# CPEX #42: Storing the Bounding Box of a grid

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### 1. Introduction

CGNS currently do not store explicitly the bounding box of a grid defined in a GridCoordinates\_t node. This information can be computed from coordinates arrays but it would be convenient to store and retrieve it quickly as algorithms could then harness this data (for load on demand, search process or). For instance the following paper shows usage of bounding box in an HPC context:

http://www.cie.bgu.tum.de/publications/masterthesis/2015 Ertl Master.pdf

As a matter of fact, major existing cfd file formats already provide this metadata :

- Xdmf is using Information node to store bounds : http://www.xdmf.org/index.php/XDMF Model and Format#Information
- Ensight gold format supports model extents:
   <a href="http://www3.ensight.com/EnSight92">http://www3.ensight.com/EnSight92</a> Docs/UserManual.pdf section "EnSight Gold Geometry File Format"
- VTK XML file format uses xml attribute to keep Extent of the grid

- ...

The proposal is thus to add the bounding box as an optional data of GridCoordinates\_t node.

## 2. Proposed extension, CGNS/SIDS

The simple modification consists in attaching the Bounding Box as an optional data of GridCoordinates in section 7.1 of CGNS SIDS.

```
GridCoordinates_t< int IndexDimension, int VertexSize[IndexDimension], int PhysicalDimension > :=

{
    DataArray_t < DataType, PhysicalDimension, 2> BoundingBox; (o)

    List( Descriptor_t Descriptor1 ... DescriptorN); (o)

    Rind_t<IndexDimension> Rind; (o/d)

List( DataArray_t<DataType, IndexDimension, DataSize[]>
    DataArray1 ... DataArrayN); (o)

DataClass_t DataClass; (o)

DimensionalUnits_t DimensionalUnits; (o)

List( UserDefinedData_t UserDefinedData1 ... UserDefinedDataN); (o)

};
```

Following text will be added after the Notes of section 7.1: The Bounding Box array will store minimum and maximum of coordinates values sorted by an alphabetical order for cartesian and cylindrical coordinates while Spherical and Auxiliary coordinates retain a specific order to be coherent with the existing SIDS notation:

```
    Bounding Box for 3D <u>cartesian coordinates</u>:
    [[Min (CoordinateX), Max(CoordinateX)],
    [Min (CoordinateY), Max(CoordinateY)],
    [Min (CoordinateZ), Max(CoordinateZ)]]
```

Bounding Box for 3D <u>cylindrical coordinates</u>:

[[Min (CoordinateR), Max(CoordinateR)],

[Inf (CoordinateTheta), Sup (CoordinateTheta)],

[Min (CoordinateX), Max(CoordinateX)]]

or

[[Min (CoordinateR), Max(CoordinateR)],

[Inf (CoordinateTheta), Sup(CoordinateTheta)],

[Min (CoordinateY), Max(CoordinateY)]]

or

[[Min (CoordinateR), Max(CoordinateR)],

[Inf (CoordinateTheta), Sup(CoordinateTheta)],

[Min (CoordinateZ), Max(CoordinateZ)]]

Bounding Box for 3D <u>spherical coordinates</u>:
 [[Min (CoordinateR), Max(CoordinateR)],
 [Inf (CoordinateTheta), Sup(CoordinateTheta)],
 [Inf (CoordinatePhi), Sup (CoordinatePhi)]]

Bounding Box for 3D <u>Auxiliary coordinates</u>:
 [[Min (CoordinateXi), Max(CoordinateXi)],
 [Min (CoordinateEta), Max(CoordinateEta)],
 [Min (CoordinateZeta), Max(CoordinateZeta)]]

Thus, all coordinate systems are handled in a deterministic way. For 2D coordinates the order is kept the same as for 3D.

Angle coordinates part of a bounding box is defined by *Inf(CoordinateTheta)* and *Sup(CoordinateTheta)* (respectively *Inf(CoordinatePhi)* and *Sup(CoordinatePhi)* for spherical coordinate angle) where *Inf* and *Sup* operators ensure unicity of the angle interval. The constraints for valid angle bounding box limits are:

- Inf(CoordinateTheta) is included in [0; 2π]
- Inf(CoordinateTheta) < Sup(CoordinateTheta)</li>
- Sup(CoordinateTheta) Inf(CoordinateTheta) ≤ 2π

# 1. Modification of CGNS/Filemap

The proposal consists in storing the Bounding Box information directly in GridCoordinates\_t Data (that was not used before). Thus GridCoordinates\_t mapping will be the following :

#### Node Attributes

Name: GridCoordinates or user defined

**Label:** GridCoordinates\_t **DataType:** MT or R4 or R8

**Dimension: 2** 

**Dimension Values: Physical Dimension, 2** 

Data: BoundingBox

Children: See GridCoordinates\_t figure

Cardinality: 0,N

Parameters: IndexDimension, VertexSize, PhysicalDimension

Functions: DataSize

### 3. Modification of CGNS/MLL

A new function should be introduced for reading bounding box while keeping compatibility with existing code:

ier = cg\_grid\_boundingbox\_read(int fn, int B, int Z, int G, DataType\_t DataType, void \*Data);

### Input/Output

fn CGNS file index number.

Base index number, where  $1 \le B \le$  nbases. Z Zone index number, where  $1 \le Z \le$  nzones. G Grid index number, where  $1 \le G \le$  ngrids.

**DataType** Type of data in the bounding box. The admissible types are RealSingle,

RealDouble.

**Data** The bounding box data array.

ier Error status.

In case the bounding box information is not present, Data will remain untouched and a warning will be emitted.

A similar function is specified for writing bounding box to an existing Grid:

```
ier = cg grid boundingbox write(int fn, int B, int Z, int G, DataType t DataType, void* Data);
```

The CGNS MLL rely on the user to compute the bounding box and ensure that the bounding box being stored is coherent with the GridCoordinates stored.

# 4. Conflict and compatibility concern

Modifying GridCoordinates\_t in CGNS/SIDS does not seem to create conflict with existing CGNS convention. Indeed, an existing CGNS file without Bounding box information in GridCoordinates nodes would be read and emits a warning only when trying to access the bounding box information and this situation can be handle properly. In case of CGNS file with Bounding Box information, existing codes will just ignore the data.

#### 5. Observations

To determine the system of coordinates being used for the GridCoordinates\_t node and thus the bounding box, reading the coordinate array names is needed. Adding a ReferenceFrame notion would be a great feature to remove this pattern.