THE FOURIER TRANSFORM

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1 Approximations

We first give some useful approximation results.

Proposition 1.1 (Continuity of translation in L^p). Let $f \in L^p(\mathbb{R}^n)$, and define $f_h(x) = f(x+h)$. Then,

$$||f_h - f||_p \to 0 \text{ as } h \to 0.$$

Proof. $\forall \epsilon > 0$, we can choose $g \in C_c(\mathbb{R}^n)$ with $||g - f|| < \epsilon$. Now, we have

$$||f_h - f||_p \le ||f_h - g_h||_p + ||g_h - g||_p + ||f - g||_p.$$

The first and third terms are both less than ϵ , while the second term goes to 0 as $h \to 0$ since g is continuous with compact support.

Theorem 1.2 (Approximations by good kernels). Let $K \in L^1(\mathbb{R}^n)$ with $\int_{\mathbb{R}^n} K(x) dx = 1$. Define $K_{\epsilon}(x) := \epsilon^{-n} K(x/\epsilon)$. If $f \in L^p(\mathbb{R}_n)$, then $f * K_{\epsilon} \in L^p(\mathbb{R}^n)$ with

$$||f * K_{\epsilon}||_{p} \le ||f||_{p} ||K||_{1}.$$

Moreover, we have $f * K_{\epsilon} \to f$ in L^p as $\epsilon \to 0$.

Proof. Note that $||K_{\epsilon}||_1 = ||K||_1$. The first assertion $||f * K_{\epsilon}||_p \le ||f||_p ||K||_1$ is an immediate consequence of Minkowski's inequality. For the second assertion, since $\int_{\mathbb{R}^n} K_{\epsilon}(x) dx = 1$, we have

$$f * K_{\epsilon}(x) - f(x) = \int_{\mathbb{R}^n} (f(x-y) - f(x)) K_{\epsilon}(y) dy.$$

Apply Minkowski's inequality, we get

$$||f * K_{\epsilon} - f||_{p} \le \int_{\mathbb{R}^{n}} ||f_{y} - f||_{p} |K_{\epsilon}(y)| dy,$$

where $f_y(x) = f(x - y)$. Note that $||f_y - f||_p \to 0$ as $y \to 0$, so $\forall \delta > 0$, $\exists \eta$ such that $||f_y - f||_p < \delta$ whenever $|y| < \eta$. Thus, separating \mathbb{R}^n into $\{|y| < \eta\}$ and $\{|y| \ge \eta\}$, we have

$$||f * K_{\epsilon} - f||_{p} \le \delta ||K||_{1} + 2 ||f||_{p} \int_{|y| > p} |K_{\epsilon}(y)| dy.$$

Note that the second integral goes to 0 as $\epsilon \to 0$ as long as η is positive, so it follows that $||f * K_{\epsilon} - f||_{p} \to 0$.

If $f \in L^1_{loc}$ and $\varphi \in C_c^{\infty}(\mathbb{R}^n)$, then by dominated convergence, $f * \varphi \in C_c^{\infty}(\mathbb{R}^n)$ and

$$D^{\alpha}(f * \varphi) = f * (D^{\alpha}\varphi).$$

Note that such a φ exists, for example

$$\varphi(x) = \begin{cases} k \exp(-\frac{1}{1-|x|^2}), & |x| < 1 \\ 0, & |x| \ge 1 \end{cases},$$

where the constant k is added to ensure $\int_{\mathbb{R}^n} \varphi = 1$. Since all L^p functions are in L^1_{loc} , the previous approximation theorem immediately implies the following.

Corollary 1.3. Smooth functions with compact support are dense in L^p .

2 Basics in L^1 and inversion

Let $f \in L^1(\mathbb{R}^n)$. The Fourier transform of f is defined by

$$\hat{f}(\xi) = \int_{\mathbb{R}^n} f(x)e^{-2\pi i \xi \cdot x} dx.$$

The following properties of L^1 Fourier transform are easy to prove:

- 1. $||\hat{f}||_{\infty} \leq ||f||_{1}$, and \hat{f} is uniformly continuous on \mathbb{R}^{n} ;
- 2. (Scaling). If $\lambda > 0$ and $\delta_{\lambda} f(x) = f(\frac{x}{\lambda})$, then

$$\widehat{\delta_{\lambda}f}(\xi) = \lambda^n \hat{f}(\lambda \xi).$$

3. (Convolution). If $f, g \in L^1$, then $\widehat{f * g} = \widehat{f}\widehat{g}$.

Theorem 2.1 (Riemann-Lebesgue). If $f \in L^1$, then $\hat{f}(\xi) \to 0$ as $|\xi| \to \infty$.

Proof. The theorem is true when f is an indicator function of some rectangle in \mathbb{R}^n ; so it is also true when f is a linear combination of such functions. Since step functions are dense in L^1 , we can find a sequence of step functions g_k such that $||g_k - f||_1 \to 0$. Now, we have

$$\hat{f}(\xi) = \int_{\mathbb{R}^n} (f(x) - g_k(x))e^{-2\pi i \xi \cdot x} dx + \widehat{g}_k(\xi).$$

Choose k large (independent of ξ) so that the first term is smaller than ϵ , and the second term goes to 0 when $|\xi|$ grows to infinity, so the left hand side can be made arbitrarily small $|\xi| \to \infty$.

We will frequently use the Fourier transform of a Gaussian; in particular, the Fourier transform of $\exp(-\pi|x|^2)$ is itself. To see this, it suffices to consider the case $x \in \mathbb{R}$. We first assume $\eta \in \mathbb{R}$, and we can complete the squares to get

$$\int_{\mathbb{R}} e^{-\pi x^2} e^{-2\pi \eta x} dx = e^{\pi \eta^2}.$$

Now consider the left hand side as a function of $\eta \in \mathbb{C}$. Since the integral converges uniformly on all compact sets in \mathbb{C} , it is an analytic function and we can get its value by analytic continuation. Thus, setting $\eta = i\xi$ gives us the desired answer. Now, let

$$\varphi_{\epsilon}(x) = \exp(-\epsilon |x|^2),$$

then a simple scaling argument yields

$$\widehat{\varphi}_{\epsilon}(\xi) = \left(\frac{\pi}{\epsilon}\right)^{n/2} \exp(-\pi^2 |\xi|^2 / \epsilon). \tag{1}$$

We now turn to the question of inversion. Clearly, we have

$$\int_{\mathbb{R}^n} \hat{f}(\xi) e^{2\pi i \xi \cdot x} d\xi = \int_{\mathbb{R}^n} \int_{\mathbb{R}^n} f(y) e^{-2\pi i \xi \cdot (y-x)} dy d\xi. \tag{2}$$

If we change the order of integration on the right hand side, then we will get $\int_{\mathbb{R}^n} f(y)\delta(x-y)dy$, which is exactly f(x) whenever f is continuous at x. But this change of order of integration is just at an informal level, and we need to carefully justify this heuristic.

Theorem 2.2 (L^1 Inversion). If both f and \hat{f} are in L^1 , then

$$f(x) = \int_{\mathbb{R}^n} \hat{f}(\xi) e^{2\pi i \xi \cdot x} d\xi \ a.e.$$

Proof. In order to apply Fubini's theorem, we multiply the Gaussian function $\exp[-\epsilon|\xi|^2]$ on both sides of (2). For the left hand side, by dominated convergence theorem, we have

$$\int_{\mathbb{R}^n} \hat{f}(\xi) e^{2\pi i \xi \cdot x} e^{-\epsilon |\xi|^2} d\xi \to \int_{\mathbb{R}^n} \hat{f}(\xi) e^{2\pi i \xi \cdot x} d\xi, \ \forall x$$

as $\epsilon \to 0$. Note that this is where we have used $\hat{f} \in L^1$. For the right hand side, we apply Fubini's theorem and implement (1), we get

$$\int_{\mathbb{R}^n} \int_{\mathbb{R}^n} f(y) e^{-2\pi i \xi \cdot (y-x)} e^{-\epsilon |\xi|^2} dy d\xi = (f * G_{\epsilon})(x),$$

where $G_{\epsilon}(y) = \left(\frac{\pi}{\epsilon}\right)^{n/2} \exp(-\pi^2|y|^2/\epsilon)$, and we have $f * G_{\epsilon} \to f$ in L^1 . Thus, we can substract a subsequence which converges a.e. to f. The proof of the theorem is complete by taking $\epsilon \to 0$ along that subsequence.

As an immediate consequence, we obtain the following corollary. Note that it is definitely not true for general L^1 functions.

Corollary 2.3. If both f and \hat{f} are in L^1 , then f can be modified on a set of measure 0 to be a continuous and bounded function.

3 L^2 theory

If $f \in L^2$, it is not immediately obvious how to define its Fourier transform. We shall however start with functions in $L^1 \cap L^2$.

Theorem 3.1 (Plancherel). If $f \in L^1(\mathbb{R}^n) \cap L^2(\mathbb{R}^n)$, then $\hat{f} \in L^2$ and we have

$$||\hat{f}||_2 = ||f||_2$$
.

Proof. The proof also involves approximating the delta function by Gaussian kernels. By monotone convergence theorem, we have

$$\int_{\mathbb{R}^n} |\hat{f}(\xi)|^2 \exp(-\epsilon |\xi|^2) d\xi \to ||\hat{f}||_2^2, \tag{3}$$

with the right hand side possibly being ∞ . We now need to show that it also converges to $||f||_2^2$. Note that we can write $|\hat{f}(\xi)|^2 = \hat{f}(\xi)\overline{\hat{f}(\xi)}$ in terms of Fourier integrals, and apply Fubini's theorem to integrate ξ out first to we get

$$\int_{\mathbb{R}^n} |\hat{f}(\xi)|^2 \exp(-\epsilon |\xi|^2) d\xi = \int_{\mathbb{R}^n} f(x) \left(\int_{\mathbb{R}^n} \bar{f}(x-y) G_{\epsilon}(y) dy \right) dx.$$

By a similar argument as before, we can show that the right hand side converges to $||f||_2$. This implies $\hat{f} \in L^2$ and $||\hat{f}||_2 = ||f||_2$.

Now let $f \in L^2$, and choose a sequence $\{f_j\} \in L^1 \cap L^2$ such that $||f_j - f||_2 \to 0$. Since $||\widehat{f_j} - \widehat{f_k}||_2 = ||f_j - f_k||_2$, $\{\widehat{f_j}\}$ is also a Cauchy sequence in L^2 , and hence we can define

$$\hat{f} := \lim_{j \to +\infty} \widehat{f}_j$$

It is clear that the limit is independent of the choice of the sequence f_j . We thus **define** this \hat{f} to be the Fourier transform of the L^2 function f. Moreover, we have

$$||\hat{f}||_2 = \lim_{j \to +\infty} ||\hat{f}_j||_2 = \lim_{j \to +\infty} ||f_j||_2 = ||f||_2.$$

We have now defined the Fourier transform \mathcal{F} on L^2 , which is a linear **isometry** from $L^2(\mathbb{R}^n)$ into $L^2(\mathbb{R}^n)$. The next theorem asserts that this map is **unitary**: it is onto and invertible! The proof of this fact is by approximations in a similar way as before.

Theorem 3.2. The Fourier transform \mathcal{F} on $L^2(\mathbb{R}^n)$ is unitary, with inverse

$$(\mathcal{F}^{-1}f)(x) = (\mathcal{F}f)(-x), f \in L^2(\mathbb{R}^n).$$

Example 3.3. Let $f \in L^2(\mathbb{R})$, and suppose there exists $g \in L^2(\mathbb{R})$ such that f' = g weakly. We claim that f can be modified on a set of measure 0 to be a continuous function. In fact, we have

$$2\pi i \xi \hat{f}(\xi) = \hat{g}(\xi) \in L^2(\mathbb{R}).$$

Write

$$\int_{\mathbb{R}} |\hat{f}| d\xi = \int_{|\xi| \le 1} |\hat{f}| d\xi + \int_{|\xi| > 1} |\hat{f}| d\xi.$$

The first term on the right hand side is finite since $\hat{f} \in L^2$ and the set $\{|\xi| \leq 1\}$ has finite measure. For the second term, we have

$$\int_{|\xi|>1} |\hat{f}| d\xi \le \left(\int_{|\xi|>1} \frac{1}{\xi^2} d\xi \right)^{\frac{1}{2}} \left(\int_{|\xi|>1} \xi^2 |\hat{f}(\xi)|^2 d\xi \right)^{\frac{1}{2}} < +\infty.$$

Thus, $\hat{f} \in L^1(\mathbb{R})$ and the claim follows. Note that f is more than merely being continuous. In fact, f can be modified on a set of measure 0 such that it is Hölder- $\frac{1}{2}$, a consequence of Morrey's inequality.

Remark 3.4. The above example is not true if n = 2. Let $\alpha \in (0, \frac{1}{2})$, and consider for example the function $f(x) = (\log(1/|x|))^{\alpha}$ for $|x| < \frac{1}{2}$, f(x) = 0 for $|x| \ge 1$ and 'smoothly interpolate' between. Then, $f \in L^2$, and both $\frac{\partial}{\partial x_1} f$ and $\frac{\partial}{\partial x_2} f$ are in L^2 weakly, but f cannot be modified on a set of measure 0 to a continuous function.

4 Extension to L^p ?

To proceed to L^p , one might think of mimicing the L^2 approach: first defining it on the dense subset $L^1 \cap L^p$, then extending it to all of L^p . The essence is whether there exists a q and C = C(n, p, q) such that the following inequality holds

$$||\hat{f}||_q < C ||f||_p, \qquad \forall f \in L^1 \cap L^p. \tag{4}$$

One first observes that if such an inequality holds, then q cannot be arbitrary. In fact, $\frac{1}{p} + \frac{1}{q} = 1$ is the only possible choice of q. To see this, suppose $f \in L^1 \cap L^p$, and let $f_{\lambda}(x) = f(\lambda x)$, then f_{λ} must satisfy (4) with the same constant C for all λ . Also, we have

$$\|\widehat{f_{\lambda}}\|_{q} = \lambda^{-n(1-\frac{1}{q})} \|\widehat{f}\|_{q}, \qquad \|f_{\lambda}\|_{p} = \lambda^{-\frac{n}{p}} \|f\|_{p}.$$

By sending λ to 0 and to $+\infty$ respectively, one can easily see that the only choice for q is the conjugate of p. Our second observation is that no such inequality exists for p > 2. To see this, consider

$$f(x) = \exp \left[-(a+bi)|x|^2 \right], \ a > 0.$$

By sending $b \to \infty$, we can see that (4) cannot hold if p > 2. Nevertheless, we have a positive result for $p \in (1,2)$.

Theorem 4.1 (Hausdorff - Young). Let $p \in (1,2)$ and $\frac{1}{p} + \frac{1}{q} = 1$. Then, there exists C = C(n, p, q) such that

$$||\hat{f}||_q < C ||f||_p, \qquad \forall f \in L^1 \cap L^p.$$

Remark 4.2. The Fourier transform for general L^p functions can be defined via tempered distributions. These turn out to be equivalent with the above approach when $p \in [1, 2]$.

5 The heat equation

We now apply some properties of the Fourier transform to solve the heat equation

$$\partial_t u = \Delta u, \qquad u(x,0) = g(x)$$
 (5)

for the unknown $u: \mathbb{R}^n \times \mathbb{R}^+ \to \mathbb{R}$, where $g \in \mathcal{S}(\mathbb{R}^n)$. Since the Fourier transform turns differentiation into multiplication, taking the transform on both sides with the spatial variable yields

$$\hat{u}'(\xi, t) = -4\pi |\xi|^2 \hat{u}(\xi, t), \qquad \hat{u}(\xi, 0) = \hat{g}(\xi),$$

where the differentiation on the left hand side is with respect to t. For each $\xi \in \mathbb{R}^n$, this is an ODE in t and the solution is

$$\hat{u}(\xi, t) = \hat{g}(\xi) \exp\left(-4\pi |\xi|^2 t\right). \tag{6}$$

Note that the second term is the Fourier transform of the heat kernel

$$H_t(x) = (4\pi t)^{-n/2} e^{-\frac{|x|^2}{4t}},$$

so we actually have

$$u(x,t) = (g * H_t)(x).$$

One can check by differentiation under the integral sign that this indeed solves the heat equation (5).

Remark 5.1. The expression on the right hand side of (6) suggests that t cannot be negative. This amounts to the fact that given the initial value at t = 0, one cannot solve the heat equation backwards. In other words, the heat flow cannot be reversed.

Remark 5.2. If the initial condition $g \ge 0$ and is strictly positive somewhere, then as long as t > 0, $u(x,t) = (g * H_t)(x)$ is strictly positive for every x. This says that the heat flow has infinite propagation.

Let us now consider the inhomogeneous heat equation

$$\partial_t u = \Delta u + f, \qquad u(x,0) = g(x).$$
 (7)

We again assume for simplicity that both f and g are smooth and all derivatives have rapid decay. Same as before, taking Fourier transform on both sides with respect to spatial variable gives rise to an ODE with unknown $\hat{u}(\xi,t)$ in t. Solving this ODE and inverting the Fourier transform gives

$$u(x,t) = (g * H_t)(x) + \int_0^t \int_{\mathbb{R}_n} f(y,s) H_{t-s}(x-y) dy ds.$$

Remark 5.3. Note that for every s, the function

$$v_s(x,t) = \int_{\mathbb{R}^n} f(y,s) H_{t-s}(x-y) dy = (f(\cdot,s) * H_{t-s})(x)$$

solves the homogeneous problem

$$\partial_t v_s = \Delta v_s, \qquad v_s(x,s) = f(x,s)$$

for $t \geq s$. Integrating v_s from 0 to t gives the solution to the original equation (7) with initial condition g = 0. This is an example of Duhamel's principle.