CSE 142 Assignment 5, Fall 2023

2 Questions, 100 pts, due: 23:59 pm, Dec 6th, 2023

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Instruction

- Submit your assignments onto **Gradescope** by the due date. Upload a zip file containing:
 - (1) The saved/latest .ipynb file, please rename this file with your name included.
 - (2) Also save your file into a pdf version, if error appears, save an html version instead (easy to grade for written questions).

For assignment related questions, please reach TA or grader through Slack/Piazza/Email.

• This is an **individual** assignment. All help from others (from the web, books other than text, or people other than the TA or instructor) must be clearly acknowledged.

Objective

- **Task 1:** EM algorithm (Coding)
- **Task 2:** Neural Networks (Coding + Theory)

Question 1. (EM algorithm, 30 pts)

Question 1.1. Implement EM Algorithm in Python from scratch.

```
In []: from scipy.stats import multivariate_normal
import numpy as np

def e_step(data, mu, sigma, pi, k):

##############################

weights = np. zeros((len(data), k))

for i in range(k):
    #find distribution given mu and sigma for each gaussian
    distribution = multivariate_normal(mean=mu[i], cov=sigma[i])
    #find likelihood for each datapoint
    weights[:, i] = pi[i] * distribution.pdf(data)
#normalize weights
```

```
weights = weights / np. sum(weights, axis=1, keepdims=True)
    # HINTS: ##
    ## distribution = multivariate_normal() from scipy can be used to find distribution g
    ## likelihood = distribution.pdf() can be then used to find likelihood for each datapd
    ## you will find z ik here (let's call it as "weights")
    return weights
def m_step(data, mu, sigma, pi, weights, k):
    for i in range(k):
                  # update mean
                  mu[i] = np. sum(weights[:, i]. reshape(-1, 1) * data, axis=0) / np. sum(weights[:, i]. reshape(-1, i] * data, axis=0) / np. sum(weights[:, i]. reshape(-1, i] * data, axis=0) / np. sum(weights[:, i]. reshape(-1, i] * data, axis=0) / np. sum(weights[:, i]. reshape(-1, i] * data, axis=0) / np. sum(weights[:, i]. reshape(-1, i] * data, axis=0) / np. sum(weights[:, i]. reshape(-1, i] * data, axis=0) / np. sum(weights[:, i]. reshape(-1, i] * data, axis=0) / np. sum(weights[:, i]. reshape(-1, i] * data, axis=0) / np. sum(weights[:, i]. reshape(-1, i] * data, axis=0) / np. sum(weights[:, i]. reshape(-1, i] * data, axis=0) / np. sum(weights[:, i]. reshape(-1, i] * data, axis=0) / np. sum(weights[:, i]. reshape(-1, i] * data, axis=0) / np. sum(weights[:, i]. reshape(-1, i] * data, axis=0) / np. sum(weights[:, i]. reshape(-1, i
                  # update covariance matrix
                  sigma[i] = np. cov(data. T, aweights=weights[:, i])
                  # update prior probability
                  pi[i] = np. mean(weights[:, i])
    # HERE YOU WILL UPDATE VALUES OF mu, sigma and pi
    ## numpy.cov() can be used to find sigma, i.e., covariance matrix
    return mu, sigma, pi # updated mu, sigma, pi
def gmm(data, mu, sigma, pi, k, max_iterations=1000):
        for _ in range(max_iterations):
                  # update cluter assignment weights
                  weights = e_step(data, mu, sigma, pi, k) # WRITE CODE FOR E-Step
                  # update mu, sigma and prior proabilities locations
                  mu, sigma, pi = m_step(data, mu, sigma, pi, weights, k) # WRITE CODE FOR M-Ste
        # final assignment update
        weights = e_step(data, mu, sigma, pi, k)
         assignments = np. argmax (weights, axis=1)
                                                                                                             # pick cluster with maximum probabili
         return mu, sigma, pi, assignments
```

Question 1.2. Run your code on following toy dataset we provided in the Assignment 4. Run for different k-values, where $k = \{3, 4\}$ and

- 1. visualize 2-D gaussian ellipses with $\mu \in \mathbb{R}^2$ and $\Sigma \in \mathbb{R}^{2 imes 2}$ you obtained.
- 2. plot the cluster assignments for different k's (as done in assignment 4) for both GMM and K-Means side by side for comparison. There will total 4 plots, 2 plots for each 'k' value.
- 3. Write your observations (open question)

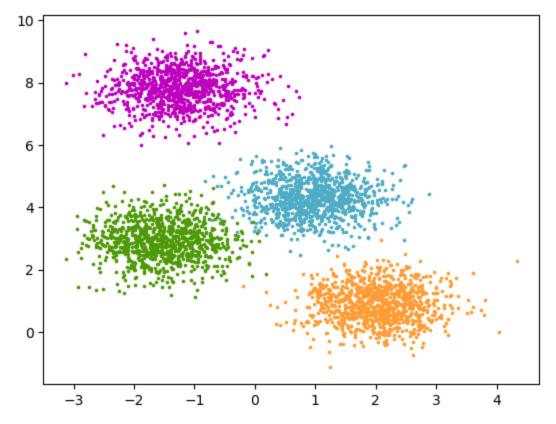
```
In []: from sklearn.datasets import make_blobs
import matplotlib.pyplot as plt

# Generate sample data
n_samples = 4000
n_components = 4

X, y_true = make_blobs(
    n_samples=n_samples, centers=n_components, cluster_std=0.60, random_state=0)

colors = ["#4EACC5", "#FF9C34", "#4E9A06", "m"]

for k, col in enumerate(colors):
    cluster_data = y_true == k
    plt.scatter(X[cluster_data, 0], X[cluster_data, 1], c=col, marker=".", s=10)
```



```
# function to get initial cluster parameters (mu, sigma and pi)
def get_initial_parameters(k, X):

# initial weights given to each cluster
pi = np. full(shape=k, fill_value=1/k)

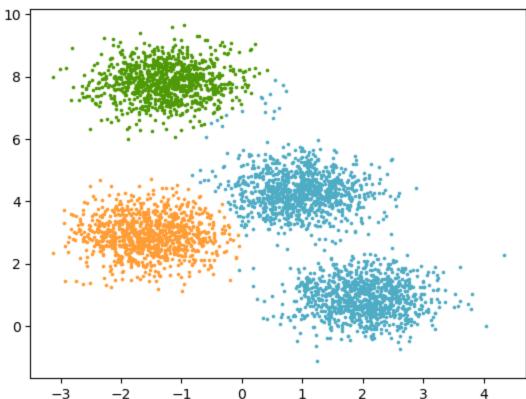
# dataset is divided randomly into k parts of unequal sizes
random_row = np. random. randint(low=0, high=X. shape[0], size=k)

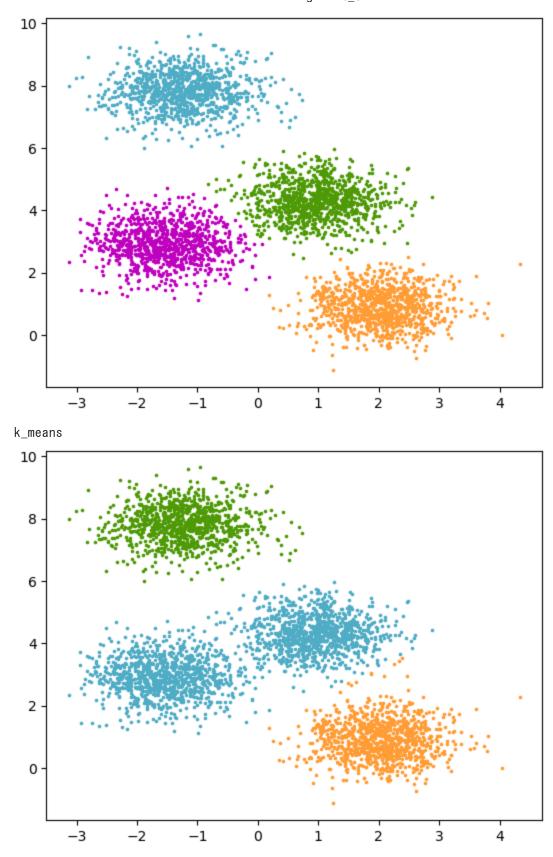
# initial value of mean of k Gaussians
mu = [ X[row_index,:] for row_index in random_row ]

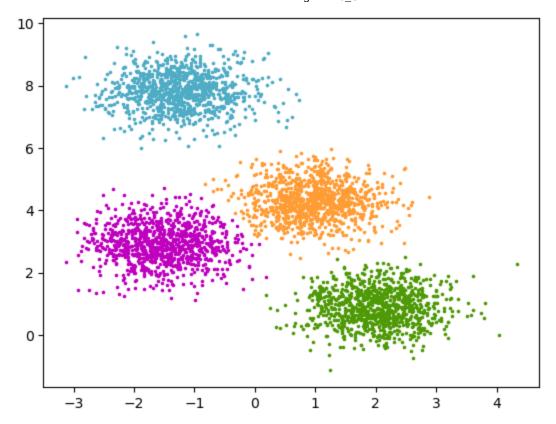
# initial value of covariance matrix of k Gaussians
sigma = [ np. cov(X. T) for _ in range(k) ]
```

```
return pi, mu, sigma
### KMEANS FUNCTIONS###
def update_assignments(data, centroids):
  k = np. shape(centroids)[0]
  assignment_list = []
  for i in range(k):
   #calculate norm of the vector
   norm = np. linalg. norm(data-centroids[i], axis=1)
   assignment list append (norm)
  #minimum element of the array in the particular axis
  assignments = np. argmin(assignment_list, axis=0)
  return assignments
def update_centroids(data, centroids, assignments):
  k = np. shape (centroids) [0]
  new_centroids = []
  for i in range(k):
    new_centroids. append (data[assignments == i]. mean (axis=0))
  new_centroids = np. array (new_centroids)
  return new_centroids
def kmeans(data, centroids, max_iterations):
  for j in range(max_iterations):
   # update cluter assignments
   assignments = update_assignments(data, centroids)
   # update centroid locations
   centroids = update_centroids(data, centroids, assignments)
  # final assignment update
  assignments = update_assignments(data, centroids)
  return centroids, assignments
def get_initial_clusters(k, X):
  random_indices = np. random. randint(0, X. shape[0], k)
  initial_centroids = X[random_indices]
  return initial_centroids
##################
## Main code ##
print("GMM")
for k in [3, 4]:
  pi_initial, mu_initial, sigma_initial = get_initial_parameters(k, X)
  #### GMM #####
  mu_final, sigma_final, pi_final, gmm_cluster_assignments = gmm(X, mu_initial, sigma_i
  for k, col in enumerate(colors):
      cluster_data = gmm_cluster_assignments == k
      plt.scatter(X[cluster_data, 0], X[cluster_data, 1], c=col, marker=".", s=10)
  plt. show()
#### KMEANS ####
print(f"k_means")
for k in [3,4]:
  initial_centroids = get_initial_clusters(k, X)
  final_centroids, kmeans_cluster_assignments = kmeans(X, initial_centroids, max_iterat
```









The ways GMM and K-means start its cluster division is different, but they both perform well for the correct k.

For when k=3 while the cluster number is 4, k-means give a division according to its closeness as a vector, while GMM gives a division according to its closeness vertically. Also from how GMM considers both mean and covariance, it gives a softer assignments compared to K-means.

Question 2. Neural Networks (70 pts)

Consider the following neural network:

```
In [ ]: from google.colab import drive
    drive.mount('/content/drive')
    from IPython.display import Image

Image(filename='/content/drive/My Drive/CSE142/Assignment5/New_NN.png', width=400)
```

ModuleNotFoundError

Traceback (most recent call last)

c:¥ドキュメント¥github¥UCSC-CSE142-MachineLearning¥Assignment5¥Assignment5_CS E142.jpvnb Cell 10 line 1

----> 1 from google.colab import drive

 $\label{lem:code-notebook-cell:/c%3A/%E3%83%89%E3%82%AD%E3%83%A5%E3%83%A1%E3%83%B3%E3%83%88/github/UCSC-CSE142-MachineLearning/Assignment5/Assignment5_CSE142.ipynb#X12sZmlsZQ%3D%3D?line=1'>2 drive.mount('/content/drive')$

 $\label{lem:code-notebook-cell:/c} $$ a href='vscode-notebook-cell:/c\%3A/\%E3\%83\%89\%E3\%82\%AD\%E3\%83\%A5\%E3\%83\%A1\%E3\%83\%B 3\%E3\%83\%88/github/UCSC-CSE142-MachineLearning/Assignment5/Assignment5_CSE142.ipynb#X12s ZmlsZQ%3D%3D?line=2'>3 from IPython.display import Image$

ModuleNotFoundError: No module named 'google'

where
$$a_i=\Sigma_j w^i_j z_j$$
 , $z_i=f_i(a_i)$ for $i=1,2,3,4,z_5=a_5$ (an input neuron), and $f_1(x)=f_2(x)=f_3(x)=f_4(x)=\text{sigmoid}(x)$.

Question 2.1. Write a function to simulate the neural network (20 pts)

Answer:

$$egin{aligned} a_2 &= w_5^2 * z_5, a_3 = w_5^3 * z_5, a_4 = w_5^4 * z_5 \ &z_2 = f(a_2), z_3 = f(a_3), z_4 = f(a_4) \ &a_1 = w_2^1 sigmoid(z_2) + w_3^1 sigmoid(z_3) + w_4^1 sigmoid(z_4) \ &z = \Sigma_i sigmoid(a_i) \end{aligned}$$

Where

$$i = [2, 3, 4]$$

Therefore

$$z = sigmoid(w_2^1 sigmoid(f(w_5^2 * z_5)) + w_3^1 sigmoid(f(w_5^3 * z_5)) + w_4^1 sigmoid(f(w_5^4 * z_5)))$$

Question 2.2 Deduce the equation to calculate δ_i (the error value per neuron) for all the neurons. (20 pts)

Write a function that given a training sample and the weights of the network calculate δ_i for each neuron.

Hint:

#

SIGMOID

$$f(x) = \frac{1}{1 + e^{-x}}$$

df(x)/dx = f(x)(1-f(x))

#

LOSS FUNCTION

$$error = 0.5 * (z_1 - target)^2$$

#

DERIVATES

 $\partial error/\partial w_3^1=\partial error/\partial z_1*\partial z_1/\partial a_1*\partial a_1/\partial w_3^1$ (using chain rule) $\delta_5=\partial error/\partial w_5^3+\partial error/\partial w_5^2+\partial error/\partial w_5^4$ (total error from connected neurons)

Answer:

$$\begin{split} \delta_1 &= \partial error/\partial a_1 = \partial L/*partial z_1/\partial z_1/\partial a_1 = (z_1-t)f(a_1) = (z_1-t)*f(a_1)(1-f(a_1)) \\ \delta_2 &= \partial error/\partial a_2 = \partial error/\partial z_1*\partial z_1/\partial z_2*\partial z_2/\partial a_2 = f'(a_2)*w_2^1*\delta 1 \\ \delta_3 &= \partial error/\partial a_3 = \partial error/\partial z_1*\partial z_1/\partial z_3*\partial z_3/\partial a_3 = f'(a_3)*w_3^1*\delta 1 \\ \delta_4 &= \partial error/\partial a_4 = \partial L/\partial z_1*\partial z_1/\partial z_4*\partial z_4/\partial a_4 = f'(a_4)*w_4^1*\delta 1 \\ \delta_5 &= \partial error/\partial w_5^2 + \partial error/\partial w_5^3 + \partial error/\partial w_5^4 = \partial L/\partial a_1*\partial a_1/\partial w_5^2 + \partial L/\partial a_1*\partial a_1/\partial w_5^3 + \partial error/\partial w_5^3 + \partial error/\partial w_5^4 = \partial L/\partial a_1*\partial a_1/\partial w_5^2 + \partial L/\partial a_1*\partial a_1/\partial w_5^3 + \partial error/\partial w_5^3 + \partial error/\partial w_5^4 = \partial L/\partial a_1*\partial a_1/\partial w_5^2 + \partial L/\partial a_1*\partial a_1/\partial w_5^3 + \partial error/\partial w_5^3 + \partial error/\partial w_5^4 = \partial L/\partial a_1*\partial a_1/\partial w_5^2 + \partial L/\partial a_1*\partial a_1/\partial w_5^3 + \partial error/\partial w_5^4 = \partial L/\partial a_1*\partial a_1/\partial w_5^2 + \partial L/\partial a_1*\partial a_1/\partial w_5^3 + \partial error/\partial w_5^4 + \partial error/\partial w$$

Therefore

$$egin{align} \delta_1 &= f(a_1)(1-f(a_1))*(z_1-target) \ \delta_2 &= f(a_2)(1-f(a_2)*w_2^1*\delta 1 \ \delta_3 &= f(a_3)(1-f(a_3)*w_2^1*\delta 1 \ \delta_4 &= f(a_4)(1-f(a_4)*w_2^1*\delta 1 \ \end{align}$$

According to the derivative initialization in the question, δ_5 would be:

$$\delta_5 = \delta 1 * (z_2 + z_3 + z_4)$$

According to the derivative from the back propagation on the class slides, δ_5 would be:

$$\delta_5 = \delta_2 * w_5^2 + \delta_3 * w_5^3 + \delta_4 * w_5^4$$

Question 2.3 (15 pts)

Assuming that the weight matrix is:

use the functions from items (a) and (b) to calculate the output of each neuron, z_i , and the error, δ_i , for the following training samples:

$$egin{array}{ccc} x & y \\ 0.0 & 0.5 \\ 1.0 & 0.1 \\ \end{array}$$

Answer:

Question 2.4 (15 pts)

Implement a function to train the neural network **from scratch** using the stochastic gradient descent **(mainly you need to implement forward_pass and backward_pass)**. Use this function to train the network with the following training samples:

$$\begin{array}{cccc} x & y \\ -3.0 & 0.7312 \\ -2.0 & 0.7339 \\ -1.5 & 0.7438 \\ -1.0 & 0.7832 \\ -0.5 & 0.8903 \\ 0.0 & 0.9820 \\ 0.5 & 0.8114 \\ 1.0 & 0.5937 \\ 1.5 & 0.5219 \\ 2.0 & 0.5049 \\ 3.0 & 0.5002 \end{array}$$

Plot the evolution of the error and the final predictions of the trained network. Write down the weights of the trained nettwork.

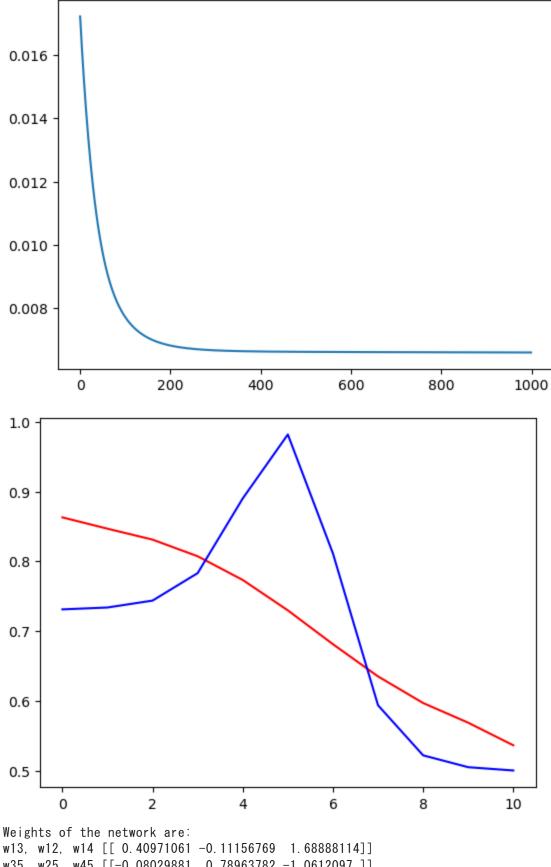
In []: ## HELPER CODE##

```
import numpy as np
import matplotlib.pyplot as plt
# defining the backprop for Sigmoid Function
def backprop_sigmoid(x):
 return x*(1-x)
# defining the Sigmoid Function
def sigmoid(x):
 return 1 / (1 + np. exp(-x))
def forward_pass(X, weights_input_hidden, weights_hidden_output):
   # calculating hidden layer activations
   # find "hiddenLayer_activations" here
   hiddenLayer_activations = sigmoid(np.dot(X, weights_input_hidden))
   #############################
   # calculating the output
   # find "output" here
   output = sigmoid(np.dot(hiddenLayer_activations, weights_hidden_output))
   return output, hiddenLayer_activations
def backward_pass(X, y, output, weights_hidden_output, weights_input_hidden, hiddenLaye
 # calculating rate of change of error w.r.t weight between hidden and output layer
 # find gradients for w13, w12, w14 and let's store them in "error_wrt_weights_hidden_d
 # NOTE: "error_wrt_weights_hidden_output" will be same size as "weights_hidden_output"
 error_output = output - y
 error_wrt_weights_hidden_output = np.dot(hiddenLayer_activations.T, error_output * ba
 ####################################
 # calculating rate of change of error w.r.t weights between input and hidden layer
 # find gradients for w35, w45, w25 and let's store them in "error_wrt_weights_input_hi
 # NOTE: "error_wrt_weights_input_hidden" will be same size as "weights_input_hidden"
 #############################
 error_hidden = np. dot(error_output * backprop_sigmoid(output), weights_hidden_output.
 error_wrt_weights_input_hidden = np. dot(X.T, error_hidden * backprop_sigmoid(hiddenLa
 return error_wrt_weights_hidden_output, error_wrt_weights_input_hidden
# Train function
def train(X_train, y_train):
```

```
# defining the model architecture
    inputLayer_neurons = 1 # number of neurons at input
   hiddenLayer_neurons = 3 # number of hidden layers neurons
   outputLayer_neurons = 1 # number of neurons at output layer
   # initializing weight
   weights_input_hidden = np. random.uniform(size=(inputLayer_neurons, hiddenLayer_neur
   weights_hidden_output = np. random. uniform(
        size=(hiddenLayer_neurons, outputLayer_neurons)
   )
   # defining the parameters
    Ir = 0.1
                   # CAN BE CHANGED IF REQUIRED
    epochs = 1000 # CAN BE CHANGED IF REQUIRED
    losses = []
   for ep in range (epochs):
      output_, hiddenLayer_activations = forward_pass(X_train, weights_input_hidden, we
      ## Backward Propagation
      # calculating error
      error = np. square(output_ - y_train) / 2
      error_wrt_weights_hidden_output, error_wrt_weights_input_hidden = backward_pass(X)
                                                                                       WE
                                                                                       Wŧ
                                                                                       hi
      # updating the weights
      weights_hidden_output = weights_hidden_output - Ir * error_wrt_weights_hidden_out
      weights_input_hidden = weights_input_hidden - Ir * error_wrt_weights_input_hidden
      # print error at every 100th epoch
      epoch_loss = np. average(error)
      if ep \% 100 == 0:
          print(f"Error at epoch {ep} is {epoch_loss:.5f}")
      # appending the error of each epoch
      losses. append (epoch_loss)
   plt. plot (losses)
   plt. show()
   final_pred, _ = forward_pass(X_train, weights_input_hidden, weights_hidden_output)
   plt. plot(final_pred, c='r')
   plt. plot(y_train, c='b')
   plt. show()
   print("Weights of the network are: ")
   print("w13, w12, w14", weights_hidden_output. T)
   print("w35, w25, w45", weights_input_hidden)
## HELPER CODE ##
```

```
# defining training data
X_{train} = np. zeros((11, 1)). astype(np. float32)
y_{train} = np. zeros((11, 1)). astype(np. float32)
X_{train}[0] = -3
X_{train}[1] = -2
X_{train}[2] = -1.5
X_{train}[3] = -1.0
X_{train}[4] = -0.5
X \text{ train}[5] = 0.0
X_{train}[6] = 0.5
X_{train[7]} = 1.0
X_{train[8]} = 1.5
X_{train}[9] = 2.0
X_{train}[10] = 3.0
y_{train}[0] = 0.7312
y_{train[1]} = 0.7339
y_{train}[2] = 0.7438
y_{train}[3] = 0.7832
y_{train}[4] = 0.8903
y_{train[5]} = 0.9820
y_{train[6]} = 0.8114
y_{train[7]} = 0.5937
y_{train[8]} = 0.5219
y_{train}[9] = 0.5049
y_{train}[10] = 0.5002
train(X_train, y_train)
```

```
Error at epoch 0 is 0.01722
Error at epoch 100 is 0.00772
Error at epoch 200 is 0.00683
Error at epoch 300 is 0.00667
Error at epoch 400 is 0.00664
Error at epoch 500 is 0.00663
Error at epoch 600 is 0.00662
Error at epoch 700 is 0.00662
Error at epoch 800 is 0.00661
Error at epoch 900 is 0.00661
```



w35, w25, w45 [[-0.08029881 0.78963782 -1.0612097]]

In []: