BERT

Bidirectional Encoder Representations from Transformer

Team 7

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Outline

1. Transformer
   1.1. Encoder
   1.2. Self-Attention

2. BERT
   2.1. Archtecture & Input
   2.2. 2 stage Training
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   2.5. FineTune
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3. BERT-Family
   3.1. SpanBERT, Roberta, ALBERT

Transformer

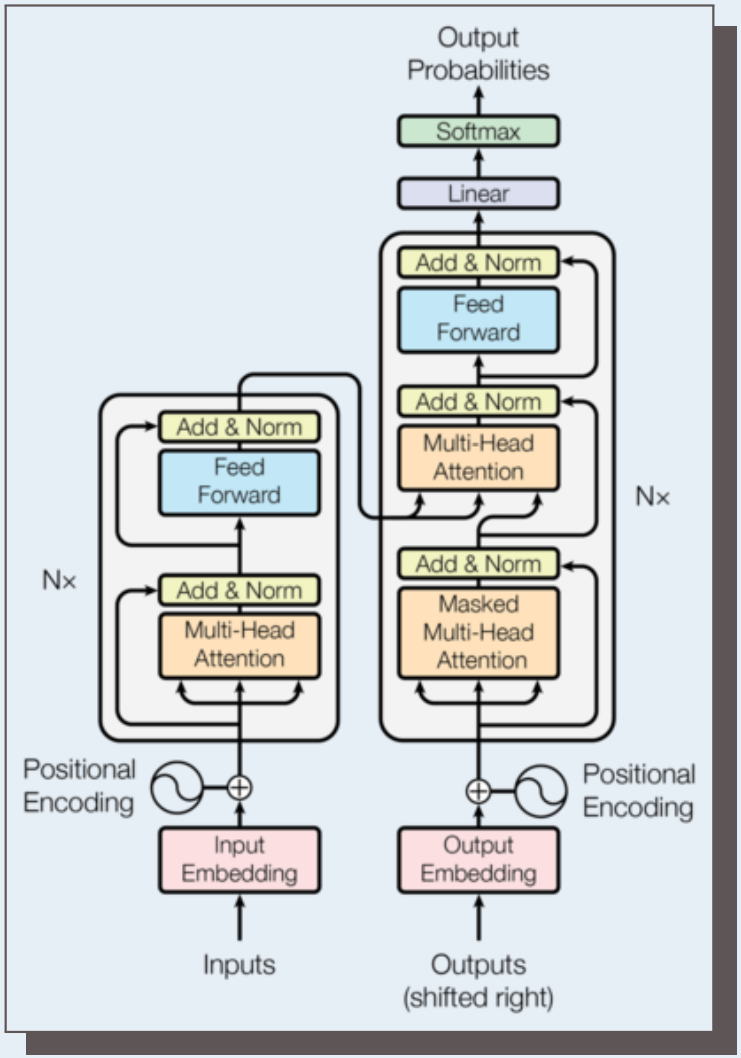

Figure: **Transformer**: Attention is all you need

Overview

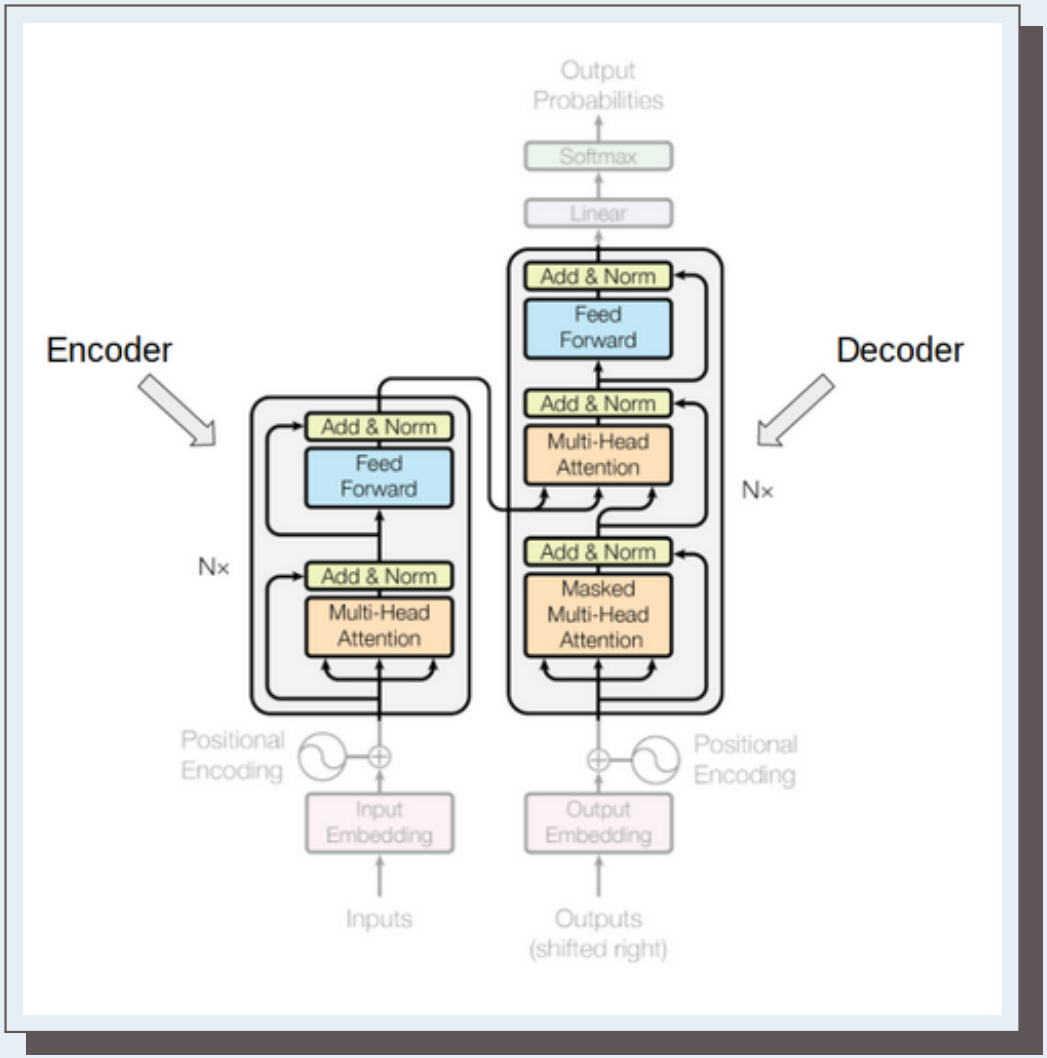

Figure: **Encoder-Decoder**

Encoder

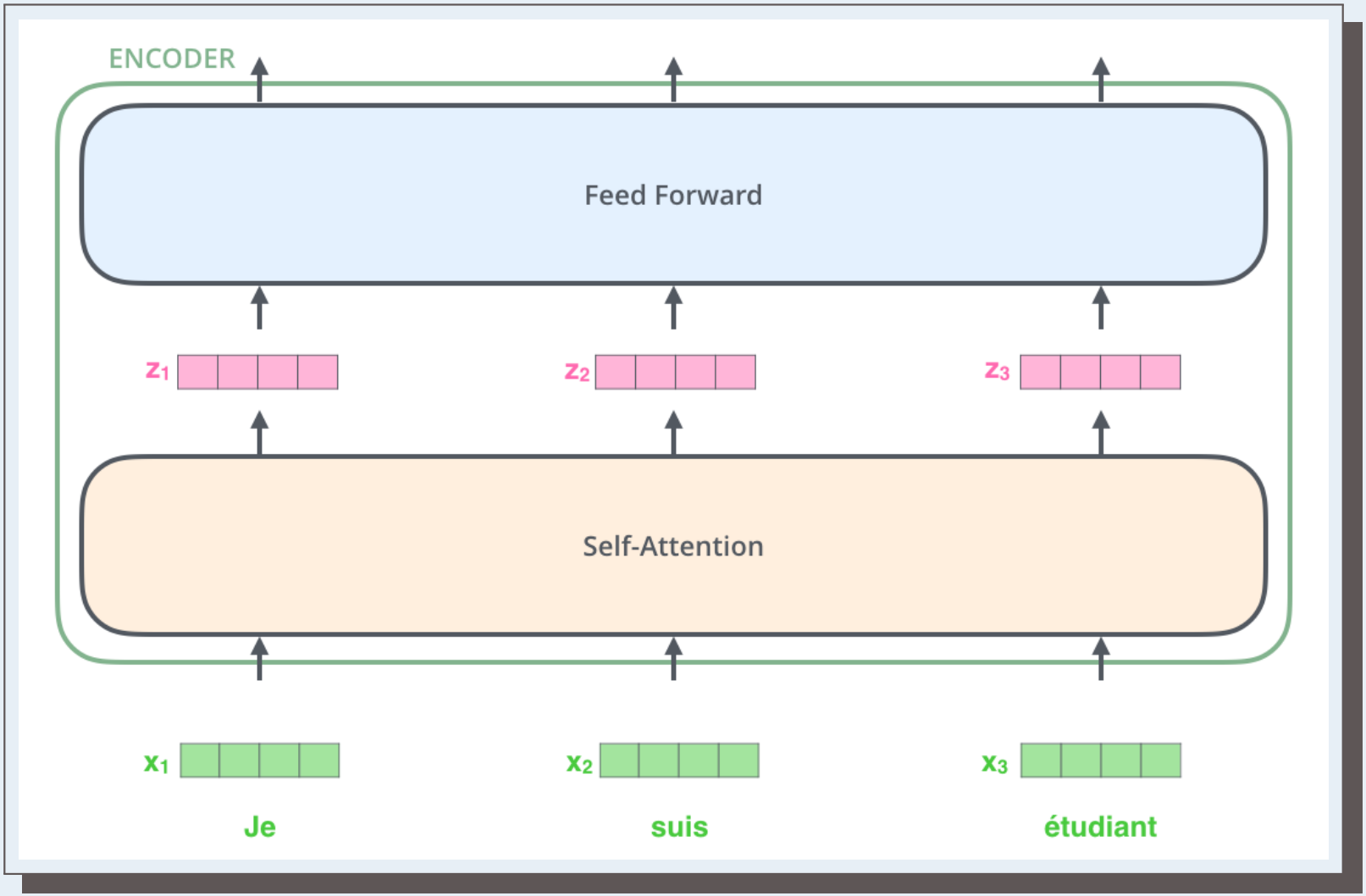

Figure: **1 Encoder-layer**

Self-Attention

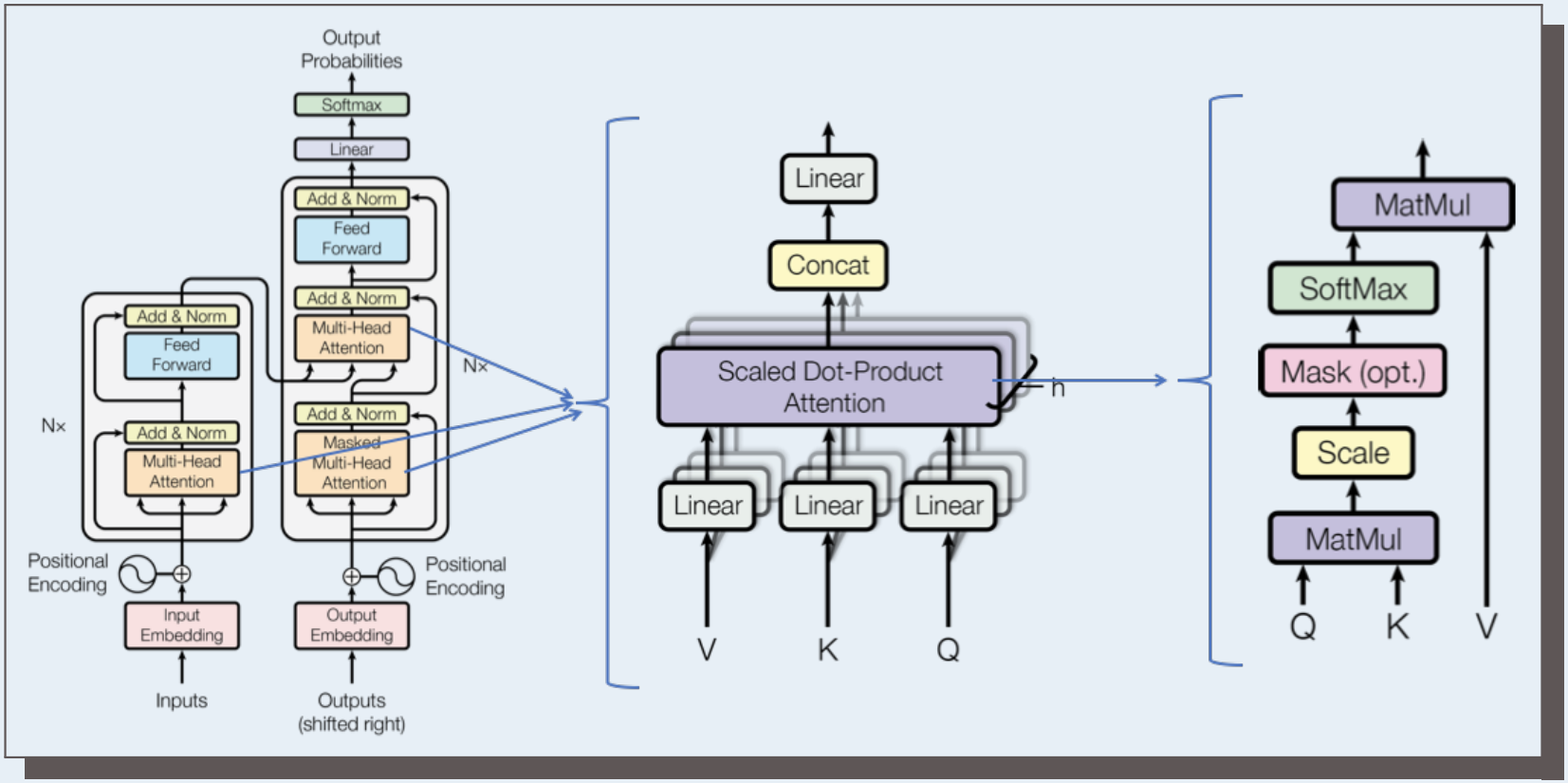

Figure: **Self-Attention**

BERT

Figure: **BERT**

Archtecture

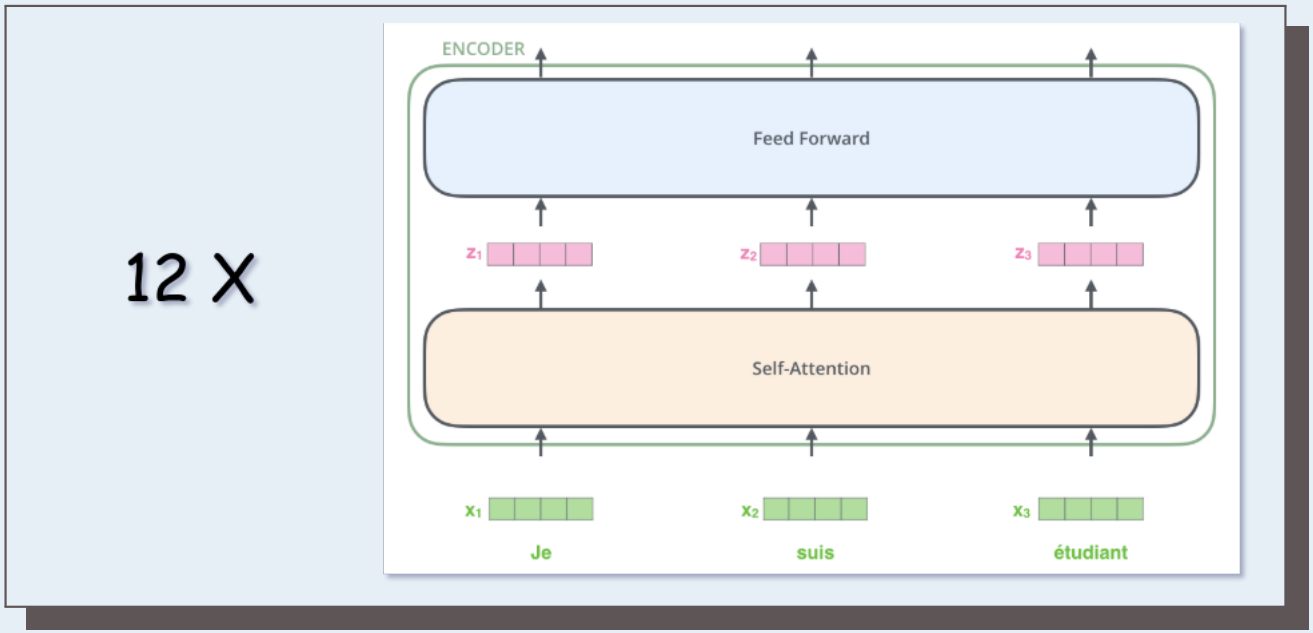

Figure: **BERT-Architecture**

Input

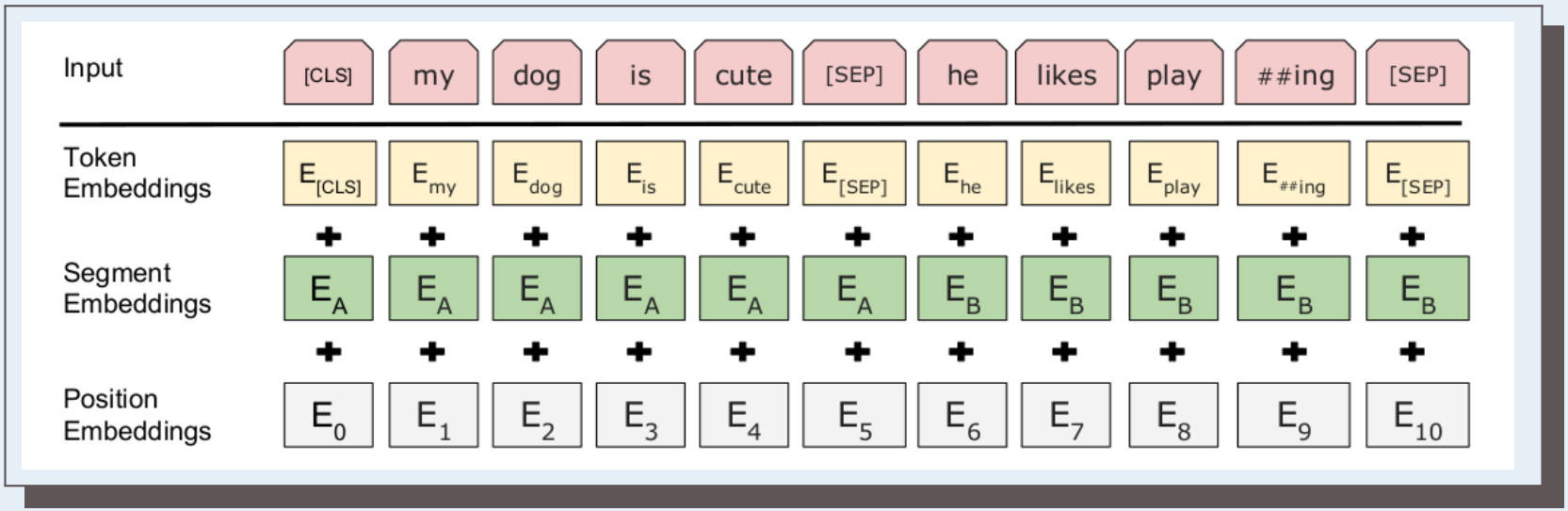

Figure: **BERT-Input**

2-stage-training

Pre-training

Self-supervised tasks.

Finetune

3 finetune tasks.

Pre-Training

Pretraining tasks

2 pretraining tasks

NSP

Next Sentence Prediction

MLM

Masked Language Model - self supervised learning

NSP

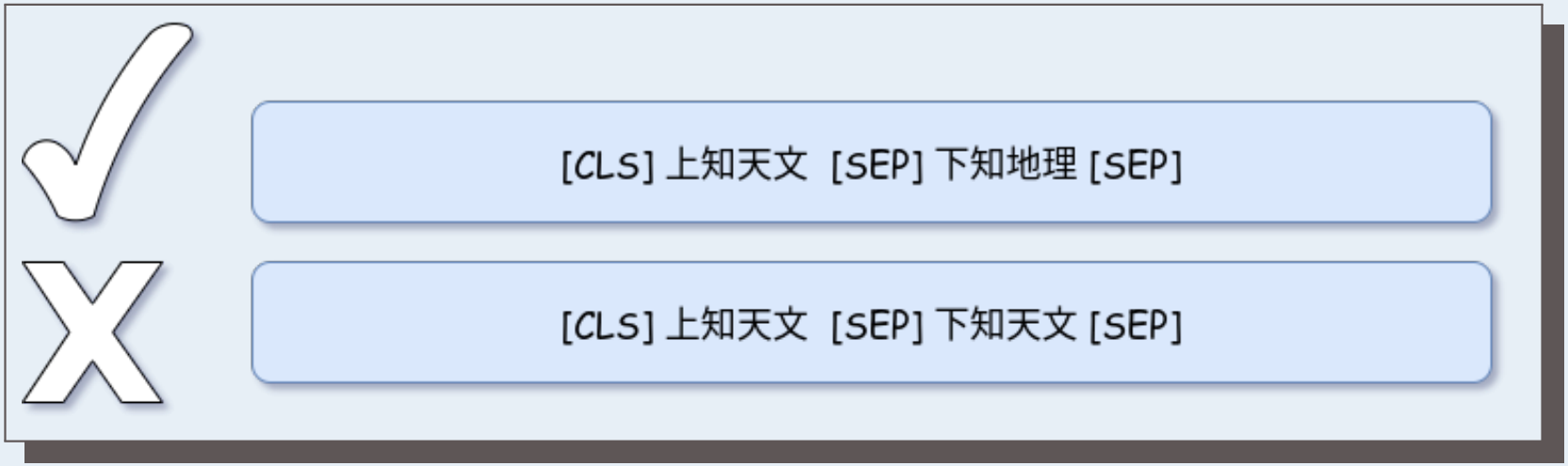

Figure: **Next Sentence Prediction**

Figure: **[CLS] token classifier**

What is self-supervised learning ?

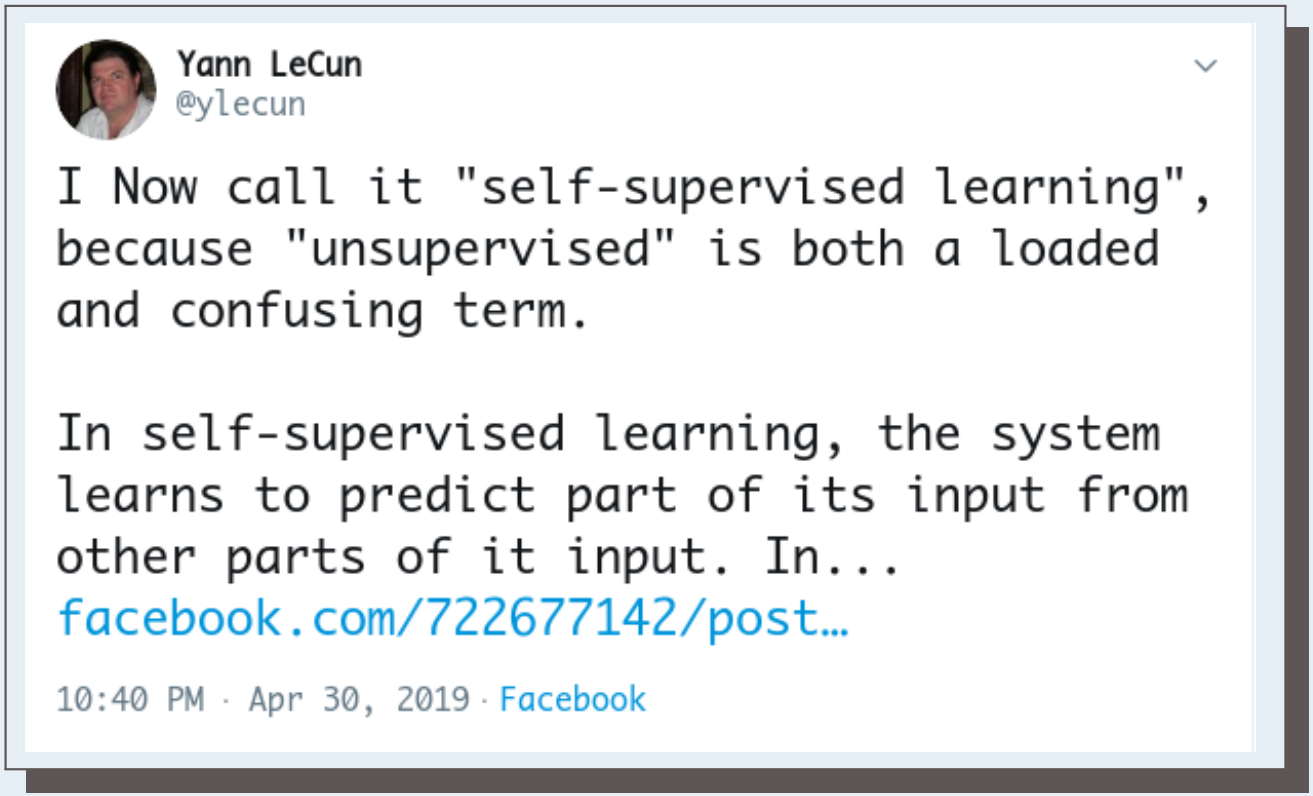

Figure: **Self-supervised learning definition**

MLM

Figure: **Masked LM**

Figure: **MLM classifier**

Fine-Tune

Downstream tasks:

NER

Name Entity Recognition

NLI

Natural Language Inference

QA

Question Answering

NLI

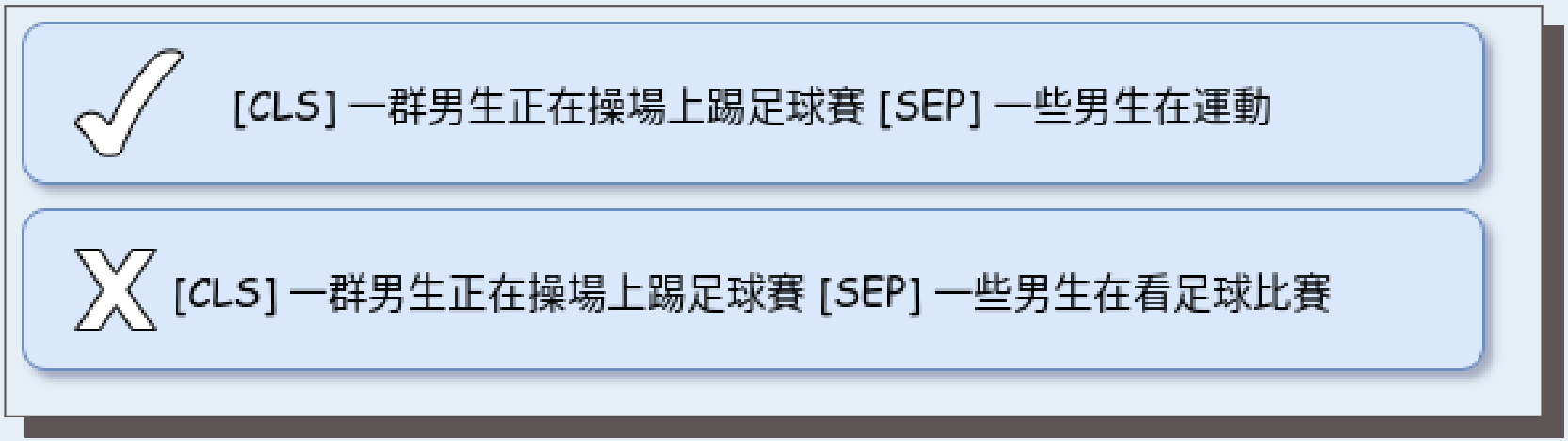

Figure: **Natural Language Inference**

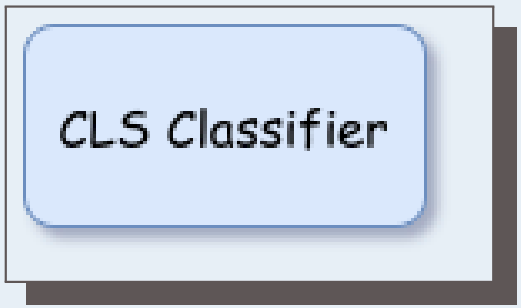

Figure: **[CLS] token classifier**

QA

[CLS] 彼得住在哪裡 ？ [SEP] 彼得是一個居住在歐洲的聰明男孩，
最近新冠肺炎在歐洲疫情十分險峻，聰明的彼得想到了一個方法，去減緩疫情的發展。[SEP]

Ans: 歐洲
start index: 17 end index: 18

Figure: **Question Answering Example**

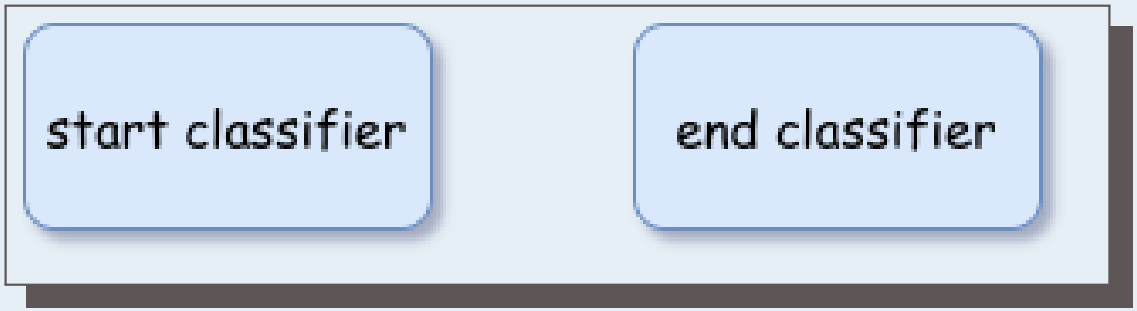

Figure: **Random initialize two classifiers**

Conclusion 2-stage training

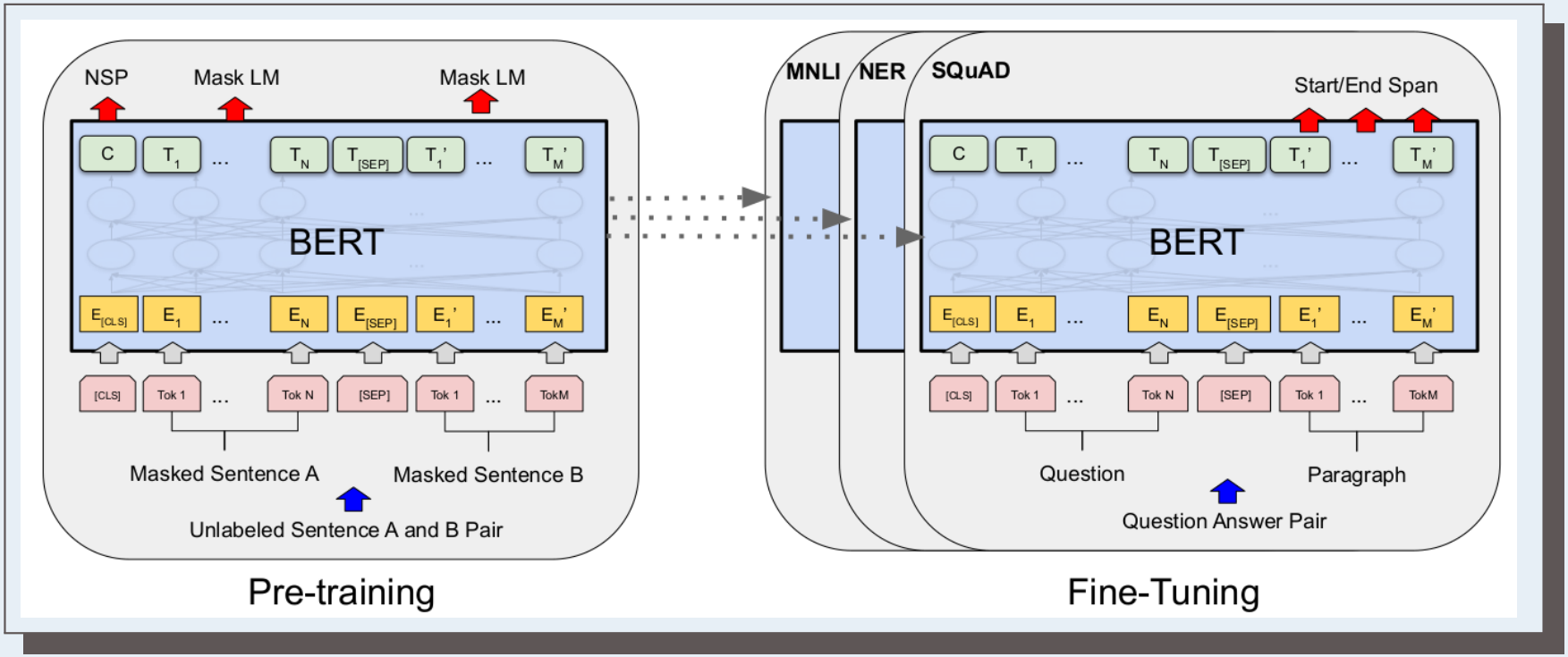

Figure: **2-stage training**

BERT-Family (1)

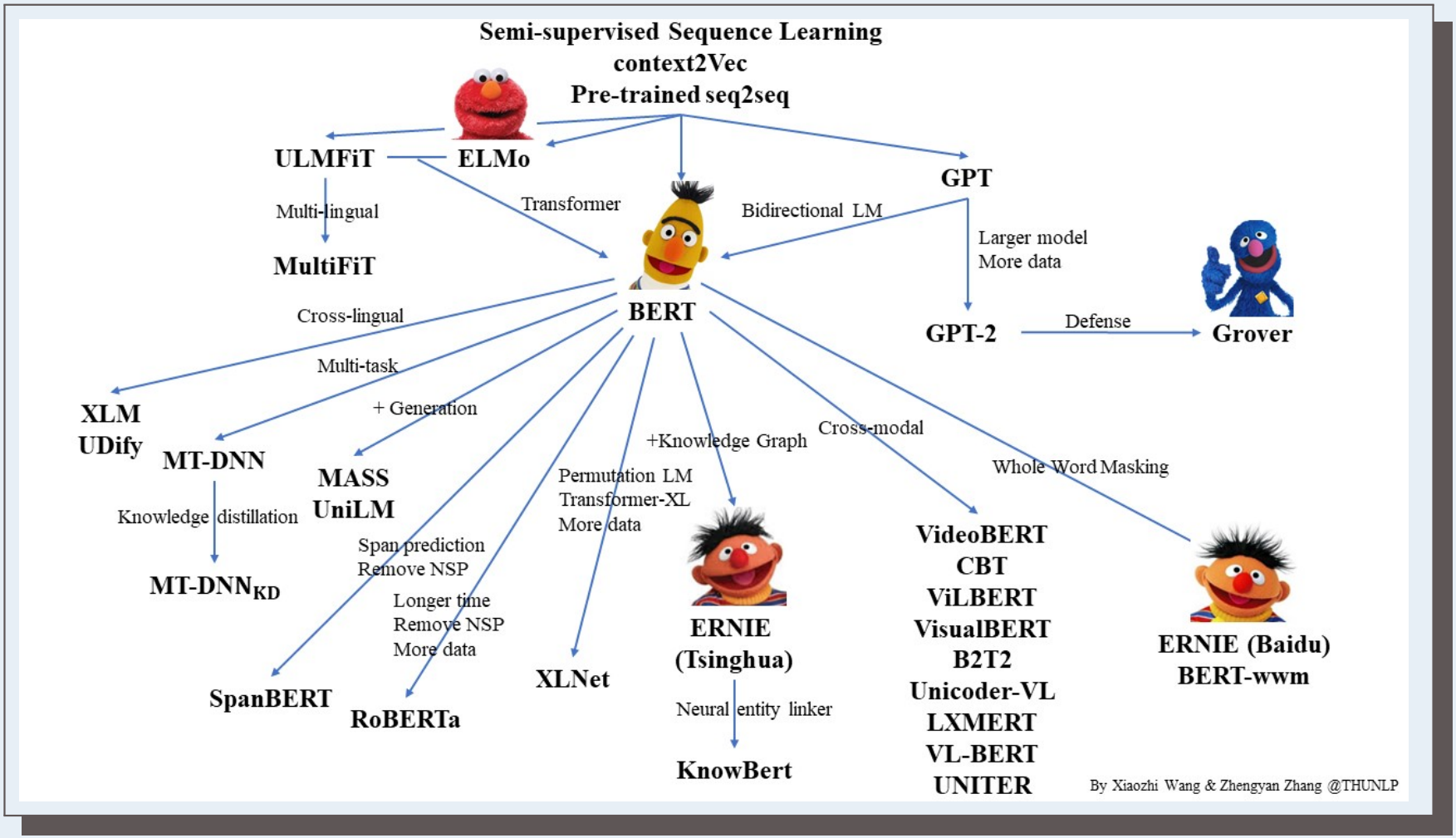

Figure: **BERT Family**

BERT-Family (2)

SpanBERT - EMNLP2019

Improving Pre-training by Representing and Predicting Spans

Roberta - ICLR2020 Reject

A Robustly Optimized BERT Pretraining Approach

ALBERT - ICLR2020 Spotlight

A Lite BERT for Self-supervised Learning of Language Representations

SpanBERT, Roberta, ALBERT

Difference with BERT - SpanBERT

1. change NSP task to SBO (span boundary objective) task.
2. mask random consecutive spans.

Difference with BERT - Roberta

1. More big batch size when training bert.
2. More optimal hyperparameters.
3. More data.
4. Remove NSP task.

Difference with BERT - ALBERT

1. change NSP task to SOP (Sentence Order Prediction) task.
2. One layer recall 12 times to build 12 layers. (share parameters)
3. factorize embedding table. initize small and project to big dimension.