

TD 6

∇u , Δu , $\nabla \cdot \underline{w}$, $\nabla \times \underline{w}$
 ↙ ↘ ↙ ↘
 champs scalaires champs de vecteurs

$$\int_V \frac{\partial u}{\partial x_i} dx = \int_{\partial V} u n_i ds$$

D $\Delta u = \nabla \cdot (\nabla u)$ ✓

→ $\nabla \cdot (u \underline{v}) = u(\nabla \cdot \underline{v}) + \underline{v} \cdot \nabla u$ ✓

→ $\nabla \times (u \underline{v}) = u(\nabla \times \underline{v}) + \nabla u \times \underline{v}$ ✓

a) $\nabla \cdot (\nabla u) = \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(\frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(\frac{\partial u}{\partial z} \right)$
 $= \Delta u$

b) $\nabla \cdot (u \underline{v}) = \frac{\partial}{\partial x} (u \cdot v_x) + \frac{\partial}{\partial y} (u \cdot v_y) + \frac{\partial}{\partial z} (u \cdot v_z)$

où $\underline{v} = (v_x, v_y, v_z)$

↓ ↙ ↘
 formule d'identification du produit

$$= \frac{\partial u}{\partial x} v_x + u \frac{\partial v_x}{\partial x} + \frac{\partial u}{\partial y} v_y + u \frac{\partial v_y}{\partial y} + \frac{\partial u}{\partial z} v_z + u \frac{\partial v_z}{\partial z} = \nabla u \cdot \underline{v} + u \cdot \nabla \cdot \underline{v}$$

c) $\nabla \times (u \underline{v}) = \begin{pmatrix} \frac{\partial}{\partial y} (u v_z) - \frac{\partial}{\partial z} (u v_y) \\ \frac{\partial}{\partial z} (u v_x) - \frac{\partial}{\partial x} (u v_z) \\ \frac{\partial}{\partial x} (u v_y) - \frac{\partial}{\partial y} (u v_x) \end{pmatrix}$

$w = u \underline{v}$

$= (u v_x, u v_y, u v_z)$

$w_x = u v_x, w_y = u v_y$

$$= \left(\begin{array}{c} \frac{\partial u}{\partial y} v_z - \frac{\partial u}{\partial z} v_y + u \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) \\ \frac{\partial u}{\partial z} v_x - \frac{\partial u}{\partial x} v_z + u \left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) \\ \frac{\partial u}{\partial x} v_y - \frac{\partial u}{\partial y} v_x + u \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right) \end{array} \right)$$

$\underbrace{\hspace{10em}}_{\nabla u \times \underline{v}} \quad \underbrace{\hspace{10em}}_{u \cdot \nabla \times \underline{w}}$

$$\begin{aligned} \bullet \nabla \times (\nabla u) &= \nabla \times \left(\frac{\partial u}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial u}{\partial z} \right) \\ &= \left(\frac{\partial^2 u}{\partial z \partial y} - \frac{\partial^2 u}{\partial y \partial z}, \dots \right) = \underline{0} \end{aligned}$$

$$\begin{aligned} \bullet \nabla \cdot (\nabla \times \underline{v}) &= \nabla \cdot \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z}, \frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x}, \frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right) \\ &= \frac{\partial}{\partial x} (1) + \frac{\partial}{\partial y} (2) + \frac{\partial}{\partial z} (3) = 0 \end{aligned}$$

Important: $\forall u, \underline{v} \quad \nabla \times (\nabla u) = 0$
 $\nabla \cdot (\nabla \times \underline{v}) = 0$

$$2) \int_{\Omega} \frac{\partial w}{\partial x_i} dx = \int_{\partial \Omega} w \cdot n_i(x) ds \quad (\text{Green})$$

Intégration par parties, $w = u \cdot v$ et on remplace dans la formule de Green

$$\int_{\Omega} \frac{\partial}{\partial x_i} (uv) dx = \int_{\partial \Omega} uv n_i(x) ds$$

$$\int_{\Omega} \left(\frac{\partial u}{\partial x_i} v + u \frac{\partial v}{\partial x_i} \right) dx = \int_{\partial \Omega} uv n_i(x) ds$$

$$\left| \int_{\Omega} \frac{\partial u}{\partial x_i} v dx = - \int_{\Omega} u \frac{\partial v}{\partial x_i} dx + \int_{\partial \Omega} uv n_i ds \right|$$

↙ première formule d'intégration par parties

• On utilise cette formule ; on remplace u par $\frac{\partial u}{\partial x_i} =$

$$\int_{\Omega} \frac{\partial^2 u}{\partial x_i^2} v dx = - \int_{\Omega} \frac{\partial u}{\partial x_i} \cdot \frac{\partial v}{\partial x_i} dx$$

$$+ \int_{\partial \Omega} \frac{\partial u}{\partial x_i} \cdot v \cdot n_i ds$$

$i=1, \dots, n$

On va sommer toutes les relations

$$\int_{\Omega} \Delta u \cdot v \, dx = - \int_{\Omega} \nabla u \cdot \nabla v \, dx + \int_{\partial \Omega} (\nabla u \cdot \underline{n}) v \, ds$$

$\frac{\partial u}{\partial n}$

$$\Rightarrow \boxed{\int_{\Omega} \Delta u \cdot v \, dx = - \int_{\Omega} \nabla u \cdot \nabla v \, dx + \int_{\partial \Omega} \frac{\partial u}{\partial n} v \, ds}$$

3) Formule de Stokes

$$\nabla \cdot (\varphi \underline{w}) = \varphi \cdot \nabla \cdot \underline{w} + \underline{w} \cdot \nabla \varphi$$

(voir l'exercice 1)

On intègre sur le domaine Ω

$$\boxed{\int_{\Omega} (\nabla \cdot \underline{w}) \varphi \, dx = \int_{\Omega} \nabla \cdot (\varphi \underline{w}) \, dx -$$

$$\int_{\Omega} \underline{w} \cdot \nabla \varphi \, dx$$

$$= - \int_{\Omega} \underline{w} \cdot \nabla \varphi \, dx + \int_{\Omega} \sum_{i=1}^3 \frac{\partial}{\partial x_i} (\varphi w_i) \, dx$$

$$= - \int_{\Omega} \underline{w} \cdot \nabla \varphi \, dx + \sum_{i=1}^3 \int_{\partial \Omega} \varphi (w_i \cdot n_i(x)) \, dx$$

$$= - \int_{\Omega} \underline{w} \cdot \nabla \varphi \, dx + \int_{\partial \Omega} (\underline{w} \cdot \underline{n}) \varphi \, ds$$

si jamais $\varphi = 1 \Rightarrow \nabla \varphi = 0$

$$\int_{\Omega} \nabla \cdot \underline{w} \, dx = \int_{\partial \Omega} \underline{w} \cdot \underline{n} \, ds$$

formule de la divergence (Gauss)

$$④ \quad \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ \partial_x & \partial_y & \partial_z \\ u_x & u_y & u_z \end{vmatrix} =$$

$$= \underline{i} (\partial_y u_z - \partial_z u_y) - \underline{j} (\partial_x u_z - \partial_z u_x) + \underline{k} (\partial_x u_y - \partial_y u_x)$$

$$\nabla \times (\varphi \underline{w}) = \varphi \nabla \times \underline{w} + \nabla \varphi \times \underline{w}$$

(exercice 1) \leadsto on intègre et on applique la formule de Green

$$\boxed{\int_{\Omega} (\nabla \times \underline{w}) \varphi \, d\mathbf{x} = \int_{\partial\Omega} \nabla \times (\varphi \underline{w}) \, d\mathbf{n} - \int_{\partial\Omega} \nabla \varphi \times \underline{w} \, d\mathbf{s}}$$

$$= \int_{\Omega} \underline{w} \times \nabla \varphi \, d\mathbf{x}$$

$$+ \int_{\partial\Omega} \left(\frac{\partial}{\partial y} (\varphi w_z) - \frac{\partial}{\partial z} (\varphi w_y), \right.$$

$$\left. \frac{\partial}{\partial z} (\varphi w_x) - \frac{\partial}{\partial x} (\varphi w_z), \right.$$

$$\left. \frac{\partial}{\partial x} (\varphi w_y) - \frac{\partial}{\partial y} (\varphi w_x) \right)^T d\mathbf{x}$$

$$= \int_{\Omega} \underline{w} \times \nabla \varphi \, d\mathbf{x} + \int_{\partial\Omega} \varphi (w_z n_y - w_y n_z),$$

Green

$$\varphi (w_x n_z - w_z n_x),$$

$$\varphi (w_y n_x - w_x n_y) \Big]^T d\mathbf{s}$$

$$= \int_{\Omega} \underline{w} \times \nabla \varphi \, d\mathbf{x} + \int_{\partial\Omega} (\underline{n} \times \underline{w}) \varphi \, d\mathbf{s}$$

$$= \boxed{\int_{\Omega} \underline{w} \times \nabla \varphi \, d\mathbf{x} - \int_{\partial\Omega} (\underline{w} \times \underline{n}) \varphi \, d\mathbf{s}}$$

$$\delta \varphi = 1 \quad \int_{\Omega} (\nabla \times \underline{w}) \, d\mathbf{x} = - \int_{\partial\Omega} (\underline{w} \times \underline{n}) \, d\mathbf{s}$$

$$\textcircled{5} \quad \begin{cases} -u''(x) = f(x), & x \in (0,1) \\ u(0) = u(1) = 0 \end{cases}$$

$$u(x) = x \int_0^1 f(s)(1-s) ds - \int_0^x f(s)(x-s) ds$$

On vérifie si u est solution du problème aux limites.

Conditions aux limites:

$$\checkmark \cdot u(0) = 0 \cdot \int_0^1 f(s)(1-s) ds - \int_0^0 f(s)(x-s) ds = 0$$

$$\checkmark \cdot u(1) = \int_0^1 f(s)(1-s) dx - \int_0^1 f(s)(1-s) ds = 0$$

$$u'(x) = \int_0^1 f(s)(1-s) ds -$$

$$- \left(x \int_0^x f(s) ds - \int_0^x f(s) \cdot s ds \right)'$$

$$= \int_0^1 f(s)(1-s) ds - \int_0^x f(s) ds - x f(x) + x f(x)$$

$$u'(x) = \int_0^1 f(s)(1-s) ds - \int_0^x f(s) ds$$

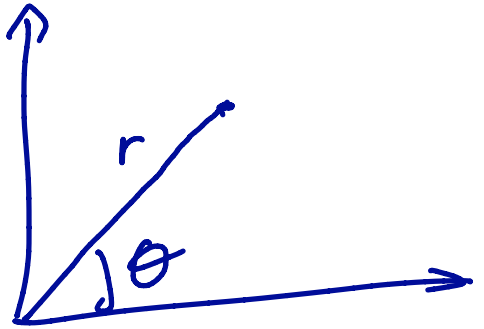
$$u''(x) = -f(x) \leadsto u \text{ est solution du problème}$$

$$6) \Delta u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}$$

Ecrire en coordonnées polaires

$$(x, y) \longrightarrow (r, \theta)$$

$$\begin{cases} x = r \cos \theta, & x = x(r, \theta) \\ y = r \sin \theta, & y = y(r, \theta) \end{cases}$$



$$\leadsto \boxed{r = \sqrt{x^2 + y^2}}$$

$$\theta = \arctan \frac{y}{x}$$

$$\begin{cases} \frac{\partial u}{\partial x} = \frac{\partial u}{\partial r} \cdot \frac{\partial r}{\partial x} + \frac{\partial u}{\partial \theta} \cdot \frac{\partial \theta}{\partial x} \\ \frac{\partial u}{\partial y} = \frac{\partial u}{\partial r} \cdot \frac{\partial r}{\partial y} + \frac{\partial u}{\partial \theta} \cdot \frac{\partial \theta}{\partial y} \end{cases}$$

$$\frac{\partial r}{\partial x} = \frac{x}{\sqrt{x^2 + y^2}} = \frac{r \cos \theta}{r} = \cos \theta$$

$$\frac{\partial r}{\partial y} = \frac{y}{\sqrt{x^2 + y^2}} = \frac{r \sin \theta}{r} = \sin \theta$$

$$\frac{\partial \theta}{\partial x} = -\frac{y}{x^2 + y^2} = -\frac{\sin \theta}{r}$$

$$\frac{\partial \theta}{\partial y} = \frac{x}{x^2 + y^2} = \frac{\cos \theta}{r}$$

$$\frac{\partial u}{\partial x} = \cos \theta \cdot \frac{\partial u}{\partial r} - \frac{\sin \theta}{r} \frac{\partial u}{\partial \theta}$$

$$\frac{\partial u}{\partial y} = \sin \theta \frac{\partial u}{\partial r} + \frac{\cos \theta}{r} \frac{\partial u}{\partial \theta}$$

$$\begin{aligned} \frac{\partial^2 u}{\partial x^2} &= \frac{\partial}{\partial x} \left(\cos \theta \cdot \frac{\partial u}{\partial r} - \frac{\sin \theta}{r} \frac{\partial u}{\partial \theta} \right) \\ &= \frac{\partial}{\partial r} \left(\cos \theta \cdot \frac{\partial u}{\partial r} - \frac{\sin \theta}{r} \frac{\partial u}{\partial \theta} \right) \cdot \left(\frac{\partial r}{\partial x} \right) \\ &\quad + \frac{\partial}{\partial \theta} \left(\cos \theta \cdot \frac{\partial u}{\partial r} - \frac{\sin \theta}{r} \frac{\partial u}{\partial \theta} \right) \cdot \left(\frac{\partial \theta}{\partial x} \right) \end{aligned}$$

$\frac{\partial r}{\partial x} = \cos \theta$
 $\frac{\partial \theta}{\partial x} = -\frac{\sin \theta}{r}$

$$\begin{aligned} &= \left(\cos \theta \cdot \frac{\partial^2 u}{\partial r^2} + \frac{\sin \theta}{r^2} \frac{\partial u}{\partial \theta} - \frac{\sin \theta}{r} \frac{\partial^2 u}{\partial r \partial \theta} \right) \cos \theta \\ &\quad + \left(-\sin \theta \frac{\partial u}{\partial r} + \cos \theta \frac{\partial^2 u}{\partial r \partial \theta} - \frac{\cos \theta}{r} \frac{\partial u}{\partial \theta} \right. \\ &\quad \left. - \frac{\sin \theta}{r} \frac{\partial^2 u}{\partial \theta^2} \right) \cdot \left(-\frac{\sin \theta}{r} \right) \end{aligned}$$

$$\begin{aligned} \frac{\partial^2 u}{\partial y^2} &= \frac{\partial}{\partial y} \left(\sin \theta \frac{\partial u}{\partial r} + \frac{\cos \theta}{r} \frac{\partial u}{\partial \theta} \right) \\ &= \frac{\partial}{\partial r} \left(\sin \theta \frac{\partial u}{\partial r} + \frac{\cos \theta}{r} \frac{\partial u}{\partial \theta} \right) \cdot \left(\frac{\partial r}{\partial y} \right) \\ &\quad + \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial u}{\partial r} + \frac{\cos \theta}{r} \frac{\partial u}{\partial \theta} \right) \cdot \left(\frac{\partial \theta}{\partial y} \right) \end{aligned}$$

$\frac{\partial r}{\partial y} = \sin \theta$
 $\frac{\partial \theta}{\partial y} = \frac{\cos \theta}{r}$

$$= \left(\sin\theta \frac{\partial^2 u}{\partial r^2} - \frac{\cos\theta}{r^2} \frac{\partial u}{\partial \theta} + \frac{\cos\theta}{r} \frac{\partial^2 u}{\partial \theta \partial r} \right) \sin\theta$$

$$+ \left(\cos\theta \frac{\partial u}{\partial r} - \frac{\sin\theta}{r} \frac{\partial u}{\partial \theta} + \frac{\cos\theta}{r} \frac{\partial^2 u}{\partial \theta^2} \right) \frac{\cos\theta}{r}.$$

On somme les 2 :

$$\boxed{\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{\partial^2 u}{\partial r^2} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} + \frac{1}{r} \frac{\partial u}{\partial r}}$$

↓
très utile quand la géométrie
du domaine s'y prête !

Remarque : Il y a aussi des coordonnées
sphériques ou cylindriques, etc. . .