\beta}$

- **Always defect:**  $5 + \beta 1 + \beta^2 1 + \beta^3 1 + \dots = 5 + \beta \frac{1}{1-\beta}$

	<i>C</i>	<i>D</i>
<i>C</i>	3, 3	0, 5
<i>D</i>	5, 0	1, 1

# Infinitely-Repeated Games

- Example: **Prisoner's Dilemma** – Can we sustain cooperation?

- **Always cooperate:**  $3 + \beta 3 + \beta^2 3 + \beta^3 3 + \dots = 3 + \beta \frac{3}{1-\beta}$

- **Always defect:**  $5 + \beta 1 + \beta^2 1 + \beta^3 1 + \dots = 5 + \beta \frac{1}{1-\beta}$

- **Difference:**  $-2 + \beta 2 + \beta^2 2 + \beta^3 2 + \dots = -2 + \beta \frac{2}{1-\beta}$

# Infinitely-Repeated Games

- Example: **Prisoner's Dilemma** – Can we sustain cooperation?
  - **Difference:**  $-2 + \beta 2 + \beta^2 2 + \beta^3 2 + \dots = \beta \frac{2}{1-\beta} - 2$
  - If we want the “**always cooperate**” to have a higher payoff:
    - $\beta \frac{2}{1-\beta} - 2 \geq 0$
    - $\beta \geq \frac{1}{2}$
  - **Interpretation:** if we want to sustain cooperation, the agent needs to care about tomorrow at least as half as much as it cares about today!

# Exercise

- Could we sustain cooperation in this infinitely-repeated game?

	<i>C</i>	<i>D</i>
<i>C</i>	3, 3	0, 10
<i>D</i>	10, 0	1, 1

Defection is more attractive!

# Repeated Games

- Agents can condition future decisions based on past actions
- This generates many equilibria: Folk Theorems
- Check “The Evolution of Trust”, Nicky Case
  - <https://ncase.me/trust/>



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- Folk Theorem
- **Replicator dynamics**



# Evolutionary Learning and other Large-population models

- Consider large populations
- Model the evolution of behavior of the whole population
- Standard model technique in biology, social networks, human population behavior.

## **MULTIAGENT SYSTEMS**

### **Algorithmic, Game-Theoretic, and Logical Foundations**

**Yoav Shoham, Kevin Leyton-Brown, 2008**

# Evolutionary Learning and other Large-population models

The *replicator dynamic* models a population undergoing frequent replicator interactions.

## Replicator dynamic

Basic interaction between any two agents

	<b><i>A</i></b>	<b><i>B</i></b>
<b><i>A</i></b>	$x, x$	$u, v$
<b><i>B</i></b>	$v, u$	$y, y$

agents have no distinct roles (symmetric game)

# Evolutionary Learning and other Large-population models

Replicator dynamic

	<i>A</i>	<i>B</i>
<i>A</i>	$x, x$	$u, v$
<i>B</i>	$v, u$	$y, y$

- $\varphi_t(A)$  – number of agents playing *A* at time *t*
- $\theta_t(A) = \frac{\varphi_t(A)}{\sum_a \varphi_t(a)}$  - ratio of agents playing *A* at time *t*
- $u_t(a) = \sum_b \theta_t(b)u(a, b)$

# Evolutionary Learning and other Large-population models

## Replicator dynamic

- $u_t(a) = \sum_b \theta_t(b) u(a, b)$
- $u_t^* = \sum_a \theta_t(a) u_t(a)$

The number of agents change proportionally to their utility.

- $\dot{\varphi}_t(a) = \varphi_t(a) u_t(a)$
- $\theta_t(A) = \frac{\varphi_t(A)}{\sum_a \varphi_t(a)}$
- $\dot{\theta}_t(A) = \frac{\dot{\varphi}_t(A) \sum_a \varphi_t(a) - \varphi_t(A) \sum_a \dot{\varphi}_t(a)}{(\sum_a \varphi_t(a))^2} = \theta_t(a) [u_t(a) - u_t^*]$

# Replicator dynamics

```
def dynreplicator(g,th):
    va = g.payoff_matrices[0]@th
    v = th@va
    dth = th * (va-v)

    return dth

ddx = np.zeros((100,100))
ddy = np.zeros((100,100))

for kk in Games.keys():
    g = Games[kk]
    for ix in np.linspace(0, .99, 10,):
        for iy in np.linspace(0, .99, 10):
            dth = dynreplicator(g,[ix,iy])
            ddx[int(ix*10),int(iy*10)],ddy[int(ix*10),int(iy*10)] = dth

plt.figure()
plt.subplot(1,2,1)
plt.quiver(xx,yy,ddx,ddy)
plt.title(kk)

th = [0.7,0.3]
TH = []
for ii in np.arange(0,20,dt):

    dth = dynreplicator(g,th)
    th = np.clip(th + dth * dt, 0, 1)
    th /= np.sum(th)
    TH += [th]
plt.subplot(1,2,2)
plt.plot(TH)
plt.title(kk)
```

# Replicator dynamics

**Definition 7.7.2 (Steady state)** A steady state of a population using the replicator dynamic is a population state  $\theta$  such that for all  $a \in A$ ,  $\dot{\theta}(a) = 0$ .

**Definition 7.7.3 (Stable steady state)** A steady state  $\theta$  of a replicator dynamic is stable if for every neighborhood  $U$  of  $\theta$  there is another neighborhood  $V$  of  $\theta$  such that if  $\theta_0 \in V$  then  $\theta_t \in U$  for all  $t > 0$ .

**Definition 7.7.4 (Asymptotically stable state)** A steady state  $\theta$  of a replicator dynamic is asymptotically stable if it is stable, and in addition if for every neighborhood  $U$  of  $\theta$  it is the case that if  $\theta_0 \in U$  then  $\lim_{t \rightarrow \infty} \theta_t = \theta$ .

# What is the equilibria? Is it stable?

	$A$	$B$
$A$	0, 0	1, 1
$B$	1, 1	0, 0

Figure 7.9: The Anti-Coordination game.



# Anti-Coordination Game

- $u(a) = 0 \cdot \theta + 1 \cdot (1 - \theta) = 1 - \theta$
- $u(b) = 1 \cdot \theta + 0 \cdot (1 - \theta) = \theta$
- $u^* = (1 - \theta) \cdot \theta + \theta \cdot (1 - \theta) = 2 \cdot (1 - \theta) \cdot \theta$
- $d\theta = \theta(1 - \theta - 2 \cdot \theta(1 - \theta)) = \theta(1 - 3 \cdot \theta + 2 \cdot \theta^2)$
- $d\theta = 0$  for  $\theta = 0.5$
- $d\theta > 0$  for  $\theta < 0.5$
- $d\theta < 0$  for  $\theta > 0.5$

# Stag-Hare

- What are the Nash Eq?
- Is there an asymptotic equilibria?

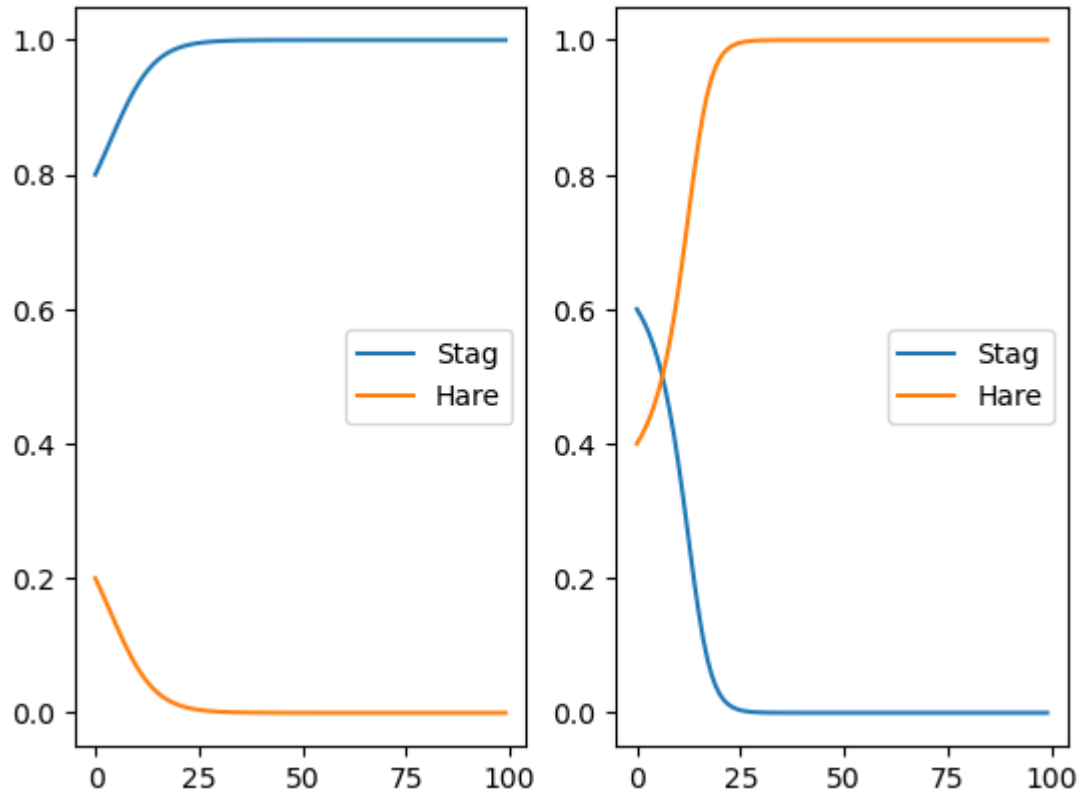
	Stag	Hare
Stag	10, 10	1, 8
Hare	8, 1	5, 5

# Stag-Hare

	Stag	Hare
Stag	10, 10	1, 8
Hare	8, 1	5, 5

- $u(s) = 10\theta + 1(1 - \theta) = 9\theta + 1$
- $u(h) = 8\theta + 5(1 - \theta) = 3\theta + 5$
- $u^* = (9\theta + 1)\theta + (3\theta + 5)(1 - \theta) = 6\theta^2 - \theta + 5$
- $u(s) - u^* = (9\theta + 1) - (6\theta^2 - \theta + 5) = -6\theta^2 + 10\theta - 4$
- $u(s) - u^* = 0 \Rightarrow \theta = 1 \vee \theta = 2/3$

# Stag-Hare



- $u(s) = 10\theta + 1(1 - \theta) = 9\theta + 1$
- $u(h) = 8\theta + 5(1 - \theta) = 3\theta + 5$
- $u^* = (9\theta + 1)\theta + (3\theta + 5)(1 - \theta) = 6\theta^2 - \theta + 5$
- $u(s) - u^* = (9\theta + 1) - (6\theta^2 - \theta + 5) = -6\theta^2 + 10\theta - 4$
- $u(s) - u^* = 0 \Rightarrow \theta = 1 \vee \theta = 2/3$

# Replicator dynamics

- In a given game the populations will converge to the Nash equilibria?
- What if there is more than one?
- And if there is none?

# Replicator dynamics

**Theorem 7.7.5** *Given a normal-form game  $G = (\{1, 2\}, A = \{a_1, \dots, a_k\}, u)$ , if the strategy profile  $(S, S)$  is a (symmetric) mixed strategy Nash equilibrium of  $G$  then the population share vector  $\theta = (S(a_1), \dots, S(a_k))$  is a steady state of the replicator dynamic of  $G$ .*

**Theorem 7.7.6** *Given a normal-form game  $G = (\{1, 2\}, A = \{a_1, \dots, a_k\}, u)$  and a mixed strategy  $S$ , if the population share vector  $\theta = (S(a_1), \dots, S(a_k))$  is a stable steady state of the replicator dynamic of  $G$ , then the strategy profile  $(S, S)$  is a mixed strategy Nash equilibrium of  $G$ .*

# Replicator dynamics

**Definition 7.7.7 (Trembling-hand perfect equilibrium)** A mixed strategy  $S$  is a (trembling-hand) perfect equilibrium of a normal-form game  $G$  if there exists a sequence  $S_0, S_1, \dots$  of fully mixed-strategy profiles such that  $\lim_{n \rightarrow \infty} S_n = S$ , and such that for each  $S_k$  in the sequence and each player  $i$ , the strategy  $S_i$  is a best response to the strategies  $S_{k-i}$ .

**Theorem 7.7.8** Given a normal-form game  $G = (\{1, 2\}, A, u)$  and a mixed strategy  $S$ , if the population share vector  $\theta = (S(a_1), \dots, S(a_k))$  is an asymptotically stable steady state of the replicator dynamic of  $G$ , then the strategy profile  $(S, S)$  is a Nash equilibrium of  $G$  that is trembling-hand perfect and isolated.

# Evolutionarily stable strategies

Unlike the steady states discussed earlier, it does not require the replicator dynamic; rather it is a static solution concept.

Roughly speaking, an evolutionarily stable strategy is a mixed strategy that is “resistant to invasion” by new strategies.

**Definition 7.7.10 (Weak ESS)**  $S$  is a weak evolutionarily stable strategy if and only if for some  $\epsilon > 0$  and for all  $S'$  it is the case that either  $u(S, S) > u(S', S)$  holds, or else both  $u(S, S) = u(S', S)$  and  $u(S, S) \geq u(S', S)$  hold.



# Evolutionarily stable strategies

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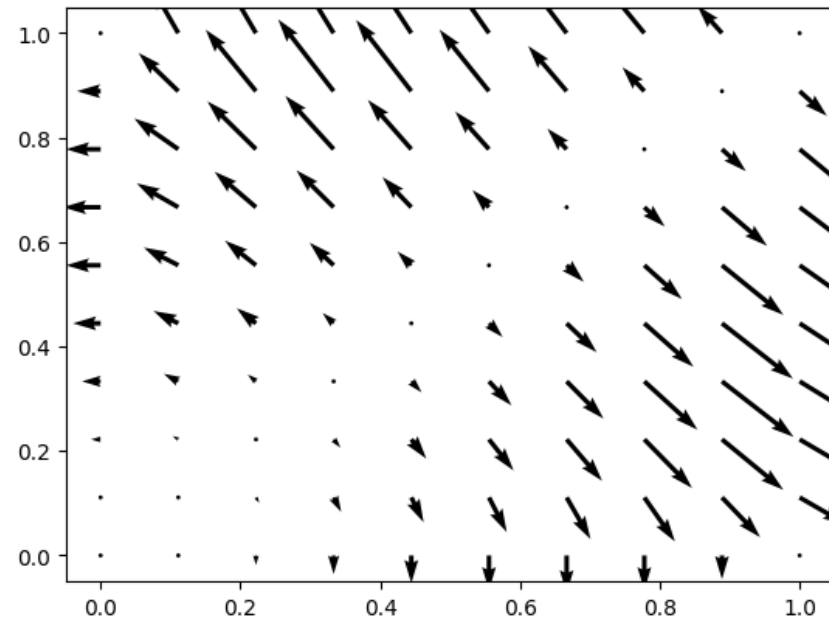
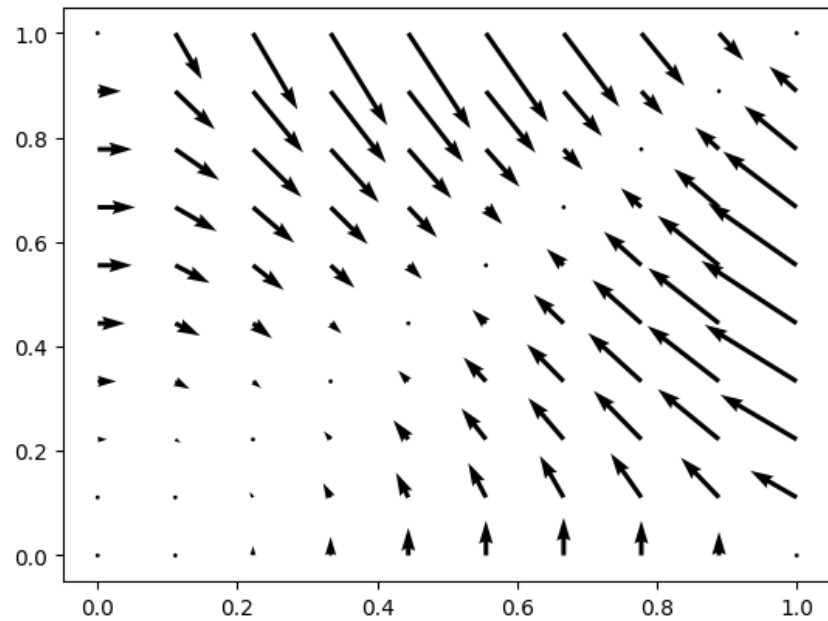
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**Theorem 7.7.11** *Given a symmetric two-player normal-form game  $G = (\{1, 2\}, A, u)$  and a mixed strategy  $S$ , if  $S$  is an evolutionarily stable strategy then  $(S, S)$  is a Nash equilibrium of  $G$ .*

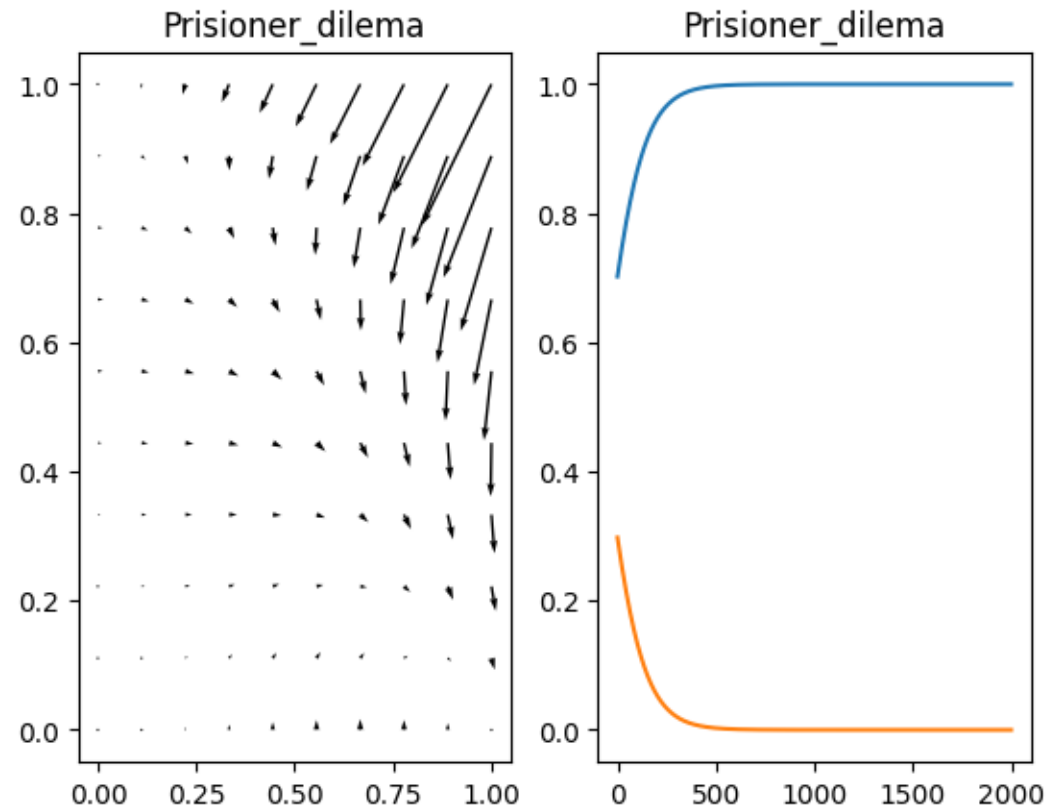
**Theorem 7.7.12** *Given a symmetric two-player normal-form game  $G = (\{1, 2\}, A, u)$  and a mixed strategy  $S$ , if  $(S, S)$  is a strict (symmetric) Nash equilibrium of  $G$ , then  $S$  is an evolutionarily stable strategy.*

**Theorem 7.7.13** *Given a symmetric two-player normal-form game  $G = (\{1, 2\}, A, u)$  and a mixed strategy  $S$ , if  $S$  is an evolutionarily stable strategy then it is an asymptotically stable steady state of the replicator dynamic of  $G$ .*

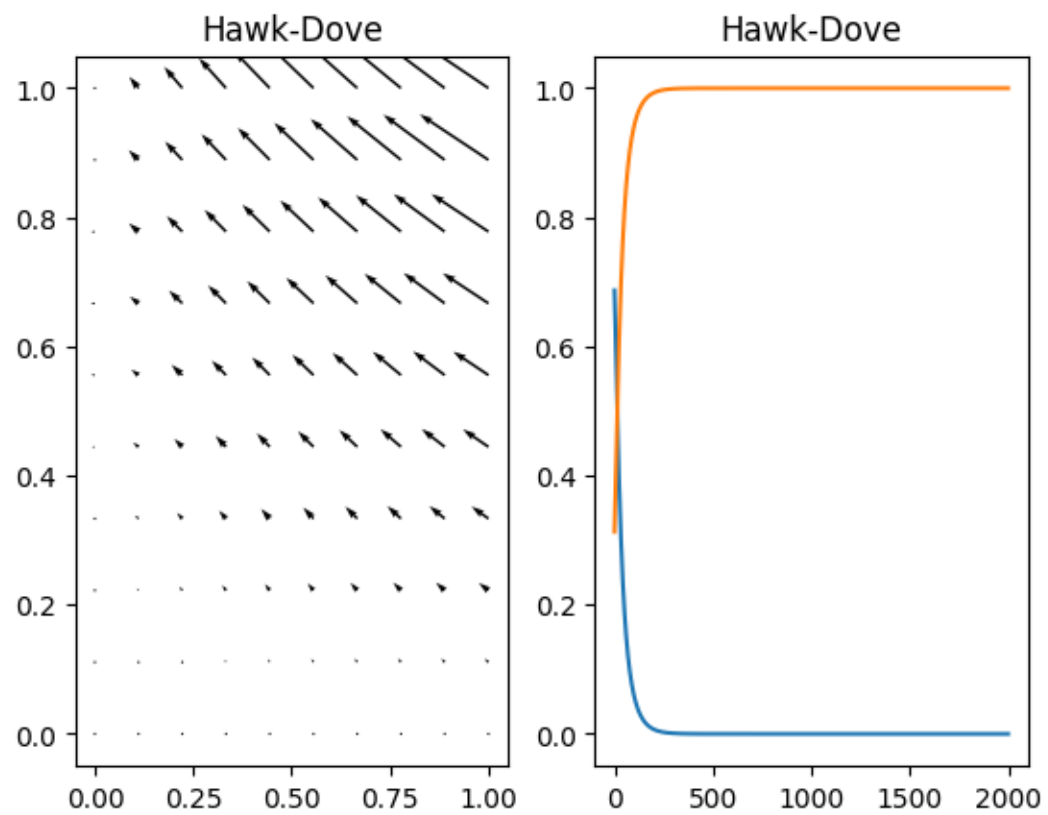
# Matching Pennies



# Prisoner dilemma



# Hawk-Dove



# Thank You



[rui.prada@tecnico.ulisboa.pt](mailto:rui.prada@tecnico.ulisboa.pt)  
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alberto.sardinha