The Ramsey growth model

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A short history of the model

- ► Frank Ramsey (see https://en.wikipedia.org/wiki/Frank_P._Ramsey) made several important contributions in his short life (he died at 26) one of them Ramsey (1928)
- ▶ His contribution was only fully recognized in the early 1960's (Cass (1965), Koopmans (1965)) as presenting a rigorous alternative to the ad-hoc aspects (dynamic inefficiency) of the Solow (1956) model (now we call it exogenous growth theory)
- ► It was rejoined again in the middle of the 1980's which saw the onset of **endogenous growth theory**
- ▶ It is also the founding rock of the DGE (dynamic general equilibrium theory) of macroeconomics

The basic idea

- Output is produced by physical capital and labor and can be used for investment or for consumption (everything in per capita terms): this introduces an intratemporal budget constraint
- > savings is determined by a arbitrage between present and future consumption: it balances two effects:
 - ▶ present consumption is a good thing, although its utility decreases with the amount consumed;
 - ▶ however, if people sacrifice present consumption, by saving and increasing the capital stock, they improve their prospects for more consumption in the future;
- this idea can be formalized as an intertemporal optimization problem

Assumptions

- ▶ Production:
 - closed economy producing a single composite good
 - production uses two factors: labor and physical capital
 - production technology: neoclassical (increasing, concave, Inada, CRTS)
- ► Reproducible factor:
 - physical capital (machines)
- ▶ Population:
 - exogenous (can be constant or increase exponentially)

Assumptions: continuation

- ► Households: optimizing behavior
 - ▶ maximize an intertemporal utility functional with consumption as the control variable
 - subject to a budget constraint
 - ▶ labor is supplied inelastically
 - have perfect foresight
- ► Equilibrium is Pareto optimal, therefore it is equivalent to a social welfare problem

The model: production technology

► In aggregate terms

$$Y(t) = F(A, K(t), L(t)) = AK(t)^{\alpha} L(t)^{1-\alpha}, \ 0 < \alpha < 1$$

where: A TFP productivity, K stock of capital, L=N loabor input = population

► In per capita terms:

$$y(t) = Ak(t)^{\alpha}$$

where y = Y/N and k = K/N

The model: preferences

Preferences: of the representative agent

▶ the intertemporal utility functional is

$$V[c] = \int_0^\infty u(c(t))e^{-\rho t}dt$$

- $ightharpoonup c = C/N \text{ per capita consumption, } [c] = (c(t))_{t \in [0,\infty)}$
- ightharpoonup
 ho > 0 is the rate of time preference
- ▶ the instantaneous utility function is

$$u(c) = \begin{cases} \frac{c^{1-\theta} - 1}{1 - \theta}, & \text{if } \theta \in (0, \infty) / \{1\} \\ \ln(c), & \text{if } \theta = 1 \end{cases}$$

where $1/\theta$ is the elasticity of intertemporal substitution

- ► We are assuming an **homogeneous agent** (or representative) economy
- ► There are two versions of the model
 - **centralized** version: maximization of social welfare given the budget constraint
 - ▶ decentralized (DGE) version: individual maximization of households an firms coordinated by market equilibrium
- As there are no externalities they are **equivalent** (in the sense that generate the **same allocations**, of consumption and capital, over time)

Centralized version: the Ramsey model:

The centralized version

- ► The central planner is a "benevolent dictator" (acts on behalf of the best interests of the society)
- ► The central planner solves the problem

$$\max_{(c)_{t\geq 0}} \int_0^\infty \frac{c(t)^{1-\theta} - 1}{1-\theta} e^{-\rho t} dt$$
subject to
$$\dot{k} = G(k) \equiv Ak(t)^\alpha - c(t) - \delta k(t),$$

$$k(0) = k_0 > 0, \text{ given}$$

$$\lim_{t \to \infty} h(t)k(t) \ge 0$$

physical capital is asymptotically bounded (h(t)) is any discount factor)

Solving by using the Pontriyagin's max principle

► The current-value Hamiltonian is

$$H(c, k, q) = \frac{c^{1-\theta} - 1}{1 - \theta} + q(Ak^{\alpha} - c - \delta k)$$

▶ the optimality conditions are

$$\begin{split} \frac{\partial H}{\partial c} &= 0 \text{ (optimality condition)} \\ \dot{q} &= \rho q - \frac{\partial H}{\partial k} \text{ (Keynes-Ramsey rule)} \\ \lim_{t \to \infty} q(t)k(t)e^{-\rho t} &= 0 \text{ (transversality condition)} \end{split}$$

▶ the admissibility conditions

$$\dot{k} = G(k)$$
 (aggregate constraint)
 $k(0) = k_0 > 0$ (initial condition)

Solving by using the Pontriyagin's max principle

► The current-value Hamiltonian is

$$H(c, k, q) = \frac{c^{1-\theta} - 1}{1 - \theta} + q \left(Ak^{\alpha} - c - \delta k \right)$$

▶ the optimality conditions are

$$c^{-\theta}(t) = q(t), \text{ for } t \in [0, \infty)$$
$$\dot{q} = q(t) \left(\rho + \delta - \alpha A k(t)^{\alpha - 1} \right), \text{ for } t \in [0, \infty)$$
$$\lim_{t \to \infty} q(t) k(t) e^{-\rho t} = 0, \text{ for } t = \infty$$

▶ the admissibility conditions

$$\dot{k} = Ak(t)^{\alpha} - c(t) - \delta k(t), \text{ for } t \in [0, \infty)$$

 $k(0) = k_0 > 0, \text{ for } t = 0$

The modified Hamiltonian dynamic system

An optimum path $(c^*(t), k^*(t))_{t \in [0, +\infty)}$ is the solution of the (MHDS)

$$\dot{k} = Ak(t)^{\alpha} - c(t) - \delta k(t) \tag{1}$$

$$\dot{c} = \frac{c}{\theta} \left(r(k(t)) - \rho - \delta \right)$$
 (2)

$$0 = \lim_{t \to \infty} c(t)^{-\theta} k(t) e^{-\rho t}$$
 (3)

$$k(0) = k_0 \text{ given}$$
 (4)

▶ where the (gross) rate of return of capital

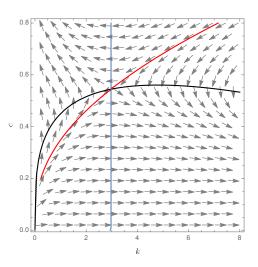
$$r(k) = \alpha A k^{\alpha - 1}$$

- ► In general this system does not have an explicit solution (also called exact or closed form)
- We can only find an **exact solution** for the case $\theta = \alpha$ (which is counterfactual)
- ▶ Analytical methods for finding the solution (unique way to solve it if $\theta \neq \alpha$): **linear approximation** of the solution converging to the steady state, which satisfies the transversality constraint
- In all cases, it is always a good idea to build the phase diagram

By linear approximation

- \triangleright step 0: try to draw the phase diagram of system (1)-(2)
- ▶ step1: find the steady state (consistent with the transversality and initial conditions)
- ▶ step 2: find the linear approximation of system (1)-(2) in the neighborhood of the steady state
- ▶ step 3: find the general solution of the linearized system
- ▶ step 4: find the particular solution by using the transversality and the initial conditions
- ▶ step 5: sit back and try to understand the meaning of the solution

step 0: phase diagram



step 1: Steady states

▶ Steady states are fixed points of the system

$$c^{ss} = A(k^{ss})^{\alpha} - \delta k^{ss},$$

$$\frac{c^{ss}}{\theta} (r(k^{ss}) - (\rho + \delta)) = 0.$$

▶ there are three steady states

$$(k^{ss}, c^{ss}) = \{(0, 0), ((A/\delta)^{1/(1-\alpha)}, 0), (\bar{k}, \bar{c})\}$$

for

$$\bar{k} = \left(\frac{\alpha A}{\delta + \rho}\right)^{\frac{1}{1-\alpha}}, \ \bar{c} = \beta \, \bar{k}$$

where $\beta \equiv \frac{\rho + \delta(1-\alpha)}{\alpha}$

• (\bar{k}, \bar{c}) satisfies the transversality condition but $((A/\delta)^{1/(1-\alpha)}, 0)$ does not

step 2: linearized MHDS

▶ The linearised MHDS in the neighbourhood of (\bar{c}, \bar{k}) is

$$\begin{pmatrix} \dot{k} \\ \dot{c} \end{pmatrix} = \begin{pmatrix} \rho & -1 \\ \frac{\bar{c}r'(\bar{k})}{\theta} & 0 \end{pmatrix} \begin{pmatrix} k(t) - \bar{k} \\ c(t) - \bar{c} \end{pmatrix}$$

• where
$$r'(\bar{k}) = (\alpha - 1)\alpha A k^{\alpha - 2} \Big|_{k = \bar{k}} = -\frac{(1 - \alpha)(\rho + \delta)}{\bar{k}} < 0$$

▶ and
$$\frac{\bar{c}r'(\bar{k})}{\theta} = -d \equiv -\frac{(1-\alpha)\beta(\rho+\delta)}{\theta} < 0$$

step 3: finding the general solution of the linearized MHDS

- ▶ the system is of type $\dot{x} = Jx$
- ▶ where the Jacobian matrix is

$$\mathbf{J} = \begin{pmatrix} \rho & -1 \\ -d & 0 \end{pmatrix}$$

▶ the solution is of type

$$x(t) = h_s \mathbf{V}^s e^{\lambda_s t} + h_u \mathbf{V}^u e^{\lambda_u t}$$

• where λ_j are the eigenvalues, and \mathbf{V}^j are the associated eigenvectors of J, and (h_s, h_u) are arbitrary constants

step 3: finding the general solution of the linearized MHDS

ightharpoonup the eigenvalues of $\bf J$ are

$$\lambda_u = \frac{\rho}{2} + \left[\left(\frac{\rho}{2} \right)^2 + d \right]^{1/2} > \rho > 0$$

$$\lambda_s = \frac{\rho}{2} - \left[\left(\frac{\rho}{2} \right)^2 + d \right]^{1/2} < 0$$

- ▶ satisfying $\lambda_s + \lambda_u = \rho > 0$, $\lambda_s \lambda_u = -d < 0$
- ▶ then (k, \bar{c}) is a saddle-point

step 3: finding the general solution of the linearized MHDS

- ▶ the eigenvectors are determined as follows
- $ightharpoonup V^s$ solves the homogeneous system

$$(\mathbf{J} - \lambda_s \mathbf{I}_2) \mathbf{V}^s = \mathbf{0}$$

▶ that is

$$\begin{pmatrix} \rho - \lambda_s & -1 \\ -d & -\lambda_s \end{pmatrix} \begin{pmatrix} \mathbf{V}_1^s \\ \mathbf{V}_2^s \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

• the members of vector \mathbf{V}^s should satisfy (because $\rho - \lambda_s = \lambda_u$ and $\lambda_s \lambda_u = -d$)

$$\lambda_u \mathbf{V}_1^s - \mathbf{V}_2^s = 0 \implies \mathbf{V}^s = \begin{pmatrix} 1 \\ \lambda_u \end{pmatrix}$$

ightharpoonup for \mathbf{V}^u we find (prove this)

$$\lambda_s \mathbf{V}_1^u - \mathbf{V}_2^u = 0 \implies \mathbf{V}^u = \begin{pmatrix} 1 \\ \lambda_s \end{pmatrix}$$

step 4: finding the particular solution of the linearized MHDS

▶ Then the general solution is

$$\begin{pmatrix} k(t) - \bar{k} \\ c(t) - \bar{c} \end{pmatrix} = h_s \begin{pmatrix} 1 \\ \lambda_u \end{pmatrix} e^{\lambda_s t} + h_u \begin{pmatrix} 1 \\ \lambda_s \end{pmatrix} e^{\lambda_u t}$$

We determine h_s and h_u by forcing the general solution to satisfy the two remaining conditions

$$\lim_{t \to \infty} \frac{k(t)}{c(t)^{\theta}} e^{-\rho t} = 0, \text{ and } k(0) = k_0$$

- the first condition holds if $\lim_{t\to\infty}(c(t)-\bar{c})=\lim_{t\to\infty}(k(t)-\bar{k})=0$, i.e., they converge to the steady state, which is obtained by eliminating the effect of $e^{\lambda_u t}$ (because $\lim_{t\to\infty}e^{\lambda_u t}=\infty$) by setting $h_u=0$
- the second condition holds if

$$k(0) - \bar{k} = h_s = k_0 - \bar{k} \implies h_s = k_0 - \bar{k}$$

step 4: finding the particular solution of the linearized MHDS

▶ the approximate solution is, for $t \in [0, \infty)$

$$k(t) = \bar{k} + (k_0 - \bar{k})e^{\lambda_s t}$$

$$c(t) = \bar{c} + \lambda_u (k_0 - \bar{k})e^{\lambda_s t}.$$
(5)

where

$$\bar{k} = \left(\frac{\alpha A}{\delta + \rho}\right)^{\frac{1}{1-\alpha}}, \ \bar{c} = \beta \ \bar{k}$$

and $\lambda_u > \rho > 0 > \lambda_s$.

step 5: understanding the solution

ightharpoonup at t=0 we have

$$\begin{pmatrix} k(0) \\ c(0) \end{pmatrix} = \begin{pmatrix} k_0 \\ \bar{c} + \lambda_u (k_0 - \bar{k}) \end{pmatrix}$$

observe that λ_u gives the variation of consumption as $c(0) - \bar{c} = \lambda_u(k_0 - \bar{k})$ and the initial consumption is determined from **future data** $(\bar{c} \text{ and } \bar{k})$

▶ asymptotically (i.e., in the long run)

$$\lim_{t \to \infty} \binom{k(t)}{c(t)} = \binom{\bar{k}}{\bar{c}} = \binom{1}{\beta} \bar{k}$$

the solution converges to the steady state (this means that the transversality condition is satisfied)

► the saddle path dynamics implies that the solution is unique. We say it is determinate

Case $\theta \neq \alpha$ benchmark case: phase diagrams for $\theta > \alpha$

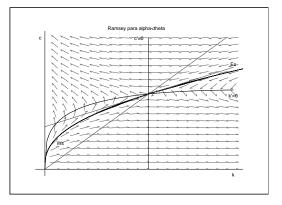


Figure: Exact (dark) and approximate (light) solutions

Case $\theta \neq \alpha$: phase diagrams for $\theta < \alpha$

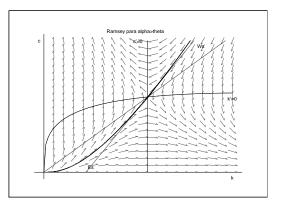
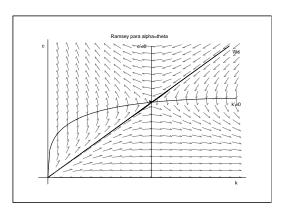


Figure: Exact (dark) and approximate (light) solutions

Case $\theta = \alpha$: phase diagram



Growth implications

► The unique steady state which satisfies the initial and the transversality conditions is

$$\bar{k} = \left(\frac{\alpha A}{\delta + \rho}\right)^{\frac{1}{1-\alpha}}, \ \bar{c} = \beta \ \bar{k}$$

for
$$\beta \equiv \frac{\rho + \delta(1-\alpha)}{\alpha}$$

▶ the associated long-run GDP is

$$\bar{y} = A\bar{k}^{\alpha} = \left[A \left(\frac{\alpha}{\delta + \rho} \right)^{\alpha} \right]^{\frac{1}{1 - \alpha}}.$$
 (6)

Ramsey model Per-capita GDP dynamics

▶ the **approximate** per-capita output path is generated by

$$y(t) = \left[\bar{y}^{1/\alpha} + (y(0)^{1/\alpha} - \bar{y}^{1/\alpha}) e^{\lambda_s t} \right]^{\alpha}$$
 (7)

the model only displays transitional dynamics as $\lambda_s < 0$.

▶ the solution converges asymptotically to the steady state

$$\lim_{t \to \infty} y(t) = \bar{y} = \left[A \left(\frac{\alpha}{\delta + \rho} \right)^{\alpha} \right]^{1/(1-\alpha)}$$

Growth implications

- 1. there is no long-run growth $\bar{g} = 0$
- 2. the **long-run level** \bar{y} depends on $(A, \delta, \rho, \alpha)$: productivity, the rate of depreciation, the rate of time preference (impatience) and on the income shares (see equation (6));
- 3. there is **only transitional dynamics**: the **speed** and the pattern of convergence depends on the relationship between the capital share, α , in income and the intertemporal elasticity of substitution θ (see equation (7)). This is because

$$\lambda_s = \frac{\rho}{2} - \left[\left(\frac{\rho}{2} \right)^2 + \frac{(1 - \alpha) \beta (\rho + \delta)}{\theta} \right]^{\frac{1}{2}} < 0$$

the higher $|\lambda_s|$ is the faster the transition speed is.

dynamic general equilibrium (DGE) model

Decentralized version:

The Neoclassical DGE model

Assumption

- ▶ Representative household: has initial financial wealth b(0), receives has wage income w and financial income (rb), and decides on consumption (c) and savings (\dot{b}) ;
- ▶ Households own firms with physical capital (k) which is only financed by bonds: thus b = k. Firms transform capital and labor into output (y)
- ► There are accounting restrictions.
- ▶ All markets are competitive
- ▶ Other assumptions: infinite-lived households with isoelastic utility and Cobb-Douglas production, function and no frictions.

Household problem

► Household's problem: maximize discounted intertemporal utility subject to a financial constraint

$$\max_{c(.)} \int_0^\infty \frac{c(t)^{1-\theta}}{1-\theta} e^{-\rho t} dt$$
subject to
$$\dot{b} = r(t)b(t) + w(t) - c(t), \ t \ge 0$$

$$b(0) = b_0$$

$$\lim_{t \to \infty} e^{-\int_t^\infty r(s) ds} \ge 0$$

where b = bonds, w = wage

Household problem

▶ Optimality conditions

$$\dot{c} = \frac{c(t)}{\theta} (r(t) - \rho)$$

$$\lim_{t \to \infty} e^{-\rho t} c(t)^{-\theta} b(t) = 0$$

► Admissibility conditions

$$\dot{b} = r(t)b(t) + w(t) - c(t), \ t \ge 0$$
$$b(0) = b_0$$

The firm's problem

► Firm's problem (price taker in all the markets): maximizes present value of profits

$$\max_{i} \int_{0}^{\infty} (Ak(t)^{\alpha} - w(t) - i(t)) e^{-R(t)} dt$$

subject to
$$\dot{k} = i - \delta k$$

$$k(0) = k_{0}$$

- observations
 - ▶ the discount factor is the (endogeneous) market interest rate $R(t) = \int_{t}^{\infty} r(s) ds$
 - the control variable: investment expenditure
 - no adjustment cost: investment expendiure is equal to gross investment
 - constraint: net investment = gross investment minus depreciation

The firm's problem

► Hamiltonian

$$H(i, k, q) = Ak^{\alpha} - w - i + q(1 - \delta k)$$

▶ Optimality conditions:

$$\frac{\partial H(i, k, q)}{\partial i} = 0 \iff q(t) = 1, \text{ for all } t \ge 0$$

► Canonical equation

$$\dot{q} = q \left(r(t) + \delta - \alpha A k^{\alpha - 1} \right)$$

As q = 1 then $\dot{q} = 0$ then this is equivalent to

$$r(t) = \alpha A k(t)^{\alpha - 1} - \delta$$
, for all $t \ge 0$

The general equilibrium determination

- ▶ Micro-macro constraints and equilibrium conditions:
 - Accounting identity b(t) = k(t),
 - $\blacktriangleright \text{ Then } \dot{b}(t) = \dot{k}(t),$
 - ► Market equilibrium condition

$$y = c + i$$

► From

$$\dot{b}(t) = \dot{k}(t) \iff rb + w - c = i - \delta k \iff rk + w + \delta k = y$$

$$\iff y - \delta k = Ak^{\alpha} - \delta k = rk + w$$

▶ Then we get

$$\dot{k} = A k^{\alpha} - c - \delta k$$

The general equilibrium

▶ We obtain the same dynamic system as in the Ramsey model

$$\dot{k} = Ak(t)^{\alpha} - c(t) - \delta k(t)$$

$$\dot{c} = \frac{c(t)}{\theta} (r(t) - \rho), \text{ where } r(t) = \alpha Ak(t)^{\alpha - 1} - \delta$$

▶ Then the allocations of c and k are equal: we say that the equilibrium is Pareto efficient)

Comparative dynamics

- Assume the economy is in a steady state \bar{c}_0 and \bar{k}_0 for the initial $A_0 = A$. We take \bar{k}_0 as an initial point (or previous k_0)
- ▶ Shock: unanticipated, permanent, increase in TPF $A_1 = A_0 + dA$ for dA > 0 as a result of the pandemic or war
- ▶ We write (\bar{k}_1, \bar{c}_1) the steady state associated to A_1 and take as the new steady state (our previous (\bar{k}, \bar{c}))
- ► Steady state multipliers

$$\begin{split} \frac{\bar{k}_1 - \bar{k}_0}{dA} &= d_A \bar{k}(A) \Big|_{\bar{k} = \bar{k}_0, A = A_0} = \frac{\bar{k}_0}{(1 - \alpha) A_0} \\ \frac{\bar{c}_1 - \bar{c}_0}{dA} &= d_A \bar{c}(A) \Big|_{\bar{k} = \bar{k}_0, A = A_0} = \beta \ d_A \bar{k}(A) \Big|_{\bar{k} = \bar{k}_0, A = A_0} \end{split}$$

Comparative dynamics

▶ The change in the variables in the transition are

$$d_A k(t) = \frac{k(t) - \bar{k}_0}{dA}, \ d_A c(t) = \frac{c(t) - \bar{c}_0}{dA}$$

From equation (5) we have

$$d_A k(t) = d_A \bar{k} \left(1 - e^{-\lambda_s t} \right), \text{ for } t \ge 0$$

$$d_A c(t) = d_A \bar{c} - \lambda_u d_A \bar{k} e^{-\lambda_s t} = d_A \bar{k} \left(\beta - \lambda_u e^{-\lambda_s t} \right), \text{ for } t \ge 0$$

▶ where the long run multipliers are

$$d_A k(\infty) = d_A \bar{k} > 0$$

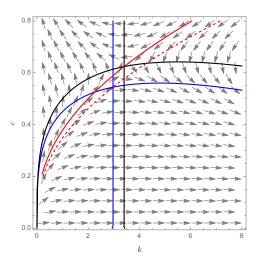
$$d_A c(\infty) = d_A \bar{c} = \beta d_A \bar{k} > 0$$

▶ the impact multipliers are

$$d_A k(0) = 0$$

$$d_A c(0) = d_A \bar{k} (\beta - \lambda_u) \geq 0 \iff \beta \geq \lambda_u$$
(prove this)

Phase diagram for a productivity shock



References

- ► Ramsey (1928), Cass (1965) Koopmans (1965)
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