# Mathematical Economics Continuous time: calculus of variations

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# Continuous time calculus of variations problem

• Find the path  $x^* = (x^*(t): 0 \le t \le T)$  that solves the problem

$$\max_{(x(t))_{t \in [0,T]}} \int_0^T F(t, x(t), \dot{x}(t)) dt$$

- given x(0)
- $\bullet$  given the horizon T
- and possibly other constraints on the value of x(T)

# Calculus of variations: simplest problem

• Find  $x^* = (x^*(t))_{0 \le t \le T}$  that solves the problem:

$$\max_{(x(t))_{t \in [0,T]}} \int_0^T F(t, x(t), \dot{x}(t)) dt$$

given  $x(0) = \phi_0$  and  $x(T) = \phi_T$ .

## CV simplest problem: solution

#### Proposition (Necessary first order conditions)

Let  $x^* = (x^*(t))_{0 \le t \le T}$  be the solution to the simplest CV problem. Then  $x^*$  verifies the following conditions

$$\begin{cases} F_x(t, x^*(t), \dot{x}^*(t)) - \frac{d}{dt} \left( F_x(t, x^*(t), \dot{x}^*(t)) \right) = 0 & Euler \ equation \\ x^*(0) = \phi_0 & initial \ condition \\ x^*(T) = \phi_T & terminal \ condition \end{cases}$$



## The Euler-Lagrange equation

• The Euler equation is a 2nd order ODE (ordinary differential equation)

$$F_x^* = F_{\dot{x}\dot{t}}^* + F_{\dot{x}\dot{x}}^* \dot{x}^* + F_{\dot{x}\dot{x}}^* \ddot{x}^*, \ 0 \le t \le T.$$

# Cake eating problem (terminal state given)

• Find  $C^* = (C^*(t))_{0 \le t \le T}$  that

$$\max_{(C(t))_{t \in [0,T]}} \int_0^T \ln(C(t)) e^{-\rho t} dt$$

• subject to

$$\dot{W}(t) = -C(t)$$
, for  $t \in [0, T]$ 

given  $W(0) = \phi$  and W(T) = 0

 $\bullet$  Formulated as a CV problem: find  $\mathit{W}^* = (\mathit{W}^*(t))_{0 \le t \le \mathit{T}}$  that

$$\max_{(W(t))_{t \in [0,T]}} \int_0^T \ln(-\dot{W}(t)) e^{-\rho t} dt$$

given 
$$W(0) = \phi$$
 and  $W(T) = 0$ 

# Cake eating problem (terminal state given)

• Euler equation

$$\frac{d}{dt}\left(e^{-\rho t}\frac{1}{\dot{W}}\right) = 0 \Leftrightarrow \ddot{W} + \rho \dot{W} = 0$$

- Solution:
  - We know that  $C(t) = -\dot{W}(t)$ , therefore, the Euler equation becomes  $\dot{C} = -\rho C(t)$  with solution

$$C(t) = C(0)e^{-\rho t}$$

where C(0) is unknwon.

• But  $\dot{W}(t) = \frac{dW(t)}{dt} = -C(t)$  can be separated as dW = -C(t)dt. Integrating

$$\int_{W(0)}^{W(t)} dW = - \int_0^t C(s) ds \Leftrightarrow W(t) - W(0) = -C(0) \int_0^t e^{-\rho s} ds$$

• But  $W(0) = \phi$ , and

$$\int_0^t e^{-\rho s} ds = \frac{1}{\rho} \left( 1 - e^{-\rho t} \right)$$

# Cake eating problem (fixed terminal state)

• Then

$$W(t) = \phi - \frac{C(0)}{\rho} \left( 1 - e^{-\rho t} \right)$$

where C(0) is still unknown.

• To find C(0) we use the terminal condition W(T) = 0. Therefore

$$\phi - \frac{C(0)}{\rho} (1 - e^{-\rho T}) = 0 \Rightarrow \frac{C(0)}{\rho} = \phi (1 - e^{-\rho T})^{-1}$$

• The solution to the cake-eating problem is

$$W^*(t) = \frac{e^{-\rho t} - e^{-\rho T}}{1 - e^{-\rho T}} \phi, \text{ for } t \in [0, T]$$

• compare with the discrete time analog.

# Calculus of variations: free end-point problem

• Find  $x = (x(t))_{0 \le t \le T}$  that

$$\max_{(x(t))_{t \in [0,T]}} \int_0^T F(t,x(t),\dot{x}(t)) dt$$

given  $x(0) = \phi_0$ , and x(T) is free.

## CV free endpoint problem: solution

• Necessary conditions: the solution to the CV problem  $x^* = (x^*(t))_{0 \le t \le T}$  verifies:

$$\begin{cases} F_x(t,x^*(t),\dot{x}^*(t)) - \frac{d}{dt}\left(F_{\dot{x}}(t,x^*(t),\dot{x}^*(t))\right) = 0 & \text{Euler equation} \\ x^*(0) = \phi_0 & \text{initial condition} \\ F_{\dot{x}}(T,x^*(T),\dot{x}^*(T)) = 0 & \text{transversality condition} \end{cases}$$

# Cake eating problem (free terminal state)

 As in the previous case, the Euler equation and the initial condition yield

$$W(t) = \phi + \frac{C(0)}{\rho} \left( 1 - e^{-\rho t} \right)$$

where C(0) is unknown.

• To find C(0) we use now the transversality condition  $F_{\dot{W}}(T) = 0$ 

$$F_{\dot{W}}(T) = \frac{e^{-\rho T}}{\dot{W}(T)} = -\frac{e^{-\rho T}}{C(T)} = -\frac{e^{-\rho T}}{C(0)e^{-\rho T}} = -\frac{1}{C(0)}$$

• Then  $F_{\dot{W}}(T) = 0$  if and only if  $C(0) = \infty$  which means that our problem is misspecified.

#### Calculus of variations: constrained terminal state

• Find  $x = (x(t))_{0 \le t \le T}$  that

$$\max_{(x(t))_{t \in [0,T]}} \int_0^T F(t, x(t), \dot{x}(t)) dt$$

given  $x(0) = \phi_0$ , and  $x(T) \ge \phi_T$  where  $\phi_0$  and  $\phi_T$  are given.

## CV constrained terminal state problem: solution

• Necessary conditions: the solution to the CV problem  $x^* = (x^*(t))_{0 \le t \le T}$  verifies:

$$\begin{cases} F_x(t,x^*(t),\dot{x}^*(t)) - \frac{d}{dt}\left(F_{\dot{x}}(t,x^*(t),\dot{x}^*(t))\right) = 0 & \text{Euler equation} \\ x^*(0) = \phi_0 & \text{initial condition} \\ F_{\dot{x}}(T,x^*(T),\dot{x}^*(T))\left(x^*(T) - \phi_T\right) = 0 & \text{transversality condition} \end{cases}$$

# Cake eating problem with $\phi_T = 0$

• As in the previous case, the Euler equation and the initial condition yield

$$W(t) = \phi - \frac{C(0)}{\rho} (1 - e^{-\rho t})$$

where C(0) is an arbitrary constant.

• To find C(0) we use now the transversality condition  $F_{\dot{W}}(T)W(T) = 0$ 

$$F_{\dot{W}}(T)W(T) = -\frac{\phi - \frac{C(0)}{\rho}(1 - e^{-\rho T})}{C(0)} = 0$$

to find again

$$\frac{C(0)}{\rho} = \phi \left(1 - e^{-\rho T}\right)^{-1}$$

• Then the solution is **formally (but not conceptually)** the same as in the fixed terminal state problem.

#### Calculus of variations: discounted infinite horizon

• Find  $x = (x(t))_{t \in \mathbb{R}_+}$  that

$$\max_{(x(t))_{t \in [0,T]}} \int_0^\infty f(x(t), \dot{x}(t)) e^{-\rho t} dt, \ \rho t$$

given 
$$x(0) = \phi_0$$

• Euler equation

$$e^{-\rho t} f_x(x^*, \dot{x}^*) - \frac{d}{dt} \left( e^{-\rho t} f_{\dot{x}}(x^*, \dot{x}^*) \right) = 0$$

• is equivalent to the 2nd order ODE

$$f_x(x^*, \dot{x}^*) + \rho f_{\dot{x}}(x^*, \dot{x}^*) - f_{\dot{x}\dot{x}}(x^*, \dot{x}^*)\dot{x} - f_{\dot{x}\dot{x}}(x^*, \dot{x}^*)\ddot{x} = 0$$

# Calculus of variations: discounted infinite horizon constrained terminal value

• Find  $x = (x(t))_{t \in \mathbb{R}_+}$  that

$$\max_{(x(t))_{t \in [0,T]}} \int_0^\infty f(x(t), \dot{x}(t)) e^{-\rho t} dt, \ \rho t$$

given 
$$x(0) = \phi_0$$
,  $\lim_{t\to\infty} x(t) \ge 0$ 

• Necessary conditions:

$$\begin{cases} f_x(x^*, \dot{x}^*) + \rho f_{\dot{x}}(x^*, \dot{x}^*) - f_{\dot{x}\dot{x}}(x^*, \dot{x}^*) \dot{x} - f_{\dot{x}\dot{x}}(x^*, \dot{x}^*) \ddot{x} = 0 \\ x^*(0) = \phi \\ \lim_{t \to \infty} e^{-\rho t} f_{\dot{x}}(x^*(t), \dot{x}^*(t)) x^*(t) = 0 \end{cases}$$

# Cake eating problem: infinite horizon

• Find  $W^* = (W^*(t))_{t \in \mathbb{R}_+}$  that

$$\max_{(W(t))_{t \in [0,\infty)}} \int_0^\infty \ln\left(-\dot{W}(t)\right) e^{-\rho t} dt$$

given  $W(0) = \phi$  and  $\lim_{t\to\infty} W(t) \ge 0$ 

• The first order conditions are

$$\begin{cases} \rho \, \dot{W}^*(t) + \ddot{W}^*(t) = 0 \\ W^*(0) = \phi \\ -\lim_{t \to \infty} e^{-\rho t} \frac{W^*(t)}{\dot{W}^*(t)} = 0 \end{cases}$$

## Cake eating problem: infinite horizon

 We already found the solution to the Euler equation, given the initial condition to be

$$W(t) = \phi - \frac{C(0)}{a} \left(1 - e^{-\rho t}\right)$$

where C(0) is unknown

• Therefore

$$\dot{W}(t) = -C(0)e^{-\rho t}$$

then

$$-e^{-\rho t} \frac{W^*(t)}{\dot{W}^*(t)} = \frac{1}{C(0)} \left( \phi - \frac{C(0)}{\rho} + \frac{C(0)}{\rho} e^{-\rho t} \right)$$

• Substituting in the transversality condition

$$\lim_{t\to\infty}e^{-\rho t}\frac{W^*(t)}{\dot{W}^*(t)}=\frac{1}{C(0)}\left(\phi-\frac{C(0)}{\rho}\right)=0$$

if and only if  $C(0) = \rho \phi$ 

## Cake eating problem: infinite horizon

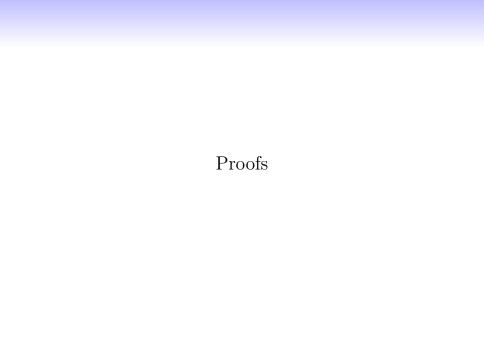
• Therefore, the solution to the problem: find  $W^* = (W^*(t))_{t \in \mathbb{R}_+}$  that

$$\max_{(\mathit{W}(t))_{t \in [0,\infty)}} \int_0^\infty \ln \left(-\, \dot{\mathit{W}}(t)\right) e^{-\rho t} dt$$

given  $W(0) = \phi$  and  $\lim_{t\to\infty} W(t) \ge 0$ 

• is

$$W^*(t) = \phi e^{-\rho t}, \ t \in [0, \infty)$$



#### Proof of proposition 1

- Assume we know the solution  $x^*$  for the problem.
- The optimal value

$$V(x^*) = \int_0^T F(t, x^*(t), \dot{x}^*(t)) dt.$$

• For an admissible perturbation  $x(t) = x^*(t) + \epsilon h(t)$  the value functional is

$$V(x) = \int_0^T F(t, x^*(t) + \epsilon h(t), \dot{x}^*(t) + \epsilon \dot{h}(t)) dt$$

• The variation is  $V(x) - V(x^*)$  is

$$\int_{0}^{T} \left( F_{x}(t, x^{*}(t), \dot{x}^{*}(t)) \epsilon h(t) + F_{\dot{x}}(t, x^{*}(t), \dot{x}^{*}(t)) \epsilon \dot{h}(t) \right) dt$$

$$= \epsilon \left( \int_{0}^{T} \left( F_{x}(t, x^{*}(t), \dot{x}^{*}(t)) h(t) + F_{\dot{x}}(t, x^{*}(t), \dot{x}^{*}(t)) \dot{h}(t) \right) dt \right) =$$

$$= \epsilon \left( \int_{0}^{T} \left( F_{x}(t, x^{*}(t), \dot{x}^{*}(t)) - \frac{d}{dt} F_{\dot{x}}(t, x^{*}(t), \dot{x}^{*}(t)) h(t) \right) dt +$$

$$+ F_{\dot{x}}(T, x^{*}(T), \dot{x}^{*}(T)) h(T) - F_{\dot{x}}(0, x^{*}(0), \dot{x}^{*}(0)) h(0))$$

## Proof of proposition 1

• A functional (or Gâteux) derivative, evaluated at the optimal path, is

$$\delta V(x^*) = \lim_{\epsilon \to 0} \frac{V(x^* + \epsilon h) - V(x^*)}{\epsilon} = \left| \frac{dV(x^*)}{d\epsilon} \right|_{\epsilon = 0}$$

- Then  $\delta V(x^*) = 0$  if and only if the following holds:
  - For the simple CV problem:

$$F_x(t, x^*(t), \dot{x}^*(t)) - \frac{d}{dt}F_{\dot{x}}(t, x^*(t), \dot{x}^*(t)) = 0$$
 and  $h(T) = 0$ 

• For the free-terminal state CV problem:

$$F_x(t, x^*(t), \dot{x}^*(t)) - \frac{d}{dt}F_x(t, x^*(t), \dot{x}^*(t)) = 0$$
 and  $F_x(T, x^*(T), \dot{x}^*(T)) = 0$ 

• Because h(0) = 0 is an admissibility condition.

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