

Stochastic Processes

Problems on Convergence of Sequences of Random Variables

Karthik P. N.

Assistant Professor, Department of AI

Email: pnkarthik@ai.iith.ac.in

07/08 February 2025

• Let $\{X_n\}_{n=1}^{\infty}$ be a sequence of independent random variables with

$$\mathbb{P}\left(X_n=rac{1}{2}\left(1-rac{1}{n}
ight)
ight)=\mathbb{P}\left(X_n=rac{1}{2}\left(1+rac{1}{n}
ight)
ight)=rac{1}{2}.$$

- Determine whether $\{X_n\}_{n=1}^{\infty}$ converges in mean-squared sense.
- Determine whether $\{X_n\}_{n=1}^{\infty}$ converges in almost-sure sense.

• Let $\{X_n\}_{n=1}^{\infty}$ be a sequence of independent random variables with

$$\mathbb{P}\left(X_n = \frac{1}{2}\left(1 - \frac{1}{n}\right)\right) = \mathbb{P}\left(X_n = \frac{1}{2}\left(1 + \frac{1}{n}\right)\right) = \frac{1}{2}\left(1 - \frac{1}{n}\right), \qquad \mathbb{P}(X_n = 1) = \frac{1}{n}.$$

- Determine whether $\{X_n\}_{n=1}^{\infty}$ converges in distribution.
- Determine whether $\{X_n\}_{n=1}^{\infty}$ converges in almost-sure sense.

• For each $n \in \mathbb{N}$, let

$$X_n \sim \mathcal{N}\left(0, \frac{1}{n}
ight).$$

Determine the limit and the forms of convergence.

• Let $X_1, X_2, \cdots \overset{\text{i.i.d.}}{\sim} \operatorname{Exp}(1)$. For each $n \in \mathbb{N}$, let

$$Y_n = \max\{X_1,\ldots,X_n\}.$$

- Compute the CDF of Y_n .
- Show that

$$\lim_{n\to\infty} \mathbb{P}(Y_n \leq a \log n) = egin{cases} 0, & a < 1, \ 1, & a > 1. \end{cases}$$

What can you conclude from this result about the sequence $\left\{\frac{Y_n}{\log n}\right\}_{n=1}^{\infty}$?

• Let $W_1, W_2, \cdots \overset{\text{i.i.d.}}{\sim} \mathcal{N}(0, \sigma^2)$ for some fixed $\sigma > 0$. Let $X_0 = 0$, and for each $n \in \mathbb{N}$, let

$$X_{n+1} = \frac{X_n + W_{n+1}}{2}.$$

Prove that $\{X_n\}_{n=1}^{\infty}$ converges in distribution.



In a computer vision application, you have trained a neural network to detect objects in images by predicting bounding boxes. Each bounding box is represented by (x, y) coordinates for its center (along with width and height). After deployment, you suspect there might be a systematic bias in the predicted x-coordinate of the bounding box centers. For instance, the model might be consistently shifting bounding boxes slightly to the left or right. Let

 $X_i = (\text{predicted } x_i) - (\text{ground truth } x_i)$ for *i*th image.



In a computer vision application, you have trained a neural network to detect objects in images by predicting bounding boxes. Each bounding box is represented by (x, y) coordinates for its center (along with width and height). After deployment, you suspect there might be a systematic bias in the predicted x-coordinate of the bounding box centers. For instance, the model might be consistently shifting bounding boxes slightly to the left or right. Let

$$X_i = (\text{predicted } x_i) - (\text{ground truth } x_i) \quad \text{for } i \text{th image.}$$

A reasonable model: $X_1, X_2, \cdots \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(\mu, 1)$, where μ is unknown model parameter



In a computer vision application, you have trained a neural network to detect objects in images by predicting bounding boxes. Each bounding box is represented by (x, y) coordinates for its center (along with width and height). After deployment, you suspect there might be a systematic bias in the predicted x-coordinate of the bounding box centers. For instance, the model might be consistently shifting bounding boxes slightly to the left or right. Let

$$X_i = (\text{predicted } x_i) - (\text{ground truth } x_i)$$
 for *i*th image.

A reasonable model: $X_1, X_2, \cdots \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(\mu, 1)$, where μ is unknown model parameter

• Suppose that model parameter is θ . Define loss under θ as

$$\ell(X_1,\ldots,X_n;\theta)=\frac{1}{n}\sum_{i=1}^n(X_i-\theta)^2.$$



In a computer vision application, you have trained a neural network to detect objects in images by predicting bounding boxes. Each bounding box is represented by (x, y) coordinates for its center (along with width and height). After deployment, you suspect there might be a systematic bias in the predicted x-coordinate of the bounding box centers. For instance, the model might be consistently shifting bounding boxes slightly to the left or right. Let

$$X_i = (\text{predicted } x_i) - (\text{ground truth } x_i)$$
 for *i*th image.

A reasonable model: $X_1, X_2, \cdots \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(\mu, 1)$, where μ is unknown model parameter

• Suppose that model parameter is θ . Define loss under θ as

$$\ell(X_1,\ldots,X_n;\theta)=\frac{1}{n}\sum_{i=1}^n(X_i-\theta)^2.$$

Determine the model parameter $\widehat{\theta}_n$ that minimizes the loss and hence fits the data best.

In a computer vision application, you have trained a neural network to detect objects in images by predicting bounding boxes. Each bounding box is represented by (x, y) coordinates for its center (along with width and height). After deployment, you suspect there might be a systematic bias in the predicted x-coordinate of the bounding box centers. For instance, the model might be consistently shifting bounding boxes slightly to the left or right. Let

$$X_i = (\text{predicted } x_i) - (\text{ground truth } x_i)$$
 for *i*th image.

A reasonable model: $X_1, X_2, \cdots \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(\mu, 1)$, where μ is unknown model parameter

• Suppose that model parameter is θ . Define loss under θ as

$$\ell(X_1,\ldots,X_n;\theta)=\frac{1}{n}\sum_{i=1}^n(X_i-\theta)^2.$$

Determine the model parameter $\widehat{\theta}_n$ that minimizes the loss and hence fits the data best.

• Show that $\widehat{\theta}_n \xrightarrow{\text{a.s.}} \mu$.



Consider a large language model that produces token embeddings at some intermediate layer (say L). Each token embedding is a vector in \mathbb{R}^d for some large d. Focus on the first coordinate X of the vector embedding, and suppose that you observe, across many contexts, the value of X. Denote these values by X_1, X_2, \ldots



Consider a large language model that produces token embeddings at some intermediate layer (say L). Each token embedding is a vector in \mathbb{R}^d for some large d. Focus on the first coordinate X of the vector embedding, and suppose that you observe, across many contexts, the value of X. Denote these values by X_1, X_2, \ldots

A plausible model: $X_1, X_2, \cdots \overset{\mathrm{i.i.d.}}{\sim} \mathcal{N}(0, 1)$



Consider a large language model that produces token embeddings at some intermediate layer (say L). Each token embedding is a vector in \mathbb{R}^d for some large d. Focus on the first coordinate X of the vector embedding, and suppose that you observe, across many contexts, the value of X. Denote these values by X_1, X_2, \ldots

A plausible model: $X_1, X_2, \cdots \overset{\text{i.i.d.}}{\sim} \mathcal{N}(0, 1)$

Suppose that the first coordinate of the vector embedding of layer L has a strong bearing on some downstream performance metric Y (e.g., how "on-topic" the generated text is). We want to capture this dependence.



Consider a large language model that produces token embeddings at some intermediate layer (say L). Each token embedding is a vector in \mathbb{R}^d for some large d. Focus on the first coordinate X of the vector embedding, and suppose that you observe, across many contexts, the value of X. Denote these values by X_1, X_2, \ldots

A plausible model: $X_1, X_2, \cdots \overset{\text{i.i.d.}}{\sim} \mathcal{N}(0,1)$

Suppose that the first coordinate of the vector embedding of layer L has a strong bearing on some downstream performance metric Y (e.g., how "on-topic" the generated text is). We want to capture this dependence.

We wish to model the relationship between X and Y is given by

$$Y_i = \beta X_i + \varepsilon_i,$$

where $\beta \in \mathbb{R}$ is unknown, and $\varepsilon_1, \varepsilon_2 \overset{\text{i.i.d.}}{\sim} \mathcal{N}(0, \sigma^2)$, independent of X_1, X_2, \ldots , and σ^2 is known

$$Y_i = \beta X_i + \varepsilon_i$$

$$\beta \in \mathbb{R}$$
 unknown, $\varepsilon_1, \varepsilon_2 \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \sigma^2)$ (independent of X_1, X_2, \ldots), σ^2 known

• Considering n data points $\{(X_i, Y_i)\}_{i=1}^n$, write down the expression for the ℓ_2 loss (a.k.a. squared loss) between input and output.

$$Y_i = \beta X_i + \varepsilon_i$$

- $\beta \in \mathbb{R}$ unknown, $\varepsilon_1, \varepsilon_2 \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \sigma^2)$ (independent of X_1, X_2, \ldots), σ^2 known
 - Considering n data points $\{(X_i, Y_i)\}_{i=1}^n$, write down the expression for the ℓ_2 loss (a.k.a. squared loss) between input and output.
 - Determine the value of model parameter, say $\widehat{\beta}_n$, that minimizes the ℓ_2 loss.

$$Y_i = \beta X_i + \varepsilon_i$$

 $\beta \in \mathbb{R}$ unknown, $\varepsilon_1, \varepsilon_2 \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \sigma^2)$ (independent of X_1, X_2, \ldots), σ^2 known

- Considering n data points $\{(X_i, Y_i)\}_{i=1}^n$, write down the expression for the ℓ_2 loss (a.k.a. squared loss) between input and output.
- Determine the value of model parameter, say $\widehat{\beta}_n$, that minimizes the ℓ_2 loss.
- Prove that

$$\widehat{\beta}_n \xrightarrow{\text{a.s.}} \beta.$$