# EDAN96 Applied Machine Learning

Lecture 9: Training Techniques, Backward Propagation, and Automatic Differentiation

Pierre Nugues

Pierre.Nugues@cs.lth.se

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#### Content

Overview and practice of some neural network architectures:

- Logistic loss
- The Module class
- Dense vectors
- A word on data loaders
- Backward propagation
- A word on automatic differentiation

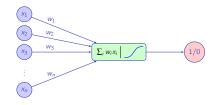
# Creating a Network with PyTorch

So far, we have used the Sequential class to create networks For more complex architectures, we need to derive a class from nn.Module

This class must have the \_\_init\_\_() and forward() methods:

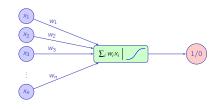
- In the \_\_init\_\_() constructor, you declare and create all the trainable parameters
- forward() implements the computation of the forward pass

# Logistic Regression



```
model = nn.Sequential(
    torch.nn.Linear(input_dim, 1),
    torch.nn.Sigmoid())
```

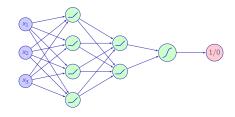
## Logistic Regression



```
class Model(nn.Module):
    def __init__(self, input_dim):
        super().__init__()
        self.fc1 = nn.Linear(input_dim, 1)

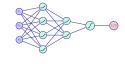
def forward(self, x):
    x = torch.sigmoid(self.fc1(x))
    return x
```

## Neural Networks with Hidden Layers



```
model = nn.Sequential(
    nn.Linear(input_dim, 4),
    nn.ReLU(),
    nn.Linear(4, 2),
    nn.ReLU()
    nn.Linear(2, 1),
    torch.nn.Sigmoid()
    )
```

## Neural Networks with Hidden Layers



```
class Model2(nn.Module):
    def __init__(self, input_dim):
        super().__init__()
        self.fc1 = nn.Linear(input_dim, 4)
        self.fc2 = nn.Linear(4, 2)
        self.fc3 = nn.Linear(2, 1)
    def forward(self, x):
        x = torch.relu(self.fc1(x))
        x = torch.relu(self.fc2(x))
        x = torch.sigmoid(self.fc3(x))
        return x
```

## Code Example

Experiment: Deriving a class with a Jupyter Notebook:
https://github.com/pnugues/edan96/blob/main/programs/
8-Salammbo\_class\_torch.ipynb

## Problems with Softmax

The logistic and softmax functions are typical activations of the last layer They are numerically unstable. Take for instance

$$softmax(1000.0, 1000.0, 1000.0) = (\frac{1}{3}, \frac{1}{3}, \frac{1}{3}).$$

Now try to compute it from the formula:

$$softmax(x_i) = \frac{e^{x_i}}{\sum_j e^{x_j}}$$

# Multiclass in PyTorch

To solve the numerical under or overflows, PyTorch integrates softmax in the cross entropy loss

```
It uses a specific function called LogSumExp . See https://en.wikipedia.org/wiki/LogSumExp See also:
```

https://gregorygundersen.com/blog/2020/02/09/log-sum-exp/ The last layer of a multiclass classification is typically a linear layer. For instance:

```
model = nn.Sequential(
    nn.Linear(input_dim, 5),
    nn.ReLU(),
    nn.Linear(5, 3)
)
```

The layer outputs are called logits

The cross entropy loss uses a logit input in PyTorch: https://pytorch.org/docs/stable/generated/torch.nn.CrossEntropyLoss html

## Code Example

#### **Experiment:**

The code of a neural network with a sequential model is very close to that of logistic regression.

We just list the layers and activation functions

Jupyter Notebook: https://github.com/pnugues/edan96/blob/

main/programs/9-Salammbo\_multi\_torch.ipynb

# Binary Classification from Logits

Binary and multiclass classifications have different architectures in PyTorch.

Maybe a bug in the API design?

We can use the nn.BCEWithLogitsLoss() to have a logit input:

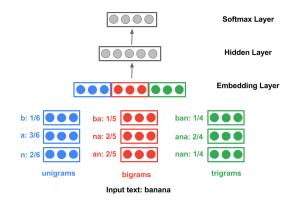
```
model2 = nn.Sequential(
    nn.Linear(input_dim, 4),
    nn.ReLU(),
    nn.Linear(4, 2),
    nn.ReLU(),
    nn.Linear(2, 1)
)
```

**Experiment:** Deriving a class with a Jupyter Notebook:

```
https://github.com/pnugues/edan96/blob/main/programs/10-Salammbo_class_logits_torch.ipynb
```

## Sum of Embeddings in CLD3

#### CLD3 computes the weighted sum of embeddings



# Categorical Values: Multi-hot encoding

A collection of two documents D1 and D2:

D1: Chrysler plans new investments in Latin America.

D2: Chrysler plans major investments in Mexico.

Multi-hot encoding (also called a bag-of-words representation):

D.	america	chrysler	in	investments	latin	major	mexico	new	plans
1	1	1	1	1	1	0	0	1	1
2	0	1	1	1	0	1	1	0	1

This technique can create extremely large sparse vectors

#### **Dense Vectors**

We can replace one-hot vectors by dense ones using embeddings A dense representation is a trainable vector of 10 to 300 dimensions.

The vector parameters are learned in the fitting procedure.

Dimensionality reduction inside a neural network or another procedure.

Example: GloVe file 100d.

Many techniques, often based on language modeling, here CBOW

#### Cloze Test

Guess a missing word given its context. Using the example: Sing, O goddess, the anger of Achilles son of Peleus,

Cloze test: A reader, given the incomplete phrase:

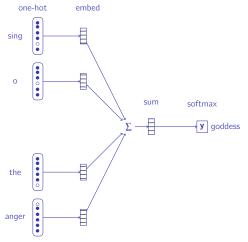
Sing, O \_\_\_\_, the anger of Achilles

has to fill in the blank with the correct word, here **goddess**. Easy to create a dataset for a Cloze test

$$X = \begin{bmatrix} sing & o & the & anger \\ o & goddess & anger & of \\ goddess & the & of & achilles \\ the & anger & achilles & son \\ anger & of & son & of \\ of & achilles & of & peleus \end{bmatrix}; \mathbf{y} = \begin{bmatrix} goddess \\ the \\ anger \\ of \\ achilles \\ son \end{bmatrix}$$

#### **CBOW Architecture**

Context words one-hot encoded, in practice just an index, followed by an **embedding layer.** 



# Embeddings in PyTorch

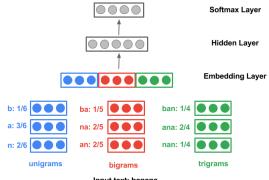
```
PyTorch has an Embedding(num_embeddings, embedding_dim, ...)
class
An embedding object is a matrix from which we can extract embedding
vectors using an index
This is just a lookup table
# Creates trainable vectors of size 64
embedding_chars = nn.Embedding(MAX_CHARS, 64)
 Extracts embeddings in rows 3 and 2,
 corresponding to two characters
embedding_chars(torch.LongTensor([3, 2]))
```

## Code Example

Experiment: Embeddings with a Jupyter Notebook: https://github.com/pnugues/edan96/blob/main/programs/11-pytorch\_embeddings.ipynb
To create a batch, we would need to pad the character, bigram, and trigram hash codes.

## Sum of Embeddings in CLD3

#### CLD3 computes the weighted sum (mean) of the embeddings



Input text: banana

# Embedding Bags in PyTorch

EmbeddingBags class creates embedding objects.

```
embedding_bag = nn.EmbeddingBag(MAX_CHARS, 64) # default mean
embedding_bag = nn.EmbeddingBag(MAX_CHARS, 64, mode='sum')
```

Given a list of embeddings (a list of rows) as input, an embedding bag returns:

- The mean,
- 2 The sum, or
- **3** The weighted sum of the embeddings.

We specify the weights with a per\_sample\_weights parameter. https://pytorch.org/docs/stable/generated/torch.nn. EmbeddingBag.html

# Programming Embedding Bags in PyTorch (I)

# Programming Embedding Bags in PyTorch (II)

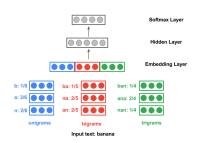
With bags of unequal sizes, we have to use a list of offsets

# Adding the embeddings

Describe a language detector: Given a string predict the language:

- Bonjour -> French
- Guten Tag -> German

Follow the complete compact language detector (CLD3) https://github.com/google/cld3



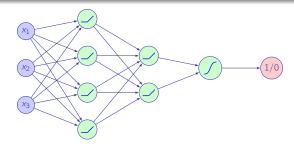
## Code Example

**Experiment:** Classification with embedding bags Jupyter Notebook: https://github.com/pnugues/pnlp/blob/main/notebooks/11\_07\_language\_detector.ipynb

#### Data Loaders

- Current datasets have now terabytes of data
- Impossible to fit into memory (even Tatoeba)
- For real world applications, you will have to use or write a data loader that can create smaller, processable batches from your storage
- This involves the Dataset and DataLoader classes
- Beyond the scope of this lecture
- Read on this here: https://pytorch.org/blog/ efficient-pytorch-io-library-for-large-datasets-many-file

# Backpropagation: The Forward Pass



#### The forward pass:

- **1** Layer 1  $f^{(1)}(W^{(1)}\mathbf{x})$ , where  $f^{(1)}$  is the activation function.
- **2** For the second layer,  $f^{(2)}(W^{(2)}f^{(1)}(W^{(1)}x))$ ,
- **3** Last layer (*L*) and output the prediction:

$$\hat{y} = f^{(L)}(W^{(L)}...f^{(2)}(W^{(2)}f^{(1)}(W^{(1)}\mathbf{x}))...).$$

• For the figure  $\hat{y} = f^{(3)}(W^{(3)}W^{(2)}W^{(1)}\mathbf{x})$ , where  $f^{(3)}(x)$  is the logistic function.

#### Naive Gradient Descent

Try to minimize the difference between the predicted and observed annotations:  $Loss(y, \hat{y})$ .

$$\mathbf{w}_{(k+1)} = \mathbf{w}_{(k)} - \alpha_{(k)} \nabla Loss(\mathbf{w}_{(k)}).$$

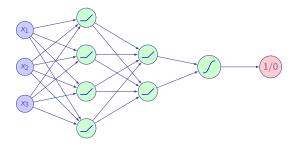
We compute the gradient:

$$\frac{\partial Loss(\mathbf{w})}{\partial w_{ij}^{(l)}} = \frac{\partial (-y \ln \hat{y} - (1-y) \ln(1-\hat{y}))}{\partial w_{ij}^{(l)}} \\
= \frac{\partial (-y \ln f^{(3)} (W^{(3)} W^{(2)} W^{(1)} \mathbf{x}) - (1-y) \ln(1-f^{(3)} (W^{(3)} W^{(2)} W^{(1)} \mathbf{x})))}{\partial w_{ij}^{(l)}},$$

for all the weights  $w_{ij}^{(I)}$ . Method impractical in real cases (billions of weights)

# Breaking Down the Computation

We first compute the gradient with respect to the inputs.



$$\hat{y} = \mathbf{a}^{(L)},$$
  
 $= f^{(L)}(\mathbf{z}^{(L)}),$   
 $= f^{(L)}(W^{(L)}\mathbf{a}^{(L-1)})$ 

#### Recurrence Relation

We can show that this relation applies for any pair of adjacent layers I and I-1 in the network:

$$\nabla_{\mathbf{z}^{(l-1)}}\mathbf{z}^{(l)} = f^{(l-1)\prime}(\mathbf{z}^{(l-1)})^{\mathsf{T}} \odot \mathcal{W}^{(l)}.$$

For our network:

$$\nabla_{\mathbf{x}} Loss(y, \hat{y}) = -\frac{\partial (y \ln \hat{y} + (1 - y) \ln(1 - \hat{y}))}{\partial \mathbf{x}}, 
= -\frac{y - \hat{y}}{\hat{y}(1 - \hat{y})} \hat{y}(1 - \hat{y}) W^{(3)} W^{(2)} W^{(1)}, 
= (\hat{y} - y) W^{(3)} W^{(2)} W^{(1)}, 
= (f^{(3)} (W^{(3)} W^{(2)} W^{(1)} \mathbf{x}) - y) W^{(3)} W^{(2)} W^{(1)}.$$

## Gradient with Respect to the Weights

We now compute the gradient with respect to  $W^{(I)}$ , I being the index of any layer. From the chain rule, for the last layer, L, we have:

$$\nabla_{W^{(L)}} Loss(y, \hat{y}) = \frac{\partial Loss(y, \hat{y})}{\partial \mathbf{z}^{(L)}} \frac{\partial \mathbf{z}^{(L)}}{\partial W^{(L)}}$$

and

$$\mathbf{z}^{(L)} = W^{(L)} f^{(L-1)} (\mathbf{z}^{(L-1)}),$$
  
=  $W^{(L)} \mathbf{a}^{(L-1)}.$ 

The partial derivatives of  $\mathbf{z}^{(L)}$  with respect to  $W^{(L)}$  simply consist of the transpose of  $\mathbf{a}^{(L-1)}$ . Then, we have:

$$\frac{\partial \mathbf{z}^{(L)}}{\partial W^{(L)}} = \mathbf{a}^{(L-1)\mathsf{T}}.$$

We can show:

$$\nabla_{W^{(l)}} Loss(y, \hat{y}) = \nabla_{\mathbf{z}^{(l)}} Loss(y, \hat{y}) \mathbf{a}^{(l-1)\mathsf{T}}.$$

## Code Example

**Experiment:** Checking the gradient with PyTorch Jupyter Notebook: https://github.com/pnugues/edan96/blob/main/programs/backprop\_mse\_test.ipynb

## Backward Differentiation

A generalization of backpropagation

PyTorch records all the operations in the forward pass
It then computes the graph of derivatives using the chain rule proceeding

backwards

1 https:

//pytorch.org/blog/overview-of-pytorch-autograd-engine/

https://github.com/pytorch/pytorch/blob/master/tools/ autograd/derivatives.yaml

Using PyTorch's example:

$$f(x,y) = \log xy$$

We have:

$$g(x,y) = xy$$

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial g} \frac{\partial g}{\partial x} = \frac{1}{xy} y = \frac{1}{x}$$

$$\frac{\partial f}{\partial y} = \frac{\partial f}{\partial g} \frac{\partial g}{\partial y} = \frac{1}{xy} x = \frac{1}{y}$$

# Computing the Gradient

Modern machine-learning platforms use an automatic differentiation algorithm.

- For a video overview: https://www.youtube.com/playlist? list=PLZHQObOWTQDNU6R1\_67000Dx\_ZCJB-3pi, especially the two last lectures;
- PyTorch https://pytorch.org/tutorials/beginner/blitz/ autograd\_tutorial.html
- Functions: https://github.com/pytorch/pytorch/blob/ master/tools/autograd/derivatives.yaml
- For a description of it in Tensorflow, see https://www.tensorflow.org/guide/autodiff
- For a description of the tf.gradients class: https://www.tensorflow.org/api\_docs/python/tf/gradients
- For a more elaborate description: http://www.cs.toronto.edu/ ~rgrosse/courses/csc421\_2019/slides/lec06.pdf