

# 介面實驗

## 實驗二

如何使用智慧型 IC 開發 ASA-I2C

擴充介面卡

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日期：109/8/25

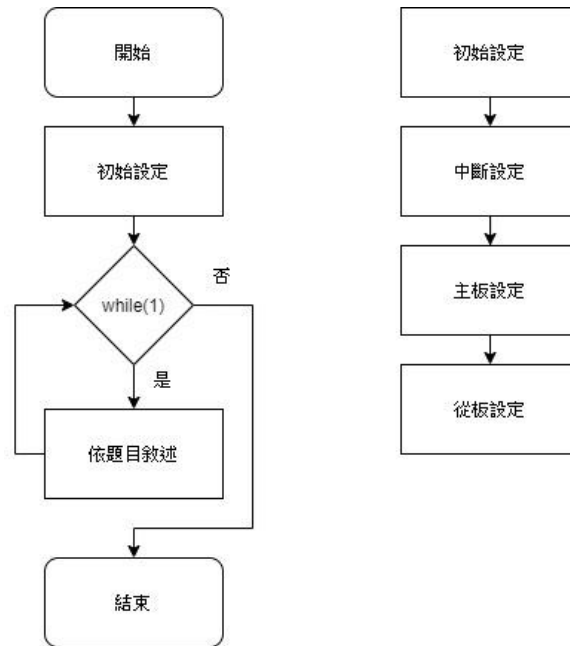
# 介面實驗工作日誌

實驗二

109 年 8 月 25 日

組別		姓名	黃鈺淳	學號	108303013
實驗起始時間	109/8/18			費時	7 天
實驗結束時間	109/8/25				
所遭遇問題					
解決方法					
完成心得項目					
調查	<input type="checkbox"/> 是否有看課程講解影片 是否實用？有何建議？		<input type="checkbox"/> 是否有看實驗教學影片 是否實用？有何建議？		

## 一、流程圖



## 二、程式碼

### 實驗一、休眠模式下單發量測溫度

```
#include "c4mlib.h"

#define SLAADD 0x48

#define Mode 5

#define WAITTICK 50

#define TempRegister 0x00

#define ConfigRegister 0x01

void SetUp();

float Bin2Dec(uint8_t, uint8_t);

int main()
{
    char ans;
    C4M_STDIO_init();
    SetUp();
    while (1)
    {
        printf("Read Temperature(Y/N):\n");
```

```

scanf("%s", &ans);

if (ans == 'Y' || ans == 'y')
{
    ans = 'N';

    TWIM_ftm(Mode, SLAADD, ConfigRegistor, 0x80, 7, &one, WAITTICK); //設定單發模式

    TWIM_rec(Mode, SLAADD, TempRegistor, 2, Temperature, WAITTICK); //接收溫度

    printf("Temperature: %.4f\n\n", Bin2Dec(Temperature[0], Temperature[1] >> 4));

}

}

return 0;
}

void SetUp()
{
    //通訊設定

    TWI_fpt(&TWSR, 0x03, 0, 0); //TWPS=DIV_BY_1

    TWI_fpt(&TWCR, 0x01, 0, 1); //致能TWI通訊

    TWI_fpt(&TWCR, 0x45, 0, 0x45); //致能TWI ACK致能

    TWI_fpt(&TWAR, 0xfe, 1, SLAADD); //設定TWI編號(slave of this card)

    TWI_fpt(&TWAR, 0x01, 0, 0); //設定廣播關閉

    TWI_fpt(&TWBR, 0xff, 0, 12); //設定工作時脈 276.48KHz

    uint8_t one = 1, third = 3, Temperature[2] = {0, 0};

    TWIM_ftm(Mode, SLAADD, ConfigRegistor, 0x01, 0, &one, WAITTICK); //設定休眠模式

    TWIM_ftm(Mode, SLAADD, ConfigRegistor, 0x60, 5, &third, WAITTICK); //設定精度為0.0625度C

}

float Bin2Dec(uint8_t num1, uint8_t num2)
{
    int integer = 0;

    float point = 0;

    for (int i = 6; i > -1; i--)
    {
        integer += (num1 >> i) & 1;

        if (i)
            integer *= 2;
    }
}

```

```

    for (int i = 0; i < 4; i++)
    {
        point += (num2 >> i) & 1;
        point /= 2;
    }

    if (num1 / 128)
    {
        return (integer + point) - 128;
    }
    else
    {
        return (integer + point);
    }
}

```

## 實驗二、比較模式下過溫度中斷警告

```

#include "c4mlib.h"

#define SLAADD 0x48
#define Mode 5
#define WAITTICK 50
#define TempRegistor 0x00
#define ConfigRegistor 0x01
#define T_low_Registor 0x02
#define T_high_Registor 0x03

void SetUp();

float Bin2Dec(uint8_t, uint8_t);

char TempStatus = 0;
uint8_t Temperature[2] = {0, 0};

int main()
{

    C4M_STDIO_init();

    SetUp();

    printf("-----start-----\n");

```

```

while (1)
{
    // printf("TempStatus=%d\n", TempStatus);

    // printf("Temperature : %.4f degree\n", Bin2Dec(Temperature[0], Temperature[1] >> 4));

    // TWIM_rec(Mode, SLAADD, TempRegistor, 2, Temperature, WAITTICK); //接收溫度

    if (TempStatus)
    {
        TempStatus = 0;

        printf("Temperature too HIGH(OVER 30 Degree)\n");

        printf("Now temperature is : %.4f Degree\n", Bin2Dec(Temperature[0], Temperature[1] >> 4));

    }

    _delay_ms(200);
}

return 0;
}

ISR(INT2_vect)
{
    TempStatus = 1;

    TWIM_rec(Mode, SLAADD, TempRegistor, 2, Temperature, WAITTICK); //接收溫度
}

void SetUp()
{
    //中斷登入設定

    EICRA = 0x30; //設定上升緣觸發

    DDRD = 0xfb; //PD2輸入

    EIMSK = 0x04; //INT2中斷啟用

    sei();

    //通訊設定

    TWI_fpt(&TWSR, 0x03, 0, 0); //TWPS=DIV_BY_1

    TWI_fpt(&TWCR, 0x01, 0, 1); //致能TWI通訊

    TWI_fpt(&TWCR, 0x45, 0, 0x45); //致能TWI ACK致能

    TWI_fpt(&TWAR, 0xfe, 1, SLAADD); //設定TWI編號(slave of this card)

    TWI_fpt(&TWAR, 0x01, 0, 0); //設定廣播關閉

    TWI_fpt(&TWBR, 0xff, 0, 12); //設定工作時脈 276.48KHz

```

```

uint8_t zero = 0, one = 1, third = 3;
uint8_t ThresholdTemp[2] = {29, 30};
TWIM_ftm(Mode, SLAADD, ConfigRegistor, 0x01, 0, &zero, WAITTICK); //設定連續感測模式
TWIM_ftm(Mode, SLAADD, ConfigRegistor, 0x02, 1, &zero, WAITTICK); //設定溫度比較模式
TWIM_ftm(Mode, SLAADD, ConfigRegistor, 0x04, 2, &one, WAITTICK); //設定警告訊號為HI
TWIM_ftm(Mode, SLAADD, ConfigRegistor, 0x60, 5, &third, WAITTICK); //設定精度為0.0625度C
TWIM_trm(Mode, SLAADD, T_low_Registor, 2, &ThresholdTemp[0], WAITTICK); //設定低溫門檻為29度
TWIM_trm(Mode, SLAADD, T_high_Registor, 2, &ThresholdTemp[1], WAITTICK); //設定高溫門檻為30度
}

```

```

float Bin2Dec(uint8_t num1, uint8_t num2)

```

```

{
    int integer = 0;
    float point = 0;

    for (int i = 6; i > -1; i--)
    {
        integer += (num1 >> i) & 1;
        if (i)
            integer *= 2;
    }

    for (int i = 0; i < 4; i++)
    {
        point += (num2 >> i) & 1;
        point /= 2;
    }

    if (num1 / 128)
    {
        return (integer + point) - 128;
    }
    else
    {
        return (integer + point);
    }
}

```

### 實驗三、量測模式下固定周期量測並顯示

```
#include "c4mlib.h"

#define SLAADD 0x48

#define Mode 5

#define WAITTICK 50

#define TempRegistor 0x00

#define ConfigRegistor 0x01

#define T_low_Registor 0x02

#define T_high_Registor 0x03


void SetUp();

float Bin2Dec(uint8_t, uint8_t);


char TempStatus = 0;

int counter = 0, sec = 0;

uint8_t Temperature[2] = {0, 0};


int main()
{

    C4M_STDIO_init();

    SetUp();

    printf("-----start-----\n");


    while (1)
    {

        if (TempStatus)
        {
            TempStatus = 0;

            printf("Now temperature is : %.4f Degree\n", Bin2Dec(Temperature[0], Temperature[1] >> 4));

        }

        _delay_ms(200);

    }

    return 0;
}


ISR(TIMER2_COMP_vect)
```



```

{
    counter++;

    if (counter == 200)
    {
        counter = 0;
        TempStatus = 1;
        TWIM_rec(Mode, SLAADD, TempRegister, 2, Temperature, WAITTICK); //接收溫度
    }
}

void SetUp()
{
    //中斷登入設定
    REGFPT(&TCCR2, 0x48, 3, 1); //波形:方波
    REGFPT(&TCCR2, 0x07, 0, 4); //除頻值設定 N=256
    REGFPT(&TIMSK, 0x80, 7, 1); //TIM2中斷致能

    uint8_t OCR2_cycle = 215;
    REGPUT(&OCR2, 1, &OCR2_cycle); //除頻值 f=100hz
    sei();

    //通訊設定
    TWI_fpt(&TWSR, 0x03, 0, 0); //TWPS=DIV_BY_1
    TWI_fpt(&TWCR, 0x01, 0, 1); //致能TWI通訊
    TWI_fpt(&TWCR, 0x45, 0, 0x45); //致能TWI ACK致能
    TWI_fpt(&TWAR, 0xfe, 1, SLAADD); //設定TWI編號(slave of this card)
    TWI_fpt(&TWAR, 0x01, 0, 0); //設定廣播關閉
    TWI_fpt(&TWBR, 0xff, 0, 12); //設定工作時脈 276.48KHz

    uint8_t zero = 0, one = 1, third = 3;
    TWIM_ftm(Mode, SLAADD, ConfigRegister, 0x01, 0, &zero, WAITTICK); //設定連續感測模式
    TWIM_ftm(Mode, SLAADD, ConfigRegister, 0x02, 1, &one, WAITTICK); //設定溫度量測模式
    TWIM_ftm(Mode, SLAADD, ConfigRegister, 0x04, 2, &one, WAITTICK); //設定警告訊號為HI
    TWIM_ftm(Mode, SLAADD, ConfigRegister, 0x60, 5, &third, WAITTICK); //設定精度為0.0625度C
}

float Bin2Dec(uint8_t num1, uint8_t num2)
{

```

```
int integer = 0;
float point = 0;

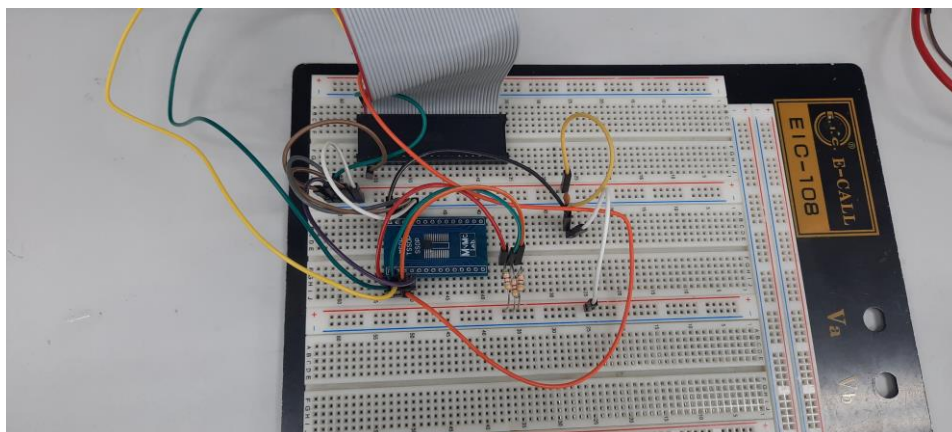
for (int i = 6; i > -1; i--)
{
    integer += (num1 >> i) & 1;
    if (i)
        integer *= 2;
}

for (int i = 0; i < 4; i++)
{
    point += (num2 >> i) & 1;
    point /= 2;
}

if (num1 / 128)
{
    return (integer + point) - 128;
}
else
{
    return (integer + point);
}
}
```

### 三、實驗數據

#### 1. 電路圖



## 2.實驗數據

```
>> Read Temperature(Y/N):
<< Y
>> Temperature:29.1875
>>
>> Read Temperature(Y/N):
<< Y
>> Temperature:31.5625
>>
>> Read Temperature(Y/N):
<< Y
>> Temperature:29.1250
>>
>> Read Temperature(Y/N):
<< Y
>> Temperature:32.1875
>>
>> Read Temperature(Y/N):
<< Y
>> Temperature:30.5000
```

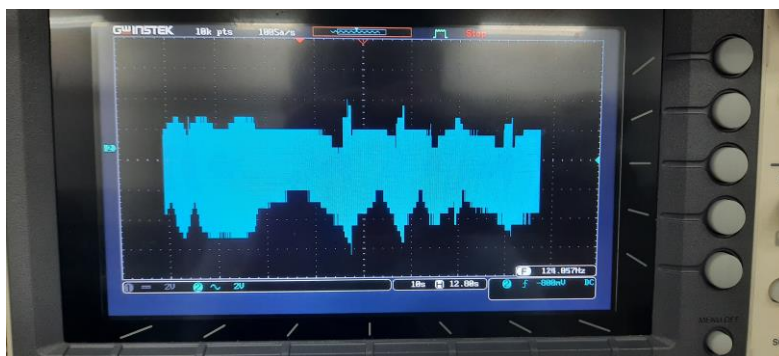
### 實驗 2-1

```
>> -----start-----
>> Temperature too HIGH(OVER 30 Degree)!
>> Now temperature is : 30.0000 Degree
>> Temperature too HIGH(OVER 30 Degree)!
>> Now temperature is : 30.0000 Degree
>> Temperature too HIGH(OVER 30 Degree)!
>> Now temperature is : 30.0000 Degree
```

### 實驗 2-2

```
>> Now temperature is : 27.3750 Degree
>> Now temperature is : 27.3750 Degree
>> Now temperature is : 27.3750 Degree
>> Now temperature is : 27.3750 Degree
>> Now temperature is : 29.8125 Degree
>> Now temperature is : 30.8750 Degree
>> Now temperature is : 31.3125 Degree
>> Now temperature is : 31.5625 Degree
>> Now temperature is : 31.6875 Degree
>> Now temperature is : 31.6875 Degree
>> Now temperature is : 31.0625 Degree
>> Now temperature is : 30.2500 Degree
>> Now temperature is : 29.6875 Degree
>> Now temperature is : 29.3125 Degree
>> Now temperature is : 29.1250 Degree
>> Now temperature is : 29.0000 Degree
>> Now temperature is : 28.9375 Degree
```

### 實驗 2-3



### 實驗 2-2