TBM 1: Prepare Assembly Aid Tray for Force Fitting

Team name:			
Referee name:			
Achievements		yes	
The robot correctly identifies the assembly aid tray and the corresponding QR code:			no
The robot correctly identifies the container and the corresponding QR code:			
The robot inserts the right objects into the aid tray:			
The robot correctly delivers the tray to the force fitting station:			
The robot correctly executes the force fitting ope	eration:		
Penalized Behaviors			
The robot bumps into obstacles in the test bed:			
The robot drops an object:			
The robot stops working:			
Disqualifying Behaviors			
The robot damages or destroys the objects reque	ested to manipulate: \square		
The The robot damages the test bed:			
Team leader signature:			

TBM 2: Plate Drilling

Team name:		
Referee name:		
Achievements		
The robot correctly identifies perfect plates and sorts them in the corresponding card file box:	yes	no
The robot correctly identifies unusable plates and sorts them in the corresponding card file box:		
The robot correctly identifies faulty plates, machines them, and sorts them in the corresponding card file box:		
Penalized Behaviors The robot bumps into obstacles in the test bed:		
The robot drops a plate: \Box		
The robot misses a report:		
The robot stops working: \Box		
Disqualifying Behaviors		
The robot damages or destroys the objects requested to manipulate: $\ \square$		
The robot damages the test bed: $\hfill\Box$		
Team leader signature:		

TBM 3: Fill a Box with Parts for Manual Assembly

Team name:				
Referee name:				
Achievements				
The robot correctly identifies the required parts	and brings them to t	the destination:	yes	no
Penalized Behaviors				
The robot bumps into obstacles in the test bed:				
The robot drops an object:				
The robot stops working:				
Disqualifying Behaviors				
The robot damages or destroys the objects reque	ested to manipulate:			
The robot damages the test bed:				
Team leader signature:				