

# CSE 105: Data Structures and Algorithms-I (Part 2)

Instructor  
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# Graphs and Trees: Representation and Search

# Tree Implementation

**We have already seen the following**  
binary tree data structure

```
struct BTreeNode {  
    int data;  
    struct BTreeNode *left, *right;  
}
```

# Tree Implementation

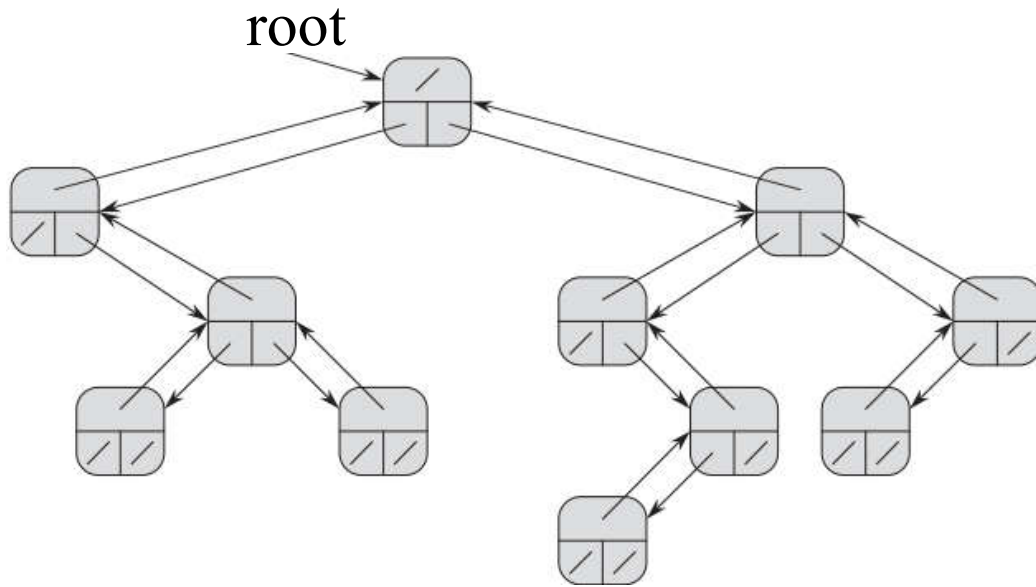
**We have already seen the** following binary tree data structure

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struct BTreeNode {  
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Some applications may require to store **parent** information in the node

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struct BTreeNode {  
    int data;  
    struct BTreeNode *left, *right, *parent;  
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# Tree Implementation



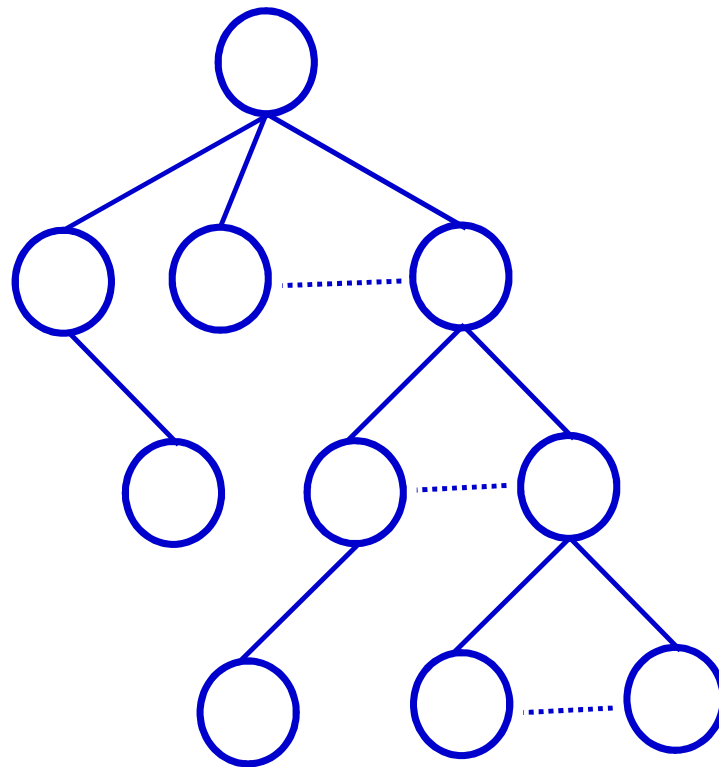
Some applications may require to store **parent** information in the node

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# Tree Implementation

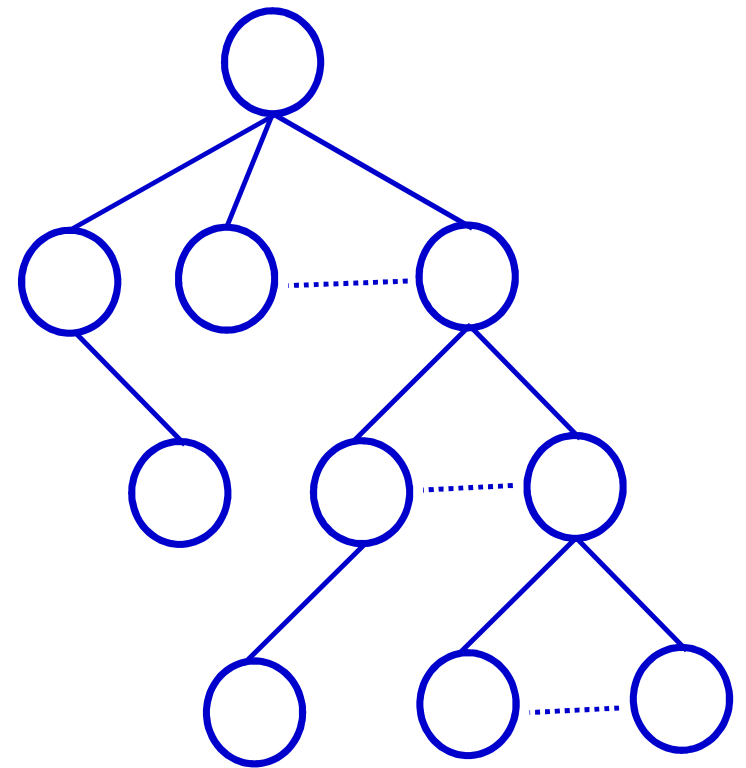
If a tree has unbounded number  
children



# Tree Implementation

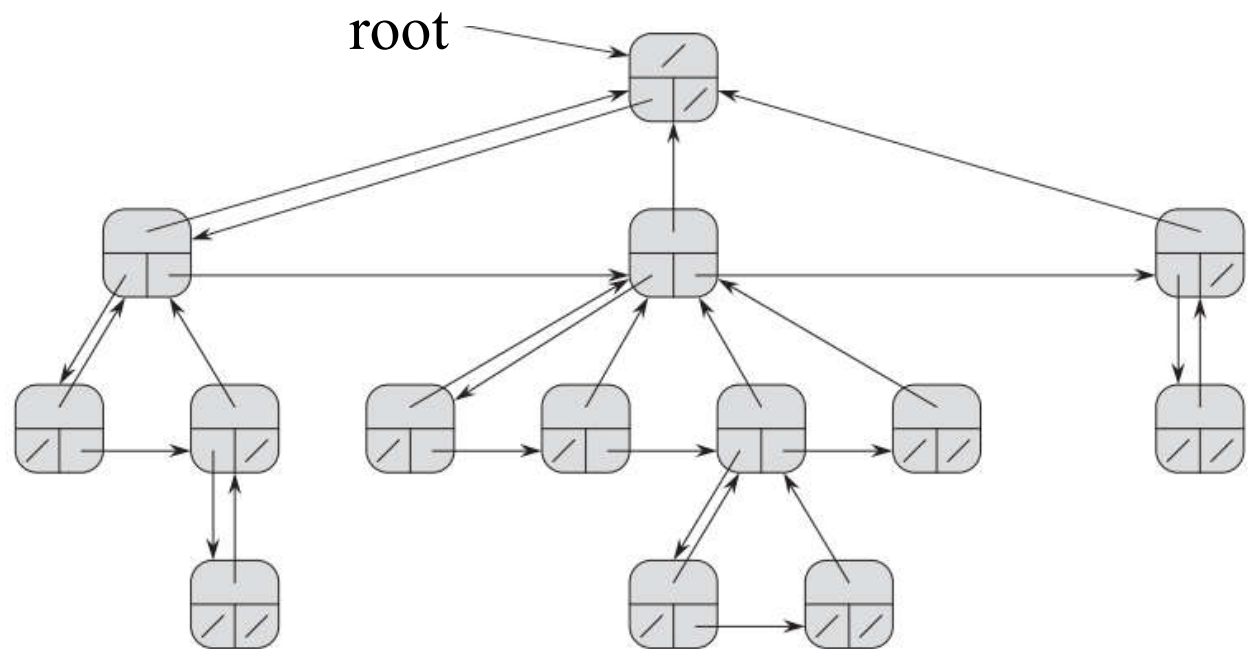
If a tree has unbounded number children

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struct BTreeNode {  
    int data;  
  
    struct BTreeNode *left, *rightsibling, *parent;  
}
```



# Tree Implementation

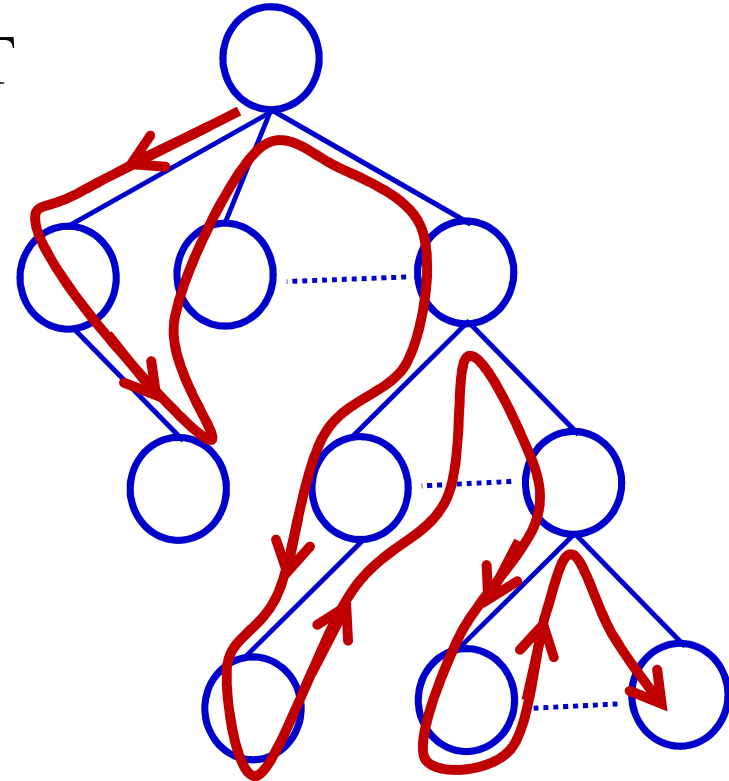
```
struct BTreeNode {  
    int data;  
    struct BTreeNode *left, *rightsibling, *parent;  
}
```





# Tree Traversal

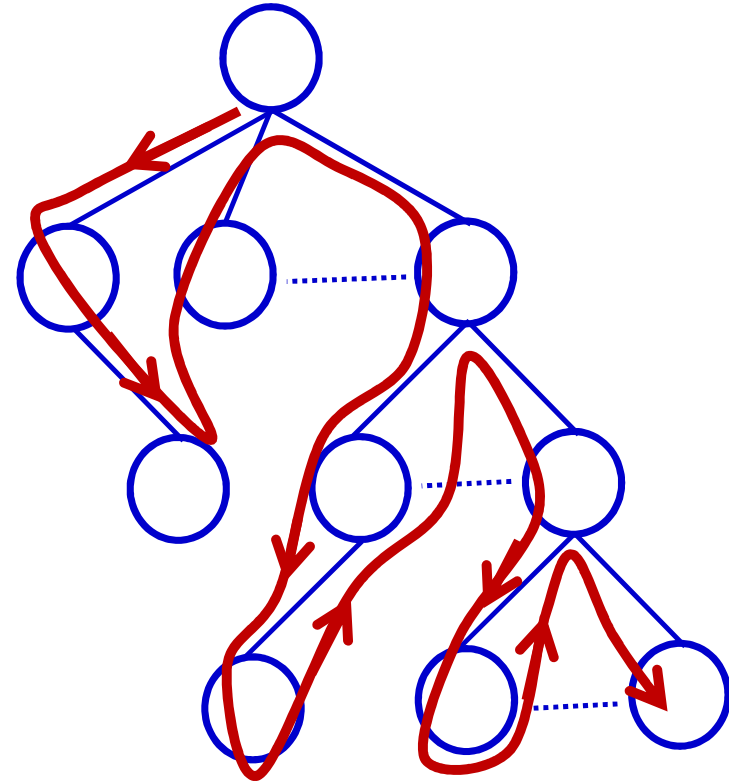
- process for **visiting the nodes** in **some order** is called a **traversal**.
- **systematic way of visiting** all the nodes of T
- visits the root and traverses its subtrees



# Tree Traversal

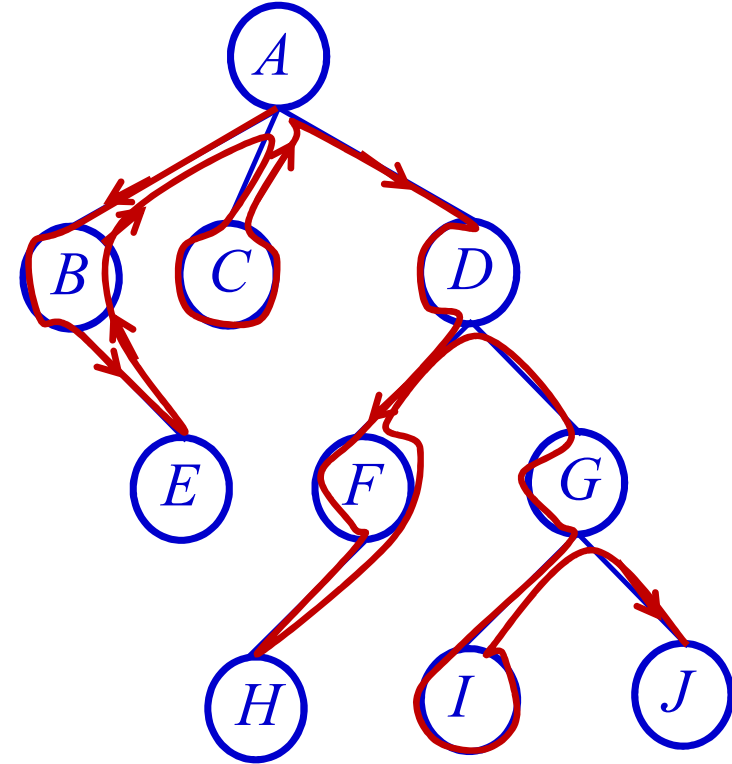
## 3 main traversal methods:

- **Preorder** Traversal (applicable for any tree)
- **Postorder** Traversal (applicable for any tree)
- **Inorder** Traversal (of a binary tree)
- Other than the above, **level order traversal**
- Traversing **every node exactly once** is called an **enumeration** of the tree's nodes.



# Preorder Tree Traversal

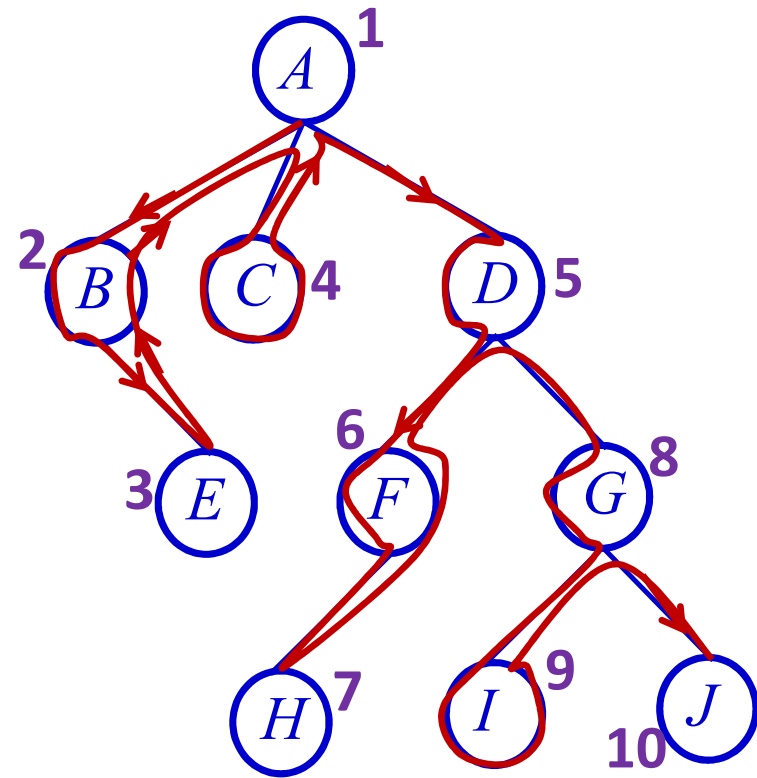
- a node is visited **before** its descendants
- subtrees are traversed according to the order of the children
- We assume a left to right order



# Preorder Tree Traversal

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- subtrees are traversed according to the order of the children
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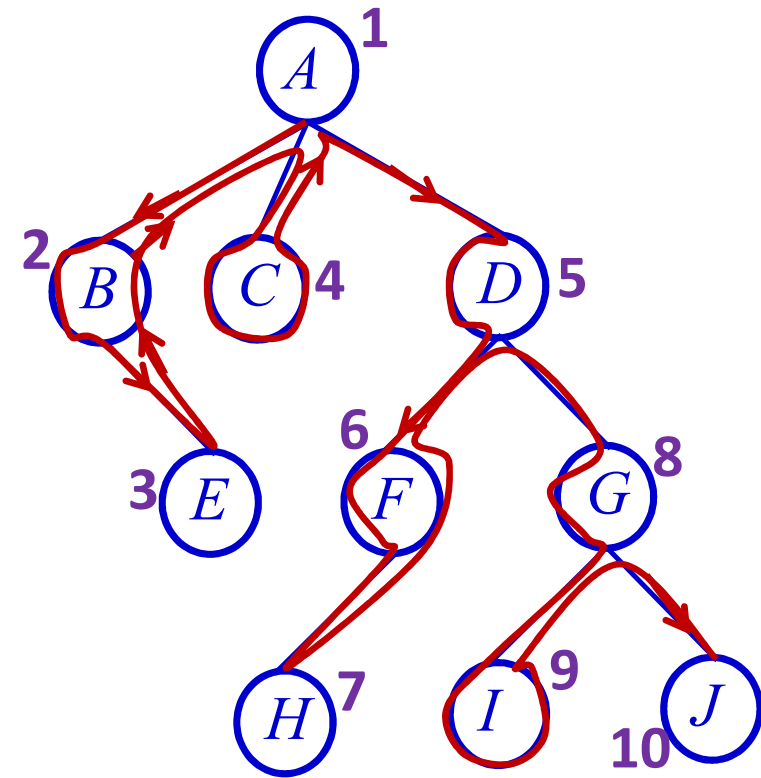
Traversal: **A B E C D F H G I J**



# Preorder Tree Traversal

- a node is visited **before** its descendants
- subtrees are traversed according to the order of the children
- We assume a left to right order

**Algorithm** *preOrder(v)*  
If  $v$  is NULL, return  
*visit(v)*  
for each child  $w$  of  $v$   
    *preOrder(w)*



# Postorder Tree Traversal

- a node is visited **only after** all its descendants are visited

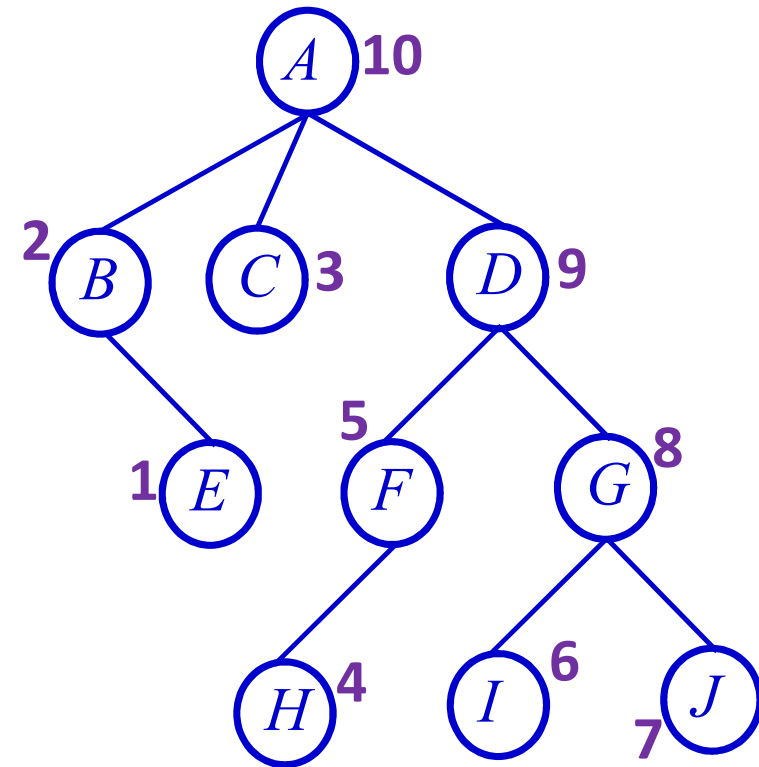
**Algorithm** *postOrder*(*v*)

If *v* is NULL, return  
for each child *w* of *v*

*postOrder* (*w*)

*visit*(*v*)

Traversal: E B C H F I J G D A



# Inorder Tree Traversal

- Only for **binary tree**
- a node is visited *after* its left branch and *before* all its right branch are visited

**Algorithm** *inOrder*(*v*)

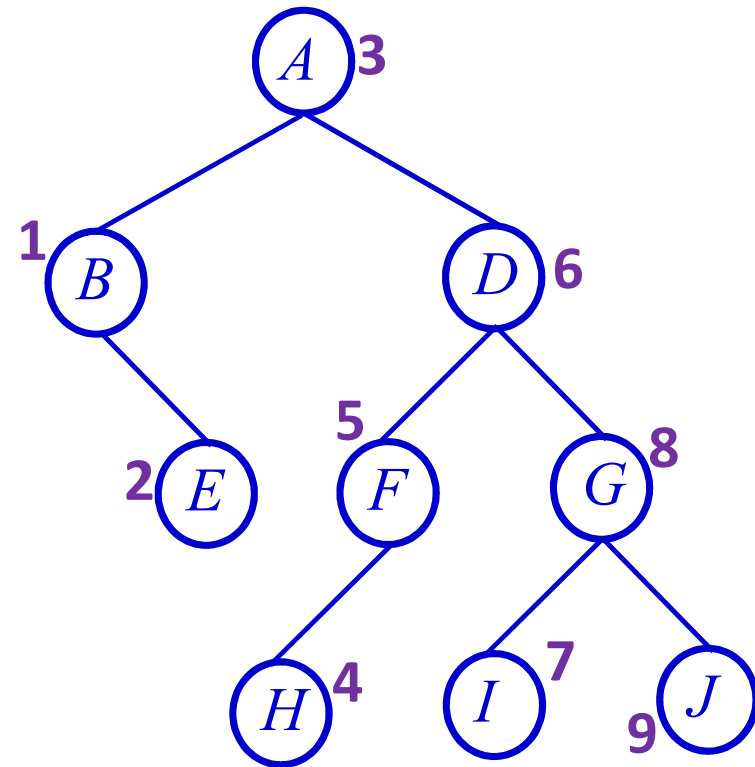
If *v* is NULL, return

*inOrder*( leftChild(*v*) )

*visit*(*v*)

*inOrder*( rightChild(*v*) )

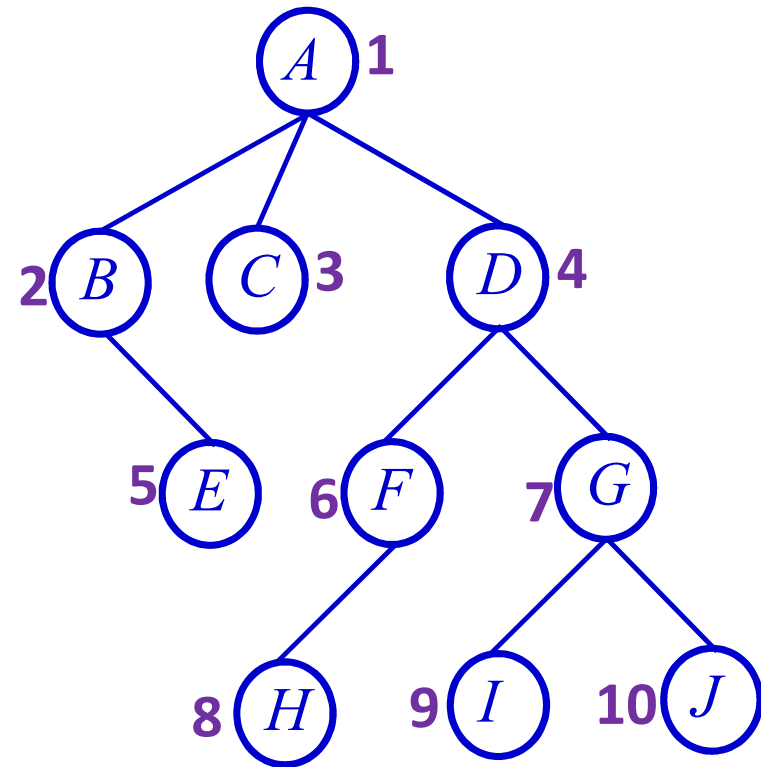
Traversal: B E A H F D I G J



# Level order Tree Traversal

- Nodes are visited **level by level** from left to right
- Nodes at level  $i$  are visited before nodes at level  $i + 1$

Traversal: **A B C D E F G H I J**





# Preorder Tree Traversal Code for Binary Tree

**We have already seen the** following  
binary tree data structure

```
struct BTreeNode {  
    int data;  
    struct BTreeNode *left, *right;  
}
```

# Preorder Tree Traversal Code for Binary Tree

**We have already seen the following**  
binary tree data structure

```
struct BTreeNode {  
    int data;  
    struct BTreeNode *left, *right;  
}
```

```
struct BTreeNode *root;
```

```
/* Recursive Algorithm */  
void preorder(struct BTreeNode *rt)  
{  
    if (rt == NULL) return; // Empty subtree  
    visit_and_doSomething(rt);  
    preorder(rt->left);  
    preorder(rt->right);  
}
```

# Inorder Tree Traversal Code for Binary Tree

```
struct BTreeNode {  
    int data;  
    struct BTreeNode *left, *right;  
}
```

```
struct BTreeNode *root;
```

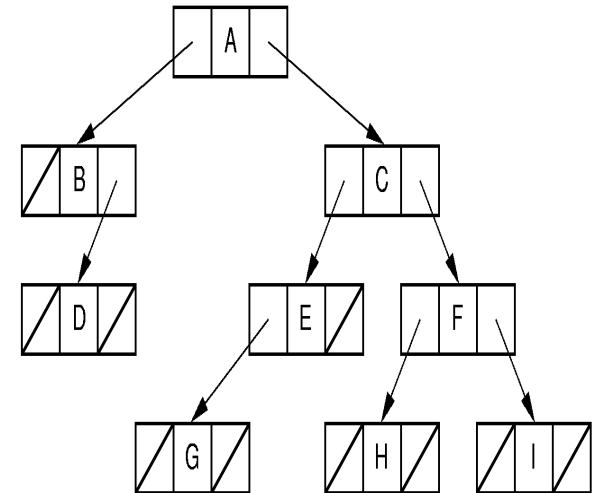
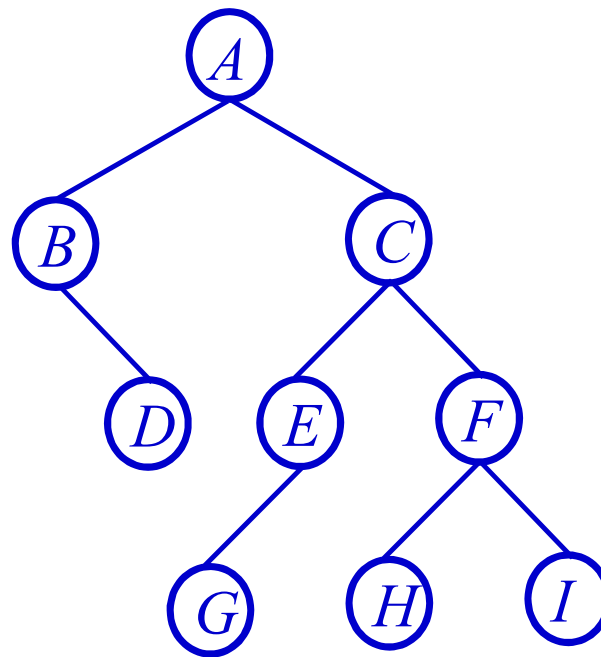
```
/* Recursive Algorithm */  
void inorder(struct BTreeNode *rt)  
{  
    if (rt == NULL) return; // Empty subtree  
    inorder(rt->left);  
    visit_and_doSomething(rt);  
    inorder(rt->right);  
}
```

# Postorder Tree Traversal Code for Binary Tree

```
/* Recursive Algorithm */  
void postorder(struct BTreeNode *rt)  
{  
    if (rt == NULL) return; // Empty subtree  
    postorder(rt->left);  
    postorder(rt->right);  
    visit_and_doSomething(rt);  
}
```

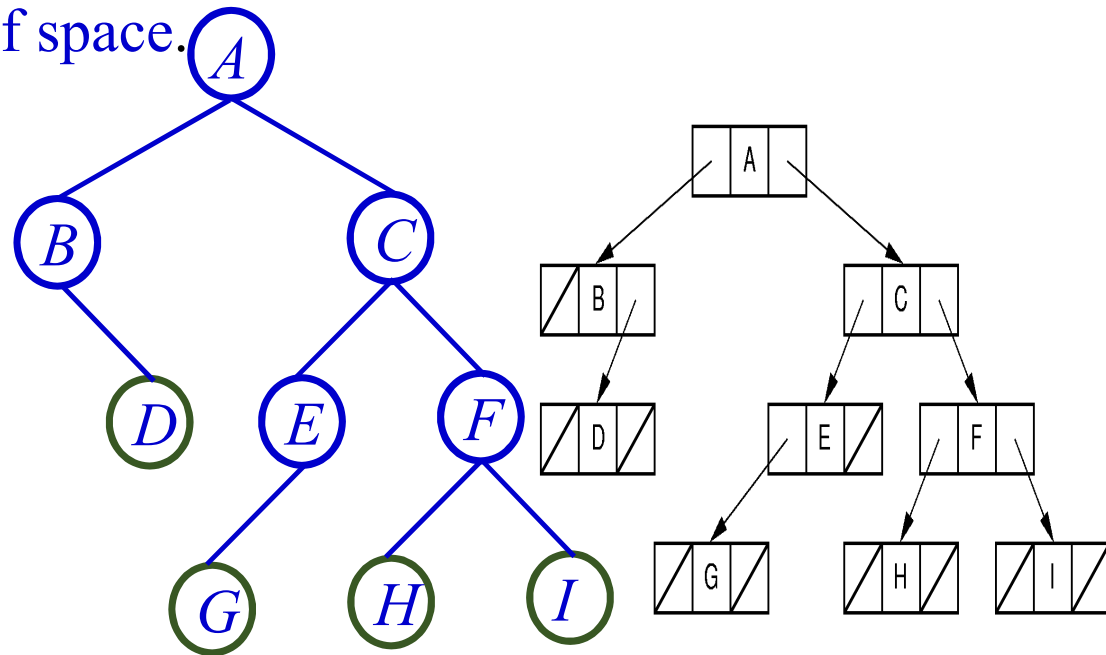
# Binary Tree Implementation Issues

```
struct BTnode {  
    int data;  
    struct BTnode *left, *right;  
}
```



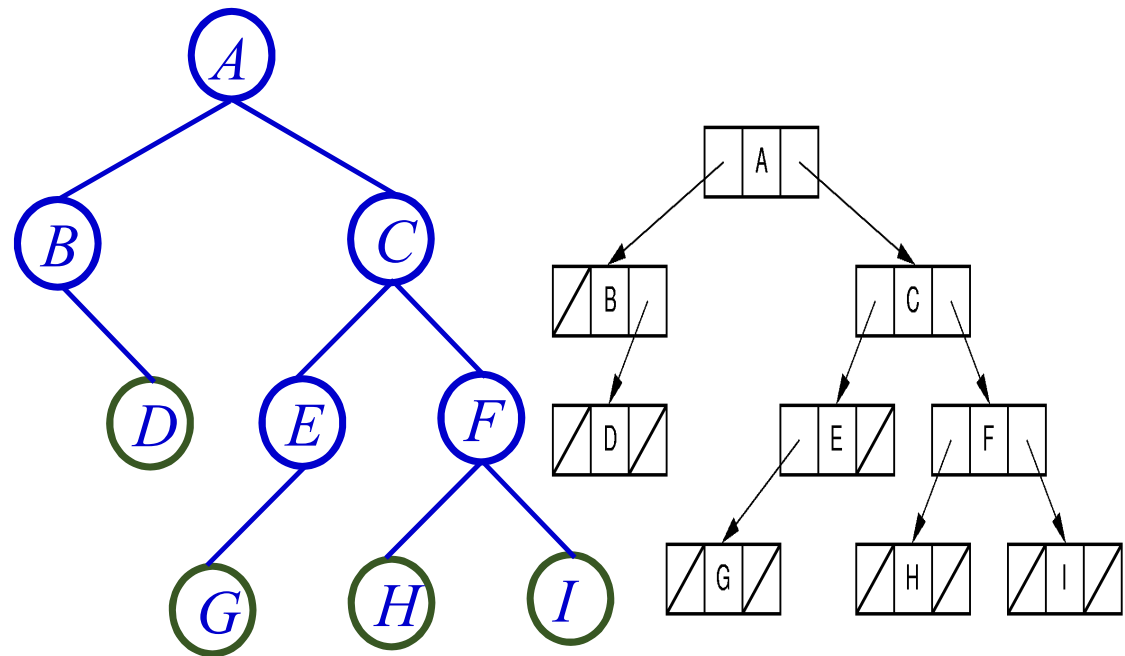
# Binary Tree Implementation Issues

- Same class/structure for all **leaves** and **internal** nodes.
  - Using the same class for both will **simplify** the implementation,
  - but might be an **inefficient** use of space.



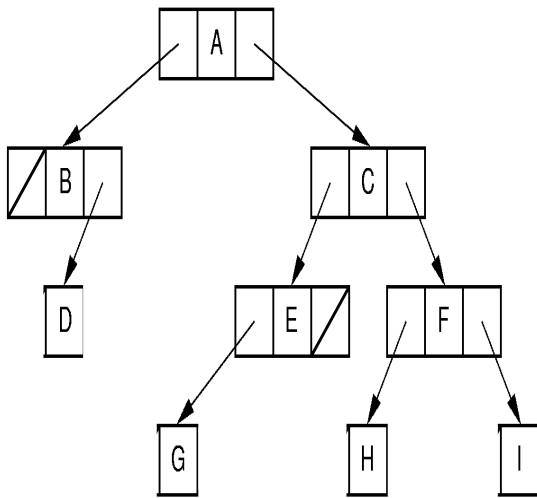
# Binary Tree Implementation Issues

- Some applications require data values only for the leaves.
- Other applications require one type of value for the leaves and another for the internal nodes.

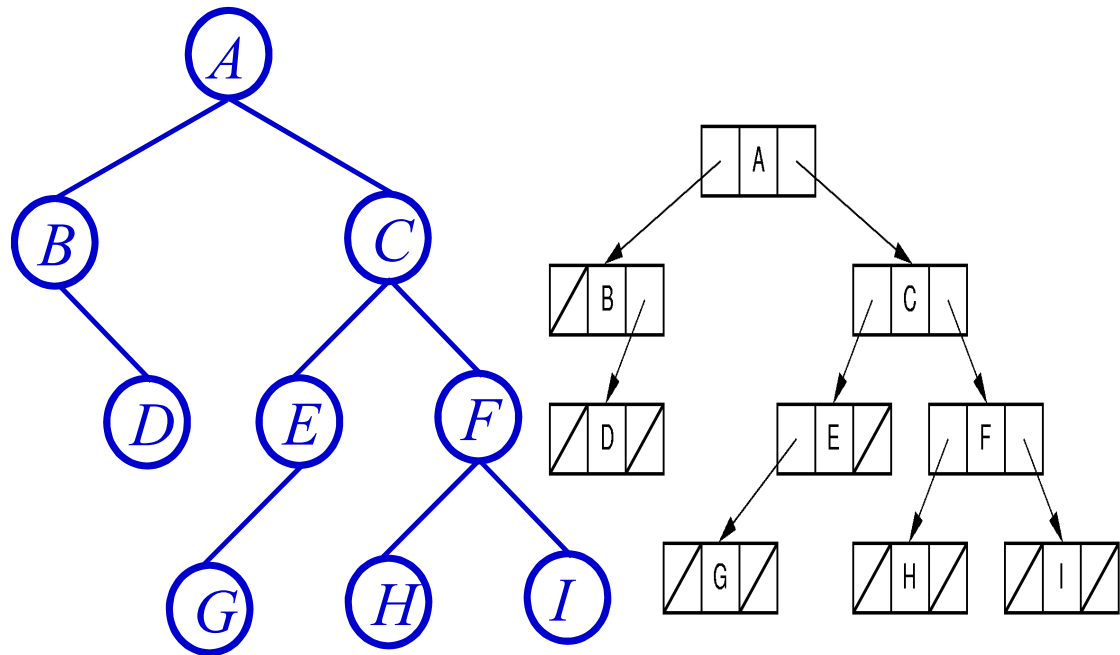


# Binary Tree Implementation Issues

- Some applications require data  
Also, it seems **wasteful to store child pointers in the leaf nodes.**

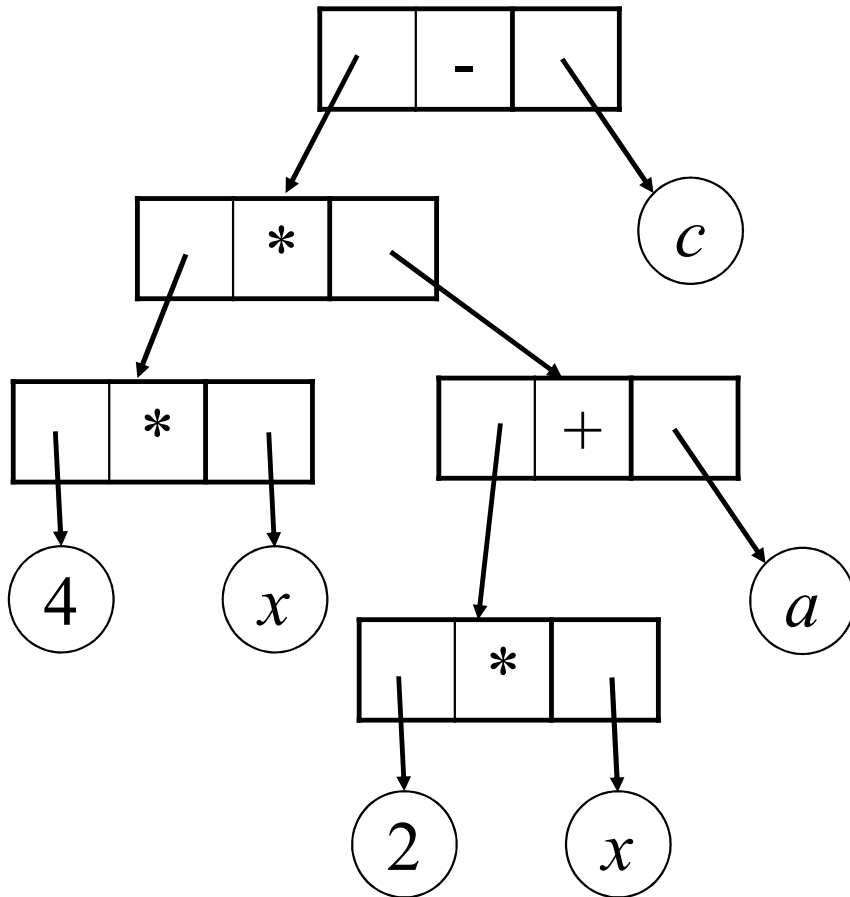


**NO child pointer in leaves**





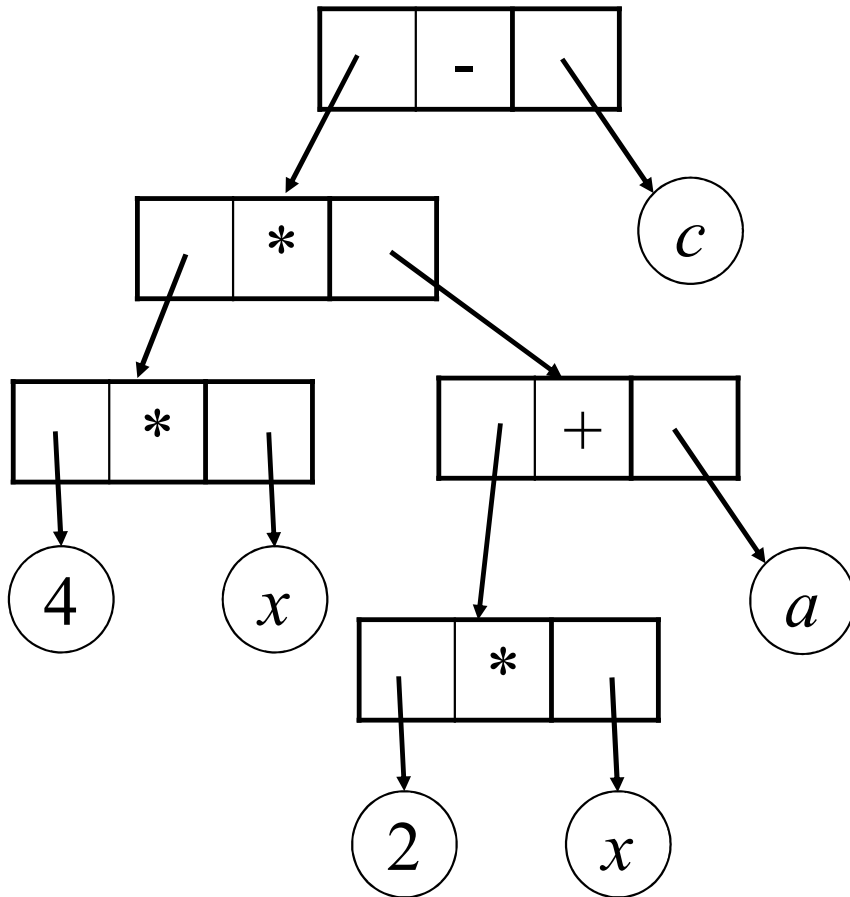
# Binary Tree Implementation Issues



$$4x(2x + a) - c$$

$$4 * x * (2 * x + a) - c$$

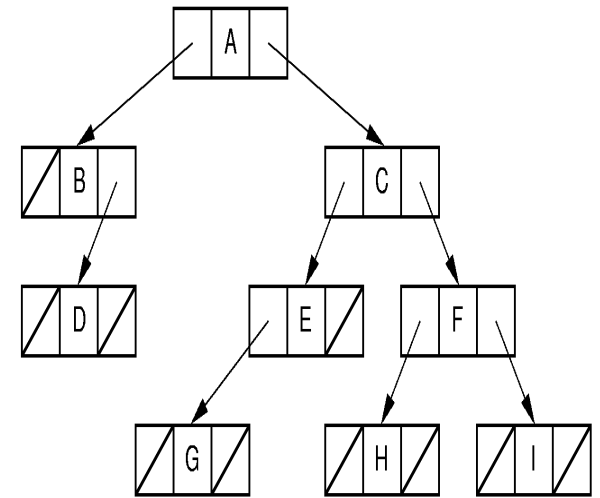
# Binary Tree Implementation Issues



- Internal nodes store operators
  - could store a **small code** identifying the **operator** (a single byte for the operator's symbol)
- the leaves store operands
  - i.e., variable names or numbers, (considerably larger in order to handle the wider range of possible values)
  - **No child pointers** though

# Space Analysis for Binary Tree Implementation

- Every **node** has **two pointers** to its children
- total space =  $n(2P + D)$  for a tree of  $n$  nodes
  - $P$ : space required by a pointer
  - $D$ : amount of space required by a data value
- So, total overhead:  $2Pn$
- Overhead fraction:  $2P/(2P+D)$
- $P = D \Rightarrow 2/3^{\text{rd}}$  of its total space is overhead



# Space Analysis for Binary Tree Implementation

- $P = D \Rightarrow 2/3^{\text{rd}}$  of its total space is overhead
- From the Full Binary Tree Theorem: Half of the pointers are **null**.
  - half of the pointers are “wasted” **NULL values that serve only to indicate tree** structure, but which do not provide access to new data.

