PRAGATHI PRAVEENA

HUMAN-COMPUTER AND HUMAN-ROBOT INTERACTION RESEARCHER

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Research Interests _____

I have 8+ years of experience prototyping interactive systems and studying user interactions with them using both quantitative and qualitative methods. My research interests include human-centered robotics, robotic cameras, mixed-initiative systems, and computer-supported collaborative work.

EDUCATION _____

2017—Dec 2023 MS and PhD in Computer Science, University of Wisconsin—Madison, USA

(expected) Advisors: Dr. Bilge Mutlu and Dr. Michael Gleicher

2011—2015 **Bachelor of Technology in Electrical Engineering**, Indian Institute of Technology Madras, India

Work & Research Experience _____

| 2017—Present Graduate Researcher, People and Robots Lab, University of Wisconsin—M | -Madison |
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Designed, built, and evaluated human-robot interfaces to enable remote and collaborative work Expanded a grant's original scope by initiating a new research direction that combined HRI & CSCW

2015—2017 **Junior Research Scientist**, Data Analytics Lab, **Xerox Research Centre India**

Developed and evaluated novel algorithms to estimate respiratory patterns using a webcam

Patents licensed by a California-based baby monitor startup

2014—2015 Undergraduate Researcher, Assistive Technology Lab, Indian Institute of Technology Madras

Summer 2014 Undergraduate Researcher, Group for Neural Theory, École Normale Supérieure, France

Summer 2013 **Project Intern**, Electrical and Electronics Maintenance, **Bosch India**

Publications _____

See my <u>Google Scholar</u> and <u>ResearchGate</u> profiles for an up-to-date list of my publications and links to papers.

* indicates equal contribution

JOURNAL ARTICLES

[J3] CSCW '23 Praveena, P., Wang, Y., Senft, E., Gleicher, M., & Mutlu, B. "Periscope: A Robotic Camera System

to Support Remote Physical Collaboration." Proceedings of the ACM on Human-Computer Interaction (PACM-HCI), Track: Computer-Supported Cooperative Work and Social Computing.

ORAL PRESENTATION AT MINNEAPOLIS, MN, USA

[J2] Human Factors '22 Ramesh, B., Konstant, A., **Praveena, P.**, Senft, E., Gleicher, M., Mutlu, B., Zinn, M., & Radwin, R.

G. "Manually Acquiring Targets from Multiple Viewpoints Using Video Feedback." Human

Factors. (Impact factor: 3.6)

[J1] TSP '17 Prathosh, A.P., **Praveena, P.**, Mestha, L.K., & Bharadwaj, S. "Estimation of Respiratory Pattern

from Video Using Selective Ensemble Aggregation." IEEE Transactions on Signal Processing.

(Impact factor: 4.9)

REFEREED FULL CONFERENCE PAPERS

| INCI ENCED I OLE V | SOM ENERGE I AI ENG |
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| [C10] ICRA '23 | Wang, Y., Praveena, P. , Rakita, D., and Gleicher, M. "RangedIK: An Optimization-Based Robot Motion Generation Method for Ranged-Goal Tasks." IEEE International Conference on Robotics and Automation. |
| [C9] IROS '22 | Senft, E., Hagenow, M., Praveena, P. , Radwin, R., Zinn, M., Gleicher, M., & Mutlu, B. "A Method for Automated Drone Viewpoints to Support Remote Robot Manipulation." IEEE/RSJ International Conference on Intelligent Robots and Systems. |
| [C8] HRI '22 | Praveena, P. , Molina, L., Wang, Y., Senft, E., Mutlu, B., & Gleicher, M. "Understanding Control Frames in Multi-Camera Robot Telemanipulation." ACM/IEEE International Conference on Human-Robot Interaction. (58/234 = 25% acceptance rate) Online Oral Presentation |
| [C7] HRI '20 | Praveena, P. , Rakita, D., Mutlu, B., & Gleicher, M. "Supporting Perception of Weight through Motion-induced Sensory Conflicts in Robot Teleoperation." ACM/IEEE International Conference on Human-Robot Interaction. (67/279 = 24% acceptance rate) Online Oral Presentation [Best Paper Award Finalist] |
| [C6] ICRA '19 | Praveena, P. , Rakita, D., Mutlu, B., & Gleicher, M. "User-Guided Offline Synthesis of Robot Arm Motion from 6-DoF Paths." IEEE International Conference on Robotics and Automation. |
| [C5] HRI '19 | Praveena, P. , Subramani, G., Mutlu, B., & Gleicher, M. "Characterization of Input Methods for Human-to-robot Demonstrations." ACM/IEEE International Conference on Human-Robot Interaction. (48/201 = 24% acceptance rate) ORAL PRESENTATION AT DAEGU, SOUTH KOREA |
| [C4] BIBE '16 | Chatterjee, A., Prathosh, A.P., Praveena, P. , & Upadhya, V. "Real-time Visual Respiration Rate Estimation with Dynamic Scene Adaptation." IEEE International Conference on Bioinformatics and Bioengineering. |
| [C3] BIBE '16 | Chatterjee, A., Prathosh, A.P., Praveena, P. , & Upadhya, V. "A Vision Based Method for Real-time Respiration Rate Estimation Using a Recursive Fourier Analysis." IEEE International Conference on Bioinformatics and Bioengineering. |
| [C2] BIBE '16 | Upadhya, V., Chatterjee, A., Prathosh, A.P., & Praveena, P. "Respiration Monitoring through Thoraco-Abdominal Video with an LSTM." IEEE International Conference on Bioinformatics and Bioengineering. |
| [C1] EMBC '16 | Chatterjee, A., Prathosh, A.P., & Praveena, P. "Real-time Respiration Rate Measurement from Thoracoabdominal Movement with a Consumer Grade Camera." IEEE International Conference of the Engineering in Medicine and Biology Society. <i>Poster Presentation at Orlando, FL, USA</i> |
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REFEREED EXTENDED ABSTRACTS

| [S2] CSCW '23 | Meng, H., Wang, Y., Praveena, P. , Gleicher, M., & Mutlu, B. "Demonstrating Periscope: A Robotic Camera System to Support Remote Physical Collaboration." ACM Conference On Computer-Supported Cooperative Work and Social Computing. <i>Demo at Minneapolis, MN, USA</i> |
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| [S1] CHI '23 | Praveena, P.* , Cagiltay, B.*, Gleicher, M., & Mutlu, B. "Exploring the Use of Collaborative Robots in Cinematography." ACM Conference on Human Factors in Computing Systems. (330/968 = 34% acceptance rate) Poster Presentation at Hamburg, Germany [ACM SIGCHI Gary Marsden Travel Award] |

DOCTORAL CONSORTIA

[DC2] HRI '23 Praveena, P., Gleicher, M., & Mutlu, B. "Designing Robotic Camera Systems to Enable

Synchronous Remote Collaboration." ACM/IEEE International Conference on Human-Robot

Interaction. (19/75 = 25% acceptance rate) Poster Presentation at Stockholm, Sweden

[DC1] RSS '20 Praveena, P., Mutlu, B., & Gleicher, M. "Human-Robot Interfaces for Physical Interactions."

Robotics: Science and Systems. (28/88 = 32% acceptance rate) Online Oral Presentation

OTHER PUBLICATIONS

[M2] HCIC '18 Praveena, P., Mutlu, B., & Gleicher, M. "Communicating Physical Interactions to Robots."

Human-Computer Interaction Consortium Workshop: Al and HCI.

POSTER PRESENTATION AT WATSONVILLE, CA, USA

[M1] BEATS '14 Praveena, P., Kavalam, J., & Jacob, N. "A smartphone-based vision simulator." International

Conference on Biomedical Engineering and Assistive Technologies.

ORAL PRESENTATION AT CHANDIGARH, INDIA

PATENTS

[P2] "System and method for extracting a periodic signal from video." 2019. US Patent 10,192,307.

[P1] "Determining respiration rate from a video of a subject breathing." 2018. US Patent 9,861,302.

RESEARCH GRANTS _____

Co-Authored

Expanding Our Vision Award, McPherson Eye Research Institute, UW-Madison

"Designing Interfaces to Enhance the Experience of Remote Vision through Robotic Cameras"

Investigator: Bilge Mutlu (PI); Period: 2023-2024; Amount: \$10,000

Honors & Awards _

- 2023 **ACM SIGCHI Gary Marsden Travel Award**, Full support of \$2200 for travel to CHI (Hamburg, Germany)
- HRI Pioneer, Funded participant in selective doctoral consortium (25% acceptance) at HRI (stockholm, sweden)
- 2020 **RSS Pioneer**, Funded participant in selective doctoral consortium (32% acceptance) at RSS (virtual)
- 2020 **Best Paper Award Finalist** (top 5%), ACM/IEEE Human-Robot Interaction (HRI)
- 2016 **Xerox Patent Award**, Awarded by Xerox Co. to the lead inventor on a filed patent
- Institute Blues (top 3 in ~800 graduates) and Motorola prize (#1 in ~150 EE and CS graduates)

 Recognized for exceptional overall achievement during undergraduate studies at IIT Madras
- 2014 **French Government Charpak Scholarship**, 2 months research support at ENS, Paris

MENTORING __

PHD STUDENTS, UW-Madison

2023—Present Yuna Hwang, Expressive robot motion generation using natural language
2023—Present Christine Lee, Explanations for unexpected robot behavior and program repair
2022—2023 Yeping Wang, Robot motion generation for ranged-goal tasks; Paper: C10

PRE-DOCTORAL TRAINEES, UW-Madison

2020—2021 **Luis Molina**, Multi-camera interface for robot telemanipulation; **Paper:** C8

Undergraduate Students, UW-Madison

| 2022—2023 | Haoming Meng, Web interface for robot-supported collaboration; Paper: S2 |
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| 2022 | Lily Reback, Qualitative coding of multi-modal data |
| 2022 | Alexander Peseckis, Web-based robot motion viewer |
| 2022 | William Cong, VR platform for robot experiments |
| 2021—2022 | Gia-phong Nguyen, Web-based robot motion viewer |
| 2021—2022 | Sage Livingstone, Blender plugin for creating models of robots and scenes |
| 2019—2020 | Jack Yang, VR platform for robot experiments |
| 2019—2020 | Sayem Wani, Web interface for MOVO, a mobile bi-manual manipulator robot |
| 2019-2020 | Joshua Mathews , Control system for MOVO, a mobile bi-manual manipulator robot |

PEER MENTORING, UW-Madison

(April 2022—Present) I structured and executed a peer mentorship program in the People and Robots lab in which 2–3 graduate students meet with a different student mentor each week (original concept by Bengisu Cagiltay). Through this program, I provide peer mentorship to 12 graduate students across various sub-disciplines in HCI including HRI, assistive technology, and interaction design through **weekly sessions**.

Current Mentees: Yuna Hwang, Hailey Johnson, Amy Koike, Callie Kim, Nitzan Orr, Christine Lee, Dakota Sullivan, Irene Ho, Bengisu Cagiltay, Yaxin Hu, Laura Stegner, Nathan White

Past Mentees: Kevin Welsh

Teaching Experience _____

| Summers 2018, 2019 | Social Robotics Instructor. | Grandparents University, UW-Madison |
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Co-designed and co-taught lecture and lab session for children and their grandparents

Fall 2017 **Teaching Assistant**, ECE 203: Signals, Information and Computation, UW–Madison

Co-taught in a flipped classroom, held office hours, managed online Q&A for ~200 students

2014—2015 **President and Tutor**, Web Operations Club, Centre for Innovation, IIT Madras

Co-organized introductory and advanced sessions for 400+ students on web development Taught graphics editing and design thinking to 100+ students for web & app development

ACADEMIC SERVICE _____

REVIEWING

| 2023 | Automation in Construction |
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| 2023 | Proceedings of the ACM on Human-Computer Interaction (PACM-HCI: CSCW) |
| 2023 | ACM Conference on Human Factors in Computing Systems (CHI) |
| 2022 | IEEE Robotics and Automation Letters (RA-L) |
| 2022 | IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) |
| 2021-2023 | ACM/IEEE International Conference on Human-Robot Interaction (HRI) |

ORGANIZATION

| 2024 | Panel Chair, | Pioneers | Workshop | at HRI. | Boulder. | CO. USA |
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2021 **Local Chair**, Pioneers Workshop at RSS, Virtual

OUTREACH

| 2023 | Staff, UW–Madison CS recruitment booth, Grace Hopper Celebration, Orlando, FL, USA | | |
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| 2023 | Speaker, CS Departmental Research Symposium, UW–Madison | | |
| | "Designing Robotic Camera Systems to Enable Synchronous Remote Collaboration" | | |
| | [Best Talk Award - Top 2 in 14] | | |
| 2023 | Volunteer , Demos in the lab for 60 students from La Follete High School, Madison, WI, USA | | |
| 2022 | Organizer (along with Yaxin Hu), <u>Human-Centered Computing Meetup</u> | | |

EXTRA-CURRICULAR _____

| 2019 | Morgridge Entrepreneurial Bootcamp, UW-Madison |
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| | Selected to attend a one-week training program in technology entrepreneurship for graduate students |
| 2018 | gALPHA Entrepreneurship Program, UW-Madison |
| | Selected to attend a four-week venture-creation program by <i>gener8tor</i> , a nationally ranked accelerator |
| 2018 | Hackathon winner (#1 in 8 teams), EnerHack, UW–Madison |
| 2014 | Hackathon winner (#1 in ~20 teams), Geek Up, IIT Madras; Invited to present at Google DevFest, Chennai |