

Équations aux dérivées partielles – SOLUTIONS

On va faire des calculs et si c'est nécessaire on va donner des explications additionnelles

1.

$$\begin{aligned}\nabla \cdot (p\mathbf{v}) &= \frac{\partial}{\partial x}(pv_x) + \frac{\partial}{\partial y}(pv_y) + \frac{\partial}{\partial z}(pv_z) \\ &= v_x \frac{\partial}{\partial x}p + v_y \frac{\partial}{\partial y}p + v_z \frac{\partial}{\partial z}p + p\left(\frac{\partial}{\partial x}v_x + \frac{\partial}{\partial y}v_y + \frac{\partial}{\partial z}v_z\right) \\ &= \nabla p \cdot \mathbf{v} + p\nabla \cdot \mathbf{v}.\end{aligned}$$

$$\begin{aligned}\nabla \times (p\mathbf{v}) &= \left(\frac{\partial}{\partial y}(pv_z) - \frac{\partial}{\partial z}(pv_y), \frac{\partial}{\partial z}(pv_x) - \frac{\partial}{\partial x}(pv_z), \frac{\partial}{\partial x}(pv_y) - \frac{\partial}{\partial y}(pv_x)\right)^T \\ &= \begin{pmatrix} \frac{\partial}{\partial y}p v_z - \frac{\partial}{\partial z}p v_y + p\left(\frac{\partial}{\partial y}v_z - \frac{\partial}{\partial z}v_y\right) \\ \frac{\partial}{\partial z}p v_x - \frac{\partial}{\partial x}p v_z + p\left(\frac{\partial}{\partial z}v_x - \frac{\partial}{\partial x}v_z\right) \\ \frac{\partial}{\partial x}p v_y - \frac{\partial}{\partial y}p v_x + p\left(\frac{\partial}{\partial x}v_y - \frac{\partial}{\partial y}v_x\right) \end{pmatrix} \\ &= \nabla p \times \mathbf{v} + p(\nabla \times \mathbf{v}).\end{aligned}$$

$$\begin{aligned}\nabla \times (\nabla p) &= \nabla \times \left(\frac{\partial}{\partial x}p, \frac{\partial}{\partial y}p, \frac{\partial}{\partial z}p\right) \\ &= \left(\frac{\partial^2}{\partial y\partial z}p - \frac{\partial^2}{\partial y\partial z}p, \frac{\partial^2}{\partial x\partial z}p - \frac{\partial^2}{\partial x\partial z}p, \frac{\partial^2}{\partial x\partial y}p - \frac{\partial^2}{\partial x\partial y}p\right) = 0\end{aligned}$$

$$\begin{aligned}\nabla \cdot (\nabla \times \mathbf{v}) &= \nabla \cdot \left(\frac{\partial}{\partial y}v_z - \frac{\partial}{\partial z}v_y, \frac{\partial}{\partial z}v_x - \frac{\partial}{\partial x}v_z, \frac{\partial}{\partial x}v_y - \frac{\partial}{\partial y}v_x\right) \\ &= \frac{\partial^2}{\partial x\partial y}v_z - \frac{\partial^2}{\partial x\partial z}v_y + \frac{\partial^2}{\partial y\partial z}v_x - \frac{\partial^2}{\partial x\partial y}v_z + \frac{\partial^2}{\partial x\partial z}v_y - \frac{\partial^2}{\partial y\partial z}v_x = 0\end{aligned}$$

2. Dans la formule de Green on remplace d'abord u par uv ce qui conduit à

$$\int_{\Omega} \frac{\partial u}{\partial x_i} v d\mathbf{x} = - \int_{\Omega} u \frac{\partial v}{\partial x_i} d\mathbf{x} + \int_{\partial\Omega} uv n_i d\sigma.$$

On remplacera ensuite u par $\frac{\partial u}{\partial x_i}$, $i = 1, \dots, N$ et puis on sommerá les relations.

3. On va utiliser la formule $\nabla \cdot (p\mathbf{v}) = p\nabla \cdot \mathbf{v} + \mathbf{v} \cdot \nabla p$ et la formule de Green.

$$\begin{aligned}\int_{\Omega} (\nabla \cdot \mathbf{w}) \phi d\mathbf{x} &= \int_{\Omega} \nabla \cdot (\phi \mathbf{w}) d\mathbf{x} - \int_{\Omega} \mathbf{w} \cdot \nabla \phi d\mathbf{x} \\ &= - \int_{\Omega} \mathbf{w} \cdot \nabla \phi d\mathbf{x} + \int_{\Omega} \sum_{i=1}^3 \frac{\partial}{\partial x_i} (\phi \mathbf{w}) d\mathbf{x} \\ &= - \int_{\Omega} \mathbf{w} \cdot \nabla \phi d\mathbf{x} + \sum_{i=1}^3 \int_{\partial\Omega} (\phi \mathbf{w}) \cdot \mathbf{n}_i(x) d\sigma \\ &= - \int_{\Omega} \mathbf{w} \cdot \nabla \phi d\mathbf{x} + \int_{\partial\Omega} (\mathbf{w} \cdot \mathbf{n}) \phi d\sigma.\end{aligned}$$

En prenant $\phi = 1$, on a $\nabla \phi = 0$ et donc

$$\int_{\Omega} \nabla \cdot \mathbf{w} d\mathbf{x} = \int_{\partial\Omega} \mathbf{w} \cdot \mathbf{n} d\sigma.$$

4. On utilise la formule $\nabla \times (p\mathbf{v}) = p\nabla \times \mathbf{v} + \nabla p \times \mathbf{v}$ et la formule de Green.

$$\begin{aligned}\int_{\Omega} (\nabla \times \mathbf{w}) \phi d\mathbf{x} &= \int_{\Omega} \nabla \times (\phi \mathbf{w}) d\mathbf{x} - \int_{\Omega} \nabla \phi \times \mathbf{w} d\mathbf{x} \\ &= \int_{\Omega} \mathbf{w} \times \nabla \phi d\mathbf{x} + \int_{\Omega} \left(\frac{\partial}{\partial y}(\phi w_3) - \frac{\partial}{\partial z}(\phi w_2), \frac{\partial}{\partial z}(\phi w_1) - \frac{\partial}{\partial x}(\phi w_3), \frac{\partial}{\partial x}(\phi w_2) - \frac{\partial}{\partial y}(\phi w_1)\right)^T d\mathbf{x} \\ &= \int_{\Omega} \mathbf{w} \times \nabla \phi d\mathbf{x} + \int_{\partial\Omega} (\phi(w_3 n_2 - w_2 n_3), \phi(w_1 n_3 - w_3 n_1), \phi(w_2 n_1 - w_1 n_2))^T d\sigma \\ &= \int_{\Omega} \mathbf{w} \times \nabla \phi d\mathbf{x} + \int_{\partial\Omega} (\mathbf{n} \times \mathbf{w}) \phi d\sigma \\ &= \int_{\Omega} \mathbf{w} \times \nabla \phi d\mathbf{x} - \int_{\partial\Omega} (\mathbf{w} \times \mathbf{n}) \phi d\sigma\end{aligned}$$

On prend encore une fois $\phi = 1$ et on obtient:

$$\int_{\Omega} (\nabla \times \mathbf{w}) \phi d\mathbf{x} = \int_{\partial\Omega} \mathbf{w} \times \mathbf{n} d\sigma.$$

5. On vérifera que u satisfait bien l'équation ainsi que les conditions aux limites. Il est évident que $u(0) = u(1) = 0$. On évalue d'abord la dérivée première et ensuite la dérivée seconde

$$\begin{aligned} u'(x) &= \int_0^1 f(s)(1-s)ds - \int_0^x f(s)ds - xf(x) + xf(x) = \int_0^1 f(s)(1-s)ds - \int_0^x f(s)ds \\ u''(x) &= (u'(x))' = -f(x) \end{aligned}$$

donc u est bien solution du problème aux limites.

6. On va calculer d'abord quelques dérivées partielles qui vont être utiles.

$$\begin{aligned} \frac{\partial r}{\partial x} &= \frac{x}{\sqrt{x^2 + y^2}} = \frac{r \cos \theta}{r} = \cos \theta, \quad \frac{\partial r}{\partial y} = \frac{y}{\sqrt{x^2 + y^2}} = \sin \theta \\ \frac{\partial \theta}{\partial x} &= \frac{-y}{x^2 + y^2} = -\frac{\sin \theta}{r}, \quad \frac{\partial \theta}{\partial y} = \frac{x}{x^2 + y^2} = \frac{\cos \theta}{r} \end{aligned}$$

Maintenant on calcule le Laplacien

$$\begin{aligned} \Delta u &= \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \\ &= \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial u}{\partial \theta} \frac{\partial \theta}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial u}{\partial \theta} \frac{\partial \theta}{\partial y} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial r} \cos \theta - \frac{\partial u}{\partial \theta} \frac{\sin \theta}{r} \right) + \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial r} \sin \theta + \frac{\partial u}{\partial \theta} \frac{\cos \theta}{r} \right) \\ &= \frac{\partial}{\partial r} \left(\frac{\partial u}{\partial r} \cos \theta \right) \frac{\partial r}{\partial x} + \frac{\partial^2}{\partial \theta^2} \left(\frac{\partial u}{\partial r} \cos \theta \right) \frac{\partial \theta}{\partial x} - \frac{\partial}{\partial r} \left(\frac{\partial u}{\partial \theta} \frac{\sin \theta}{r} \right) \frac{\partial r}{\partial x} - \frac{\partial^2}{\partial \theta^2} \left(\frac{\partial u}{\partial \theta} \frac{\sin \theta}{r} \right) \frac{\partial \theta}{\partial x} \\ &\quad + \frac{\partial}{\partial r} \left(\frac{\partial u}{\partial r} \sin \theta \right) \frac{\partial r}{\partial y} + \frac{\partial^2}{\partial \theta^2} \left(\frac{\partial u}{\partial r} \sin \theta \right) \frac{\partial \theta}{\partial y} + \frac{\partial}{\partial r} \left(\frac{\partial u}{\partial \theta} \frac{\cos \theta}{r} \right) \frac{\partial r}{\partial y} + \frac{\partial^2}{\partial \theta^2} \left(\frac{\partial u}{\partial \theta} \frac{\cos \theta}{r} \right) \frac{\partial \theta}{\partial y} \\ &= \frac{\partial^2 u}{\partial r^2} \cos^2 \theta - \frac{\sin \theta \cos \theta}{r} \frac{\partial^2 u}{\partial r \partial \theta} + \frac{\sin^2 \theta}{r^2} \frac{\partial u}{\partial \theta} \\ &\quad - \frac{\sin \theta \cos \theta}{r} \frac{\partial^2 u}{\partial r \partial \theta} + \frac{\sin \theta \cos \theta}{r^2} \frac{\partial u}{\partial \theta} + \frac{\sin^2 \theta}{r^2} \frac{\partial^2 u}{\partial \theta^2} + \frac{\sin \theta \cos \theta}{r^2} \frac{\partial u}{\partial \theta} \\ &\quad + \frac{\partial^2 u}{\partial r^2} \sin^2 \theta + \frac{\sin \theta \cos \theta}{r} \frac{\partial^2 u}{\partial r \partial \theta} + \frac{\cos^2 \theta}{r^2} \frac{\partial u}{\partial \theta} \\ &\quad + \frac{\sin \theta \cos \theta}{r} \frac{\partial^2 u}{\partial r \partial \theta} - \frac{\sin \theta \cos \theta}{r^2} \frac{\partial u}{\partial \theta} + \frac{\cos^2 \theta}{r^2} \frac{\partial^2 u}{\partial \theta^2} - \frac{\sin \theta \cos \theta}{r^2} \frac{\partial u}{\partial \theta} \\ &= \frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} \end{aligned}$$