

# Homework 7

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## 8.7. Prove the properties of the Operator Norm

1. Prove  $\|X\| \leq \|X\| \|Y\|$

$$\|XY\| = \sup_{\alpha \neq 0} \frac{\|XY|\alpha\rangle\|}{\| |\alpha\rangle \|} = \frac{\|XY|\alpha\rangle\|}{\|Y|\alpha\rangle\|} \frac{\|Y|\alpha\rangle\|}{\| |\alpha\rangle \|}$$

If we consider  $\|Y|\alpha\rangle\| = \beta$  then,

$$\begin{aligned} \|XY\| &= \sup_{\alpha \neq 0} \frac{\|X|\beta\rangle\|}{\| |\beta\rangle \|} \frac{\|Y|\alpha\rangle\|}{\| |\alpha\rangle \|} \\ &\leq \sup_{\beta \neq 0} \frac{\|X|\beta\rangle\|}{\| |\beta\rangle \|} \sup_{\alpha \neq 0} \frac{\|Y|\alpha\rangle\|}{\| |\alpha\rangle \|} \\ &\leq \|X\| \|Y\| \end{aligned}$$

2. Prove  $\|X^\dagger\| = \|X\|$

Let  $\lambda$  be the Eigenvalue such that  $\|A\alpha\| = \lambda\|\alpha\|$

$$\|A\| = \sup_{\alpha \neq 0} \frac{\|A|\alpha\rangle\|}{\| |\alpha\rangle \|} = \sup_{\alpha \neq 0} \frac{\lambda\|\alpha\|}{\| |\alpha\rangle \|}$$

We know that  $XX^\dagger|\alpha\rangle = X^\dagger X|\alpha\rangle = \lambda\alpha$

$$= \sup_{\alpha \neq 0} \frac{\lambda\|\alpha\|}{\| |\alpha\rangle \|} = \sup_{\alpha \neq 0} \frac{\|A^\dagger|\alpha\rangle\|}{\| |\alpha\rangle \|} = \|A^\dagger\|$$

$$\Rightarrow \|X^\dagger\| = \|X\|$$

the  $|\alpha\rangle$  in the sup ranges over all  $|\alpha\rangle$ , not just eigenvectors.

not true.  $XX^\dagger + X^\dagger X$  have same eigenvalues, not eigenvectors.

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3. Prove  $\|X \otimes Y\| = \|X\| \|Y\|$

We know that,

$$\begin{aligned} \|X \otimes I|\alpha\rangle\| &\leq \|X\| \|\alpha\| \\ \|I \otimes Y|\alpha\rangle\| &\leq \|Y\| \|\alpha\| \end{aligned}$$

If we combine above equations, we get,

$$\begin{aligned} \|X \otimes Y\| &\leq \|X \otimes I\| \|I \otimes Y\| \\ &= \|X\| \|Y\| \end{aligned}$$

clear

4. Prove  $\|U\| = 1$

$$\|U\| = \sup_{\alpha \neq 0} \frac{\|U|\alpha\rangle\|}{\||\alpha\rangle\|}$$

We know that, Unitary operator preserves the Geometry of the vector.

Its inner product will not change,

$$\Rightarrow \|U|\alpha\rangle\| = \sqrt{\langle\alpha|\alpha\rangle}$$

$$\||\alpha\rangle\| = \sqrt{\langle\alpha|\alpha\rangle}$$

$$\|U\| = \frac{\sqrt{\langle\alpha|\alpha\rangle}}{\sqrt{\langle\alpha|\alpha\rangle}} = 1$$

**8.8.a** If  $\tilde{U}$  approximates  $U$  with precision  $\delta$ , then  $\tilde{U}^{-1}$  approximates  $U^{-1}$  with the same precision  $\delta$

1. Let precision be  $\delta$ , then  $\|\tilde{U} - U\| \leq \delta$ .

2. Use ancillas  $\tilde{U}^{-1}, U^{-1}$  on the left and right side respectively,

$$\delta \geq \|\tilde{U}^{-1}\| \|\tilde{U} - U\| \|U^{-1}\|$$

$$\geq \|\tilde{U}^{-1}\tilde{U}U^{-1} - \tilde{U}^{-1}UU^{-1}\|$$

3. We know that,  $\tilde{U}^{-1}\tilde{U} = UU^{-1} = I$

$$\Rightarrow \delta \geq \|U^{-1} - \tilde{U}^{-1}\|$$

4. From above equation, we can say that  $\tilde{U}^{-1}$  approximates  $U^{-1}$  with the precision  $\delta$

**8.8.b** If unitary operators  $\tilde{U}_k$  approximate unitary operators  $U_k (1 \leq k \leq L)$  with precision  $\delta_k$ , then  $\tilde{U}_L \dots \tilde{U}_1$  approximate  $U_L \dots U_1$  with precision  $\sum_k \delta_k$

1. If we consider  $k = 2$ , the approximate realization can be written as,

$$\|\tilde{U}_1\tilde{U}_2 - U_1U_2\| = \|\tilde{U}_1\tilde{U}_2 - U_1U_2 + \tilde{U}_1U_2 - U_2\tilde{U}_1\|$$

$$= \|\tilde{U}_1(\tilde{U}_2 - U_2) + (\tilde{U}_1 - U_1)U_2\|$$

By using Triangle inequality,

$$\leq \|\tilde{U}_1(\tilde{U}_2 - U_2)\| + \|(\tilde{U}_1 - U_1)U_2\|$$

$$\leq \|\tilde{U}_1\| \|\tilde{U}_2 - U_2\| + \|(\tilde{U}_1 - U_1)\| \|U_2\|$$

**2.** As our operators are unitary, we can say  $\|\tilde{U}_1\| = \|U_2\| = 1$

$$\|\tilde{U}_1\tilde{U}_2 - U_1U_2\| = \|(\tilde{U}_2 - U_2)\| + \|(\tilde{U}_1 - U_1)\| = \delta_2 + \delta_1$$

**3.** By above equation, we can say that  $\tilde{U}_L \dots \tilde{U}_1$  approximate  $U_L \dots U_1$  with precision  $\sum_k \delta_k$

1.

After  $K$  iterations of  $G$  in Grover's algorithm, we obtained

$$G^K |\psi(1,1)\rangle = |\psi(\frac{1}{\sqrt{a}} \sin((2K+1)\theta), \frac{1}{\sqrt{b}} \cos((2K+1)\theta))\rangle$$

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what is the probability of measuring state  $|A\rangle$

we know that

$$|\psi(\alpha, \beta)\rangle = \alpha |A\rangle + \beta |B\rangle \quad - (1)$$

$$\text{where } |A\rangle := \frac{1}{\sqrt{2^n}} |s\rangle; |B\rangle = \frac{1}{\sqrt{2^n}} \sum |x\rangle$$

$$a := \langle A|A\rangle = \frac{1}{2^n} \quad b := \langle B|B\rangle = 1-a \quad - (2)$$

$$|\psi(1,1)\rangle = |A\rangle + |B\rangle \quad \text{from } - (1)$$

$$G^K |\psi(1,1)\rangle = |\psi(\frac{1}{\sqrt{a}} \sin((2K+1)\theta), \frac{1}{\sqrt{b}} \cos((2K+1)\theta))\rangle$$

$$= \frac{1}{\sqrt{a}} \sin((2K+1)\theta) |A\rangle + \frac{1}{\sqrt{b}} \cos((2K+1)\theta) |B\rangle \quad - \text{from } (1)$$

we know that, if  $|v\rangle = d_x |x\rangle + d_y |y\rangle$

the probability of measuring  $|x\rangle$  in the state is  $|d_x|^2$   
the probability of measuring  $|y\rangle$  in the state  $v$  is  $|d_y|^2$

Similarly, Probability of measuring  $|A\rangle$  in  $G^K |\psi(1,1)\rangle$  is

$$= \left| \frac{1}{\sqrt{a}} \sin((2K+1)\theta) \right|^2 = \frac{1}{a} (\sin((2K+1)\theta))^2$$

$$\text{if } K = \pi/4\theta, \sin((2K+1)\theta) = \sin(\frac{\pi}{2} + \theta) = (\cos \theta)$$

we know that

$$\text{if } a = 1/2^n \quad \sin \theta = \sqrt{a}; \quad \cos \theta = \sqrt{b}$$

Probability of measuring  $|A\rangle$

$$\geq (\cos \theta)^2$$

$$\geq b$$

$$\geq (1-a) \quad (\text{from } (2))$$

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OK, but  
you  
need to  
look @ the  
error when we  
take  
as  $K = \pi/4\theta$ .



2.

(2) validate

$$\begin{bmatrix} b-a & 2b \\ -2a & b-a \end{bmatrix} = \frac{1}{2\sqrt{ab}} \begin{bmatrix} i\sqrt{b} & -i\sqrt{b} \\ \sqrt{a} & \sqrt{a} \end{bmatrix} \begin{bmatrix} \bar{d} & 0 \\ 0 & d \end{bmatrix} \begin{bmatrix} -i\sqrt{a} & \sqrt{b} \\ i\sqrt{a} & \sqrt{b} \end{bmatrix}$$

$$d = e^{i\theta} = \sqrt{b} + i\sqrt{a}$$

$$\bar{d} = \sqrt{b} - i\sqrt{a}$$

$$\begin{bmatrix} i\sqrt{b} & -i\sqrt{b} \\ \sqrt{a} & \sqrt{a} \end{bmatrix} \begin{bmatrix} \bar{d} & 0 \\ 0 & d \end{bmatrix} = \begin{bmatrix} \overset{(1)}{i\sqrt{b}\bar{d}} & \overset{(2)}{-i\sqrt{b}d} \\ \overset{(3)}{\sqrt{a}\bar{d}} & \overset{(4)}{\sqrt{a}d} \end{bmatrix}$$

$$\textcircled{1} i\sqrt{b}(\sqrt{b} - i\sqrt{a}) = (ib\sqrt{b} - ia\sqrt{b} + 2b\sqrt{a})$$

$$\textcircled{2} -i\sqrt{b}(\sqrt{b} + i\sqrt{a}) = (-ib\sqrt{b} + ia\sqrt{b} + 2b\sqrt{a})$$

$$\textcircled{3} \sqrt{a}(\sqrt{b} - i\sqrt{a}) = (b\sqrt{a} - a\sqrt{a} - 2ia\sqrt{b})$$

$$\textcircled{4} \sqrt{a}(\sqrt{b} + i\sqrt{a}) = (b\sqrt{a} - a\sqrt{a} + 2ia\sqrt{b})$$

$$\begin{bmatrix} \textcircled{1} & \textcircled{2} \\ \textcircled{3} & \textcircled{4} \end{bmatrix} \begin{bmatrix} -i\sqrt{a} & \sqrt{b} \\ i\sqrt{a} & \sqrt{b} \end{bmatrix} = \begin{bmatrix} \overset{(P)}{-i\sqrt{a}\textcircled{1} + i\sqrt{a}\textcircled{2}} & \overset{(Q)}{\sqrt{b}(\textcircled{1} + \textcircled{2})} \\ \overset{(R)}{-i\sqrt{a}\textcircled{3} + i\sqrt{a}\textcircled{4}} & \overset{(S)}{\sqrt{b}(\textcircled{3} + \textcircled{4})} \end{bmatrix}$$

$$P = 2\sqrt{ab}(b-a)$$

$$Q = 4b\sqrt{ab}$$

$$R = -4a\sqrt{ab}$$

$$S = 2\sqrt{ab}(b-a)$$

$$\begin{aligned} &= \frac{1}{2\sqrt{ab}} \begin{bmatrix} P & Q \\ R & S \end{bmatrix} = \frac{1}{2\sqrt{ab}} \begin{bmatrix} 2\sqrt{ab}(b-a) & 4b\sqrt{ab} \\ -4a\sqrt{ab} & 2\sqrt{ab}(b-a) \end{bmatrix} \\ &= \begin{bmatrix} b-a & 2b \\ -2a & b-a \end{bmatrix} \end{aligned}$$