Peter Molzer

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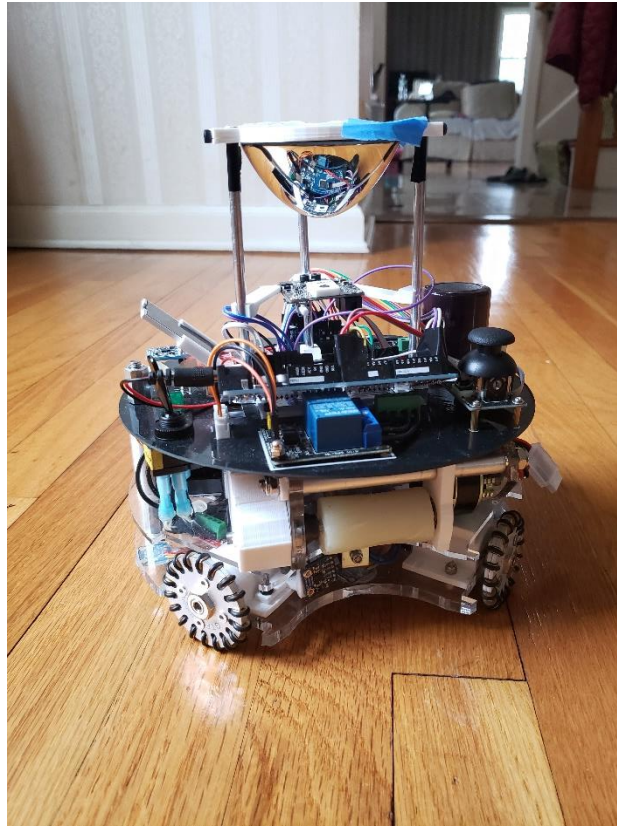
Design Projects

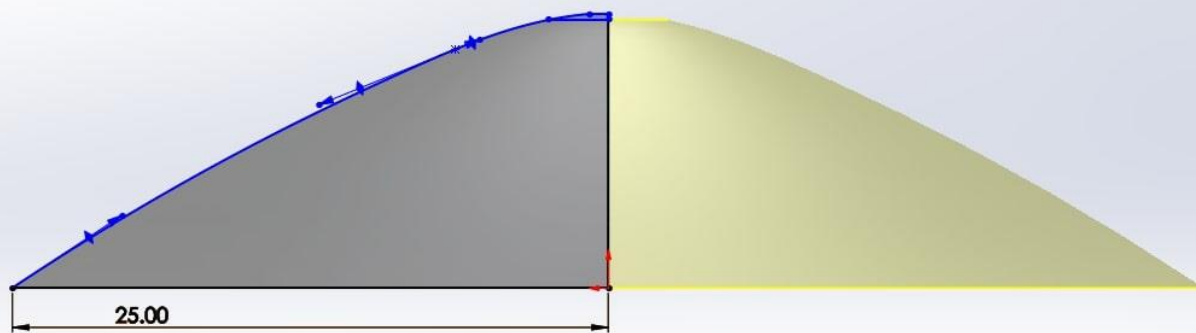*Figure 1: Front view of Robocup Jr. Soccor Robot*

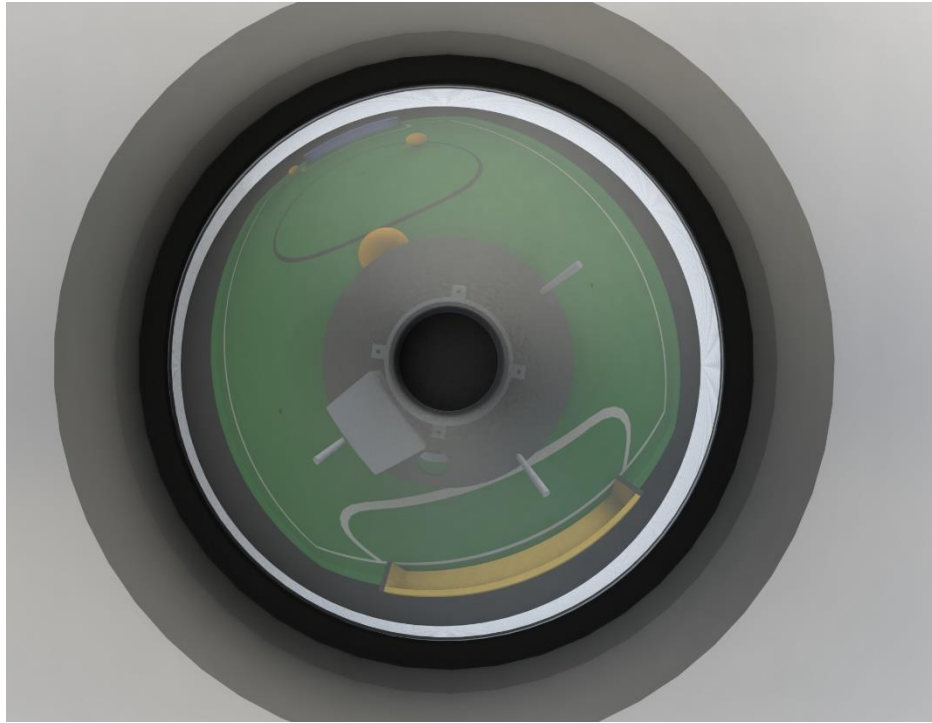*Figure 2: Iteratively designed mirror for single-camera wide range view*

Figure 3: Sample render of mirror before further adjustments

Figure 4: Sample detection of two balls