微积分计算公式

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(1) 直坐标面元: dS = dxdy
   (2) 极坐标面元: dS = r dr d\theta
   (3) 球坐标面元: \mathrm{d}S_{\rho}=\rho^2\sin\varphi\,\mathrm{d}\varphi\,\mathrm{d}\theta,微小变动: \varphi至\varphi+\mathrm{d}\varphi,\theta至\theta+\mathrm{d}\theta,径向距离\rho不变,面元处在球皮上
   (4) 球坐标面元: dS_{\varphi} = \rho \sin \varphi d\rho d\theta, 微小变动: \rho \leq \rho + d\rho, \theta \leq \theta + d\theta, 天顶角\varphi不变, 面元处在一个顶点为原点的圆锥面上
   (5) 球坐标面元: dS_{\theta} = \rho d\rho d\varphi,微小变动: \rho \leq \rho + d\rho,\varphi \leq \varphi + d\varphi,方位角\theta不变,面元处在一个竖直半平面上
   (6) 球坐标体元: dV = \rho^2 \sin \varphi \, d\rho \, d\varphi \, d\theta
   (7) 柱坐标面元: dS_{\rho} = \rho d\theta dz,情形: \rho不变,面元处在一个竖直圆柱面上
   (8) 柱坐标面元: dS_{\theta} = d\rho dz, 情形: \theta不变, 面元处在一个竖直半平面上
   (9) 柱坐标面元: dS_z = \rho d\rho d\varphi, 情形: z不变, 面元处在一个水平平面上
(10) 柱坐标体元: dV = \rho d\rho d\theta dz
(11) 极坐标换元公式: x = r \cos \theta, y = r \sin \theta, 雅可比: r
(12) 球坐标换元公式: x = \rho \sin \varphi \cos \theta, y = \rho \sin \varphi \sin \theta, z = \rho \cos \varphi, 雅可比: \rho^2 \sin \varphi
(13) 柱坐标换元公式: x = \rho \cos \theta, y = \rho \sin \theta, z = z, 雅可比: \rho
(14) 广义极坐标换元: x = ra\cos\theta, y = rb\sin\theta, 雅可比: rab
(15) 广义球坐标换元: x = a\rho \sin \varphi \cos \theta, y = b\rho \sin \varphi \sin \theta, z = c\rho \cos \varphi, 雅可比: abc\rho^2 \sin \varphi
(16) f(x) 旋转生成体的侧面积: 2\pi \int_a^b f(x) \sqrt{1 + \left[\frac{\mathrm{d}f(x)}{\mathrm{d}x}\right]^2} \, \mathrm{d}x, 体积: \pi \int_a^b [f(x)]^2 \, \mathrm{d}x
(17) 极坐标表示的弧r(\theta)从\theta=a到\theta=b间的弧长: \int_a^b \sqrt{\left[r(\theta)\right]^2+\left[\frac{\mathrm{d}r(\theta)}{\mathrm{d}\theta}\right]^2}\mathrm{d}\theta, 夹在\theta=a和\theta=b之间部分的面积: \frac{1}{2}\int_a^b \left[r(\theta)\right]^2\mathrm{d}\theta
(18) 曲线\mathbf{r}(t)在\mathbf{r}(t_0)处的切线方程: \mathbf{r}(t) = \mathbf{r}(t_0) + \mathbf{r}'(t_0)(t - t_0)
(19) 曲线\mathbf{r}(t)的线元: \mathrm{d}l = |\mathbf{r}'(t)|\mathrm{d}t
(20) 曲线\mathbf{r}(t)从t = a到t = b段的弧长: \int_a^b |\mathbf{r}'(t)| dt
(21) 曲面\mathbf{r}(u,v)的法向量: \mathbf{n} = \frac{\partial \mathbf{r}}{\partial u}(u,v) \times \frac{\partial \mathbf{r}}{\partial v}(u,v)
(22) 曲面\mathbf{r}(u,v)过\mathbf{r}_0点的切平面方程: (\mathbf{r}-\mathbf{r}_0)\cdot\mathbf{n}=0, 其中\mathbf{n}为\mathbf{r}_0处法向量
(23) 曲面\mathbf{r}(u,v)的面元: dS = |\mathbf{n}| du dv, 其中\mathbf{n}为面元处的法向量(定义如上上条,不可随意数乘)
(24) 为计算方便,定义E = \mathbf{r}_u \cdot \mathbf{r}_u, F = \mathbf{r}_u \cdot \mathbf{r}_v, G = \mathbf{r}_v \cdot \mathbf{r}_v,则曲面\mathbf{r}(u, v)的面元: dS = \sqrt{EF - G^2} du dv
(25) 特别地, 当\mathbf{r}(x,y) = (x,y,f(x,y)), 曲面\mathbf{r}(x,y)的法向量: \mathbf{n} = (-f_x,-f_y,1)
(26) 特别地, 当\mathbf{r}(x,y) = (x,y,f(x,y)), 曲面\mathbf{r}(x,y)的面元: dS = \sqrt{1 + f_x^2(x,y) + f_y^2(x,y)} dx dy
(27) 特别地, 当\mathbf{r}(x,y) = (x,y,f(x,y)), 曲面\mathbf{r}(x,y)的面积: \iint_D \sqrt{1 + f_x^2(x,y) + f_y^2(x,y)} dxdy
(28) 直坐标系线元: dr^2 = dx^2 + dy^2
(29) 极坐标系线元: dr^2 = dr^2 + r^2 d\theta^2
(30) 球坐标系线元: dr^2 = d\rho^2 + \rho^2 d\varphi^2 + \rho^2 \sin^2 \varphi \ d\theta^2 \quad \Rightarrow \quad d\mathbf{r} = d\rho \,\hat{\boldsymbol{\rho}} + \rho \,d\varphi \,\hat{\boldsymbol{\varphi}} + \rho \sin \varphi d\theta \,\hat{\boldsymbol{\theta}}
(31) 柱坐标系线元: dr^2 = d\rho^2 + \rho^2 d\theta^2 + dz^2 \Rightarrow d\mathbf{r} = d\rho \,\hat{\boldsymbol{\rho}} + \rho \,d\theta \,\hat{\boldsymbol{\theta}} + dz \,\hat{\mathbf{z}}
(32) 直坐标系nabla算子: \nabla = \frac{\partial}{\partial x} \hat{\mathbf{x}} + \frac{\partial}{\partial y} \hat{\mathbf{y}} + \frac{\partial}{\partial z} \hat{\mathbf{z}}
(33) 柱坐标系nabla算子: \nabla = \hat{\boldsymbol{\rho}} \frac{\partial}{\partial \rho} + \hat{\boldsymbol{\theta}} \frac{1}{\rho} \frac{\partial}{\partial \theta} + \hat{\mathbf{z}} \frac{\partial}{\partial z}
(34) 直坐标系Laplace算子: \Delta = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} = \nabla \cdot \nabla = \nabla^2
(35) 柱坐标系Laplace算子: \Delta f = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left( \rho \frac{\partial f}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 f}{\partial \theta^2} + \frac{\partial^2 f}{\partial z^2}.
(36) 球坐标系Laplace算子: \Delta f = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \frac{\partial f}{\partial r}) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta \frac{\partial f}{\partial \theta}) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \varphi^2}
(37) 牛顿 - 莱布尼茨公式: \varphi(\mathbf{b}) - \varphi(\mathbf{a}) = \int_a^b \nabla \varphi(\mathbf{r}) \cdot d\mathbf{r}
(38) 斯托克斯公式: \oint_{\partial S} \mathbf{F} \cdot d\mathbf{r} = \int_{S} \nabla \times \mathbf{F} \cdot d\mathbf{S} (39) 高斯公式: \oint_{\partial \Omega} \mathbf{A} \cdot d\mathbf{S} = \iiint_{\Omega} \nabla \cdot \mathbf{A} dv
(40) \mathbf{A} \times \mathbf{B} = -\mathbf{B} \times \mathbf{A}
                                                                                                                               (43) (\mathbf{A} \times \mathbf{B}) \cdot (\mathbf{C} \times \mathbf{D}) = (\mathbf{A} \cdot \mathbf{C}) (\mathbf{B} \cdot \mathbf{D}) - (\mathbf{B} \cdot \mathbf{C}) (\mathbf{A} \cdot \mathbf{D})
(41) \mathbf{A} \cdot (\mathbf{B} \times \mathbf{C}) = \mathbf{B} \cdot (\mathbf{C} \times \mathbf{A}) = \mathbf{C} \cdot (\mathbf{A} \times \mathbf{B})
                                                                                                                              (44) (\mathbf{A} \times \mathbf{B}) \times (\mathbf{C} \times \mathbf{D}) = (\mathbf{A} \cdot \mathbf{B} \times \mathbf{D}) \mathbf{C} - (\mathbf{A} \cdot \mathbf{B} \times \mathbf{C}) \mathbf{D}
(42) \mathbf{A} \times (\mathbf{B} \times \mathbf{C}) = (\mathbf{A} \cdot \mathbf{C}) \mathbf{B} - (\mathbf{A} \cdot \mathbf{B}) \mathbf{C}
(45) curl (grad f) = \nabla \times (\nabla f) = 0
                                                                                                                               (53) \nabla \cdot (\mathbf{A} \times \mathbf{B}) = \mathbf{B} \cdot \nabla \times \mathbf{A} - \mathbf{A} \cdot \nabla \times \mathbf{B}
(46) div (curl \vec{v}) = \nabla \cdot \nabla \times \vec{v} = 0
                                                                                                                               (54) \nabla \times (\mathbf{A} \times \mathbf{B}) = \mathbf{A}(\nabla \cdot \mathbf{B}) - \mathbf{B}(\nabla \cdot \mathbf{A}) + (\mathbf{B} \cdot \nabla)\mathbf{A} - (\mathbf{A} \cdot \nabla)\mathbf{B}
                                                                                                                               (55) \mathbf{A} \times (\nabla \times \mathbf{B}) = \nabla_B (\mathbf{A} \cdot \mathbf{B}) - (\mathbf{A} \cdot \nabla) \mathbf{B},
(47) \operatorname{div}(\operatorname{grad} f) = \nabla \cdot (\nabla f) = \nabla^2 f = \Delta f
(48) \nabla \times \nabla \times \vec{v} = \nabla(\nabla \cdot \vec{v}) - \nabla^2 \vec{v}
                                                                                                                               (56) \nabla \cdot (\psi \mathbf{A}) = \mathbf{A} \cdot \nabla \psi + \psi \nabla \cdot \mathbf{A}
(49) \ \nabla(\nabla \cdot \vec{v}) = \nabla \cdot (\nabla \otimes \vec{v})
                                                                                                                              (57) \nabla \times (\psi \mathbf{A}) = \psi \nabla \times \mathbf{A} + \nabla \psi \times \mathbf{A}
(50) \nabla \cdot (\mathbf{A} + \mathbf{B}) = \nabla \cdot \mathbf{A} + \nabla \cdot \mathbf{B}
                                                                                                                              (58) \nabla(\psi \phi) = \phi \nabla \psi + \psi \nabla \phi
(51) \nabla \times (\mathbf{A} + \mathbf{B}) = \nabla \times \mathbf{A} + \nabla \times \mathbf{B}
(52) \nabla (\mathbf{A} \cdot \mathbf{B}) = (\mathbf{A} \cdot \nabla) \mathbf{B} + (\mathbf{B} \cdot \nabla) \mathbf{A} + \mathbf{A} \times (\nabla \times \mathbf{B}) + \mathbf{B} \times (\nabla \times \mathbf{A})
(59) \operatorname{arctanh}(x) = \frac{1}{2} \ln \frac{1+x}{1-x}
(60) \operatorname{arcsinh}(x) = \ln(x + \sqrt{x^2 + 1})
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 $(61) \int \frac{1}{1+x^2} \, \mathrm{d}x = \arctan(x)$

(62) $\int \frac{1}{1-x^2} dx = \operatorname{arctanh}(x)$ (63) $\int \frac{1}{\sqrt{1+x^2}} dx = \operatorname{arcsinh}(x)$ (64) $\int \frac{1}{\sqrt{1-x^2}} dx = \operatorname{arcsin}(x)$

(65) $\int \sqrt{1+x^2} \, dx = \frac{1}{2} x \sqrt{1+x^2} + \frac{1}{2} \operatorname{arcsinh}(x)$

(66) $\int \sqrt{1-x^2} \, dx = \frac{1}{2} x \sqrt{1-x^2} + \frac{1}{2} \arcsin(x)$

(67) $\int \tan x \, dx = -\ln(\cos(x))$ (68) $\int \cot x \, dx = \ln(\sin(x))$ (69) $\int \frac{1}{\cos^2(x)} \, dx = \tan x$ (70) $\int \frac{1}{\sin^2(x)} \, dx = -\cot x$