PRAGATHI PRAVEENA

HUMAN-COMPUTER AND HUMAN-ROBOT INTERACTION RESEARCHER

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RESEARCH INTERESTS _____

I have 8+ years of experience prototyping interactive systems and studying user interactions with them using both quantitative and qualitative methods. My research interests include human-centered robotics, robotic cameras, mixed-initiative systems, and computer-supported collaborative work.

EDUCATION _____

2017—Dec 2023 MS and PhD in Computer Science, University of Wisconsin—Madison, USA

(expected) Advisors: Dr. Bilge Mutlu and Dr. Michael Gleicher

2011—2015 **Bachelor of Technology in Electrical Engineering**, Indian Institute of Technology Madras, India

Work & Research Experience _____

2017—Present	Graduate Researc	her , People	and Rob	oots Lab,	University of	f Wisconsin—Madison
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Designed, built, and evaluated human-robot interfaces to enable remote and collaborative work Expanded a grant's original scope by initiating a new research direction that combined HRI & CSCW

2015—2017 **Junior Research Scientist**, Data Analytics Lab, **Xerox Research Centre India**

Developed and evaluated novel algorithms to estimate respiratory patterns using a webcam

Patents licensed by a California-based baby monitor startup

2014—2015 Undergraduate Researcher, Assistive Technology Lab, Indian Institute of Technology Madras

Summer 2014 Undergraduate Researcher, Group for Neural Theory, École Normale Supérieure, France

Summer 2013 **Project Intern**, Electrical and Electronics Maintenance, **Bosch India**

Publications _____

See my <u>Google Scholar</u> and <u>ResearchGate</u> profiles for an up-to-date list of my publications and links to papers.

* indicates equal contribution

JOURNAL ARTICLES

[J3] CSCW '23 Praveena, P., Wang, Y., Senft, E., Gleicher, M., & Mutlu, B. "Periscope: A Robotic Camera System

to Support Remote Physical Collaboration." Proceedings of the ACM on Human-Computer Interaction (PACM-HCI), Track: Computer-Supported Cooperative Work and Social Computing.

ORAL PRESENTATION AT MINNEAPOLIS, MN, USA

[J2] Human Factors '22 Ramesh, B., Konstant, A., **Praveena, P.**, Senft, E., Gleicher, M., Mutlu, B., Zinn, M., & Radwin, R.

G. "Manually Acquiring Targets from Multiple Viewpoints Using Video Feedback." Human

Factors. (Impact factor: 3.6)

[J1] TSP '17 Prathosh, A.P., **Praveena, P.**, Mestha, L.K., & Bharadwaj, S. "Estimation of Respiratory Pattern

from Video Using Selective Ensemble Aggregation." IEEE Transactions on Signal Processing.

(Impact factor: 4.9)

REFEREED FULL CONFERENCE PAPERS

[C10] ICRA '23	Wang, Y., Praveena, P. , Rakita, D., and Gleicher, M. "RangedIK: An Optimization-Based Robot Motion Generation Method for Ranged-Goal Tasks." IEEE International Conference on Robotics and Automation.
[C9] IROS '22	Senft, E.*, Hagenow, M.*, Praveena, P. , Radwin, R., Zinn, M., Gleicher, M., & Mutlu, B. "A Method for Automated Drone Viewpoints to Support Remote Robot Manipulation." IEEE/RSJ International Conference on Intelligent Robots and Systems.
[C8] HRI '22	Praveena, P. , Molina, L., Wang, Y., Senft, E., Mutlu, B., & Gleicher, M. "Understanding Control Frames in Multi-Camera Robot Telemanipulation." ACM/IEEE International Conference on Human-Robot Interaction. (58/234 = 25% acceptance rate) Online Oral Presentation
[C7] HRI '20	Praveena, P. , Rakita, D., Mutlu, B., & Gleicher, M. "Supporting Perception of Weight through Motion-induced Sensory Conflicts in Robot Teleoperation." ACM/IEEE International Conference on Human-Robot Interaction. (67/279 = 24% acceptance rate) Online Oral Presentation [Best Paper Award Finalist]
[C6] ICRA '19	Praveena, P. , Rakita, D., Mutlu, B., & Gleicher, M. "User-Guided Offline Synthesis of Robot Arm Motion from 6-DoF Paths." IEEE International Conference on Robotics and Automation.
[C5] HRI '19	Praveena, P. , Subramani, G., Mutlu, B., & Gleicher, M. "Characterization of Input Methods for Human-to-robot Demonstrations." ACM/IEEE International Conference on Human-Robot Interaction. (48/201 = 24% acceptance rate) ORAL PRESENTATION AT DAEGU, SOUTH KOREA
[C4] BIBE '16	Chatterjee, A., Prathosh, A.P., Praveena, P. , & Upadhya, V. "Real-time Visual Respiration Rate Estimation with Dynamic Scene Adaptation." IEEE International Conference on Bioinformatics and Bioengineering.
[C3] BIBE '16	Chatterjee, A., Prathosh, A.P., Praveena, P. , & Upadhya, V. "A Vision Based Method for Real-time Respiration Rate Estimation Using a Recursive Fourier Analysis." IEEE International Conference on Bioinformatics and Bioengineering.
[C2] BIBE '16	Upadhya, V., Chatterjee, A., Prathosh, A.P., & Praveena, P. "Respiration Monitoring through Thoraco-Abdominal Video with an LSTM." IEEE International Conference on Bioinformatics and Bioengineering.
[C1] EMBC '16	Chatterjee, A., Prathosh, A.P., & Praveena, P. "Real-time Respiration Rate Measurement from Thoracoabdominal Movement with a Consumer Grade Camera." IEEE International Conference of the Engineering in Medicine and Biology Society. <i>Poster Presentation at Orlando, FL, USA</i>

REFEREED EXTENDED ABSTRACTS

[S2] CSCW '23	Meng, H., Wang, Y., Praveena, P. , Gleicher, M., & Mutlu, B. "Demonstrating Periscope: A Robotic Camera System to Support Remote Physical Collaboration." ACM Conference On Computer-Supported Cooperative Work and Social Computing. <i>Demo at Minneapolis, MN, USA</i>
[S1] CHI '23	Praveena, P.* , Cagiltay, B.*, Gleicher, M., & Mutlu, B. "Exploring the Use of Collaborative Robots in Cinematography." ACM Conference on Human Factors in Computing Systems. (330/968 = 34% acceptance rate) POSTER PRESENTATION AT HAMBURG, GERMANY [ACM SIGCHI Gary Marsden Travel Award]

DOCTORAL CONSORTIA

[DC2] HRI '23 Praveena, P., Gleicher, M., & Mutlu, B. "Designing Robotic Camera Systems to Enable

Synchronous Remote Collaboration." ACM/IEEE International Conference on Human-Robot

Interaction. (19/75 = 25% acceptance rate) Poster Presentation at Stockholm, Sweden

[DC1] RSS '20 Praveena, P., Mutlu, B., & Gleicher, M. "Human-Robot Interfaces for Physical Interactions."

Robotics: Science and Systems. (28/88 = 32% acceptance rate) Online Oral Presentation

OTHER PUBLICATIONS

[M2] HCIC '18 Praveena, P., Mutlu, B., & Gleicher, M. "Communicating Physical Interactions to Robots."

Human-Computer Interaction Consortium Workshop: Al and HCI.

POSTER PRESENTATION AT WATSONVILLE, CA, USA

[M1] BEATS '14 Praveena, P., Kavalam, J., & Jacob, N. "A smartphone-based vision simulator." International

Conference on Biomedical Engineering and Assistive Technologies.

ORAL PRESENTATION AT CHANDIGARH, INDIA

PATENTS

[P2] "System and method for extracting a periodic signal from video." 2019. US Patent 10,192,307.

[P1] "Determining respiration rate from a video of a subject breathing." 2018. US Patent 9,861,302.

RESEARCH GRANTS _____

Co-Authored

Expanding Our Vision Award, McPherson Eye Research Institute, UW–Madison

"Designing Interfaces to Enhance the Experience of Remote Vision through Robotic Cameras"

Investigator: Bilge Mutlu (PI); Period: 2023-2024; Amount: \$10,000

Honors & Awards _

- 2023 **ACM SIGCHI Gary Marsden Travel Award**, Full support of \$2200 for travel to CHI (Hamburg, Germany)
- HRI Pioneer, Funded participant in selective doctoral consortium (25% acceptance) at HRI (stockholm, sweden)
- 2020 **RSS Pioneer**, Funded participant in selective doctoral consortium (32% acceptance) at RSS (virtual)
- 2020 **Best Paper Award Finalist** (top 5%), ACM/IEEE Human-Robot Interaction (HRI)
- 2016 **Xerox Patent Award**, Awarded by Xerox Co. to the lead inventor on a filed patent
- 2015 Institute Blues (top 3 in ~800 graduates) and Motorola prize (#1 in ~150 EE and CS graduates)

Recognized for exceptional overall achievement during undergraduate studies at IIT Madras

2014 **French Government Charpak Scholarship**, 2 months support for research at ENS, Paris

MENTORING _

PHD STUDENTS, UW-Madison

2023—Present Yuna Hwang, Expressive robot motion generation using natural language
2023—Present Christine Lee, Explanations for unexpected robot behavior and program repair
2022—2023 Yeping Wang, Robot motion generation for ranged-goal tasks; Paper: C10

PRE-DOCTORAL TRAINEES, UW-Madison

2020—2021 **Luis Molina**, Multi-camera interface for robot telemanipulation; **Paper:** C8

Undergraduate Students, UW-Madison

2022—2023	Haoming Meng, Web interface for robot-supported collaboration; Paper: S2
2022	Lily Reback, Qualitative coding of multi-modal data
2022	Alexander Peseckis, Web-based robot motion viewer
2022	William Cong, VR platform for robot experiments
2021—2022	Gia-phong Nguyen, Web-based robot motion viewer
2021—2022	Sage Livingstone, Blender plugin for creating models of robots and scenes
2019—2020	Jack Yang, VR platform for robot experiments
2019—2020	Sayem Wani, Web interface for MOVO, a mobile bi-manual manipulator robot
2019-2020	Joshua Mathews , Control system for MOVO, a mobile bi-manual manipulator robot

PEER MENTORING, UW-Madison

(April 2022—Present) I structured and executed a peer mentorship program in the People and Robots lab in which 2–3 graduate students meet with a different student mentor each week (original concept by Bengisu Cagiltay). Through this program, I provide peer mentorship to 12 graduate students across various sub-disciplines in HCI including HRI, assistive technology, and interaction design through **weekly sessions**.

Current Mentees: Yuna Hwang, Hailey Johnson, Amy Koike, Callie Kim, Nitzan Orr, Christine Lee, Dakota Sullivan, Irene Ho, Bengisu Cagiltay, Yaxin Hu, Laura Stegner, Nathan White

Past Mentees: Kevin Welsh

Teaching Experience _____

Summers 2018, 2019	Social Robotics Instructor.	Grandparents University, UW-Madison

Co-designed and co-taught lecture and lab session for children and their grandparents

Fall 2017 **Teaching Assistant**, ECE 203: Signals, Information and Computation, UW–Madison

Co-taught in a flipped classroom, held office hours, managed online Q&A for ~200 students

2014—2015 **President and Instructor**, Web Operations Club, Centre for Innovation, IIT Madras

Co-organized introductory and advanced sessions for 400+ students on web development Taught graphics editing and design thinking to 100+ students for web & app development

ACADEMIC SERVICE _____

REVIEWING

2023	Automation in Construction
2023	Proceedings of the ACM on Human-Computer Interaction (PACM-HCI: CSCW)
2023	ACM Conference on Human Factors in Computing Systems (CHI)
2022	IEEE Robotics and Automation Letters (RA-L)
2022	IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)
2021—2023	ACM/IEEE International Conference on Human-Robot Interaction (HRI)

ORGANIZATION

2024	Panel Chair,	Pioneers	Workshop	at HRI.	Boulder.	CO. USA

2021 **Local Chair**, Pioneers Workshop at RSS, Virtual

OUTREACH

2023	Staff, UW–Madison CS recruitment booth, Grace Hopper Celebration, Orlando, FL, USA
2023	Speaker, CS Departmental Research Symposium, UW-Madison
	"Designing Robotic Camera Systems to Enable Synchronous Remote Collaboration"
	[Best Talk Award - Top 2 in 14]
2023	Volunteer , Demos in the lab for 60 students from La Follete High School, Madison, WI, USA
2022	Organizer (along with Yaxin Hu), <u>Human-Centered Computing Meetup</u>

EXTRA-CURRICULAR _____

2019	Morgridge Entrepreneurial Bootcamp, UW-Madison
	Selected to attend a one-week training program in technology entrepreneurship for graduate students
2018	gALPHA Entrepreneurship Program, UW-Madison
	Selected to attend a four-week venture-creation program by <i>gener8tor</i> , a nationally ranked accelerator
2018	Hackathon winner (#1 in 8 teams), EnerHack, UW–Madison
2014	Hackathon winner (#1 in ~20 teams), Geek Up, IIT Madras; Invited to present at Google DevFest, Chennai