

# Homework I

Due: Sep. 25. (Fri) 23:59 PM

## I. REMARK

- Reading materials: PPT materials, book (Foundations of Signal Processing, Ch 2.1-2.5)
- Please write whole processes to justify your answer.

## II. PROBLEM SET

- 1) Two vectors are given as

$$\mathbf{h} = \begin{bmatrix} h[0] \\ h[1] \\ h[2] \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}, \mathbf{x} = \begin{bmatrix} x[0] \\ x[1] \\ x[2] \\ x[3] \\ x[4] \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{bmatrix}.$$

Let  $y[n] = x[n] * h[n]$  where  $*$  denotes the convolution operator. What is  $y[n] \in \mathbb{R}^{7 \times 1}$ ? The expression can be converted to the matrix equation,  $\mathbf{y} = H\mathbf{x}$ ,  $H \in \mathbb{R}^{7 \times 5}$ . What is  $H$ ? What is the rank of  $H$ ,  $\text{rank}(H)$ ? Now, assume that  $\mathbf{y}$  and  $H$  are priorly known but  $\mathbf{x}$  is unknown. Use pseudo-inverse to obtain  $\mathbf{x}$ . Check everything in MATLAB.

- 2) In Problem 1, the columns of  $H$  are independent? Justify your answer.
- 3) In Problem 1,  $\mathbf{y}$  is in the range of  $H$ ,  $\mathbf{y} \in R(H)$ . Assume that  $\mathbf{y}$  is data and  $H$  is system. The data are distorted due to noise  $\mathbf{e}$  as  $\tilde{\mathbf{y}} = \mathbf{y} + \mathbf{e}$ , where  $\tilde{\mathbf{y}}$  denotes the distorted data. The noise is given as

$$\mathbf{e} = \begin{bmatrix} e[0] \\ e[1] \\ e[2] \\ e[3] \\ e[4] \\ e[5] \\ e[6] \end{bmatrix} = \begin{bmatrix} 0.2 \\ -0.2 \\ 0.1 \\ 0.3 \\ 0.1 \\ -0.2 \\ 0.1 \end{bmatrix}.$$

Find the estimate  $\tilde{\mathbf{x}}$  from  $\tilde{\mathbf{y}}$  using MATLAB.

- 4) In Problem 3, note that estimate  $\tilde{\mathbf{x}}$  and ground-truth  $\mathbf{x}$  are in vector space  $\mathbb{R}^7$ . Define any norm in this space, and compute the distance (metric) between two vectors,  $d = \|\tilde{\mathbf{x}} - \mathbf{x}\|$ .
- 5) In Problem 1, assume that inner product is defined as  $\langle \mathbf{a}, \mathbf{b} \rangle = \mathbf{a}^T \mathbf{b}$ . Then, derive that  $H^T$  is the adjoint of the  $H$ .
- 6) Assume that  $\mathbf{y} = A\mathbf{x}$ ,  $A \in \mathbb{R}^{M \times N}$ . When  $\text{rank}(A) < N$ , the system  $A$  is called an underdetermined system. Given  $\mathbf{y}$ , explain why there must be an infinite number of solution  $\mathbf{x}$ . In order to get one (unique) solution, it

needs a constraint. The standard one is minimizing  $\|\mathbf{x}\|$  subject to  $A\mathbf{x} = \mathbf{y}$ . When  $\|\mathbf{x}\| = \sqrt{\mathbf{x}^T \mathbf{x}}$ , derive that the solution  $\hat{\mathbf{x}}$  is

$$\hat{\mathbf{x}} = A^T(AA^T)^{-1}\mathbf{y}.$$

- 7) Download 'database1.mat' file. Load the file in MATLAB. The file contains real brain (activation) signal recorded over time using a Near-infrared Spectroscopy (NIRS) instrument. The variable  $\mathbf{y} \in \mathbb{R}^{1024 \times 1}$  corresponds to the (one-channel) data. However, the data are distorted by noise and artifact. Here, let us focus on artifact associated with DC-component. We can simply model the NIRS data as

$$\mathbf{y} = A\mathbf{x} = [\mathbf{h}, \mathbf{d}] \begin{bmatrix} a \\ b \end{bmatrix}.$$

where  $\mathbf{h}$  is hemodynamic response function and  $\mathbf{d}$  is  $[1, 1, 1, \dots, 1, 1]^T$ .  $a$  is activation strength and  $b$  is DC-component.

- Plot hemodynamic response function ( $A(:,1)$ )
- Plot DC-function ( $A(:,2)$ )
- Find an estimation  $\hat{\mathbf{x}} = [\hat{a}, \hat{b}]^T$  using pseudo-inverse.
- Plot brain activation estimate  $\hat{\mathbf{z}} = \mathbf{h}\hat{a}$ . Note that DC component is discarded (filtered).
- Plot distorted data  $\mathbf{y}$ , estimate  $\hat{\mathbf{z}}$ , and ground-truth  $\mathbf{z}$  together using "hold on". The estimate will be different from the ground-truth because we do not define other artifacts in the simple model.