TBM 1: Prepare Assembly Aid Tray for Force Fitting

Team name:			
Referee name:			
Achievements			
The robot correctly identifies the assembly aid tray and the corresponding QR code: Comment:		yes	no
The robot correctly identifies the container and to Comment:			
The robot inserts the right objects into the aid tray: Comment:			
The robot correctly delivers the tray to the force fitting station: Comment:			
The robot correctly executes the force fitting ope	eration:		
Penalized Behaviors			
The robot bumps into obstacles in the test bed:			
The robot drops an object:			
The robot stops working:			
Disqualifying Behaviors			
The robot damages or destroys the objects reque	ested to manipulate: \square		
The The robot damages the test bed:			
Benchmarking data delivered appropriately	: □ yes / □ no		
Team leader signature:			
Roforco signaturo:			

TBM 2: Plate Drilling

Team name:				
Referee name:				
Achievements				
The robot correctly identifies perfect plates and sorts them in the corresponding card file box:		sponding	yes	no
The robot correctly identifies unusable plates and sorts them in the corresponding card file box: Comment:				
The robot correctly identifies faulty plates, machines them, and sorts them in the corresponding card file box: Comment:				
Penalized Behaviors The robot bumps into obstacles in the test bed:				
The robot drops a plate:				
The robot misses a report:				
The robot stops working:				
Disqualifying Behaviors				
The robot damages or destroys the objects reque	ested to manipulate:			
The robot damages the test bed:	[
Benchmarking data delivered appropriately	7: □ yes / □ no			
Team leader signature:				
Referee signature:				

TBM 3: Fill a Box with Parts for Manual Assembly

Team name:		_		
Referee name:		<u></u>		
Achievements				
The robot correctly identifies the required parts and brings them to the destination: Comment:			yes	no
Penalized Behaviors				
The robot bumps into obstacles in the test bed:				
The robot drops an object:				
The robot stops working:				
Disqualifying Behaviors				
The robot damages or destroys the objects reque	sted to manipulate:			
The robot damages the test bed:				
Benchmarking data delivered appropriately	: □ yes / □ no			
Team leader signature:				
Referee signature:				